# VIRTUALIZATION: CPU TO MEMORY

Andrea Arpaci-Dusseau CS 537, Fall 2019

### **ADMINISTRIVIA**

- Project I Due Last Night
- Project 2 Available: Due Monday
- Discussion section: xv6 code walk through!
- Homeworks:
  - Process (Due Thursday)
  - Scheduling and MLFQ (Due Tuesday)

### AGENDA / LEARNING OUTCOMES

**CPU** virtualization

**Process Creation** 

MLFQ scheduler

Memory virtualization

Why do we need memory virtualization?

How to virtualize memory? Static, dynamic, base+bounds

# **CPU VIRTUALIZATION**

### **NEW TOPIC: PROCESS CREATION**

### Two ways to create a process

- Option I: Build a new empty process from scratch
- Option 2: Copy an existing process and change it appropriately

### OPTION 1: NEW PROCESS

- Option I: Create new process with specified executable
- Steps
  - Load specified code and data into memory;
     Create empty call stack
  - Create and initialize PCB (make look like context-switch)
  - Put process on ready list
- Advantages: No wasted work
- Disadvantages:
   Difficult to setup process and to express all possible options
  - Process permissions, where to write I/O, environment variables
  - Example: WindowsNT has call with 10 arguments

### **OPTION 2: CLONE AND CHANGE**

#### Option 2: Clone existing process and change as needed

- Example: Unix fork() and exec()
  - Fork(): Clones calling process
  - Exec(char \*file): Overlays file image on calling process
- Fork()
  - Stop current process and save its state
  - Make copy of code, data, stack, and PCB
  - Add new PCB to ready list
  - Any changes needed to child process?
- Exec(char \*file)
  - Replace current data and code segments with those in specified file
- Advantages: Flexible, clean, simple
- Disadvantages:
   Wasteful to perform copy and then overwrite of memory

### UNIX SHELLS

```
while (1) {
 char *cmd = getcmd();
 int retval = fork();
 if (retval == 0) {
   // This is the child process
   // Setup the child's process environment here
   // E.g., where is standard I/O, how to handle signals?
   exec(cmd);
   // exec does not return if it succeeds
   printf("ERROR: Could not execute %s\n", cmd);
   exit(1);
  } else {
   // This is the parent process; Wait for child to finish
   int pid = retval;
   wait(pid);
```

### STDIN AND STDOUT REDIRECTION WITH FILE DESCRIPTORS

# SCHEDULING POLICY: REVIEW

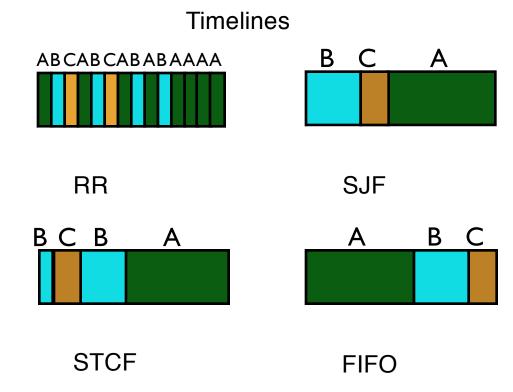
# SCHEDULING POLICY: REVIEW

#### Workload

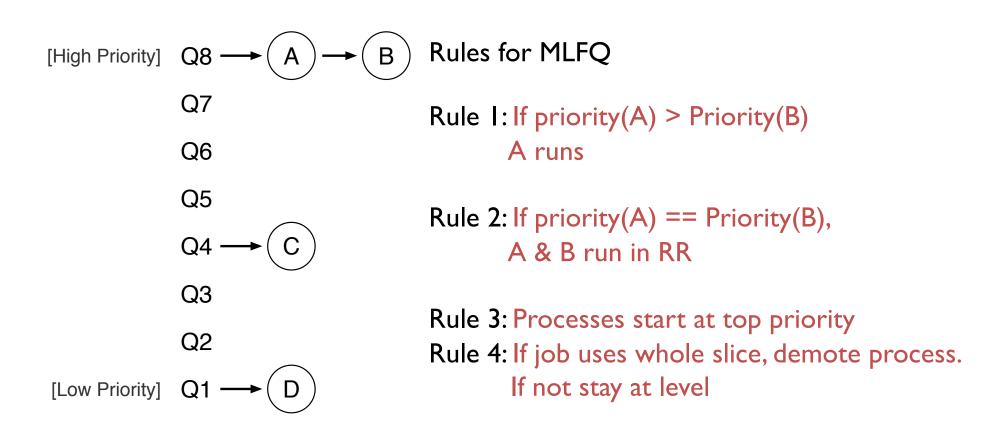
JOB	arrival	run
Α	0	40
В	0	20
С	5	10

### **Schedulers**:

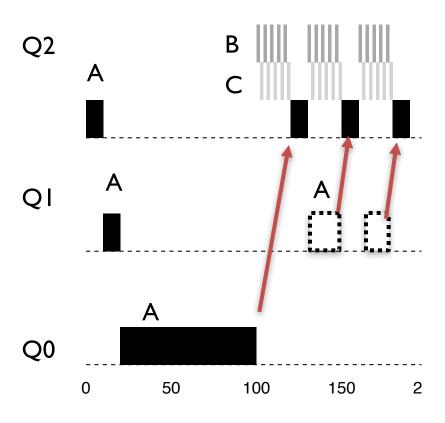
FIFO SJF STCF RR



# MLFQ EXAMPLE



# MLFQ WITH STARVATION MECHANISM



# CANVAS QUIZ: MLFQ

```
This program, mlfq.py, allows you to see how the MLFQ scheduler presented in this chapter behaves. As before, you can use this to generate problems for yourself using random seeds, or use it to construct a carefully-designed experiment to see how MLFQ works under different circumstances. To run the program, type:
```

```
Use the help flag (-h) to see the options:
```

http://pages.cs.wisc.edu/~remzi/OSTEP/Homework/homework.html

# **VIRTUALIZING MEMORY**

### MORE VIRTUALIZATION

Ist part of course: Virtualization

Virtual CPU: illusion of private CPU registers

- 2 lectures (mechanism + policy)

Virtual RAM: illusion of private memory

- 5 lectures

### MOTIVATION FOR VIRTUALIZING MEMORY

Operating System (code, data, etc.)

Current Program (code, data, etc.)

First systems did not virtualize

Uniprogramming: One process runs at a time

Disadvantages?
Only one process ready at a time
Process can destroy OS

max

64KB

## MULTIPROGRAMMING GOALS

#### Transparency:

Process is unaware of sharing Work regardless of number of processes

#### Protection:

Cannot corrupt or read OS or other process memory

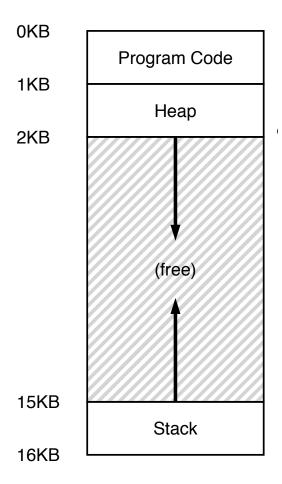
#### Efficiency:

Do not waste memory (no fragmentation) or slow down processes

#### Sharing:

Enable sharing between cooperating processes

## ABSTRACTION: ADDRESS SPACE

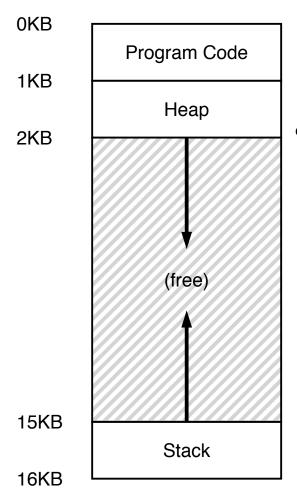


Address space: Each process has own set of addresses

How can OS provide illusion of private address space to each process?

0KB		
64KB	Operating System (code, data, etc.)	
	(free)	
128KB	Process C (code, data, etc.)	
192KB	Process B (code, data, etc.)	
256KB	(free)	
320KB	Process A (code, data, etc.)	
384KB	(free)	
448KB	(free)	
512KB		

### WHAT IS IN ADDRESS SPACE?



the code segment: where instructions live

the heap segment: contains malloc'd data dynamic data structures (it grows downward)

Static: Code and some global variables

Dynamic: Stack and Heap

(it grows upward) the stack segment: contains local variables arguments to routines, return values, etc.

## MOTIVATION FOR DYNAMIC MEMORY

### Why do processes need dynamic allocation of memory?

- Do not know amount of memory needed at compile time
- Must be pessimistic when allocate memory statically
  - Allocate enough for worst possible case; Storage is used inefficiently

### Recursive procedures

Do not know how many times procedure will be nested

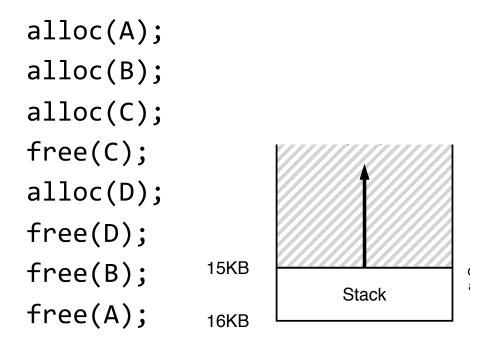
### Complex data structures: lists and trees

- struct my\_t \*p = (struct my\_t \*)malloc(sizeof(struct my\_t));

### Two types of dynamic allocation

- Stack
- Неар

### STACK ORGANIZATION



Memory must be freed in opposite order from allocation

Pointer between allocated and free space Allocate: Increment pointer Free: Decrement pointer

No fragmentation!

# WHAT GOES ON STACK?

```
main () {
    int A = 0;
    foo(A);
    printf("A: %d\n", A);
}
void foo (int Z) {
    int A = 2;
    Z = 5;
    printf("A: %d Z: %d\n", A, Z);
}
```

OS uses stack for procedure call frames (local variables and parameters)

### HEAP ORGANIZATION

Allocate from any random location: malloc(), new() etc.

- Heap memory consists of allocated and free areas (holes)
- Order of allocation and free is unpredictable

#### Advantage 16 bytes Free Works for all data structures. Disadvantages 24 bytes Alloc Allocation can be slow Has small chunks of free space - fragmentation Free 12bytes — Where to allocate 12 bytes? 16 bytes? 24 bytes?? В 16 bytes Alloc What is OS's role in managing heap?

- OS gives big chunk of free memory to process; library manages individual allocations

## ONE-MINUTE NEIGHBOR CHAT

Address	Location		
×			
main			
у			
Z			
* <b>z</b>			

### MEMORY ACCESS

```
#include <stdio.h>
#include <stdlib.h>

int main(int argc, char *argv[]) {
    int x;
    x = x + 3;
}

#include <stdio.h>

0x10:movl 0x8(%rbp), %edi

0x13:addl $0x3, %edi

0x19:movl %edi, 0x8(%rbp)

**The provious of the control of the control
```

%rbp is the base pointer:
points to base of current stack frame

otool -tv demo1.o

### TWO-MINUTE CHAT: MEMORY ACCESS

Initial %rip =  $0 \times 10$ %rbp =  $0 \times 200$ 

-

0x10: movl 0x8(%rbp), %edi

0x13: addl \$0x3, %edi

0x19: movl %edi, 0x8(%rbp)

%**rbp** is the base pointer: points to base of current stack frame

**%rip** is instruction pointer (or program counter)

**Memory Accesses** to what addresses?

How many?

### MEMORY ACCESS

Initial %rip =  $0 \times 10$ %rbp =  $0 \times 200$ 



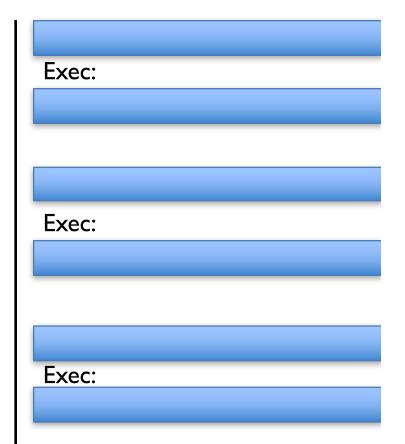
0x10: movl 0x8(%rbp), %edi

0x13: addl \$0x3, %edi

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%**rbp** is the base pointer: points to base of current stack frame

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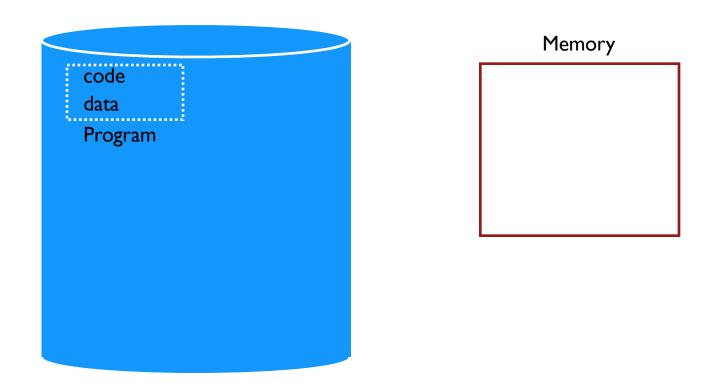


### HOW TO VIRTUALIZE MEMORY

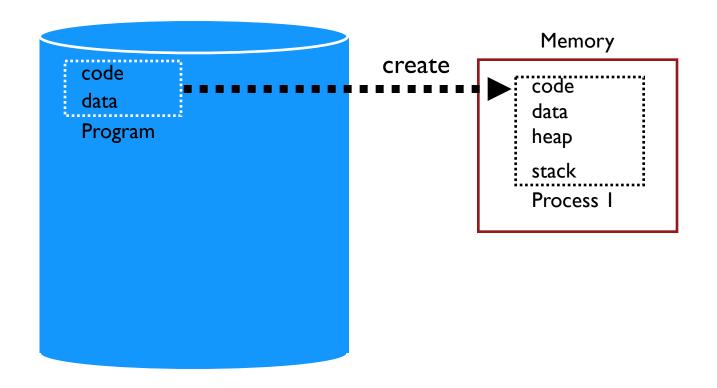
Problem: How to run multiple processes simultaneously? Addresses are "hardcoded" into process binaries How to avoid collisions?

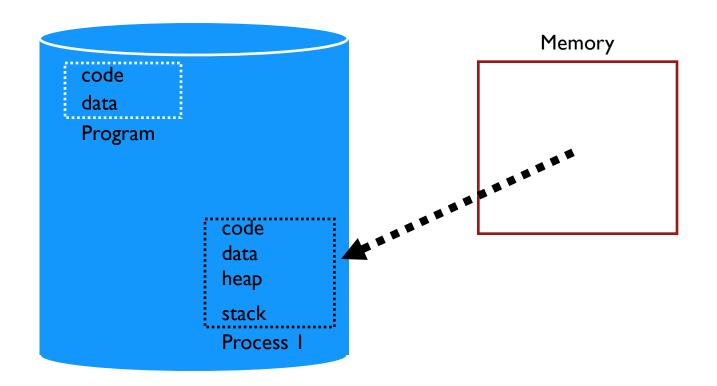
Possible Solutions for Mechanisms (covered today):

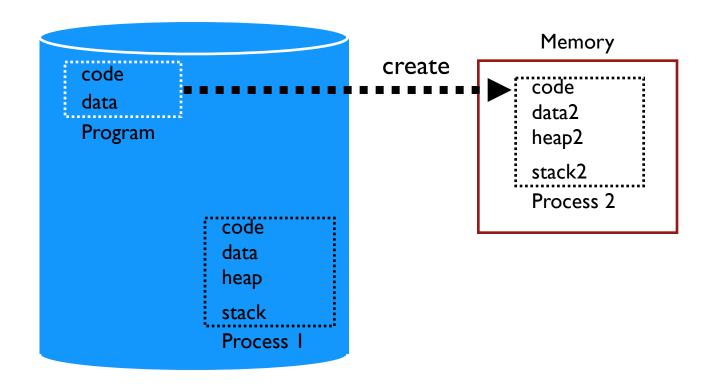
- I. Time Sharing
- 2. Static Relocation
- 3. Base
- 4. Base+Bounds

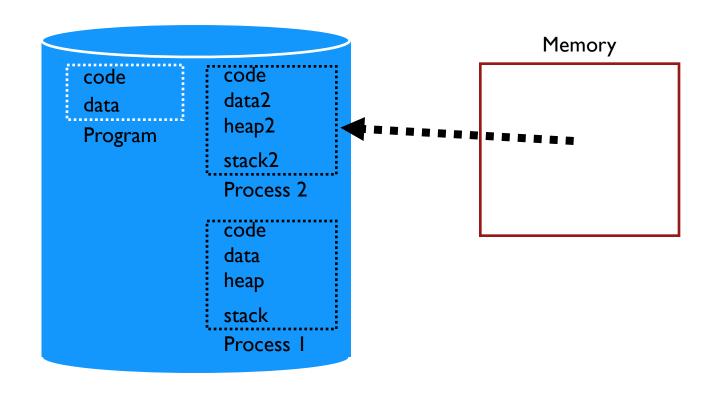


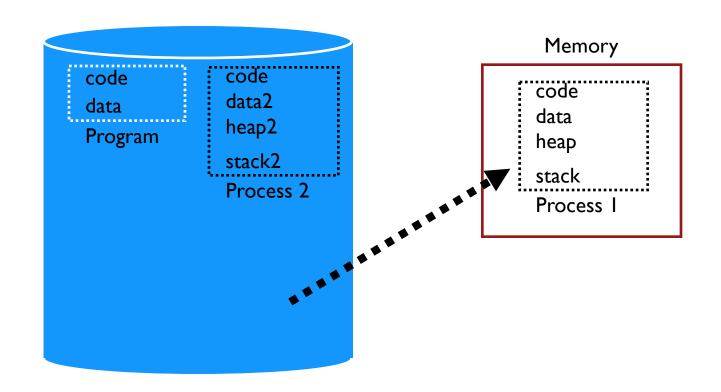
## **TIME SHARE MEMORY: EXAMPLE**











### PROBLEMS WITH TIME SHARING?

Ridiculously poor performance

Better Alternative: space sharing!

At same time, space of memory is divided across processes

Remainder of solutions all use space sharing

## 2) STATIC RELOCATION

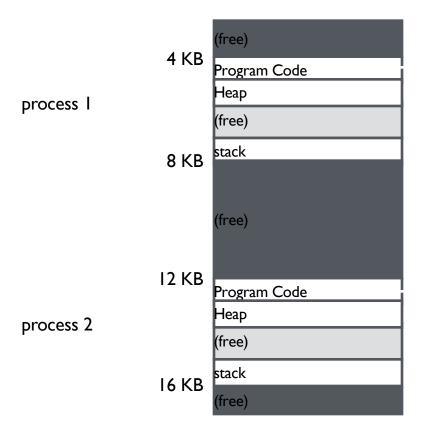
Idea: OS rewrites each program before loading it as a process in memory Each rewrite for different process uses different addresses and pointers Change jumps, loads of static data

```
0x1010: movl  0x8(%rbp), %edi
0x1013: addl  $0x3, %edi
0x1019: movl  %edi, 0x8(%rbp)

• 0x10:movl0x8(%rbp), %edi
• 0x13:addl$0x3, %edi
• 0x19:movl%edi, 0x8(%rbp)

0x3010: movl  0x8(%rbp), %edi
0x3013: addl  $0x3, %edi
0x3019: movl  %edi, 0x8(%rbp)
```

## STATIC: LAYOUT IN MEMORY



0x1010: movl 0x8(%rbp), %edi
0x1013: addl \$0x3, %edi
0x1019: movl %edi, 0x8(%rbp)

0x3010:movl 0x8(%rbp), %edi
0x3013:addl \$0x3, %edi
0x3019:movl %edi, 0x8(%rbp)

why didn't OS rewrite stack addr?

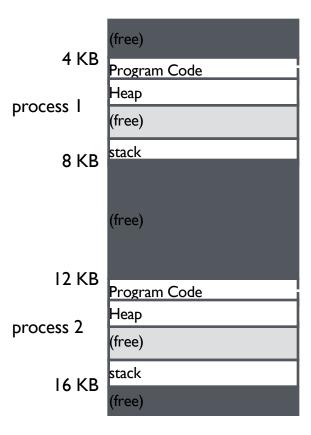
# STATIC RELOCATION: DISADVANTAGES

### No protection

- Process can destroy OS or other processes
- No privacy

Cannot move address space after it has been placed

May not be able to allocate new process



## 3) DYNAMIC RELOCATION

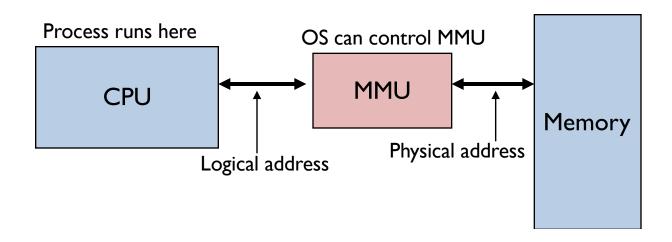
Goal: Protect processes from one another

Requires hardware support

Memory Management Unit (MMU)

MMU dynamically changes process address at every memory reference

- Process generates logical or virtual addresses (in their address space)
- Memory hardware uses physical or real addresses



### HARDWARE SUPPORT FOR DYNAMIC RELOCATION

#### Two operating modes

Privileged (protected, kernel) mode: OS runs

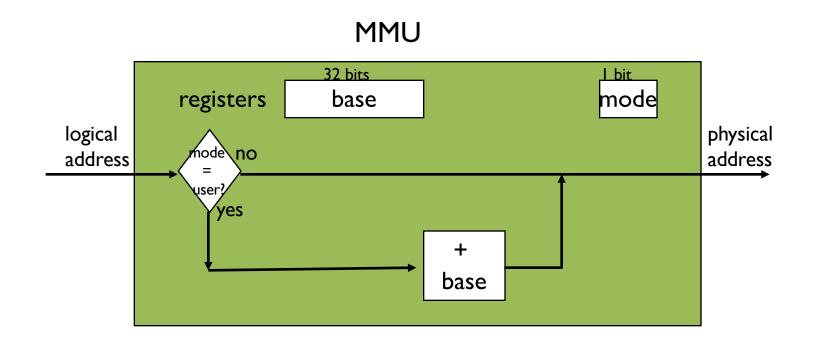
- When enter OS (trap, system calls, interrupts, exceptions)
- Allows privileged instructions to be executed
  - Can manipulate contents of MMU
- Allows OS to access all of physical memory

User mode: User processes run

Perform translation of logical address to physical address

### IMPLEMENTATION OF DYNAMIC RELOCATION: BASE REG

Translation on every memory access of user process MMU adds base register to logical address to form physical address



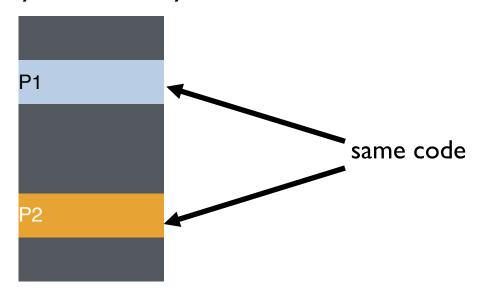
### DYNAMIC RELOCATION WITH BASE REGISTER

Translate virtual addresses to physical by adding a fixed offset each time. Store offset in base register

Each process has different value in base register

Dynamic relocation by changing value of base register!

### Physical memory



Virtual

PI: load 100, RI

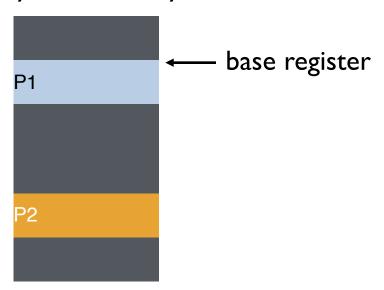
P2: load 100, R1

P2: load 1000, R1

PI:load 100, RI

# VISUAL EXAMPLE OF DYNAMIC RELOCATION: BASE REGISTER

### Physical memory



Virtual

PI: load 100, RI

P2: load 100, R1

P2: load 1000, R1

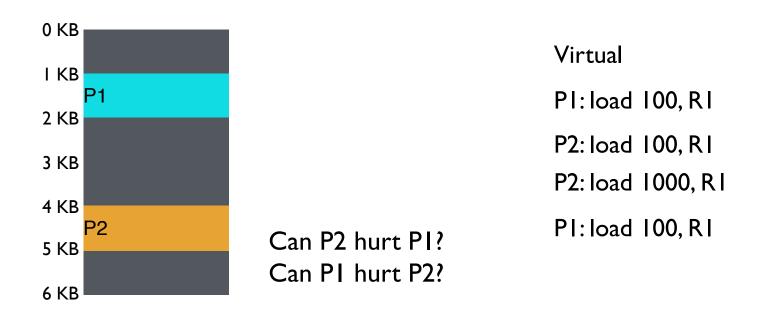
PI: load 100, RI

# VISUAL EXAMPLE OF DYNAMIC RELOCATION: BASE REGISTER

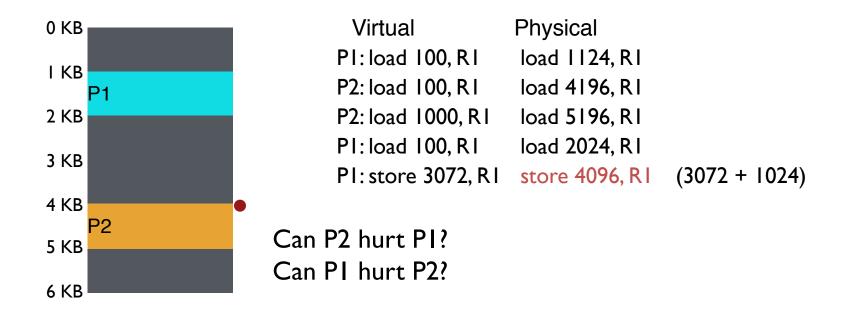
## QUIZ: WHO CONTROLS THE BASE REGISTER?

What entity performs translation of addresses with base register? (1) process, (2) OS, or (3) HW

What entity should determine contents and modify the base register? (1) process, (2) OS, or (3) HW



How well does dynamic relocation do with base register for protection?



How well does dynamic relocation do with base register for protection?

## 4) DYNAMIC WITH BASE+BOUNDS

Idea: limit the address space with a bounds register

Base register: smallest physical addr (or starting location)

Bounds register: size of this process's virtual address space

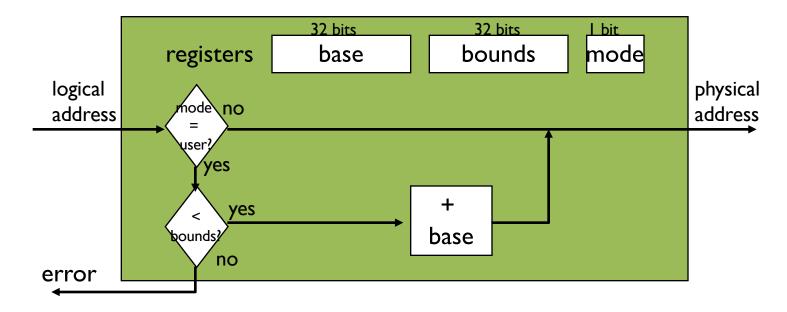
Sometimes defined as largest physical address (base + size)

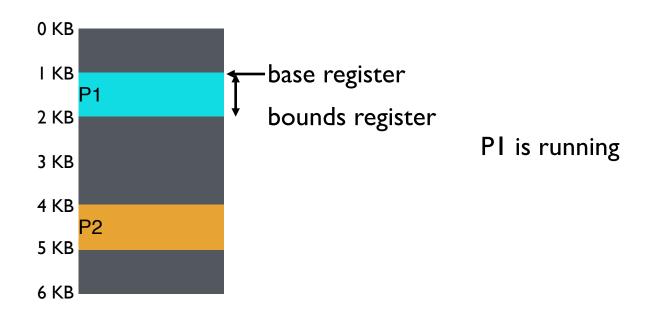
OS kills process if process loads/stores beyond bounds

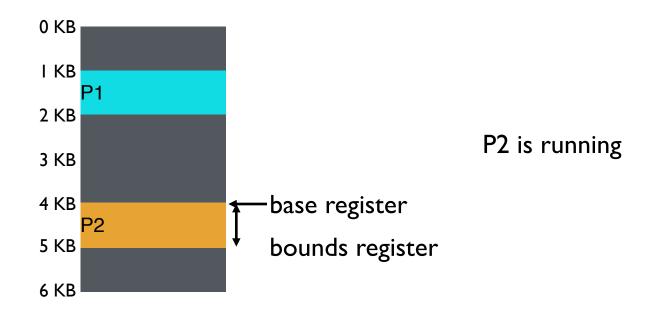
# IMPLEMENTATION OF BASE+BOUNDS

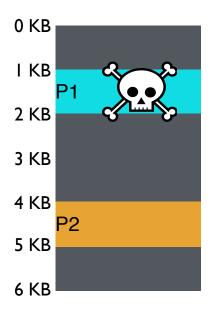
Translation on every memory access of user process

- MMU compares logical address to bounds register if logical address is greater, then generate error
- MMU adds base register to logical address to form physical address









 Virtual
 Physical

 P1: load 100, R1
 load 1124, R1

 P2: load 100, R1
 load 4196, R1

 P2: load 1000, R1
 load 5196, R1

 P1: load 100, R1
 load 2024, R1

 P1: store 3072, R1
 Interrupt OS!

Can PI hurt P2?

## MANAGING PROCESSES WITH BASE AND BOUNDS

Context-switch: Add base and bounds registers to PCB (process-control-block) Steps

- Change to privileged mode
- Save base and bounds registers of old process
- Load base and bounds registers of new process
- Change to user mode and jump to new process

What if don't change base and bounds registers when switch? Threads!

#### Protection requirement

- User process cannot change base and bounds registers
- User process cannot change to privileged mode

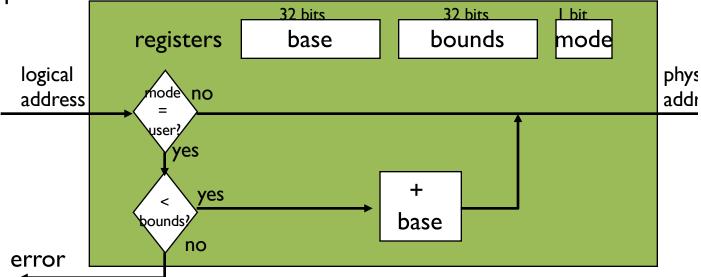
# BASE AND BOUNDS ADVANTAGES

Provides protection (both read and write) across address spaces Supports dynamic relocation

Can place process at different locations initially and also move address spaces

Simple, inexpensive implementation: Few registers, little logic in MMU

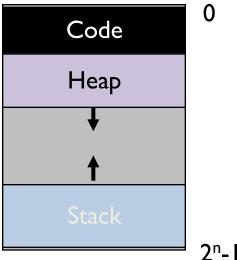
Fast: Add and compare in parallel



# BASE AND BOUNDS DISADVANTAGES

### Disadvantages

- Each process must be allocated contiguously in physical memory
- Must reserve memory that may not be used by process
- No partial sharing between processes: Cannot share limited parts of address space



# **NEXT VM TOPICS**

- Remove those disadvantages, add new ones, fix those...
  - Segmentation
  - Paging
  - Segmentation + Paging
  - Multi-level Page Tables
  - TLBs

## TO DO

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