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Math 3316

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## Assignment 4

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1.

a.

Given  $y_n = \int_0^1 \frac{x^n}{x+10} dx$  for  $n = 0, 1, 2, \dots$

$$\Rightarrow y_n * 10y_{n-1} = \int_0^1 \frac{x^n + 10x^{n-1}}{x+10} dx = y_n = \int_0^1 x^{n-1} dx = \frac{1}{n}$$

$$\text{So, } y_n = \frac{1}{n} - 10y_{n-1}$$

Thus, given  $y_n$  and solving for  $y_{n-1}$ ,

$$y_{n-1} = \frac{1}{10n} - \frac{1}{10}y_n$$

b.

...

c.

```
function yn = fixedPointFunc(func, n1, tolerance, maxIterations)
    iterations = 0;
    yn = feval(func, n1)

    while abs(n1-yn)>tolerance && iterations < maxIterations

        iterations = iterations + 1;
        n1 = yn;
        yn=feval(func,n1)
    end
end
```

The  $n_1$  was assigned from the n before 20, so 19.

d.

This approach is stable because as the iterations occur, the return becomes more and more accurate, regardless of initial guess.

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2.

a.

To prevent overflow error, you can scale down the input to prevent it from overflowing. This can be done by dividing the inputted values by  $\max(|x_1|, |x_2|, |x_3|, \dots, |x_n|)$ , then forming the summation and squares.

b.

Code to solve for l2-norm:

```
function [norm] = l2NormFunc(a)
    %||x||_2 = sqrt(sum(x_i^2)from 1->n)

    %scale input
    scalingValue = max(abs(a(:)))
    a(:) = a(:)/scalingValue;

    %length of the vector
    n = length(a)

    %variable to hold the sum
    sum = 0;

    %iterate through the terms, adding their squares to the sum
    for i = 1:n
        aiSquared = (a(i))^2;
        sum = sum + aiSquared;
    end

    %finish the algorithm and solve for norm
    norm = sqrt(sum)
    norm = norm * scalingValue
end
```

Given the vector  $a = [1, 2, 3, 4]$ , this script returned 5.477225575051661, which is  $\sqrt{1^2 + 2^2 + 3^2 + 4^2}$

Given the vector  $a = [10^{12}3, 4 * 10^{12}4, 9^{12}2, 14^{12}6]$ , the script returned 2.583048112093935e+144. The error returned a zero when calculating through

```
error = sqrt(a(1)^2 + a(2)^2 + a(3)^2 + a(4)^2) - norm
```

When running for the array  $a = [10^123, 10^124, 9^122, 10^126, 34^123, 23 * 11^124, 29^132, 14^126]$ , there was an overflow in the “error” calculating line, where the terms were squared and then added without scaling. The algorithm I wrote returned  $norm = 1.087766607871343e + 193$ , though the normal method of calculating the norm (demonstrated in the error function, though without subtracting the norm) overflowed.

3.

a.

A Newton's method-based formula that could approximate  $x = \ln(a)$  would be:

$$a_{n+1} = a_n - a_n * \ln(a_n)$$

b.

A MATLAB script demonstrating the formula from 3.a:

```

% func: function
% dfunc: derivative of function
% guess: the initial guess
% tolerance: the error tolerance
% maxRuns: the maximum number of runs allowed before declaring failure
function [] = newtonsMethod(func, dfunc, guess, tolerance, maxRuns)
    iteration = 0;

    fprintf('iteration\tta_k\ttf(a_k)\t|a_k - a_k-1|\n');

    xk = guess;
    xk1 = guess;
    error = 1;
    while (error > tolerance) && (iteration<maxRuns)
        iteration = iteration+1;

        fprintf('%d\t%d\t%d\t%.1e.\n', iteration, xk, func(xk), error);
        xk = xk1 - func(xk1)/dfunc(xk1);

        error = abs(xk - xk1);

        xk1 = xk;
    end

    xk
end

```

---

4.

This statement is true.

Given that  $A \in R^{n \times n}$  is nonsingular (has an inverse) and  $Ax = \lambda x$ , prove  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ .

$$Ax = \lambda x \Rightarrow A^{-1}Ax = A^{-1}\lambda x \Rightarrow x = A^{-1}\lambda x \Rightarrow \frac{1}{\lambda}x = A^{-1}x$$

So,  $\frac{1}{\lambda}x = A^{-1}x$ , therefore  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$

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5.

a.

Pseudo-code for LU decomposition of an upper Hessenberg matrix:

Flop count:  $n^3$

```
function [] = LU_Solver(A,b)
    %size of A
    n = length(A)

    for i = 2:n
        for j = 1:i-1
            % perform row reduction
            differenceMultiply = (A(i,j)/A(j,j))
            A(i,:) = A(i,:) - differenceMultiply*A(j,:)
        end
    end

    % set L to the edited matrix A, this is not actually necessary
    L(:,:) = A(:,:)

    %get transpose of L to get U
    %U = L'
    for i = 1:n
        for j = 1:n
            U(i,j) = L(j,i);
        end
    end
    U

end
```

b.

To solve a linear system, using an LU decomposition algorithm, it should take  $n * n * ((n + 2) + 2)$  for the gaussian elimination, then  $n^2$  for solving reverse replacement to find x from the triangular matrix.

So, it wold be  $n * n * ((n + 2) + 2) + n^2$

$= n^3 + 5n^2$ , which should be the number of operations performed