

Computer Vision: Image Classification

Deep Learning
CS 435/635

Course Instructor: Chandresh
AI Lab Coordinator @IIT Indore

Course Content

Module I: History of Deep Learning, Sigmoid Neurons, Perceptrons, and learning algorithms. Multilayer Perceptrons (MLPs), Representation Power of MLPs.,

Module II: Feedforward Neural Networks. Backpropagation. first and second-order training methods. NN Training tricks, Regularization

Module III: Introduction to Autoencoders and their characteristics, relation to PCA, Regularization in autoencoders, and Types of autoencoders, Variational Autoencoder

Module IV: Architecture of Convolutional Neural Networks (CNN), types of CNNs. **Image classification.**

Module V: Architecture of Recurrent Neural Networks (RNN), Backpropagation through time. Encoder-Decoder Models, Attention Mechanism. Advanced Topics: Transformers and BERT.

Nodule VI: Gen AI- Deep generative models: VAE, GAN,

Acknowledgement

- Russ Salakhutdinov and Hugo Larochelle's class on Neural Networks
- Neural Networks and Deep Learning course by Danna Gurari University of Colorado Boulder

Today's Topics

- Computer vision
- Era of dataset challenges
- MNIST challenge winner: LeNet
- ImageNet challenge winners: deeper learning (AlexNet, VGG, ResNet)
- Programming tutorial

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Computer Vision: Computers that “See”



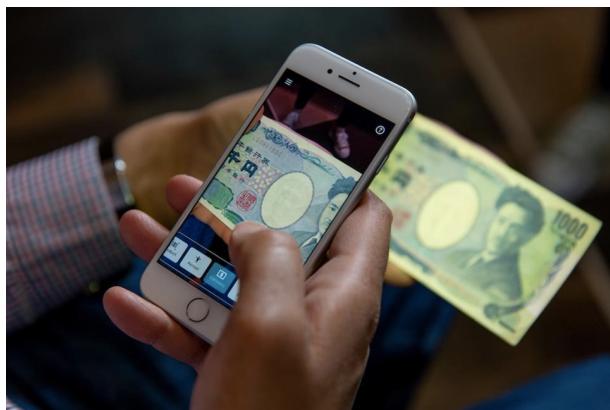
Self-driving cars



Exploration on Mars



Guided surgery



Visual assistance for people who are blind



Security

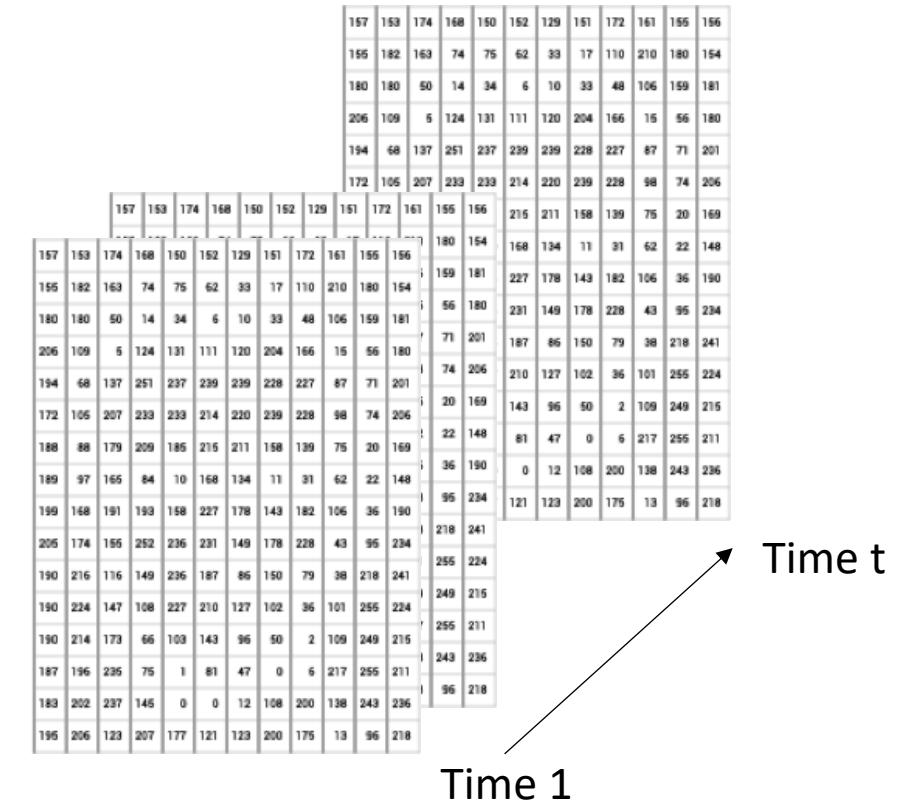
Why Discuss Computer Vision With CNNs?

- CNNs have a strong track record for vision problems
- Visual data's representation (i.e., spatial data) is naturally suited for CNNs

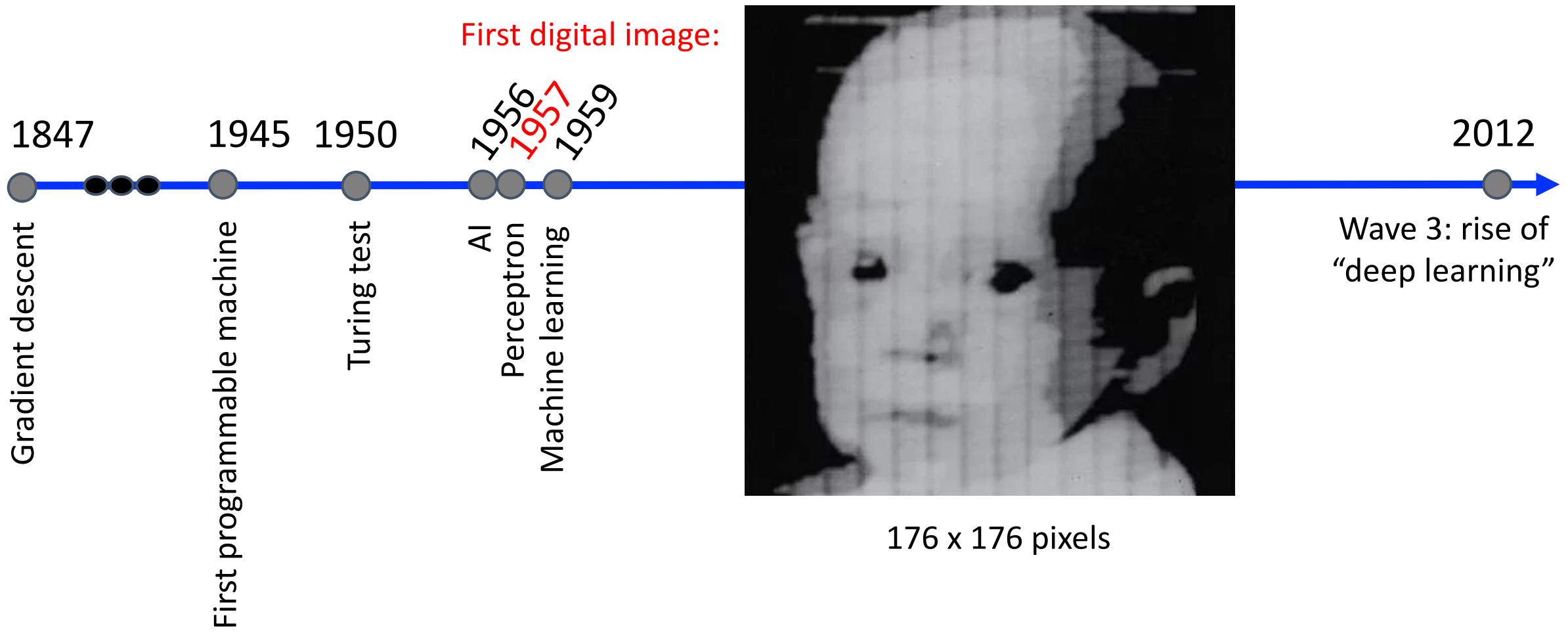
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155	182	163	74	75	62	33	17	110	210	180	154
180	180	50	14	34	6	10	33	48	106	159	181
206	109	5	124	131	111	120	204	166	15	56	180
194	68	137	251	237	239	239	228	227	87	71	201
172	105	207	233	239	214	220	239	228	98	74	206
188	88	179	209	185	215	211	158	139	75	20	169
189	97	165	84	10	168	134	11	31	62	22	148
199	168	191	193	158	227	178	143	182	106	36	190
205	174	195	252	236	231	149	178	228	43	95	234
190	216	116	149	236	187	85	150	79	38	218	241
190	224	147	108	227	210	127	102	36	101	255	224
190	214	173	66	103	143	96	50	2	109	249	216
187	196	235	75	1	81	47	0	6	217	255	211
183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

Image:

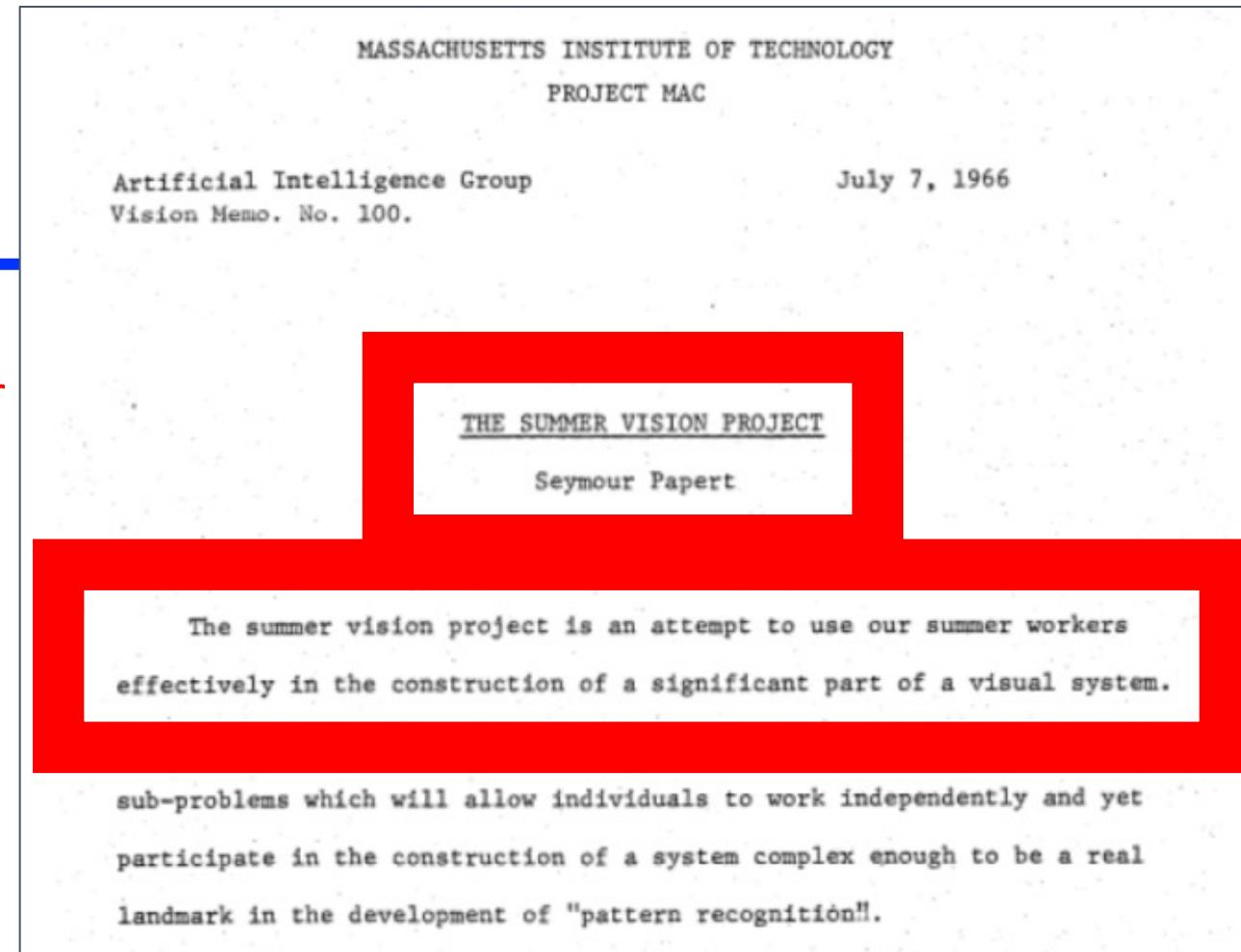
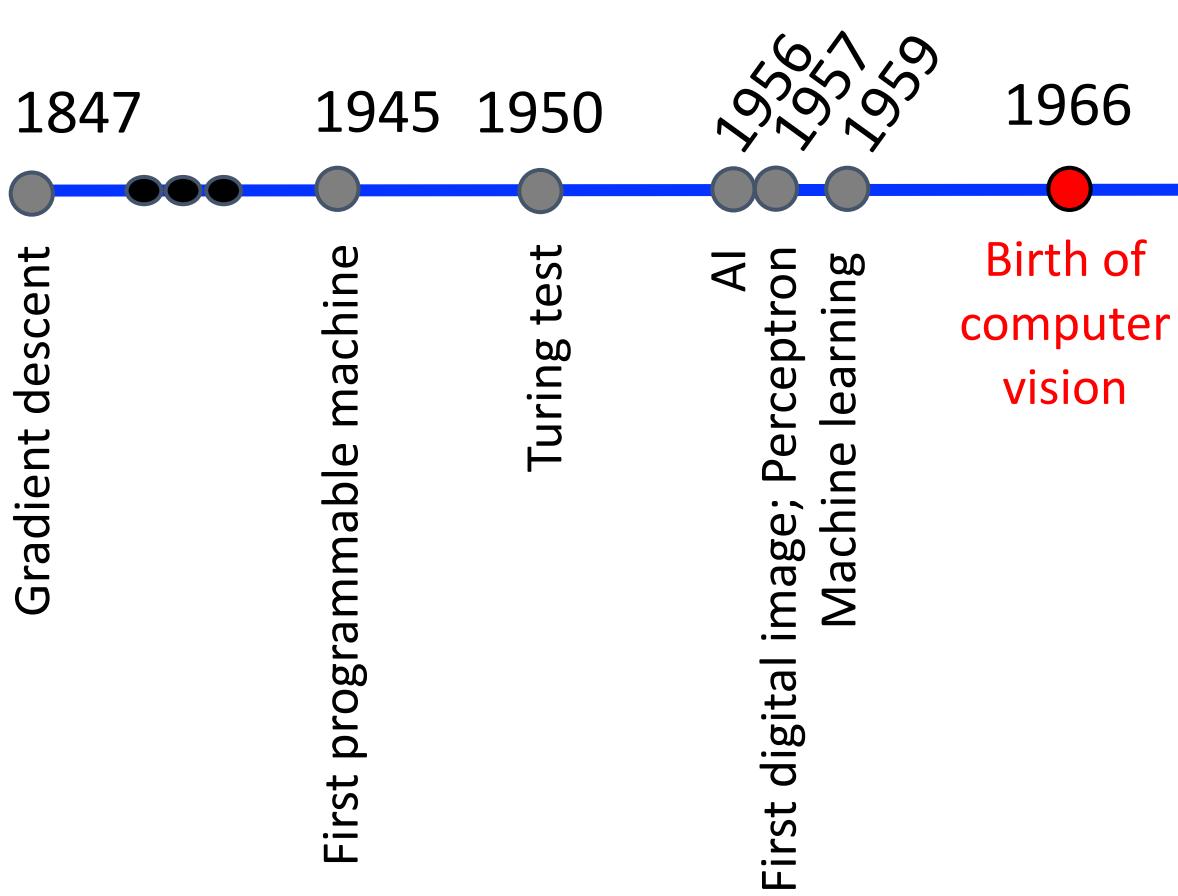
Video:



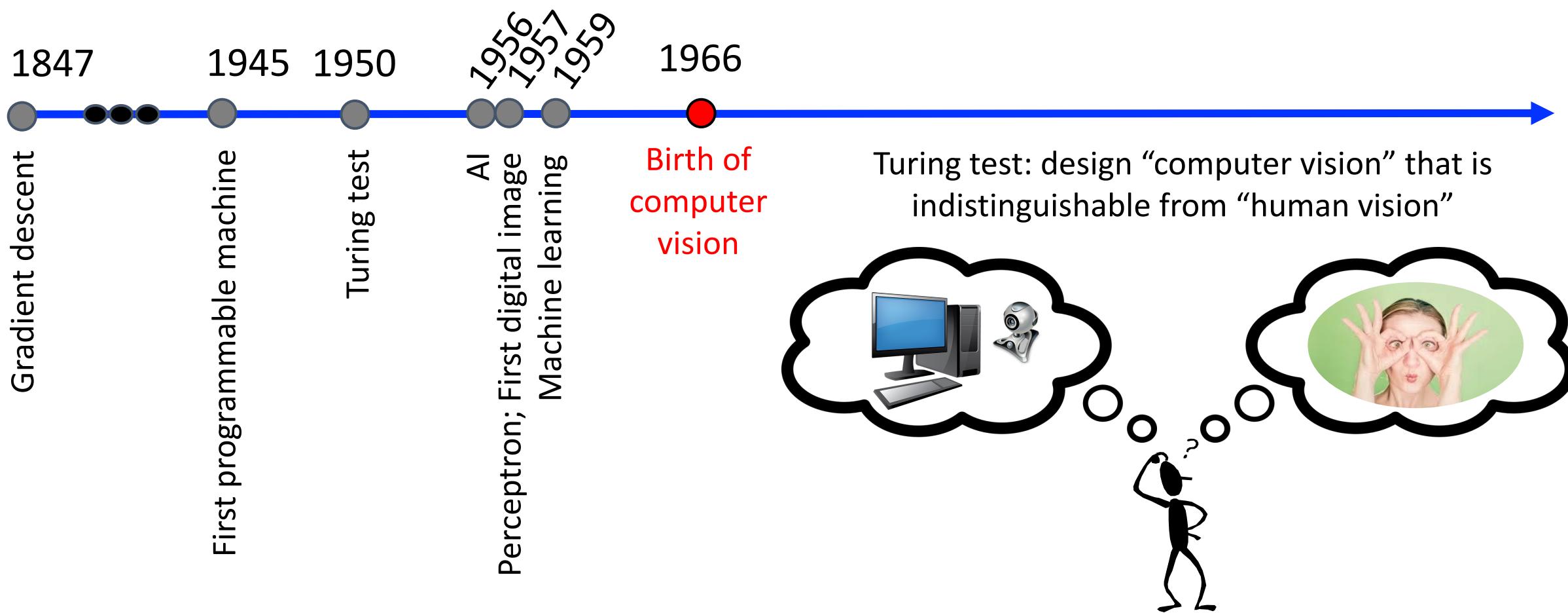
Historical Context: Origins of Computer Vision



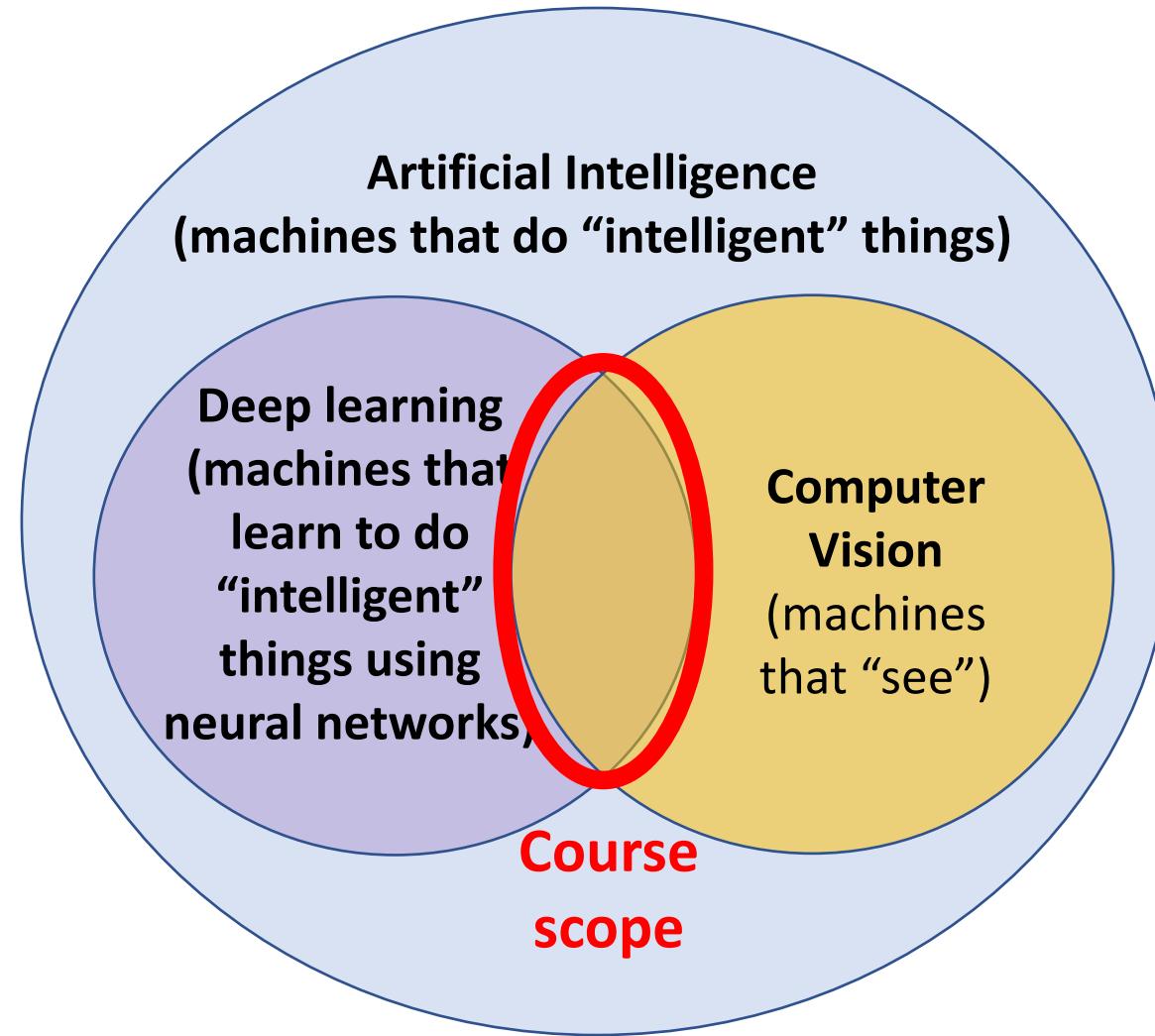
Historical Context: Origins of Computer Vision



Historical Context: Origins of Computer Vision



Computer Vision in Context



Key Challenge: Replicate Human Vision for So Much Variation for So Many Tasks!

- Object recognition
- Object detection
- Segmentation
- Image captioning
- Visual question answering
- Object tracking
- Subjective problems
- And more...

Key Challenge: Replicate Human Vision for So Much Variation for So Many Tasks!

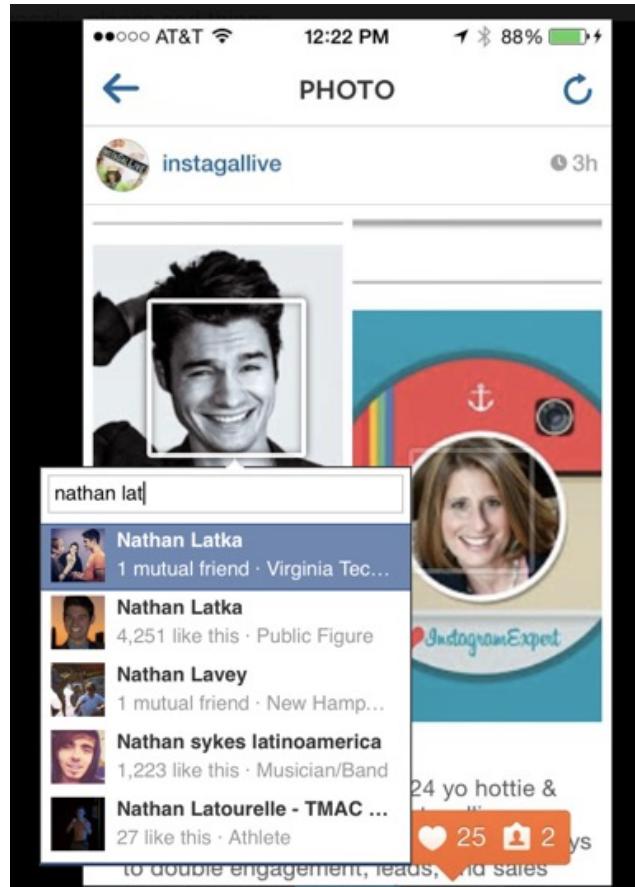
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e.g., take a picture of an object and find where to buy it

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e.g., detect faces to tag

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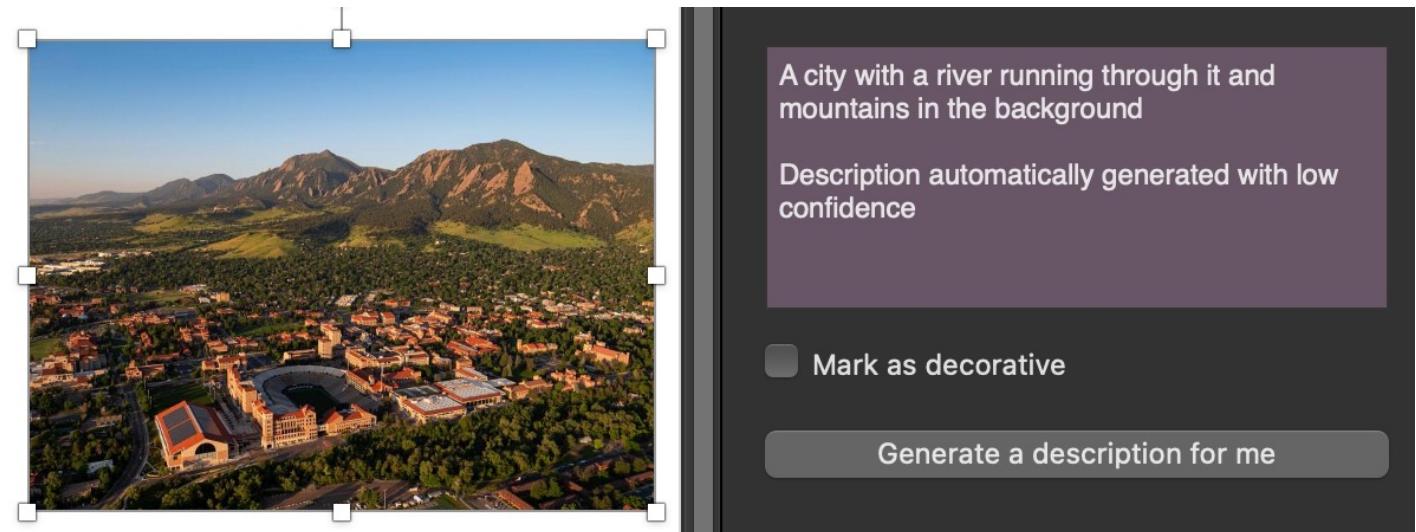


e.g., rotoscoping

<https://www.starnow.co.uk/ahmedmohammed1/photos/4650871/before-and-after-rotoscopinggreen-screening>

Key Challenge: Replicate Human Vision for So Much Variation for So Many Tasks!

- Object recognition
- Object detection
- Segmentation
- **Image captioning**
- Visual question answering
- Object tracking
- Subjective problems
- And more...



e.g., Microsoft Power Point

Key Challenge: Replicate Human Vision for So Much Variation for So Many Tasks!

- Object recognition
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- And more...



e.g., BeSpecular

<https://www.lionessesofafrica.com/blog/2015/2/15/the-startup-story-of-stephanie-cowper>

Key Challenge: Replicate Human Vision for So Much Variation for So Many Tasks!

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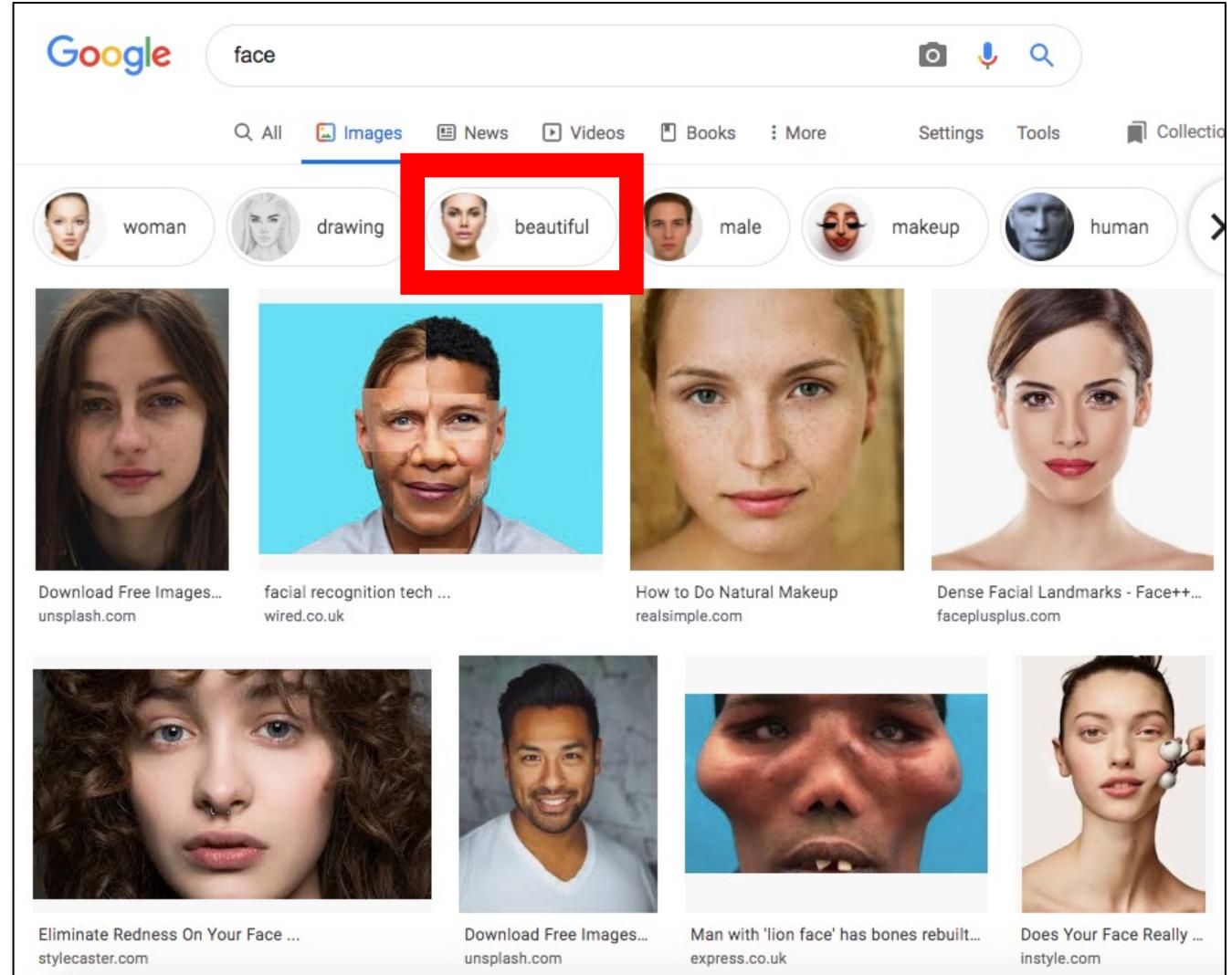
e.g., track bowling ball path



e.g., calculate bat speed

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Key Challenge: Replicate Human Vision for So Much Variation for So Many Tasks!



Illumination



Object pose



Clutter



Occlusions



Intra-class appearance



Viewpoint

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Through 1990s, Common Approach to Developing Computer Vision Models:

Algorithm Dataset



Algorithm Dataset



Algorithm Dataset

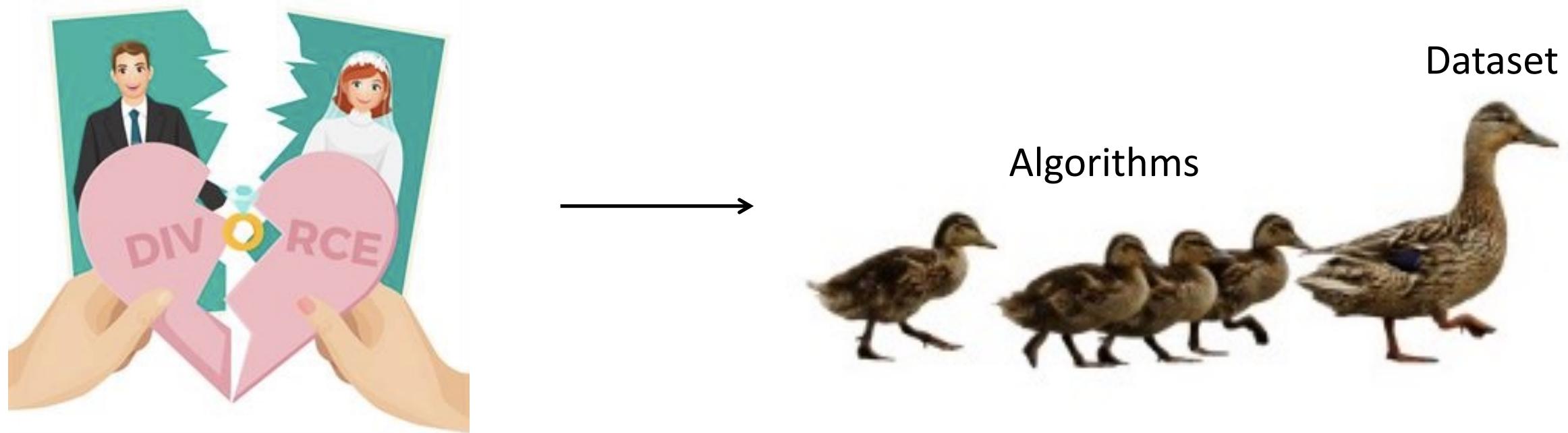


Algorithm Dataset



Datasets tended to be relatively small (e.g., 10s or 100s of examples)

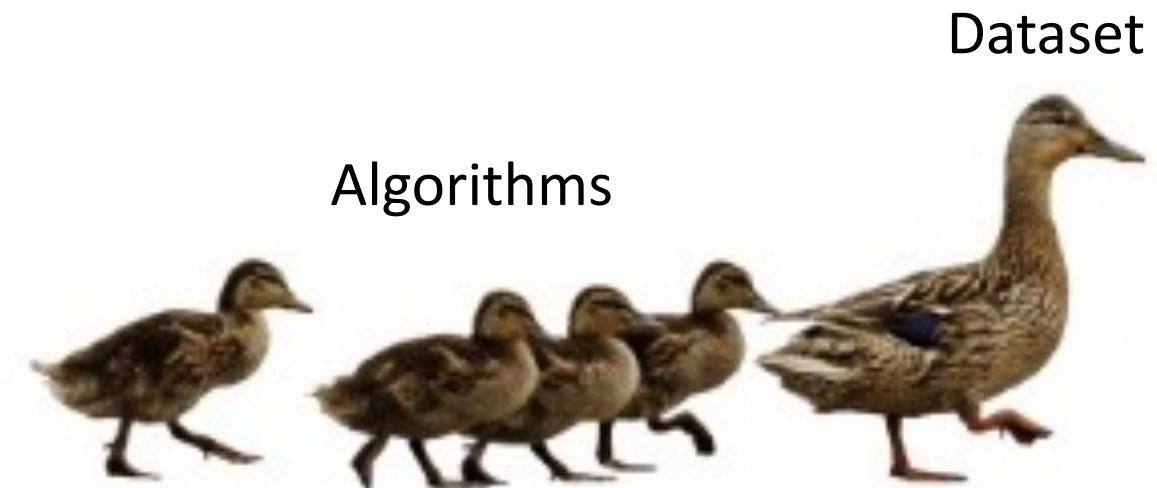
Since 1990s, Common Approach to Developing Computer Vision Models:



Datasets tend to be large (i.e., thousands to millions of examples)

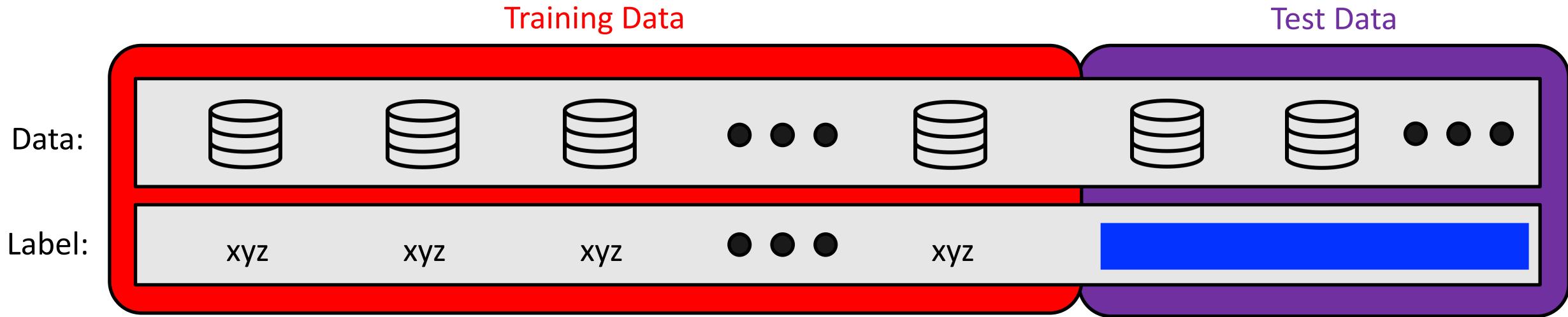
Since 1990s, Common Approach to Developing Computer Vision Models:

What do you think prompted this shift to large-scale datasets?



Datasets tend to be large (i.e., thousands to millions of examples)

Progress Charted by Progress on Community Shared Dataset Challenges: How It Works



1. Dataset split into a “**training set**” and “**test set**” with the labels for the “test set” hidden
2. Teams design a model and submit its predictions on the test set to an evaluation server
3. A public leaderboard shows the ranking of performance for all teams’ submitted models

Progress Charted by Progress on Community Shared Dataset Challenges: Why Challenges?

- Provide “fair” comparison between models
- Create a community around a shared goal

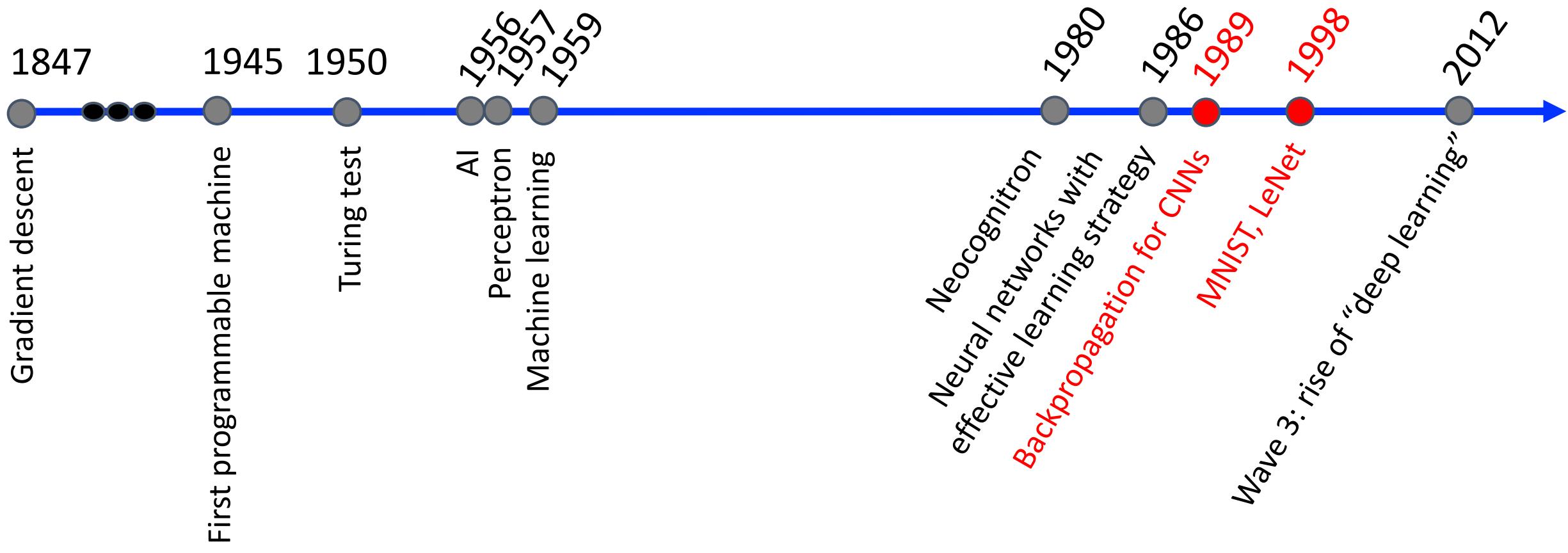
Many Public Dataset Challenges Available; e.g.,

- [Google Dataset Search](#)
- [Amazon's AWS datasets](#)
- [Kaggle datasets](#)
- [Wikipedia's list](#)
- [UC Irvine Machine Learning Repository](#)
- Quora.com
- Reddit
- Dataportals.org
- Opendatamonitor.eu
- Quandl.com

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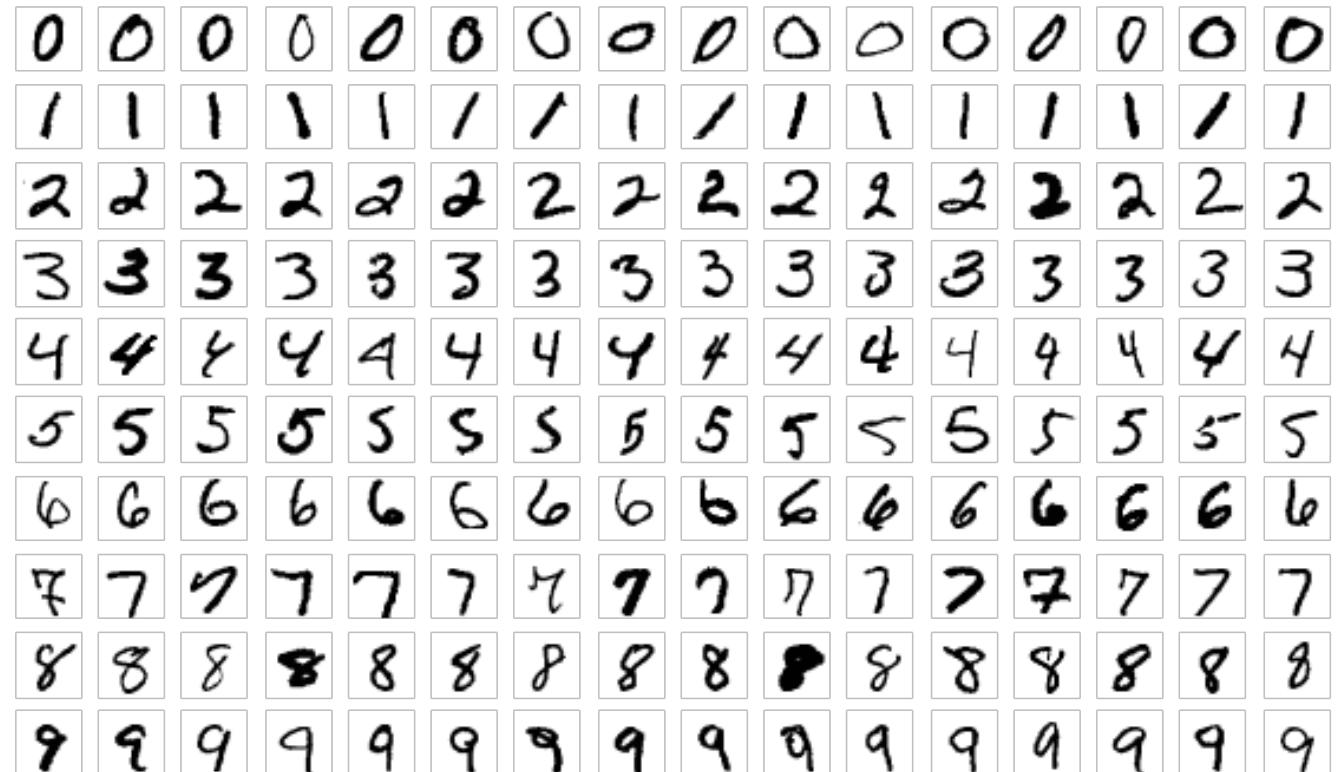
Historical Context: Inspiration



Key contribution: showing how to perform backpropagation for CNNs to enable learning thereby eliminating the need for hand-crafted filters

MNIST Dataset Challenge

- **Goal:** classify digit as 0, 1, ..., or 9
- **Evaluation metric:** accuracy (% correct)
- **Dataset:** 60,000 training and 10,000 test examples, pre-processed to be centered and same dimension; writers were different in the two sets
- **Source:** images collected by NIST from a total of 500 Census Bureau employees and high school students

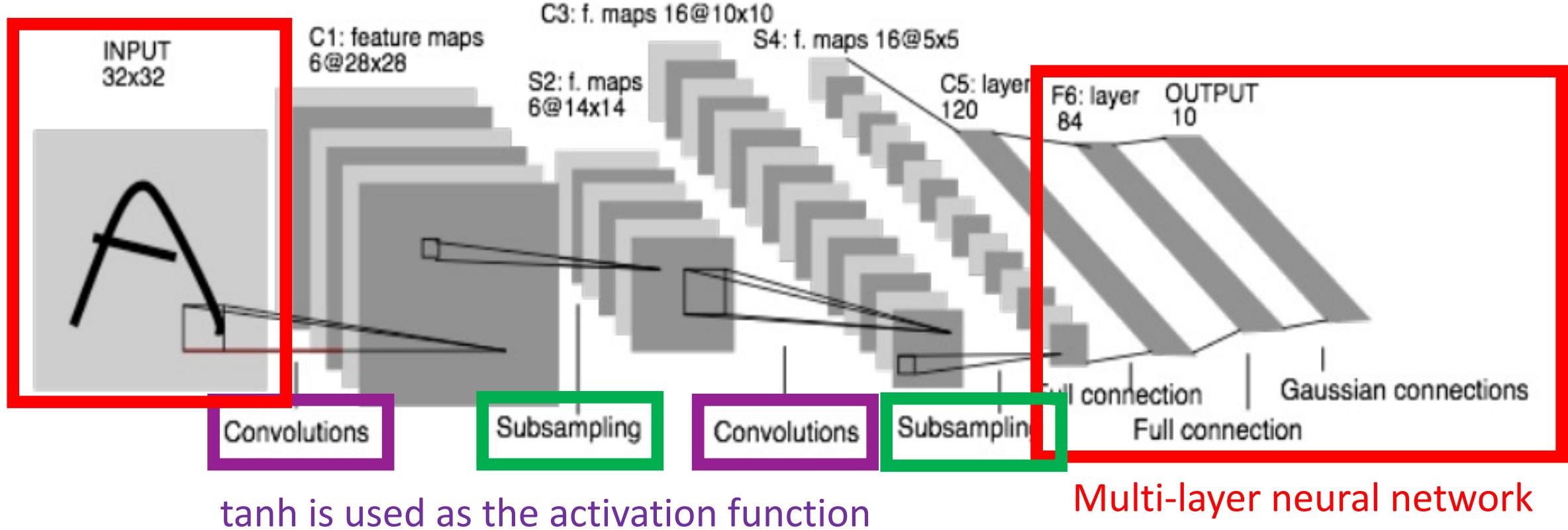


Dataset location: <http://yann.lecun.com/exdb/mnist/>

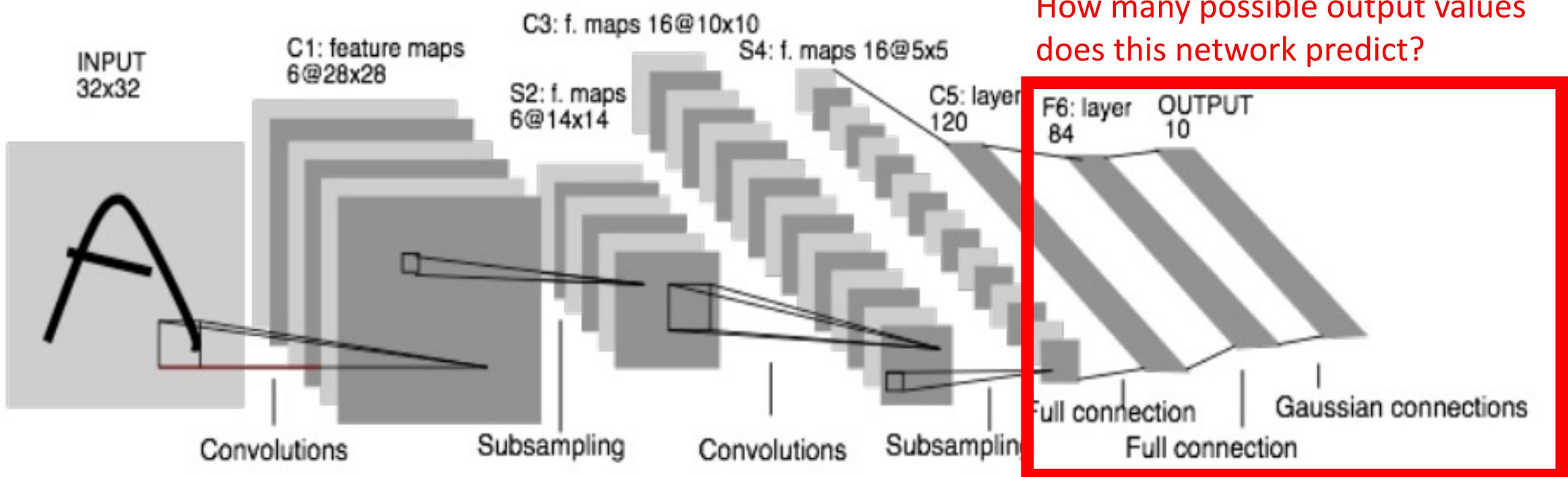
NIST dataset: <https://www.nist.gov/srd/nist-special-database-19>

Figure source: <https://commons.wikimedia.org/w/index.php?curid=64810040>

LeNet: Architecture (like Neocognitron, has convolutional layers and pooling layers)

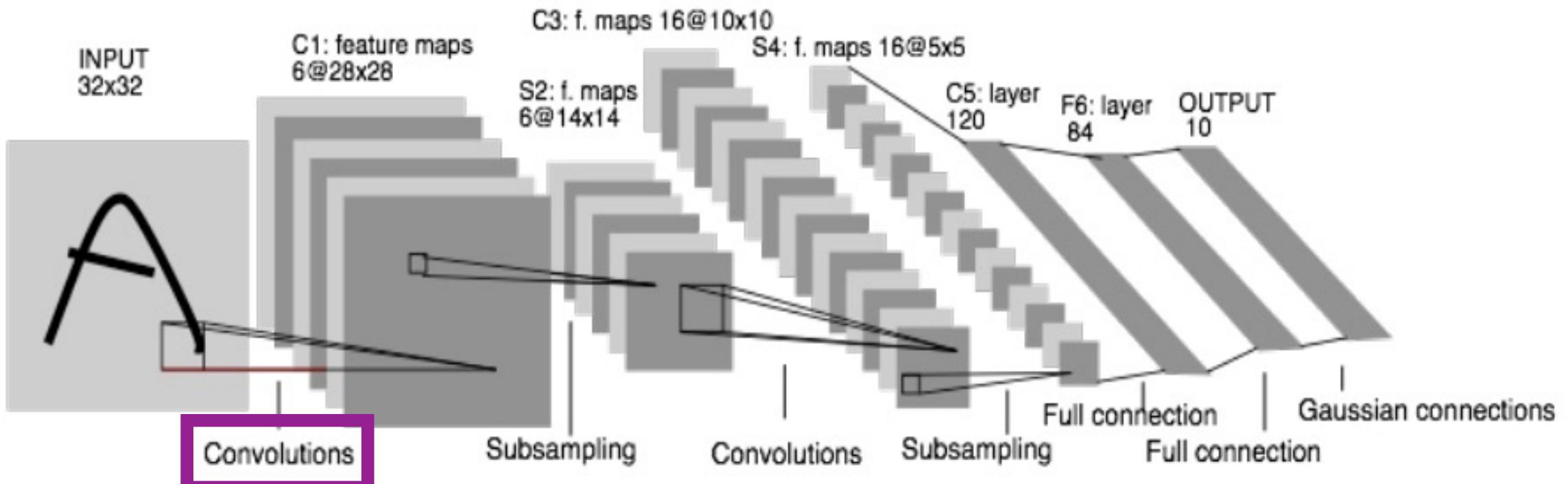


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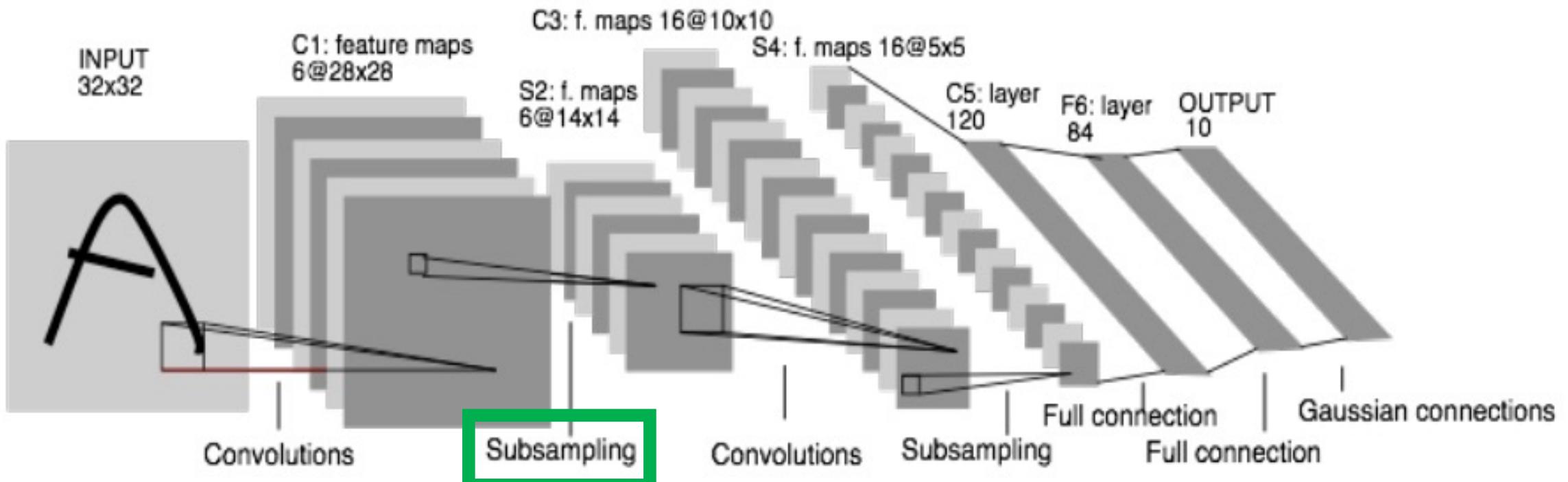
Multi-layer neural network

LeNet: Architecture (like Neocognitron, has convolutional layers and pooling layers)



How many filters are between
the input and hidden layer 1?

LeNet: Architecture (like Neocognitron, has convolutional layers and pooling layers)



What size of a neighborhood
is used for this pooling layer?

Training Procedure Approach (Key Novelty)

- Repeat until stopping criterion met:

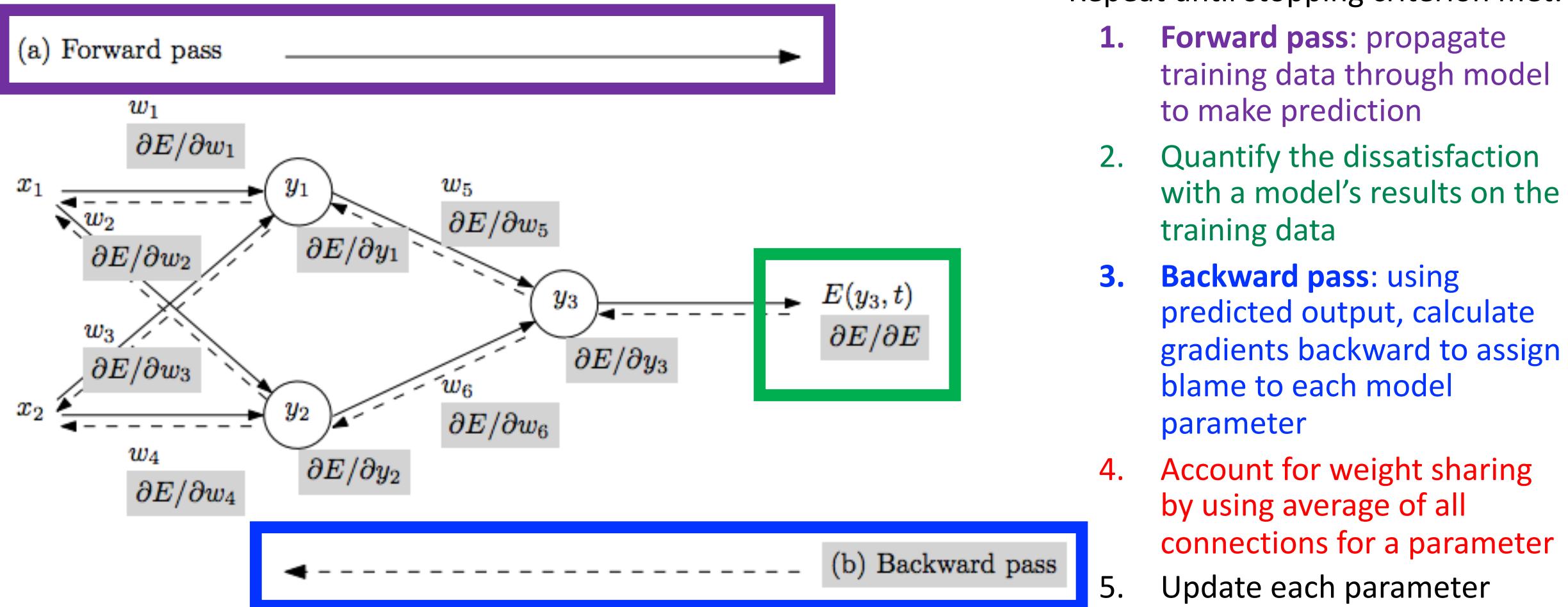
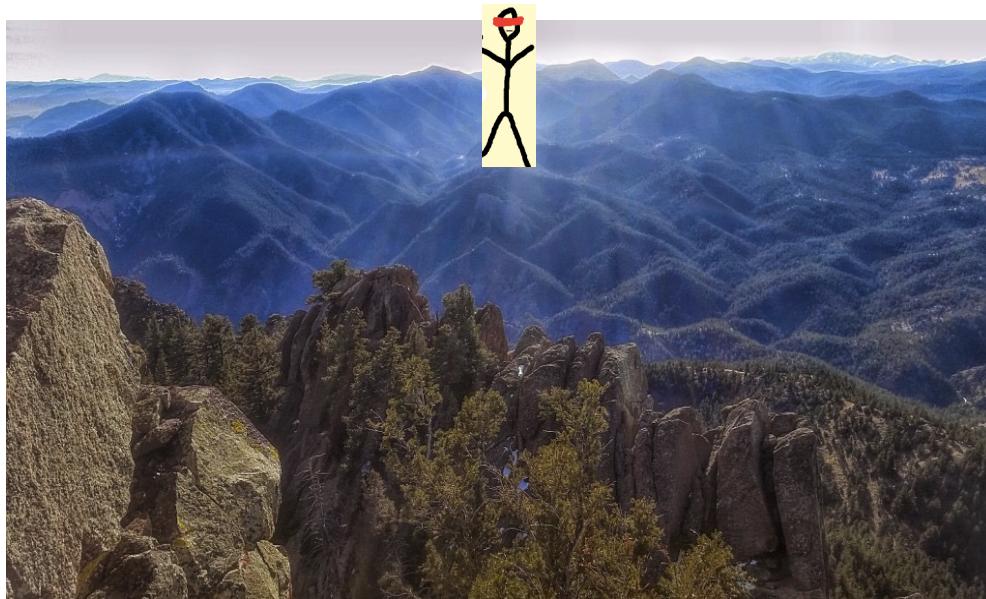


Figure from: Atilim Gunes Baydin, Barak A. Pearlmutter, Alexey Andreyevich Radul, Jeffrey Mark Siskind; Automatic Differentiation in Machine Learning: a Survey; 2018

Training Procedure Approach (Key Novelty)

Still obtain an error surface, E , based on the chosen objective function (e.g., using mean squared error, cross entropy loss)



- Repeat until stopping criterion met:
 1. **Forward pass:** propagate training data through model to make prediction
 2. **Quantify the dissatisfaction** with a model's results on the training data
 3. **Backward pass:** using predicted output, calculate gradients backward to assign blame to each model parameter
 4. Account for weight sharing by using average of all connections for a parameter
 5. Update each parameter using calculated gradients

Training Procedure Approach (Key Novelty)

Still decide how to adjust model parameters (weights, biases) to push the predictions closer to the corresponding ground truth; a different gradient derivation used to tweak each value in each convolutional filter

(covered in Section 6.3 of Kamath book and <https://www.jefkine.com/general/2016/09/05/backpropagation-in-convolutional-neural-networks/>)

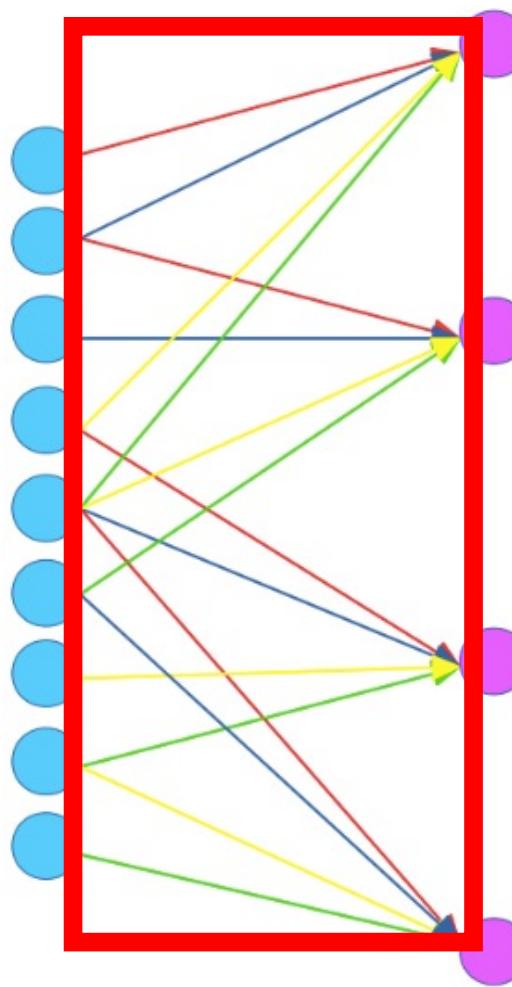
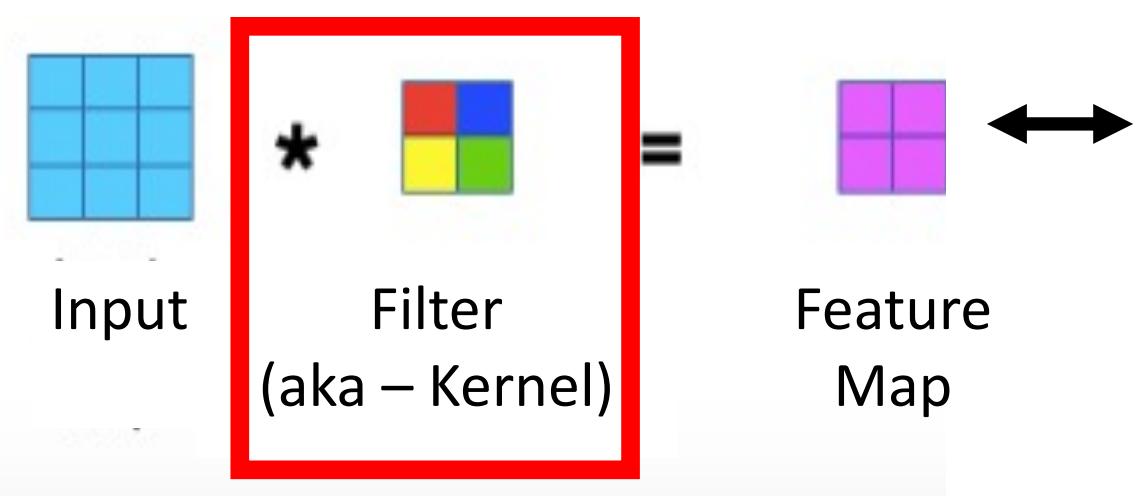


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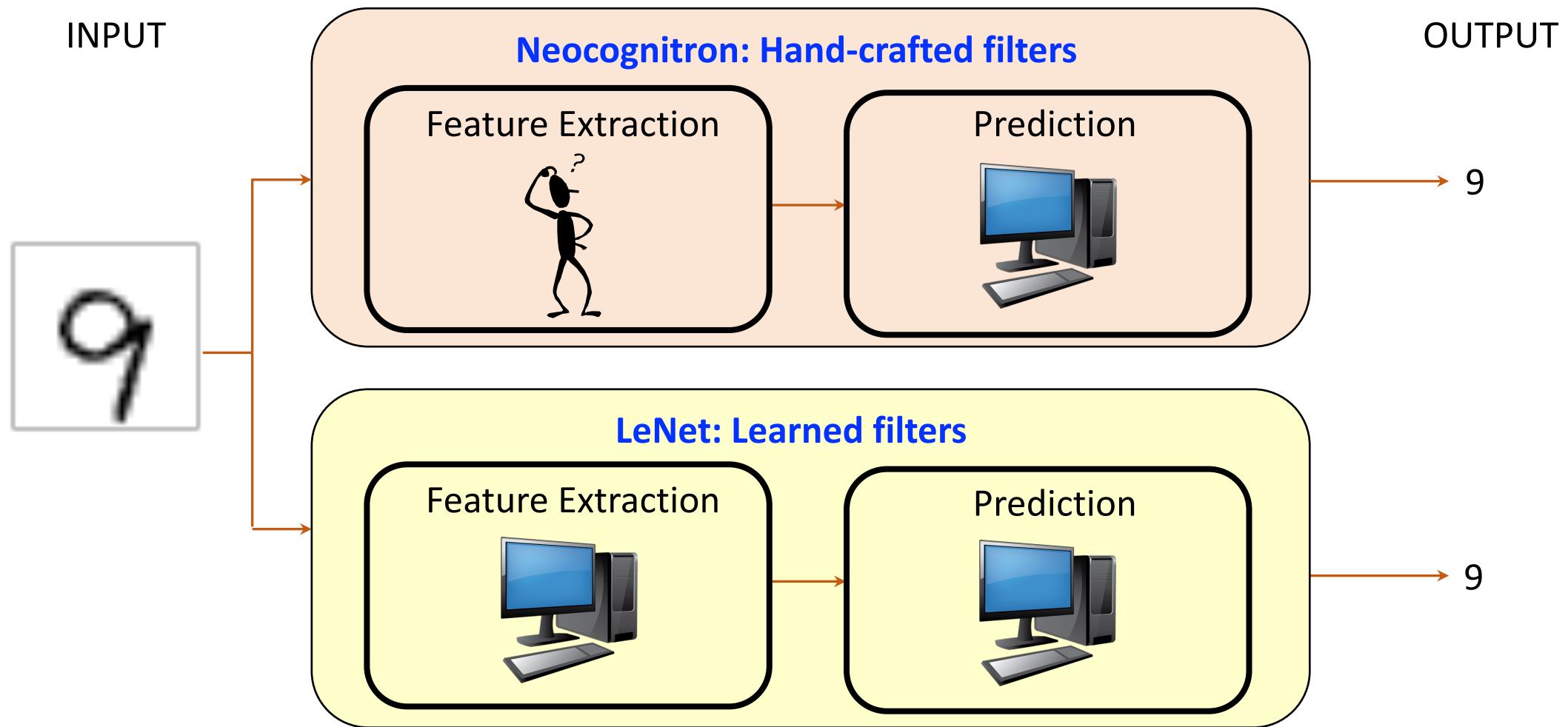
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LeNet vs Neocognitron

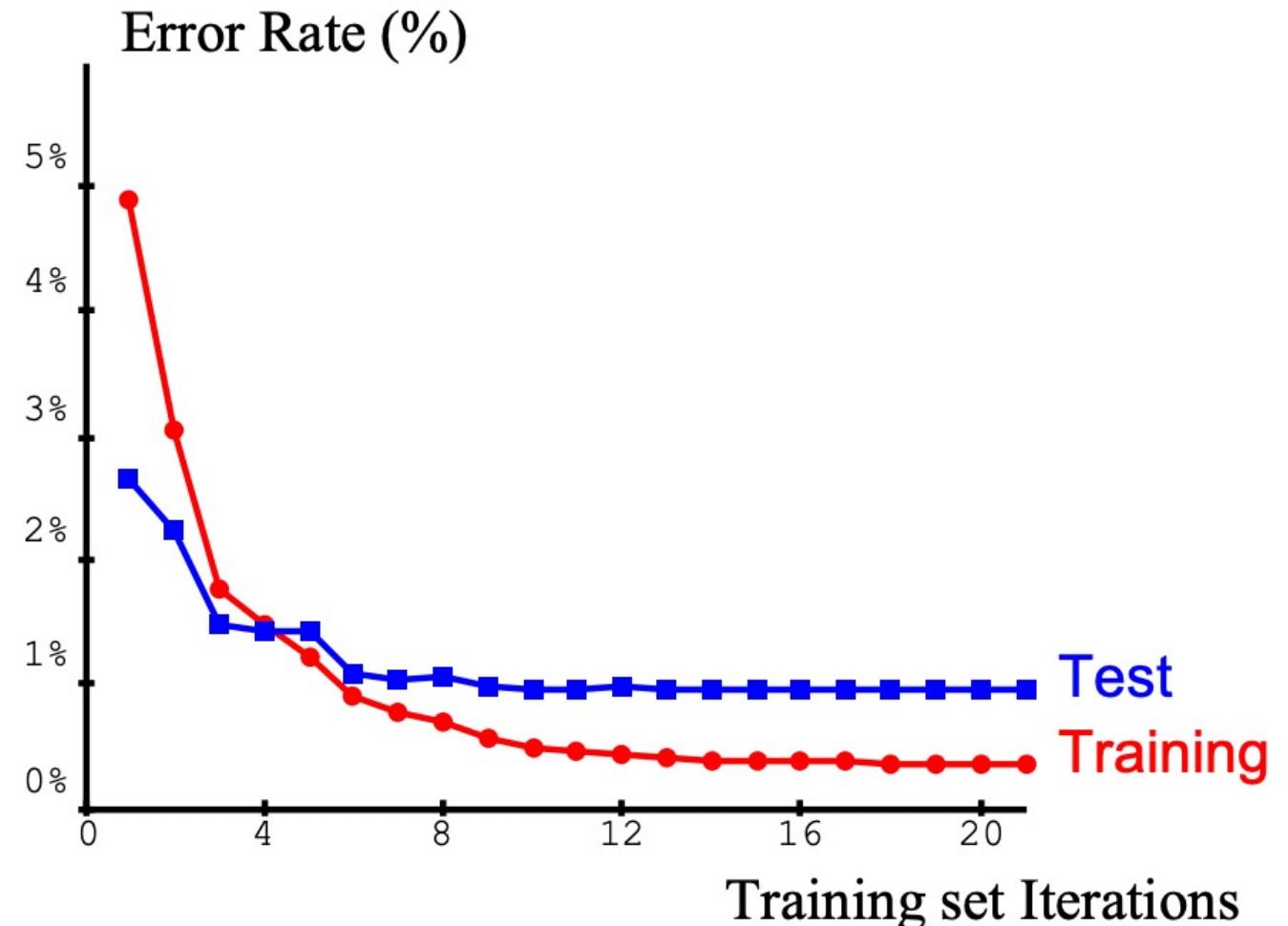


LeNet Analysis

How many epochs are needed for training to converge?

Why might overfitting not arise with more training?

- Learning rate was too large for the model to settle in a local minimum but rather oscillated randomly



LeNet Analysis

All 82 mislabeled examples
(correct answer on left,
predicted answer on right):

Why might the model be
making mistakes?

- Insufficient representation
in the training data
- Ambiguity

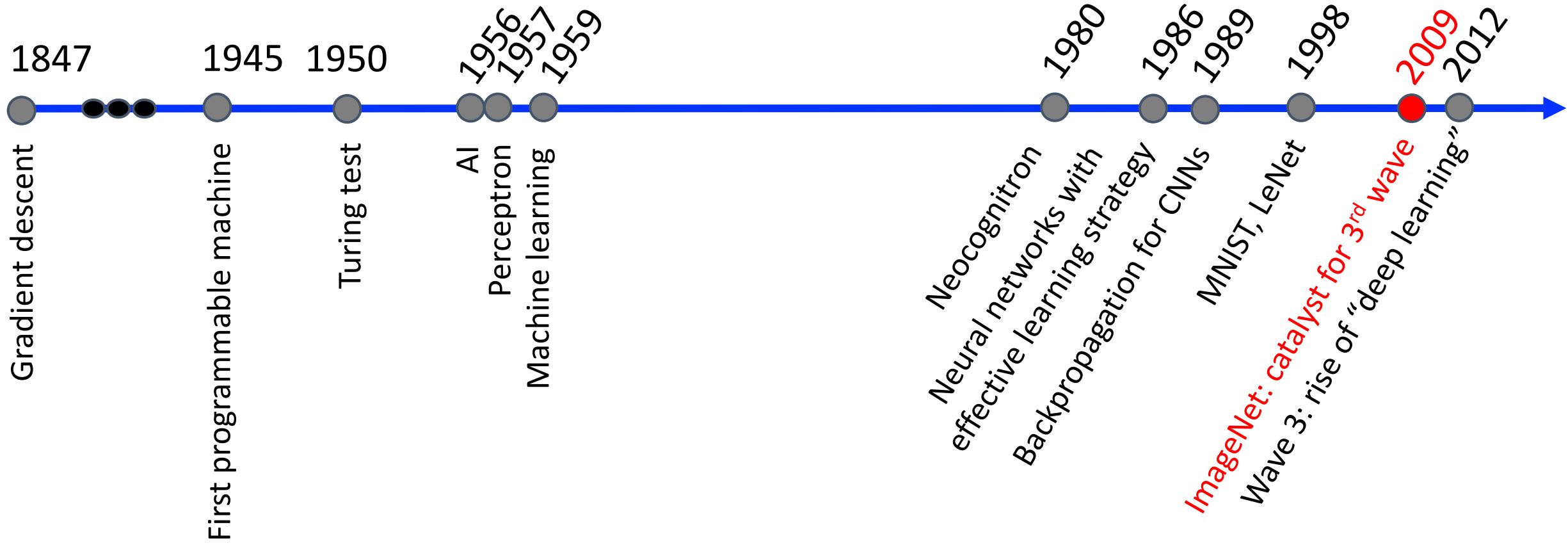


LeNet, designed on the MNIST Challenge, was used to read over 10% of checks in North America in the 1990s, reading millions of checks every month

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Historical Context



ImageNet: Predict Category from 1000 Options

- **Evaluation metric:** % correct (top-1 and top-5 predictions)
- **Dataset:** ~1.5 million images
- **Source:** images scraped from search engines, such as Flickr, and labeled by crowdworkers



ImageNet vs MNIST

- 3D objects in natural backgrounds
- Many more categories



Rise of “Deep Learning”

Progress of models on ImageNet (Top 5 Error)

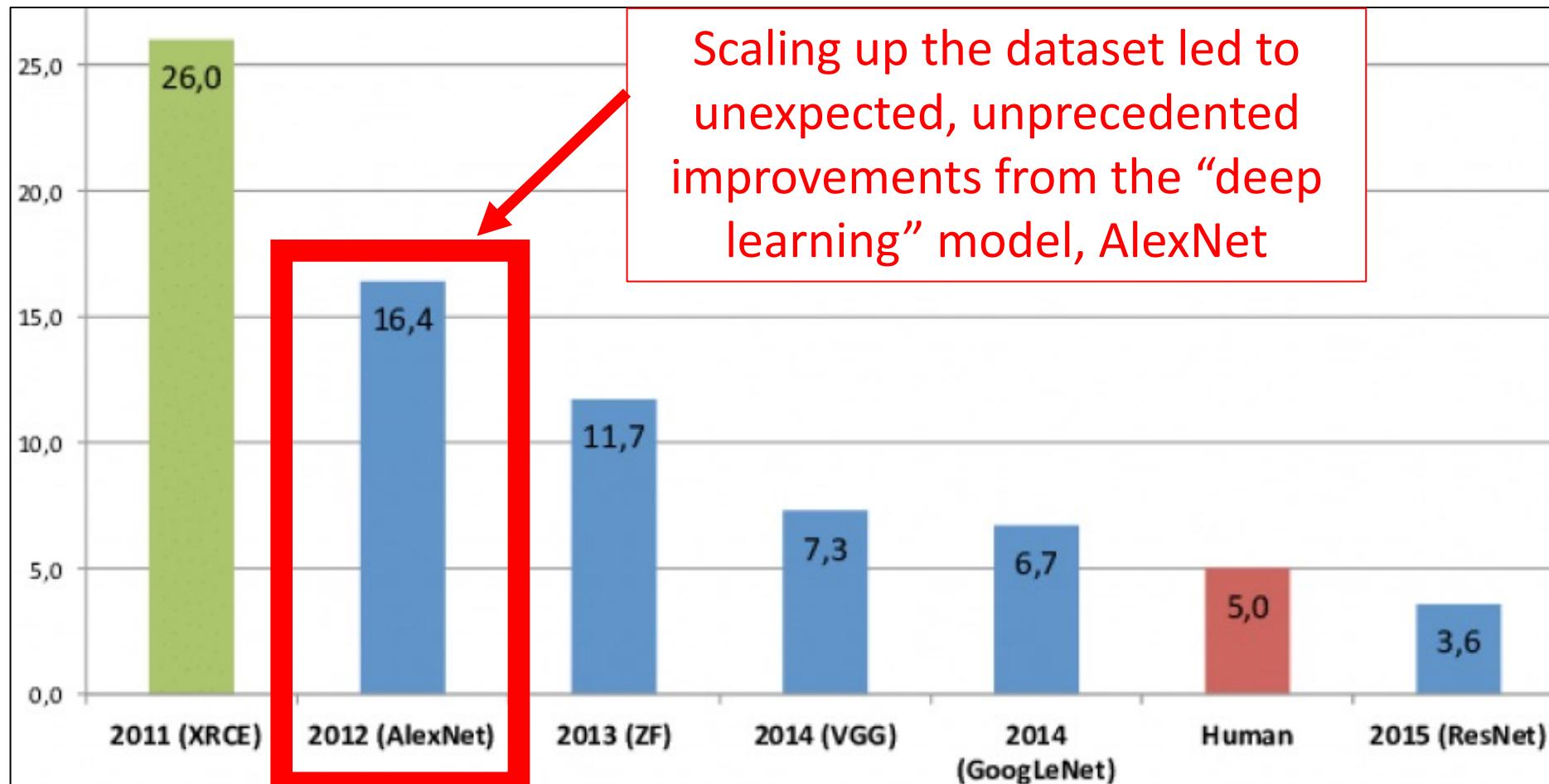
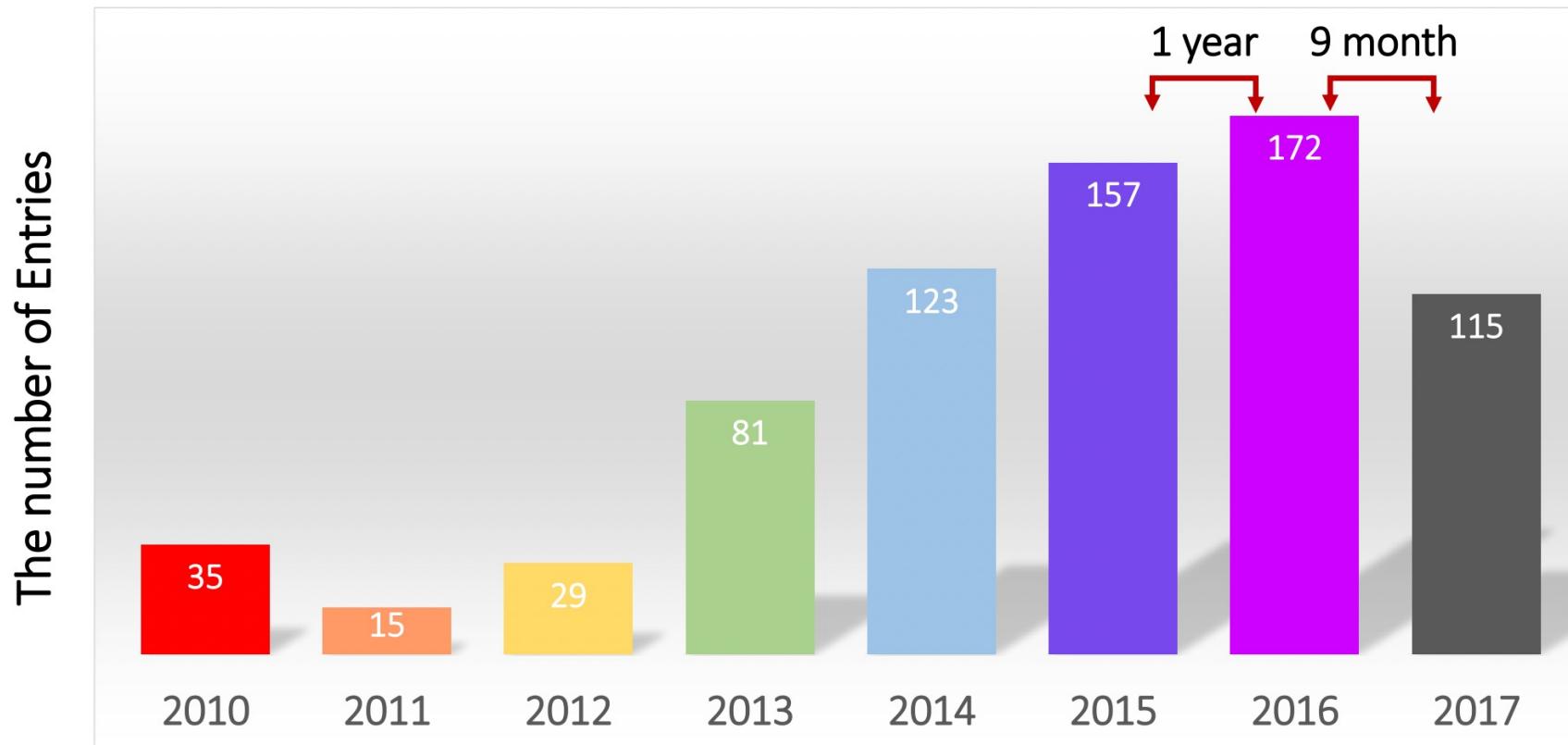


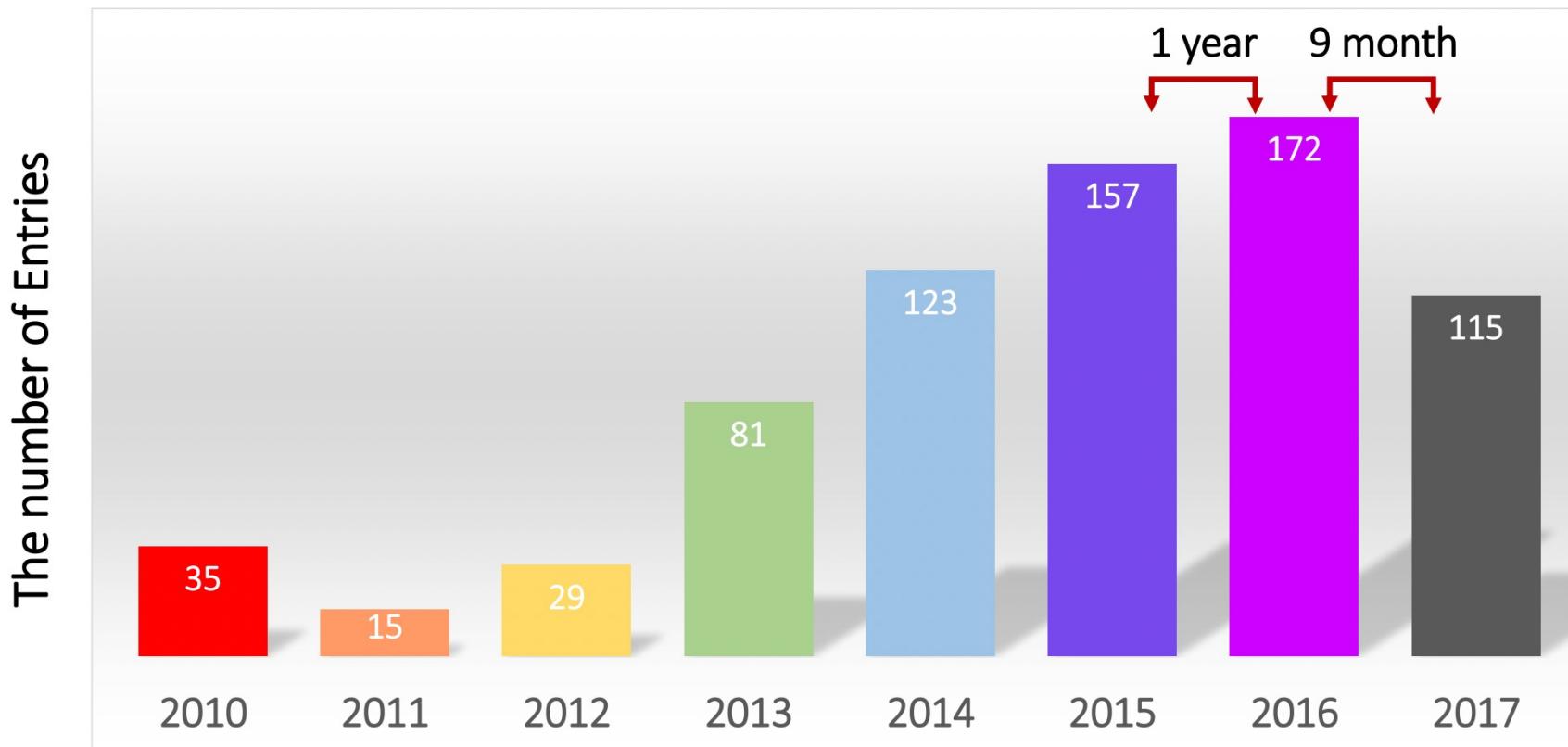
Figure Source: <https://www.edge-ai-vision.com/2018/07/deep-learning-in-five-and-a-half-minutes/>

Rise of “Deep Learning” Following AlexNet



Inspired by AlexNet, many more researchers in the computer vision community proposed neural networks and showed how to make further progress over the years!

Rise of “Deep Learning” Following AlexNet



- 727 entries (plus an entry that famously was kicked out in 2015 for cheating from Baidu)
- Labor cost ~\$110 million: assuming 3 people contribute to each entry and \$50k cost per person

Secret Sauce for State-of-Art: Deeper CNNs

Progress of models on ImageNet (Top 5 Error)

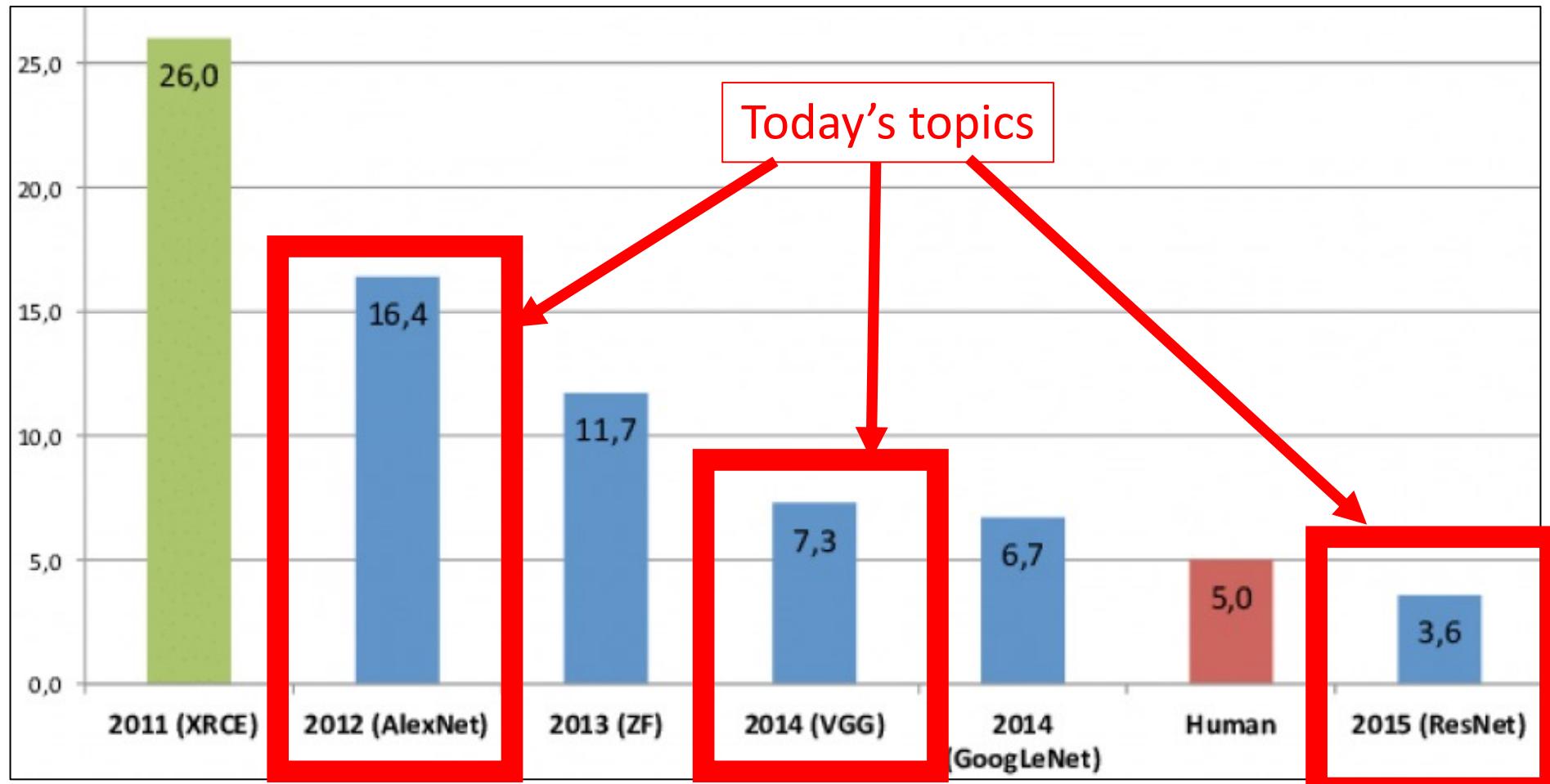
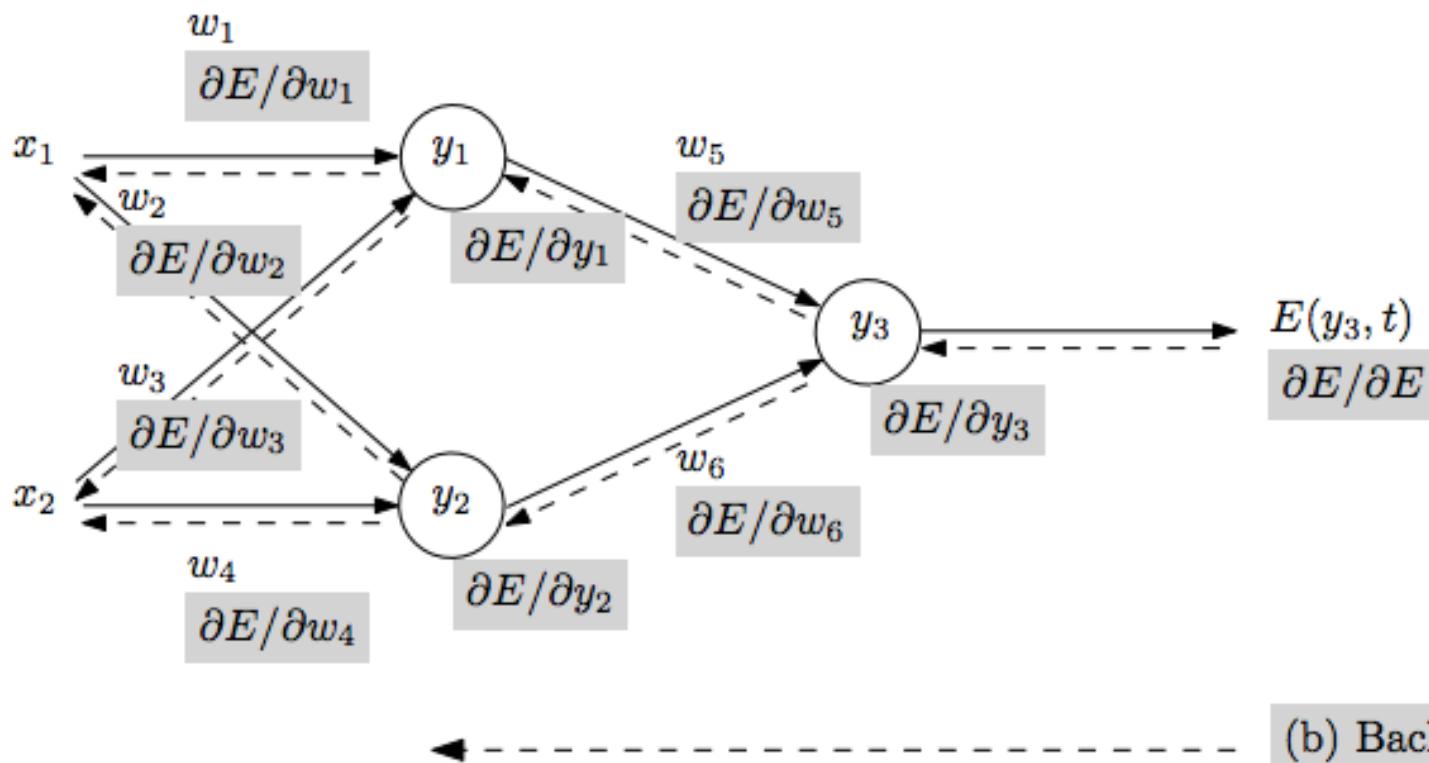


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Why It Is Difficult to Achieve Better Performance with CNNs That Are Deeper: Vanishing Gradients

(a) Forward pass



(b) Backward pass

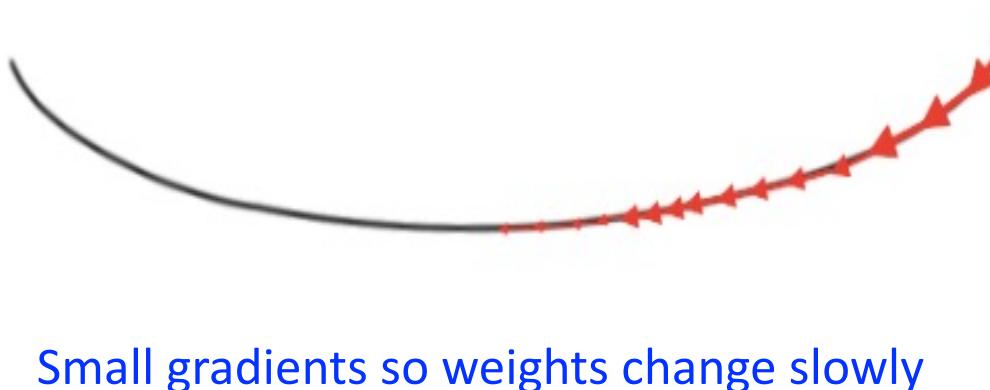
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$$W_x = W_x - \alpha \left(\frac{\partial \text{Error}}{\partial W_x} \right)$$

Figure from: Atilim Gunes Baydin, Barak A. Pearlmutter, Alexey Andreyevich Radul, Jeffrey Mark Siskind; Automatic Differentiation in Machine Learning: a Survey; 2018

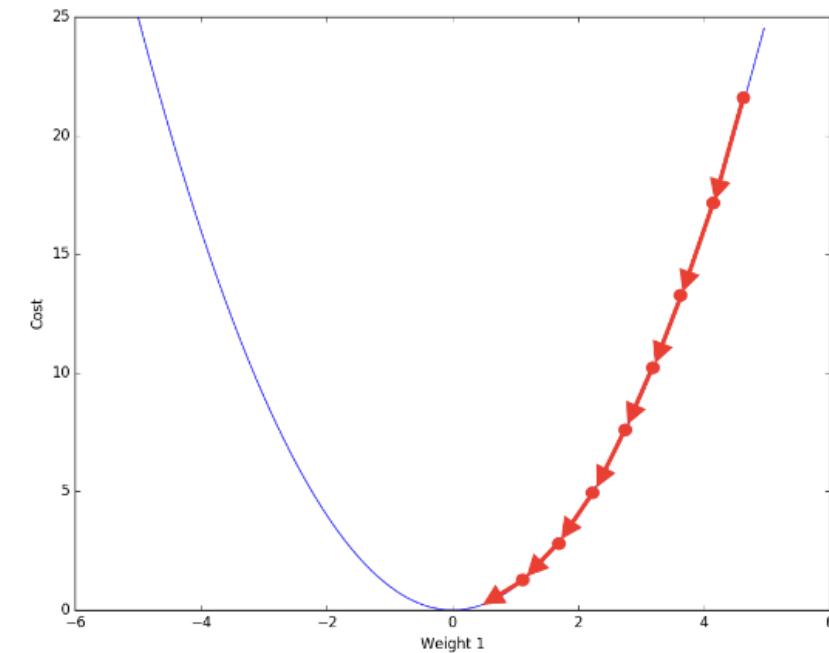
Why It Is Difficult to Achieve Better Performance with CNNs That Are Deeper: Vanishing Gradients

Cost Function 1



Small gradients so weights change slowly

Cost Function 2

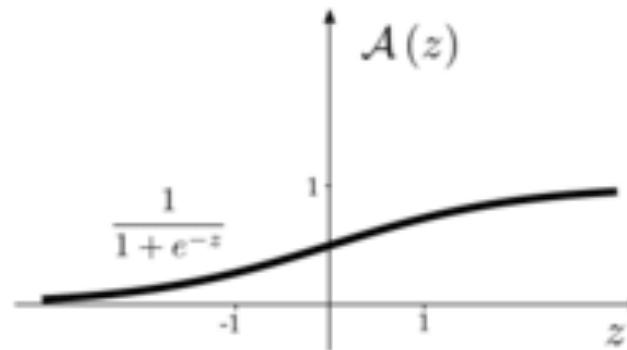


Large gradients so weights change quickly

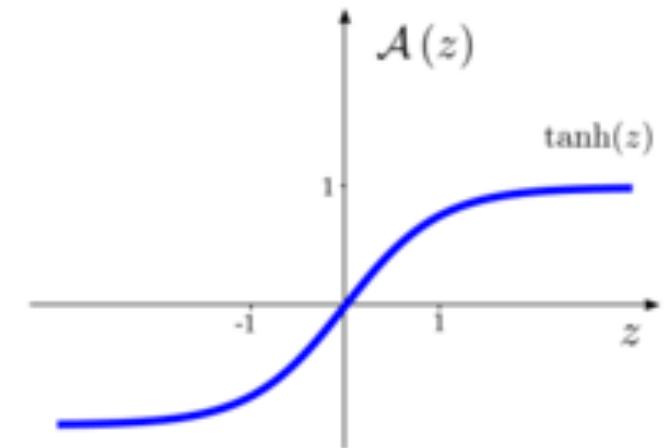
Why It Is Difficult to Achieve Better Performance with CNNs That Are Deeper: Vanishing Gradients

Recall activation functions and their derivatives:

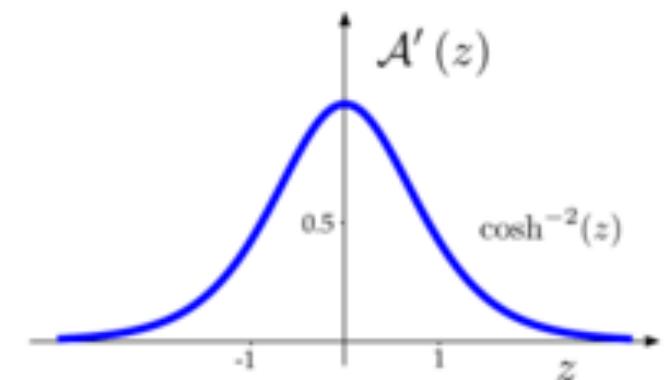
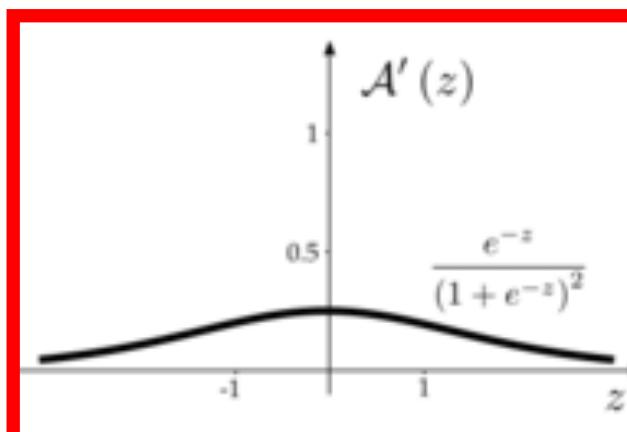
Sigmoid



Tanh

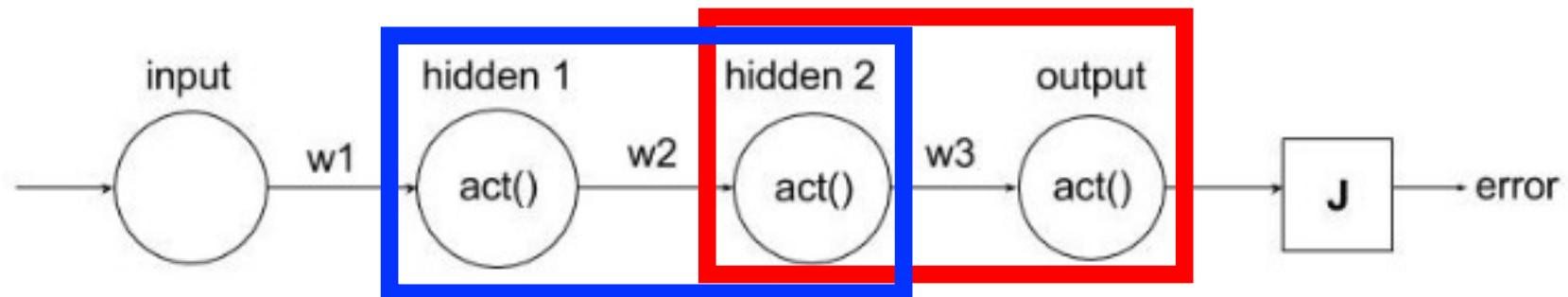


Ranges from 0 to 0.25



Vanishing Gradient Problem (e.g., sigmoid)

- Toy example:



- Error Derivative with respect to weight w1:
- $$\frac{\partial \text{error}}{\partial w1} = \frac{\partial \text{error}}{\partial \text{output}} * \frac{\partial \text{output}}{\partial \text{hidden2}} * \frac{\partial \text{hidden2}}{\partial \text{hidden1}} * \frac{\partial \text{hidden1}}{\partial w1}$$

Derivative of sigmoid activation function: (0 to 1/4)

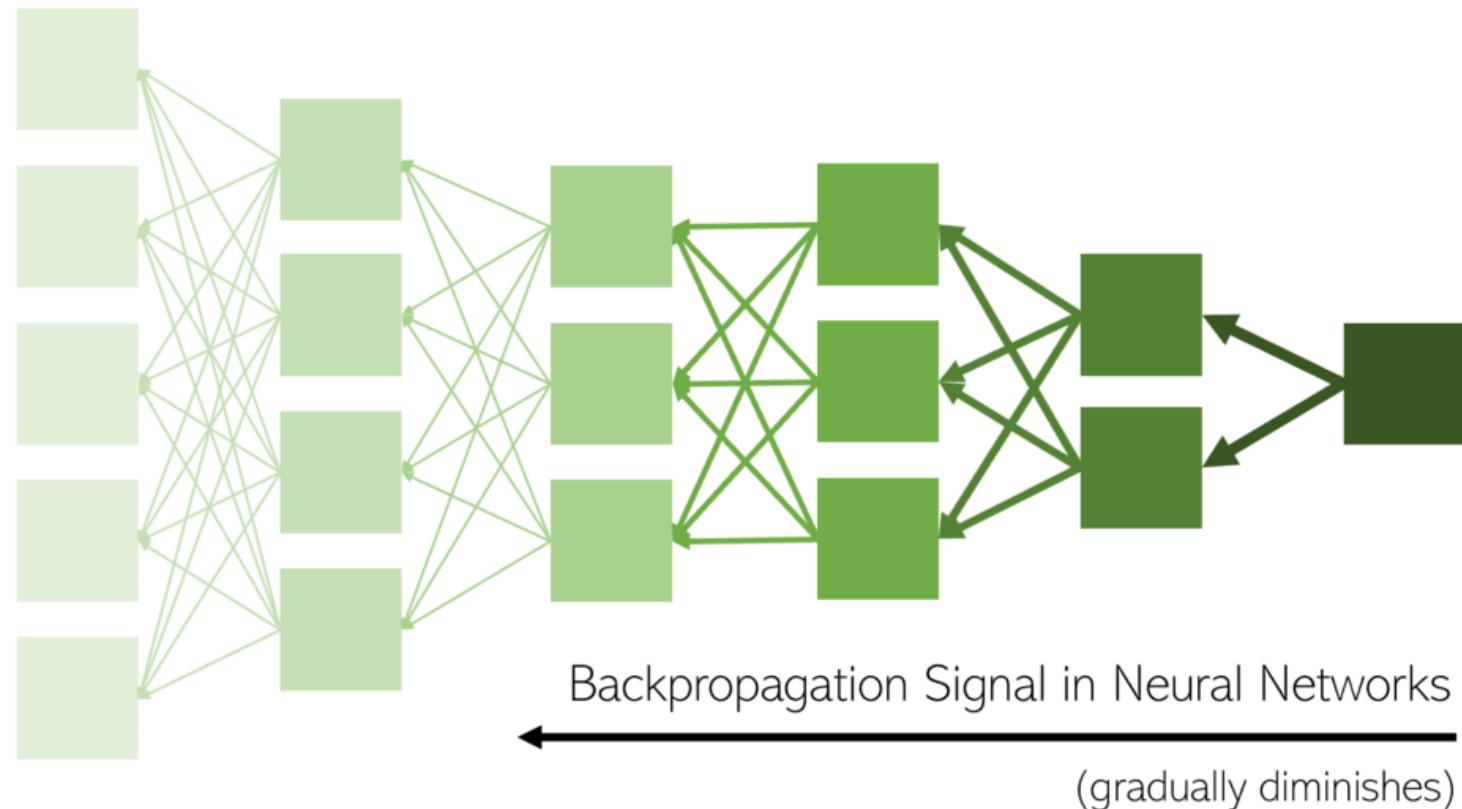
Derivative of sigmoid activation function: (0 to 1/4)

Problem: What happens as you multiply more numbers smaller than 1?

Gradient decreases as further from the last layer... and so weights barely change at training!

Vanishing Gradient Problem (e.g., sigmoid)

Smallest gradients at **earliest layers** make them **slowest to train**, yet later layers depend on those earlier layers to do something useful; consequently, NNs struggle with garbage in means garbage out



How can we avoid the vanishing gradient problem?

AlexNet: A Deeper CNN

Progress of models on ImageNet (Top 5 Error)

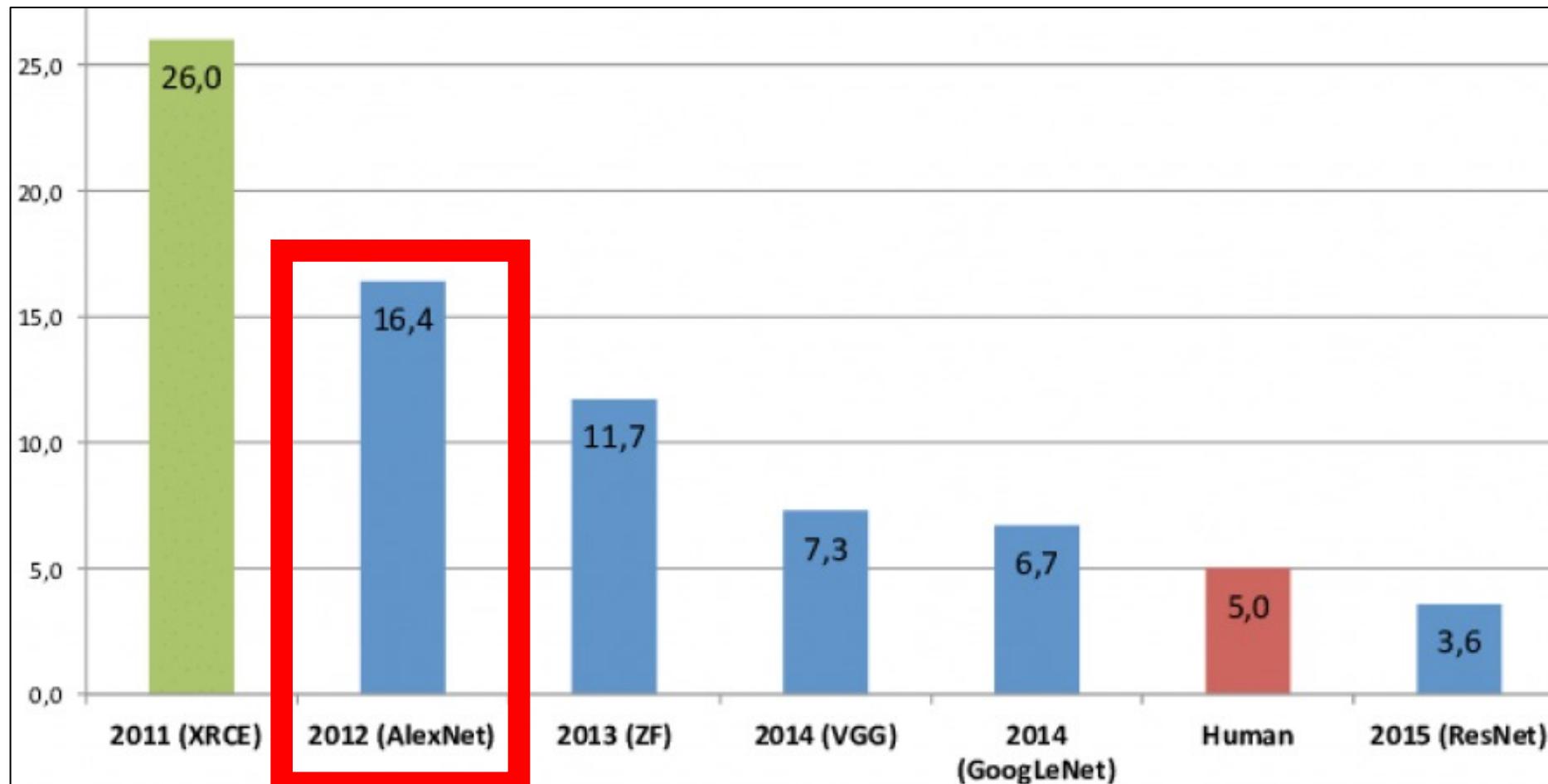
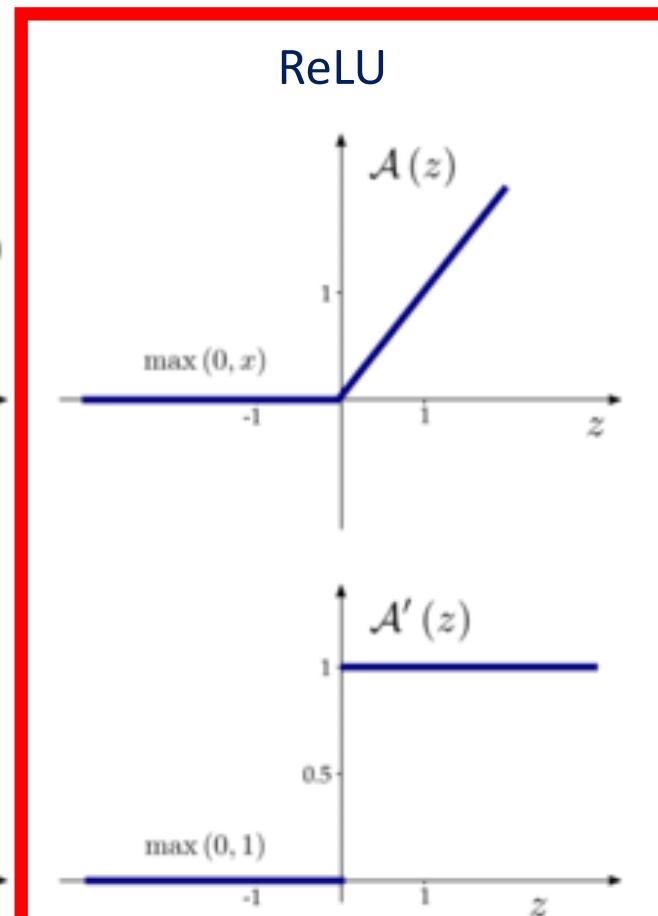
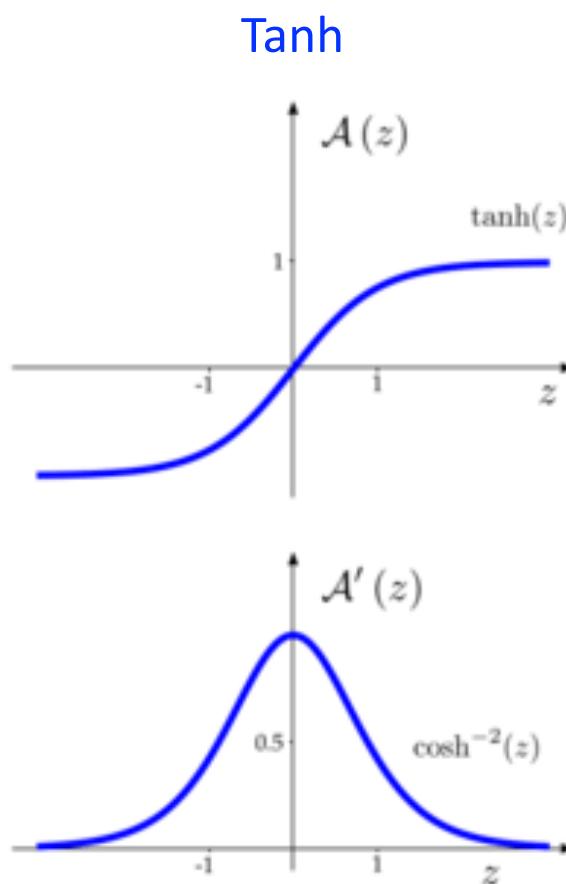
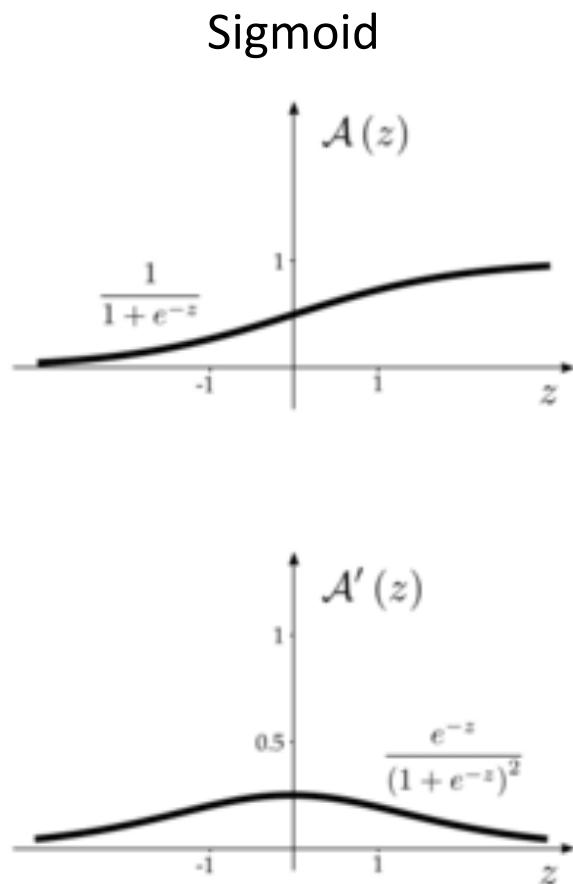


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Key Idea: Non-Saturating Activation Functions

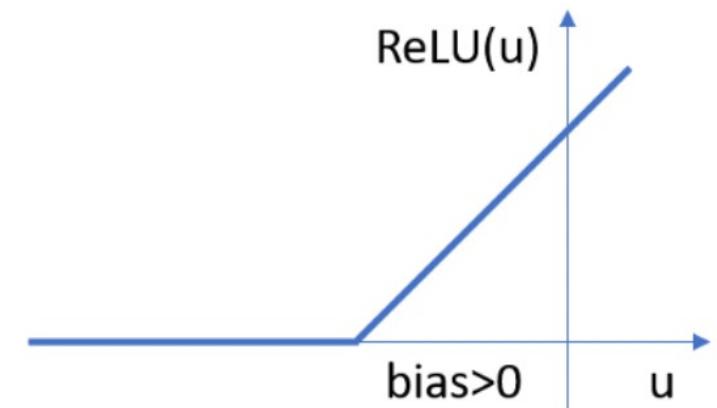
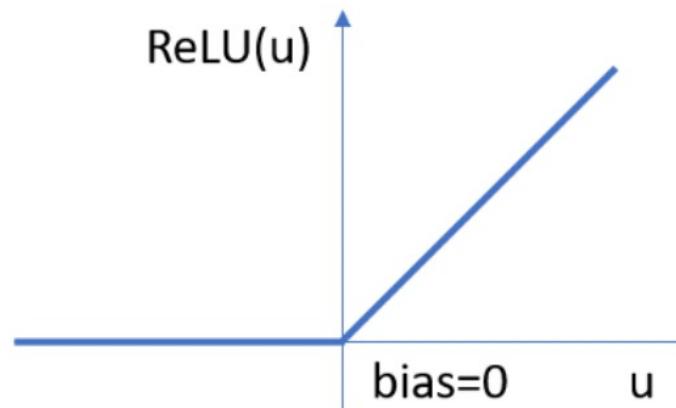
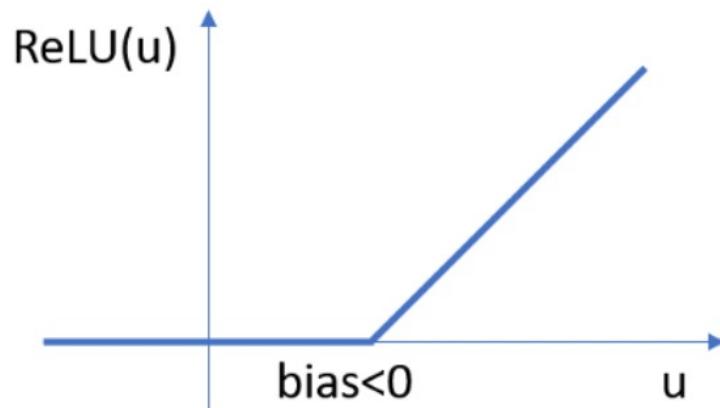
Use activation functions with derivative value equal to 1 (i.e., $1 \times 1 \times 1 \dots$ doesn't vanish)



- Benefits:
- Can preserve gradient
 - Fast to compute
 - “Dying neurons” contribute to network sparsity and so reduced model complexity

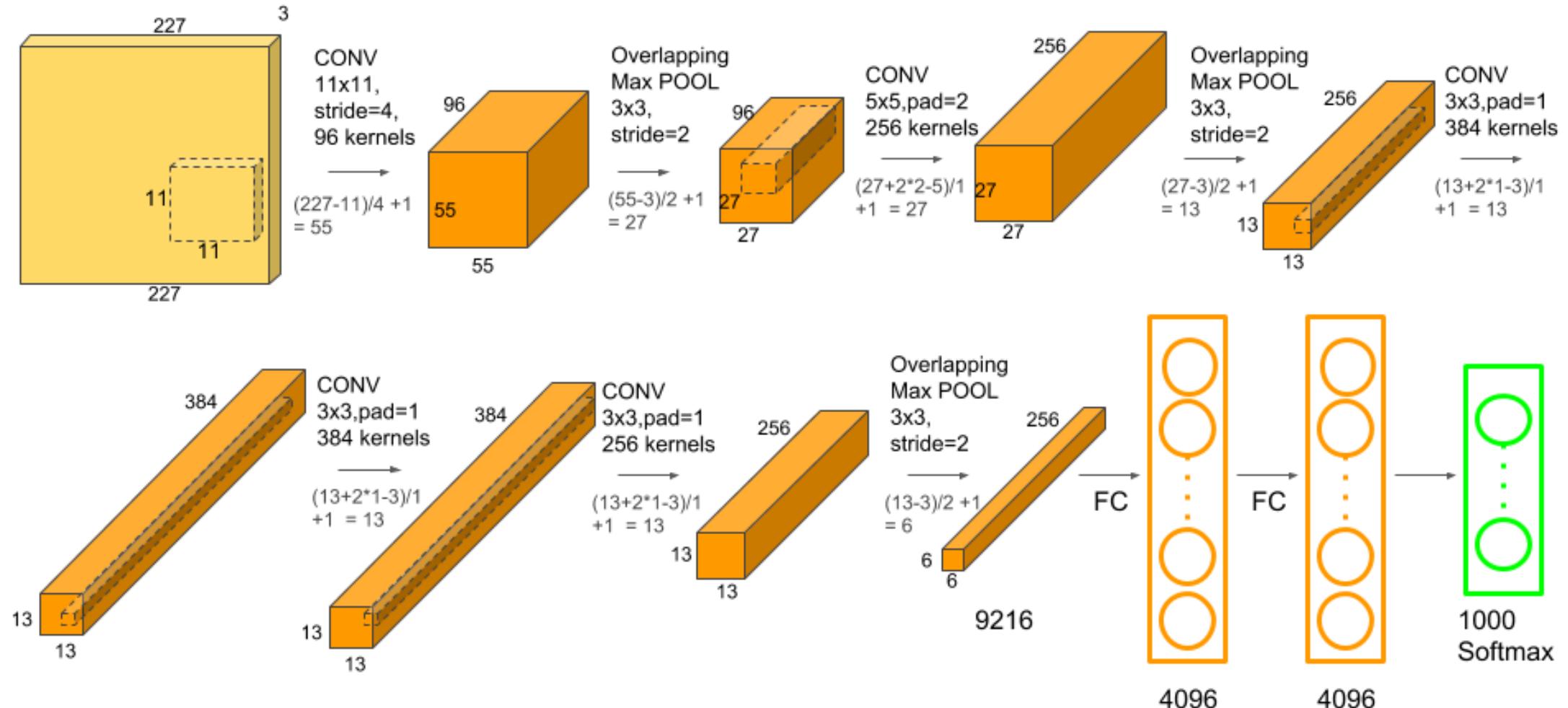
Key Idea: Non-Saturating Activation Functions

- Influence of bias term with ReLU



- What is the impact of a positive bias value?
- What is the impact of a negative bias value?

AlexNet Architecture: Similar to LeNet But With More Convolutional and Pooling Layers



AlexNet Architecture

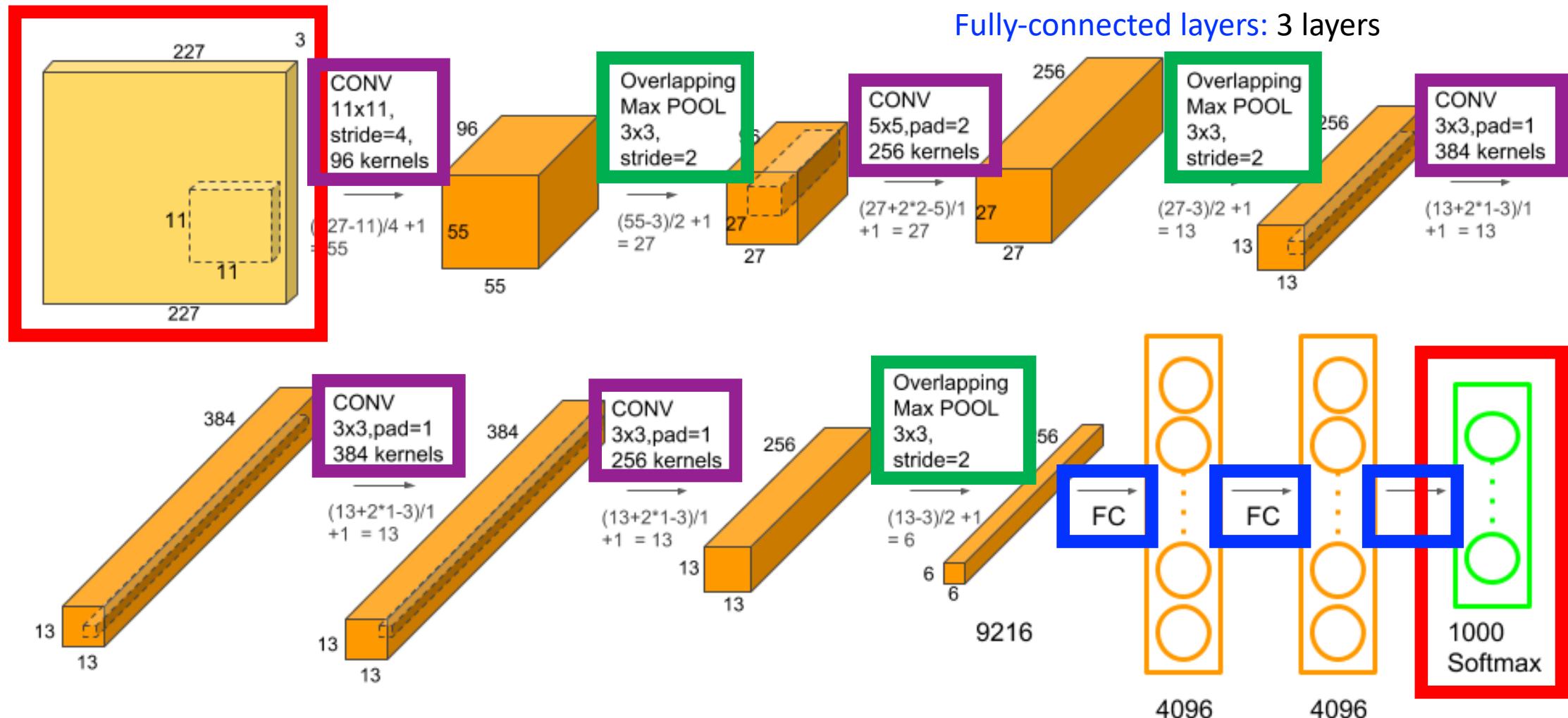
Input: RGB image resized to fixed input size

Output: 1000 class probabilities (sums to 1)

Convolutional layers: 5 layers

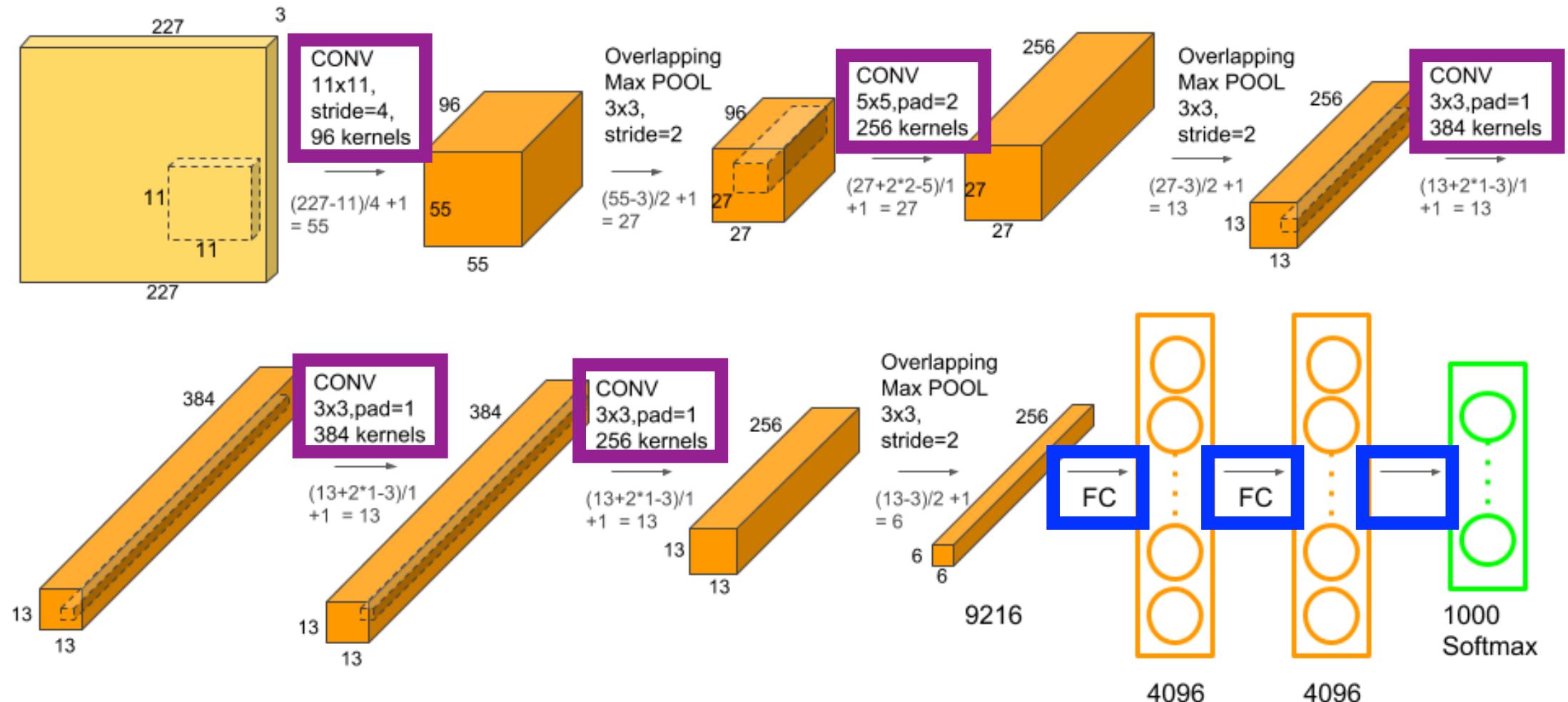
Pooling Layers: 3 layers

Fully-connected layers: 3 layers



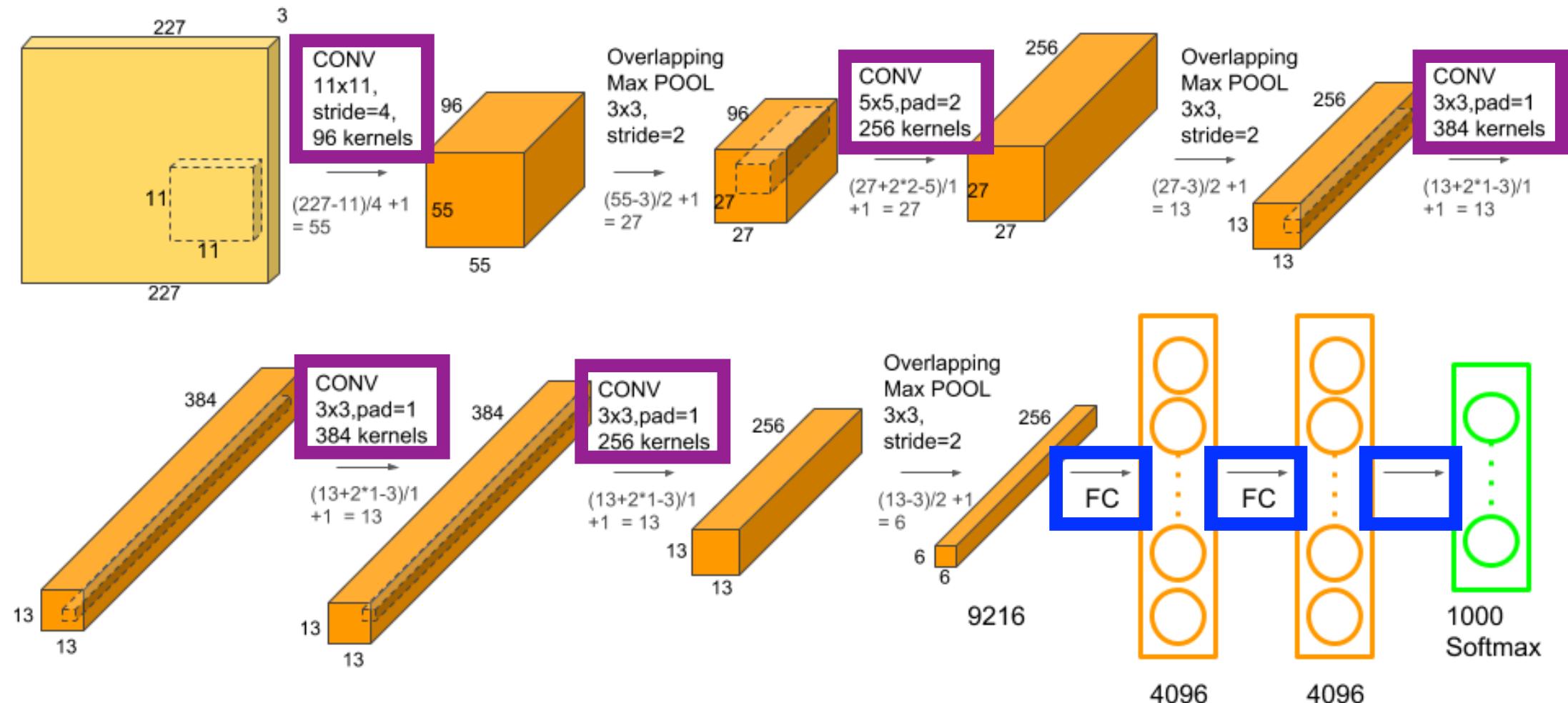
AlexNet Architecture

How many layers have model parameters that need to be learned?

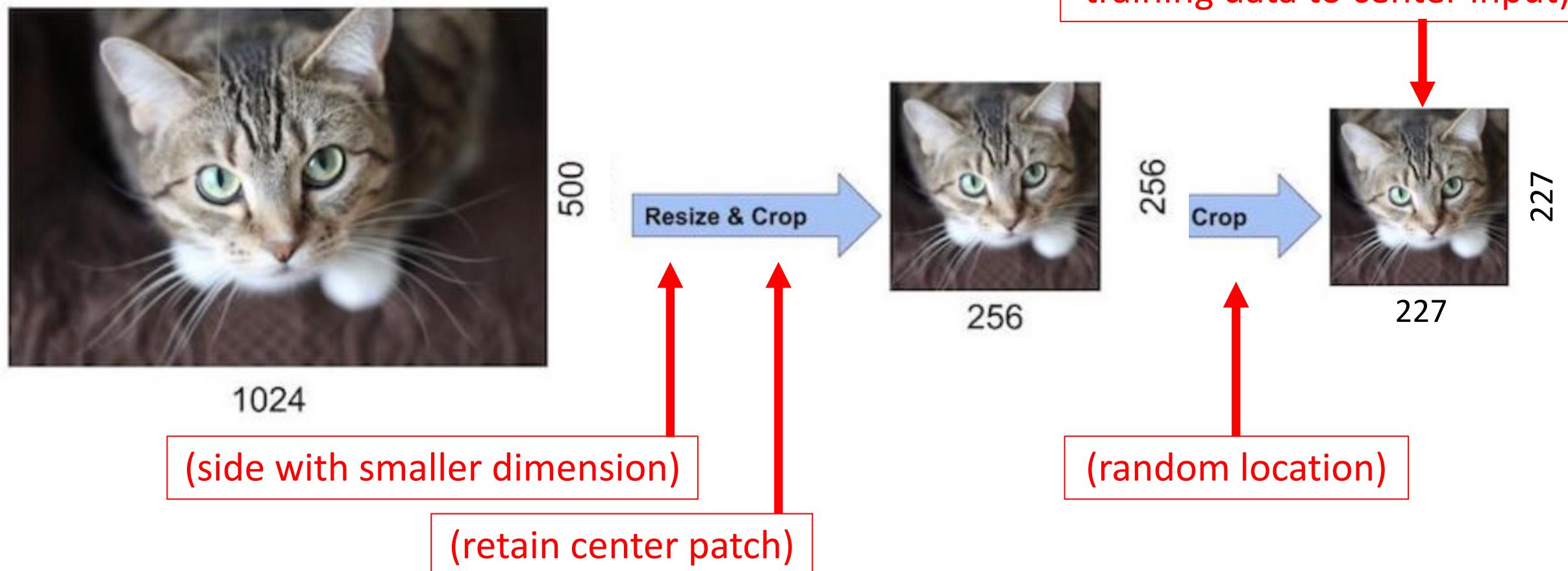


AlexNet Architecture

Altogether, 60 million model parameters must be learned!

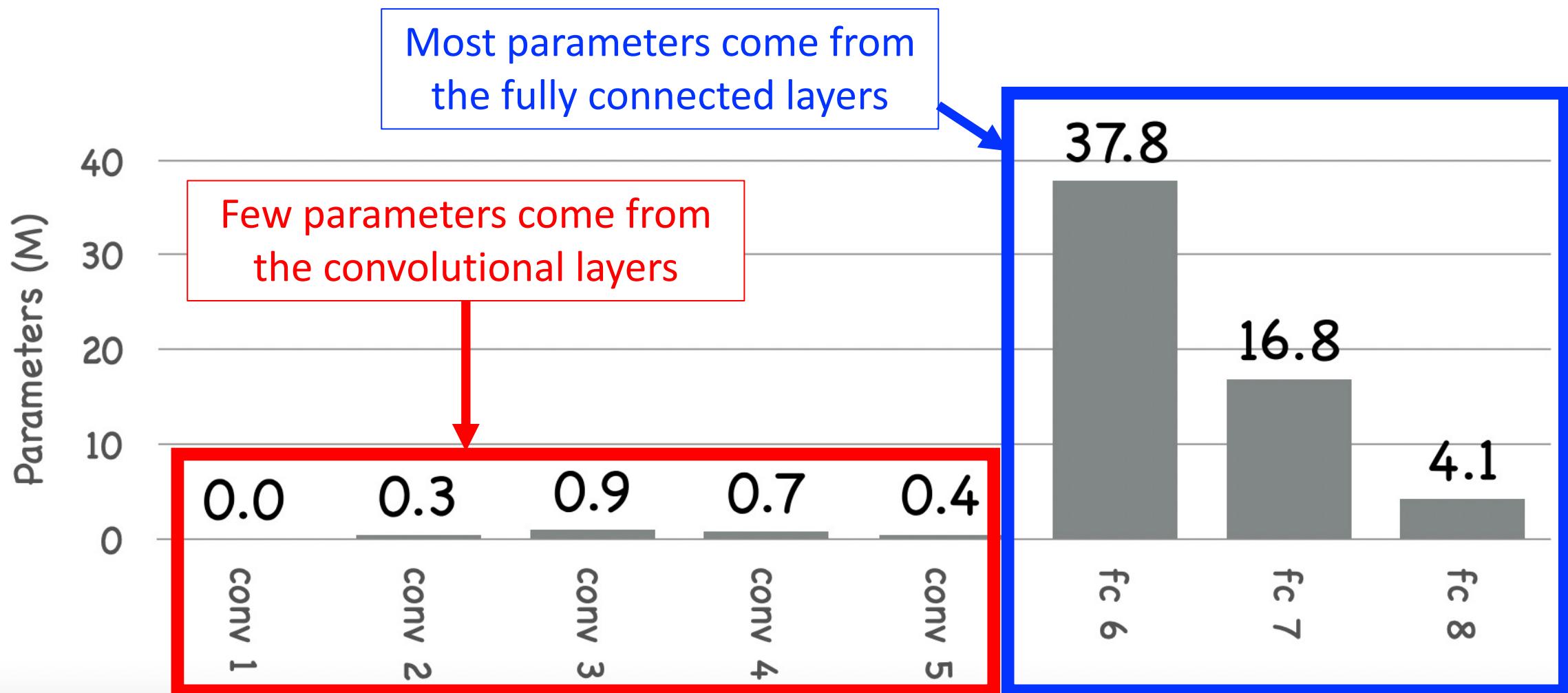


Implementation Detail: Input Preprocessing



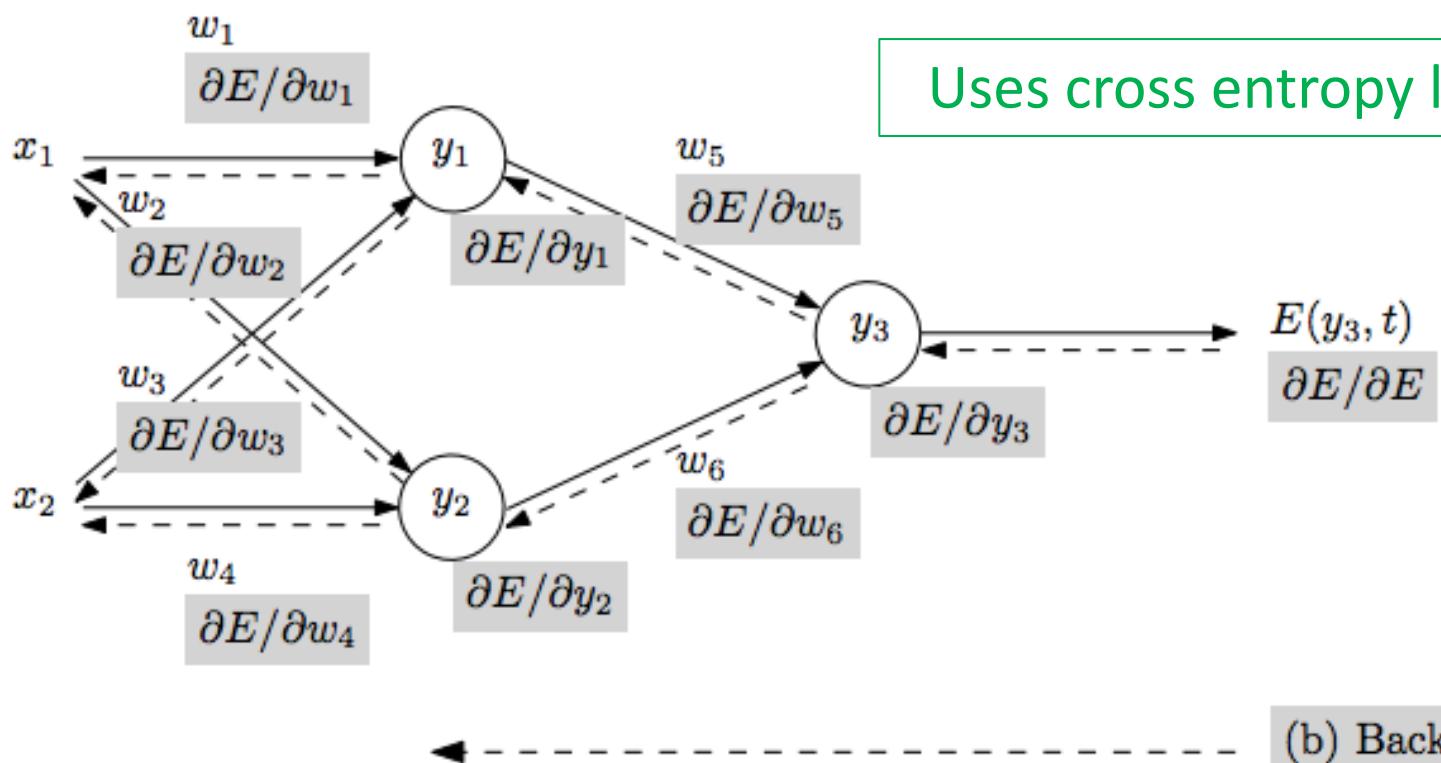
AlexNet Architecture

Altogether, 60 million model parameters must be learned!



AlexNet Training: 90 Epochs

(a) Forward pass



- Repeat until stopping criterion met:

1. **Forward pass:** propagate training data through model to make prediction
2. Quantify the dissatisfaction with a model's results on the training data
3. **Backward pass:** using predicted output, calculate gradients backward to assign blame to each model parameter
4. Update each parameter using calculated gradients

Figure from: Atilim Gunes Baydin, Barak A. Pearlmutter, Alexey Andreyevich Radul, Jeffrey Mark Siskind; Automatic Differentiation in Machine Learning: a Survey; 2018

AlexNet: Key Tricks for Going Deeper

- ReLU instead of sigmoid or tanh activation functions
- Regularization techniques: to be covered next lecture
 1. Data augmentation
 2. Dropout in fully connected layers
 3. L2 parameter norm penalty
- Trained across two GPUs

AlexNet Analysis

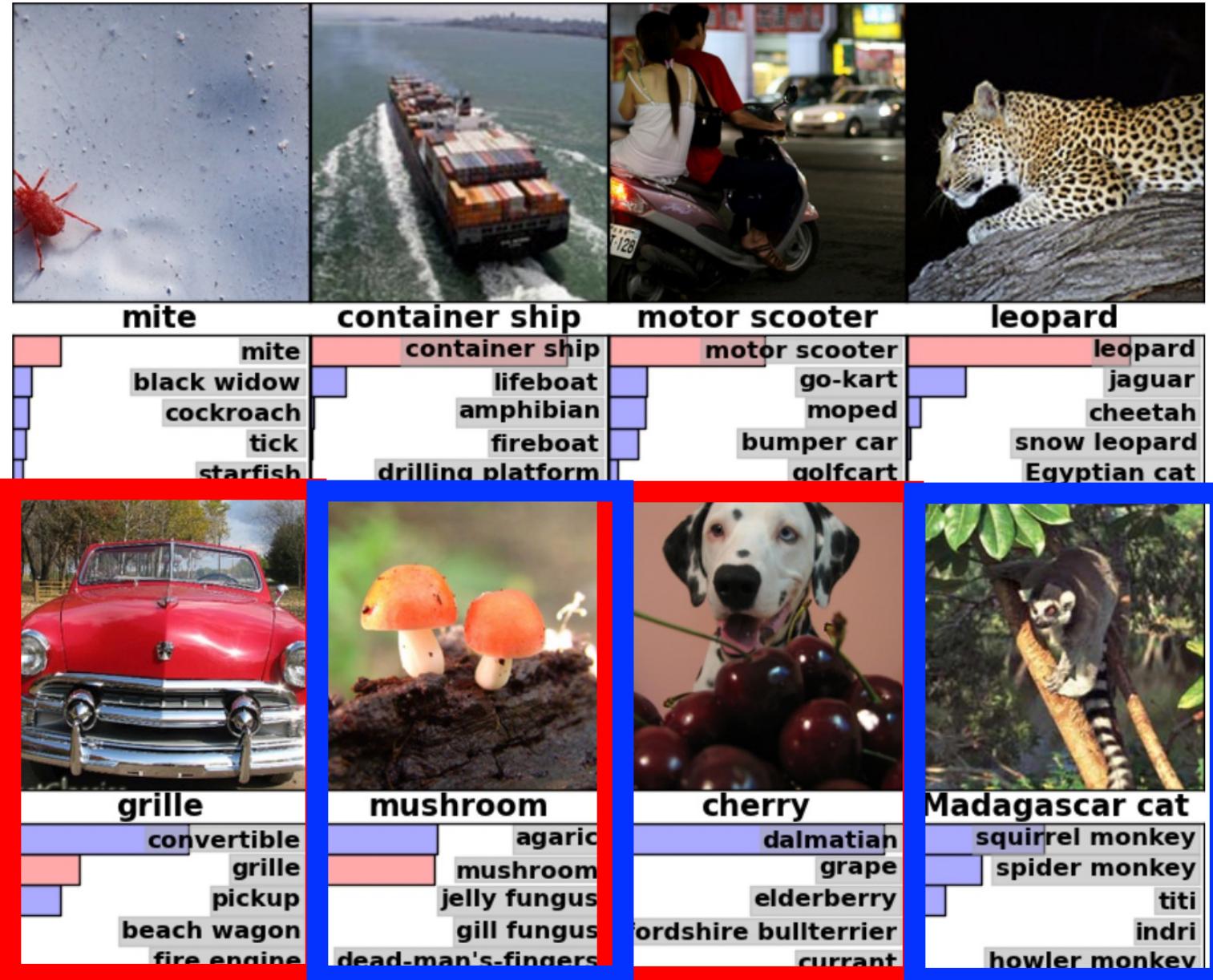
8 examples of predictions,
correct and incorrect

When/why might the model
succeed?

- Single well-defined object
(even if off-centered)

When/why might the model
fail?

- Ambiguity
- Similar categories



VGG: A Deeper CNN

Progress of models on ImageNet (Top 5 Error)

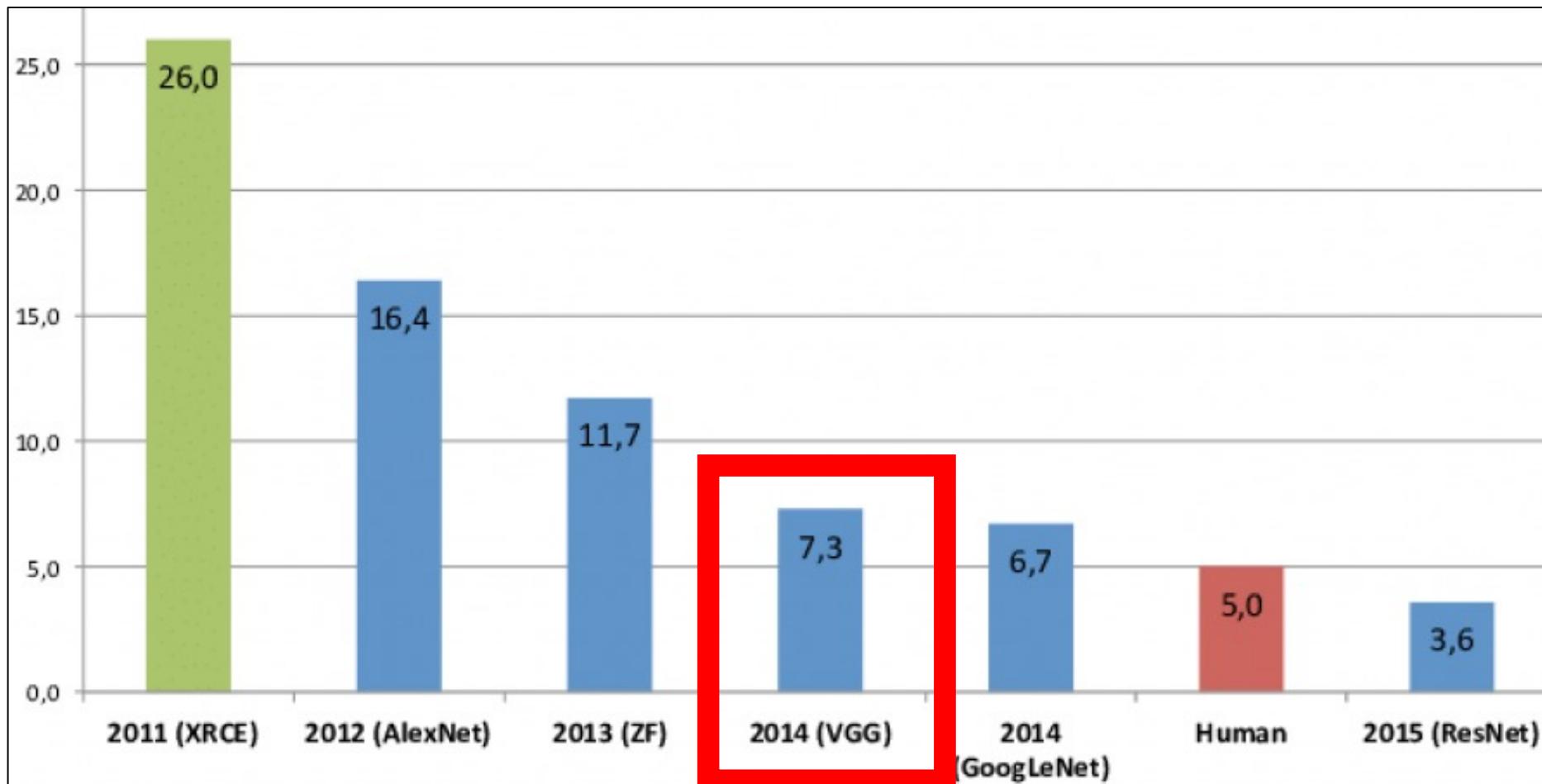


Figure Source: <https://www.edge-ai-vision.com/2018/07/deep-learning-in-five-and-a-half-minutes/>

Key Novelty: Deeper Does Better

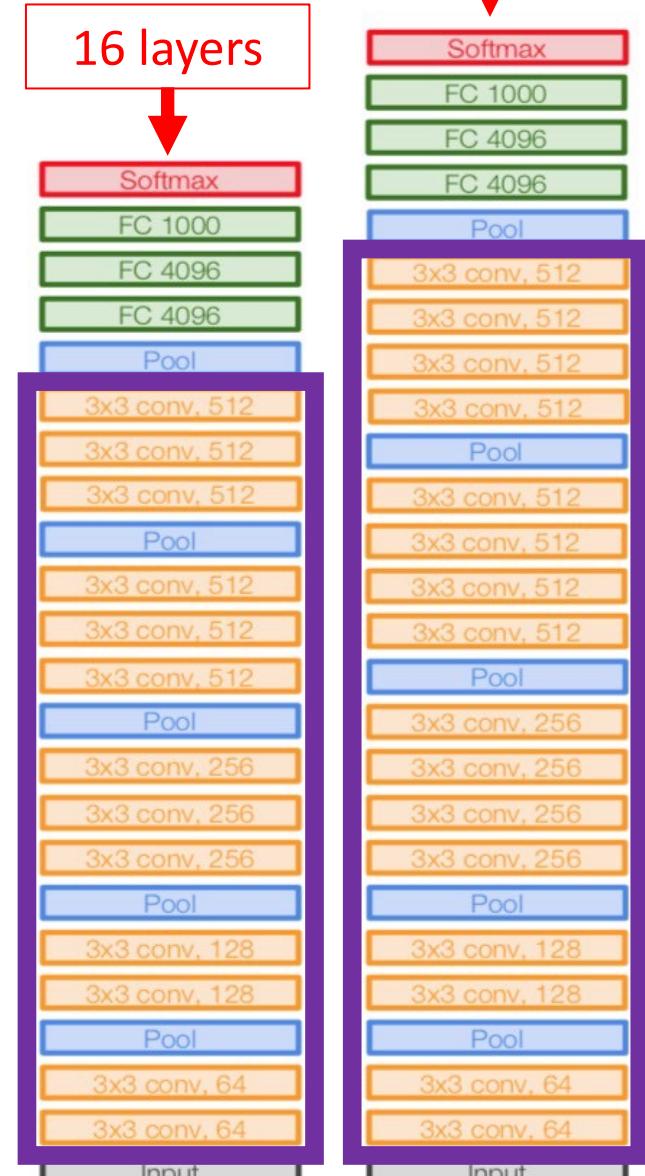
* Number of layers with learnable model parameters between input and output layer (i.e., exclude pooling layers)

Layers with differences



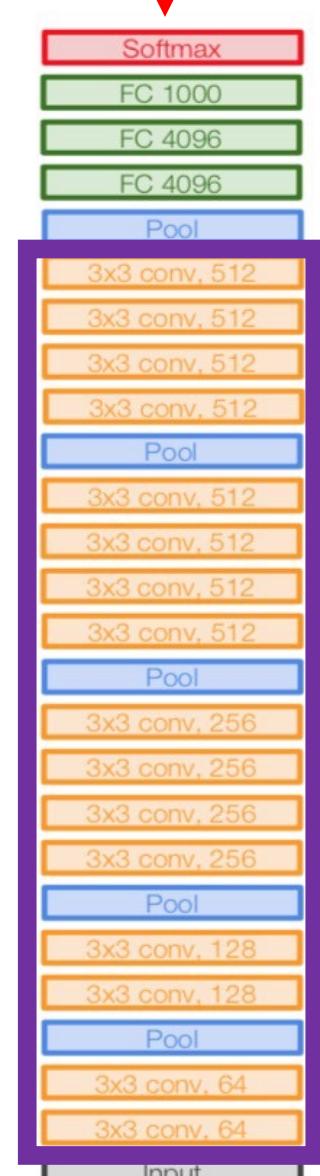
AlexNet

16 layers



VGG16

19 layers



VGG19

Key Idea: Smaller Convolutional Filters

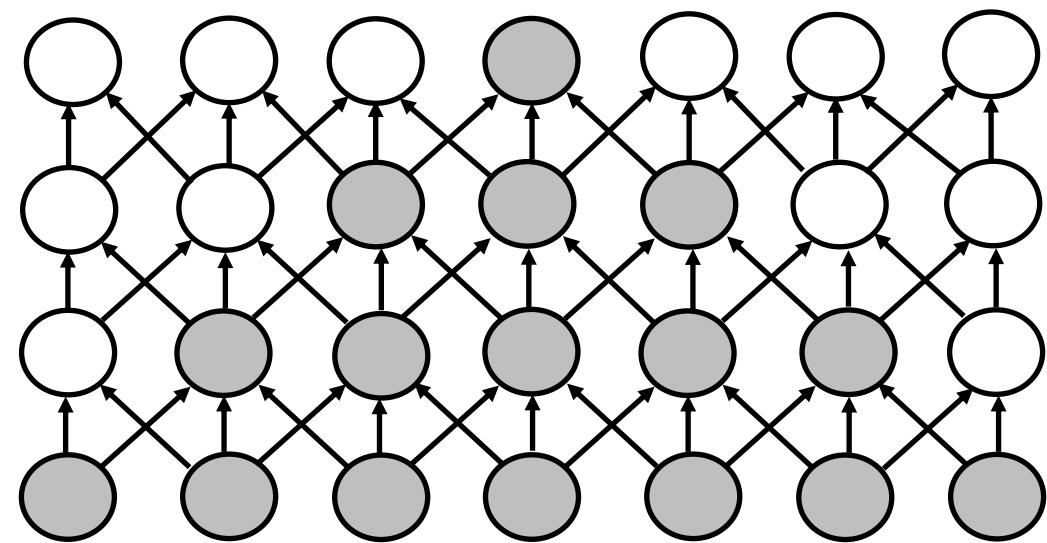
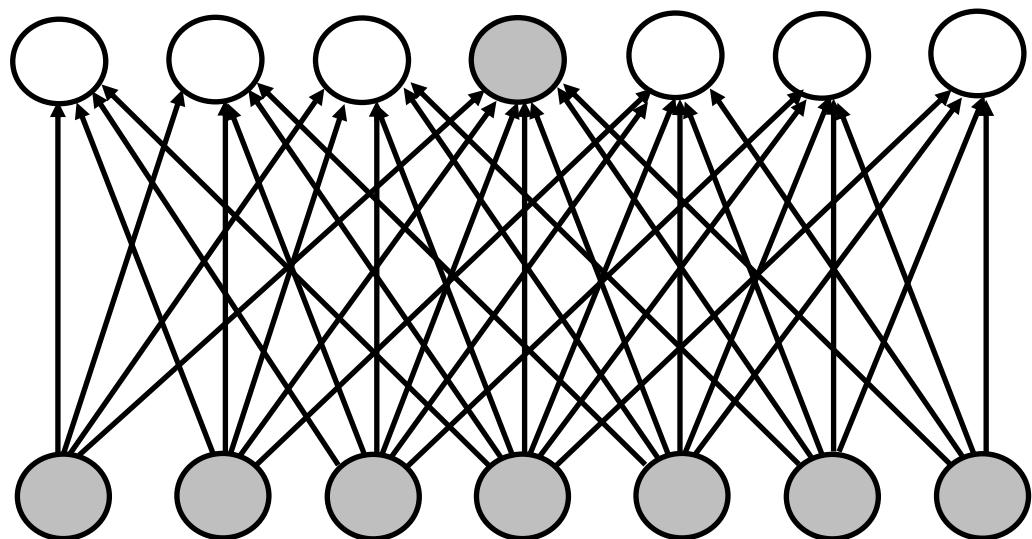
- Replace larger filter with stack of smaller filters



Figure Source (edited to fix mistakes): <https://medium.com/deep-learning-g/cnn-architectures-vggnet-e09d7fe79c45>

Key Idea: Smaller Convolutional Filters

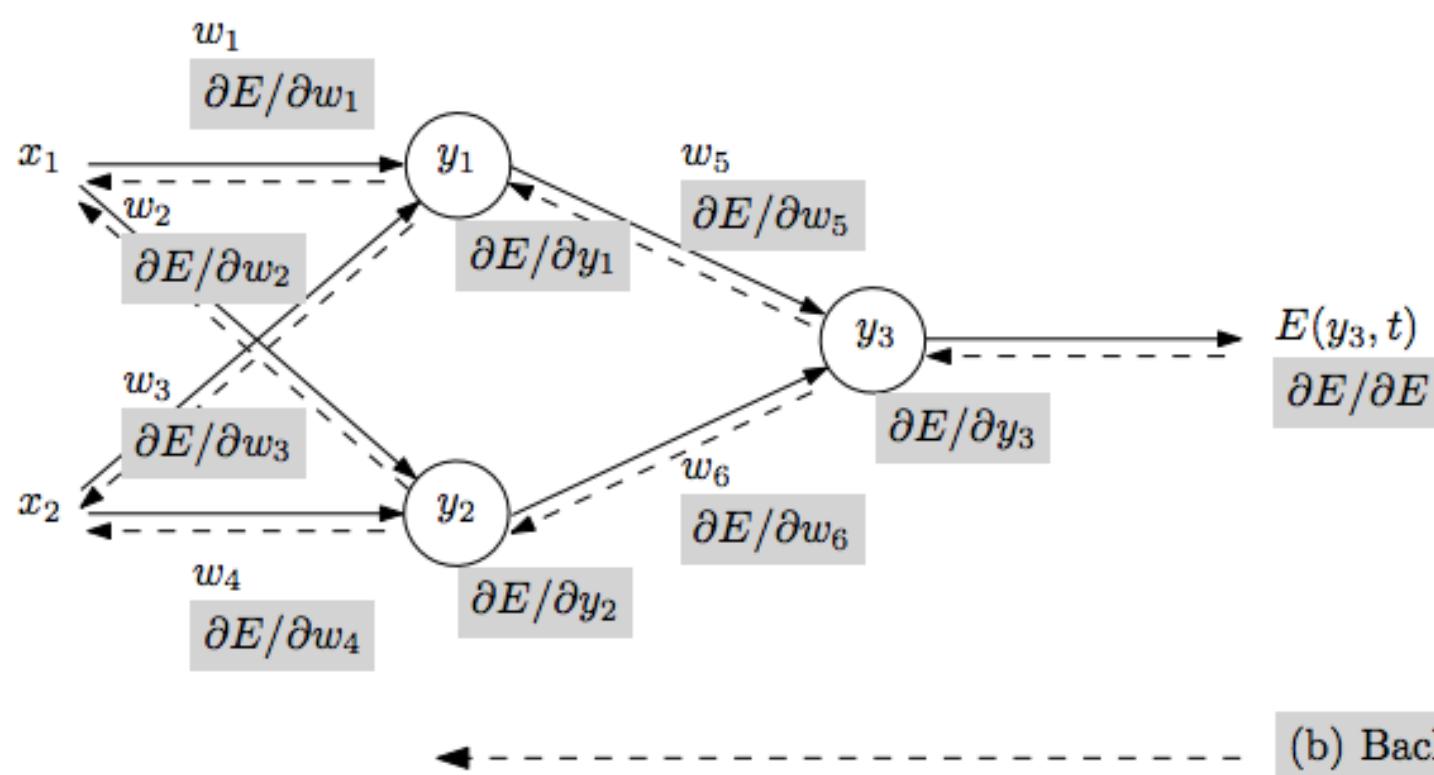
- Replace larger filter with stack of smaller filters; e.g., replace 7×7 with three 3×3 s



- Benefits:
 - More discriminative classifier since more non-linear rectifications: 3 vs 1
 - Reduces # of parameters: multiple of 27 (3×3^2) parameters vs 49 (7×7) parameters

VGG Training (follows AlexNet): 74 Epochs

(a) Forward pass



(b) Backward pass

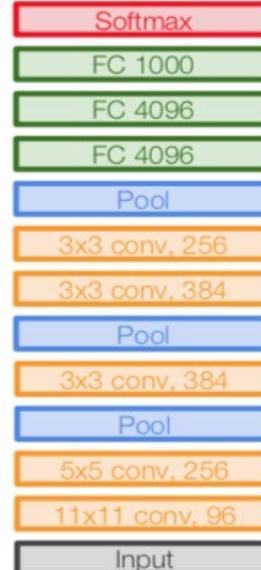
- Repeat until stopping criterion met:
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 4. Update each parameter using calculated gradients

$$W_x = W_x - \alpha \left(\frac{\partial Error}{\partial W_x} \right)$$

Figure from: Atilim Gunes Baydin, Barak A. Pearlmutter, Alexey Andreyevich Radul, Jeffrey Mark Siskind; Automatic Differentiation in Machine Learning: a Survey; 2018

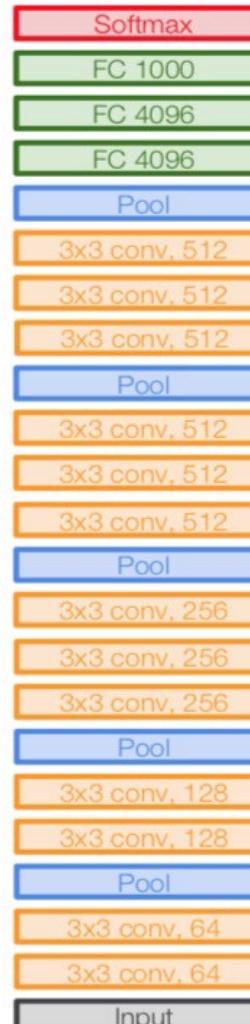
VGG Limitation: Models Are Large!

60 million parameters



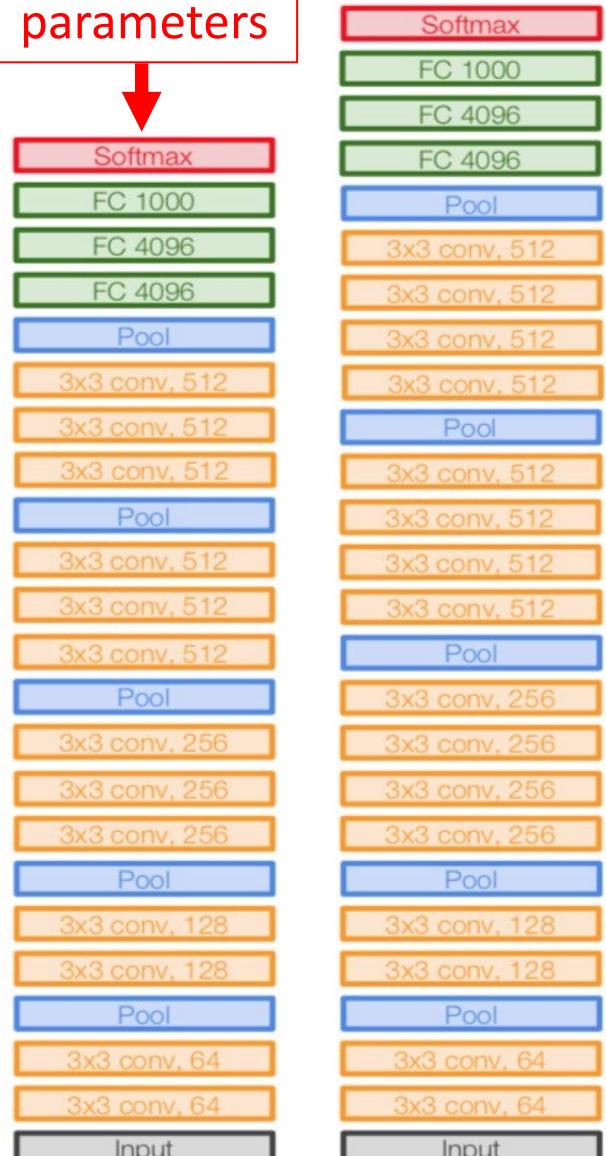
AlexNet

138 million parameters



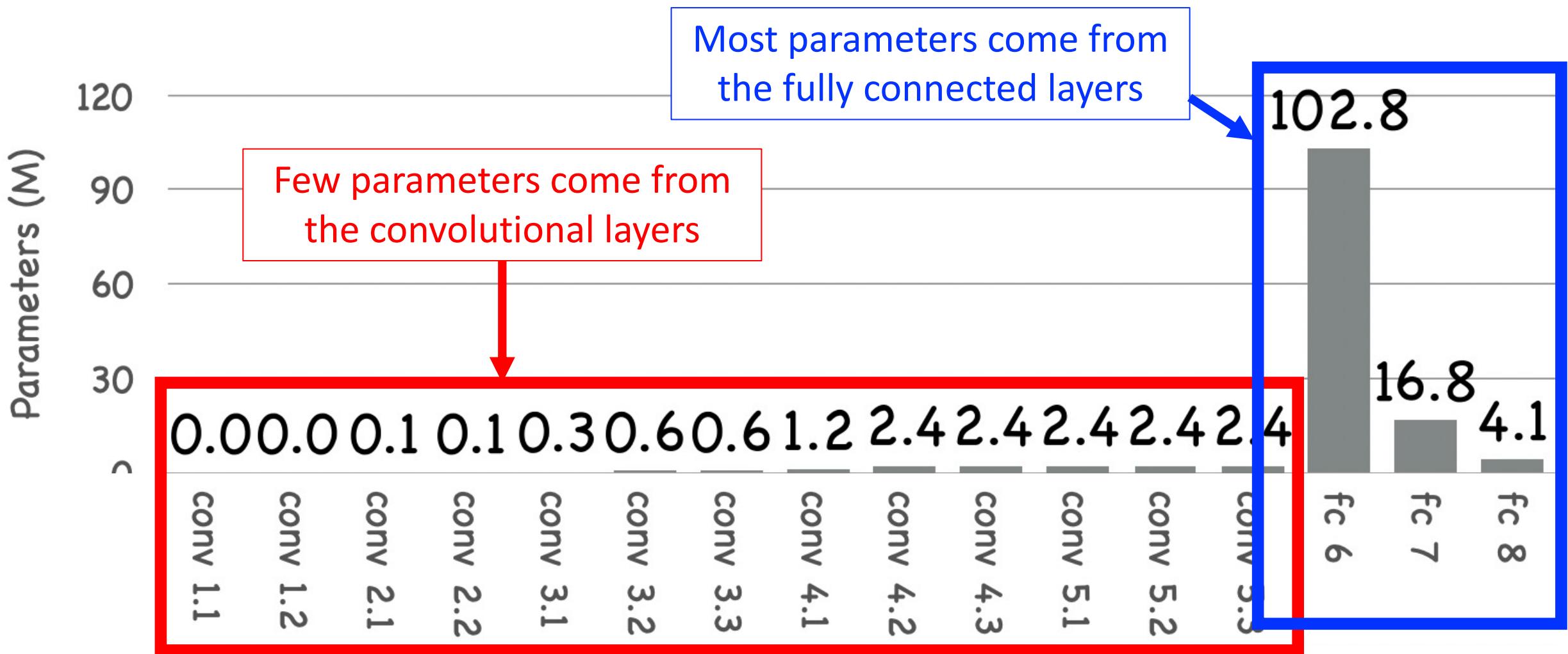
VGG16

144 million parameters



VGG19

VGG Limitation: Models Are Large (e.g., VGG16)



VGG: Key Tricks for Going Deeper

- 3x3 filters instead of larger filters
- Regularization techniques: to be covered next lecture
 1. Data augmentation
 2. Dropout in fully connected layers
 3. L2 parameter norm penalty
- Trained across multiple GPUs

ResNet: A Deeper CNN

Progress of models on ImageNet (Top 5 Error)

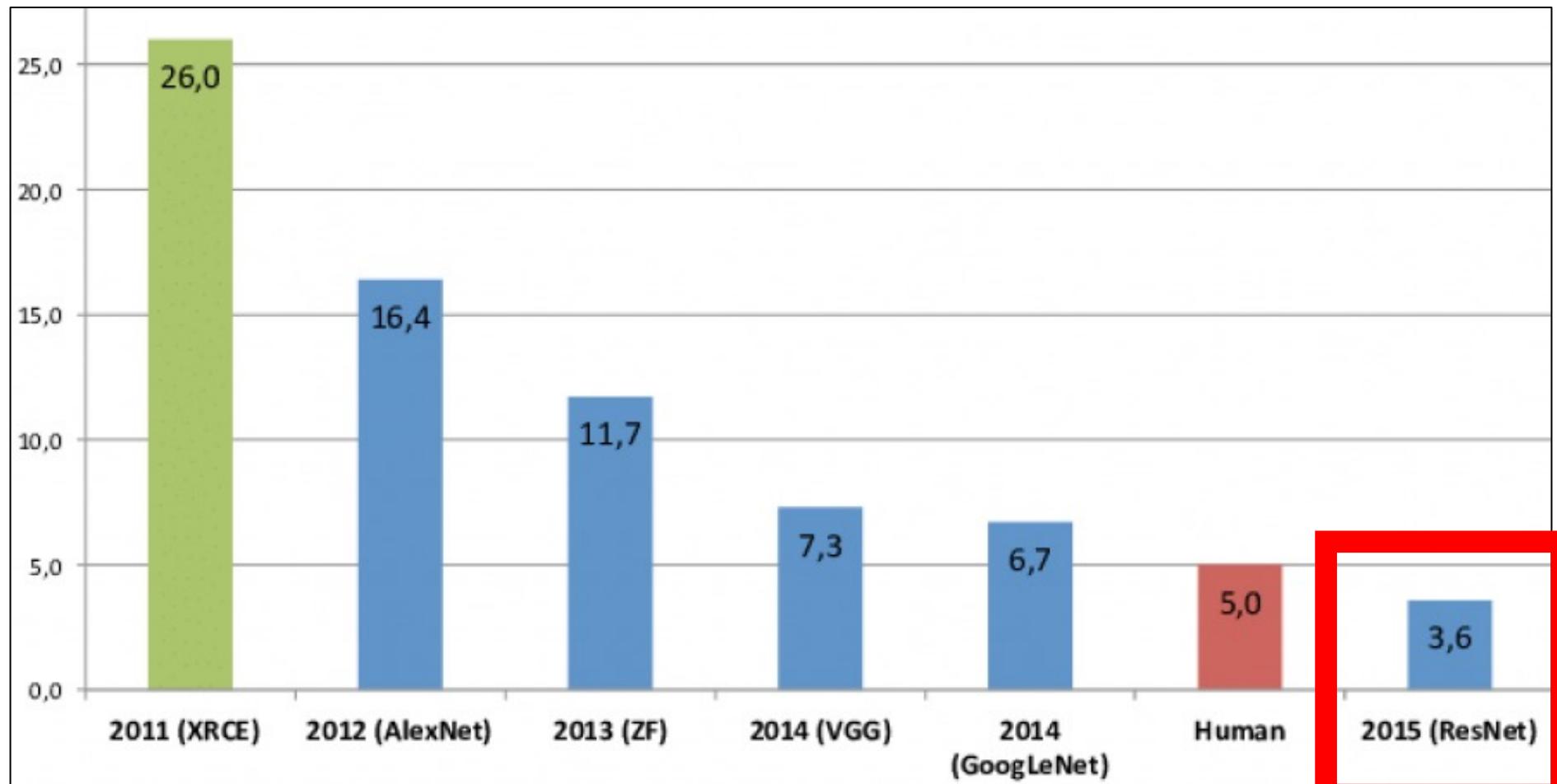


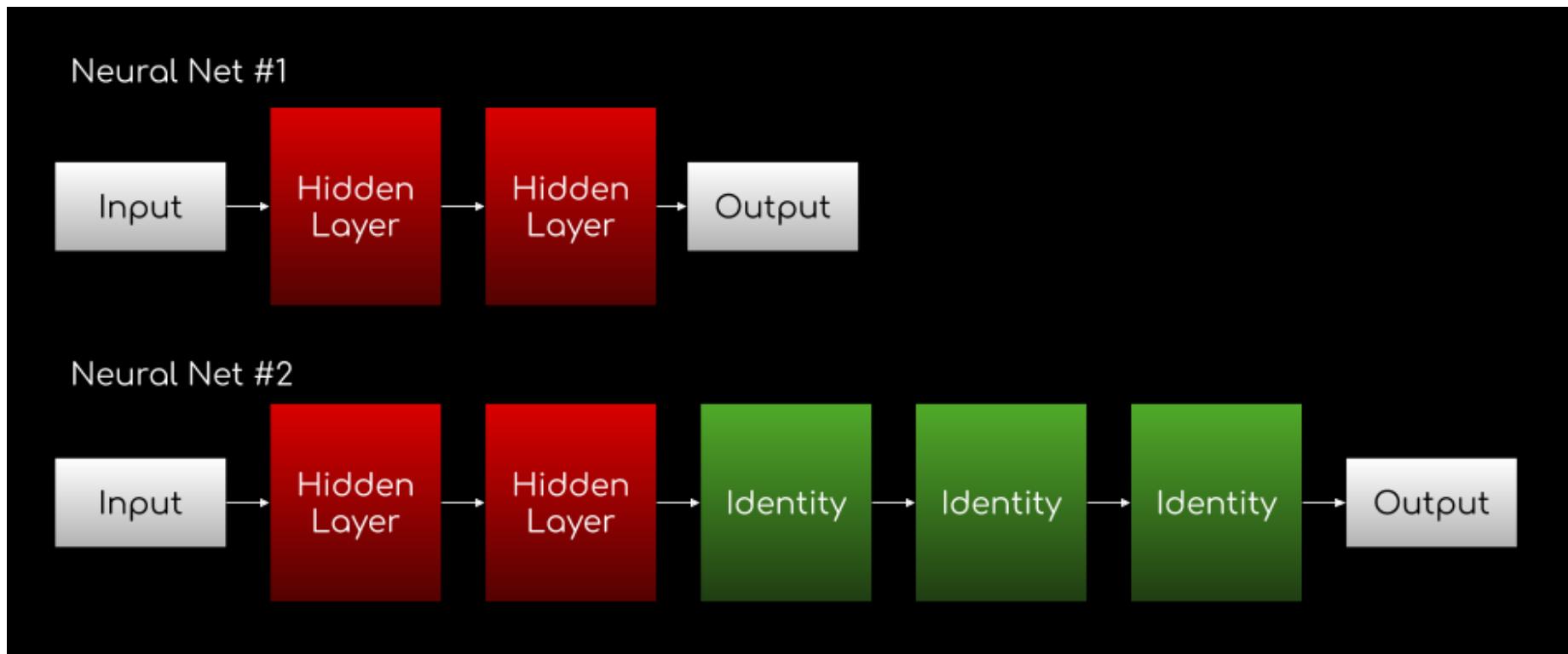
Figure Source: <https://www.edge-ai-vision.com/2018/07/deep-learning-in-five-and-a-half-minutes/>

Motivating Observation

Idea: a deeper network should perform as good if not better than shallower networks since they can learn the shallower function by simply learning “identity” functions for later layers

Observation: adding more layers leads to WORSE results!

Is the problem overfitting?

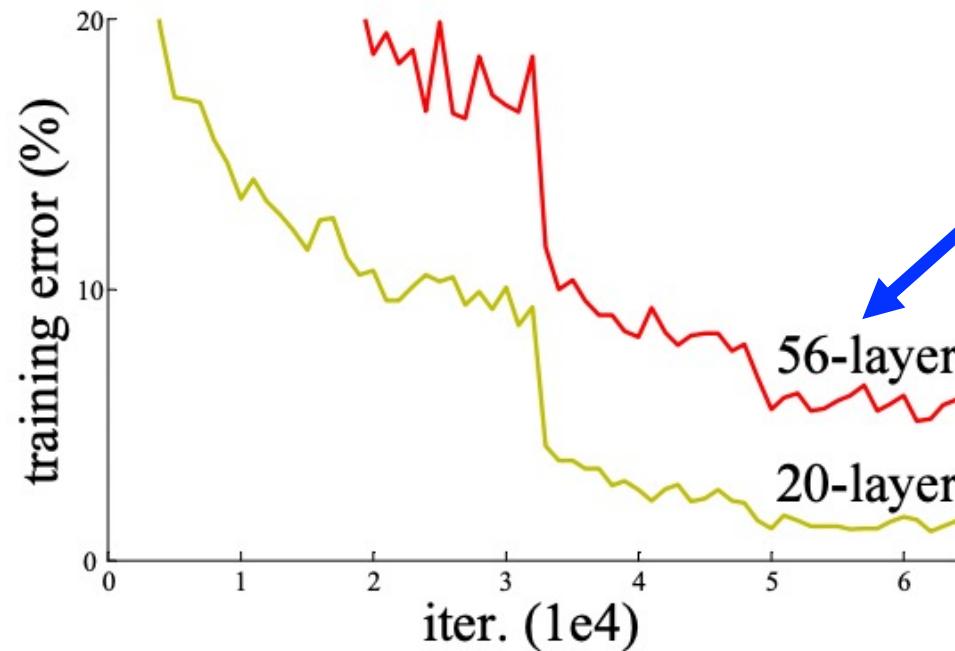


Motivating Observation

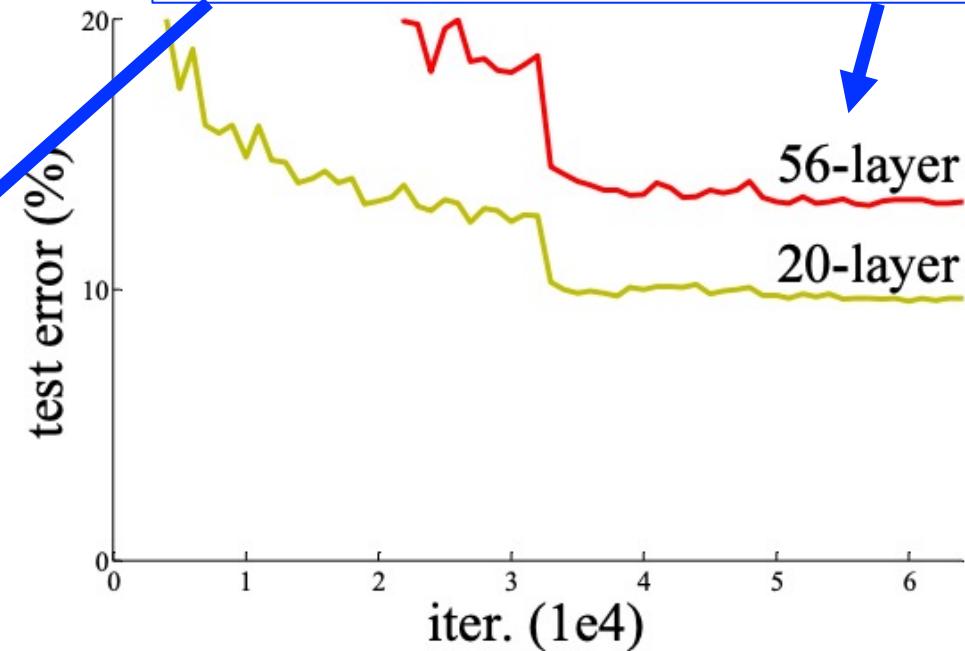
Idea: a deeper network should perform as good if not better than shallower networks since they can learn the shallower function by simply learning “identity” functions for later layers

Observation: adding more layers leads to WORSE results!

Is the problem overfitting? **NO**



Training data error (and test error)
is greater with more layers



Motivating Observation

Idea: a deeper network should perform as good if not better than shallower networks since they can learn the shallower function by simply learning “identity” functions for later layers

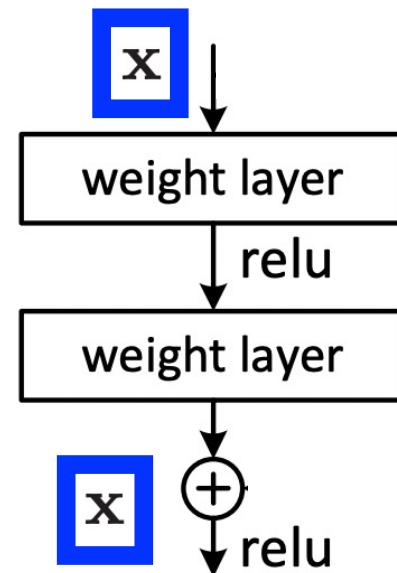
Observation: adding more layers leads to WORSE results!

Is the problem overfitting? NO

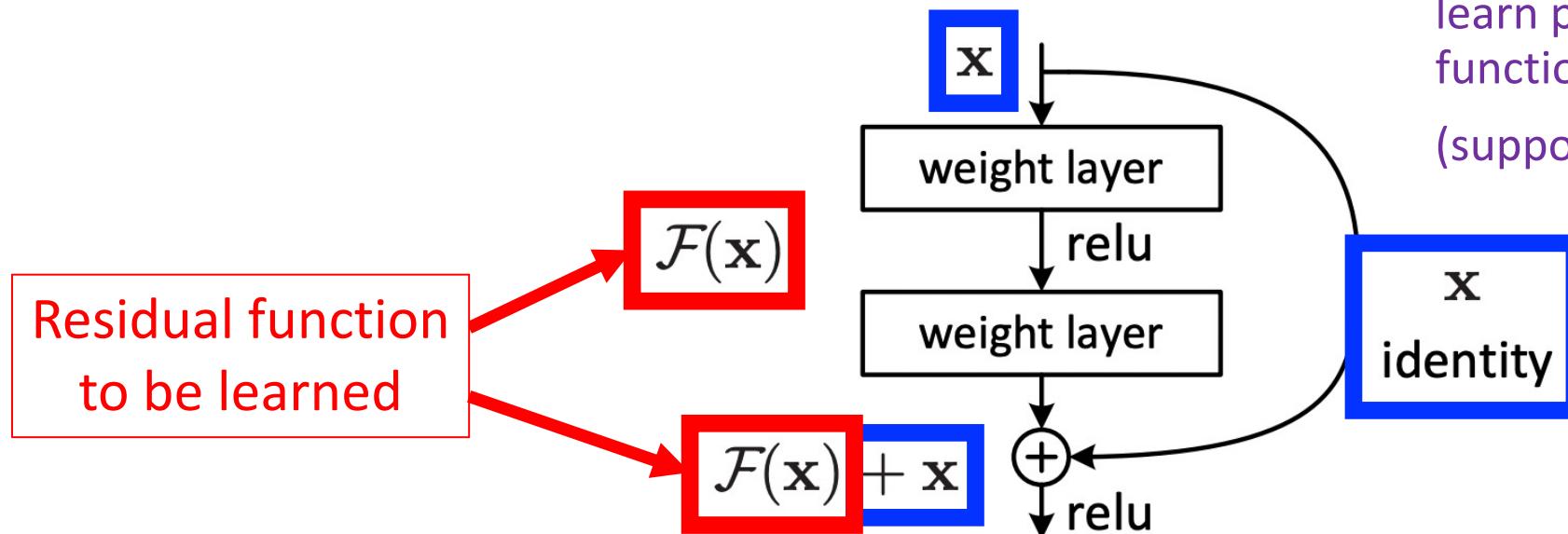
Problem: It is difficult to learn for the algorithm to learn layers of identity mappings

Problem: Difficult to Perform Identity Mapping

e.g.,

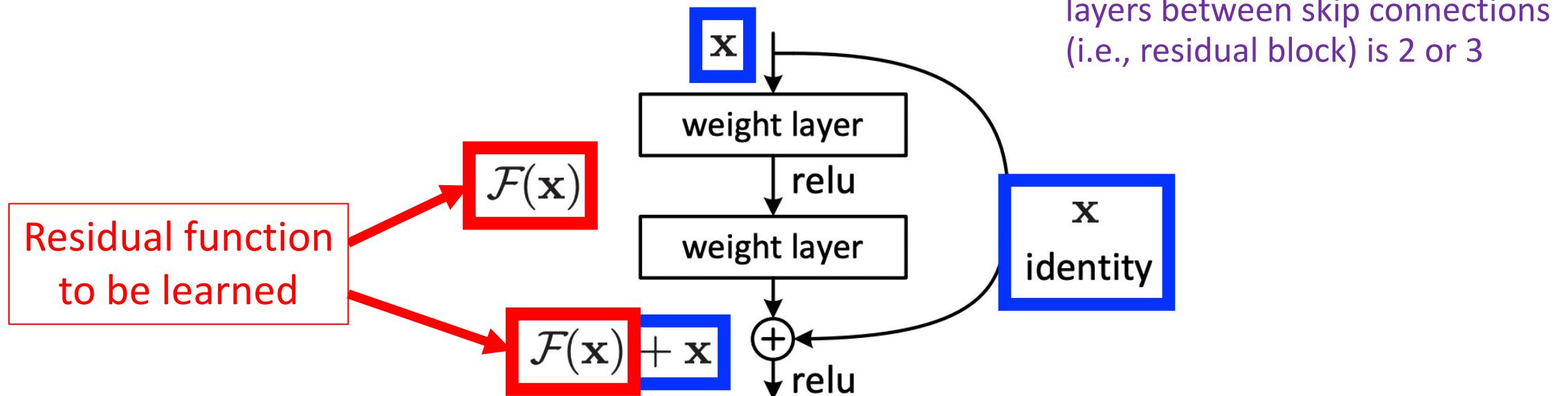


Key Idea: Skip Connections that Perform Identity Mapping



Assumption: Easier for a network to learn parameters close to 0 than a function that performs identity mapping (supported by experiments in the paper)

Key Idea: Skip Connections that Perform Identity Mapping



Key Idea: Skip Connections that Perform Identity Mapping

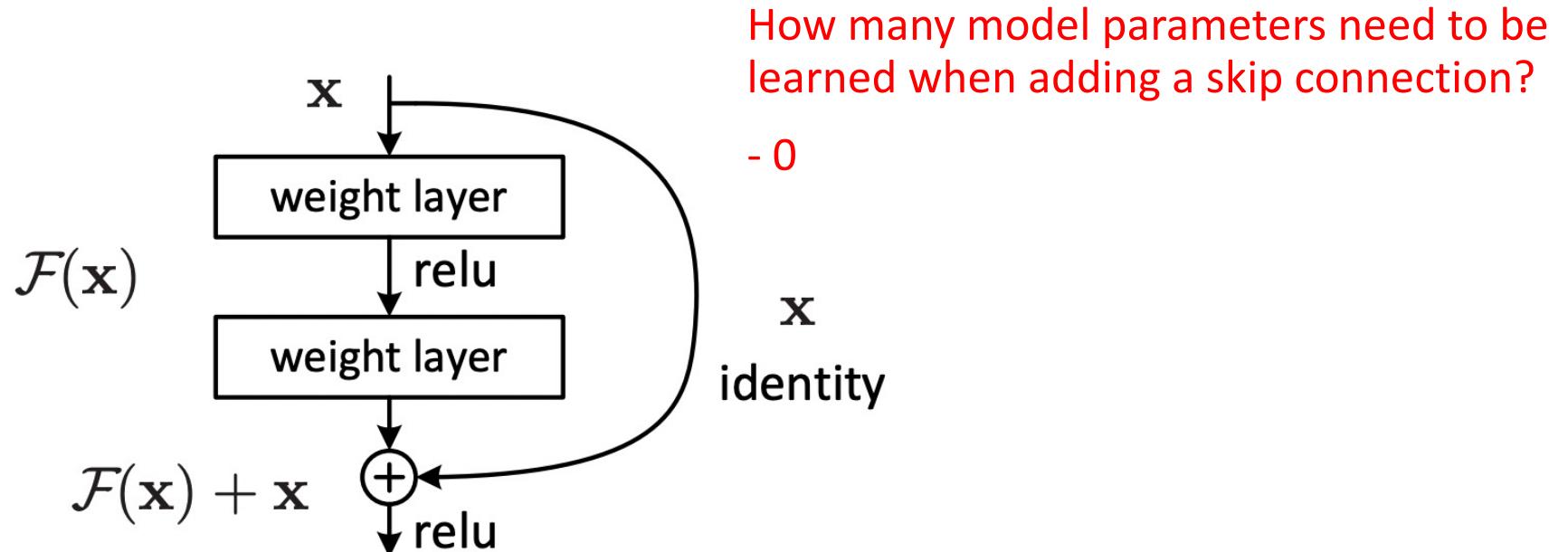
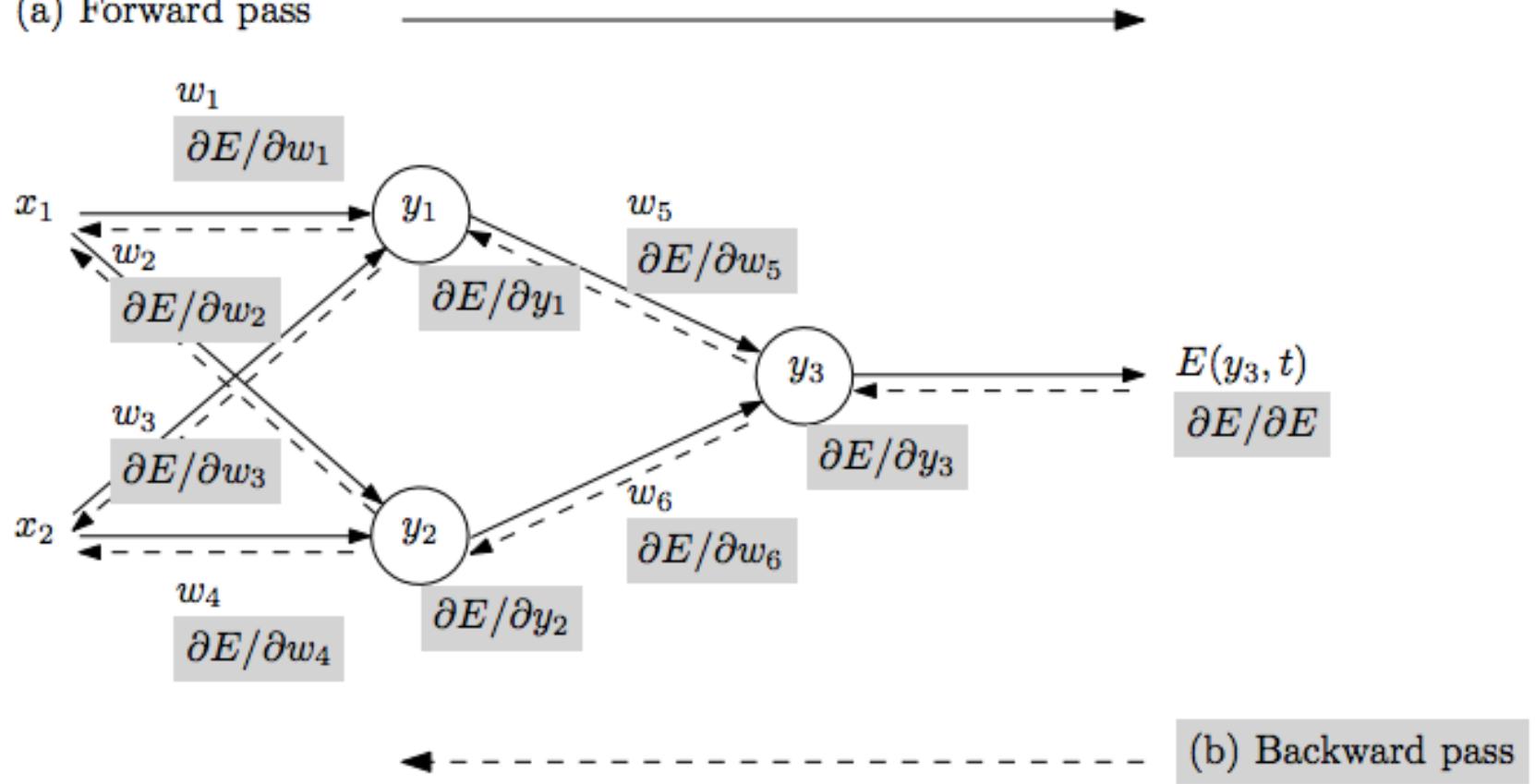


Figure 2. Residual learning: a building block.

ResNet Training (follows AlexNet)

(a) Forward pass

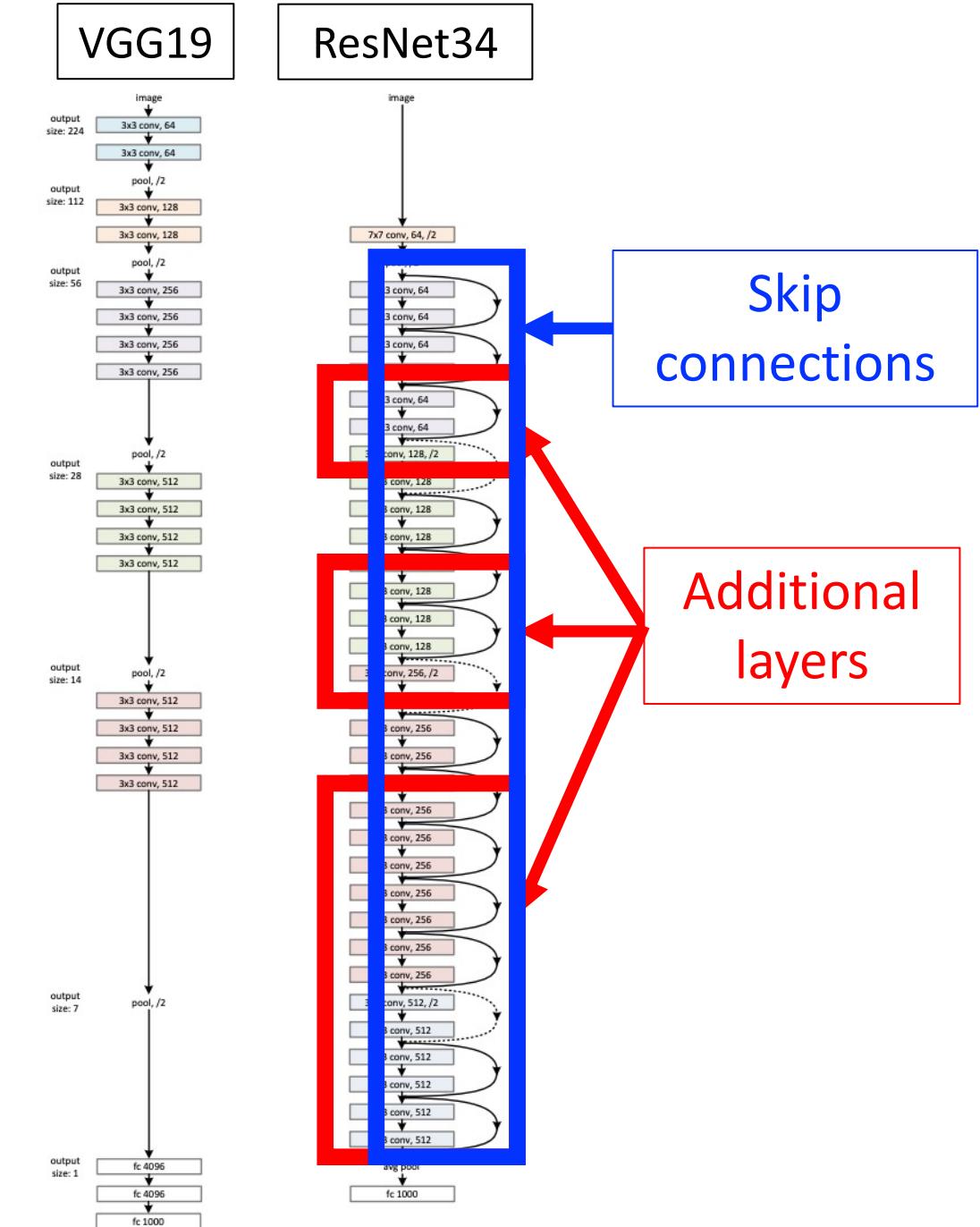


- Repeat until stopping criterion met:
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Figure from: Atilim Gunes Baydin, Barak A. Pearlmutter, Alexey Andreyevich Radul, Jeffrey Mark Siskind; Automatic Differentiation in Machine Learning: a Survey; 2018

Experimental Results

Deep residual learning framework using **skip connections** obtains state-of-art performance for the ImageNet object recognition challenge and other challenges by learning **deeper models** than prior work (18, 34, 50, 101, & 152 layers!)



Experimental Results on Validation Set

model	top-1 err.	top-5 err.
VGG-16 [40]	28.07	9.33
GoogLeNet [43]	-	9.15
PReLU-net [12]	24.27	7.38
ResNet-50	22.85	6.71
ResNet-101	21.75	6.05
ResNet-152	21.43	5.71



Performance improves with more layers

ResNet Exceeds Human Performance!

Progress of models on ImageNet (Top 5 Error)

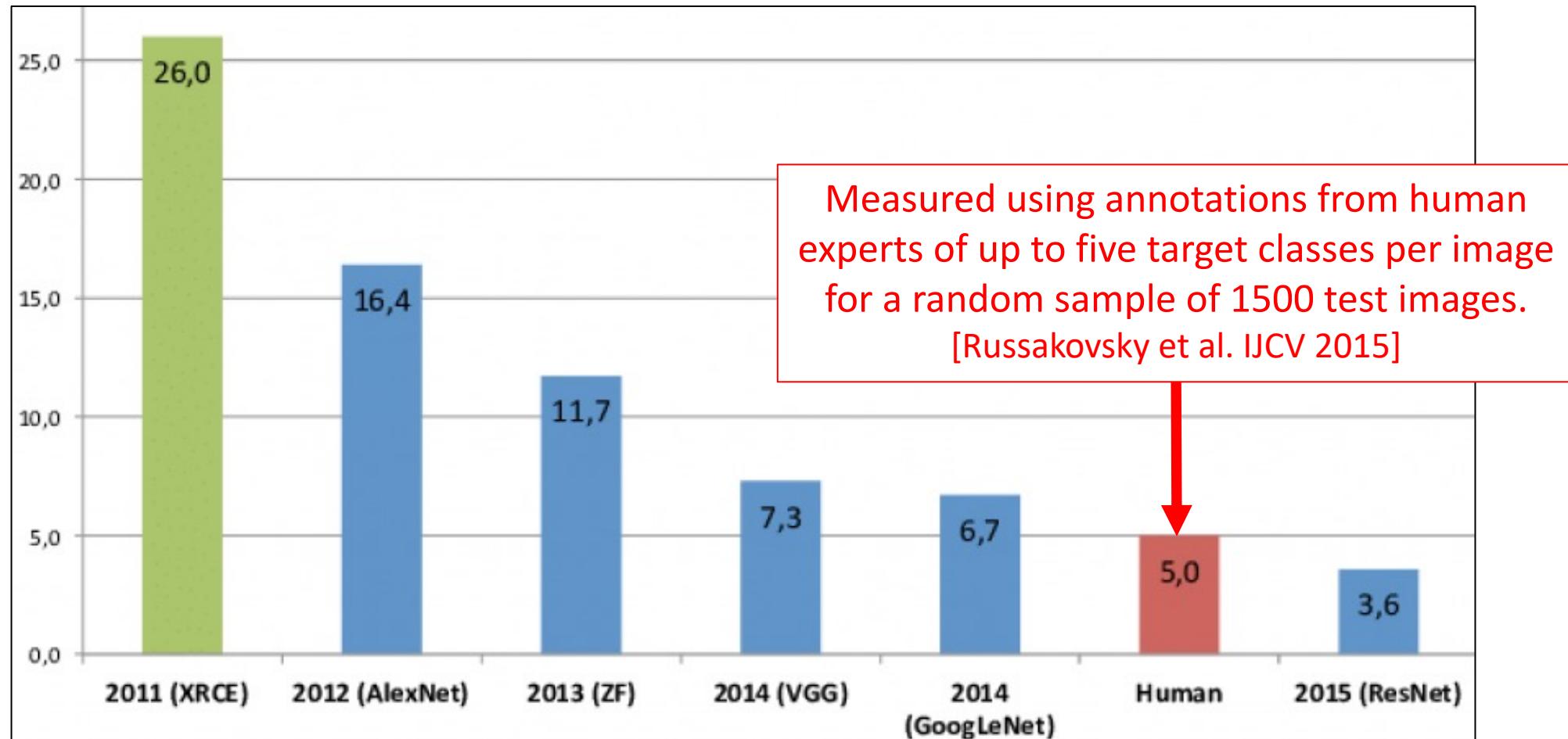


Figure Source: <https://www.edge-ai-vision.com/2018/07/deep-learning-in-five-and-a-half-minutes/>

ResNet: Key Tricks for Going Deeper

- Skip connections with residual learning

“Deeper” Models Perform Better

Progress of models on ImageNet (Top 5 Error)

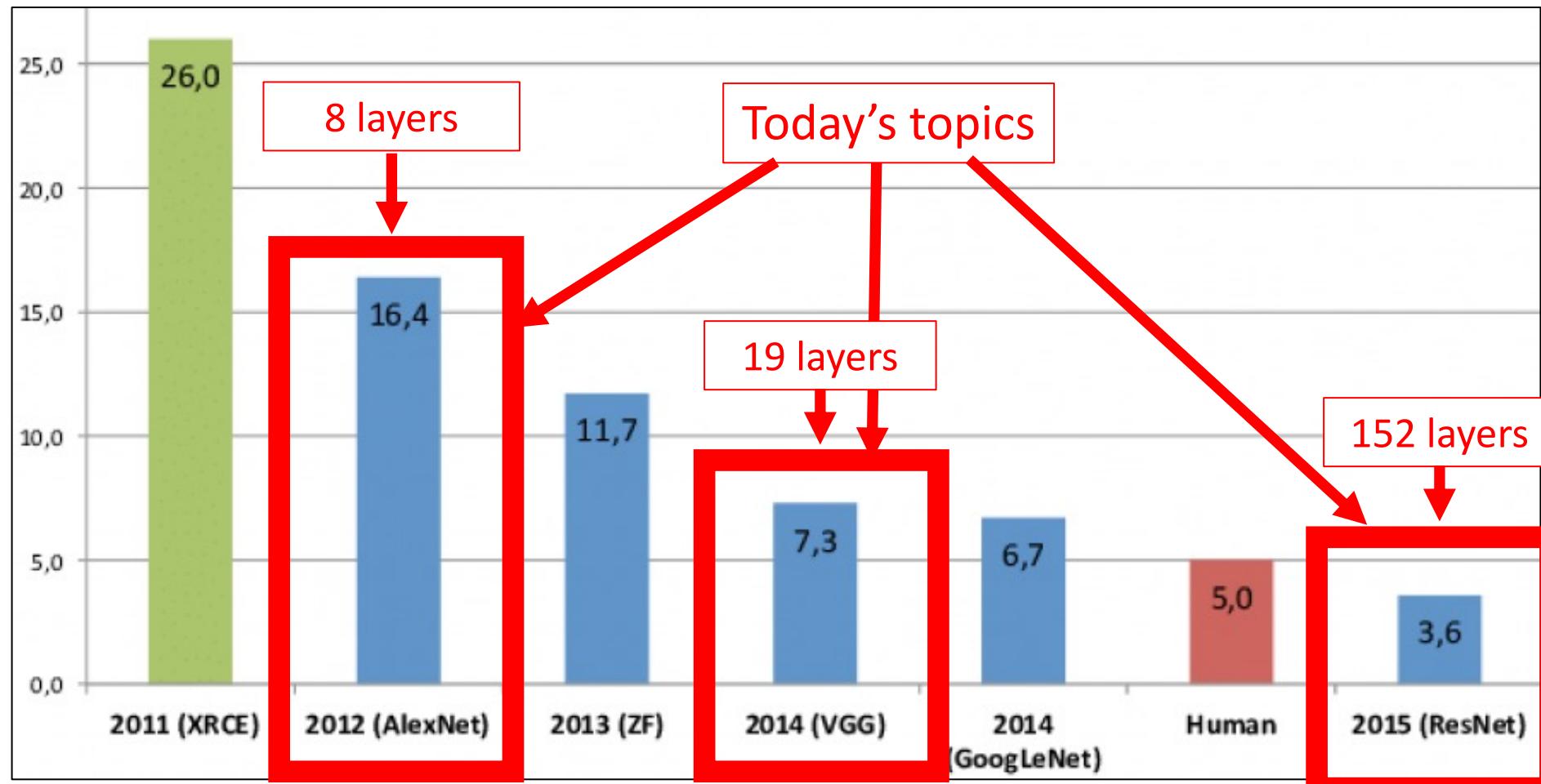


Figure Source: <https://www.edge-ai-vision.com/2018/07/deep-learning-in-five-and-a-half-minutes/>

ImageNet Impact Recognized in 2019

PAMI Longuet-Higgins Prize

Retrospective Most Impactful Paper from CVPR 2009

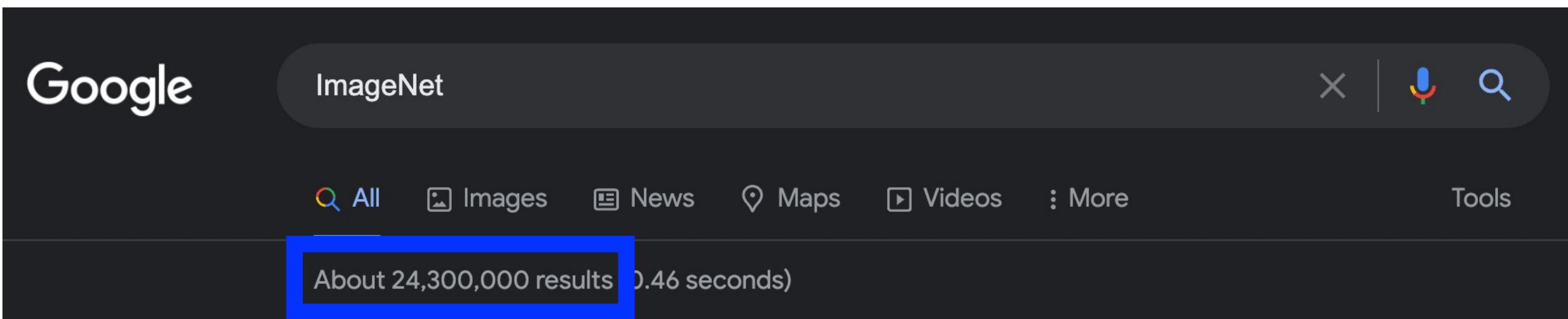
ImageNet: A large-scale hierarchical image database

Jia Deng, Wei Dong, Richard Socher,
Li-Jia Li, Kai Li, and Li Fei-Fei



<https://syncedreview.com/2019/06/18/cvpr-2019-attracts-9k-attendees-best-papers-announced-imagenet-honoured-10-years-later/>

ImageNet Impact Recognized



A screenshot of a Google search results page. The search bar at the top contains the query "ImageNet". Below the search bar are several navigation links: "All", "Images", "News", "Maps", "Videos", and "More". A blue rectangular box highlights the text "About 24,300,000 results (0.46 seconds)". On the far right, there is a "Tools" link. The overall background is dark.

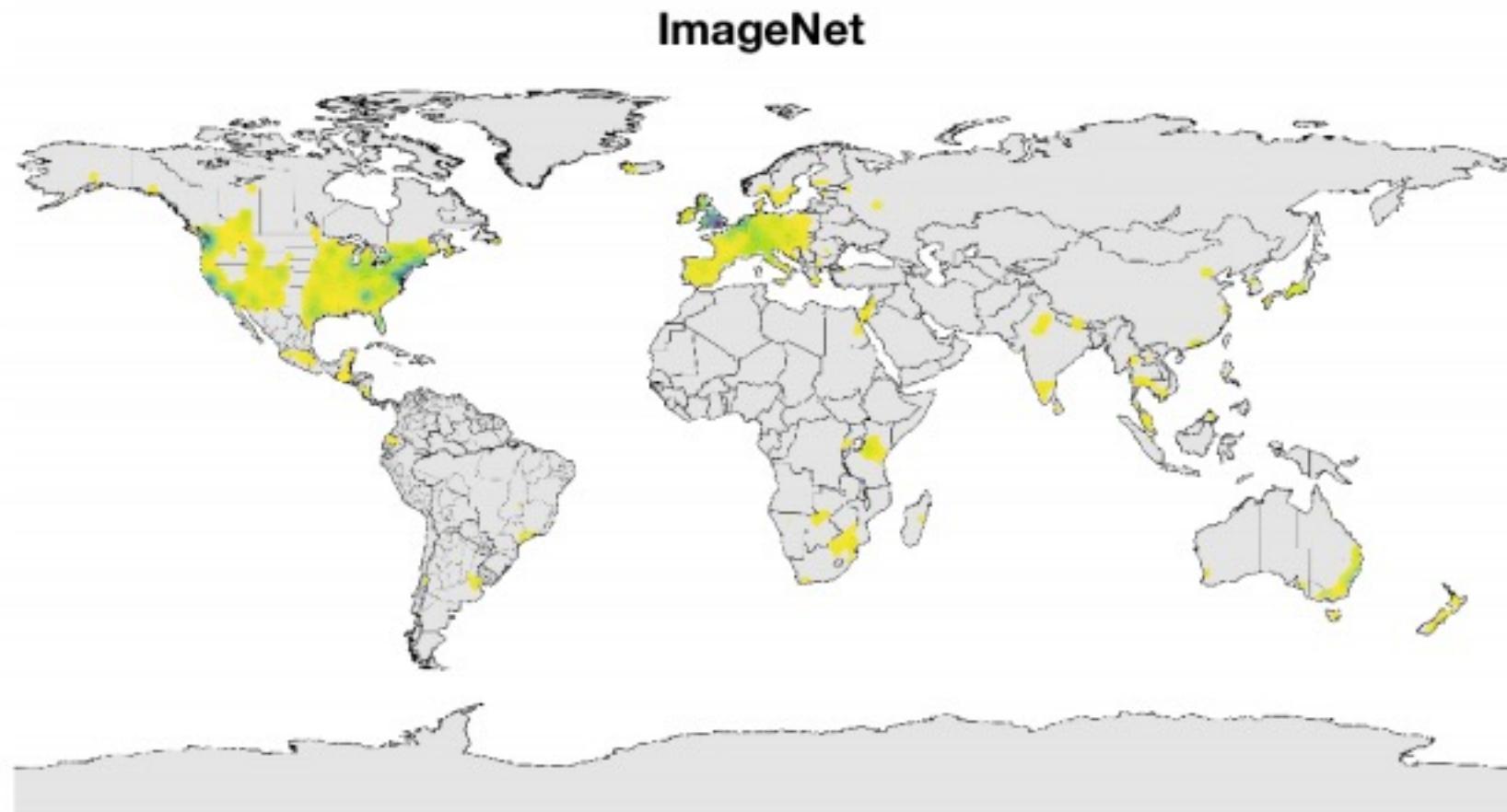
Google ImageNet × | ⚡ 🔍

All Images News Maps Videos More Tools

About 24,300,000 results (0.46 seconds)

ImageNet: Great Start...

Geographical distribution of images in the ImageNet using Flickr metadata:



Today's Topics

- Computer vision
- Era of dataset challenges
- MNIST challenge winner: LeNet
- ImageNet challenge winners: deeper learning (AlexNet, VGG, ResNet)
- Programming tutorial

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The End