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Make the Mars rover collect rocks using a **List** of directions.



- 1) Choose a robot **sprite**, a suitable planet **background**, and a rock **sprite**.
- 2) When the robot touches a rock, it picks it up (hides it).Add this code to the rock.

Clicking the green flag shows the rocks and places the rover at the start position.

3) Place the robot at a suitable start position, add the **start** block and **go to x,y** to the robot. The x,y position is where you placed the robot.



The plan is a list of directions to move the robot  $\mathbf{u}$  (up)  $\mathbf{d}$  (down)  $\mathbf{l}$  (left)  $\mathbf{r}$  (right).

- 4) Make a List called plan for the robot plan.
- 5) Add robot code to ask for the input plan and set plan to the answer.



Input a plan like "ddddddrrrrruuuurrrrr" to move the robot and collect rocks. Use a loop to work through the List.

6) Set a loop variable to 1, for the first List item.

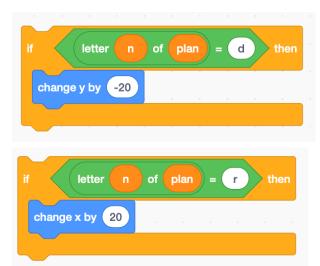


- 7) Add a loop that repeats for the length of the plan.
- 8) Inside the repeat loop, change n by 1 each time around, and wait a second.
- repeat length of plan

  change n ▼ by 1

  wait 1 seconds
- 9) The **first** thing it should do **inside** the loop (before **change n**) is move the robot in the direction given by **letter n of the plan**. If this is **equal(=)** to **d** then **change** y
- 10) Check for **r** (right) and **change x** positively **if** it finds it.

negatively to move down.



Run your code with the **green flag**, **d** and **r** might be enough to collect one rock.

Duplicate the rock.

Do you need to add code for **u** (change y positively) or **l** (change x negatively) instructions now?

**Save** your code with a good name. **File > Save now**