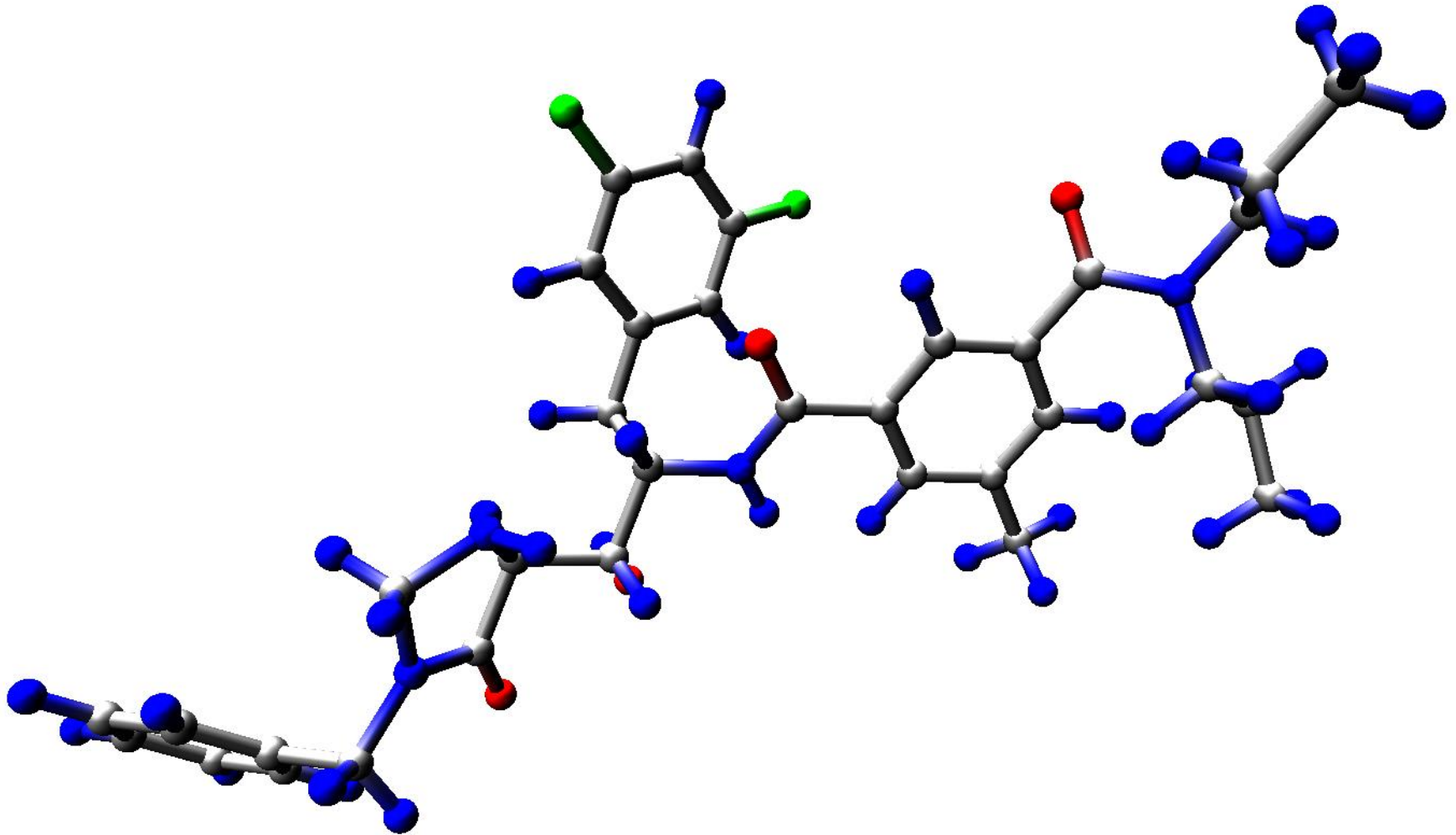


# Exercise 2

## Particle

# Exercise 2 – Particle



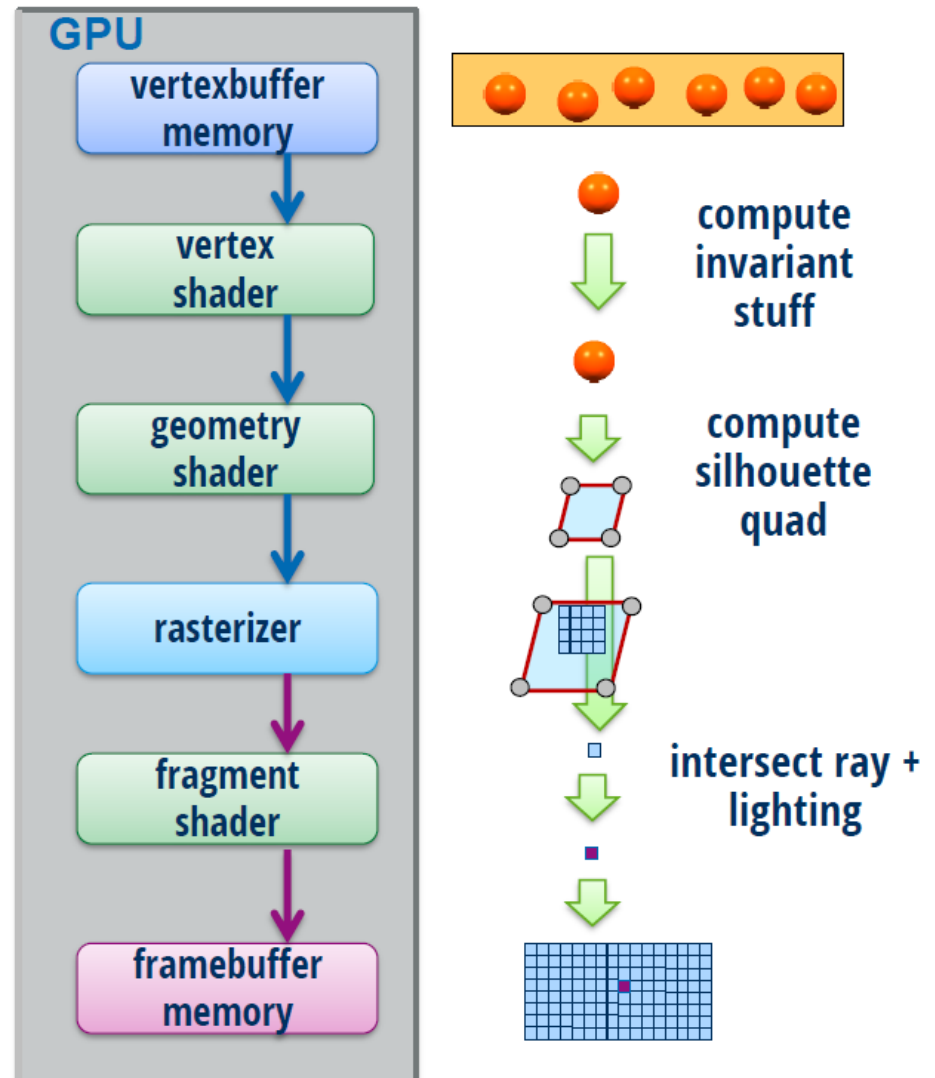


# Exercise 2 – Particle

## 1. Sphere Raycasting

Tasks:

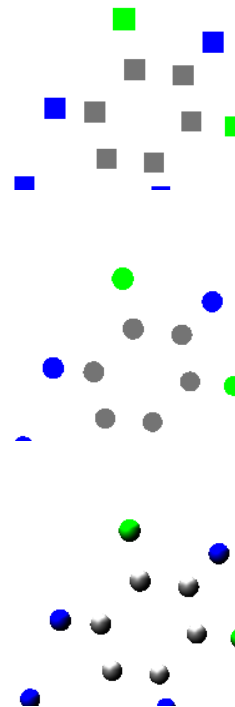
- a) Render silhouette quad
- b) Discard fragment
- c) Ray intersection with sphere
- d) Depth test



# 1. Sphere Raycasting

## Intermediate Results

- a) Render silhouette quad
- b) Discard fragment not on sphere
- c) Ray intersection with sphere
- d) Depth test





# 1. Sphere Raycasting

## a) Vertex Shader *sphere\_raycast.glvs*

### • Compute silhouette parameter *sps* in **parameter space**:

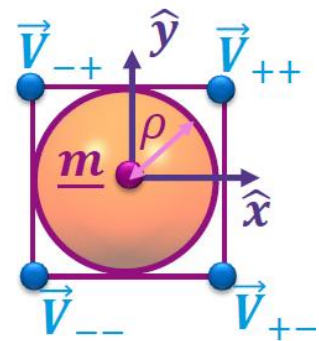
- orthogonal directions of silhouette quad with length  $\rho$ :

- $y\_tilde = \rho \cdot \hat{y}$

- $x\_tilde = \rho \cdot \hat{x}$

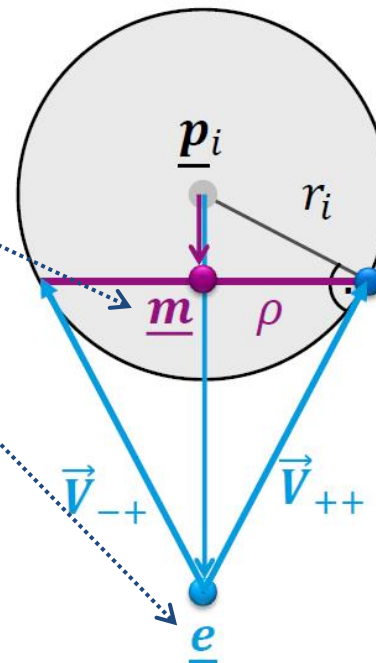
$$\vec{V}_{\pm\pm} = \underline{m} \pm \rho \hat{x} \pm \rho \hat{y}$$

$$\rho^2 = 1 - \frac{r_i^2}{e^2}$$

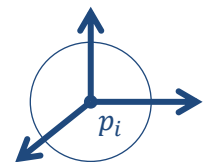


- silhouette center  $m\_tilde$   $\tilde{m} = \frac{r_i^2}{e^2} \tilde{e}$

- eye point  $e\_tilde$   $\tilde{e} = \frac{1}{r_i} (\underline{e} - \underline{p}_i)$



Parameter space:  
Sphere center at origin



$\underline{e}$  ... eye point in world coordinates  
 $\underline{p}_i$  ... sphere center in world coordinates  
 $r_i$  ... sphere radius  
 $e$  ... length of vector  $(\underline{e} - \underline{p}_i)$

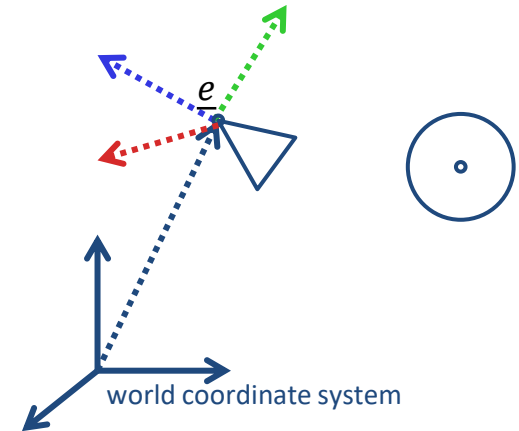
# 1. Sphere Raycasting

## Hints for a)

### ◆ Inverse of the Model View Matrix

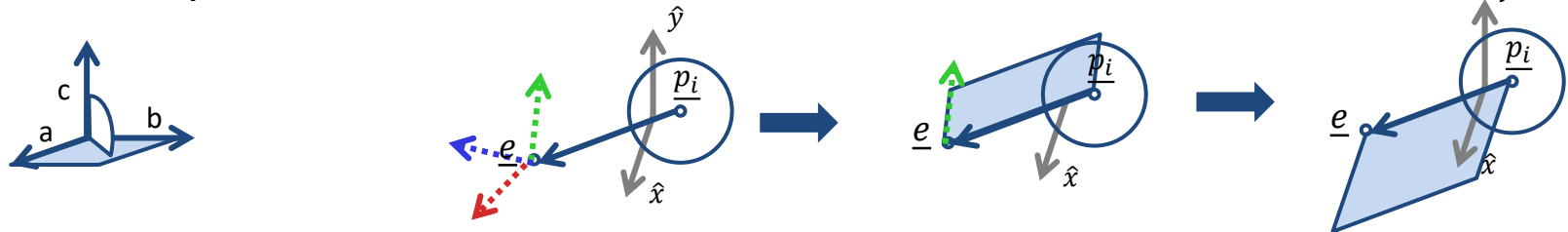
$$iMV = \begin{bmatrix} \text{red} & \text{green} & \text{blue} & \text{white} \end{bmatrix}$$

- ◆ Each column describes a vector in world coordinates



### ◆ Relation to orthogonal directions of the silhouette quad:

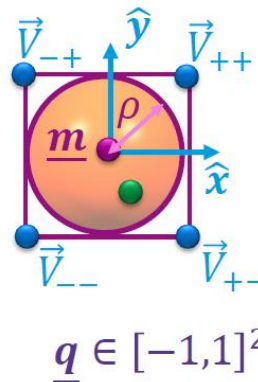
- ◆ Crossproduct:  $c = a \times b$



# 1. Sphere Raycasting

## Hints for b)

- Silhouette Quad – easy sphere intersection check
  - Attach texture coordinates  $\tilde{q} \in [-1,1]^2$  to the quad corners (struct *sphere\_quad\_info* in *sphere\_raycast.glgs*)



- This simplifies the ray intersection to:

$$\|\tilde{q}\| \leq 1$$

# 1. Sphere Raycasting

## c) Rayintersection with Sphere

- special form where  $\lambda_+$  is first intersection along ray:

$$\underline{x}_{\pm} = \underline{e} + \lambda_{\pm} \underline{\vec{V}}, \lambda_{\pm} = \frac{1}{1 \pm \beta}$$

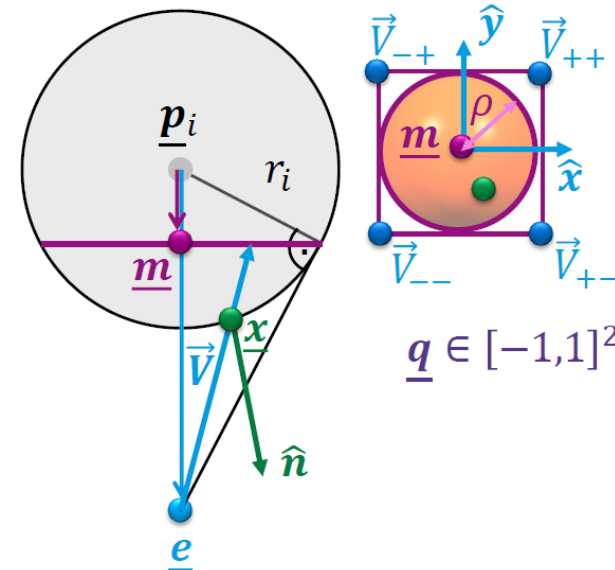
$$\beta = r_i \sqrt{1 - \|\underline{q}\|^2} / \|\underline{e} - \underline{p}_i\|$$

Hint for calculation in eye coordinates:

$\underline{e}$  ... is origin

$\underline{x}$  ... intersection point in eye coordinates

$\underline{\vec{V}}$  ... ray in eye coordinates



Normal:

$$n = \text{normalize}((NM * \tilde{e}) + \lambda * (NM * (\tilde{v} - \tilde{e})))$$

$NM$  ... Normal Matrix

$\tilde{v}$  ... point on silhouette in parameter space

invariant parts:

- could be already computed in the vertex shader
- could be already computed in the geometry shader





# 1. Sphere Raycasting

## Hints for d) Depth Correction

- In order to correct the depth we only need the depth-value (z) and w
- Therefore compute two 2D-vectors containing the z and w component of the clip coordinates of the eye and the current point on the silhouette
- Compute the intersection point with the previous vectors as eye position and for ray calculation:

$$\underline{x}_{\pm} = \underline{e} + \lambda_{\pm} \vec{V},$$

- Perform a w-clip and remapped to range of window coordinates

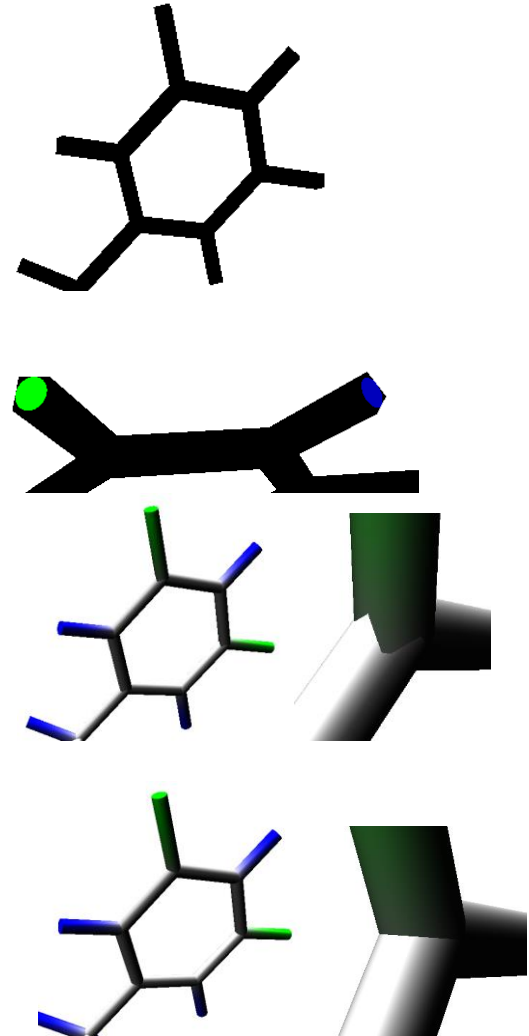


```
// vertex/geometry shader
out vec2 zw_cl;
:
    zw_cl = (MVP*position).zw;
:

// fragment shader
in vec2 zw_clip;
:
    float z_NDC = zw_cl.z/zw_cl.w;
    gl_FragDepth = 0.5*(z_NDC+1.0);
:
```

## 2. Cylinder Raycasting

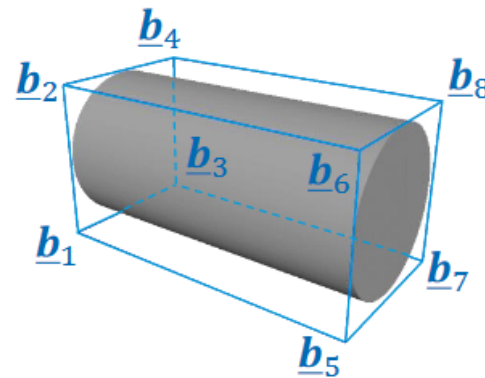
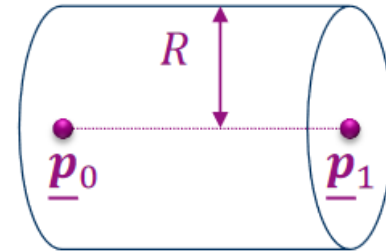
- Render silhouette as bounding box
- Ray intersection with cylinder
  - Test for planar sides of cylinder
  - Intersection with cylinder mantle
- Depth correction



**Definition:** start and end points  $\underline{p}_0$  and  $\underline{p}_1$  plus radius  $R$ .

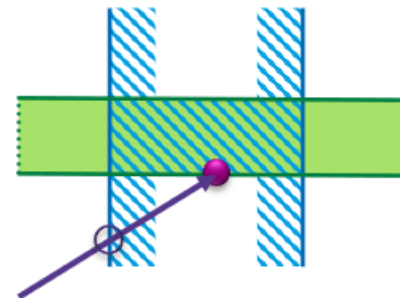
## Silhouette Cover

- ◆ tessellate object oriented bounding box (OOBB)



## Ray Intersection

- ◆ represent cylinder as intersection of two planar half-spaces and cylinder barrel
- ◆ **Intersection** is first ray point that is inside of all three parts



## OOBB Tessellation

- compute tangent vector  $\hat{\mathbf{t}}$  from  $\underline{\mathbf{p}}_{0|1}$

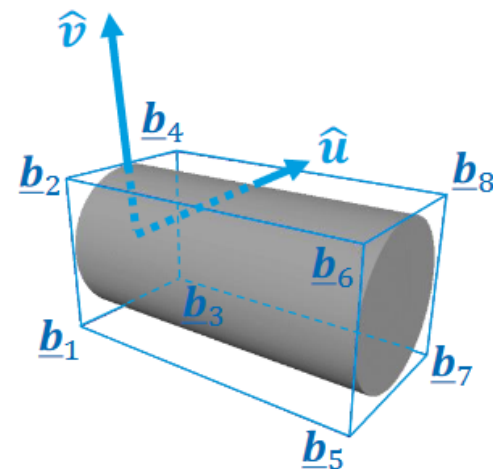
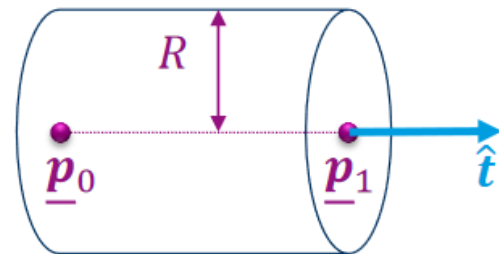
- extent to orthonormal object coordinate system  $\hat{\mathbf{u}}, \hat{\mathbf{v}}$  and  $\hat{\mathbf{t}}$ :

$$\hat{\mathbf{u}} = \text{normalize} \left( \hat{\mathbf{t}} \times \begin{cases} \hat{\mathbf{z}} & t_x^2 + t_y^2 > \epsilon \\ \hat{\mathbf{y}} & \text{sonst} \end{cases} \right)$$

$$\hat{\mathbf{v}} = \hat{\mathbf{t}} \times \hat{\mathbf{u}}$$

- box corners:  $\underline{\mathbf{b}}_{1..8} = \underline{\mathbf{p}}_{0|1} \pm R\hat{\mathbf{u}} \pm R\hat{\mathbf{v}}$
- For more efficient transformation encode information in a single 4x4-matrix:

$$\tilde{\mathbf{B}}^{\text{world}} = \begin{pmatrix} \underline{\mathbf{p}}_0 & \underline{\mathbf{p}}_1 & R\hat{\mathbf{u}} & R\hat{\mathbf{v}} \\ 1 & 1 & 0 & 0 \end{pmatrix}$$



## OOBB Tessellation

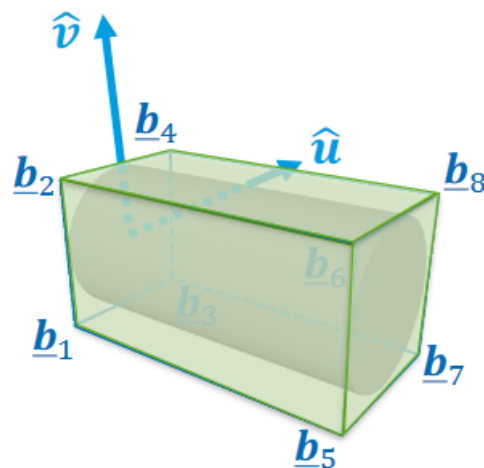
- already in vertex shader transform to clip coordinates

$$\tilde{\mathbf{B}}^{\text{clip}} = \mathbf{MVP} \cdot \tilde{\mathbf{B}}^{\text{world}}$$

- Pass  $\tilde{\mathbf{B}}^{\text{clip}}$  to geometry shader, recover clip space corners and emit length 2 triangle strip per OOBB face

$$\tilde{\mathbf{b}}_{1..8}^{\text{clip}} = \tilde{\mathbf{B}}_{0|1}^{\text{clip}} \pm \tilde{\mathbf{B}}_2^{\text{clip}} \pm \tilde{\mathbf{B}}_3^{\text{clip}}$$

- **Careful:** this pre-transformation only works with points/vectors that have either 1 or 0 in the w-component.
- Optionally perform culling of backfacing facettes





## Hints for b) Ray Intersection

- Check if fragment on planar sides of cylinder:

- $\|pos_{ucyl}.uv\|^2 < 1$  (fragment inside cylinder)
- $pos_{ucyl}.t < \epsilon$  or  $> \epsilon$  (fragment on planar parts)

- Compute ray intersection in unit cylinder coordinates

$$x = e + \lambda v$$

$$r^2 = 1 = x^2 = (e + \lambda v)^2 = e^2 + 2\lambda(e \cdot v) + \lambda^2 v^2$$

$$\Rightarrow 0 = e^2 - 1 + 2(e \cdot v)\lambda + v^2 \lambda^2$$

$$\Rightarrow \lambda_{\pm} = \left( -(e \cdot v) \pm \underbrace{\sqrt{(e \cdot v)^2 - v^2(e^2 - 1)}}_{> 0} \right) / v^2$$

