

DSP and Communications Lab

Real-Time Block Design and Simulation on DSP Board



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Real-Time Block Design

Objectives

Learn how to program real-time DSP blocks in C

Implement/test simple delay block

Implement/test FIR block

Structured DSP Programming in C

One Method

Just think of algorithm as sequential program

Code up the different steps

Problems: Not so structured. Can be confusing.

Easy to make mistakes.

Structured Method

Like what you did in MATLAB blocks in last lab

Simplifies process and keeps it clean

Draw the block diagram

Code/test the individual blocks

Connect the blocks together

Functions of a single DSP Block

`[blockname]_init(params...)`

Initializes the block

Allocates space for any buffers / state variables

Returns a pointer to the initialized state structure

`[blockname](state *, in_buffer, out_buffer)`

Function that processes samples

Takes samples from in_buffer and fills out_buffer

Can also modify state as appropriate

`[blockname]_modify()`

Allows you to change parameters or state during runtime

Example: Delay Block (delay.h header)

delay.h

“Header” file

Declares functions prototypes and constant values

Can be “included” in other files that use those functions and values

Some preliminaries

Comments

```
// This is a comment  
/* This is also  
   a comment! */
```

Including a header only once!

```
#ifndef _delay_h_  
#define _delay_h_  
  
... Header declarations ...  
  
#endif /* _delay_h_ */
```

Example: Delay Block (delay.h)

#define statements

Preprocessor directive

#define *name value*

name get substituted with *value* everywhere in the code at compile time

An efficient way to implement a “constant”

Does not create any additional code

What is the difference of the following 2 statements?

```
#define NAME value
```

```
int NAME = value;
```

Example: Delay Block (delay.h)

#define statements

```
#define NAME value
```

```
/* Size of buffer (samples). Controls maximum delay. */
```

```
#define DELAY_BUFFER_SIZE 16384
```

```
/* Mask. Used to implement circular buffer */
```

```
#define DELAY_BUFFER_CMASK (DELAY_BUFFER_SIZE-1)
```

```
/* Which memory segment the data should get stored in */
```

```
//#define DELAY_SEG_ID 0 /* IDRAM - fastest, but smallest */
```

```
#define DELAY_SEG_ID 1 /* SRAM - a bit slower, but bigger */
```

```
/* Allows alignment of buffer on specified boundary. */
```

```
#define DELAY_BUFFER_ALIGN 128
```

```
/* Samples required for 1MS of Delay */
```

```
#define DSP_SAMPLES_PER_SEC 8000
```

```
#define DELAY_SAMPLES_1MS (DSP_SAMPLES_PER_SEC/1000)
```

Example: Delay Block (delay.h)

State Structure

```
typedef struct
{
    float buffer[DELAY_BUFFER_SIZE];
    unsigned int del;
    unsigned int h, t;
} delay_state_def;
```

Similar to what you did in MATLAB

Buffer of samples

Current delay value

Head/Tail pointers

Example: Delay Block (delay.h)

Function “prototypes”

```
/*-- Function Prototypes -----*/  
  
/* Initializes the delay block */  
delay_state_def *delay_init();  
  
/* Change delay parameters */  
void delay_modify(delay_state_def *s, unsigned int new_delay);  
  
/* Processes a buffer of samples for the delay block */  
void delay(delay_state_def *s, const float x_in[], float y_out[]);
```

Defines the “calling convention” but not the actual functions

Must be “included” in each file that uses the respective functions

Example: Delay Block (delay.c)

Next, look at **delay.c**

```
#include <std.h>
#include <sys.h>
#include <dev.h>
#include <sio.h>
```

Include the named header files

System header files usually denoted with < >

Consult the TI documentation to see which need to be included

```
#include "delay.h"
#include "dsp_ap.h"
```

These are includes for your design

dsp_ap.h from “golden project” (described later)

Example: Delay Block (delay.c)

Init Function (comment block)

```
/*-----  
 * delay_init()  
 *   This function initializes a delay block with a delay of 0.  
 * Inputs:  
 *   None.  
 * Returns:  
 *   0   An error occurred  
 *   other A pointer to a new delay structure  
 *-----*/  
delay_state_def *delay_init()  
{  
    . . .
```

Strongly recommended you do these comment blocks

Show input/output of functions

Help you document what you are doing and maintain structure

Example: Delay Block (delay.c)

Init Function

```
delay_state_def *delay_init()
{
    delay_state_def *s;

    /* Allocate a new delay_state_def structure. Holds state and parameters. */
    if ((s = (delay_state_def *)MEM_calloc(DELAY_SEG_ID, sizeof(delay_state_def),
        DELAY_BUFFER_ALIGN)) == NULL)
    {
        SYS_error("Unable to create an input delay floating-point buffer.", SYS_EUSER, 0);
        return(0);
    }

    /* Set initial delay to 0 */
    s->t = 0;
    s->h = 0;

    /* Success. Return a pointer to the new state structure. */
    return(s);
}
```

Example: Delay Block (delay.c)

Modify Function

```
/*-----  
 * delay_modify()  
 *   Change operating parameters of the delay block.  
 * Inputs:  
 *   s           A pointer to the delay state structure  
 *   new_delay    The new delay value  
 *-----*/  
void delay_modify(delay_state_def *s, unsigned int new_delay)  
{  
    /* Check the requested delay */  
    if (DELAY_BUFFER_SIZE < (new_delay + BUFFER_SAMPLES))  
    {  
        /* Make delay maximum */  
        new_delay = DELAY_BUFFER_SIZE-BUFFER_SAMPLES;  
    }  
  
    /* Change the head of the buffer to obtain the requested delay. Do circular. */  
    s->h = /* REPLACE ME!!! */ ;  
}
```

Example: Delay Block (delay.c)

Processing Function

```
/*-----  
 * delay()  
 *   Process one buffer of samples with the delay block.  
 *-----*/  
void delay(delay_state_def *s, const float x_in[], float y_out[])  
{  
    int i;  
  
    /* Read all input samples into tail of buffer */  
    for (i=0; i<BUFFER_SAMPLES; i++)  
    {  
        s->buffer[s->t] = x_in[i];  
        s->t++; s->t &= DELAY_BUFFER_CMASK;  
    }  
  
    /* Read all output samples from head of buffer */  
    for (i=0; i<BUFFER_SAMPLES; i++)  
    {  
        /* REPLACE ME!!! */  
    }  
}
```

Note: Defined in dsp_ap.h. It is the number of samples that get processed each time delay() is called

Example: Delay Block (delay.c)

Using the delay block

```
/* Define a pointer to a delay state
structure */
delay_state_def *delay1;

.
.
.

/* Somewhere in the initialization code */
delay1 = delay_init();

/* Set the delay */
delay_modify(delay1, 100);

.
.
.

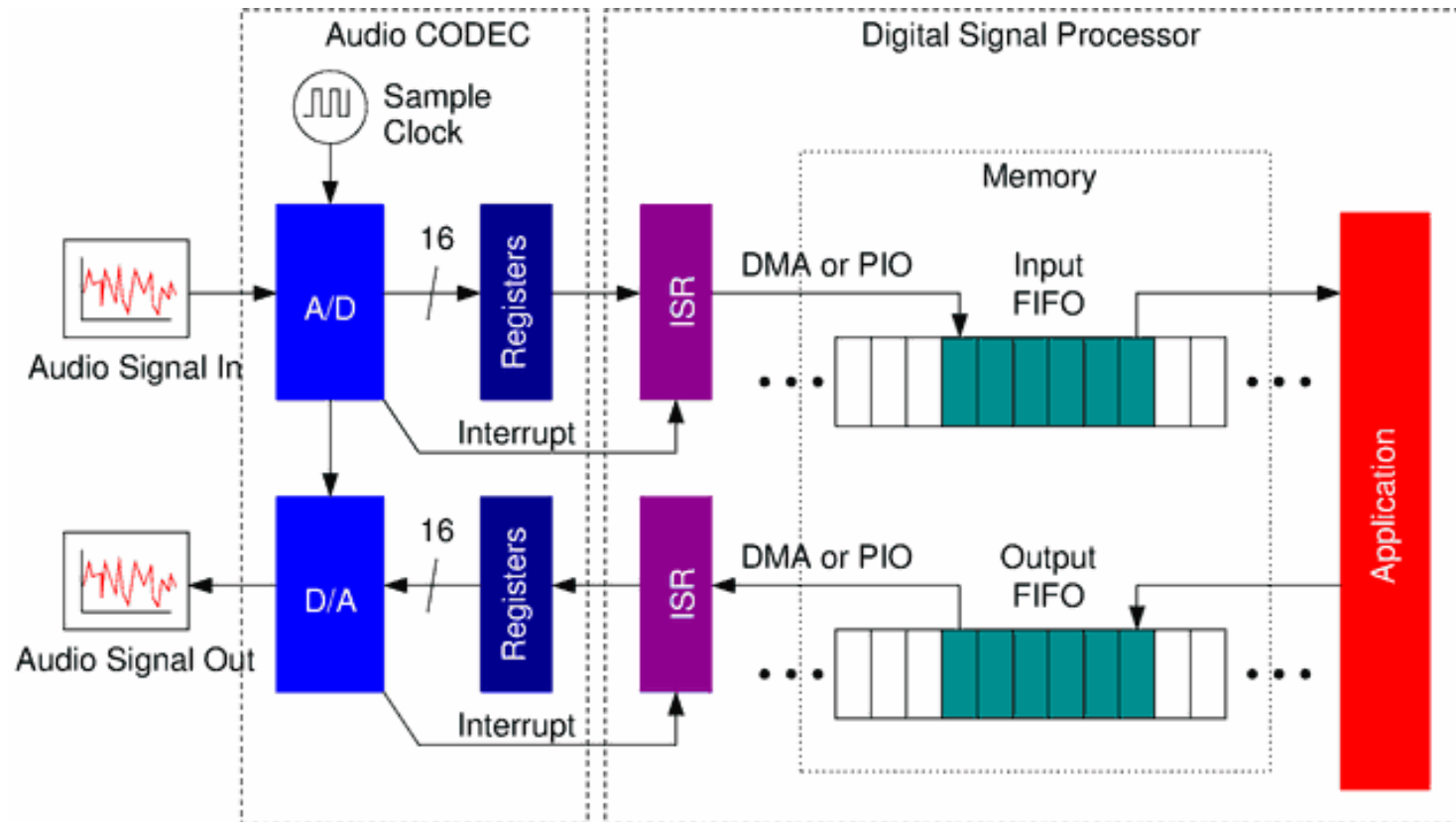
/* Somewhere in the processing code */
delay(delay1, input_samples,
output_samples);
```

Compare to MATLAB code (more elegant)

Cascading blocks simple

```
delay(delay1, input_samples,
temp_samples);
delay(delay2, temp_samples,
output_samples);
```

Audio Processing on DSP Boards



Golden Project

Motivation

Setting up a new project in CCS can be a pain

Many parameters to set, device drivers to specify

Much lab time can be wasted tracking down project-related “bugs”

Golden Project

“Golden” because it should always work

Implements the “surrounding code” needed for audio processing

You can mostly just insert your DSP designs in it

Golden Project

Eliminates the need to do the following tasks

Creating the project

Creating the DSP/BIOS CDB file and setting options

Allocating audio codec buffers

Converting samples to/from floating point

Using the Golden Project

1. Download the right file

golden_prj_c.zip

If you store the project on C:/
like on lab computers

golden_prj_d.zip

If you store it on D:/

2. Unzip it

3. Open dsp_ap.pjt (project file) in CCS

4. Modify files as needed

dsp_ap.h

dsp_ap.c

Note: should leave other files alone (but can create new files!)

Golden Project: dsp_ap.h

Important #defines to consider changing

DSP_SOURCE

sets input samples to come from “line in” (PC) or “mic” (headset)

DSP_SAMPLE_RATE

Sets the sample rate from 8kHz up to 96kHz

Golden Project: dsp_ap.c

Functions you can (should) modify

dsp_init()

Allows you to allocate variables at beginning

Good place to put calls to the blockname_init() functions of all blocks

Return 0 to indicate success, or nonzero to indicate failure

dsp_process()

Called once for each buffer of samples

```
void dsp_process(  
    const float inL[ ],  
    const float inR[ ],  
    float outL[ ],  
    float outR[ ] )  
{
```

Inputs come as floating point: inL, inR
You generate output samples: outL, outR

Golden Project: Debug / Error Indicators

Fatal errors

Rapidly flashing LEDs

Also happens if you return `!= 0` from `dsp_init()`

If this occurs, halt board and check the message log (DSP tools)

LED 3

Flashes slowly on/off for each buffer processed

Shows you that things are at least running (samples streaming)

If this doesn't happen, something got stuck in `dsp_process()`

Pass-through / loopback mode

Turn DIP switch 3 on (= up)

Copies input samples to output samples (should hear yourself talk)

Should always work if `dsp_init()` did not fail (`dsp_top.c` not modified)

Common Pitfalls in DSP Code

Stack usage

Do not declare buffers as local variables!

```
void process()
{
    float my_buffer[16384];
    int i;

    for (i=0; i<16384; i++) { ... }

    ....
}
```

DSP has limited resources

Stack is intended for small temporary variables, not big buffers

Put buffers in state variable (preferred) or as global

Common Pitfalls in DSP Code

Buffer Sizes

Be careful, since there are multiple buffer sizes:

Buffers of input/output samples

Buffer of delayed samples stored in state structure

Buffer of FIR coefficients

Etc.

They can all be different lengths

Critical in **for** loops

Make sure you know what
you are doing!

```
float in_buff[BUFFER_SAMPLES];  
float  
buffer2[DELAY_BUFFER_SAMPLES];  
  
for (i=0; i<DELAY_BUFFER_SAMPLES;  
i++)  
{  
    buffer2[i] = in_buff;  
    ....  
}
```


Common Pitfalls in DSP Code

Pointers / Arrays

- Related to the last point

- Be careful not to write/read past the end of an array

- You will not see an explicit error

- Memory corruption is very difficult to track down

- You will just see strange behavior or things will hang

Common Pitfalls in DSP Code

Allocating memory

- DSP has limited resources

- Have different types of memory (speed/size)

- If you allocate a buffer too big in IDRAM (fastest/smallest)
your program crashes

- If this happens, you should see allocation error in LOG

- Also, you may need to increase size of heap in DSP BIOS Settings
(TA can help you with this)

Common Pitfalls in DSP Code

Nested Loops

```
for (i= ...) { for (j= ...) ... }
```

Make sure you use different variables for inner/outer loops!

This sounds silly, but it happens all the time in student code

Variable types

Use **int** or **unsigned** type for loops and **float** or **double** for samples

Again, sounds silly, but many students are careless with this

Causes weird behavior

Common Pitfalls in DSP Code

Running old code

Make sure you are actually running your latest code on the DSP board!

Always explicitly

save

rebuild

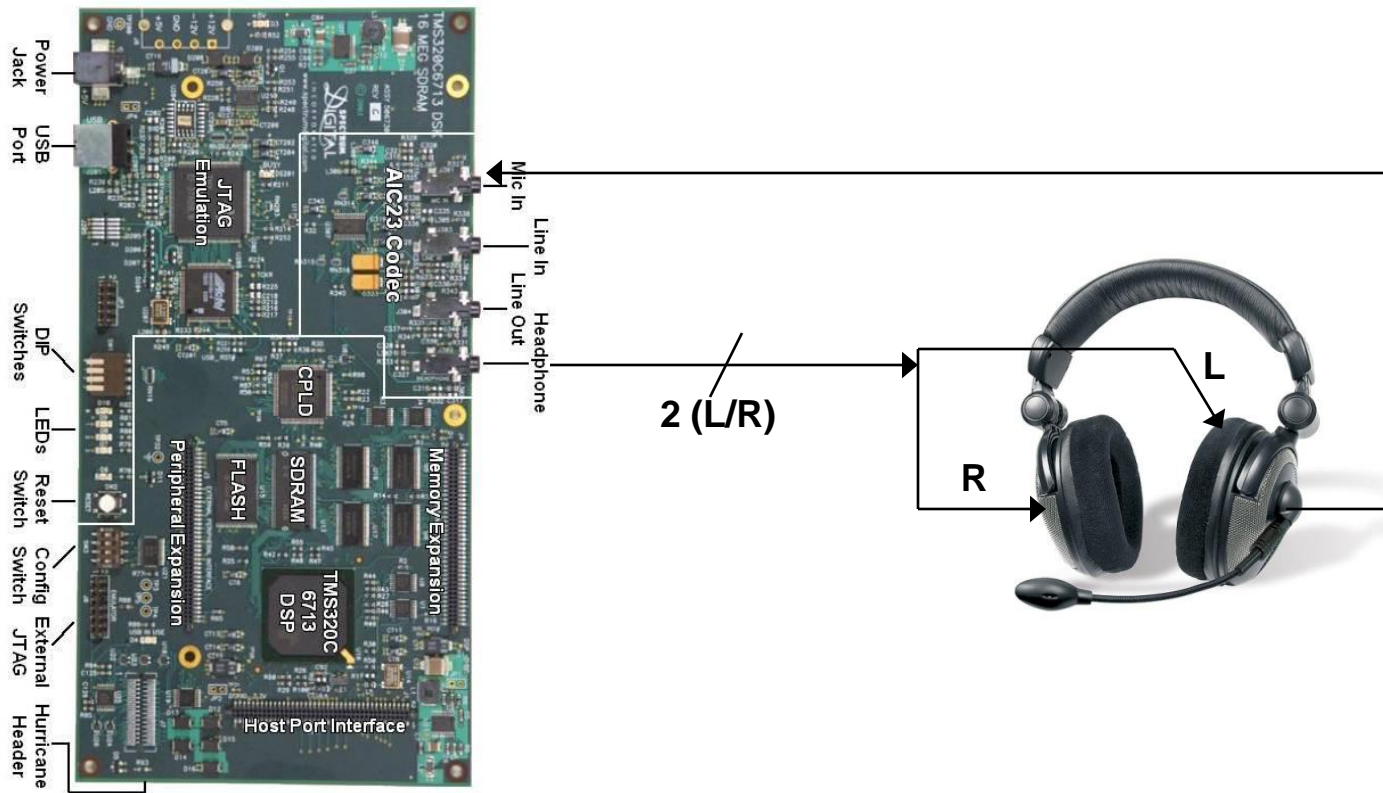
(halt), upload to board

run

If you see strange things happening with breakpoints
(they don't hit, or the code stops on a line with no code)
You are not running the version you see on the screen!

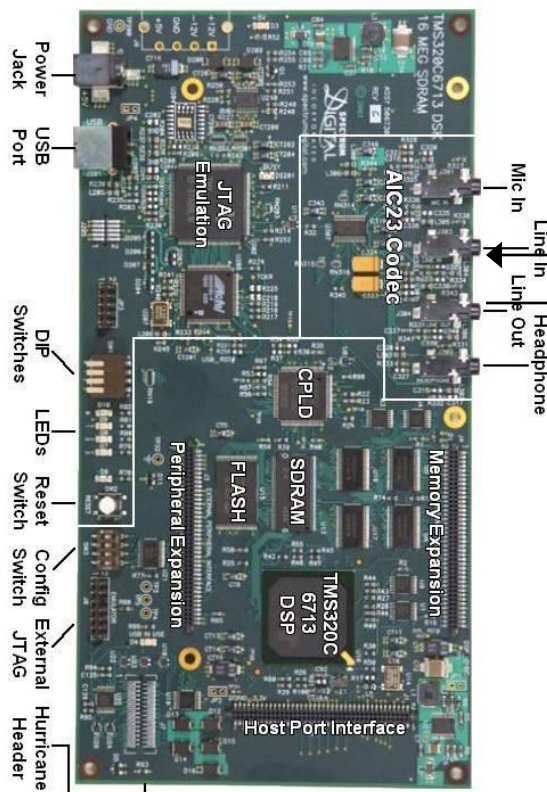
Testing your Design

Using the headset (for delay block)



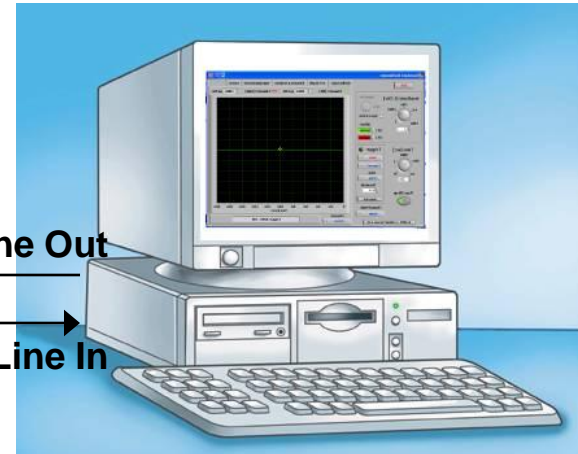
Testing your Design (2)

Using PC and Scope Program or Matlab (FIR filter)



Line Out

Line In



Use "Scope" for quick checking
Use Matlab to measure and plot
exact filter response

Questions?
