

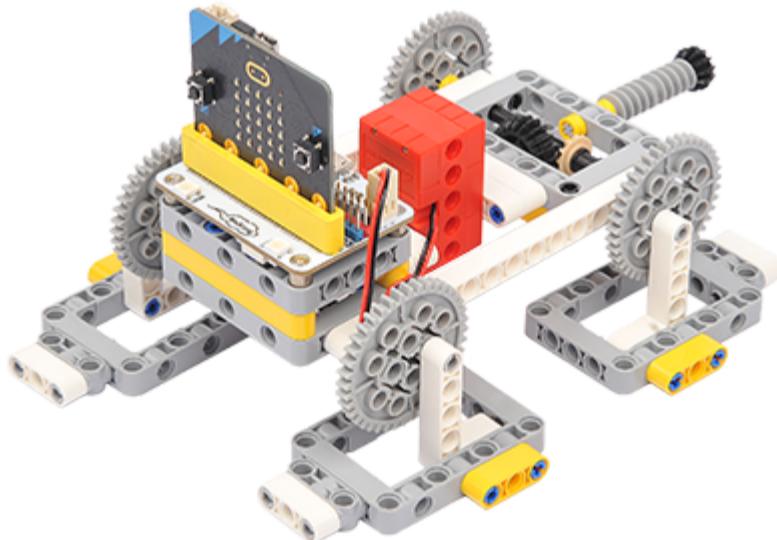
Case 32: Robot Dog

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34.1. Purpose

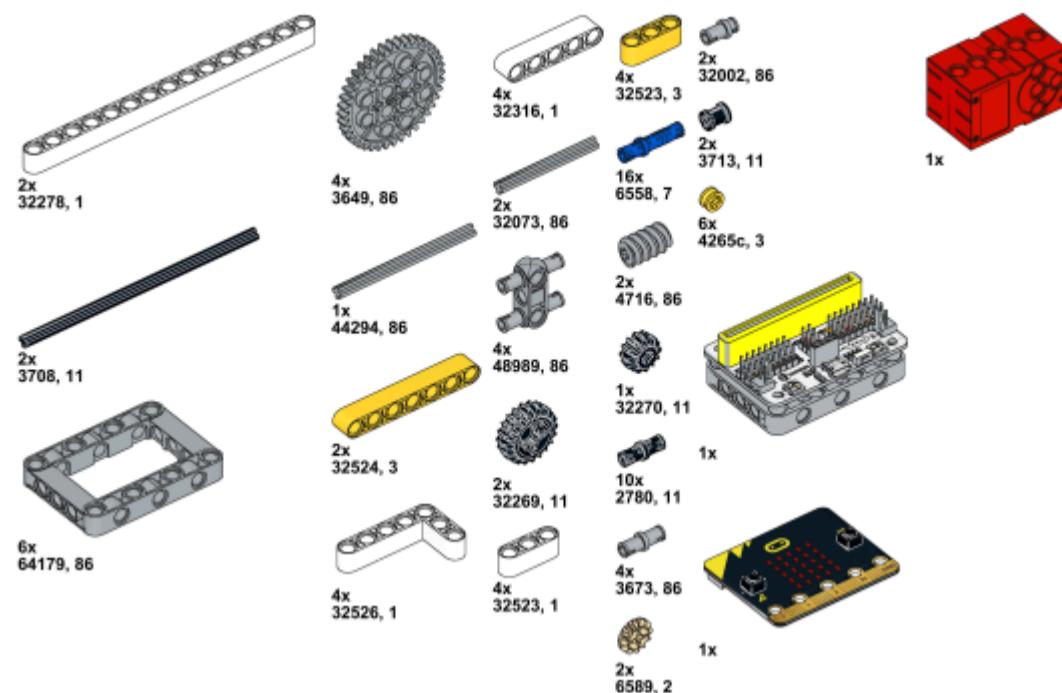
Make a robot dog.



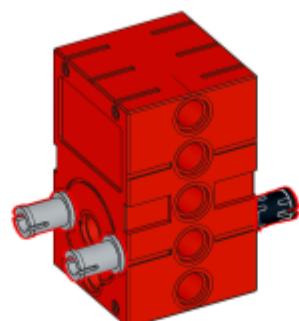
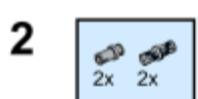
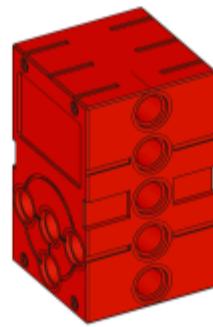
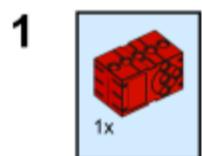
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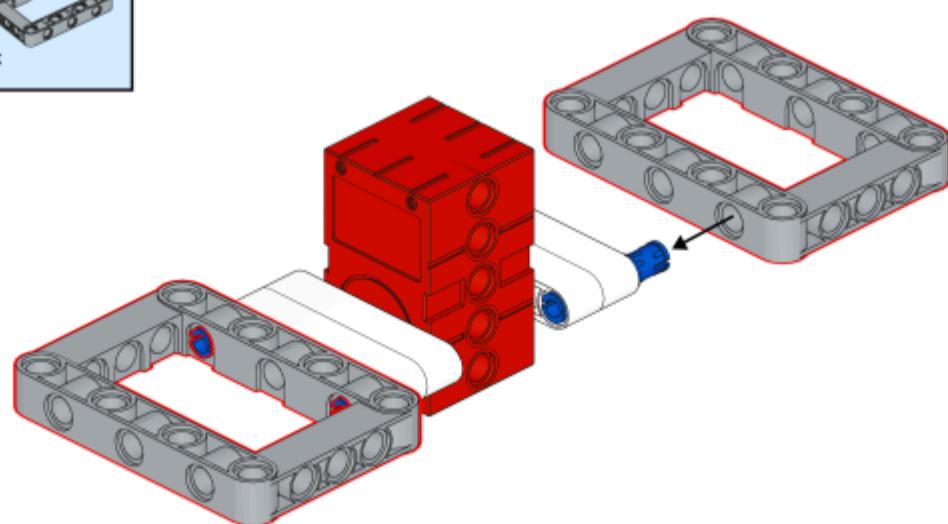
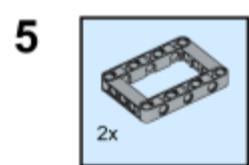
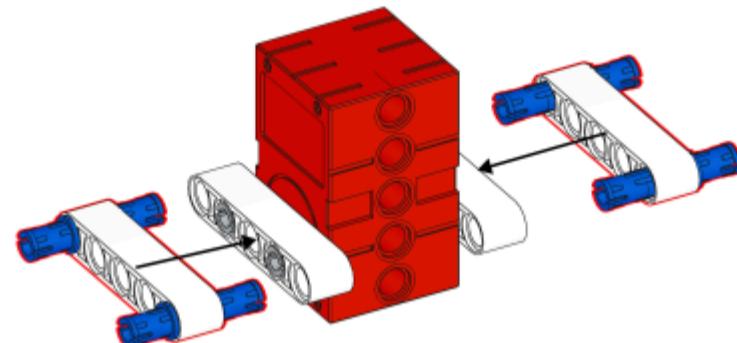
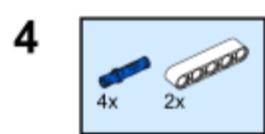
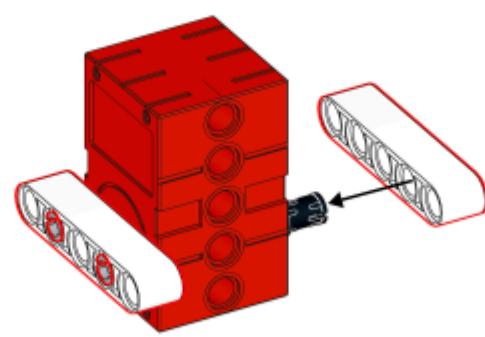
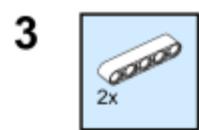
[micro:bit Wonder Building Kit](#)

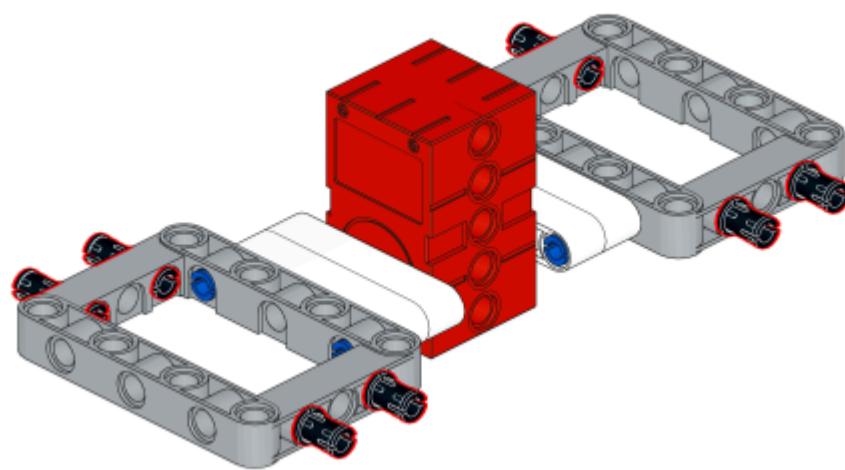
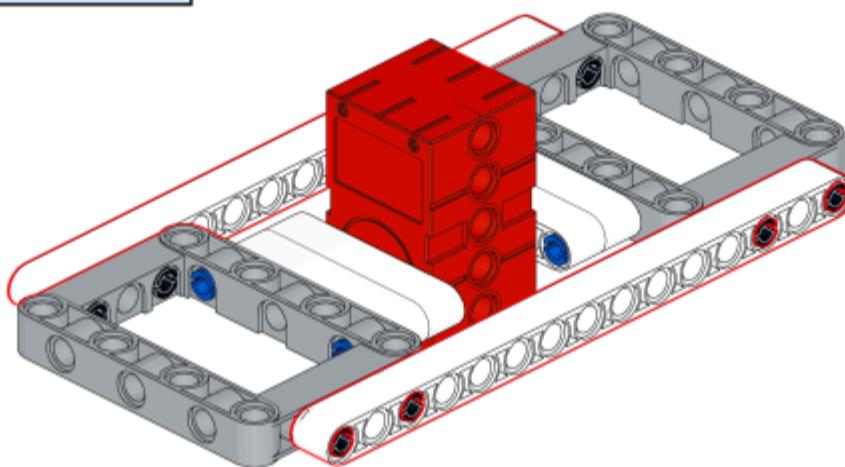
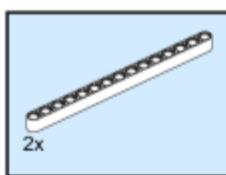
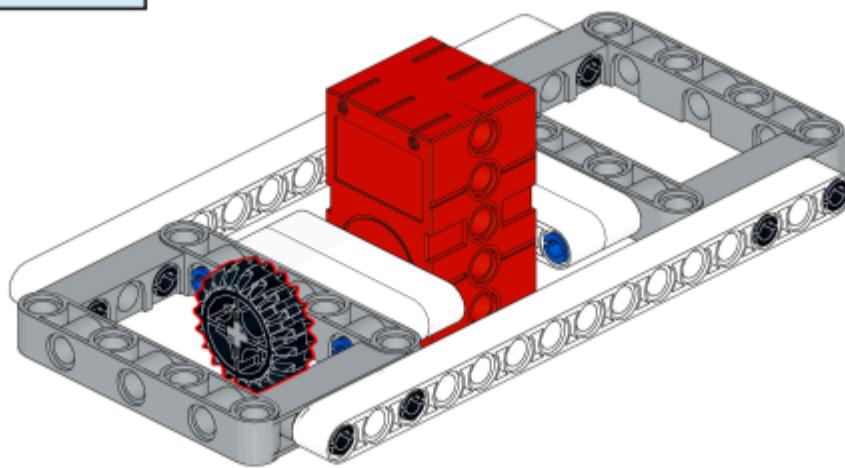
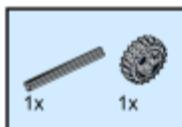
34.3. Materials Required

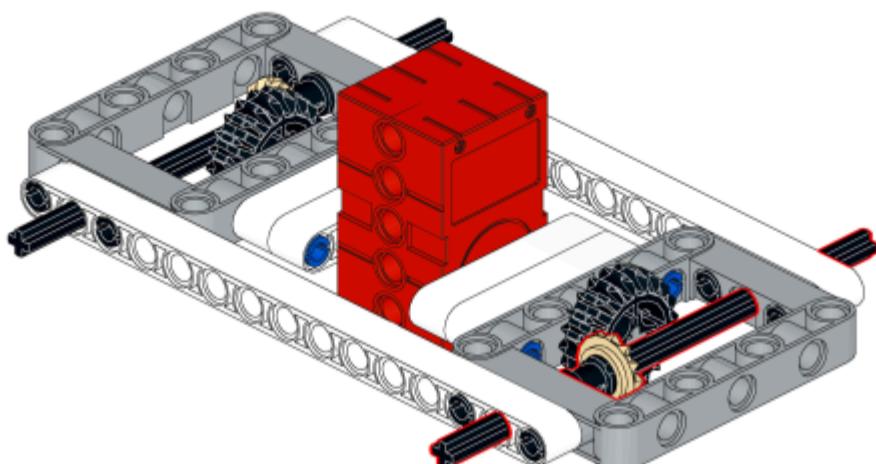
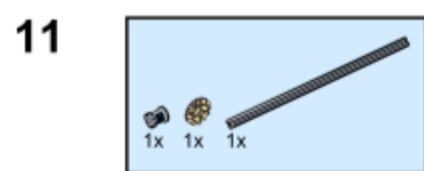
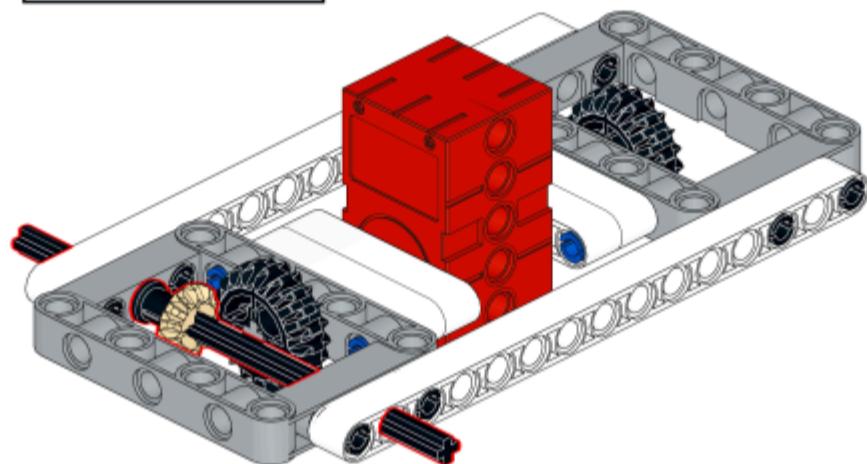
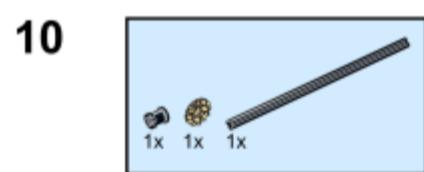
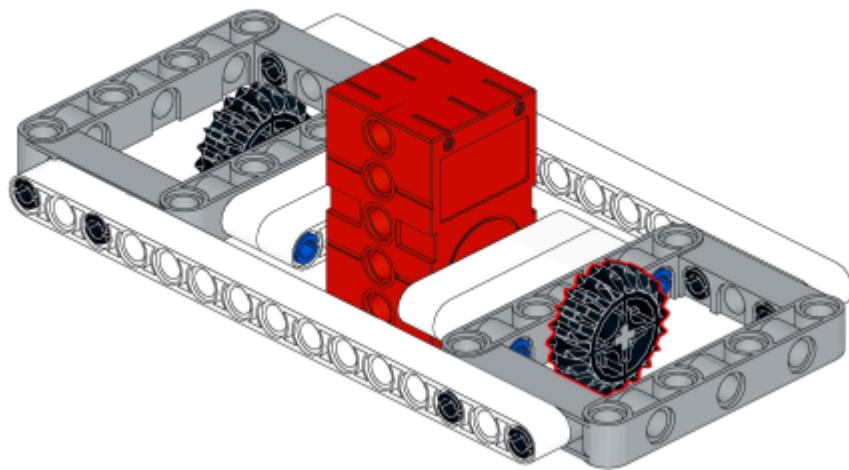
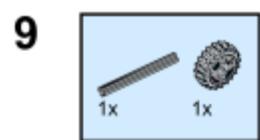


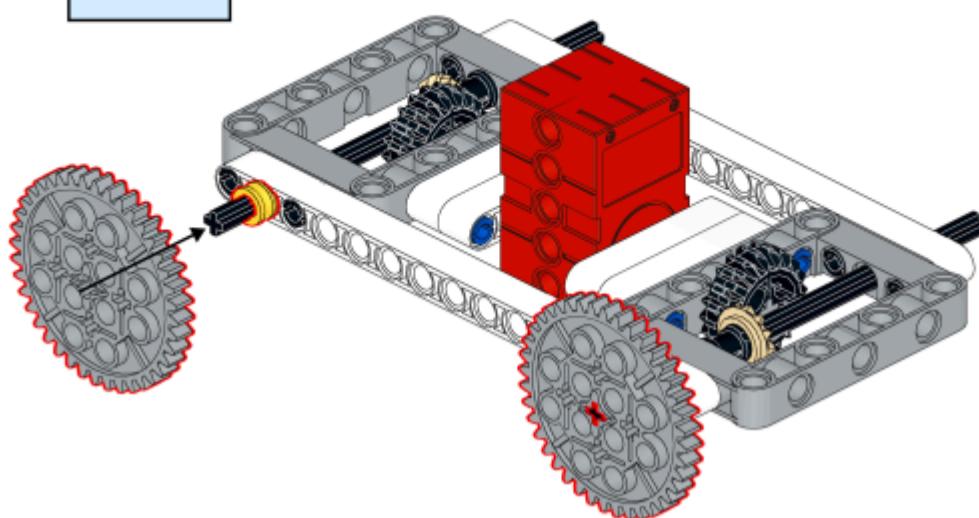
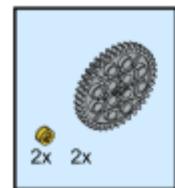
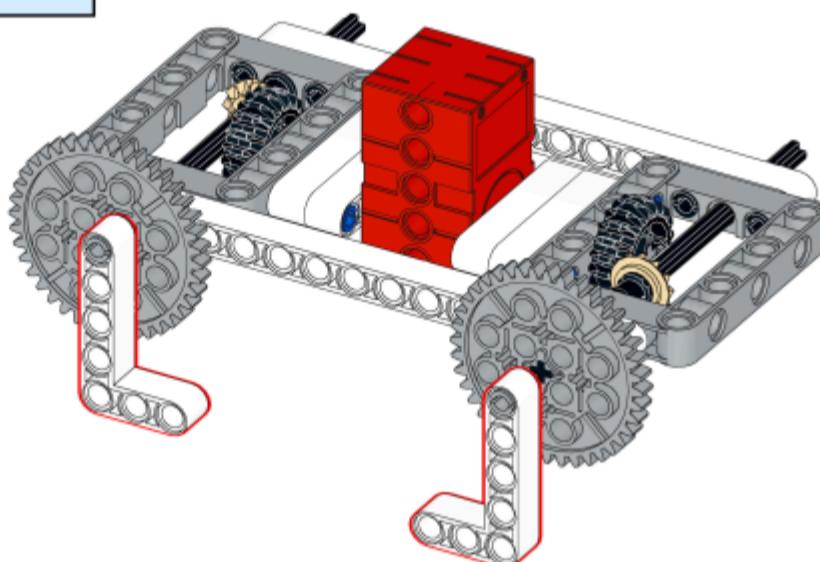
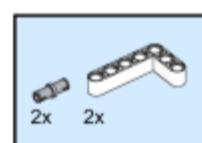
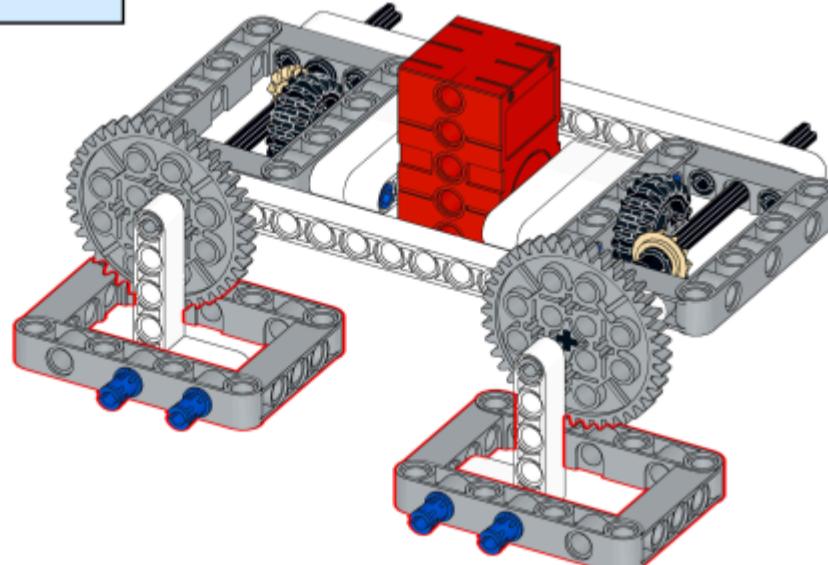
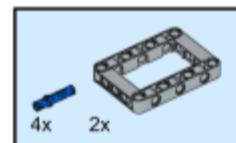
34.4. Bricks build-up

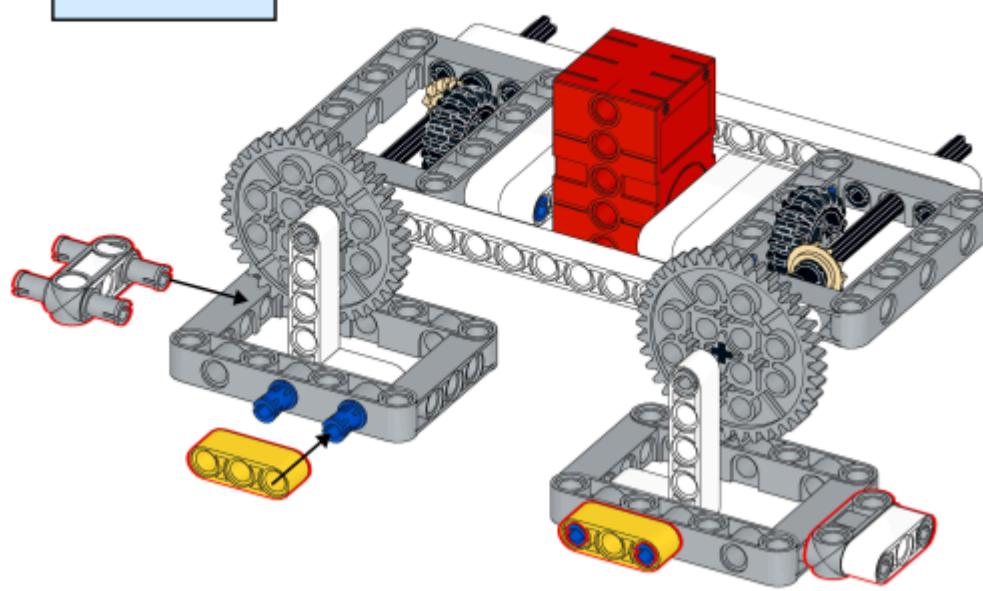
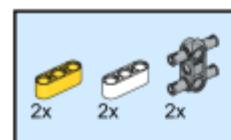
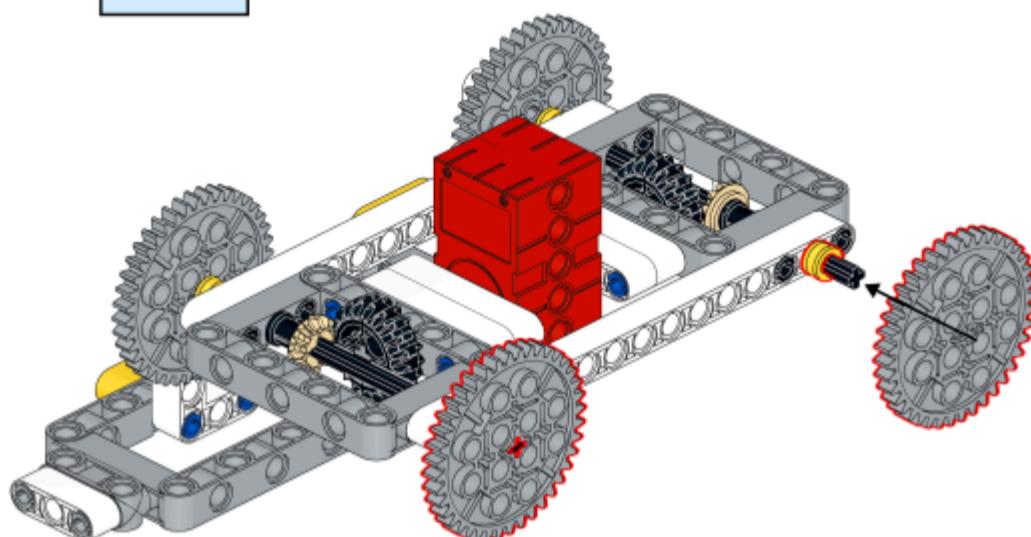
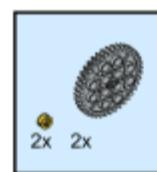
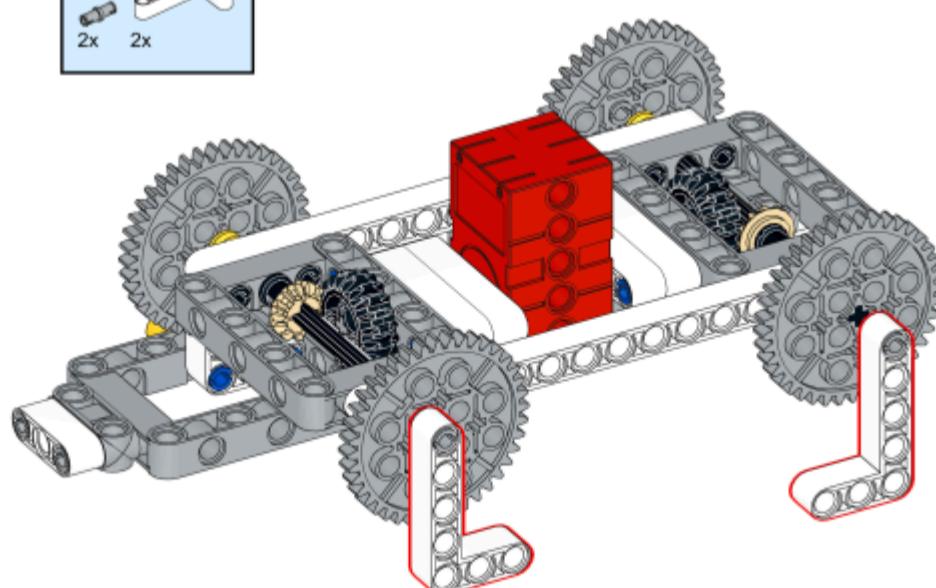
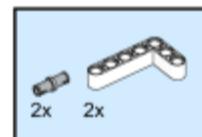


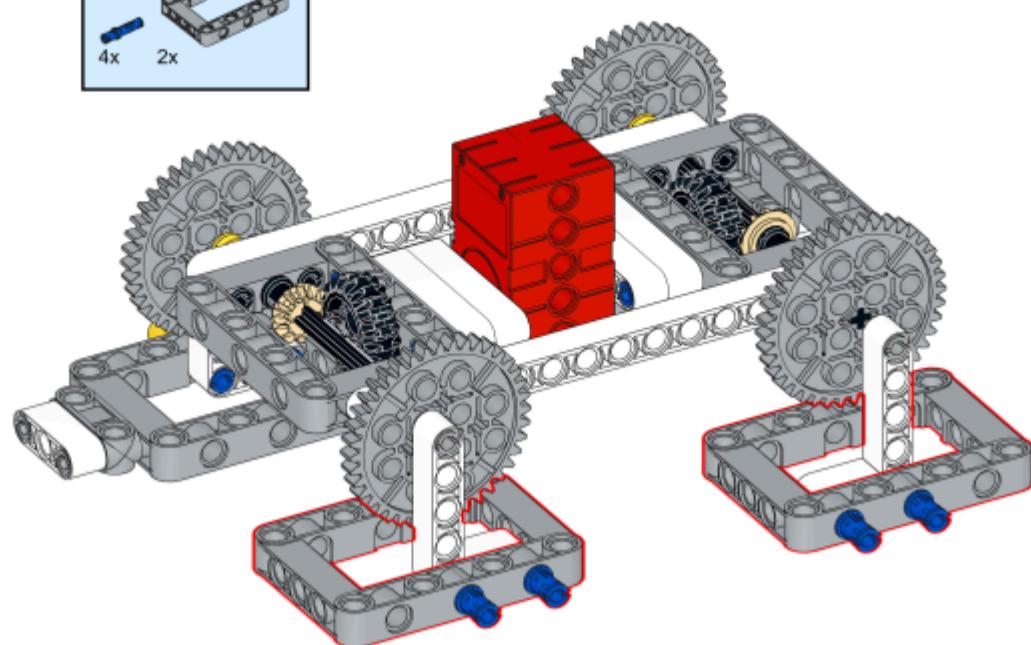
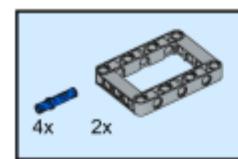
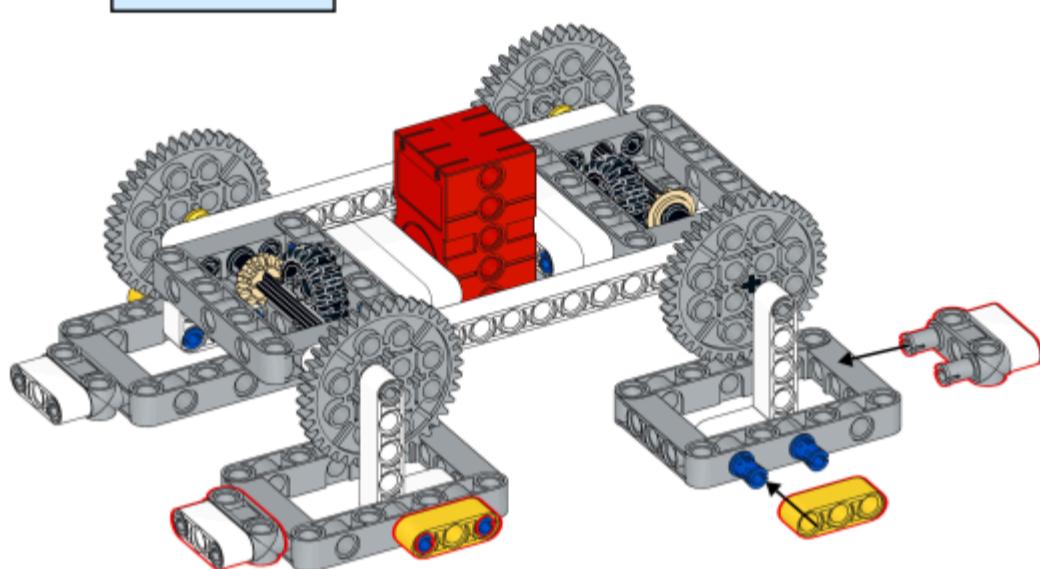
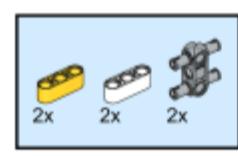
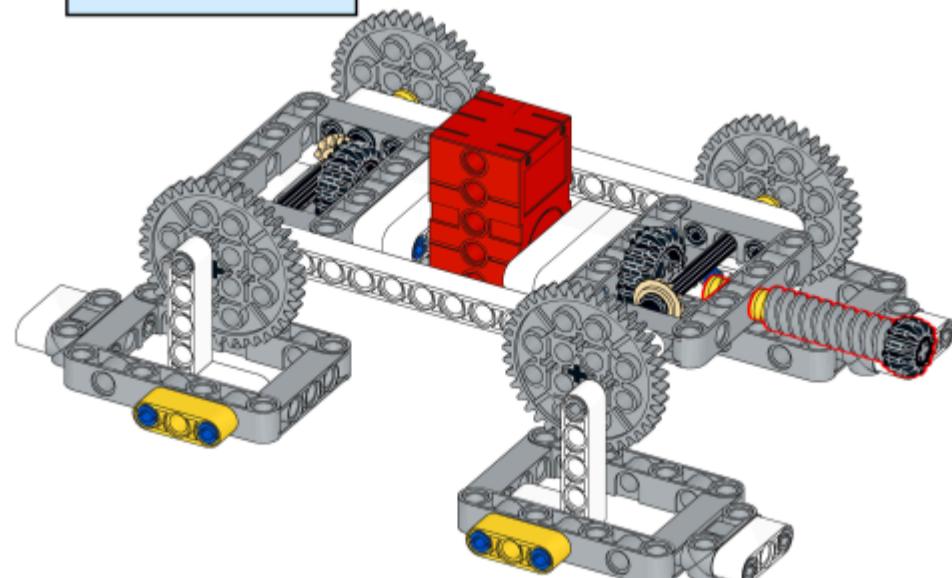
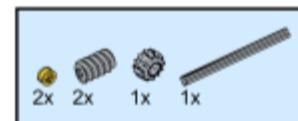


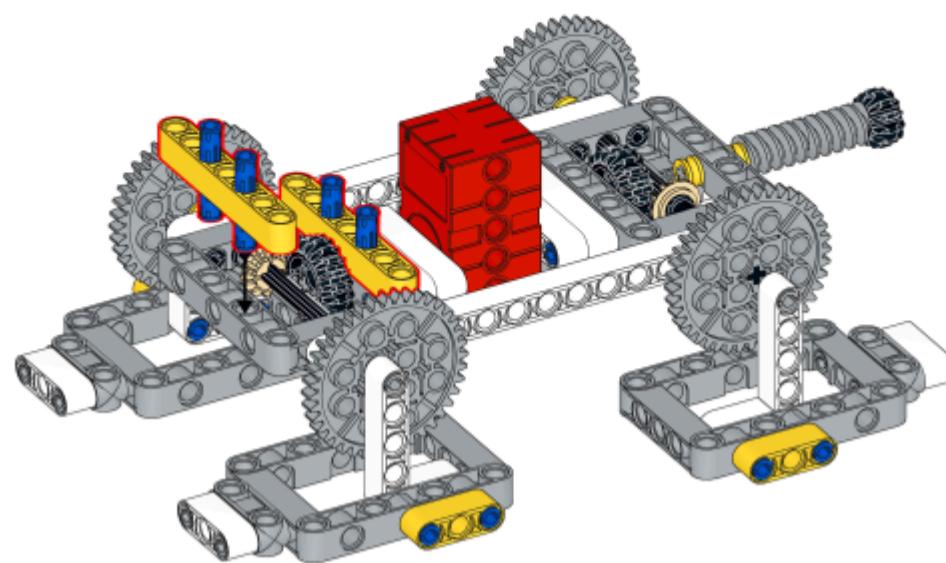
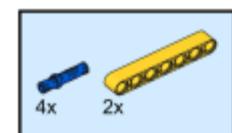
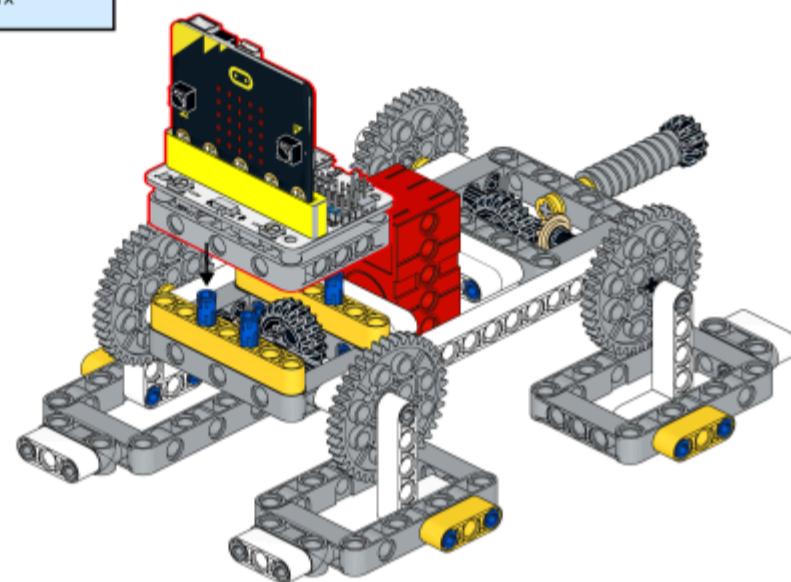
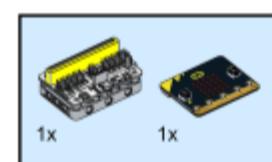
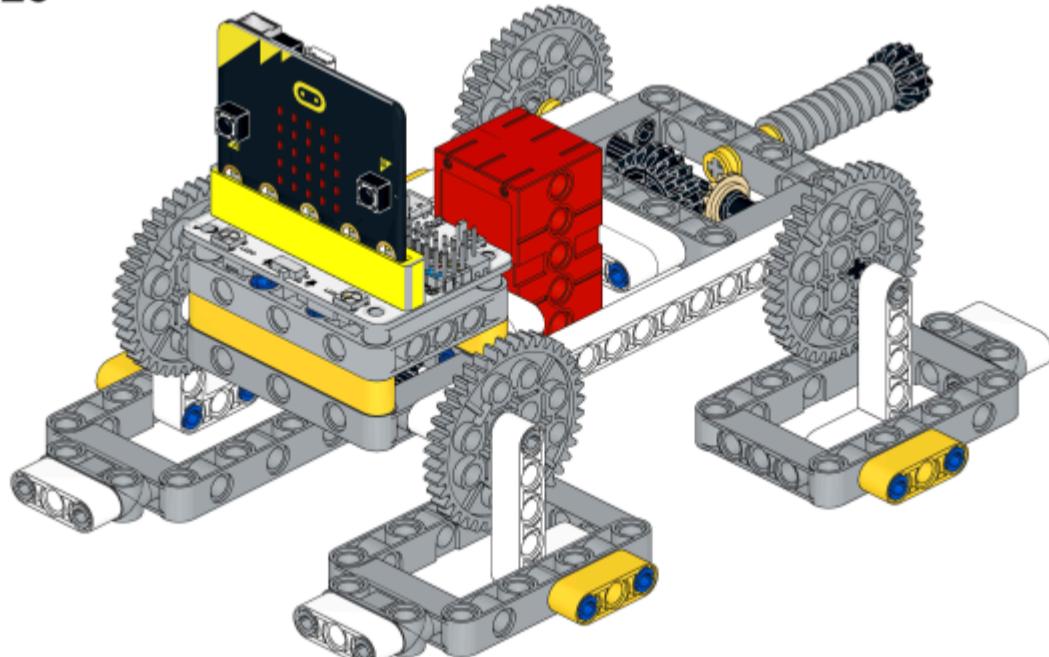
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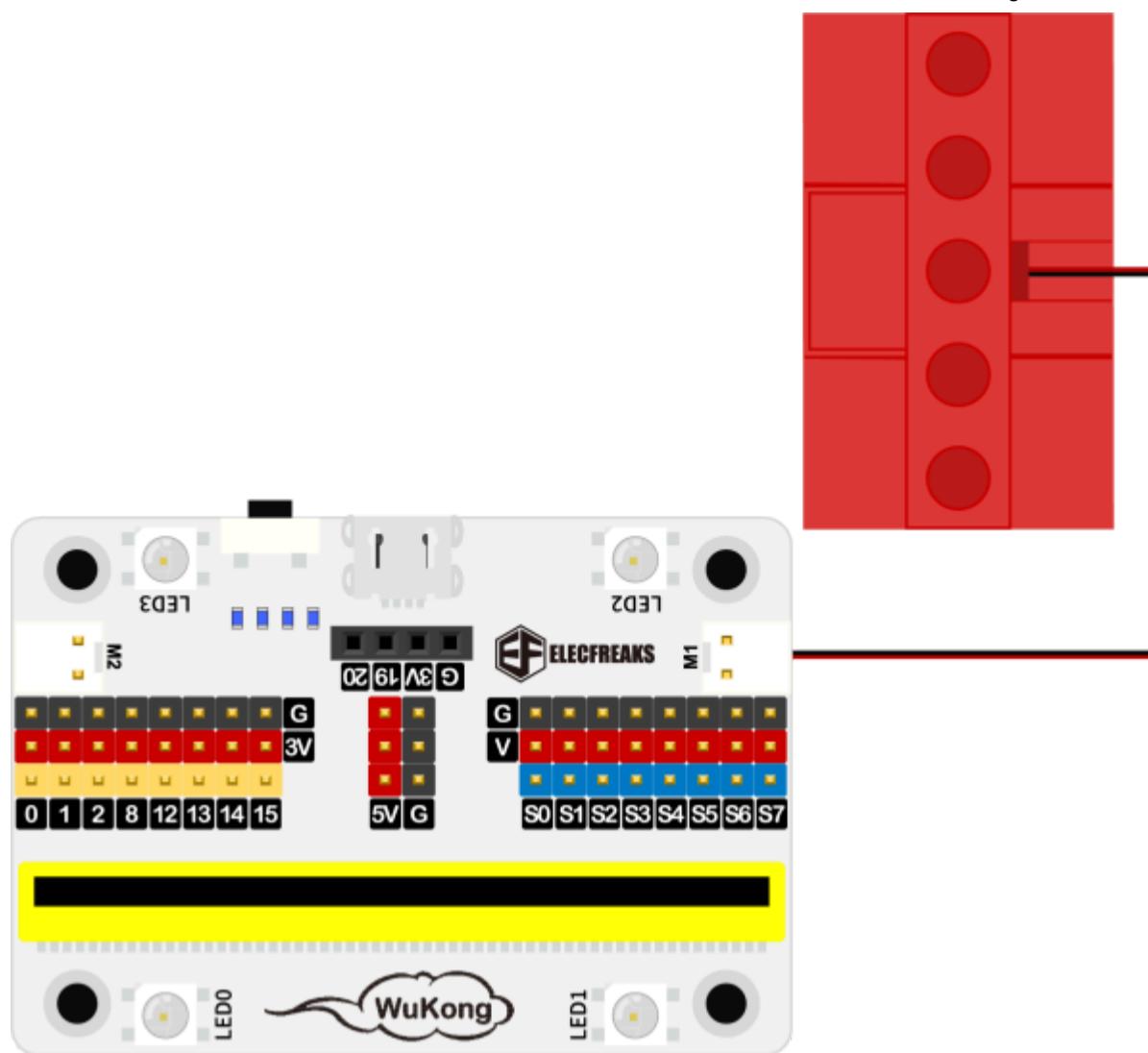
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21**22****23**

34.5. Hardware Connection

Connect a [motor](#) to M1 port on [Wukong breakout board](#).



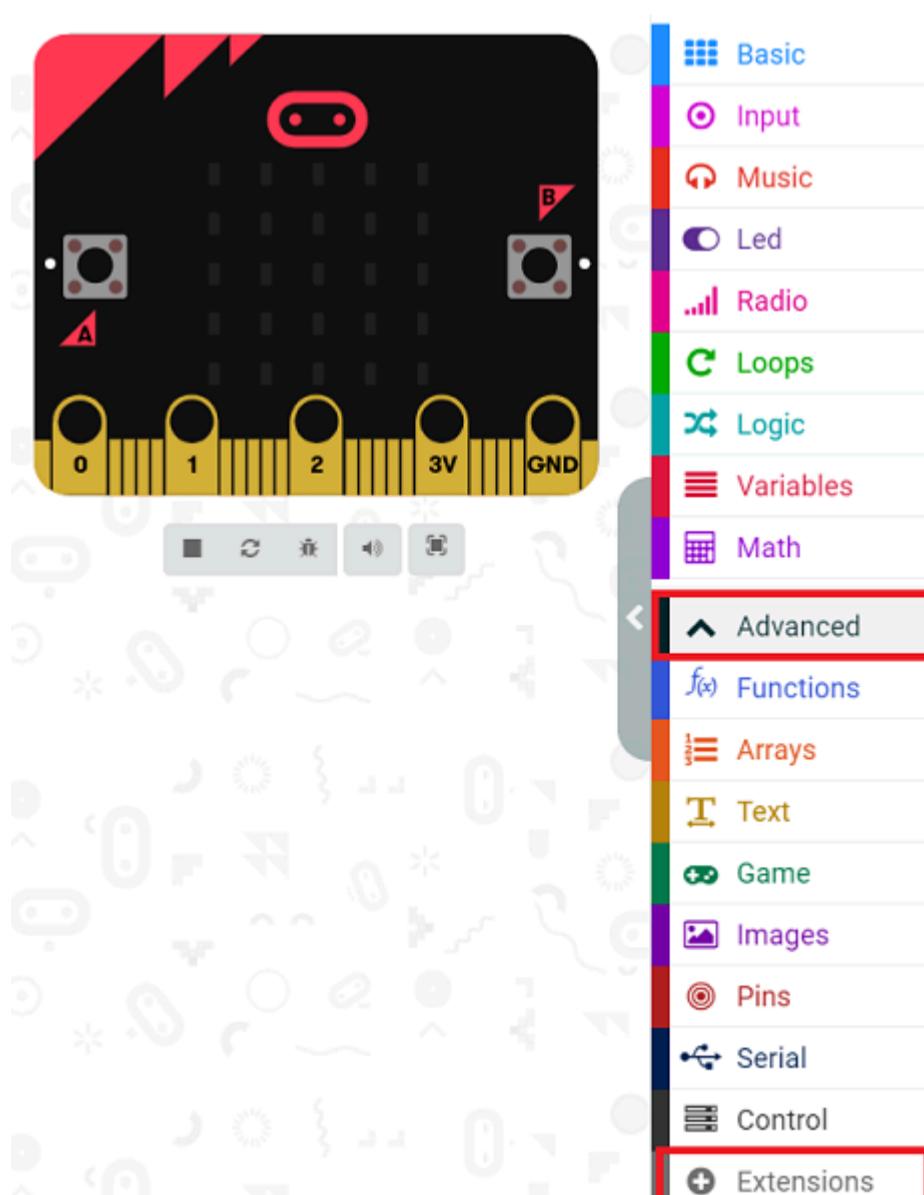
34.6. Software Platform

[MakeCode](#)

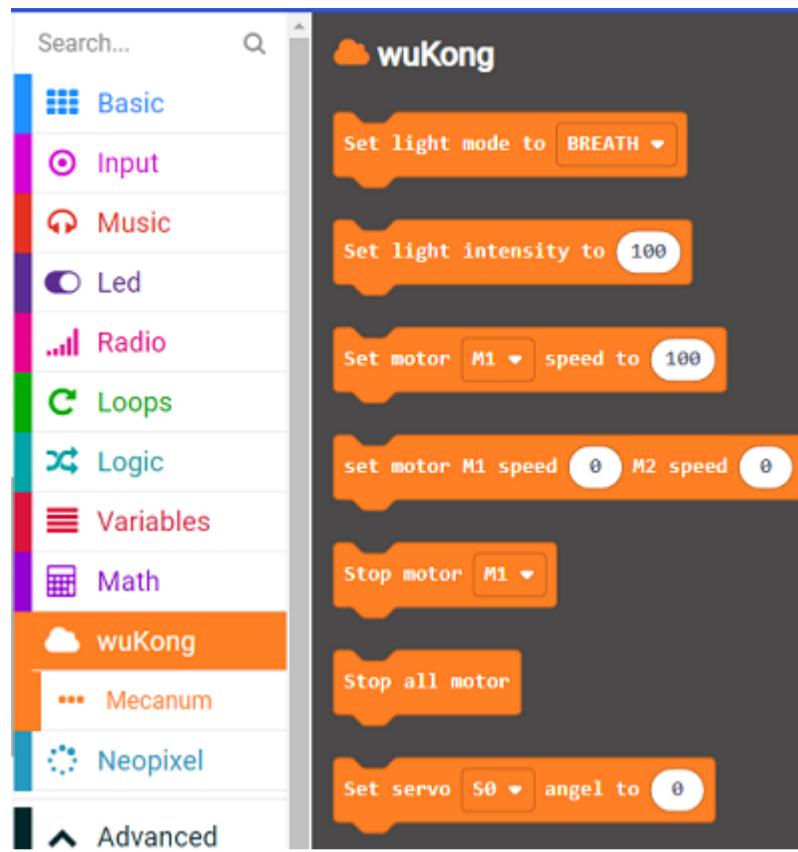
34.7. Coding

Add extensions

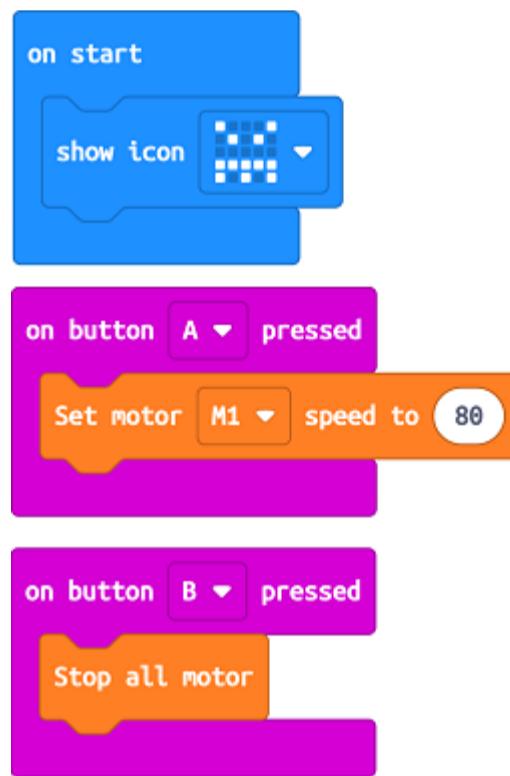
Click “Advanced” in the MakeCode to see more choices.



Search with Wukong in the dialogue box to download it.



Program



Link:https://makecode.microbit.org/_E5pWvtMr1CK1

Result

When button A is pressed, the robot dog moves forward; and when button B is pressed, the robot dog stops moving.

By ELECFREAKS Team

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