

Powertip alphanumeric dot matrix liquid crystal displays

Reflective types - RS stock numbers 214-3238, 214-3244, 214-3250, 214-3266, 214-3272, 214-3288, 214-3294, 214-3301, 214-3317, 214-3323, 214-3339, 214-3345, 214-3351, 294-8667, 294-8689, 294-8695, 294-8702, 294-8718, 294-8724, 294-8746, 294-8752 EL types - RS stock numbers 214-3367, 214-3373, 214-3395, 214-3402, 214-3418 LED types - RS stock numbers 214-3480, 214-3496, 214-3519, 214-3525, 214-3531, 214-3547, 214-3553, 214-3569, 214-3575, 215-3617, 294-8774, 294-8780, 294-8796, 294-8803, 294-8819

Intelligent, alphanumeric, dot matrix modules with integral CMOS microprocessor and LCD display drivers. The modules utilise a 5×7 dot matrix format with cursor, and are capable of displaying 192 different alphanumeric characters and symbols. The modules are available in twisted nematic and super twisted nematic grey mode. Reflective types are available in TN and STN, EL backlit types in TN, LED backlit transmissive types in TN LED backlit transflective types in STN. Inverters are required to drive the EL backlit types.

Applications

- Data terminals
- Medical instruments
- Hand-held instruments
- Hand-held data terminals
- Electronic typewriters
- Point of sale terminals
- Test instruments
- Word processors.

Features

- Single 5V power supply (excluding EL types)
- Wide viewing angle (STN)
- High contrast
- Interfaces to a 4 or 8-bit data bus
- ASC11 compatible
- Chip-on-board technology (COB)
- 192 different characters and symbols
- 8 user programmable characters
- Compact and lightweight
- Low power consumption
- Surface mounted components (SMT).
- Powerful instruction set



ATTENTION

OBSERVE PRECAUTIONS FOR HANDLING

ELECTROSTATIC SENSITIVE DEVICES

298-4607

Absolute maximum rating

Item	Symbol	Value	Unit
Power supply voltage	Vdd - Vss	-0.3 ~ + 7.0	
Driver supply voltage	Vlcd	Vdd - 13.5 ~ Vdd +0.3	V
Input voltage	Vin	-0.3 ~ Vdd +0.3	
Operating temperature range	Тор	0 ~ +50	°C
Storage temperature range	Tst	-20 ~ +60	

Description of terminals

Symbol	Input/ Output	External connection	Functio	n					
			Register selecti	on input					
RS	Innut	MPU	High Data register (for read and write)						
CA	Input	IVIFU	Low Instruction registe counter (for read)	r (for write), Busy flag, address					
			R/W signal input is used to select the read/write mode						
R/W	Input	MPU	High	Read mode					
10, 17			Low	Write mode					
E	Input	MPU	Start enable signal to read or write the data						
DB4 DB7	Input/ Output	MPU	Four high order bidirectional data transfer between the MPU used as a busy flag.	three-state data bus lines. Used for J and the LCD module. DB7 can be					
DB0 DB3	Input/ Output	MPU		hree-state data bus lines. Used for U and the LCD module. These four ation.					
Vdd		Power							
Vss		Supply	Vdd: +5V Vss: GND						
Vo		Power	Contrast adjustment voltage						
(Vlcd)		Supply	Vdd - 11~ Vdd + 0.3						

Electrical characteristics

DC characteristics (Vdd = $+5V \pm 10\%$, Vss = OV, Ta = 25°C)

Parameter	Symbol	Condition	Application	Min.	Type	Max.	Unit
			PIN				
H level input voltage (1)	Vih 1	-	DBO ~ DB7	2.2	-	Vdd	V
L level input voltage (1)	Vil l	-	RS, R/W, E	-0.3	-	0.6	V
H level output voltage (1)	Voh 1	Ioh = -0.205 mA	DBO ~ DB7	2.4	-	-	V
L level output voltage (1)	Vol l	Iol = 1.2mA	DBO ~ DB7	-	-	0.4	V
I/o leakage current	Iil	Vin = 0 to Vdd	E	-1	-	1	uA
Pull-UP Mos current	-Ip	Vdd = 5V	RS R/W DB0-DB7	50	125	250	uA
Supply current (Depends on module size)	Iop	RF oscillation, from external clock Vdd = 5v fosc = 270kHz	Vdd	- 1.3	-	0.6 2.5	mA

Internal clock operation (Rf oscillation)

Oscillation frequency	fosc	$Rf = 91k \Omega \pm 2\%$	OSC1 OSC2	190	270	350	kHz
LCD driving voltage	Vlcd	Vdd - V5	V1 ~ V5	3.0	-	11.0	V

LED Backlight Characteristics (Vf = 4.2Vtyp, 4.8Vmax. this figure must not be exceeded)

RS Part Number	Condition	Symbol	Туре	Max.	Unit
214-3480	Ta=25°C	f	70	140	mA
214-3496	Ta=25°C	f	80	160	mA
294-8796	Ta=25°C	f	190	380	mA
214-3519, 214-3525	Ta=25°C	l _f	120	240	mA
294-8774					
294-8803, 214-3531	Ta=25°C	f	360	700	mA
294-8819, 214-3474, 214-3575	Ta=25°C	_f	270	500	mA
214-3553	Ta=25°C	_f	40	80	mA
214-3569	Ta=25°C	_f	150	300	mA
215-3617	Ta=25°C	f	440	800	mA
214-3547, 294-8780	Ta=25°C	f	210	420	mA

AC characteristics (Vdd = $5V \pm 10\%$, Vss = 0V, Ta = 25° C) Read cycle (Figure 6)

Parameter	Symbol	Min.	Type	Max.	Unit	Test PIN
Enable cycle time	tc	500	-	-	ns	Е
Enable "H" level pulse width	tw	220	-	-	ns	E
Enable rise/fall time	tr,tf	-	-	25	ns	Е
RS, R/W setup time	tsu	40	-	-	ns	R/W, RS
RS, R/W address hold time	th	10	-	-	ns	R/W, RS
Read data output delay	td	-	-	120	ns	DB0 ~ DB7
Read data hold time	tdh	20	-	-	ns	DB0 ~ DB7

Write cycle (Figure 5)

Parameter	Symbol	Min.	Type	Max.	Unit	Test PIN
Enable cycle time	tc	500	-	-	ns	Е
Enable H level pulse width	tw	220	-	-	ns	Е
Enable rise/fall time	tr,tf	-	-	25	ns	Е
RS, R/W setup time	tsul	40	-	-	ns	R/W, RS
RS, R/W address hold time	th1	10	-	-	ns	R/W, RS
Date setup time	tsu2	60	-	-	ns	DB0 ~ DB7
Write data hold time	th2	10	-	-	ns	DB0 ~ DB7

298-4607

Optical characteristics

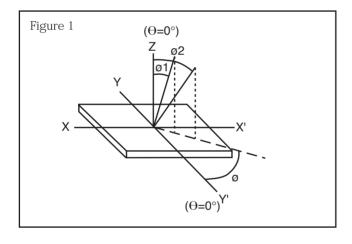
1. STN type

Item	Symbol	Condition	Min.	Typ.	Max.	Unit	Note
Viewing angle	ø2 -ø1	K = 1.4	60	-	-	deg.	*1, *2
Contrast ratio	K	ø = 10°C	5	-	-	-	*3
	11	$\theta = 0^{\circ}C$					
Response time (rise)	tr	ø = 10°C	-	150	250	ms	*4
	LI LI	$\theta = 0^{\circ}C$					
Response time (fall)	tf	ø = 10°C	-	200	300	ms	*4
	u u	$\theta = 0^{\circ}C$					

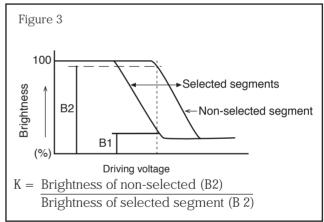
2. TN type

Item	Symbol	Condition	Min.	Typ.	Max.	Unit	Note
Viewing angle	ø2 -ø1	K = 1.4	40	-	-	deg.	*1, *2
Contrast ratio	K	$Ø = 25^{\circ}C$	-	5	-	-	*3
		$\theta = 0^{\circ}C$					
Response time (rise)	tr	ø = 25°C	-	80	120	ms	*4
	Ti Ti	$\theta = 0^{\circ}C$					
Response time (fall)	tf	ø = 25°C	-	60	90	ms	*4
		$\theta = 0^{\circ}C$					

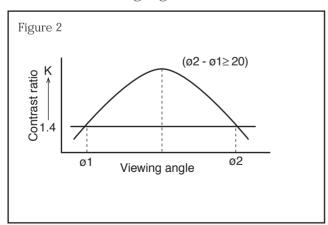
*1. Definition of $\boldsymbol{\Theta}$ and ø



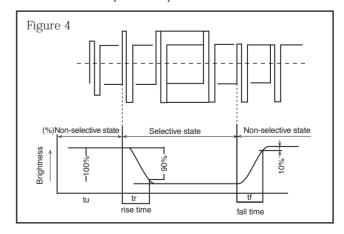
*3. Definition of contrast ratio



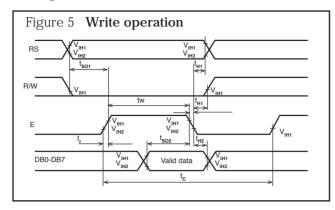
*2. Contrast vs viewing angle

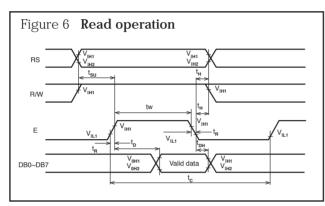


*4 Definition of optical response



Timing characteristics





The modules can be interfaced to 4 bit or 8 bit micro controllers (MPU):

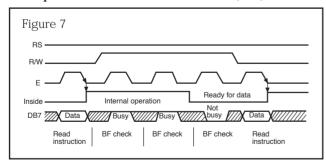
4-bit interface

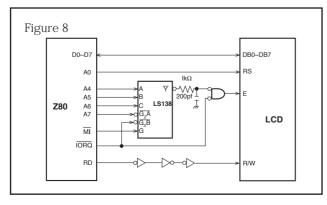
All data/command transfers are made through data bits DB4 to DB7. (Data bits DB0 to DB3 are not used). Each data transfer to the module requires two 4 bit write operations. The 4 high order bits (DB4 to DB7) should be transferred first, while the 4 low order bits (DB0 to DB3) should be transferred last.

8-bit interface

The 8 bit interface uses all 8 line data line (DB0 to DB7).

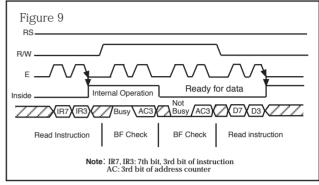
Example of interface with 8-bit MPU (Z80)

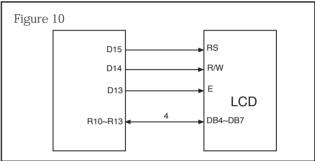




Example of interface with 4-bit MPU

The interface with a 4 bit MPU can be made using through an I/O port. If an 8 bit I/O port is not available a 4 bit I/O port can be used. The module should be initialised to accept 4 bit data and commands. Each command/data instruction must be sent as two 4 bit nibbles, high order nibble first. The busy flag (BF) should be checked every 2 cycles. (Please note that checking the busy flag requires 2 cycles as well).

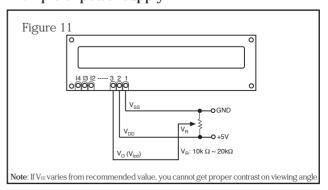




Features

- 1. Interface with 8-bit or 4-bit MPU is available.
- 2. 192 kind of alphabets, numerals, symbols and special characters can be displayed by built-in character generator (ROM).
- 3. Other preferred characters can be displayed by character generator (RAM).
- 4. Various functions of instruction are available by programming.
- Clear display
- Cursor at home
- On/off cursor
- Blink character
- Shift display
- Shift cursor
- Read/write display data etc.
- 5. Compact and light design which can be easily assembled in devices.
- 6. Single power supply +5 drive (at ambient temperature).
- 7. Low power consumption.

Example of power supply



Instructions

Instructions		Code									Description	Executed
	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	•	Time (max.)
Clear display	0	0	0	0	0	0	0	0	0	1	Clears the display and returns the cursor to the home position (Address 0)	1.64mS
Cursor at home	0	0	0	0	0	0	0	0	1	*	Returns the cursor to the home position (address 0). Also returns the display being shifted to the original position. DDRAM contents remain unchanged.	1.64mS
Entry mode set	0	0	0	0	0	0	0	1	I/D	S	Sets the cursor move direction and specifies or not to shift the display. These operations are performed during the data write and read.	40μS
Display On/off control	0	0	0	0	0	0	1	D	С	В	Sets ON/OFF of all display (D) cursor ON/OFF (C), and blink of cursor position character (B).	40μS
Cursor/display shift	0	0	0	0	0	1	S/C	R/L	*	*	Moves the cursor and shifts the display without changing DDRAM contents.	40μS
Function set	0	0	0	0	1	DL	N	F	*	*	Sets interface data length (DL) number of display lines (N) and character font (F).	40μS
CGRAM address set	0	0	0	1				ACC	, ,		Set the CGRAM address. CGRAM data is sent and received after this setting.	40μS
DDRAM address set	0	0	1				ADD)			Sets the DDRAM address. DDRAM data is sent and received after this setting.	40μS
Busy flag/address read	0	1	BF			AC			Reads busy flag (BF) indicating internal operation is being performed and reads address counter contents.	0μS		
CGRAM/DDRAM data write	1	0			W	rite (data				Writes data into DDRAM or CGRAM.	46μS
CGRAM/DDRAM Data read	1	1			Read data					Reads data from DDRAM or CGRAM.	46μS	

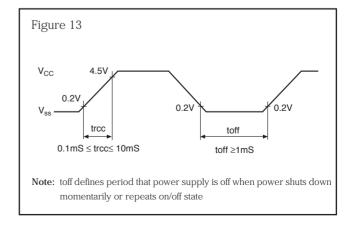
Со	de	Description	Executed time (max.)
I/D=1:Increment I/D=0:Decrement S=1:With display shift S/C=1: Display shift S/C=0: Cursor movement R/L=1: Shift to the right R/L=0: Shift to the left DL=1:8-bit	DL=0:4-bit N=1:2 lines N=0:1 line F=1:5 x 10dots F=0.5 x 7dots BF=1: Internal operation is being performed BF=0: Instruction acceptable	DDRAM:Display data RAM CGRAM:Character generator RAM ACG:CGRAM address ADD:DDRAM address corresponds to cursor address. AC: Address counter, used for both DDRAM and CGRAM *Don't care	fcp or fosc=250kHz However, when frequency changes, execution time also changes Ex If fcp or fosc is 270kHz, $40\mu S \times 250/270 = 37\mu S$

Figure 12 Standard character pattern Higher 4-bit (D4 to D7) of Character Code (Hexadecimal) 0 1 2 3 4 5 6 7 8 9 A B C D E 18924 EI 3 4 Lower 4-bit (D0 to D3) of Character Code (Hexadecimal) 5 6 7 8 SINie 9)수: J|Z|.j|z Α B CG RAN (4) С D Ш

Power supply reset

The internal reset circuit will be operated properly when the following power supply conditions are satisfied. If it is not operated properly, please perform initial setting along with the instruction.

Item	Symbol	Measuring	Stand	dard v	value	Unit
		Condition	min.	typ.	max.	
Power supply	trcc	-	0.1	-	10	mS
rise time						
Power supply	toff	-	1	-	1	mS
OFF time						



Reset function

• Initialisation made by Internal Rest Circuit

KS0066 automatically initialises (resets) when power is supplied (built-in internal reset circuit). The following instructions are executed in initialisation. The busy flag (BF) is kept in a busy state until initialisation ends. (BF=1) The busy state is 10ms after Vdd reach to 4.5V.

- 1. Display clear
- 2. Function set

DL = 1:8bit long interface data

DL = 0.4bit F=0.5 x dot character font

N = 1: 2lines

N = 0: 1line

3. Display ON/OFF control

D=0:display OFF C=0:cursor OFF B=0:blink OFF

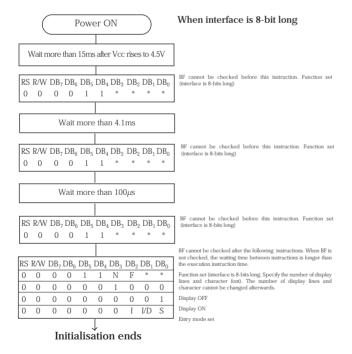
4. Entry mode set

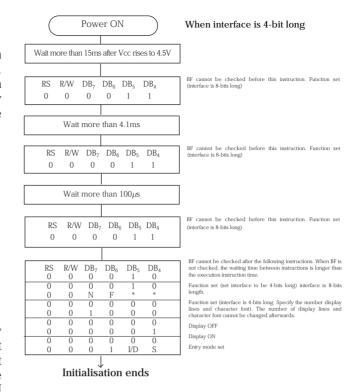
1/D=1: + 1 (increment) S=0:No shift

Note: When conditions stated in Power Supply Conditions Using Internal Reset Circuit are not satisfied, the internal reset circuit will not operate properly and initialisation will not be performed. Please make initialisation using MPU along with instructions.

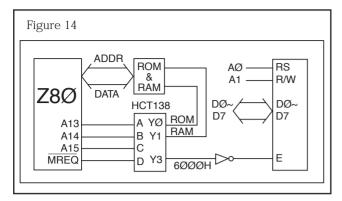
Initialisation along with instructions

If power supply conditions are not satisfied, for proper operation of internal reset circuit, it is required to make initialisation along with instruction. Please make following procedures:-





Application example



All modules except 20 x 4 and 40x4

Example of interfacing to Z8Ø MPU running at 2 Mhz

AØ is connected to RS of module

where $A\emptyset = 1$: Instruction register is selected

where $A\emptyset = \emptyset$: Data register is selected

A1 is connected to R/W of module

where $A1 = \emptyset$: Module in write mode

where A1 = 1: Module in read mode

WRINST EQU 6ØØØH :write instruction

WRDATA EQU 6ØØ1H :write data RDBUSY EQU 6ØØ2H ;read busy

Initialisation

LD	B,Ø	;power up delay	
DJNZ	\$		
LD	SP,27FFH	;stack pointer	
LD	HL, INITBL	;init table pointer	
LD	B,15	;15ms delay	
CALL	INSTR	;o/p instruction to module	
LD	B,5	;5ms delay	
CALL	INSTR	;o/p instruction to module	
LD	B,1	; one ms delay	
CALL	INSTR	;o/p instruction to module	

Function set

function set

	LD	B,4	;four modes
MODSET;	CALL	BUSY	;check for not busy
	INC	HL	;inc table pointer
	LD	A, (HL)	;get data
	LD	(WRINST),A	;and sent to module
	DJNZ	MODSET	:next mode

Write message to module

LD HL, MESSAGE ;get message table turn on display, blinking cursor;

> CALL **BUSY**

A,ØØØØ1111B ;display on, cursor LD

LD (WRINST), A :blink

;set DDRAM address to ØØH

LD A.100000000B :set to 00H CALL **MESG** ;o/p message

:set DDRAM address to 4ØH

LD A.11ØØØØØØØB :set to 4ØH CALL MESG ;o/p message

HALT ;program stop here.....

;subroutine to set DDRAM addr and o/p message

CALL BUSY MESG:

> LD (WRINST),A

;write message to module

LD **B.8** ;no. of byte to be sent

WRITE2: CALL BUSY

LD A.(HL) ;get character LD (WRDATA), A ; write to module INC ;inc pointer HL DJNZ WRITE2 ;next byte

RET

; subroutine : busy check

BUSY: **PUSH**

BUSY1: LD A. (RDBUSY)

BIT 7. A

JR NZ, BUSY1

POP ΑF

RET

;subroutine: o/p instruction to module

INSTR: CALL DELAY ;time delay LD ;get data A,(HL)LD (WRINST), A ;o/p to module

RET

; time delay subroutine

; Total delay time = $B^* 1mS$

; Register destroyed : DE

DELAY: **PUSH** HL LD DE,-1 LOOP1: LD HL. 431/5 HL, DE LOOP2: **ADD** C, LOOP2 JR DJNZ LOOP1

> POP HL

RET

; data table for initialisation routine

INITBL: DEFB ØØ11ØØØØB ;set DL to high

> ØØ111ØØØB ;8-bit, 2 lines, 5X7 DEFB

> > dots

ØØØØ1ØØØB ;display off DEFB

DEFB ØØØØØØØ1B ;clear display, return

cursor

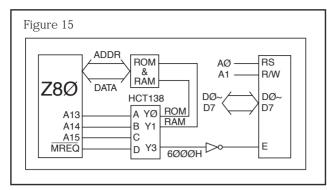
DEFB ØØØØØ11ØB ;set shift mode (entry

mode set)

; message

MESSGE: **DEFB** 'DISPLAY MODULES'

Application example for 20 x 4 and 40 x 4 displays



Example of interfacing to Z8Ø MPU running at 2 Mhz

AØ is connected to RS of module

where $A\emptyset = 1$: Instruction register is selected

where $A\emptyset = \emptyset$: Data register is selected

A1 is connected to R/W of module

where $A1 = \emptyset$: Module in read mode

where $A1 = \emptyset$: Module in read mode

WRINST EQU 6ØØØH :write instruction WRDATA EQU 6ØØ1H :write data

RDBUSY EQU 6ØØ2H read busy

Initialisation

B.Ø LD ;power up delay

DJNZ \$

LD SP.27FFH stack pointer; LD ;init table pointer HL, INITBL LD B.15 ;15ms delay

CALL. **INSTR** ;o/p instruction to module LD B.5 ;5ms delay

CALL INSTR ;o/p instruction to module

Function set

LD B. 1 ; one mS delay

HI.

CALL **INSTR** ;o/p instruction to module

Function set

: function set

LD **B.4** :four modes

MODSET: CALL BUSY ;check for not busy

> :get data LD A,(HL)

(WRINST), A ; and sent to module LD

;inc table pointer

DJNZ **MODSET** :next mode

Write message to module

INC

; turn on display, blinking cursor

BUSY CALL

A.ØØØØ1111B LD ; display on, cursor

LD (WRINST), A ;blink

;send message to display module

HL,MESSGE ;get message table

OUTMSG: LD A,(HL) ;get data from messge

table

CP \$;is end of message?

JR Z,ENDMSG ves, it is

LD no, this is the number B.A

of byte to be sent

INC HLnow, get the DDRAM

addr

LD A,(HL)

CALL BUSY ;check for not busy

SET set bit 7 to 1 7.A LD

(WRINST), A ;o/p to module NXTCHR: INC HLget character;

> LD A,(HL)

> > CALL BUSY check for not busy LD (WRDATA), A ;o/p to module

> > DJNZ NXTCHR ;o/p next character

INC HLinc pointer;

JR **OUTMSG** go and check any

more message

ENDMSG: HALT program stop here.....

subroutine: busy check

BUSY: PUSH AF

BUSY1 LD A, (RDBUSY)

> BIT 7,A

JR NZ.BUSY1

POP ΑF

RET

; SUBROUTINE : o/p instruction to module

INSTR: CALL DELAY ;time delay

LD ;get data A, (HL)

LD (WRINST), A ; o/p to module

RET

; time delay subroutine

; Total delay time = B * 1mS

; Register destroyed : DE

DELAY: PUSH HL

LOOP1:

LD DE, - 1 LD HL.431/5

LOOP2: ADD HL,DE

> JR C,LOOP2

DJNZ LOOP1

POP HL

RET

; data table for initialisation routine

INITBL: DEFB ØØ11ØØØØB ;set DL to high

DEFB ØØ111ØØØB ;8 bit, 2 lines, 5x7 dots

DEFB ØØØØ1ØØØB; display off

DEFB ØØØØØØØ1B; clear display, return

cursor

DEFB ØØØØØ11ØB ;set shift mode

; message

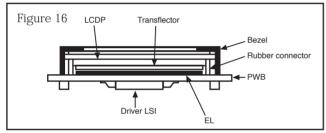
MESSGE: DEFB 18 :no. of character to be sent DEFB ØØH ;ADDR OF DDRAM **DEFB** 'This is first line DEFB 19 ;no. of character to be sent ;addr of DDRAM DEFB 4ØH DEFB 'This is second line ;no. of character to be sent DEFB 18 ;addr of DDRAM DEFB 14H DEFB 'This is third line' DEFB 19 ;no. of character to be sent DEFB 54H :addr of DDRAM DEFB 'This is fourth line' DEFB **'**\$' ;end of message **END**

EL

Flat surface light source offers simple and even illumination over large area. It has an extremely thin structure type of illumination with little heat up.

Features

- Max. 1.3mm thickness (max. 1.5mm for lead portion)
- Wide driving condition of 60- 1,000Hz and 150Vac max., with inverter, step-up voltage from 1.5V battery is available
- Emitted colour is white
- Temperature range: operating $0^{\circ}\text{C} \sim +50^{\circ}\text{C}$ Storage - $20^{\circ}\text{C} \sim +60^{\circ}\text{C}$

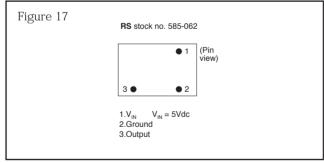


Inverter for EL back light drive

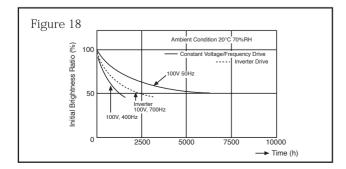
It is necessary to use inverter an when you need to operate EL with battery or a dc power supply.

- Low inverter loss and high light efficiency because it is designed as suitable for EL.
- Less change of power consumption during operation under temperature change or extended hours, which is realised by characteristics of constant supply current, minimises brightness change of EL.

Inverter connections

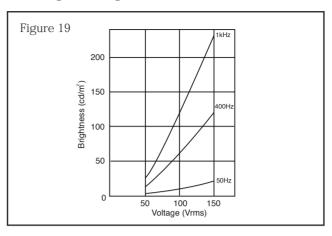


Life characteristics

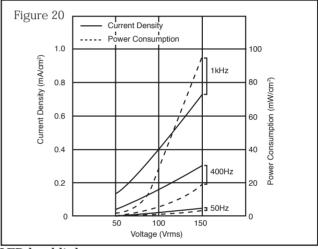


Electrical characteristics (reference data)

Voltage VS. brightness



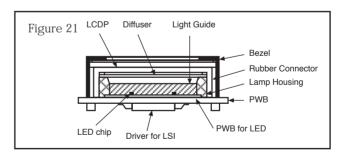
Voltage VS. current density



LED backlight types

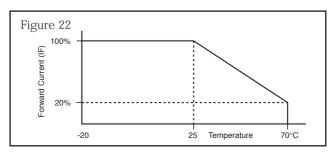
Features

- Low voltage driving (dc) is available without inverter
- Long life time 100,000 hours (average)
- No noise occurrence.



Electrical characteristics (reference data)

• Forward current derating curve



Typical Problems

- Q. Why can only 1 character line be driven on a 2 character line module?
- A. The module has either failed to initialise or has been initialised as a 1 line display
- Q. Why are some rows and/or columns of pixels missing?
- A. The module has been mounted in way which is applying pressure to the bezel supporting the LCD glass.
- Q. Why does the display remain blank after initialisation and ASCII data sent?
- A. V_{lcd} (V0) incorrectly set.

 Timing incorrect. Check that all set up times have been followed. Check that the enable pulse width is 450nS minimum.
- Q. Why can only characters 1 to 8 be addressed on a one line by sixteen character module?
- A. A 1 line by 16 character module must be treated electrically as a 2 line by 8 character display module. After initialisation Line 1 will address characters 1 to 8 (RAM address 00h to 07h) and Line 2 will address characters 9 to 16 (RAM address 40h to 47h)
- Q. Why can only lines 1 and 2 be addressed on a four line by forty character module?
- A. The module contains two independent LCD controllers that must be driven as two separate 2 line by 40 character modules. The module has two enable lines allowing the top or bottom controller to be selected. If a hardware cursor is used it should be carefully controlled when moving between controllers.
- Q. When sequentially written data is sent to a 4 line by 16/20 module, why does the cursor jump from line 1 to line 3 to line 2 to line 4.
- A. The module is electrically similar to a 2 line by forty module which has been folded in the middle such that line 3 follows line 1 and line 4 follows line 2.

Characters 1 to 20 are stored in RAM locations 00h to 13h

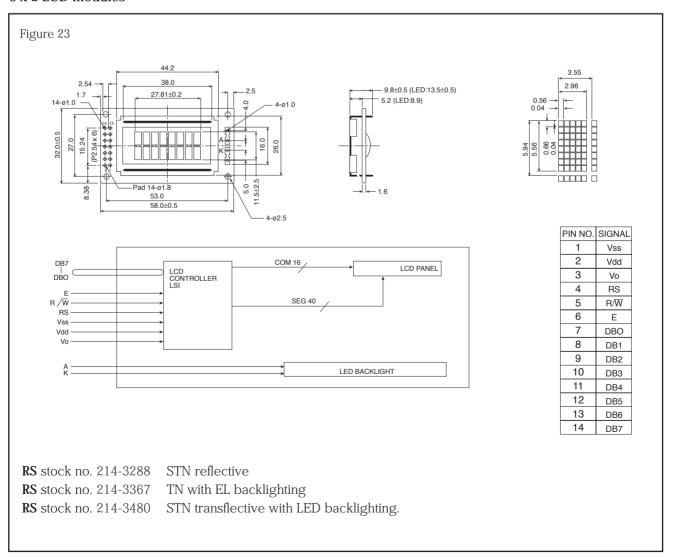
Characters 21 to 40 are stored in RAM locations 40h to 53h

Characters 41 to 60 are stored in RAM locations 14h to 27h

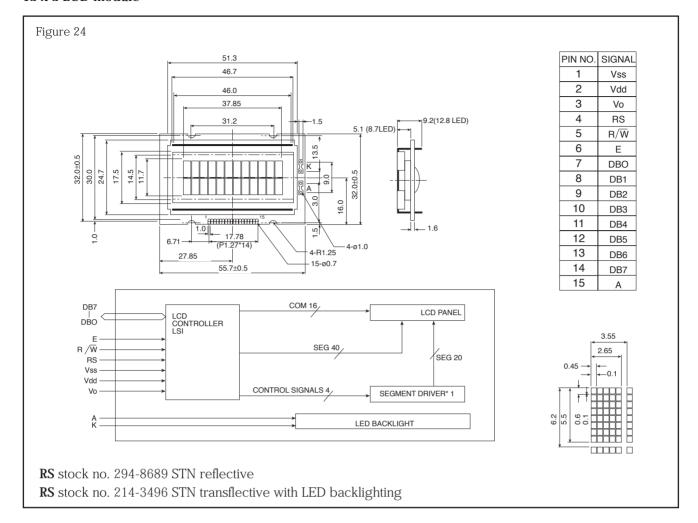
Characters 61 to 80 are stored in RAM locations 54h to 67h

Mechanical dimensions

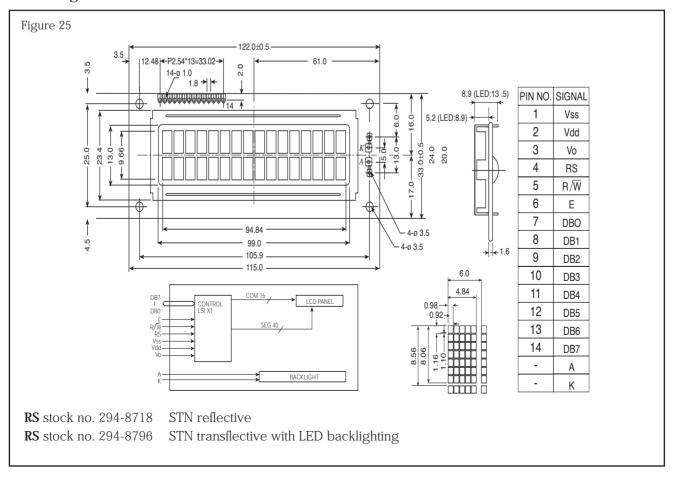
8 x 2 LCD modules



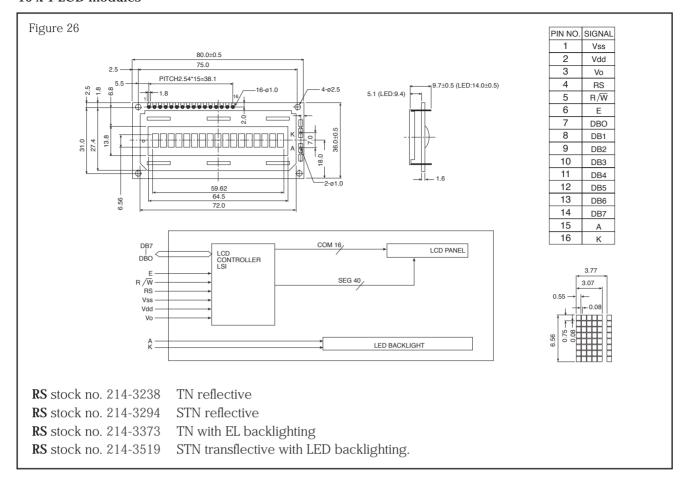
12 x 2 LCD module



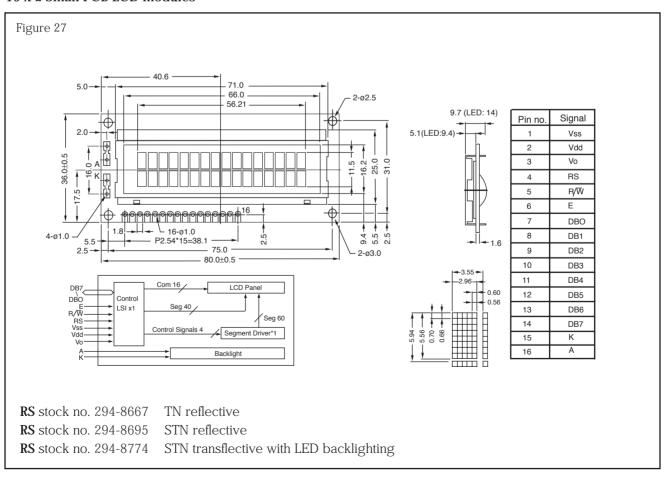
16 x 1 Large Character LCD modules



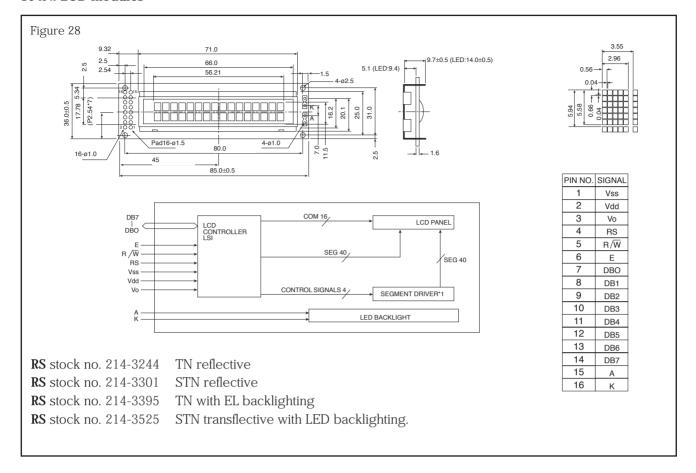
16 x 1 LCD modules



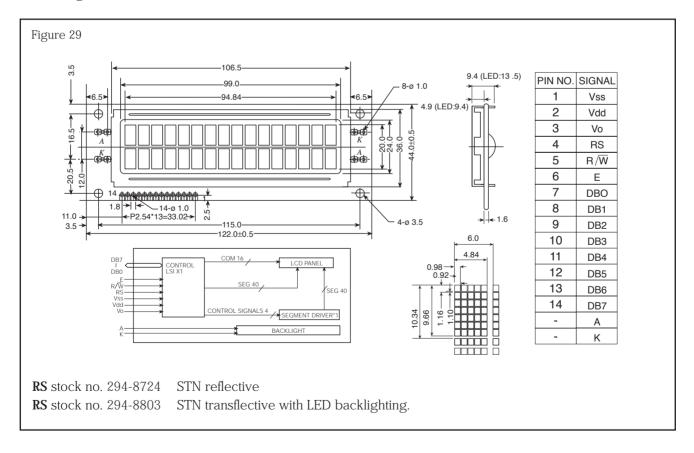
16 x 2 Small PCB LCD modules



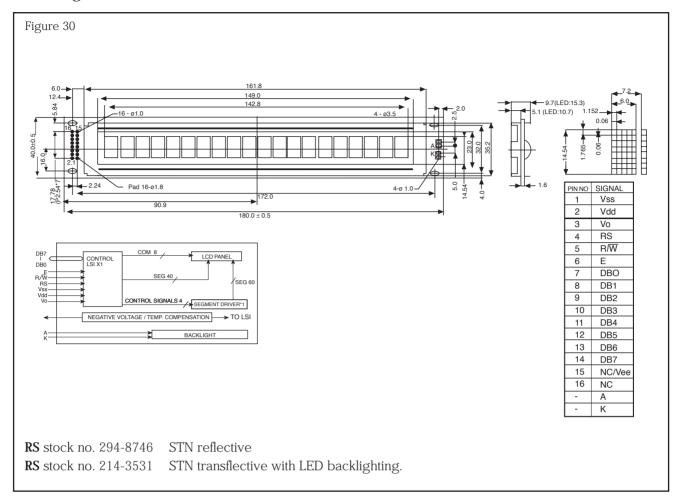
16 x 2 LCD modules



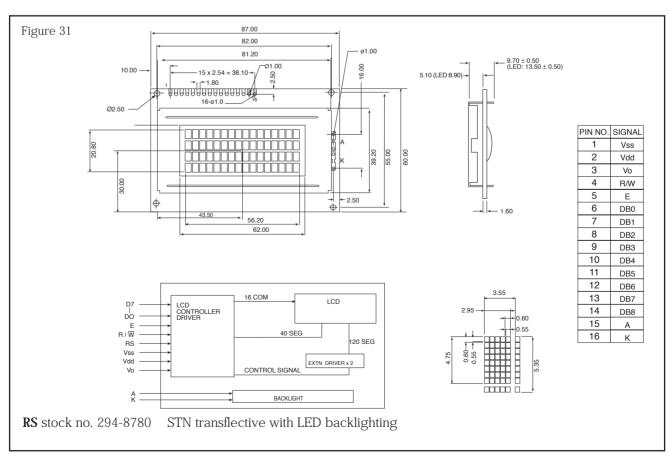
16x 2 Large Character LCD modules



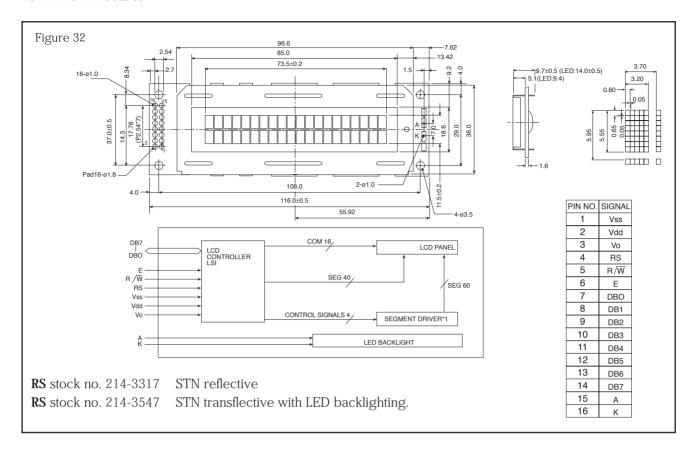
20 x 1 Large Character LCD modules



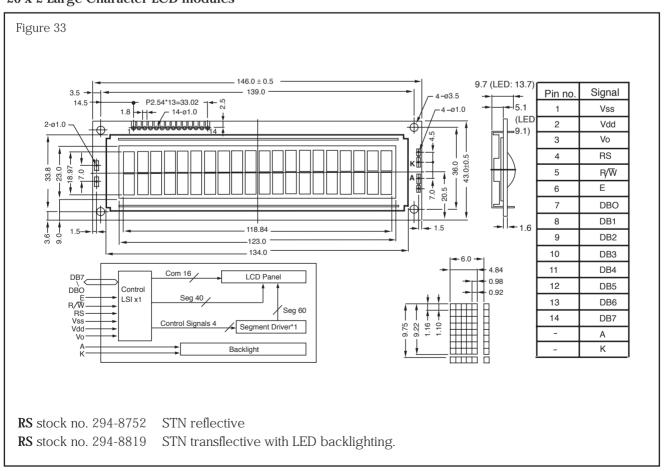
16 x 4 LCD modules



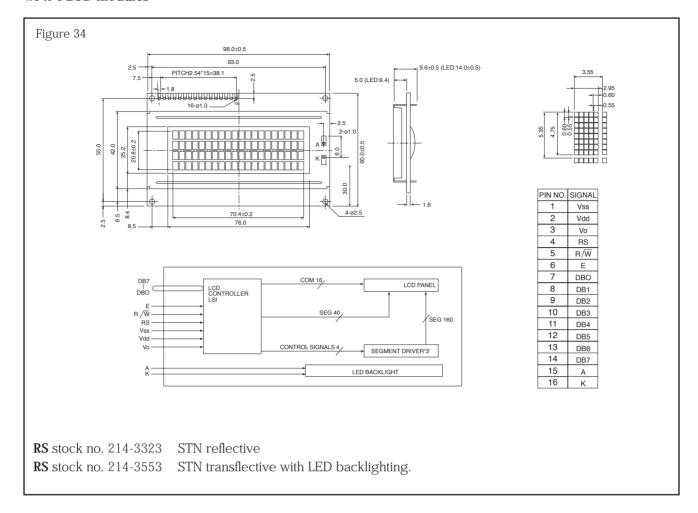
20 x 2 LCD modules



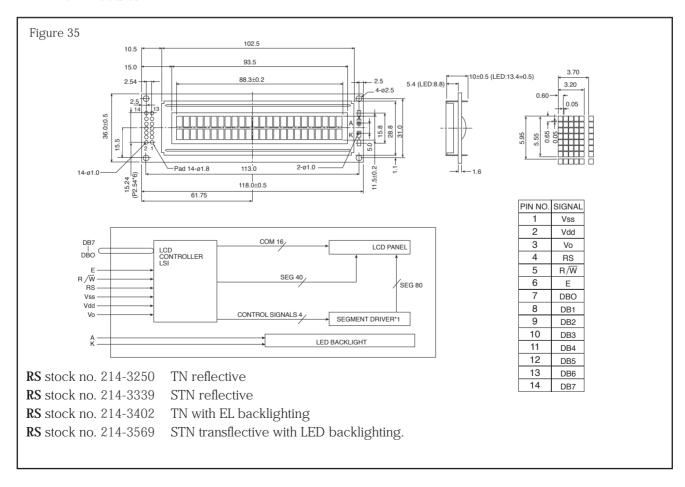
20 x 2 Large Character LCD modules



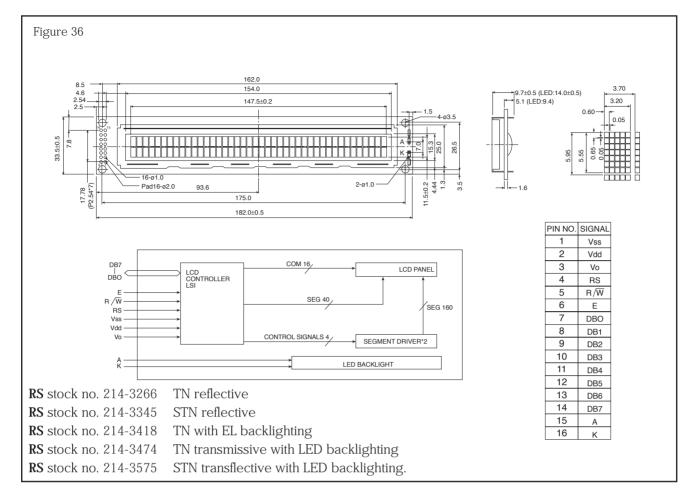
20 x 4 LCD modules



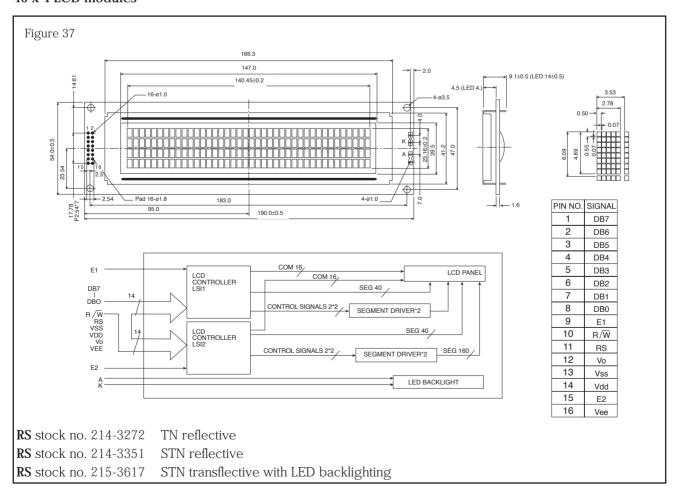
24 x 2 LCD modules



40 x 2 LCD modules



40 x 4 LCD modules



Precaution for using

1. Handling

- a) Do not touch, press or rub the display panel with a hard, stiff tool or object (e.g. tweezers) as the polarises in the panel are easily scratched.
- b) Never use organic solvents to clear the display panel as these solvents may adversely affect the polariser. To clean the display panel and dampen a bit of absorbent cotton with petroleum benzine and gently wipe the panel.
- c) Never touch terminals of electrodes of PCB or LSI leads.
- d) Avoid using or storing the LCM under high temperature and high humidity conditions. When in storage it is recommended that the device is packaged in a conductive polyethylene bag and placed under the condition where the temperature is relatively lower (10 -30°C), and direct sunlight or fluorescent lamp must be cut off.

2. Operation

- a) Never connect or disconnect the LCM from the main system while power is being supplied.
- b) If the operating temperature drops below the temperature limits, the blinking speed of the display will decrease, while if it rises above the prescribed limits, the entire display will turn black. When the temperature returns to within normal limits, the display will operate normally.

3. Workmanship

- a) Never disassemble the module.
- b) Anti static precautions must be taken, as the circuit of the module contains a CMOS LSI.

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