



THE STATE UNIVERSITY
OF NEW JERSEY

Advance Search

Constraint Satisfaction Problems

Edgar Granados

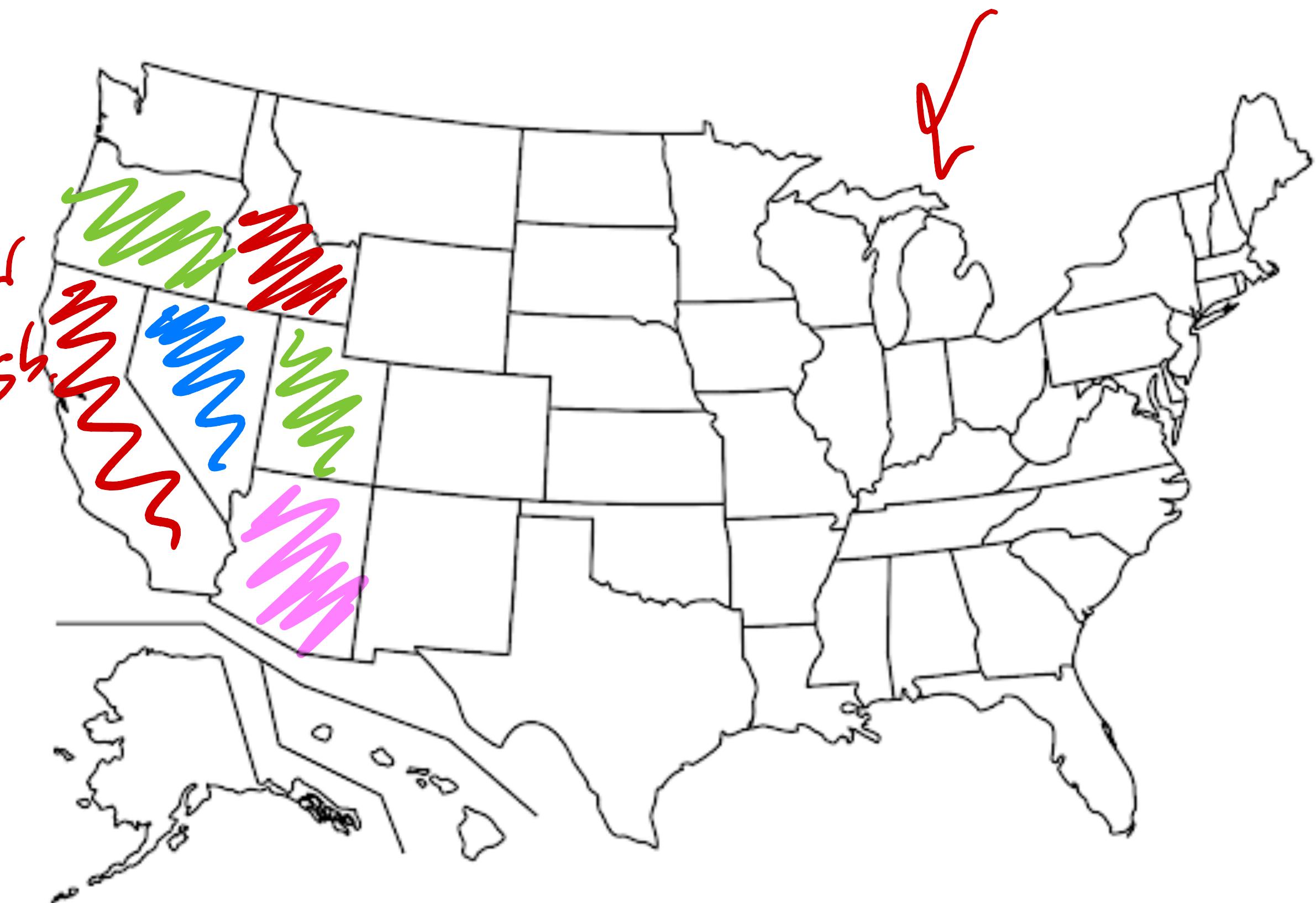
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Coloring Map

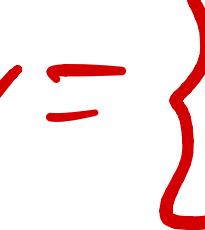
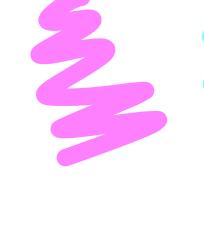
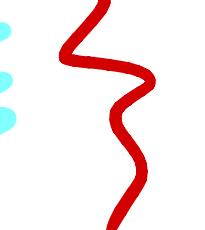
As classic search

Problem

- States: N^n of assignment
of values to some
or all
- Initial State: Empty Map
- Goal State(s): All states are colored
different than its Neigh.
- Actions: Col, state
- Transition model: Rel.
- Cost: 1

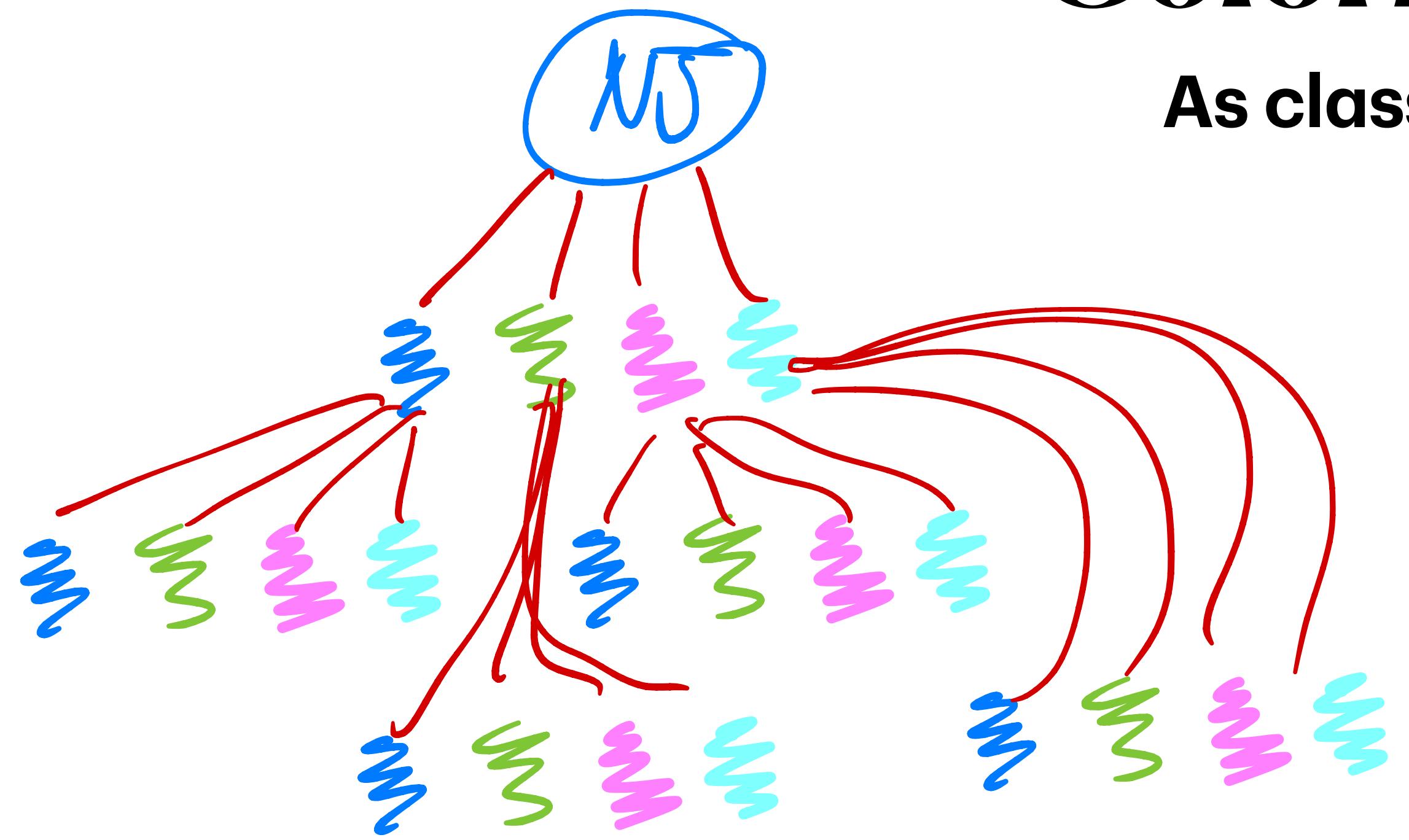


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$k = \{$     

Coloring Map

As classic search



R

Constraint Satisfaction Problems

Definition

- Problem where a state is defined as a set of constraints
- X: Set of variables $\{x_1, \dots, x_n\}$
- D: Set of domains $\{D_1, \dots, D_n\}. x_i \in D_i$
- C: Set of constraints



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Constraint Satisfaction Problems

State Space

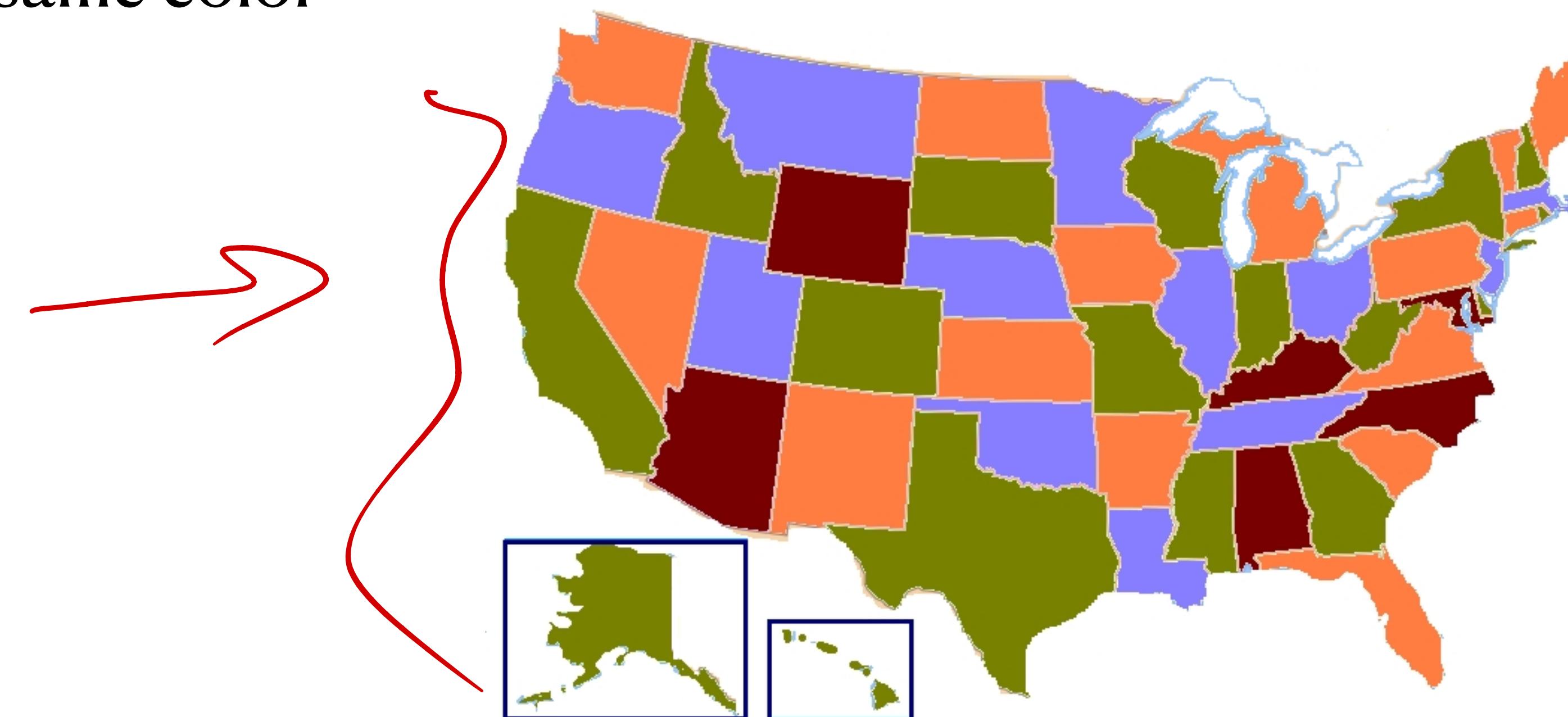
- **State:** assignment of values to some or all of the variables *VS states*
- **Consistent Assignment:** assignment not violating any constraint
- **Partial Assignment:** Assignment to some variables
- **Complete Assignment:** Assignment to all variables
- **Solution:** Consistent complete assignment

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CSP

Map Coloring

- Four color theorem (Appel and Haken, 1976)
 - Given any separation of a plane into contiguous regions, no more than four colors are required to color the regions of the map so that no two adjacent regions have the same color

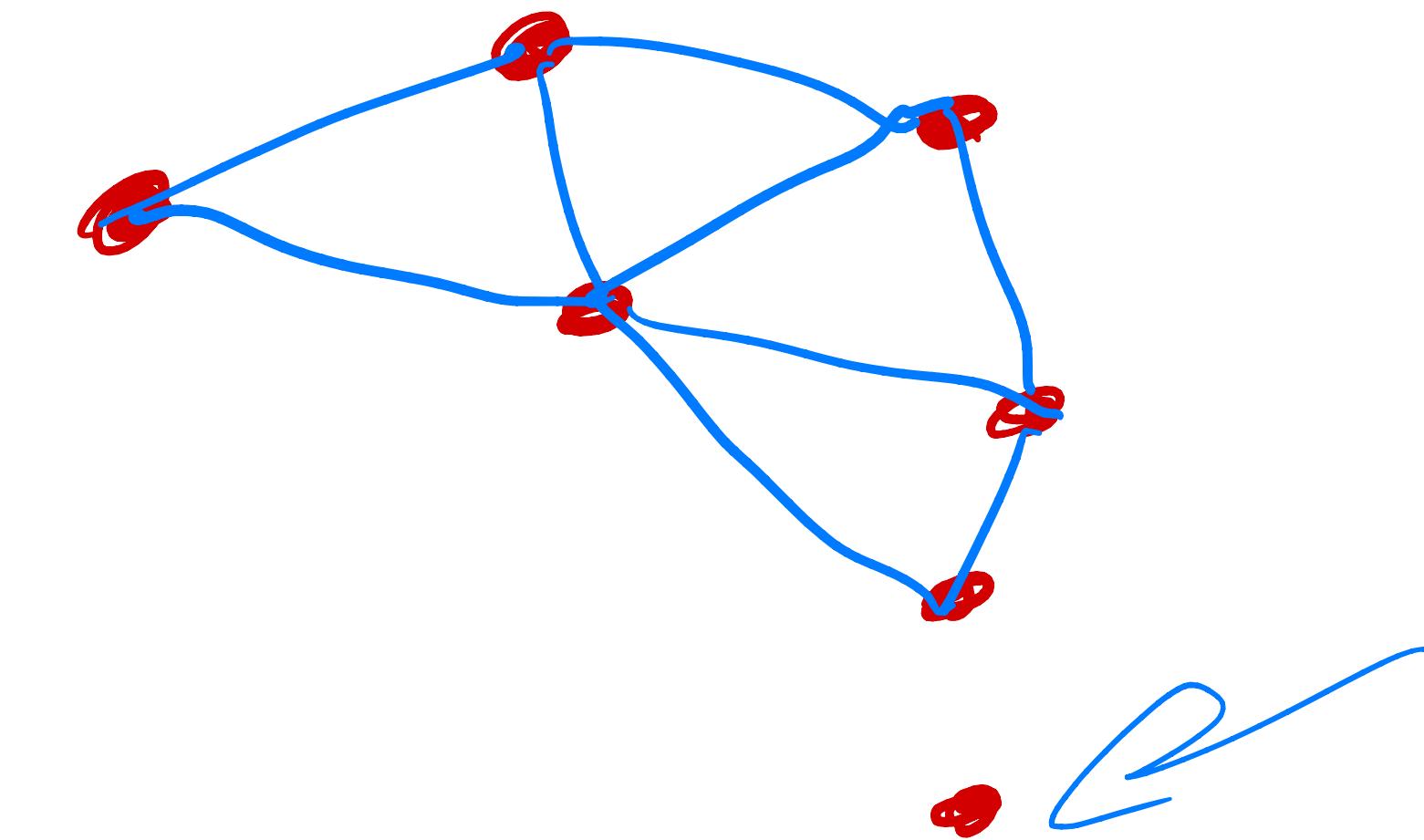


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Map Coloring

Example

- $X = \{WA, NT, SA, Q, NSW, V, T\}$
- $D_i = \{\text{red, green, blue}\}$
- $C = \{SA \neq WA, WA \neq NT, SA \neq NT, Q \neq SA, SA \neq NSW, SA \neq V, WA \neq NT, NT \neq Q, Q \neq NSW, NSW \neq V\}$



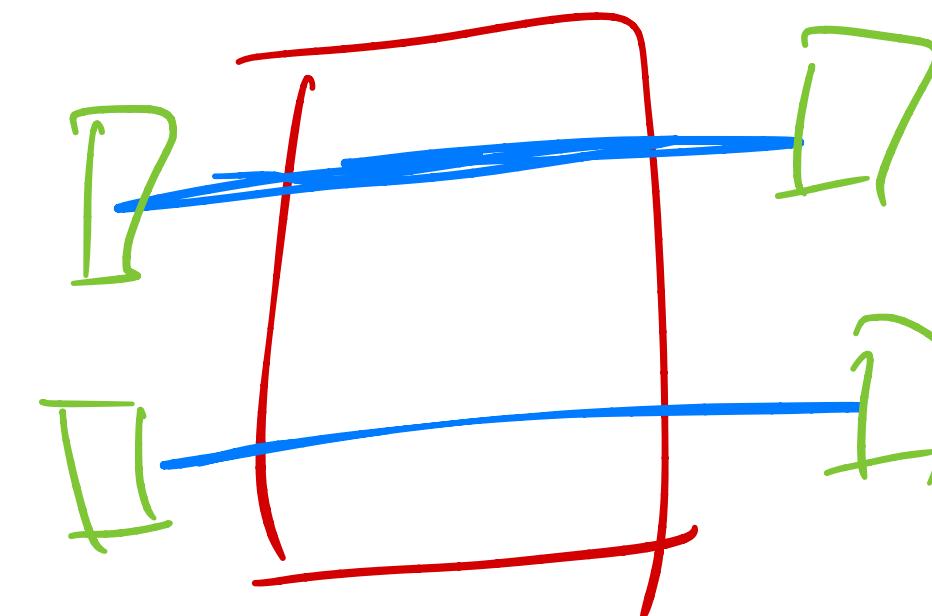
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CSP

- Why formulate a problem as a CSP?
- When to formulate a problem as a CSP?

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CSP Job-Shop Scheduling



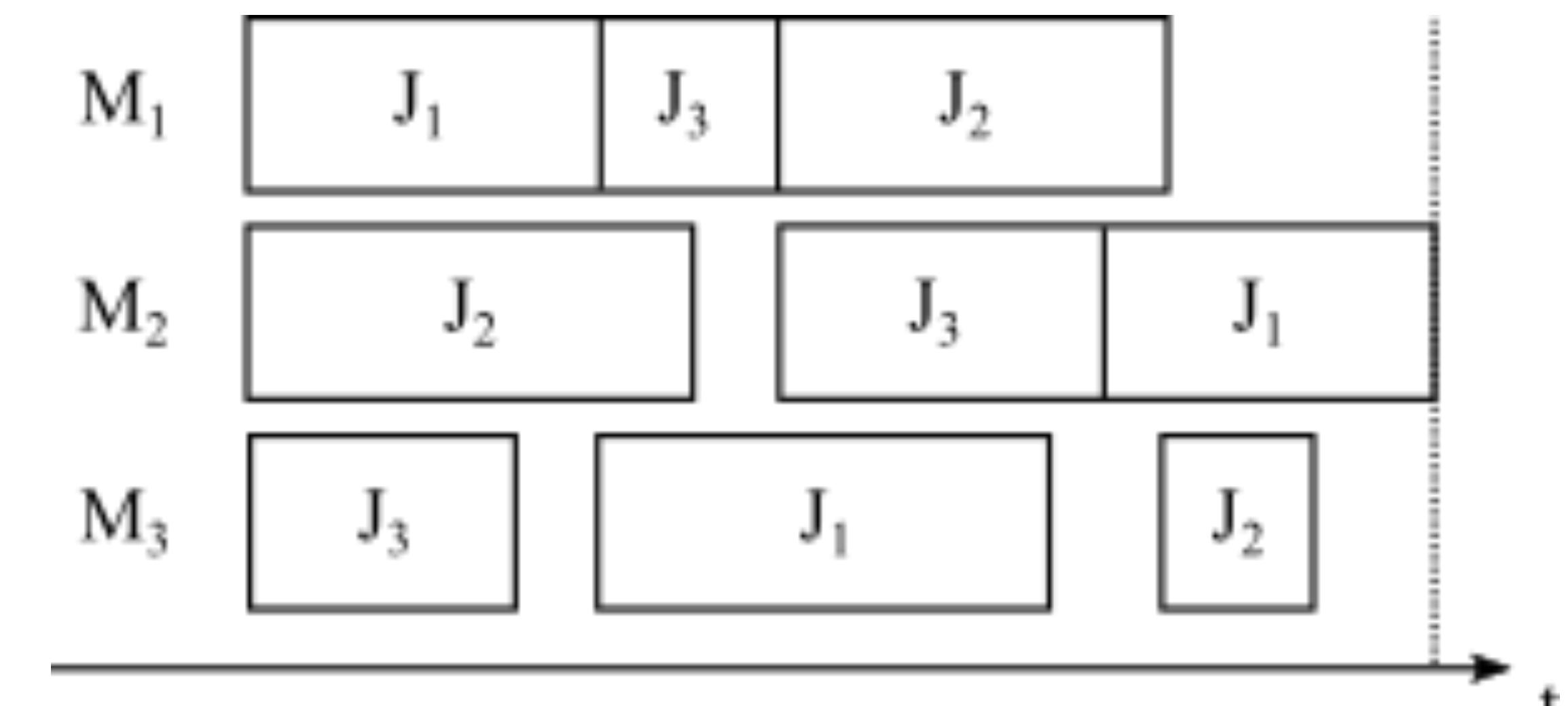
- Car assembly

1. Install Axes - 10 mins each
2. Affix wheels - 1 min each $\times 4$
3. Tighten nuts - 2 mins each $\times 4$
4. Affix hubcaps - 1 min each $\times 4$
5. Inspect - 3 mins

1

[0, 30]

15



R

- Car assembly
 - 1. Install Axes - 10 mins each
 - 2. Affix wheels - 1 min each
 - 3. Tighten nuts - 2 mins each
 - 4. Affix hubcaps - 1 min each
 - 5. Inspect - 3 mins

$T \in [0, 30]$
CSP

Job-Shop Scheduling

- (Each variable indicated the starting time of the corresponding task)

$$\mathbf{X} = \{A_i, W_{ij}, N_{ij}, C_{ij}, I\} \leftarrow k$$

$\mathbf{D} = \rightsquigarrow$ Represent the Starting time $D_k = [0, 27]$

$$\begin{aligned} A_i + 10 &\leq W_{ij} \\ W_{ij} + 1 &\leq N_{ij} \\ N_{ij} + 2 &\leq C_{ij} \\ C_{ij} + 1 &\leq I \end{aligned}$$

$$i = \{F, BS\} \quad j = \{R, L\}$$

R

- Car assembly
 - 1. Install Axes - 10 mins each
 - 2. Affix wheels - 1 min each
 - 3. Tighten nuts - 2 mins each
 - 4. Affix hubcaps - 1 min each
 - 5. Inspect - 3 mins

Job-Shop Scheduling

Disjunctive Constraints

$$i = \{F, B\} \quad j = \{R, L\}$$

- Suppose there are four workers to install wheels, but they have to share one tool that helps put the axle in place.

$$C_i = A_i + 10 \leq W_{ij}$$

$$W_{ij} + 1 \leq N_{ij}$$

$$N_{ij} + 2 \leq C_{ij}$$

$$C_{ij} + 1 \leq I$$

New C_k

$$\left[\begin{array}{l} A_F + 10 \leq k_B \\ \text{OR} \\ A_B + 10 \leq k_F \end{array} \right]$$

R

- Car assembly
 - 1. Install Axes - 10 mins each
 - 2. Affix wheels - 1 min each
 - 3. Tighten nuts - 2 mins each
 - 4. Affix hubcaps - 1 min each
 - 5. Inspect - 3 mins

Job-Shop Scheduling

Linear Programming

$[Q_1, Z_7]$

- How to model this using linear programming?

$$\begin{array}{ll} \text{Min} & \text{Inspect} \\ \text{s.t.} & \forall x_k \in X - \{\text{Inspect}\}: x_i + t_i \leq \text{Inspect} \\ & A_i + 10 \leq W_{ij} \\ & W_{ij} + 1 \leq N_{ij} \\ & N_{ij} + 2 \leq C_{ij} \\ & C_{ij} + 1 \leq I \end{array}$$

$i = \{F, BS\} \quad j = \{R, L\}$

R

CSP

Example: Crypt-arithmetic puzzle

$$\begin{array}{r} T \ W \ O \\ + \ T \ W \ O \\ \hline F \ O \ U \ R \end{array}$$

- $\mathbf{x}: \{T, W, O, F, U, R\}$
- $\mathbf{D}: D_i = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$
- $\mathbf{C}: \text{allDiff}(T, W, O, F, U, R)$

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CSP: Crypt-arithmetic puzzle

TWO + TWO - FOUR Linear programming?

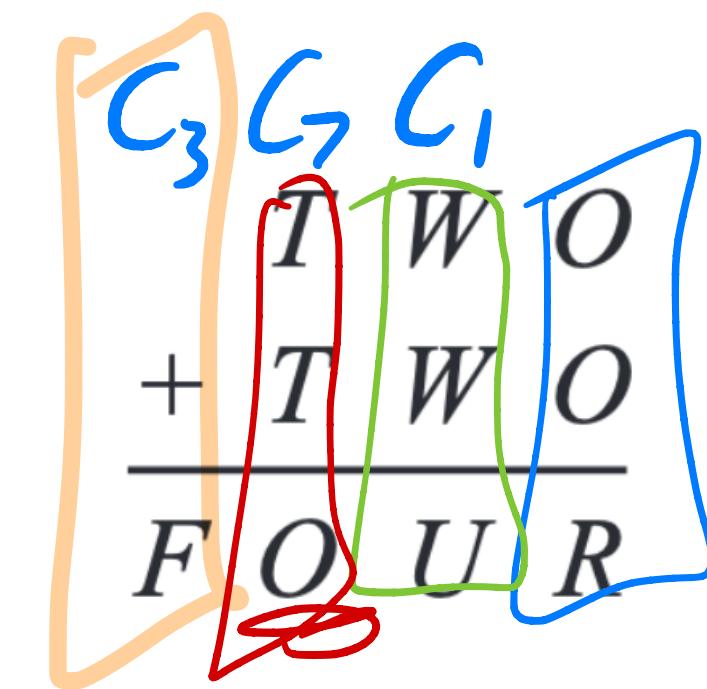
Min

S.t,

$$0 \leq x_i \leq 9$$

$$x_i \neq x_j$$

$$\begin{array}{r} \textcircled{O} \quad \boxed{\text{I}} \\ \text{T} \quad \text{W} \quad \textcircled{5} \\ + \quad \text{T} \quad \text{W} \quad \textcircled{5} \\ \hline \text{F} \quad \text{S} \quad \text{Q} \quad \textcircled{0} \end{array}$$

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CSP: Crypt-arithmetic puzzle

Hypergraph

- Graph showing n-ary constraints

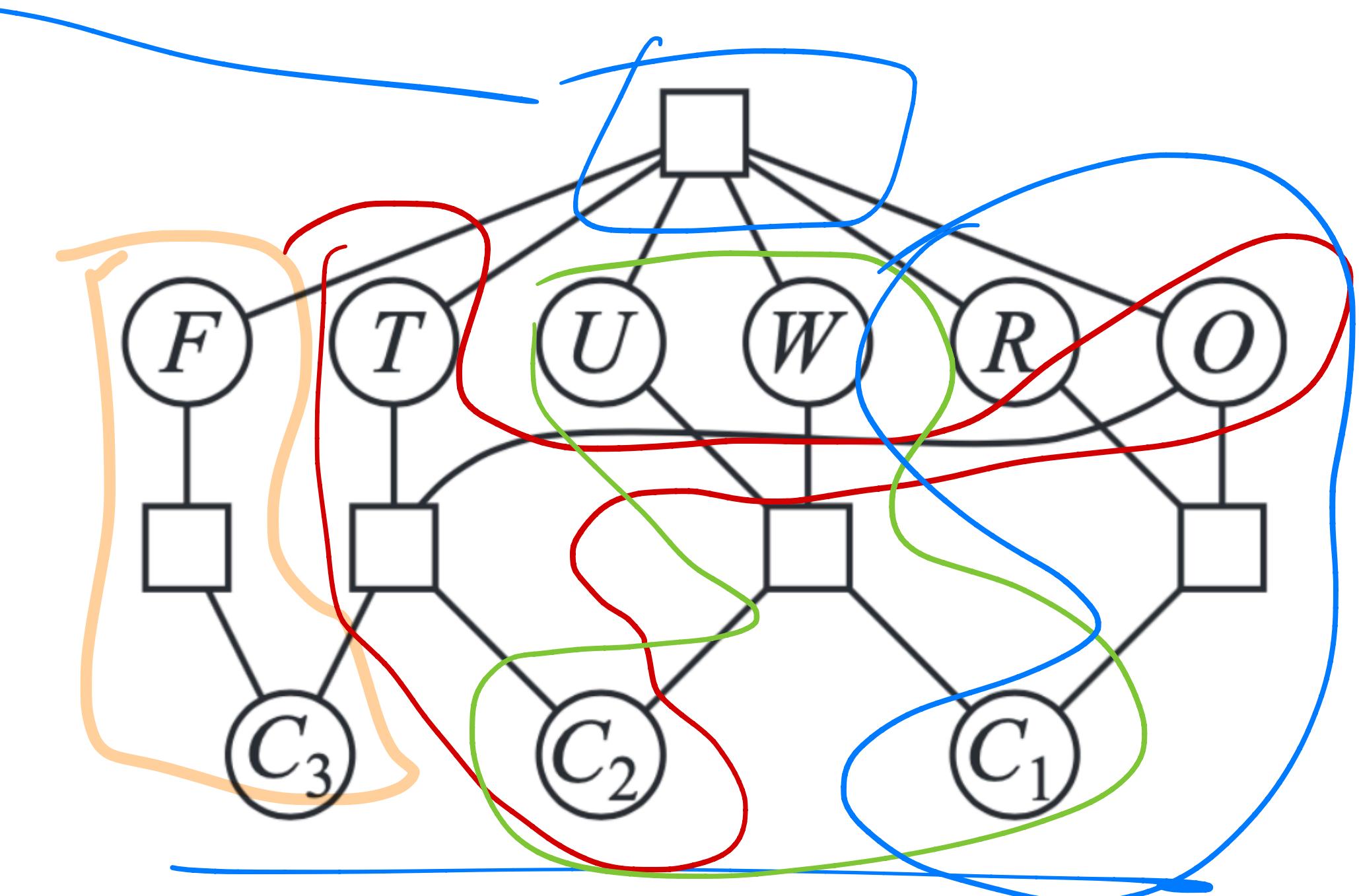
- All different constraint
- Column constraints

$$0 + 0 = R + 10 \cdot C_1$$

$$C_1 + W + W = U + 10 \cdot C_2$$

$$C_2 + T + T = O + 10 \cdot C_3$$

$$C_3 = F$$



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Constraint Propagation

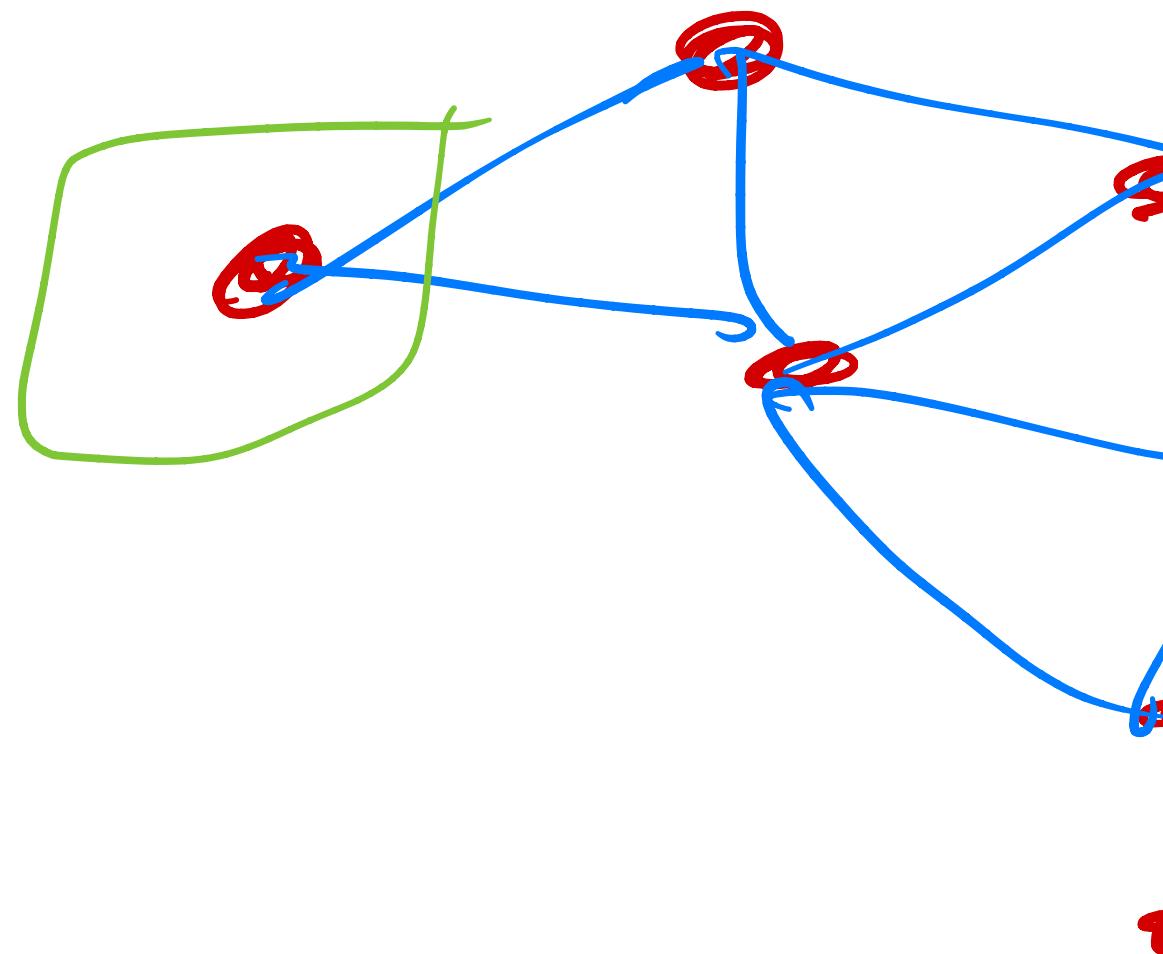
- Shrink the domain of each variable based on the constraints
- Faster search
- Force consistency:
 - Node consistency
 - Arc Consistency
 - Path Consistency
 - K-consistency

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Constraint Propagation

Node Consistency

- A variable is node consistent if all values in the variables domain satisfy the variables unary constraints
- A network is node-consistent if every variable in the network is node consistent

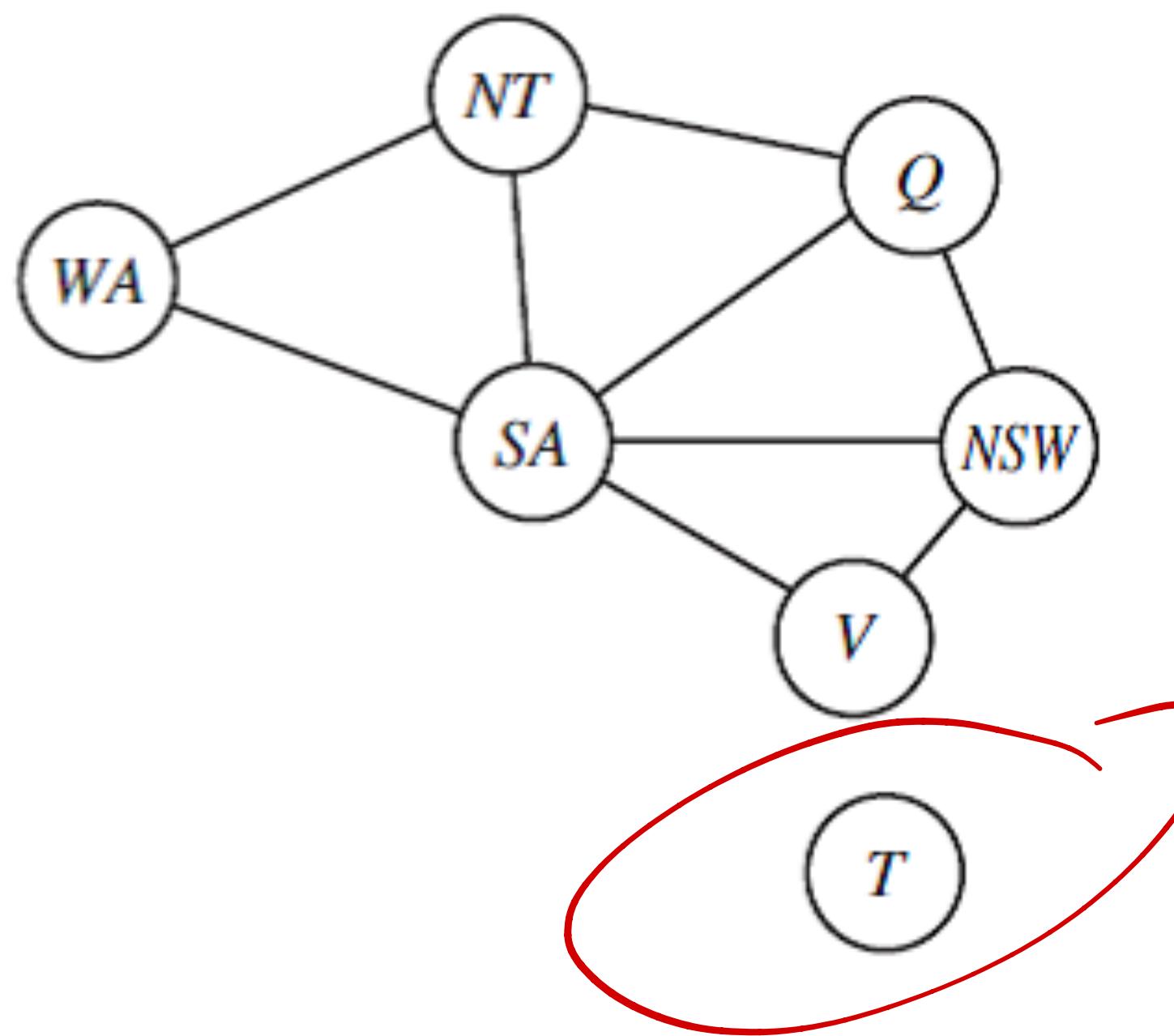


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Constraint Propagation

Arc Consistency

- A variable is arc consistent if all values in the variables domain satisfy the variables binary constraints
- X_i is arc-consistent with respect to X_j if $\forall d \in D_i, \exists d' \in D_j$ that satisfies (X_i, X_j)



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Arc Consistency

- $X: X_1, X_2$
- $D: D_i = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$
- $C: X_1 = \sqrt{X_2}$

Example

$$\begin{aligned} \mathcal{D}_1 &= \{0, 1, \dots, 9\} \\ \mathcal{D}_2 &= \{0, 1, \dots, 9\} \end{aligned}$$

Make X_1 arc consistent with X_2

Make X_2 arc consistent with X_1

$$\begin{aligned} \mathcal{D}_1 &= \{0, 1, 2, 3\} \\ \mathcal{D}_2 &= \{0, 1, 4, 9\} \end{aligned}$$

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Arc Consistency

Example

function AC-3(*csp*) **returns** false if an inconsistency is found and true otherwise

inputs: *csp*, a binary CSP with components (X, D, C)

local variables: *queue*, a queue of arcs, initially all the arcs in *csp*

while *queue* is not empty **do**

$(X_i, X_j) \leftarrow \text{REMOVE-FIRST}(\text{queue})$

if REVISE(*csp*, X_i , X_j) **then**

if size of $D_i = 0$ **then return** false

for each X_k **in** $X_i.\text{NEIGHBORS} - \{X_j\}$ **do**

 add (X_k, X_i) to *queue*

return true

function REVISE(*csp*, X_i , X_j) **returns** true iff we revise the domain of X_i

$\text{revised} \leftarrow \text{false}$

for each x **in** D_i **do**

if no value y in D_j allows (x, y) to satisfy the constraint between X_i and X_j **then**

 delete x from D_i

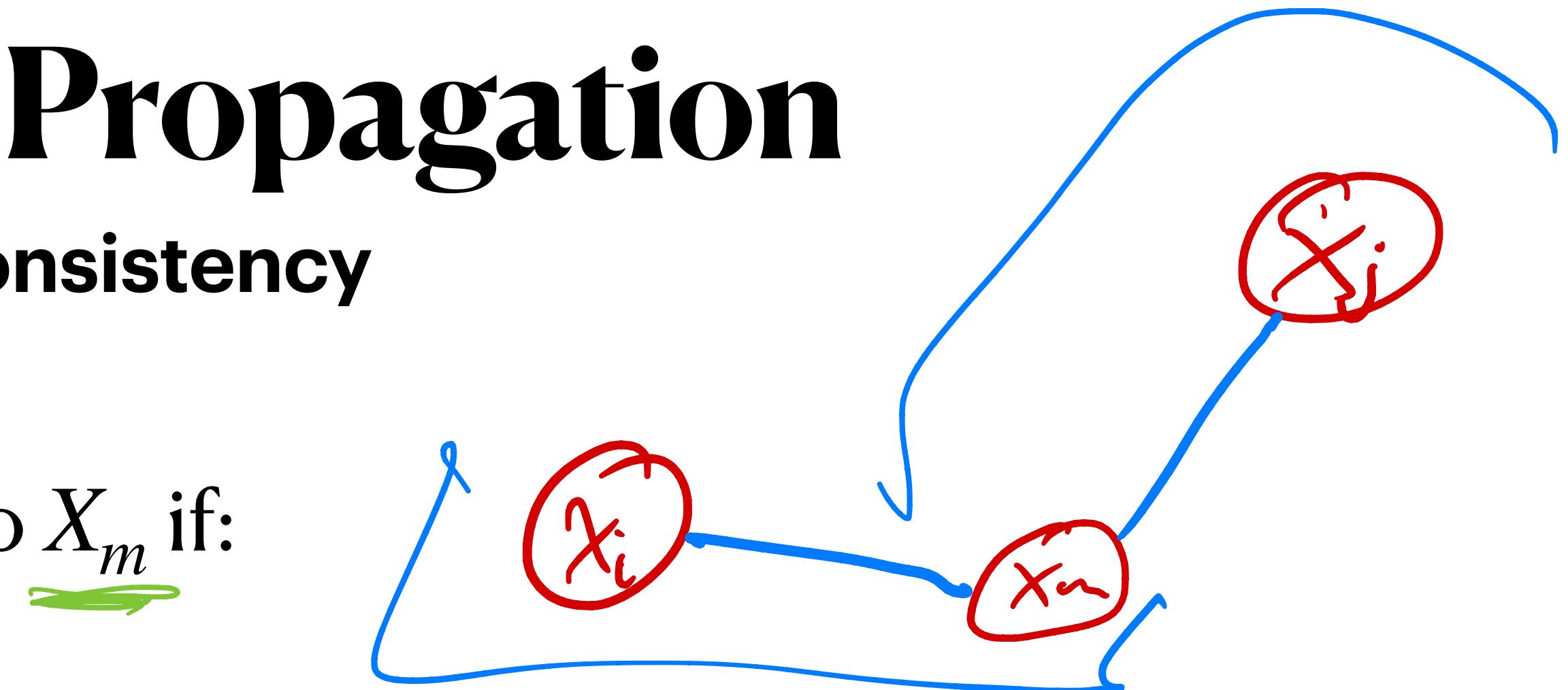
$\text{revised} \leftarrow \text{true}$

return *revised*

Constraint Propagation

Path Consistency

- (X_i, X_j) is path consistent with respect to $\underline{X_m}$ if:
~~(X_i, X_j) is path consistent~~
 - An assignment exists such that (X_i, X_m) is arc consistent
 - An assignment exists such that (X_m, X_j) is arc consistent



Constraint Propagation

Path Consistency

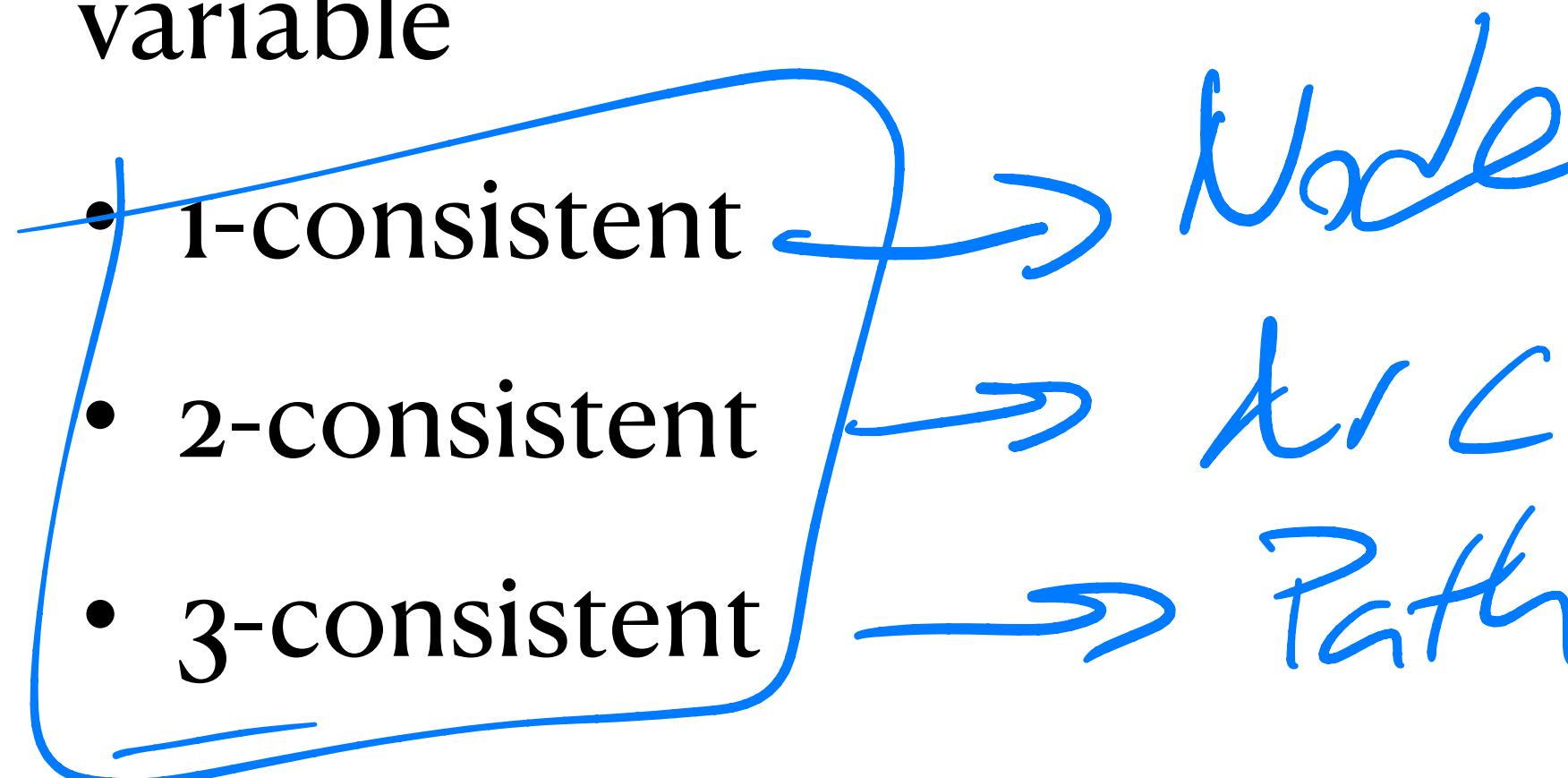
- (X_i, X_j) is path consistent with respect to X_m if:
 - (X_i, X_j) is arc consistent
 - An assignment exists such that (X_i, X_m) is arc consistent
 - An assignment exists such that (X_m, X_j) is arc consistent

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Constraint Propagation

K-Consistency

- A CSP is k-consistent if, for any set of k-1 variables and for any consistent assignment to these variables, a consistent value can always be assigned to any kth variable



Constraint Propagation

K-Consistency

- A CSP is k-consistent if, for any set of $k-1$ variables and for any consistent assignment to these variables, a consistent value can always be assigned to any k th variable
- A CSP is strongly k-consistent if it is k-consistent and is also $(k-1)$ -consistent, $(k-1)$ -consistent, (...), 1-consistent
- If a CSP has n variables, and it is strongly n -consistent, then a solution can be easily found by setting any variable to any value from its reduced domain



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Example Sudoku

- $X: \{X_{ij}\}_{j,i \in \{1, 2, 3, 4\}}$
- $D: D_{ij} = \{1, 2, 3, 4\}$
- $C:$

$$x_{ii} \neq x_{i1} \neq x_{i2} \neq x_{i3} \neq x_{i4}$$

$$i \in \{1, 2, 3, 4\}$$

$$x_{1j} \neq x_{2j} \neq x_{3j} \neq x_{4j} \quad j \in \{1, 2, 3, 4\}$$

$$(x_{11} \neq x_{12} \neq x_{21} \neq x_{22}) \wedge \\ (x_{13} \neq x_{14} \neq x_{23} \neq x_{24}) \wedge \dots$$

4	3	2	1
2	1	4	3
1	2	3	4
3	4	1	2



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Constraint Propagation

Backtracking Search

- Inference is not enough to solve CSP
 - $X: X_1, X_2$
 - $D: D_i = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$
 - $C: X_1 = \sqrt{X_2}$

$$X_1 = f(X_2)$$

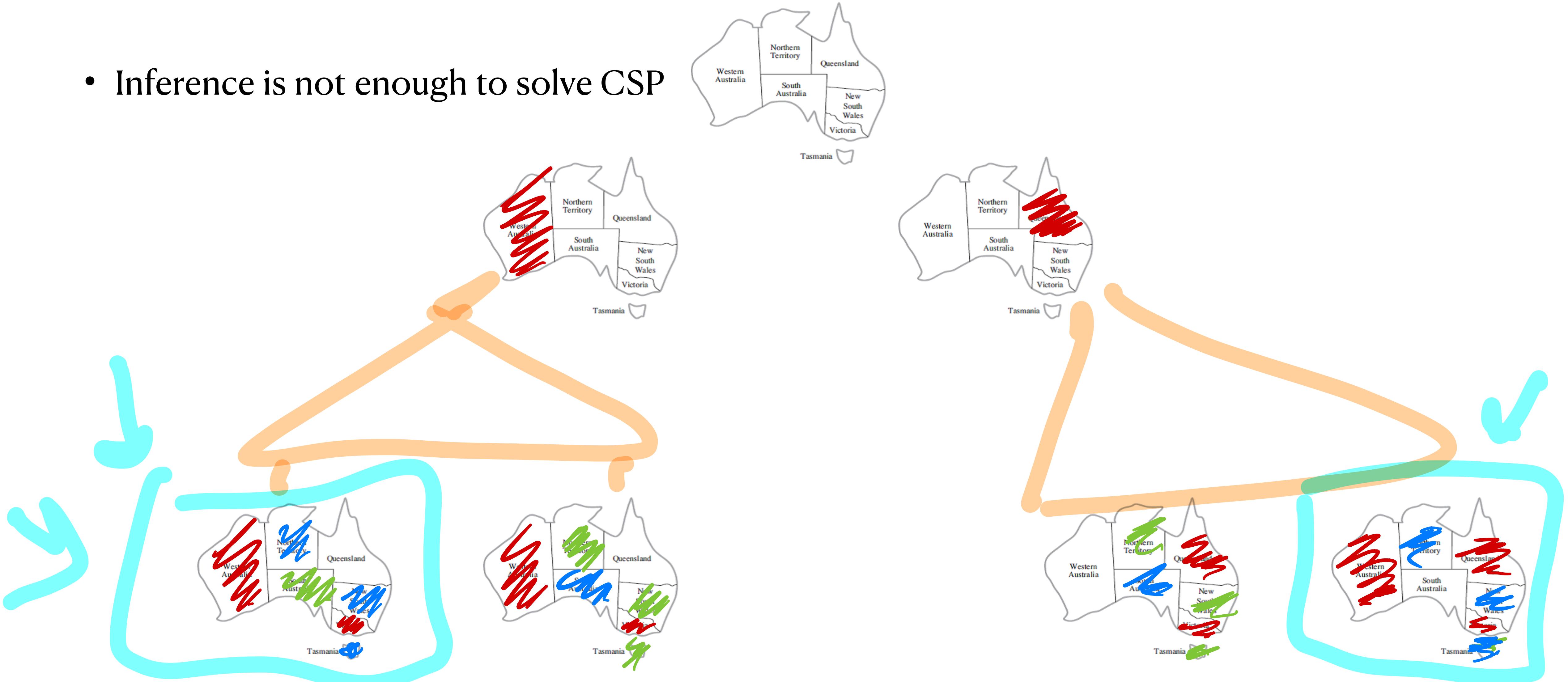
$$\begin{aligned}D_1 &= \{0, 1, 2, 3\} \\D_2 &= \{0, 1, 4, 9\}\end{aligned}$$

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Constraint Propagation

Backtracking Search

- Inference is not enough to solve CSP



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Constraint Propagation

Backtracking Search

- Inference is not enough to solve CSP
- Commutativity
 - A problem is commutative if the order of application of the set of actions does not matter



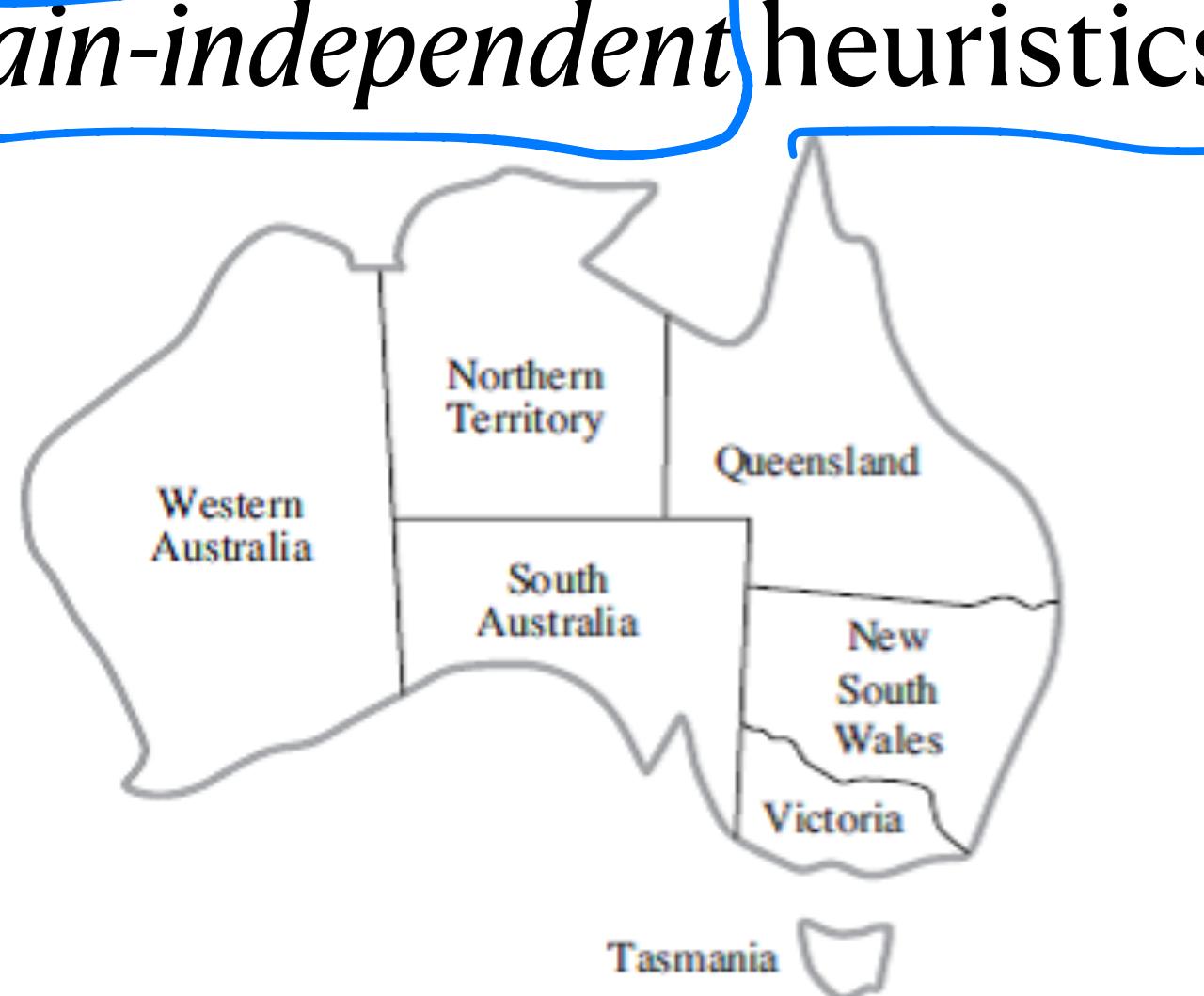
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Constraint Propagation

Backtracking Search

- Inference is not enough to solve CSP
- **Commutativity**
 - A problem is commutative if the order of application of the set of actions does not matter
- Use *domain-independent* heuristics

$$A^* = 9 \text{ th}$$



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Backtracking Search

Variable and Value Ordering

- Minimum remaining-values heuristic

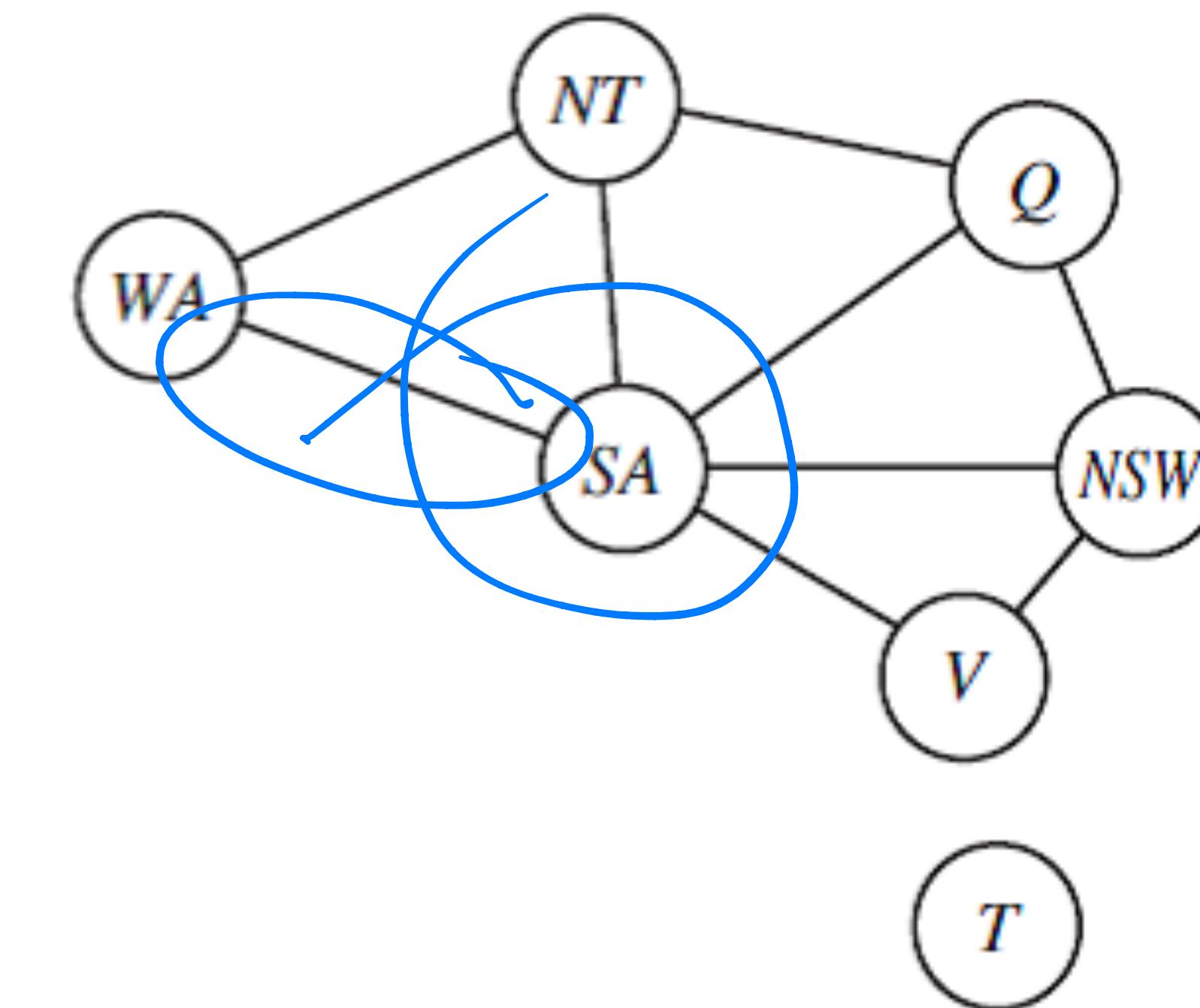
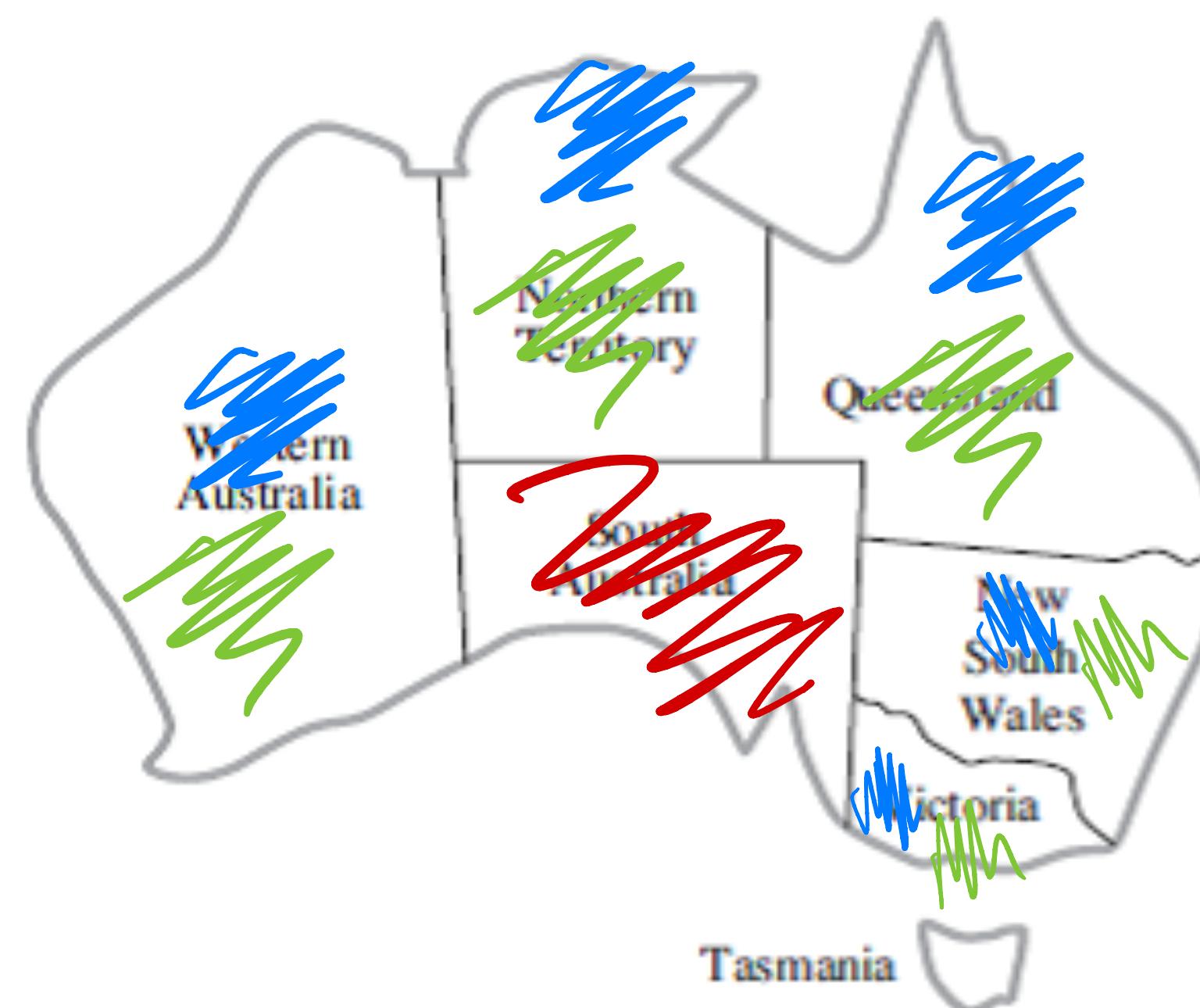


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Backtracking Search

Variable and Value Ordering

- Degree heuristic: Select the variable that is involved in the largest number of constraints on other unassigned variables

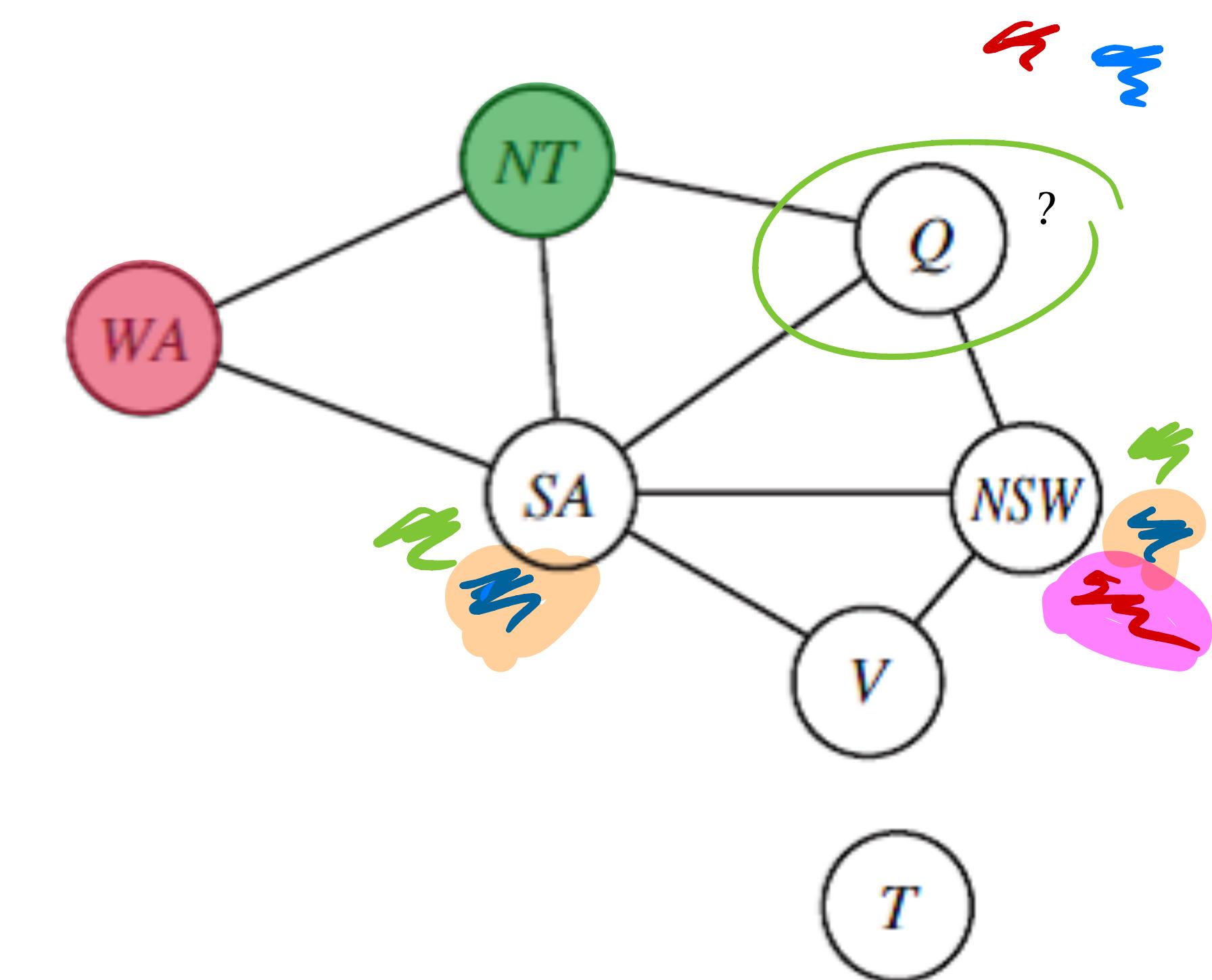


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Backtracking Search

Variable and Value Ordering

- Least-constraining-value: Select the variable that rules out the fewest choices for the neighboring variables in the constraint graph



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Backtracking Search

function BACKTRACKING-SEARCH(*csp*) **returns** a solution, or failure
 return BACKTRACK({ }, *csp*)

function BACKTRACK(*assignment*, *csp*) **returns** a solution, or failure

if *assignment* is complete **then return** *assignment*

var \leftarrow SELECT-UNASSIGNED-VARIABLE(*csp*)

for each *value* in ORDER-DOMAIN-VALUES(*var*, *assignment*, *csp*) **do**

if *value* is consistent with *assignment* **then**

 add {*var* = *value*} to *assignment*

inferences \leftarrow INFERENCE(*csp*, *var*, *value*)

if *inferences* \neq failure **then**

 add *inferences* to *assignment*

result \leftarrow BACKTRACK(*assignment*, *csp*)

if *result* \neq failure **then**

return *result*

 remove {*var* = *value*} and *inferences* from *assignment*

return failure

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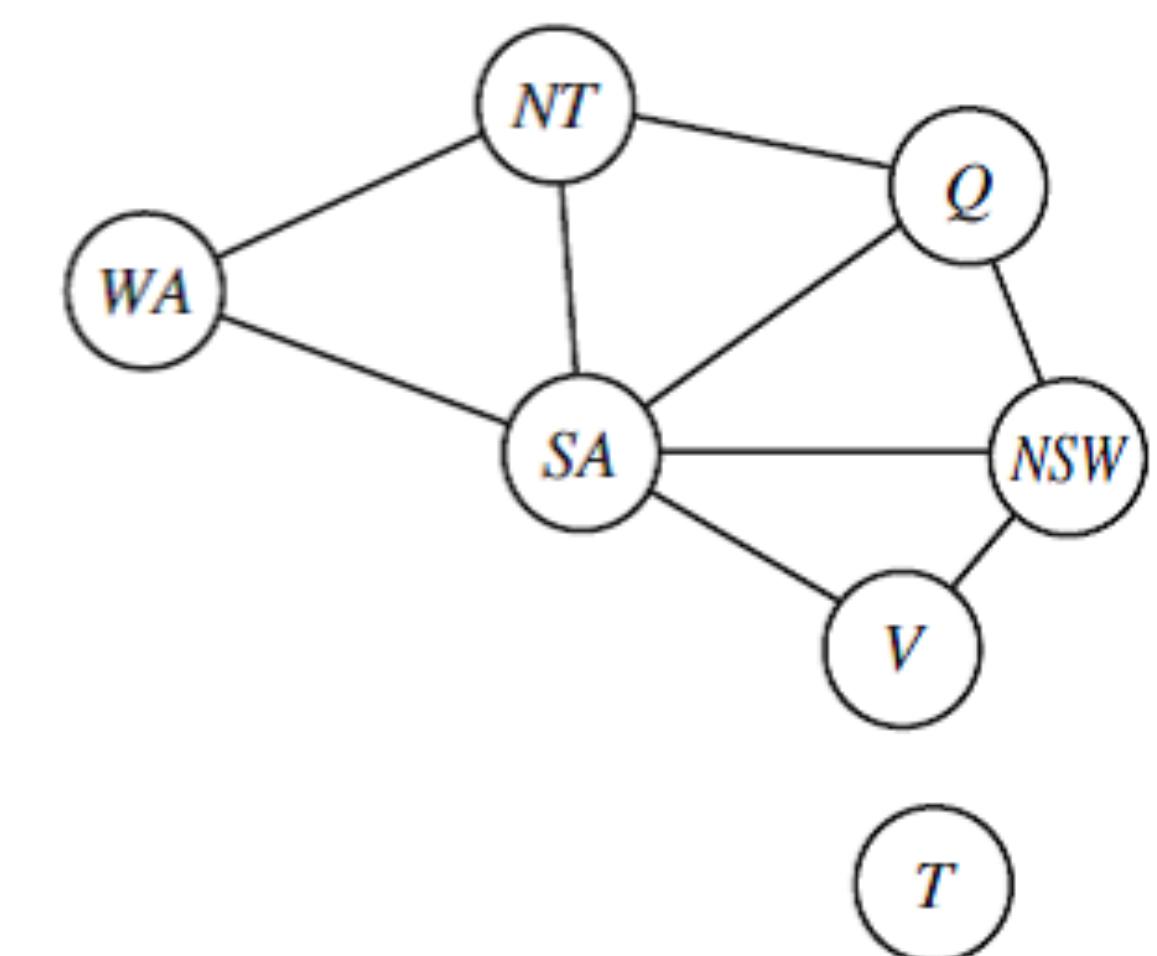
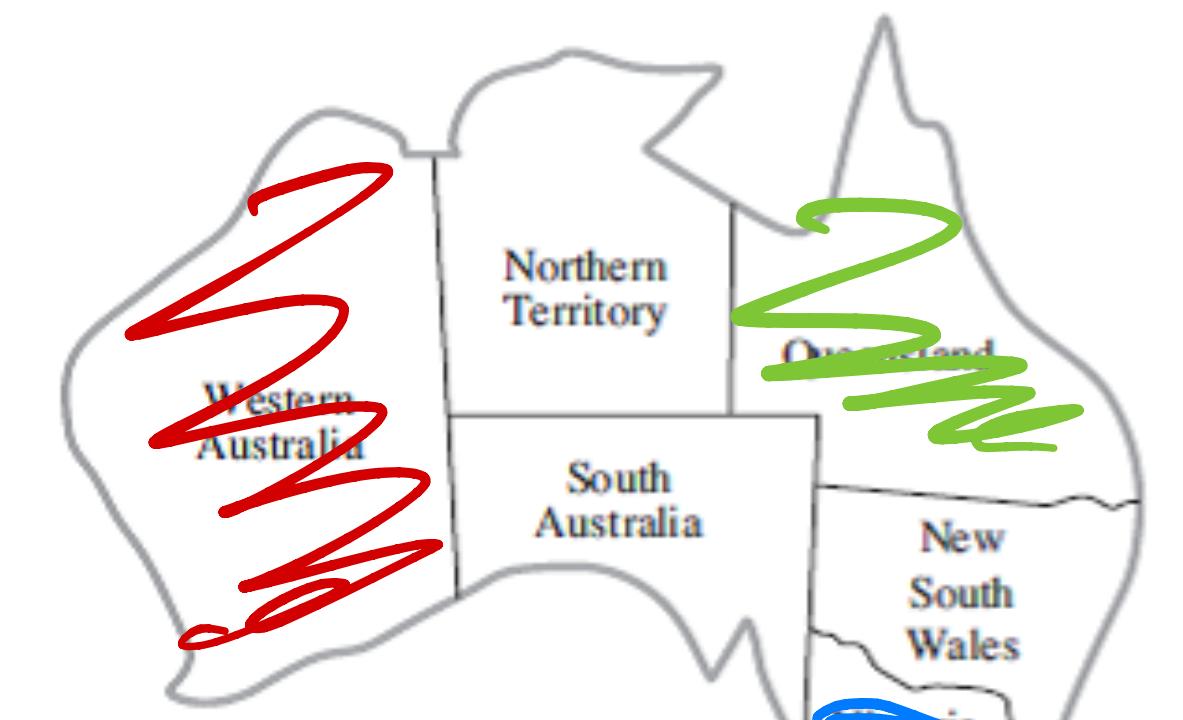
Backtracking Search

Intelligent Backtracking

- Forward Search

Initial domains
After $WA=red$
After $Q=green$
After $V=blue$

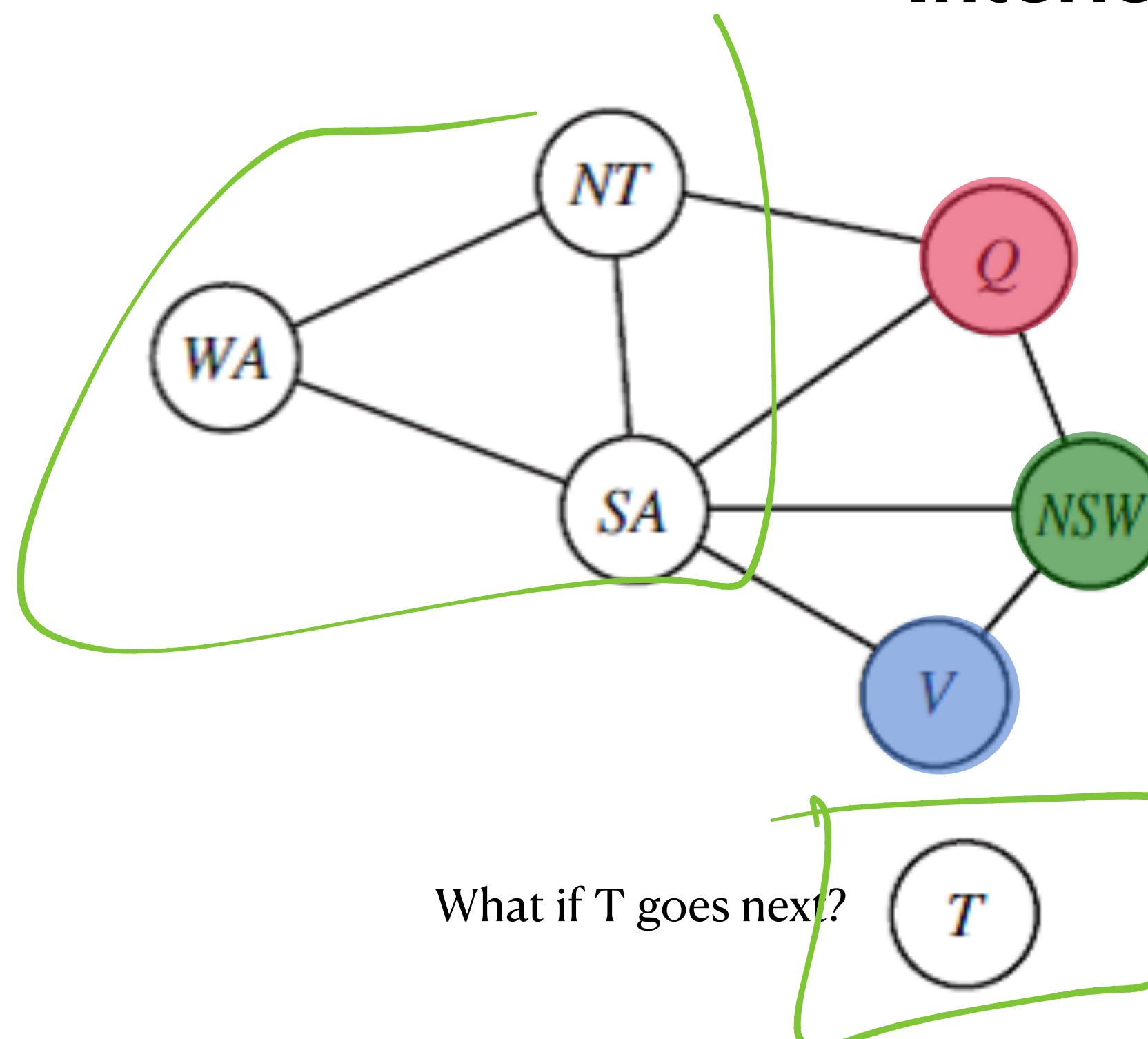
WA	NT	Q	NSW	V	SA	T
Red	Green	Red	Red	Red	Green	Red
Red	Blue	Red	Red	Red	Green	Red
	Blue	Green	Blue	Red	Green	Red
	Blue	Green	Blue	Blue	Blue	Red



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Backtracking Search

Interleaving search and inference



Initial domains
After WA=red
After Q=green
After V=blue

WA	NT	Q	NSW	V	SA	T
z y z	z y z	z y z	z y z	z y z	z y z	z y z
r r r		g g g	g g g	b b b	r r r	r r r
	b b b		g g g		b b b	
		g g g		b b b		

CSP

More (possible) Improvements

- Local Search
- Structure of the problem
 - Connected components
 - Topological sort

