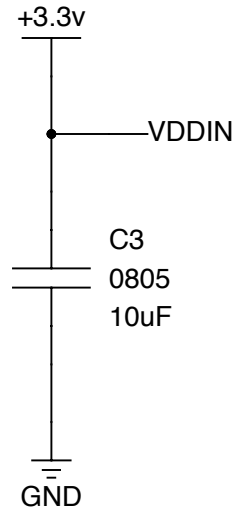
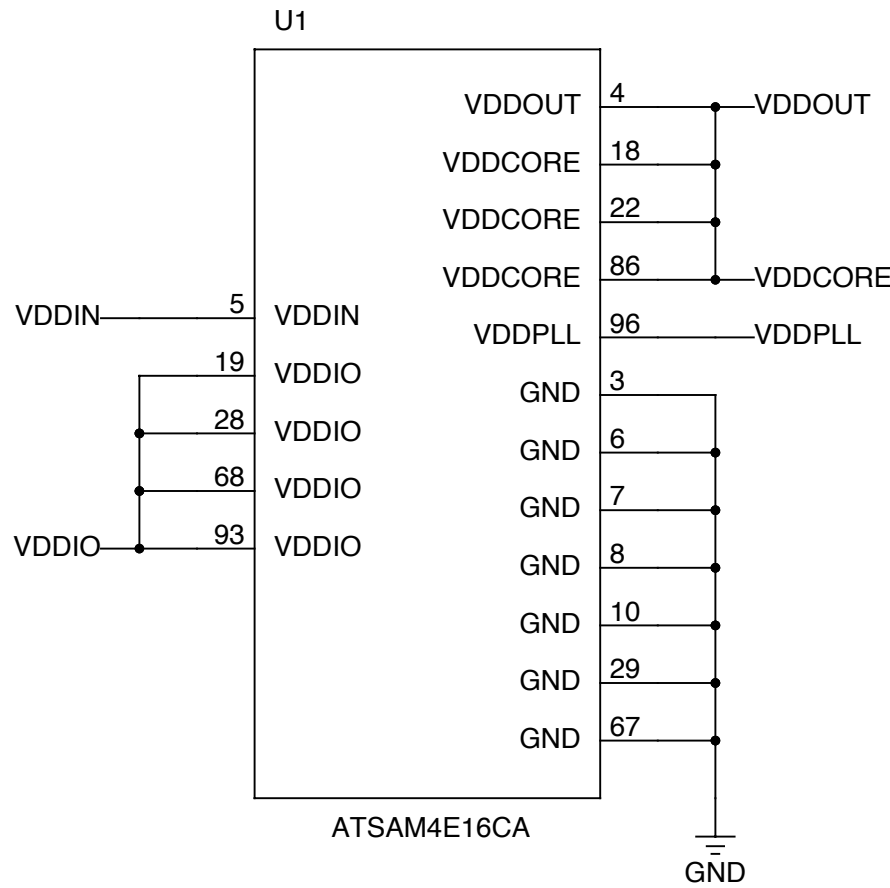
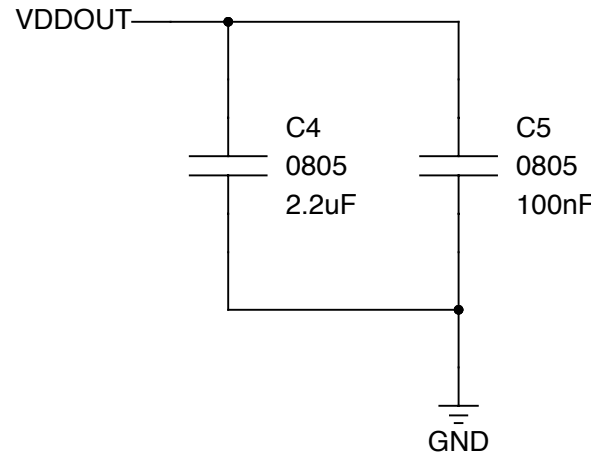
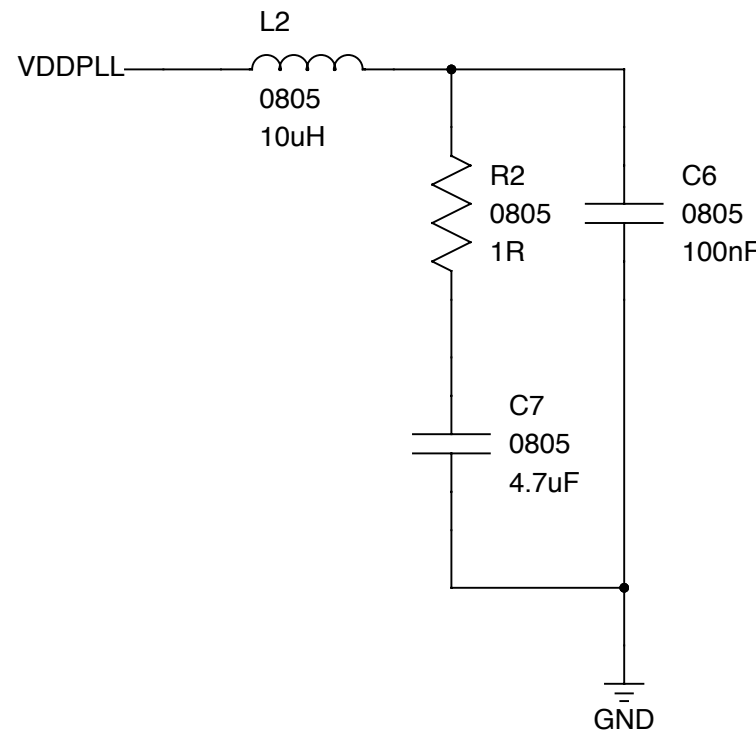
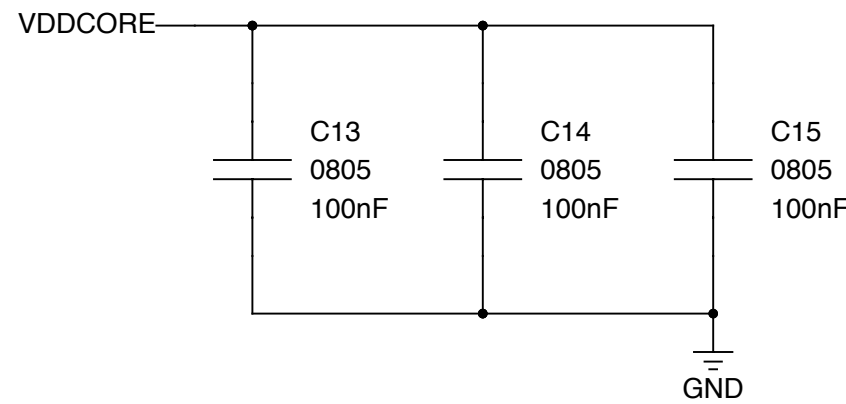
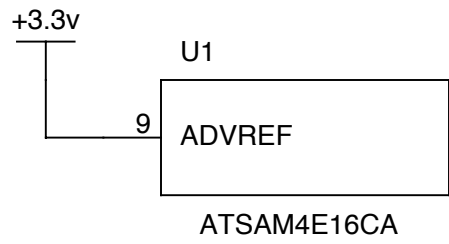
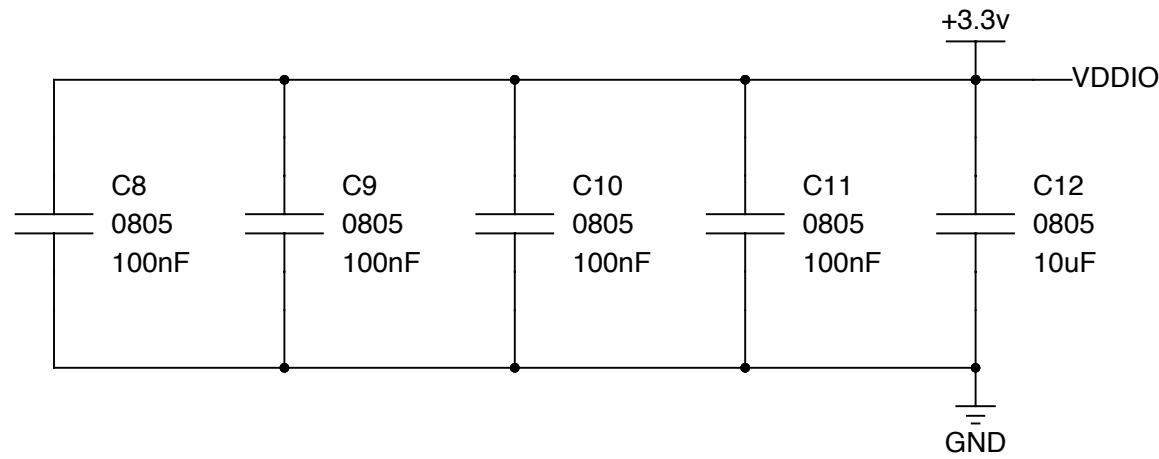
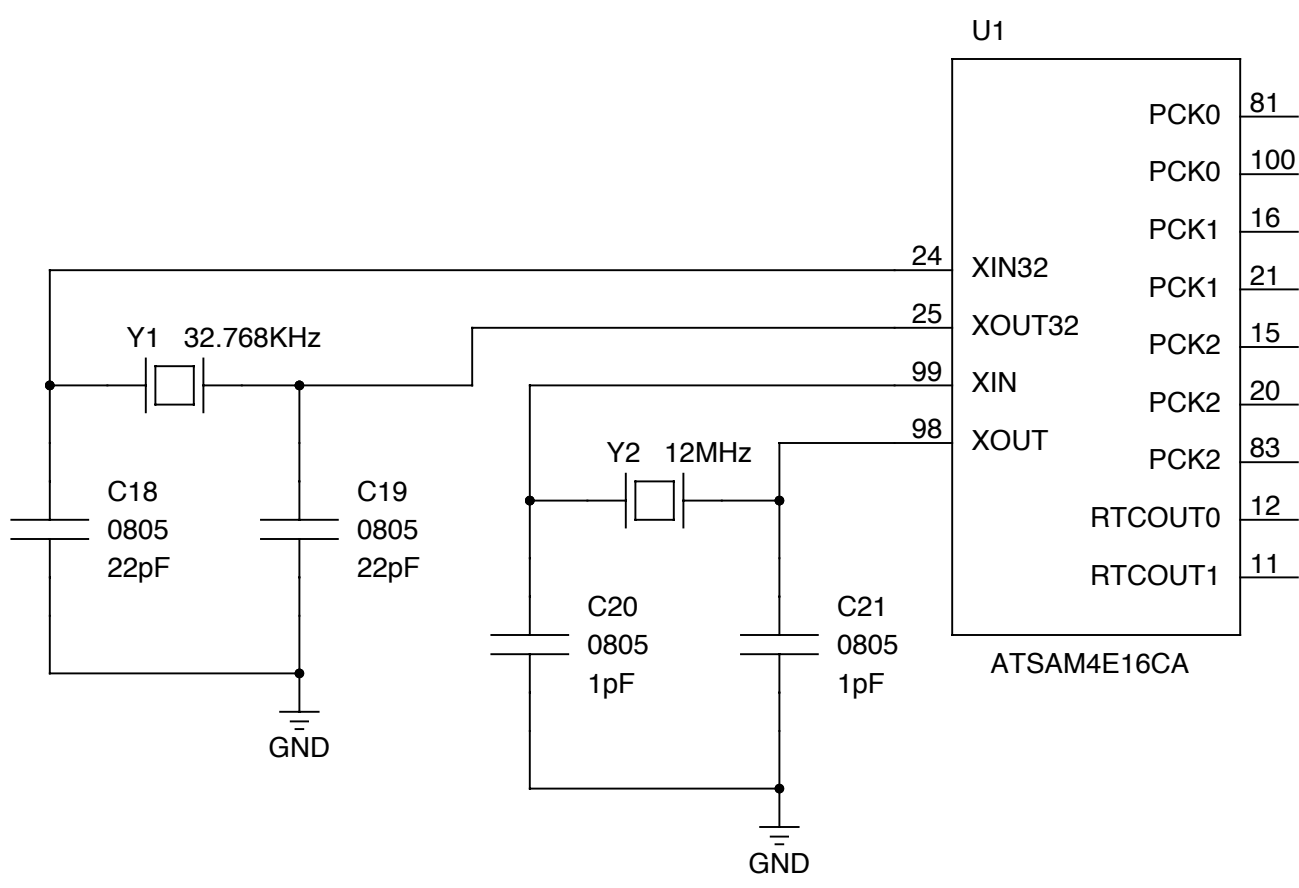


TITLE: Power
PROJECT: Quadcopter Control Board
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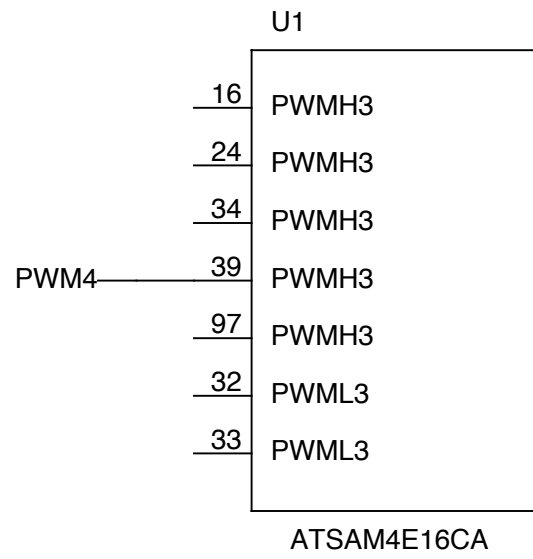
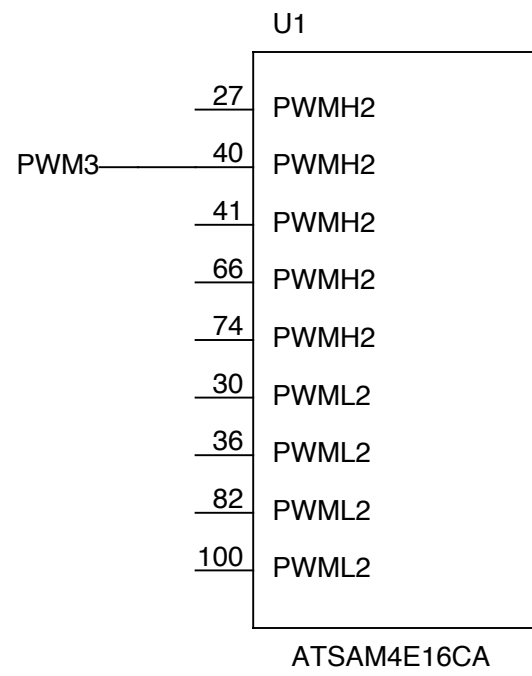
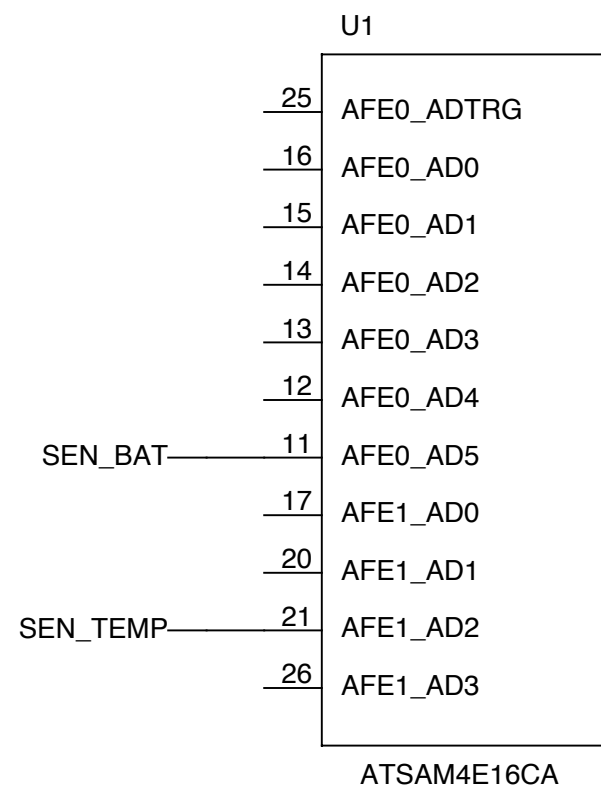
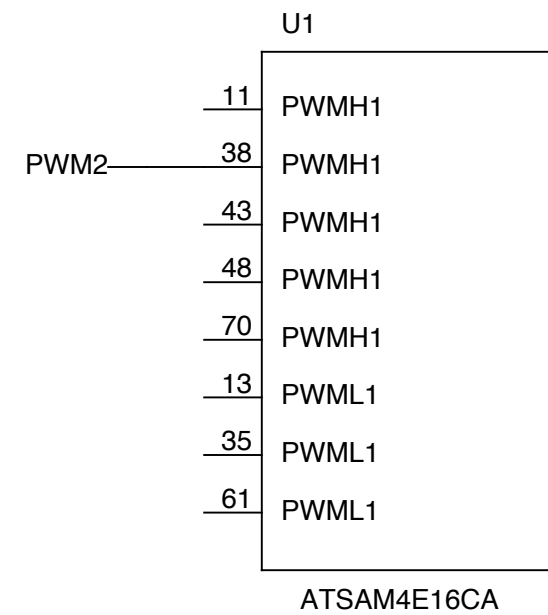
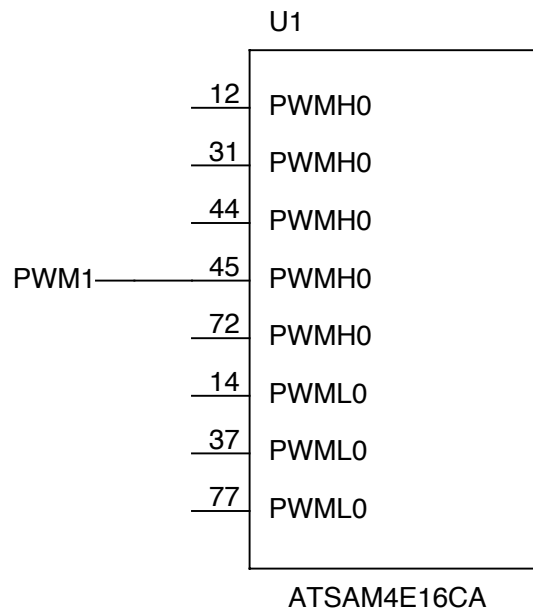
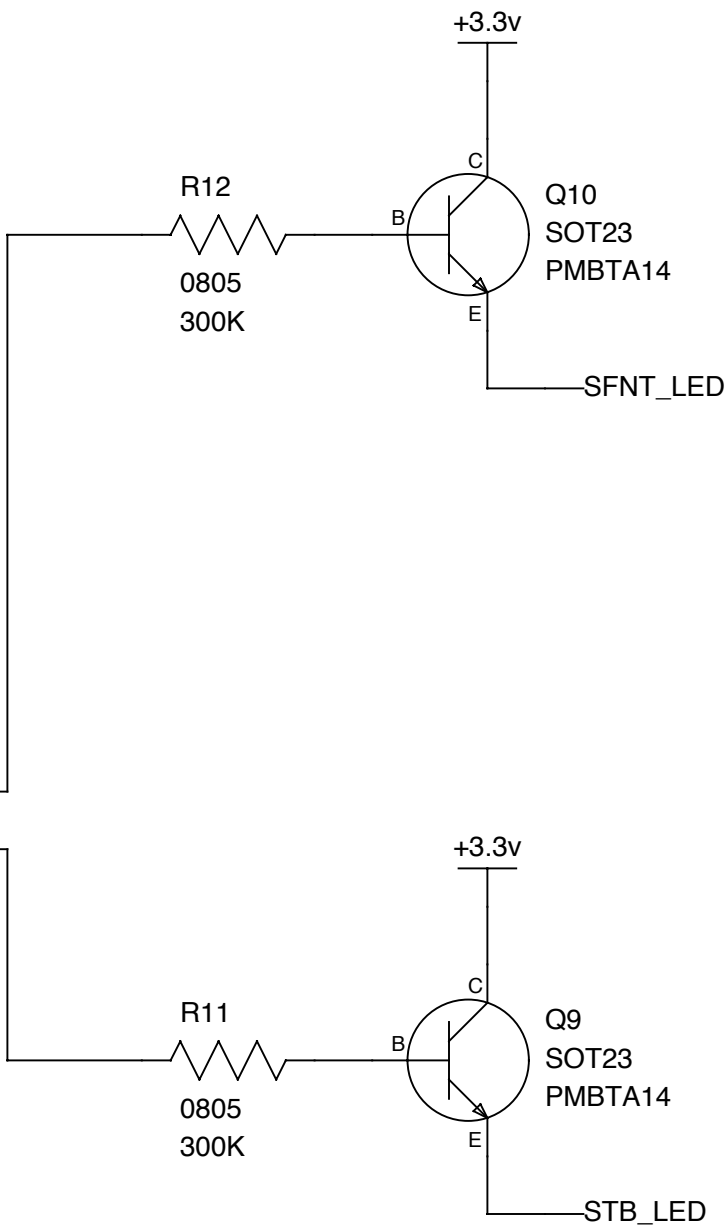
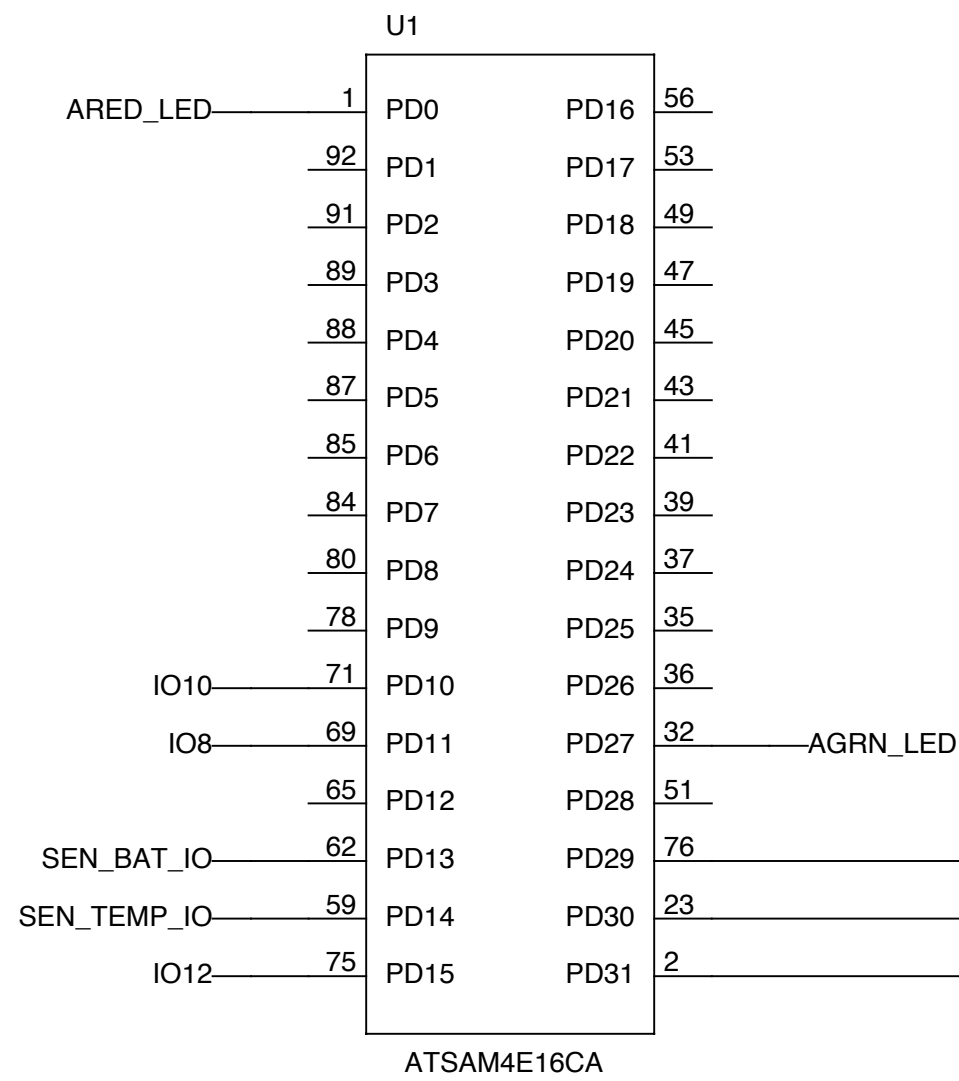
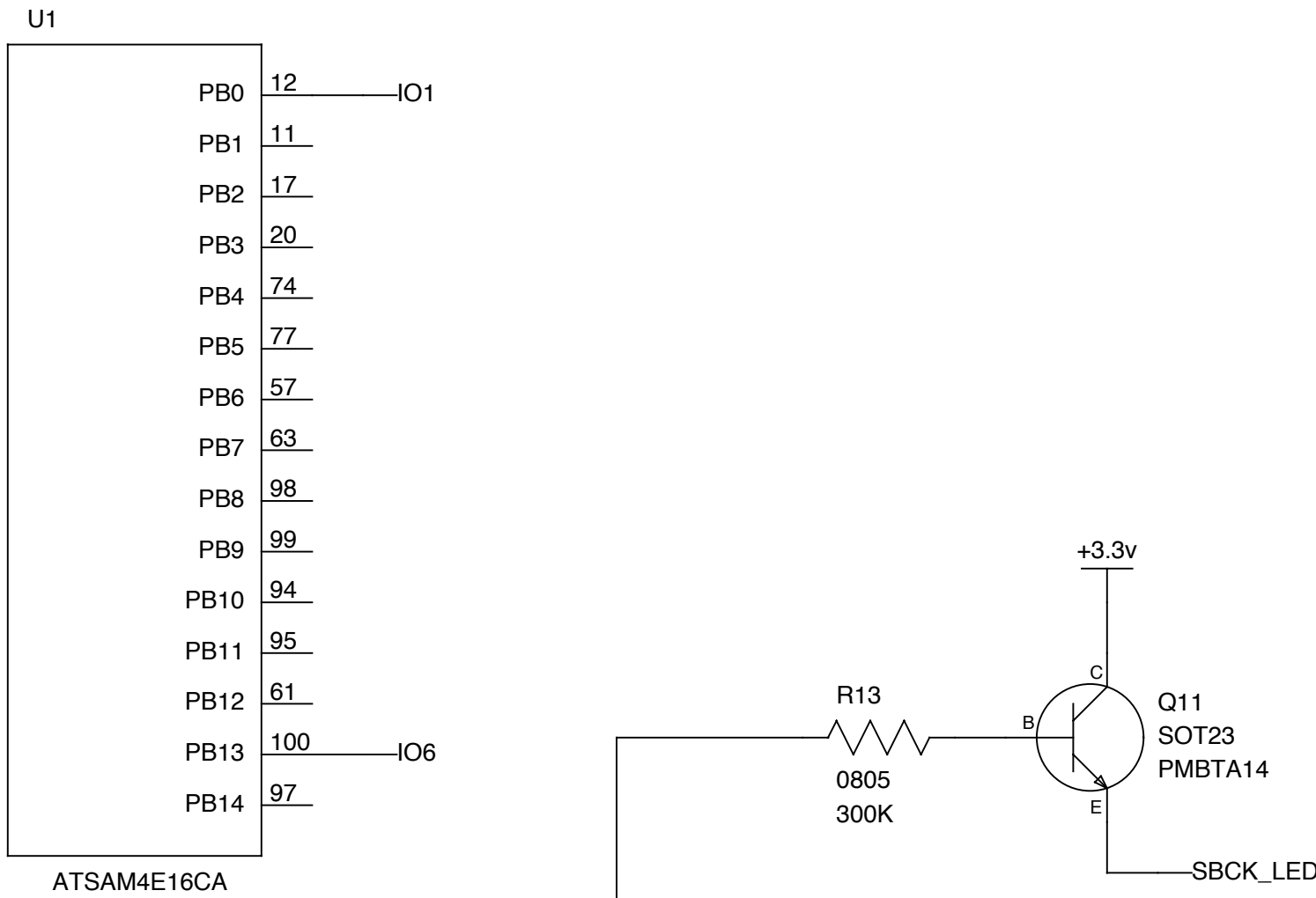
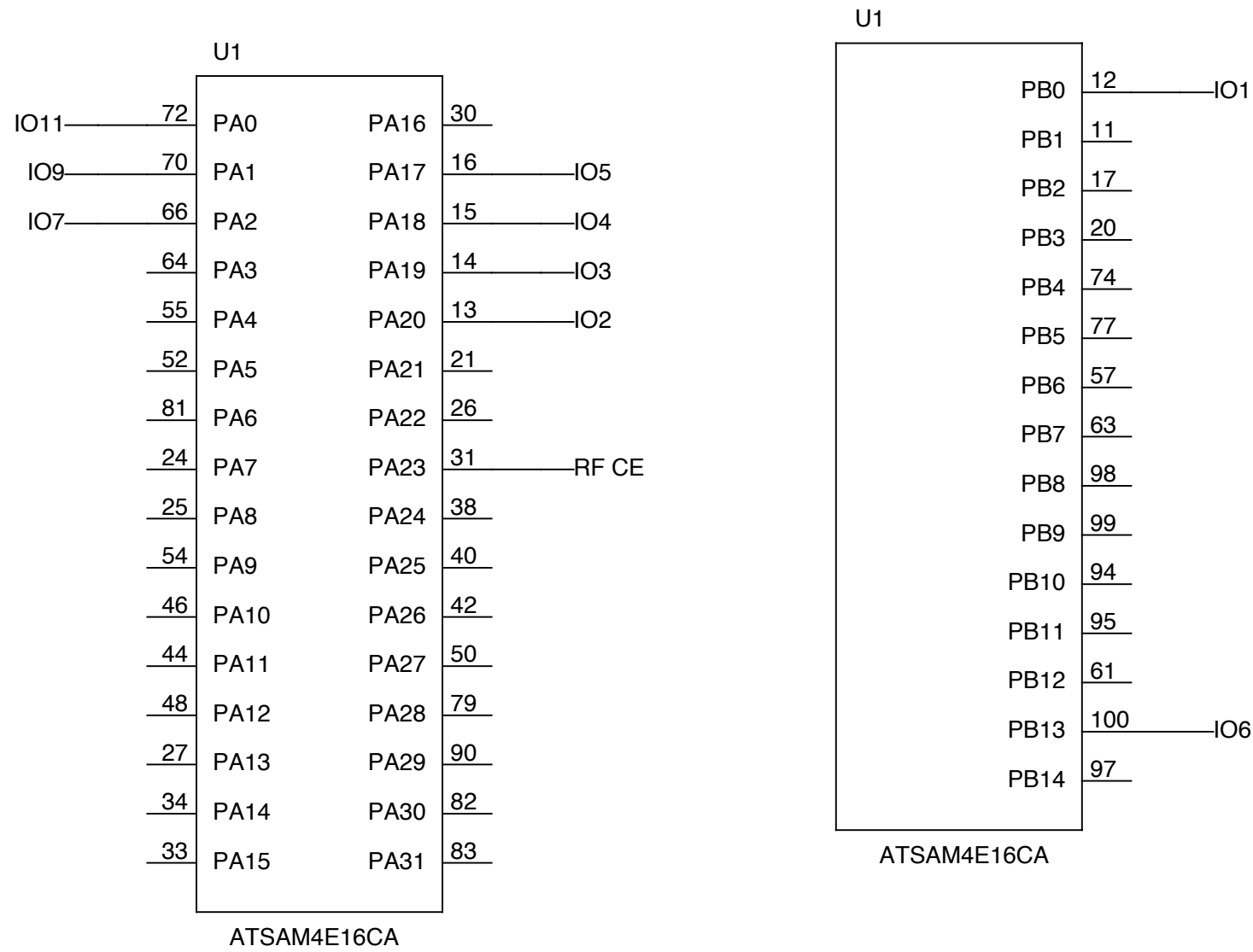
TITLE: Microcontroller Power
PROJECT: Quadcopter Control Board
DRAWN BY: Ian Glen <ian@ianglen.me>



TITLE: Microcontroller Oscillators

PROJECT: Quadcopter Control Board

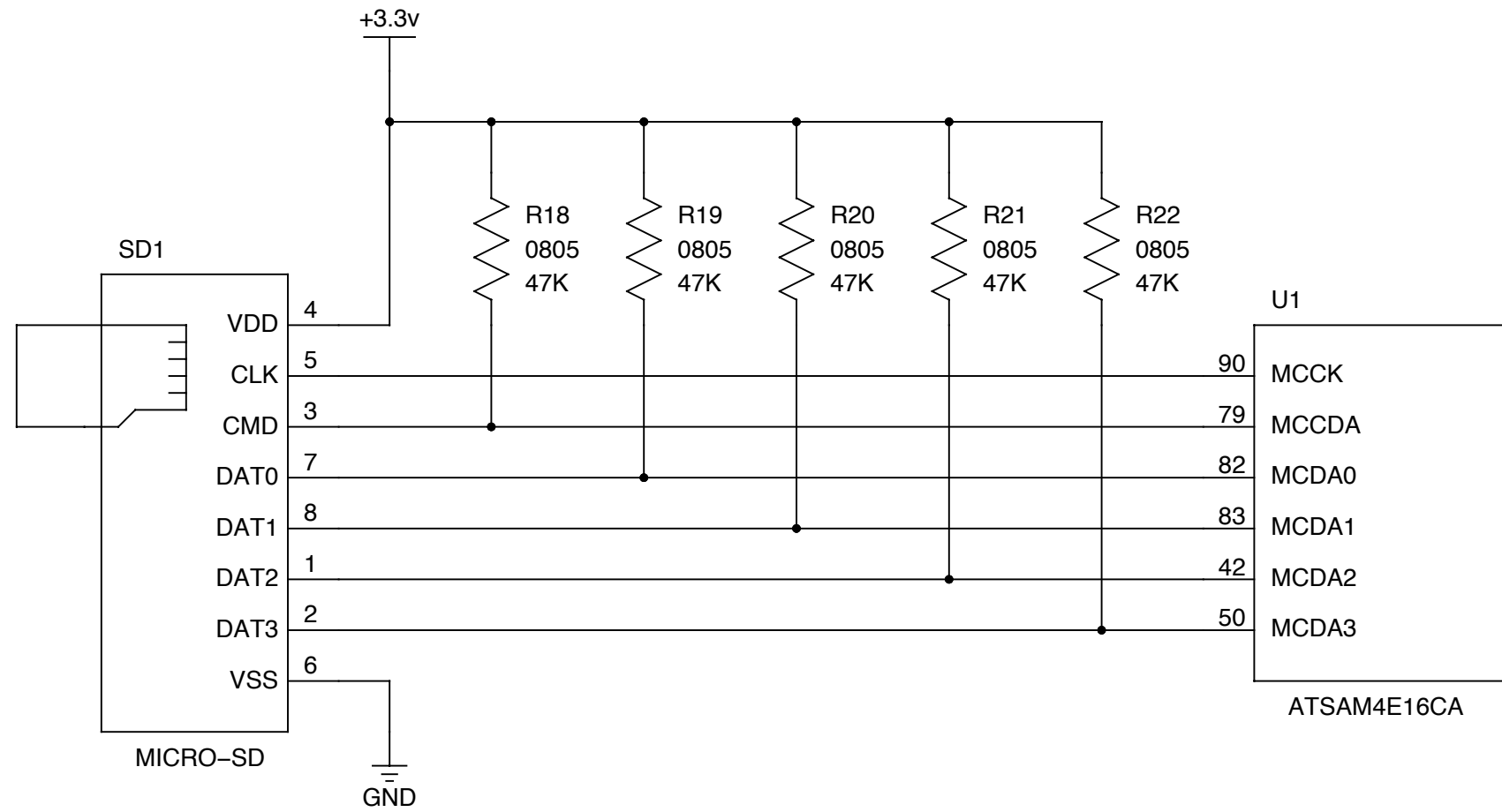
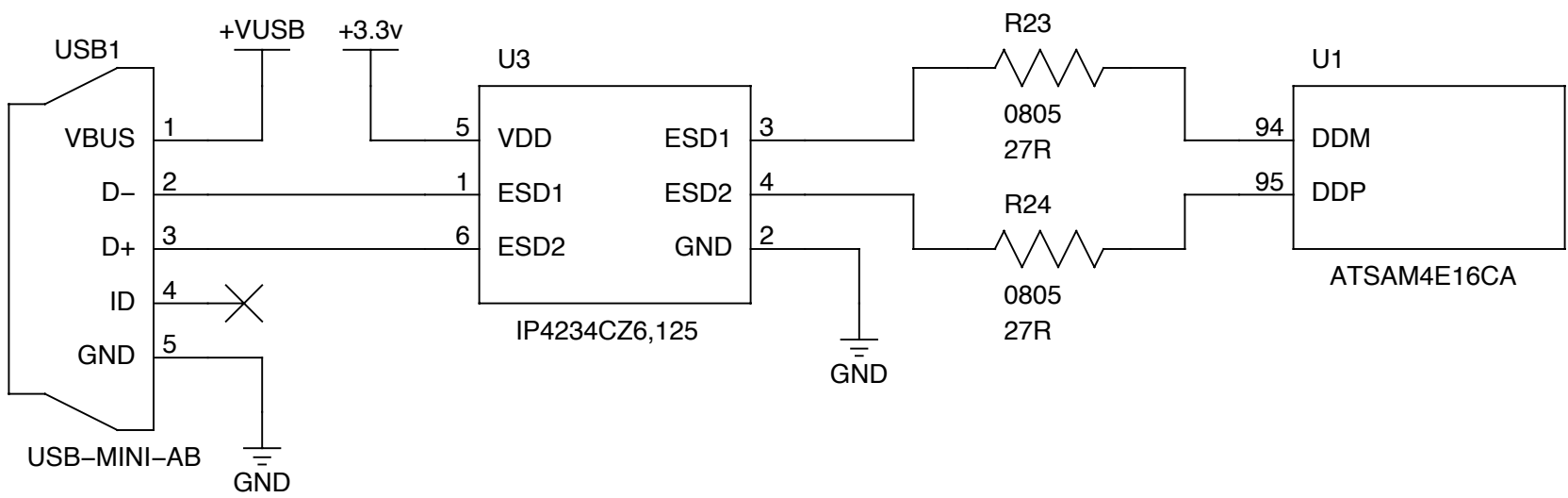
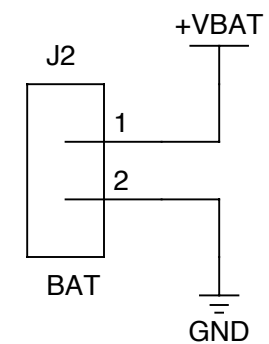
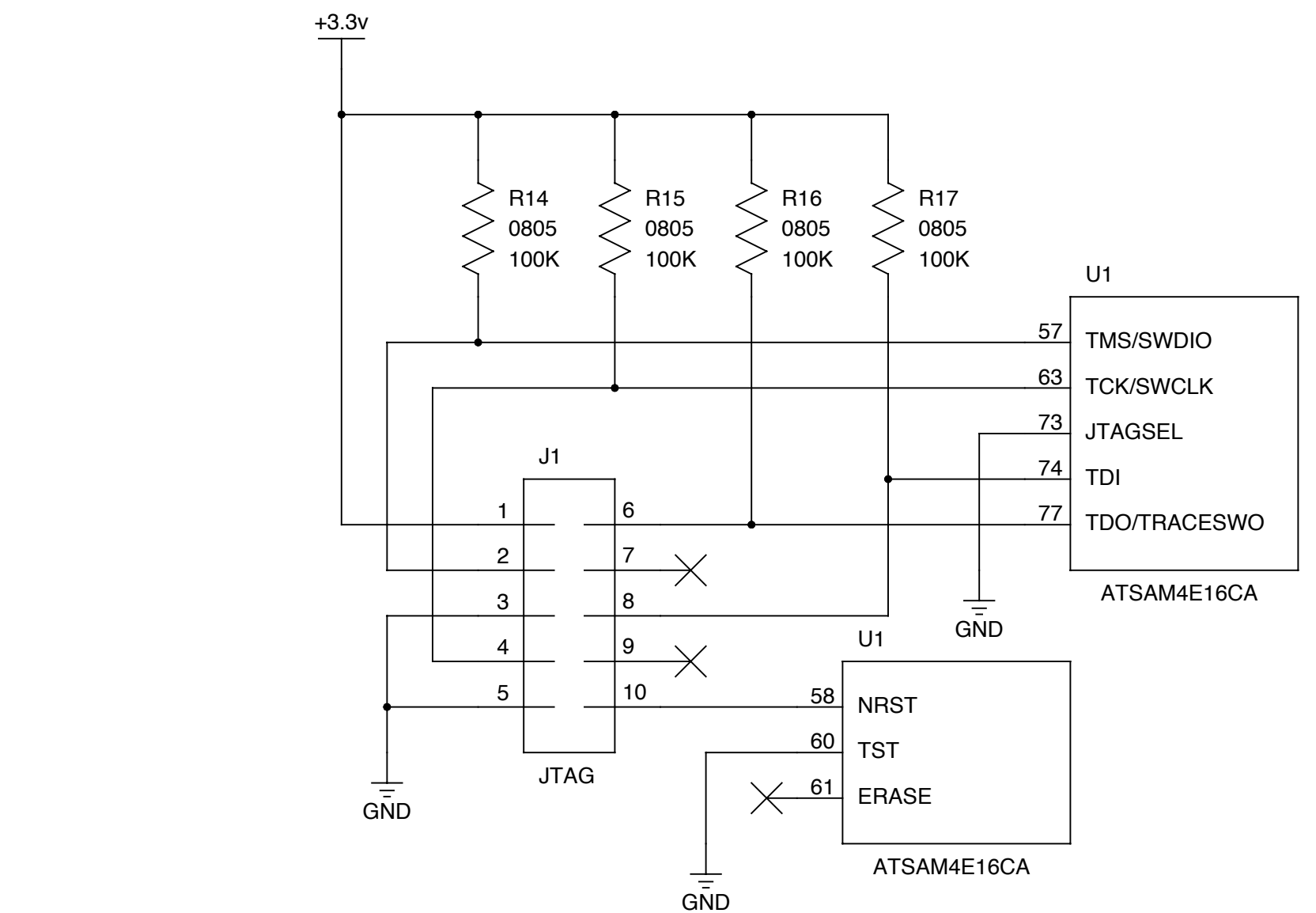
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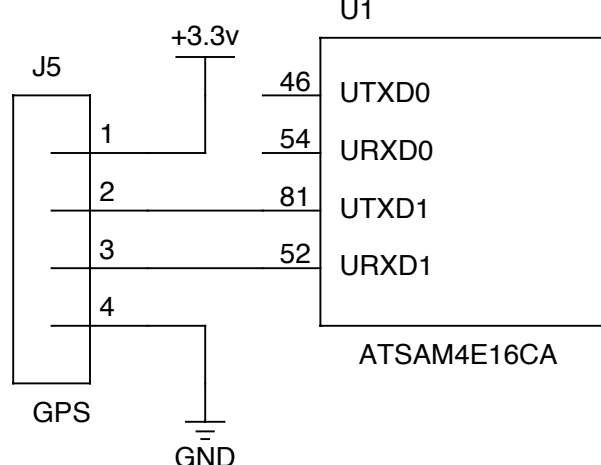
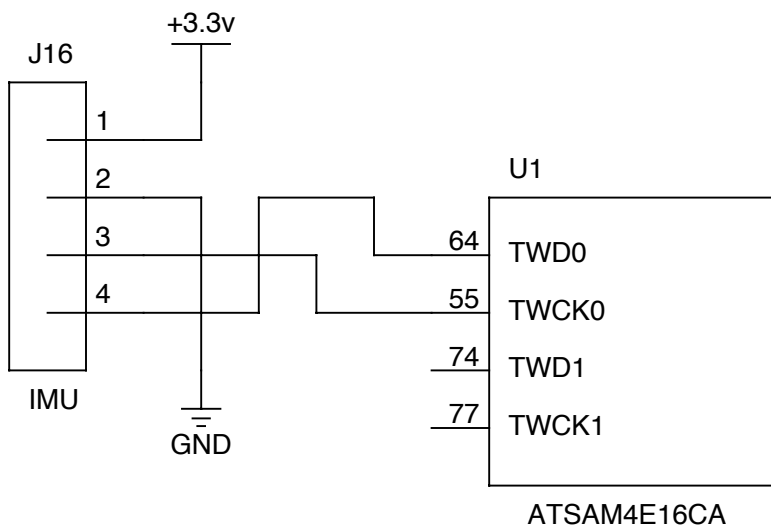
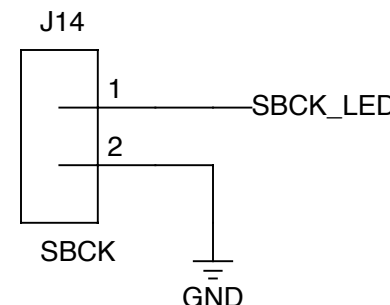
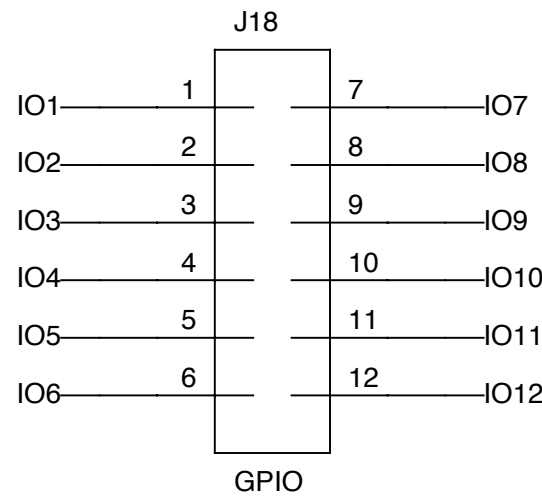
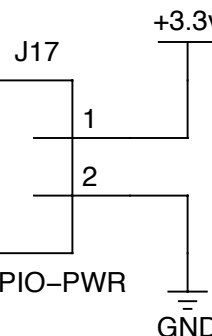
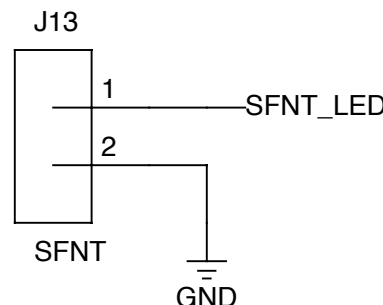
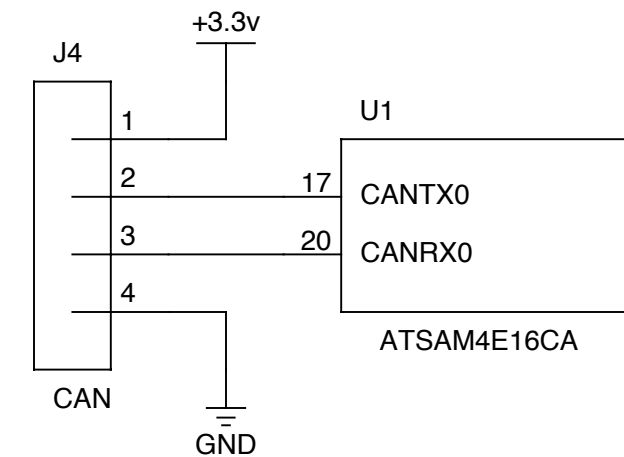
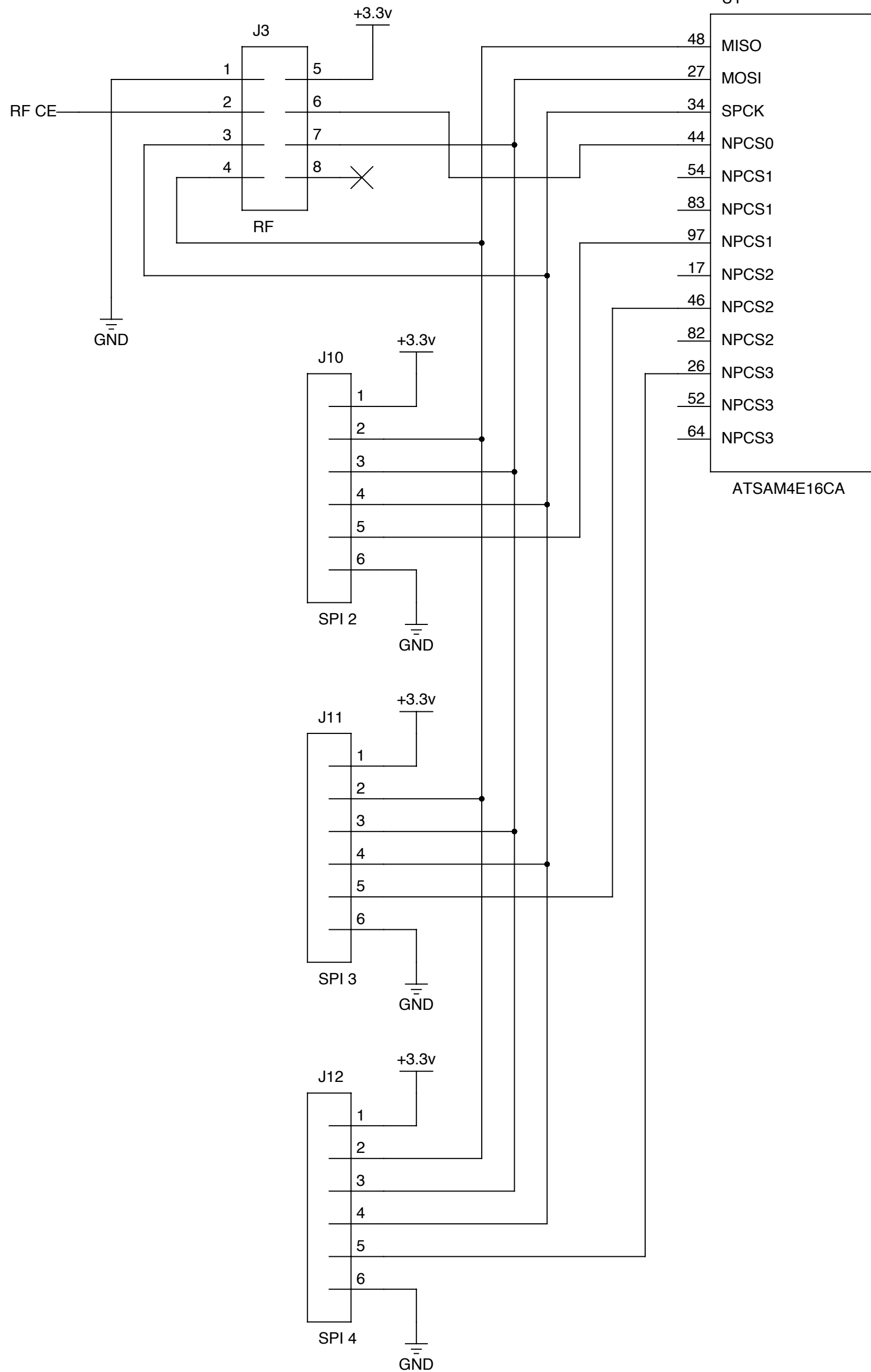
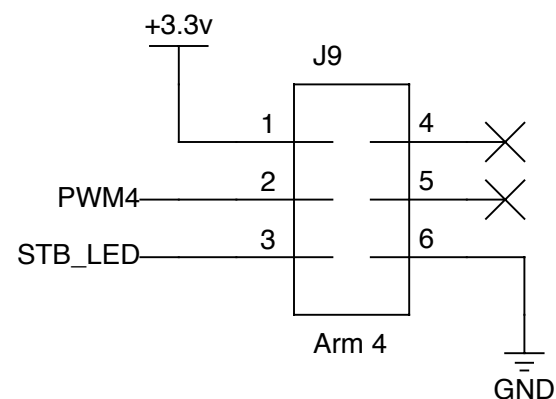
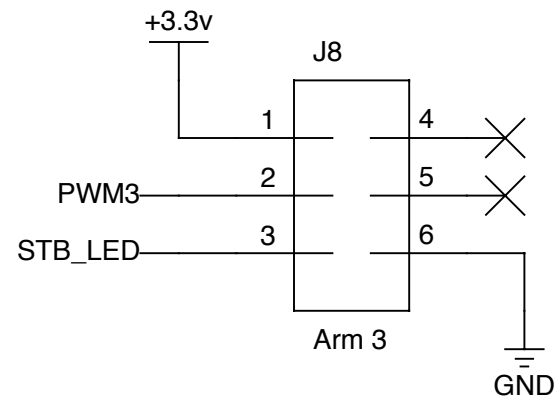
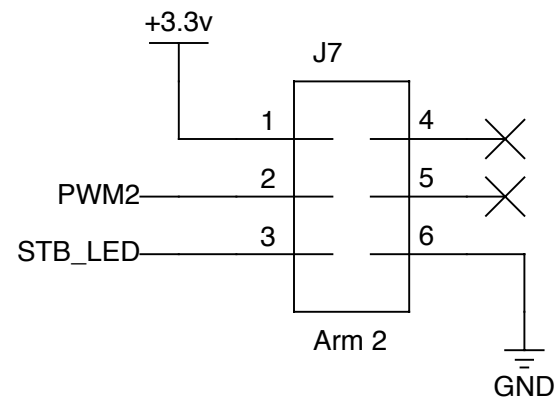
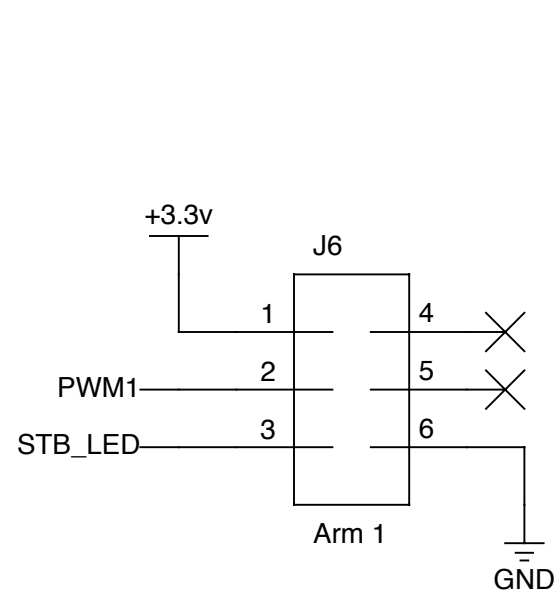
TITLE: Microcontroller I/O

PROJECT: Quadcopter Control Board

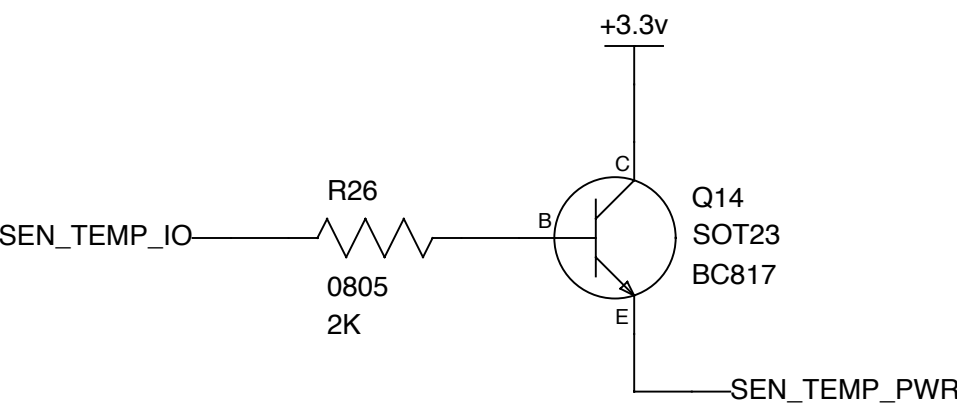
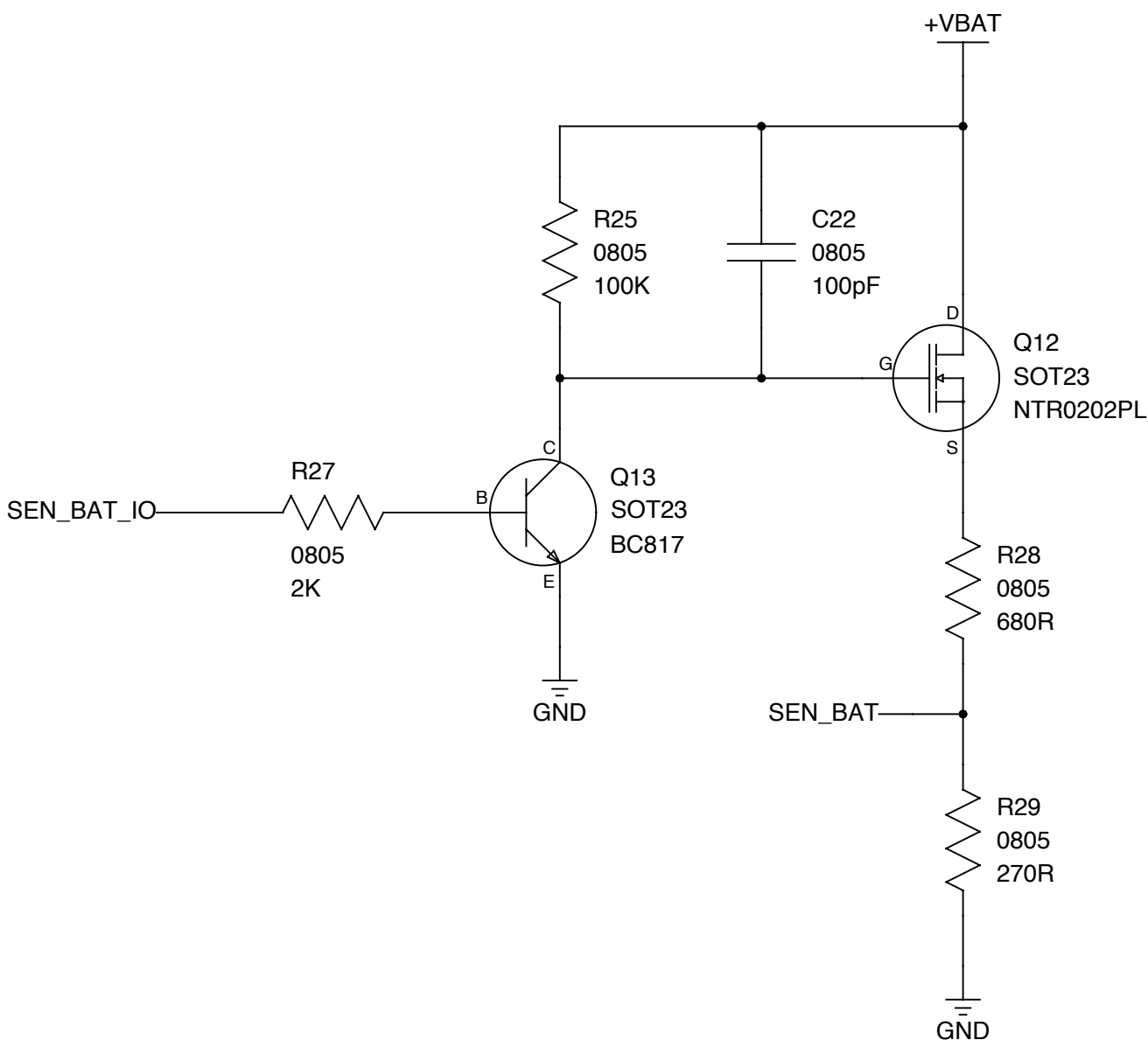
DRAWN BY: Ian Glen <ian@ianglen.me>



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DRAWN BY: Ian Glen <ian@ianglen.me>



TITLE: Peripheral Headers
PROJECT: Quadcopter Control Board
DRAWN BY: Ian Glen <ian@ianglen.me>



TITLE: Sensors
PROJECT: Quadcopter Control Board
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