

Adithya Mohan

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Education

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| Doctor of Philosophy - PhD, Artificial Intelligence (Dr. rer. nat)
<i>Technische Hochschule Ingolstadt, Germany</i> | <i>Jan 2025 – Current</i> |
| ◦ Dissertation Topic: A Path Towards Robust Embodied AI for Autonomous Systems: Leveraging DRL and Adversarial Defenses | |
| Masters in Mechatronics and Cyber Physical Systems (M.Eng)
<i>Technische Hochschule Deggendorf, Germany</i> | <i>Mar 2019 – Mar 2021</i> |
| ◦ GPA: 1.7 | |
| Bachelors in Mechanical Engineering (B.Eng)
<i>Anna University, India</i> | <i>Sept 2012 – May 2016</i> |
| ◦ GPA: 2.3 | |

Experience

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| AI Researcher - Project Lead
<i>Technische Hochschule Ingolstadt</i> | <i>Ingolstadt, Germany</i>
<i>Mar 2023 – Current</i> |
| ◦ Developed complete autonomous driving stack and sensor hardware box for real-world deployment. | |
| ◦ Implemented control and deep reinforcement learning algorithms for two autonomous cars. | |
| ◦ Integrated ROS/ROS2 as the central robotic framework. | |
| ◦ Managed a team of 3 staff and supervised thesis students. | |
| ◦ Calibrated, time- and spatially-synchronized multi-modal sensors. | |
| ◦ Research robustness in DRL for autonomous driving under adversarial attacks. | |
| ◦ Identify critical states in RL and developed ML toolkits for safe AI. | |
| AI Robotics Engineer
<i>Franka Emika GmbH</i> | <i>Munich, Germany</i>
<i>Aug 2022 – Dec 2022</i> |
| ◦ Developed and implemented a learning engine for Franka robotic arms. | |
| ◦ Designed CMake-based C++ packages with thorough unit/component test coverage. | |
| ◦ Developed ML models and followed SaFe-guided software practices. | |
| Robotics Software Engineer
<i>Quantum Systems GmbH</i> | <i>Munich, Germany</i>
<i>Sep 2021 – Jul 2022</i> |
| ◦ Developed path planning algorithms and GUI using PyQt. | |
| ◦ Built a docking station for autonomous UAV landing using UR10e robots. | |
| ◦ Designed robotics architecture and state machines for task automation. | |
| ◦ Led CI/CD integration and unit test pipelines. | |
| ◦ Trained models to differentiate Quantum Systems drones. | |
| Junior Robotics Engineer
<i>ARE23 GmbH</i> | <i>Munich, Germany</i>
<i>Aug 2020 – Aug 2021</i> |
| ◦ Developed ROS-based navigation and path planning modules. | |
| ◦ Created URDF/xacro simulation models and ML models using OpenCV, Keras, TensorFlow. | |
| ◦ Implemented cloud workflows using AWS Robomaker and Sagemaker. | |
| ◦ Built full-stack applications with React.js frontend and NGINX-based backend. | |
| ◦ Built machine learning solutions with OpenCV, Keras, and TensorFlow. | |
| ◦ Assisted in debugging and testing software systems. | |

Master Thesis Student

Innok Robotics GmbH

Regensburg, Germany

Feb 2020 – Aug 2020

- Developed a continuous monitoring tool for robot diagnostics.
- Created MySQL databases and implemented error identification systems.
- Automated analysis pipelines and visualizations in Python.

Senior Analyst - Material Planner

Flex India Pvt Ltd

Chennai, India

Jul 2016 – Aug 2018

- Led process automation initiatives and lean (Kaizen) improvements.
- Managed team operations to minimize non-value-added tasks.
- Applied supply chain analytics using R, Python, SQL, Tableau, and VBA.

Publications

The Evolution of Criticality in Deep Reinforcement Learning (ICAART'25)

Feb 2025

Chidvilas Karpenahalli Ramakrishna, **Adithya Mohan**, Zahra Zeinaly, Lenz Belzner

[The Evolution of Criticality in Deep Reinforcement Learning](#) 

Technologies

Languages: C++, C, Python, Matlab, Simulink

Technologies: ROS/ROS2, AWS, Azure