

- ①
- Distributed storage is a key abstraction
 - What should be the interface?
 - How should it work?



● Why is it hard?

③

- High performance \Rightarrow sharding
- Many servers \Rightarrow constant faults
- fault tolerance \Rightarrow Replication
- Replication \Rightarrow Potential inconsistencies
- Consistency \Rightarrow network chit chat
 \Rightarrow lower performance

● What do we mean by consistency? ①

- Ideally, same behavior as a single server
- writes one at a time (even if concurrent)
- reads latest write.

Consistency.

②

* Don't want to talk about
internals of storage

* Judge by behavior seen by clients.

Create an illusion of single node
storage.

Example

②

C1: $\text{---} w \times 10 \text{---}$

C2: $\text{---} w \times 20 \text{---}$

C3:

$\text{---} R \times ? \text{---}$

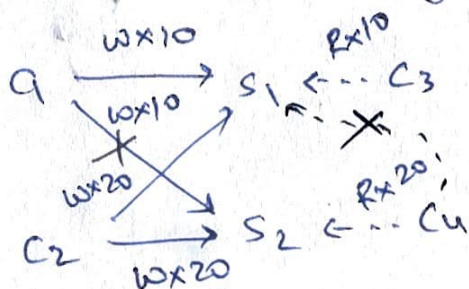
C4:

$\text{---} R \times ? \text{---}$

- Either 10 or 20, but same.
- Single server has poor FT/scalability

Bad replication design

①



- C1 crashes before sending to S2
 - S1 crashes after C3 reads, before C4 reads.
- Suddenly $x = 20$.

Consistency problems

(3)

$C_1 \vdash w_{x10} \vdash$

$C_2 \vdash w_{x20} \vdash$

$\vdash R_{x10} \vdash C_3$

$\vdash R_{x20} \vdash C_4$

$C_1 \rightarrow S_1 \rightarrow C_3$

$C_2 \not\rightarrow S_2 \rightarrow C_4$

CF Goals -

- ~~Automated~~ ^{FT} Key value store
- Data fits in memory / disk
- Many concurrent clients
- Consistent view of storage.

we want that
→ all execution histories
are linearizable.

(3)

- One can find a **total order** of all ops
 - * **matches real-time** for non-overlapping ops
 - * **read sees last write**

(4)

C1: |-----wx1-----|-----wx2-----|

C2: |-----Rx1-----|

C3: |-----Rx2-----|

client
sent
request--- start
timeactual ops happens
anywhere in
between
client recieved
response

⇒ Linearizable

happens before in real time

(4)

C1: |-----wx1-----|-----wx2-----|

C2: |-----Rx2-----| G

C3: |-----Rx1-----|

happens before in
read-write

Cycle ⇒ NOT Linearizable

(4)

|-----wx0-----|-----wx1-----|

|-----wx2-----|

|-----Rx2-----|-----Rx1-----|

⇒ LinearizableIn concurrent writes, write that started
later can be executed first.

Bad things never happen

Linearizability is a safety property

C₁: $\vdash Rx$

C₂: $\vdash Wx$

} Trivially satisfied
by a storage
system that does
nothing!

⇒ We also want liveness (even w/ faults)
↳ Good things eventually happen

Liveness

- Good things eventually happen.

Research. safety-

- * Will not publish incorrect results/
low quality research

Liveness

- * will eventually publish

Safety, liveness in concurrency.

Safety:

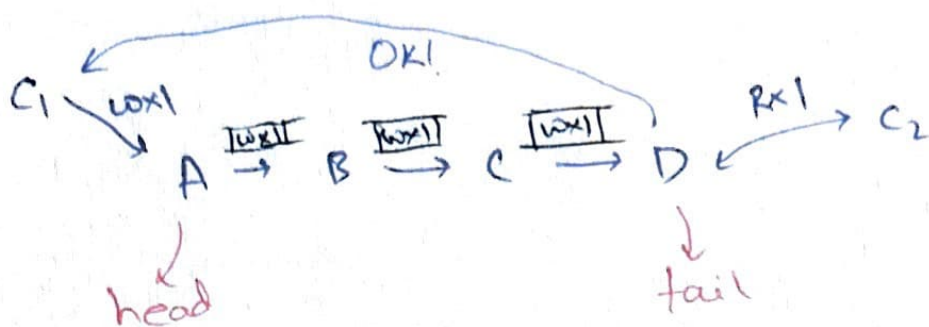
- Mutual exclusion
- No deadlocks

Liveness

- Each process will eventually get the
shared resource (Starvation freedom)

Chain Replication

③



clearly linearizable: in terms of tail server

Why TLAT (Temporal Logic of actions)

- As storage systems grow in complexity, reasoning that they behave like a single system becomes very difficult
- Adding optimizations to existing systems often can break guarantees.

Days of debugging can save hours of writing specifications.

- TLA+ lets us formally prove that one system implements another. Eg. CR implements single machine storage (linearizable)
- Prove safety / liveness

BIG IDEA:

TLA+ helps convert implementation into mathematical implication

$$CR \Rightarrow SS$$

* First 1/2nd of course

- Learn TLA+. Prove that CR implements SS.

- Very beautiful concepts - stuttering, refinement, actions, ...

* Second 1/2

- Discuss distributed storage systems. Groups of 2.