

Image Noise Reduction

Concepts



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 - ▶ Imaging sensors can be affected by ambient conditions
 - ▶ Interference can be added to an image during transmission



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 - ▶ Imaging sensors can be affected by ambient conditions
 - ▶ Interference can be added to an image during transmission
- ▶ Common types of image noise include:
 - ▶ **Salt and pepper noise:** contains random occurrences of black & white pixels
 - ▶ **Impulse noise:** contains random occurrences of white pixels
 - ▶ **Gaussian noise:** variations in intensity drawn from a Gaussian normal distribution

Noise Model

- We can consider a noisy image to be modelled as follows:

$$g(x, y) = f(x, y) + \eta(x, y)$$

where $f(x, y)$ is the original image pixel, $\eta(x, y)$ is the noise term and $g(x, y)$ is the resulting noisy pixel



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- If we can estimate the noise model we can figure out how to restore the image

Filtering to Remove Noise

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This is implemented as the simple smoothing filter

It blurs the image.

Median Filter

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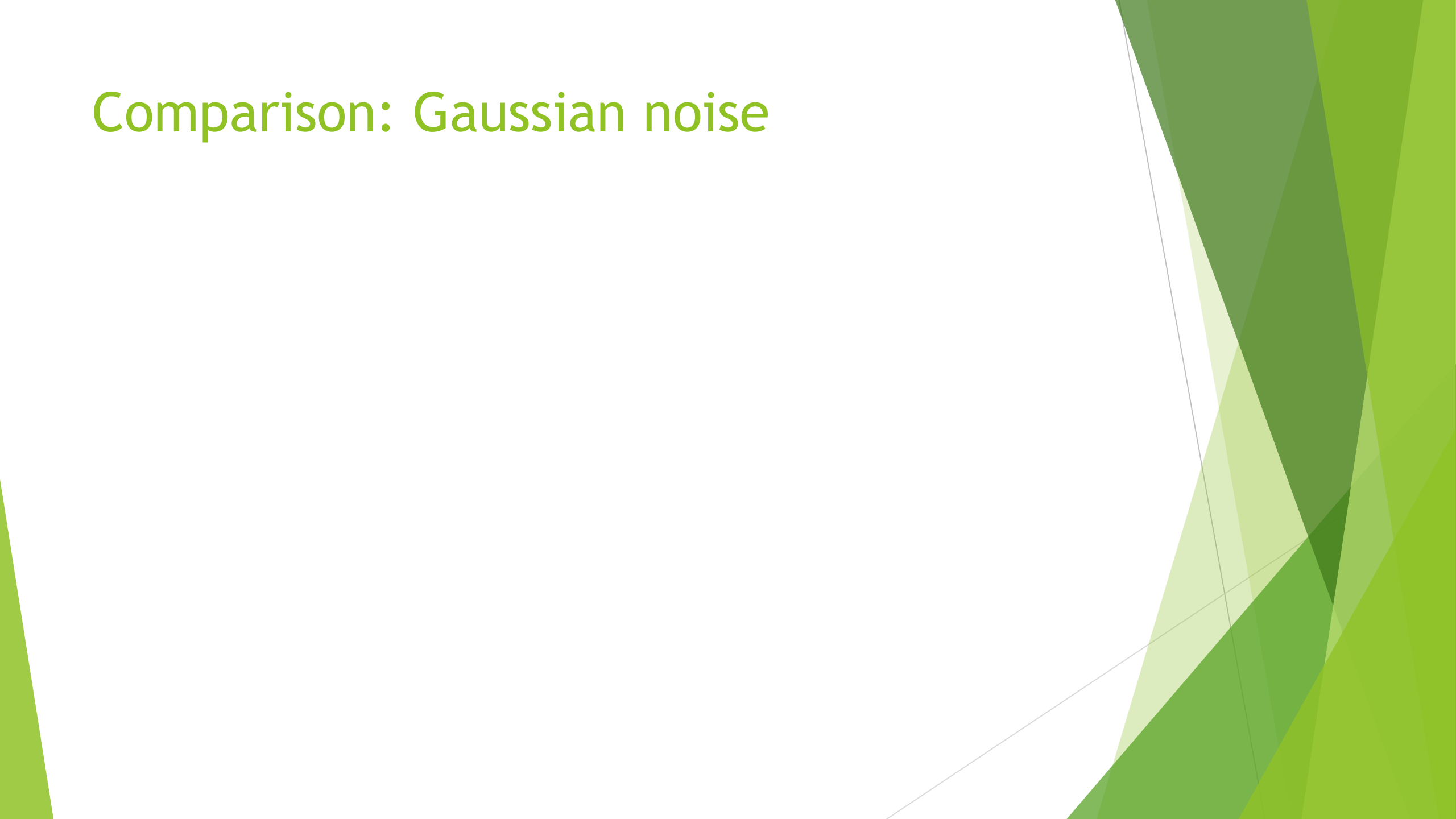
$$\hat{f}(x, y) = \underset{(s,t) \in S_{xy}}{\text{median}}\{g(s, t)\}$$



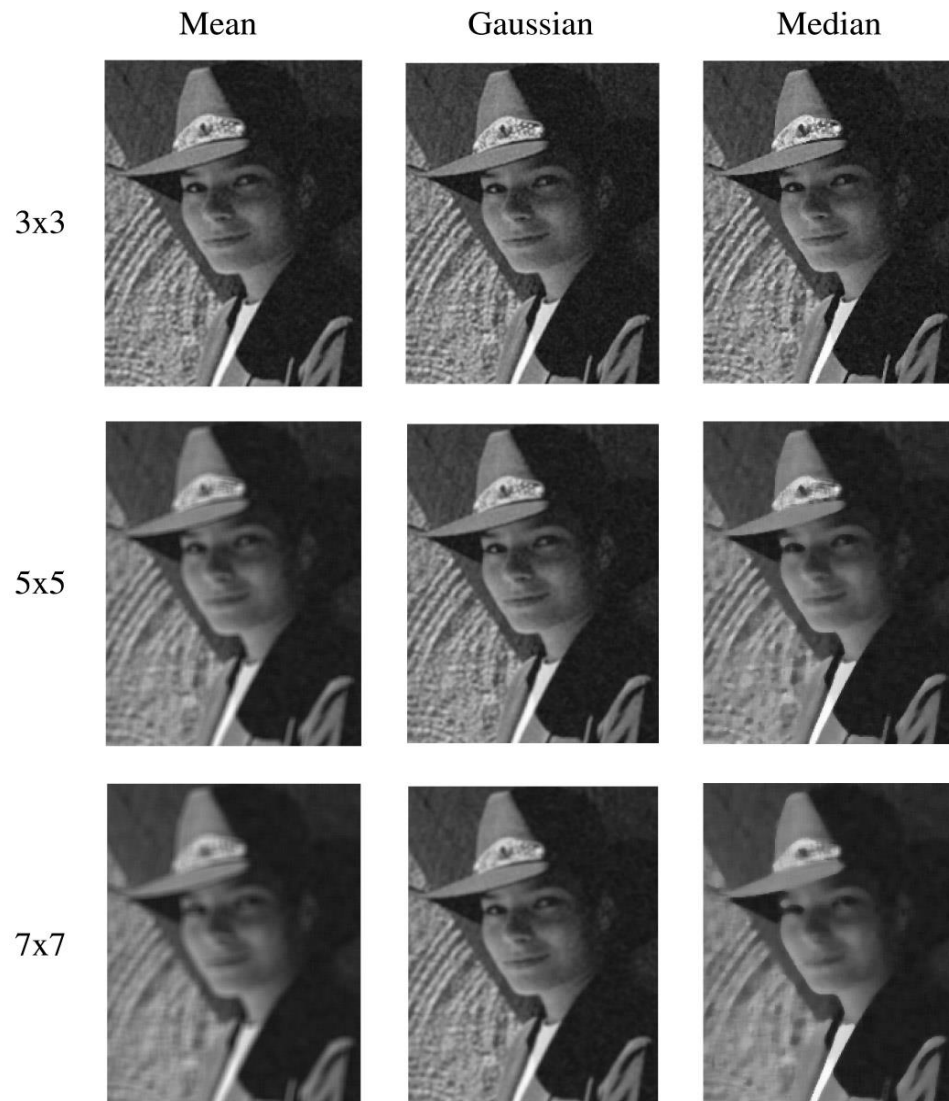
Median Filter

- ▶ Median Filter:
$$\hat{f}(x, y) = \underset{(s,t) \in S_{xy}}{\text{median}}\{g(s, t)\}$$
- ▶ Excellent at noise removal, without the smoothing effects that can occur with other smoothing filters
- ▶ Particularly good when salt and pepper noise is present

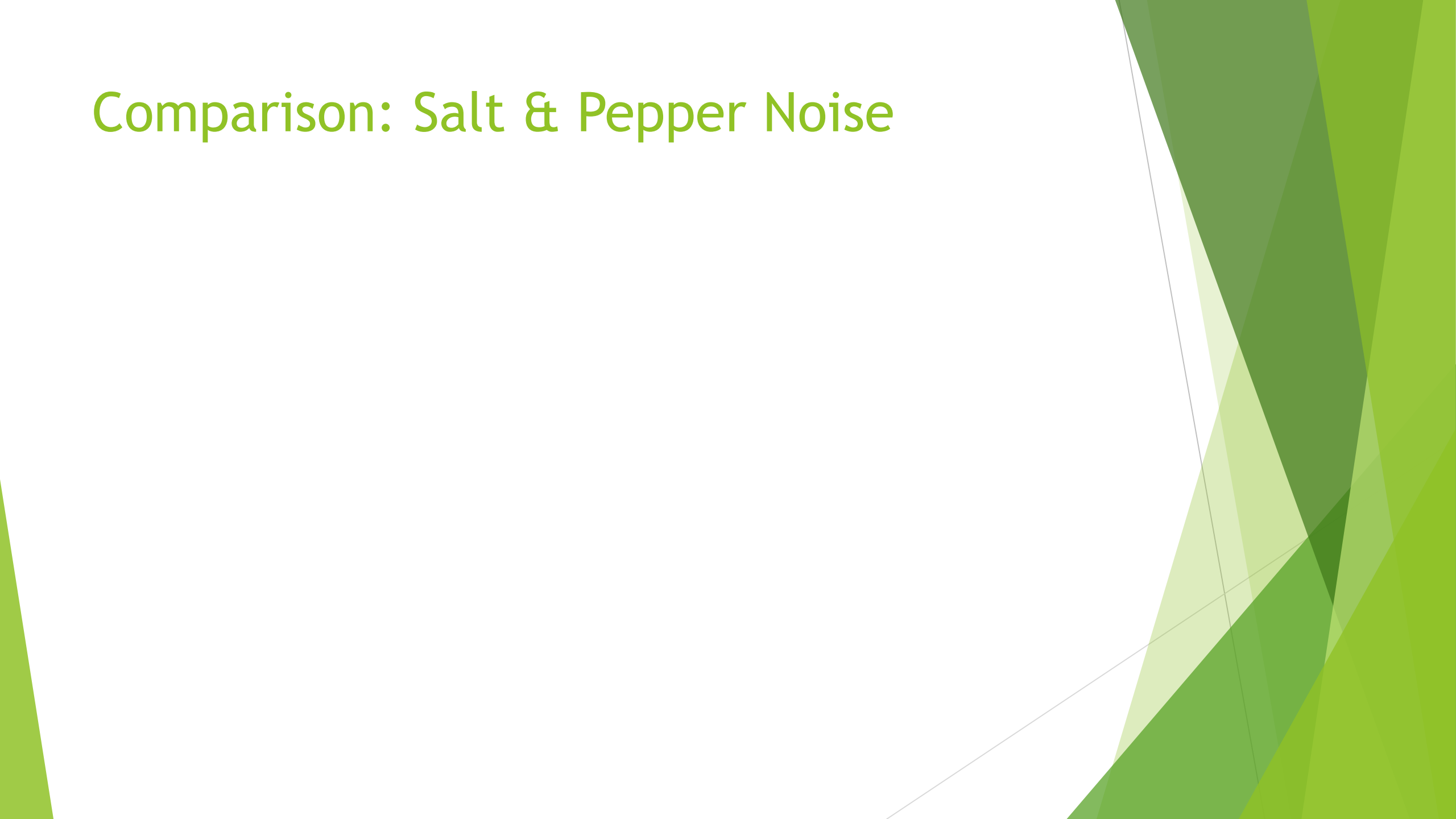
Comparison: Gaussian noise



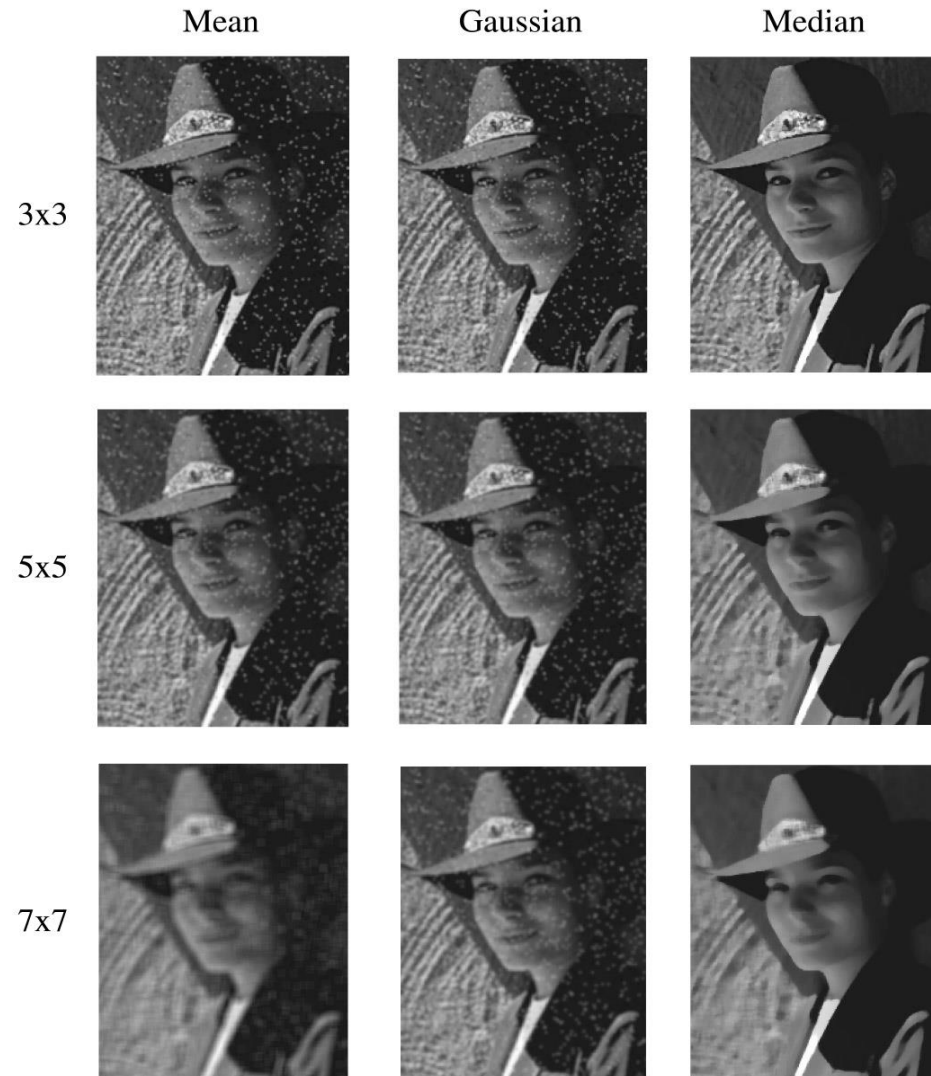
Comparison: Gaussian noise



Comparison: Salt & Pepper Noise



Comparison: Salt & Pepper Noise



Periodic Noise



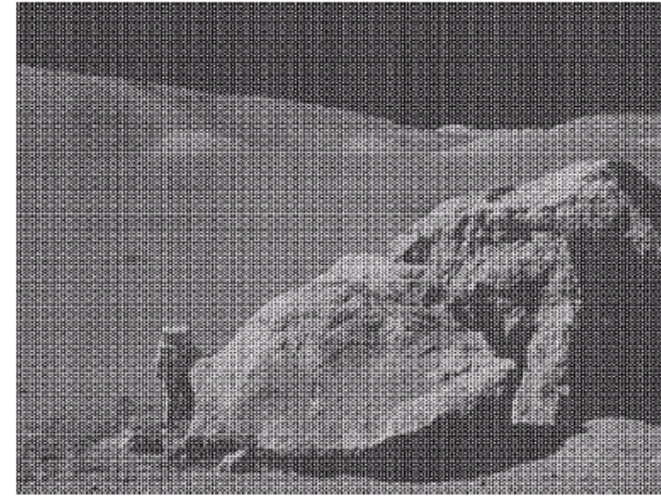
Periodic Noise

- ▶ Typically arises due to electrical or electromagnetic interference
- ▶ Gives rise to regular noise patterns in an image



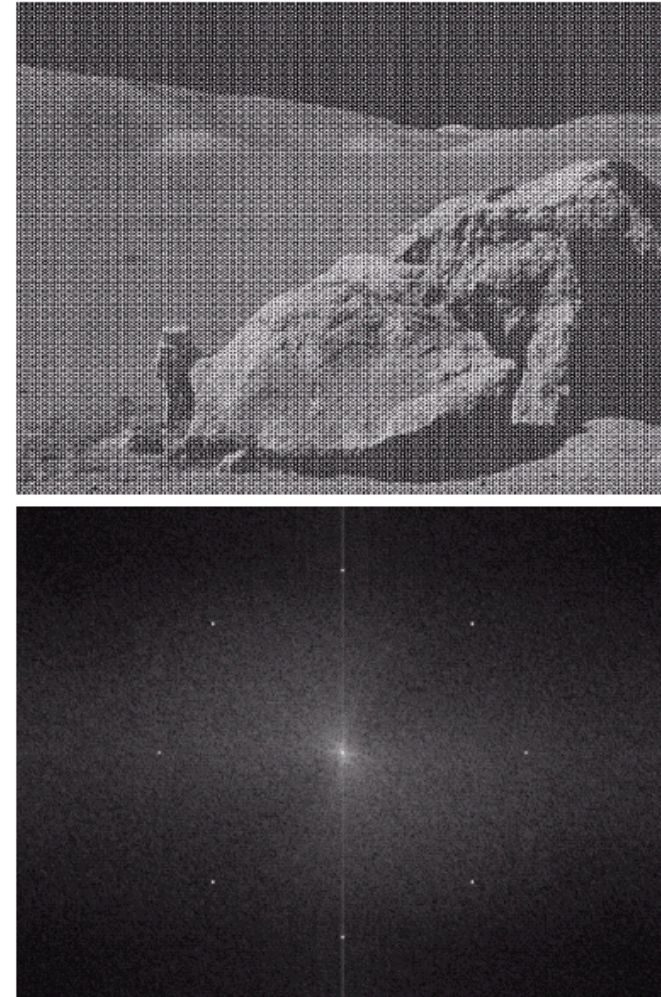
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- ▶ Frequency domain techniques in the Fourier domain are most effective at removing periodic noise



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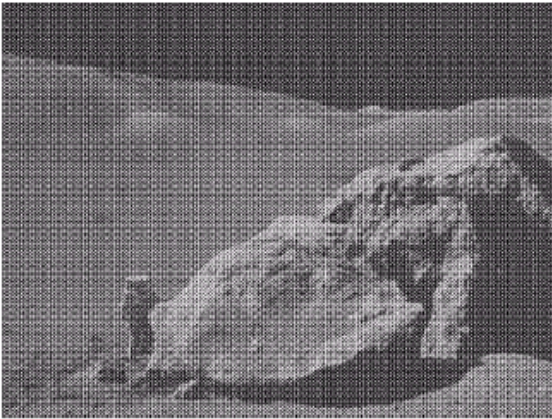
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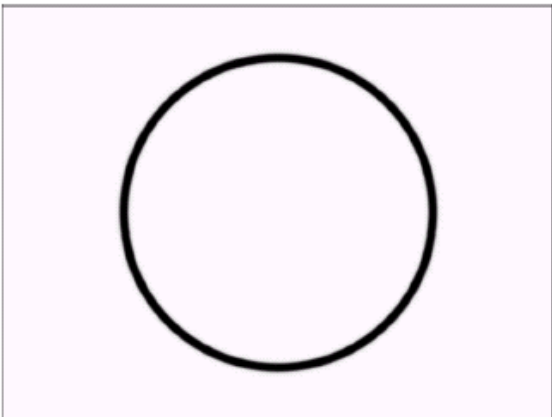
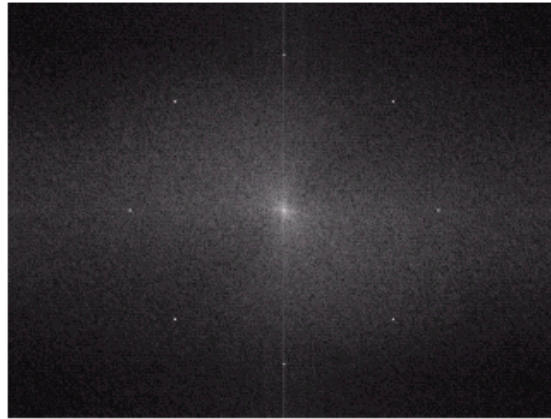
$$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) < D_0 - \frac{W}{2} \\ 0 & \text{if } D_0 - \frac{W}{2} \leq D(u, v) \leq D_0 + \frac{W}{2} \\ 1 & \text{if } D(u, v) > D_0 + \frac{W}{2} \end{cases}$$

Band Reject Filter Example

Image corrupted by
sinusoidal noise



Fourier spectrum of
corrupted image



Butterworth band reject
filter



Filtered image