

- Compact size, suitable for mini racing car installation.
- Power-efficient design.
- Low maintenance cost, robust operation in small engines environments.

4.3. Core problems to be solved & Solving ideas/methods:

Problem 1: Accurately measure flywheel speed in real time

Solution: Use a Hall sensor mounted near the flywheel to detect magnet signal. Use an Arduino microcontroller and Input Capture Interrupt to calculate the time between two consecutive pulses → from there calculate RPM.

Problem 2: Precise ignition timing control according to desired ignition angle

Solution: Calculate the time delay between the moment the signal from the Hall sensor is detected and the ignition timing.

Use Timer/Counter in Arduino Uno to generate control pulse to trigger SCR at the right time.

Problem 3: Algorithm diagrams according to the correct sequence of embedded system design.

Solution:

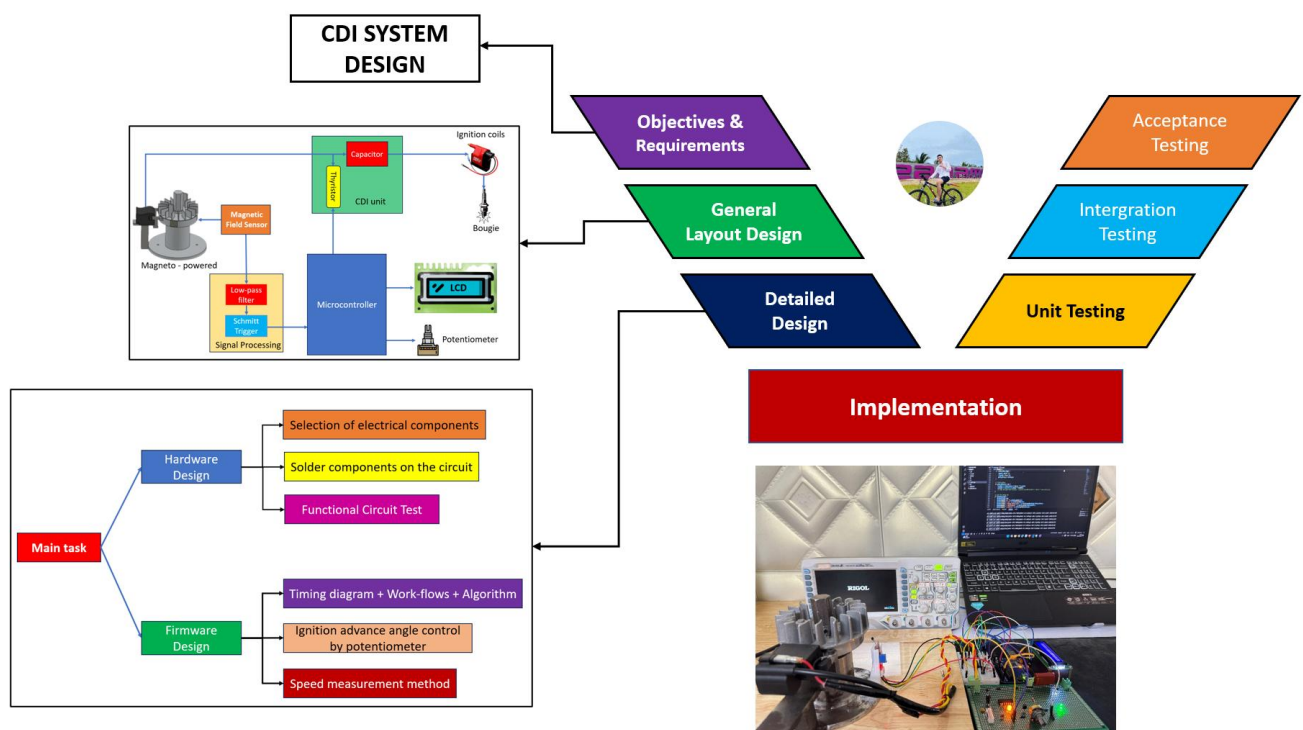


Figure 1: V-Model

4.4. Works to be done & Results:

No.	Works to be done	Required results <i>(Ex: specific data, equations, models, diagrams, parameters, charts, findings...must be achieved)</i>	Final results
1	<ul style="list-style-type: none"> - Define objective and requirements of system - Select power supplied for CDI 	<ul style="list-style-type: none"> - Design and build algorithm control of Capacitor Discharge Ignition system using magneto - powered. - Ignition type magneto of small engine. 	<ul style="list-style-type: none"> - Done: 100% - Figure 2
2	General layout design: Create system block diagram: Include magneto, capacitor, SCR, spark plug, ignition coils, signal conditioning, Hall sensor, microcontroller.	<ul style="list-style-type: none"> - Defined function of each block and their interconnections 	<ul style="list-style-type: none"> - Done (100%) - Figure 3
3	Detailed design: + Hardware & Firmware design + SCR trigger + Timing diagram + Algorithm/Work-flows + State machine + Coding	<ul style="list-style-type: none"> - Full electrical schematic - Algorithm flowcharts - Preliminary code 	<ul style="list-style-type: none"> - Done: 100% - Equation 1, 2 - Table 1,2 - Figure 4, 5, 6
4	Unit testing: Test individual modules: + Capacitor charging/discharging time + Speed signal from Hall sensor + Ignition signal	<ul style="list-style-type: none"> - Speed signals, Ignition signal - Oscilloscope waveform screenshots (Ignition pulses, speed pulses) 	<ul style="list-style-type: none"> - Done: 100% - Figure 7
5	System testing: - Integrate hardware and software:	<ul style="list-style-type: none"> - Compare measured RPM with spark timing. 	<ul style="list-style-type: none"> - Done: 100% - Figure 8,9

No.	Works to be done	Required results <i>(Ex: specific data, equations, models, diagrams, parameters, charts, findings...must be achieved)</i>	Final results
	- Verify ignition at correct timing based on RPM		
6	Actual system: - Test the entire design system	- Stability and spark strength assessment	- Done: 100% - Figure 10
7	General implementation: - Assemble complete circuit - Demonstrate working prototype	- Working system with variable speed input - Correctly timing ignition pulses	- Done: 90% - Figure 11



Figure 2: The figure ignition magneto of lawn mower

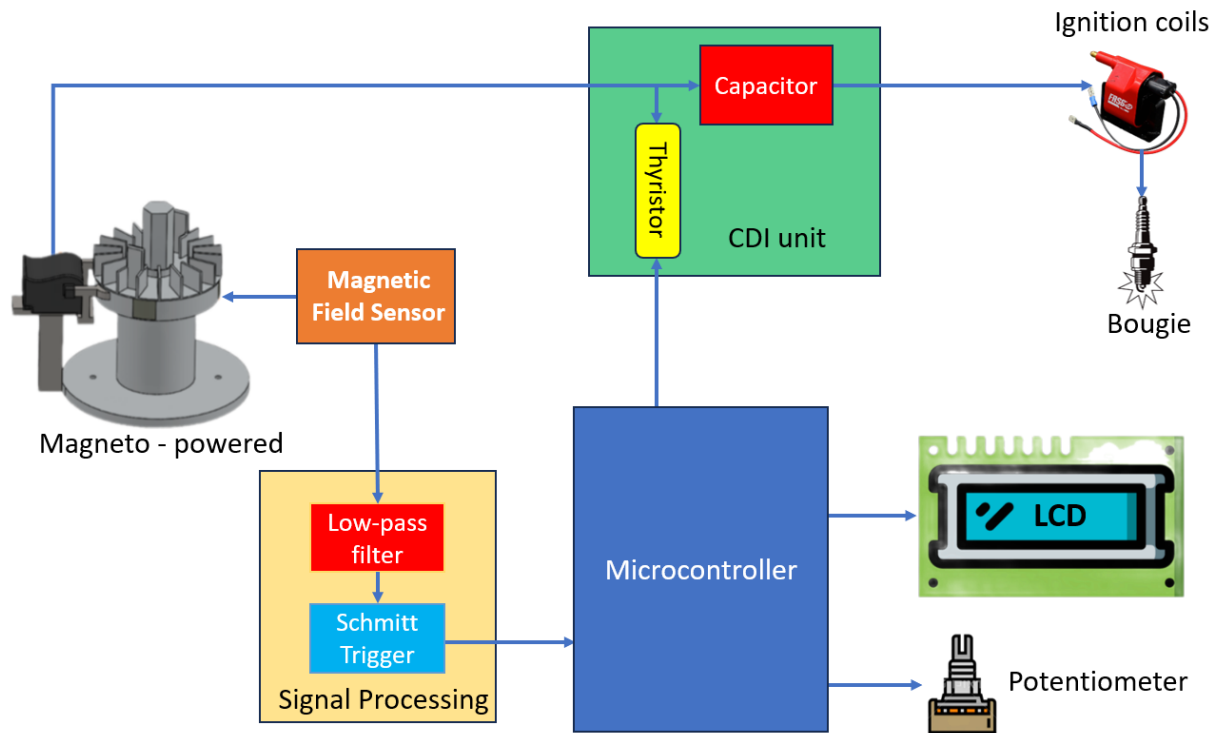


Figure 3: The figure general layout design

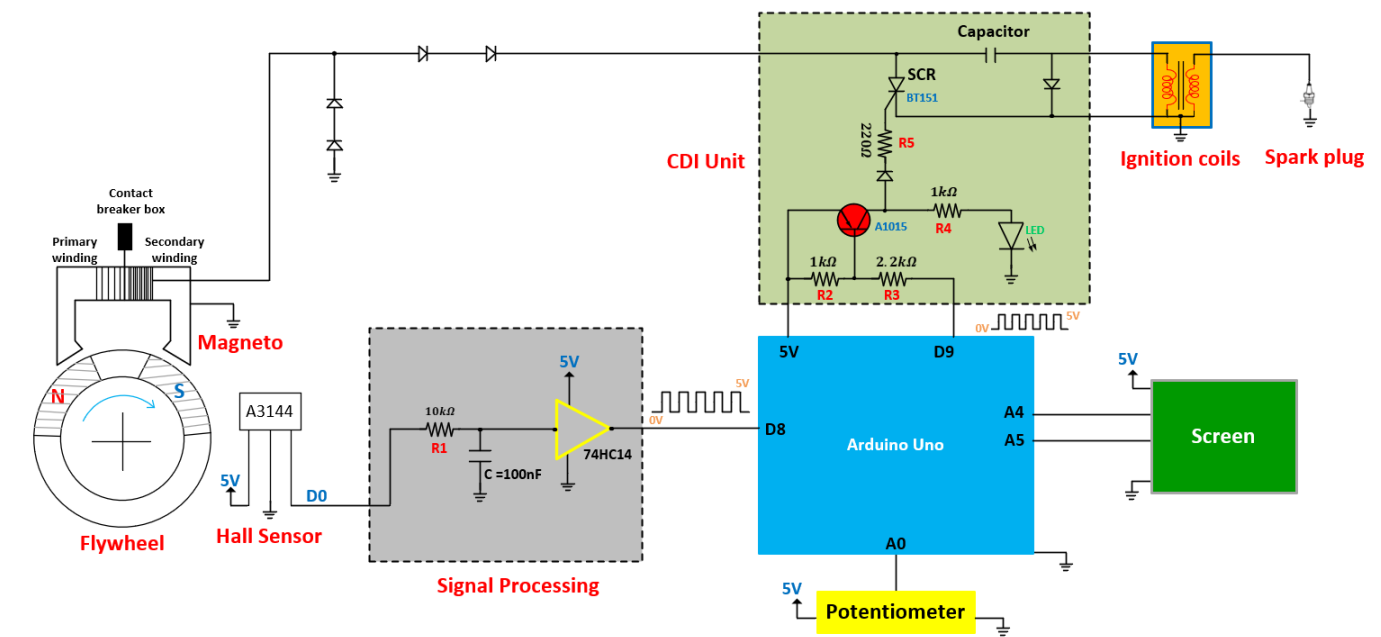


Figure 4: Wiring diagram

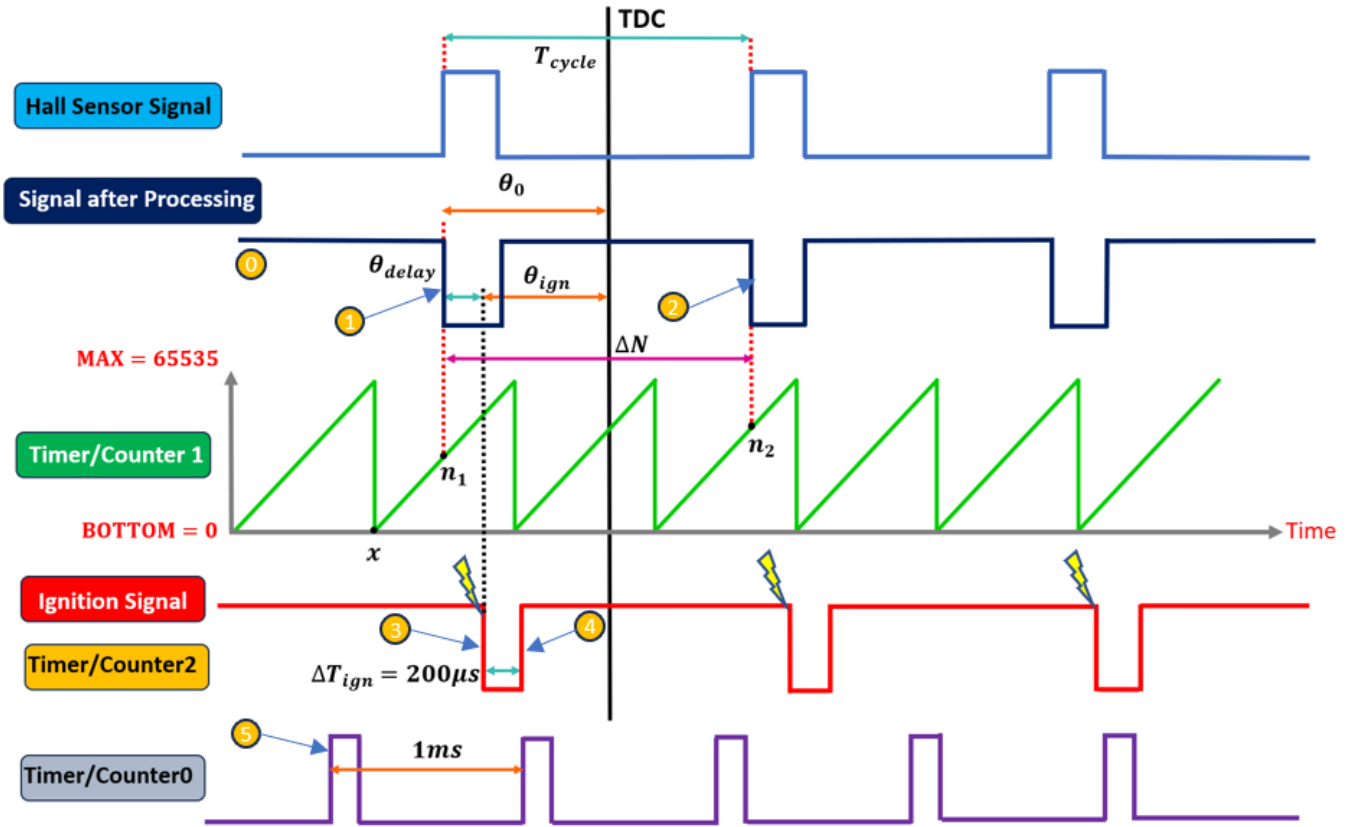


Figure 5: Timing diagram

Event	0	1	2	3	4	5
Time	Start Program	First Falling edge	Next Falling edge	Delay timeout T_{delay}	Timeout ΔT_{ign}	Every 1ms
Work	<ul style="list-style-type: none"> - Declare variables, I/O - Set up Timer 0 - Set up Timer 1 - Setup Time2 	<ul style="list-style-type: none"> - Update: $n_2 = \text{Timer1}$ - Timer 2 = T_{delay} - CAPT_flag = 1 	<ul style="list-style-type: none"> - CAPT_flag = 0 - $T_{cycle} = \frac{(\Delta N + x \times \text{MAX}) \times 64}{16 \text{ MHz}}$ - Calculation speed - Update $n_1 = n_2$ - $T_{delay} = \frac{T_{cycle} \times \theta_{delay}}{360}$ 	<ul style="list-style-type: none"> - PB9 = 0 - $\Delta T_{ign} = 200\mu s$ 	<ul style="list-style-type: none"> - PB9 = 1 	<ul style="list-style-type: none"> - Display_flag = 1 - Display on LCD

Table 1: The table for describe the event and work of timing diagram

Equation for calculation flywheel speed:

$$\Delta N = n_2 - n_1 \quad (1)$$

$$\text{Speed} = \frac{60 \times F_{\text{CPU}}}{\text{prescaler} \times (\Delta N + x \times \text{MAX})} \quad (2)$$

Where:

Speed: engine speed (rpm)

T_{cycle}: the period of hall sensor signal.

Prescaler: frequency divider (= 64);

F_{CPU}: clock speed of Arduino (= 16 MHz)

n₁: count value of Timer/Counter 1 at the rising edge of the hall sensor signal.

n₂: count value of Timer/Counter1 at the next rising edge of the hall sensor signal.

ΔN: count value of Timer/Counter1 that counted from n₁ to n₂

x: number of overflow.

	θ	T (s)	N (Ticks)
Cycle	360°	$T_{cycle} = \frac{60}{Speed}$	$N_{cycle} = \frac{F \times T_{cycle}}{prescale}$
Ign	θ_{ign}	$T_{ign} = \frac{T_{cycle} \times \theta_{ign}}{360}$	$N_{ign} = \frac{F \times T_{ign}}{prescale}$
delay	$\theta_{delay} = \theta_0 - \theta_{ign}$	$T_{delay} = \frac{T_{cycle} \times \theta_{delay}}{360}$	$N_{ign_delay} = \frac{F \times T_{delay}}{prescale}$

Table 2: The table for calculate ignition delay

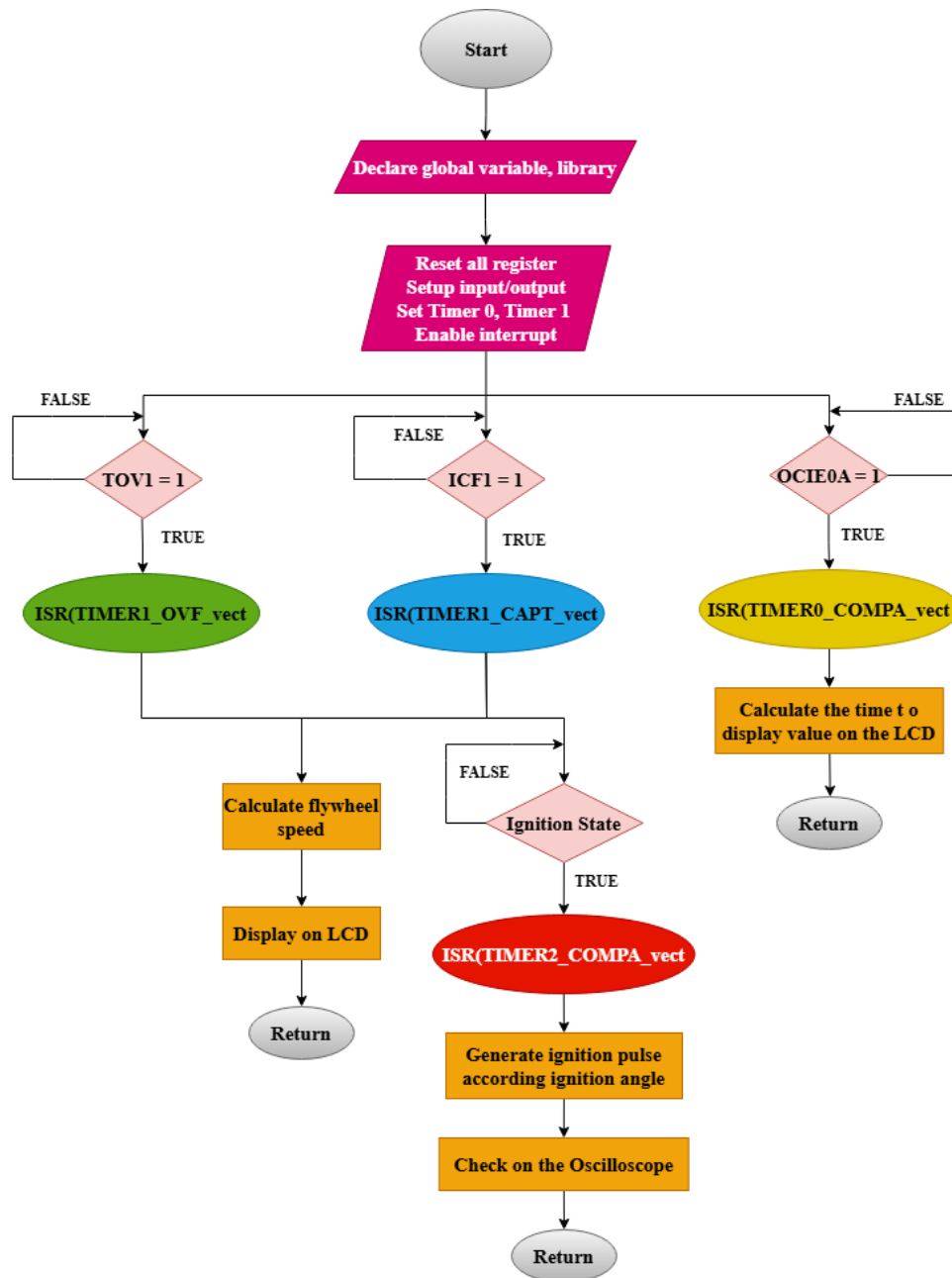
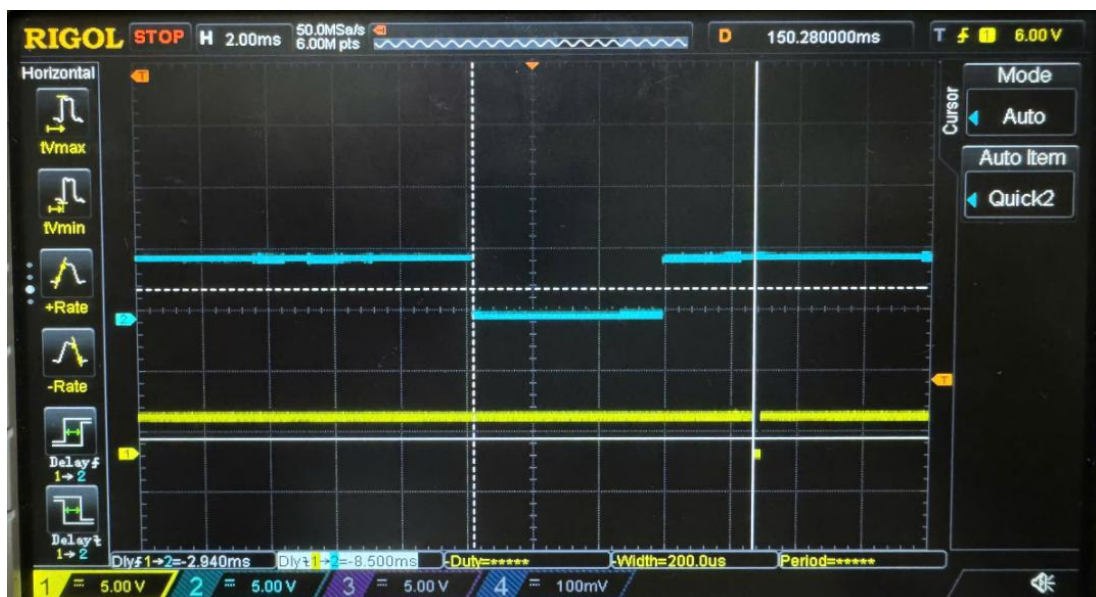


Figure 6: Main algorithm



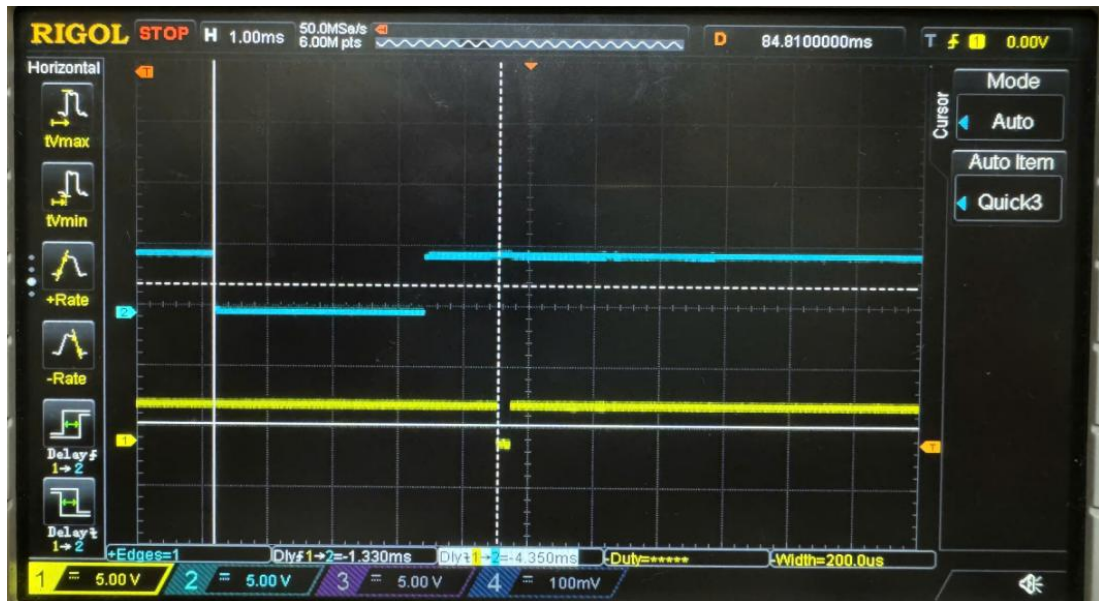


Figure 7: The figure osilloscope waveform speed signal, SCR pulse

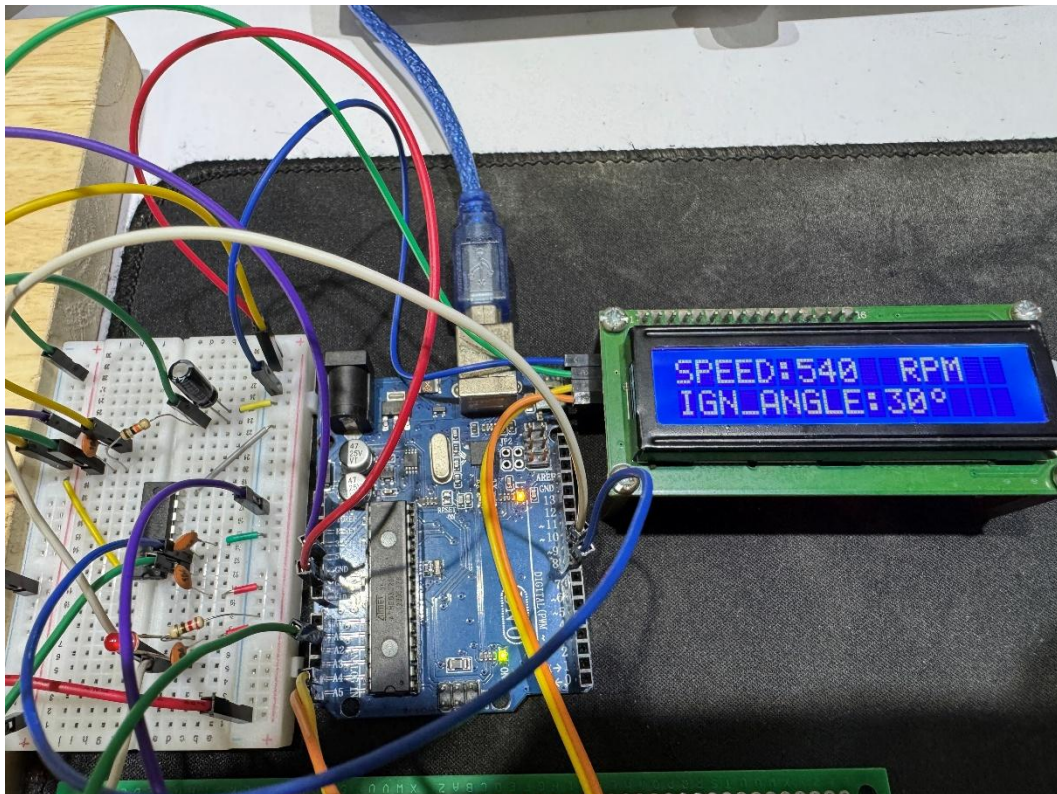


Figure 8: The value of speed on the LCD in real time



Figure 9: Compare measured speed with spark timing

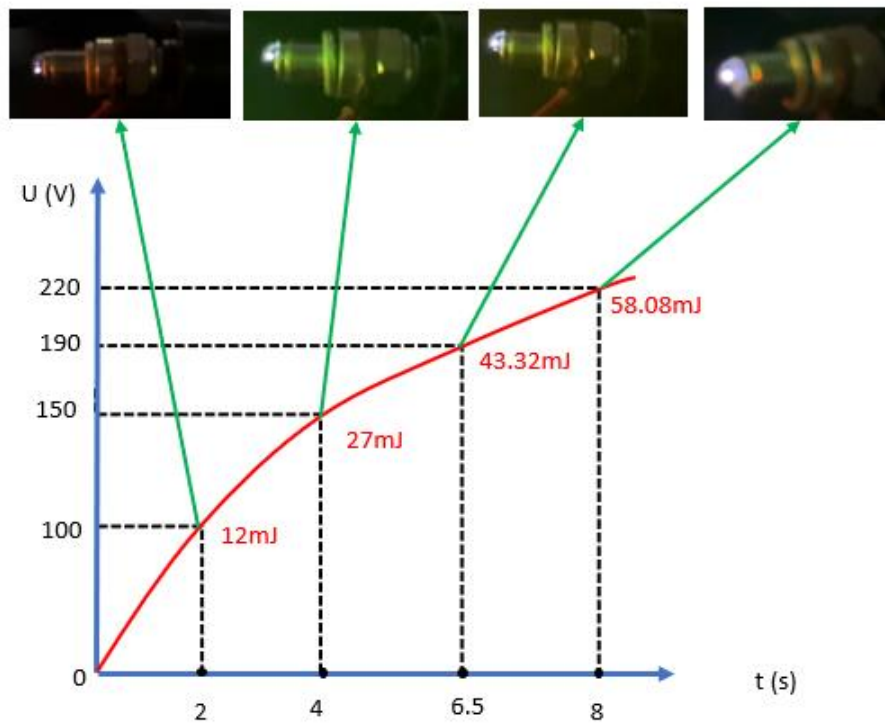


Figure 10: Spark plug ignition when system is operating

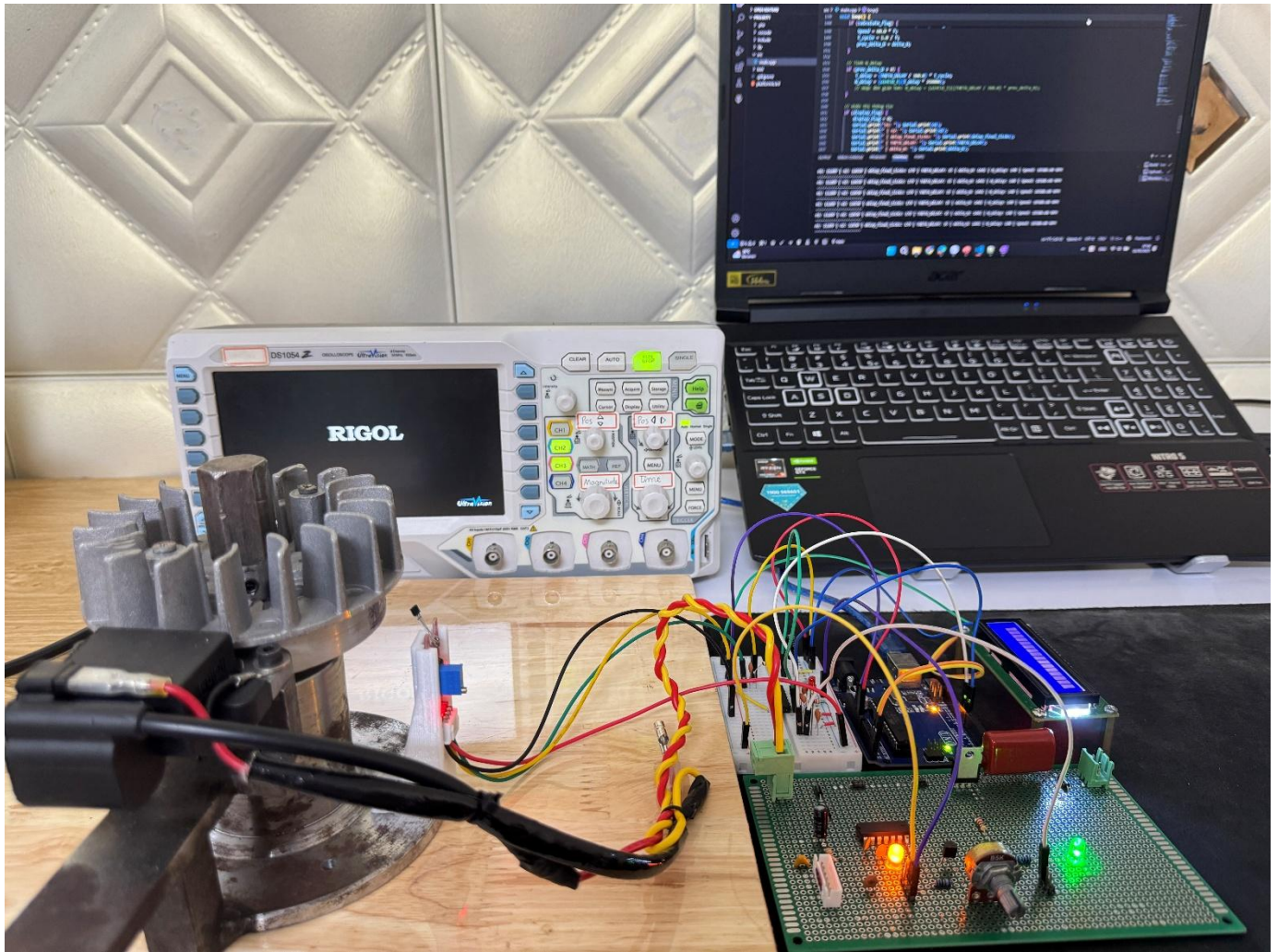


Figure 11: Realistic model of CDI ignition system using magneto - powered

4.5. Requested products:

- | | | |
|--|--|--|
| <input checked="" type="checkbox"/> Technical report | <input checked="" type="checkbox"/> Poster | <input type="checkbox"/> Scientific paper |
| <input type="checkbox"/> Software | <input checked="" type="checkbox"/> Firmware | <input type="checkbox"/> Numerical model |
| <input type="checkbox"/> General layout drawings | <input type="checkbox"/> Detailed drawing | <input type="checkbox"/> Assembly drawings |
| <input type="checkbox"/> Others: | | |

4.6. Scope of Thesis/Capstone project:

- Design a algorithm advance ignition angle control.
- Measure flywheel speed from hall sensor signal.
- Generation a simulate speed sensor signal and ignition advance angle control signal 0–60° before TDC on the Proteus.

4.7. Tasks of each team member:

No.	Member's full name	Works assigned
1	Nguyễn Quốc Kiệt	<ul style="list-style-type: none">- Design a Magneto – Powered Capacitor Discharge Ignition System.- Build algorithm control of CDI ignition system.- Simulation speed sensor signal and ignition advance angle on Proteus.

Student: Nguyễn Quốc Kiệt

- ID: 1952802

- Signature:

Date (dd/mm/yyyy): 29/05/2025

ADVISOR