

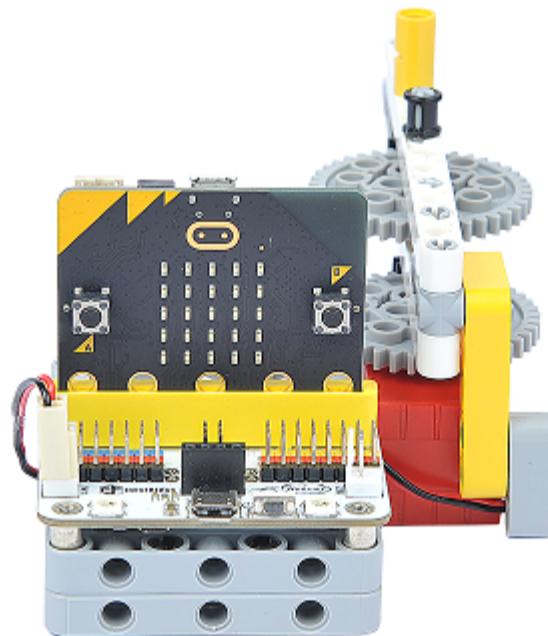
Case 03: The Gyroscope Base

Contents

- [5.1. Purpose](#)
- [5.2. Link](#)
- [5.3. Materials Required](#)
- [5.4. Bricks build-up](#)
- [5.5. Hardware Connection](#)
- [5.6. Software Platform](#)
- [5.7. Coding](#)

5.1. Purpose

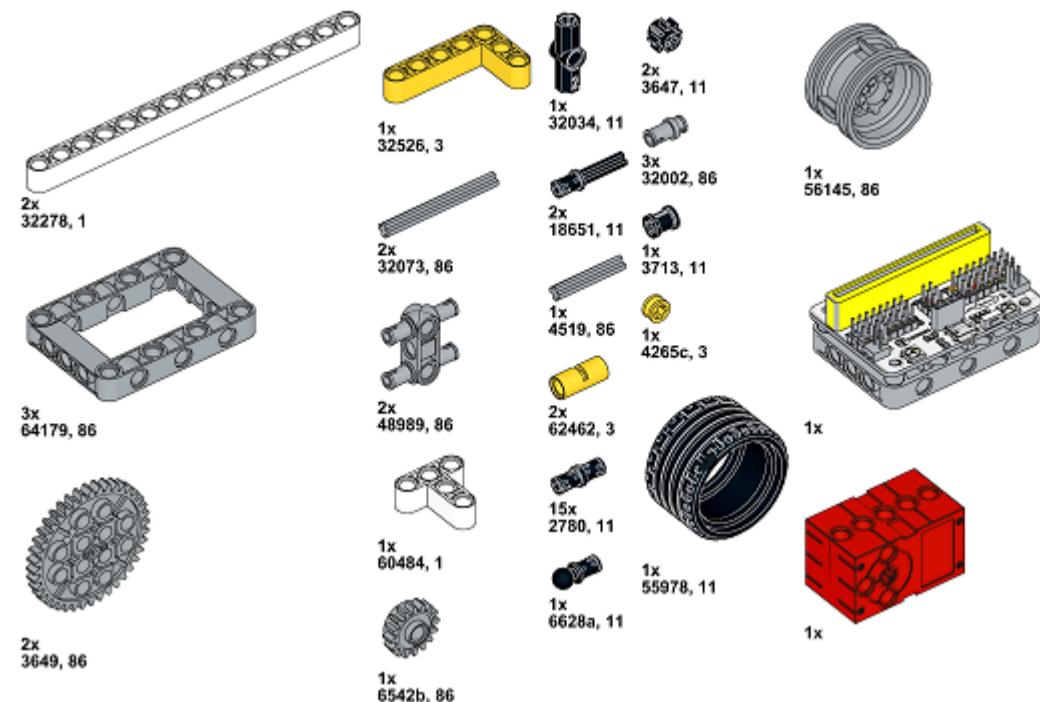
To make a gyroscope baseboard.



5.2. Link

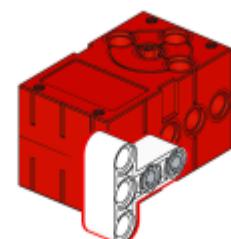
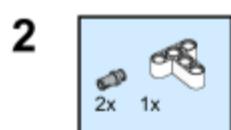
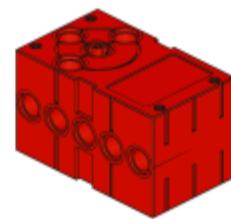
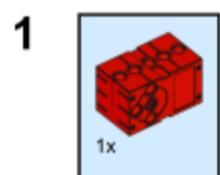
[micro:bit Wonder Building Kit](#)

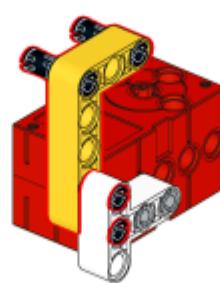
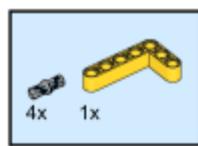
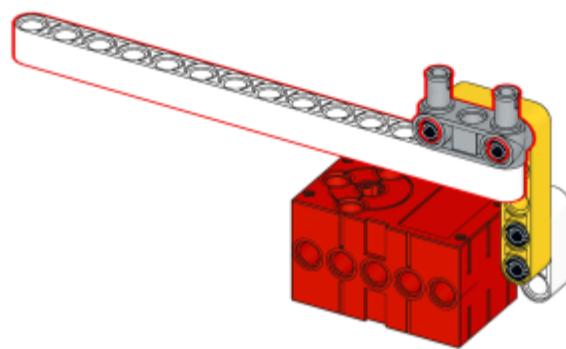
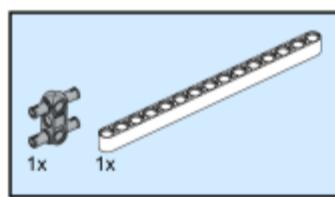
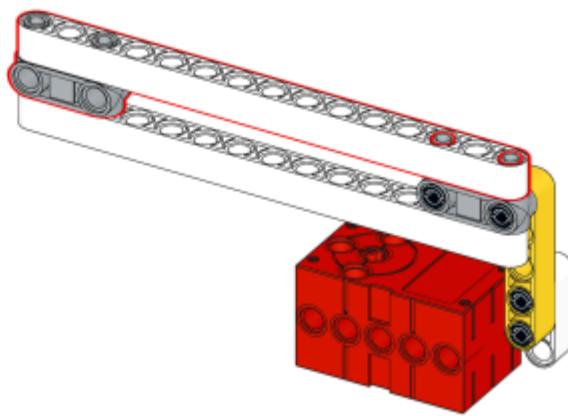
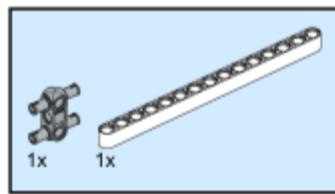
5.3. Materials Required

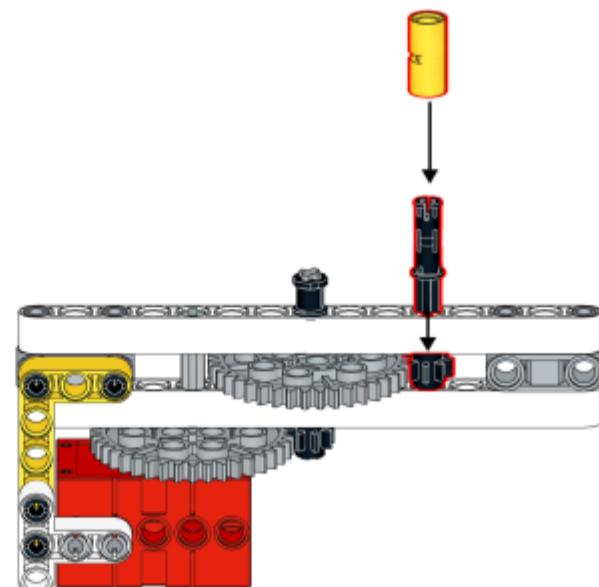
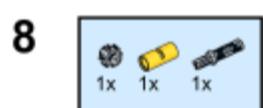
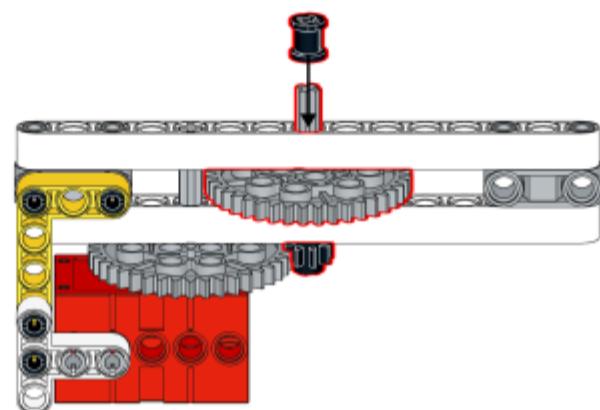
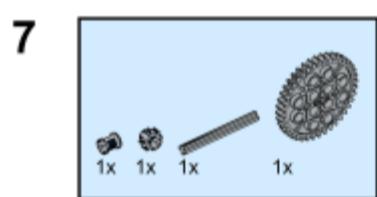
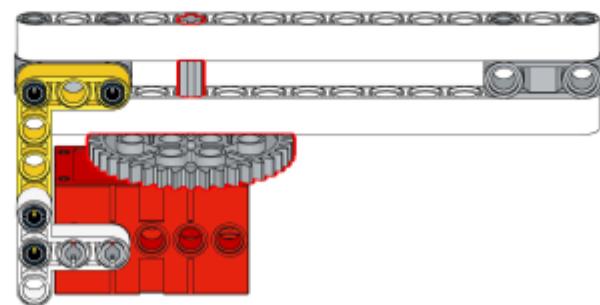
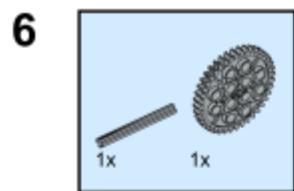


Video link: https://youtu.be/XC_tynRRxR0

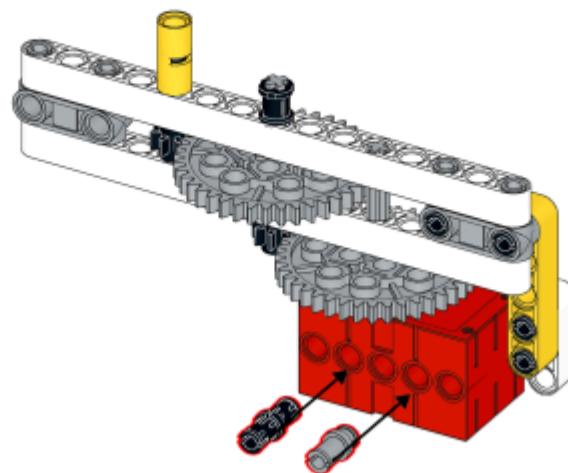
5.4. Bricks build-up



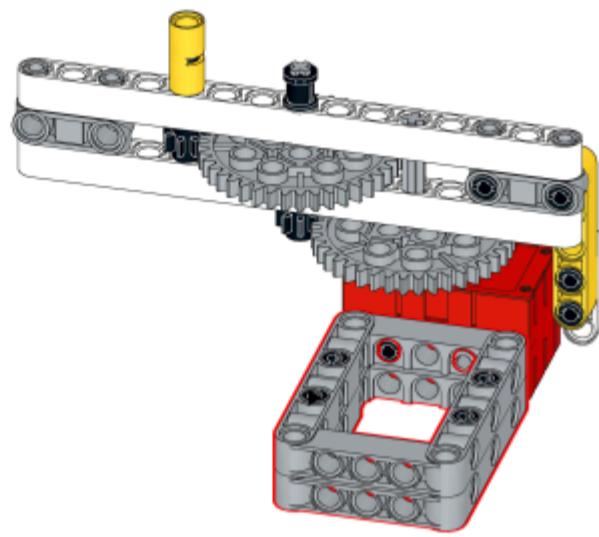
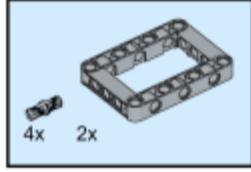
3**4****5**



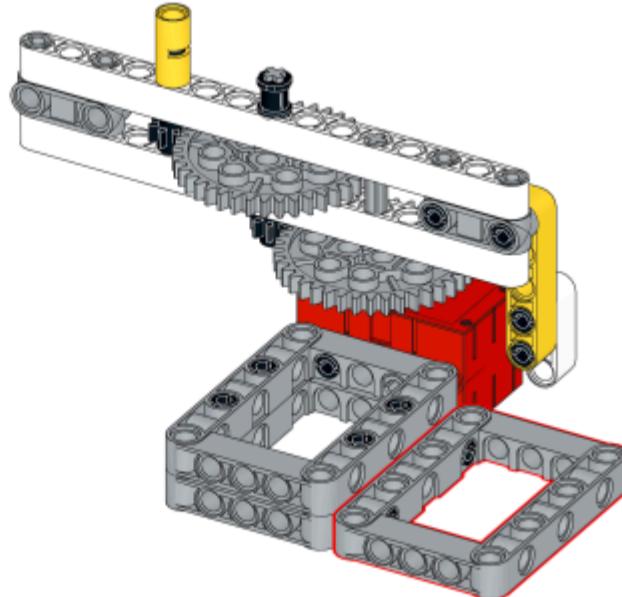
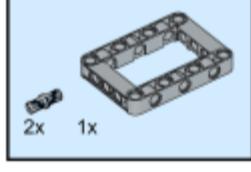
9

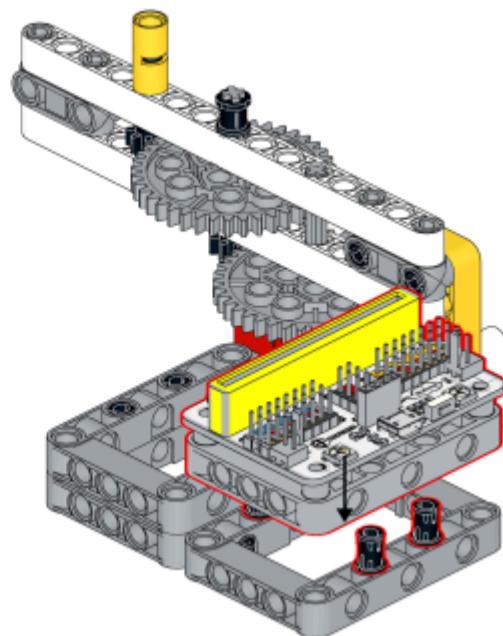
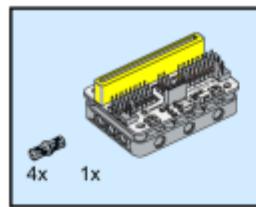
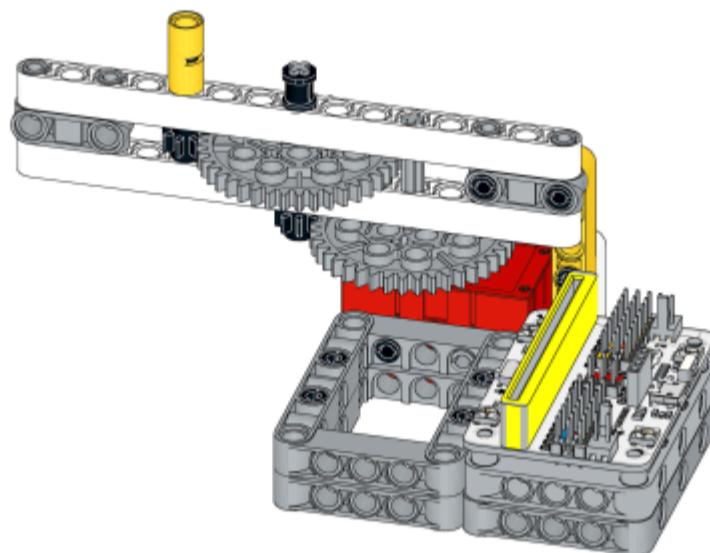


10



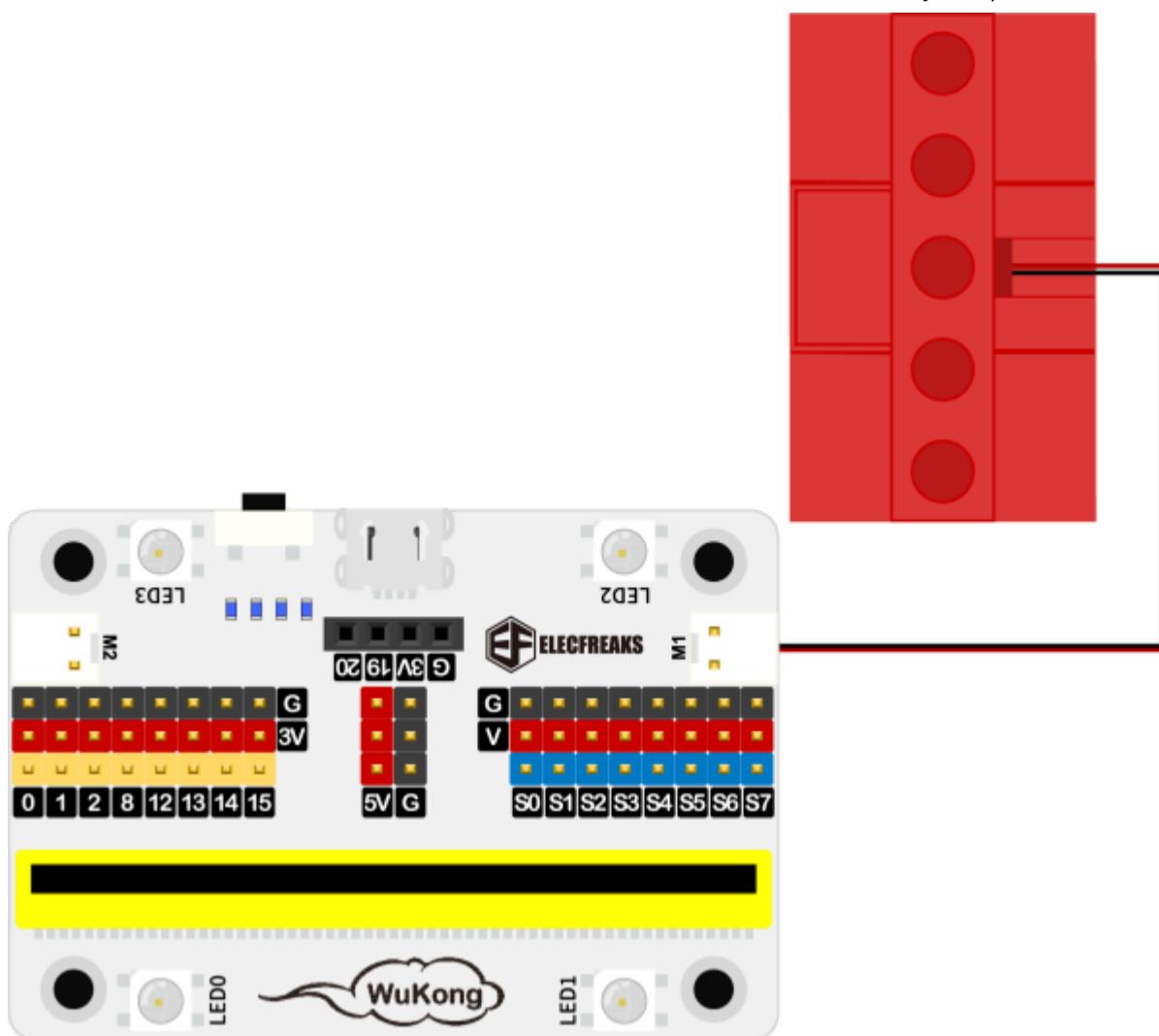
11



12**13**

5.5. Hardware Connection

Connect a [motor](#) to M1 port on [Wukong breakout board](#).



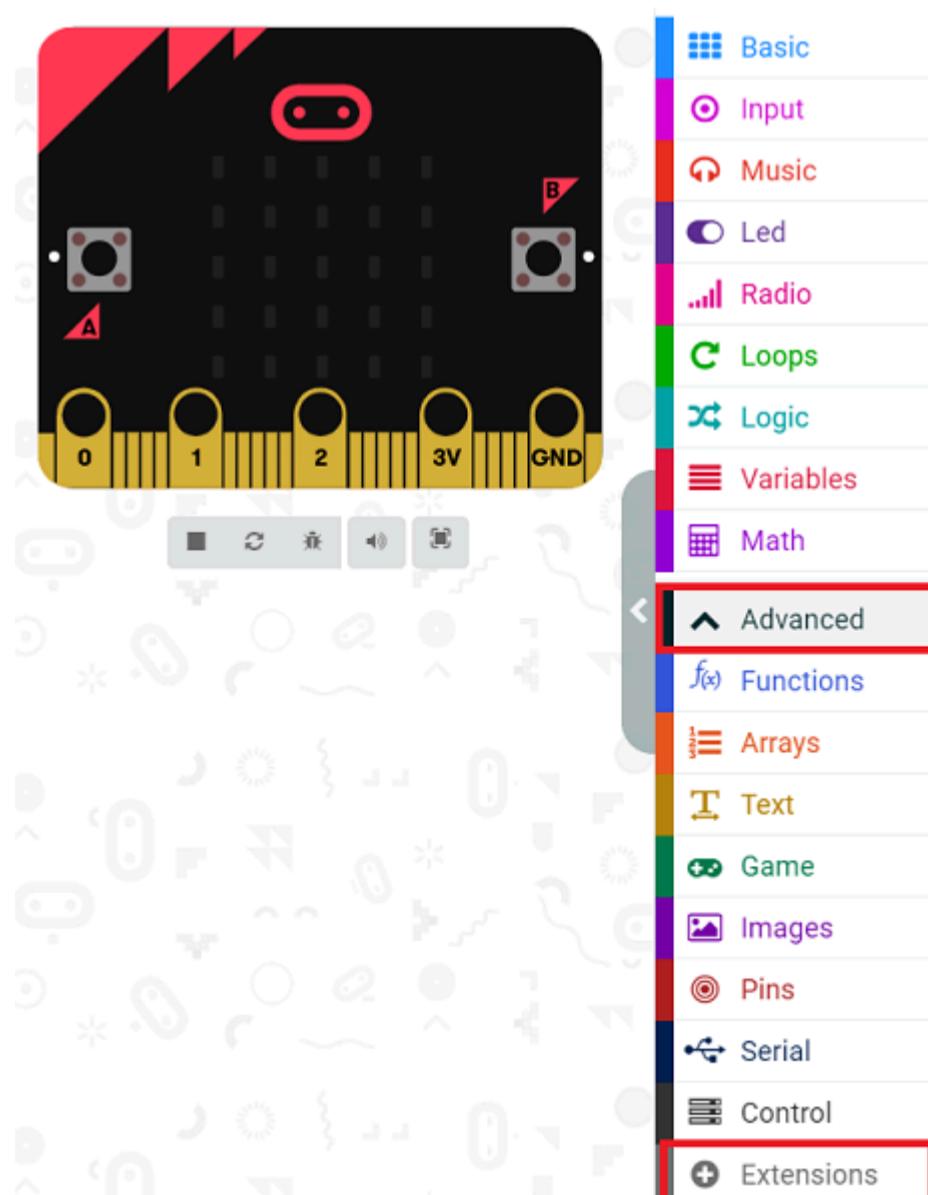
5.6. Software Platform

[MakeCode](#)

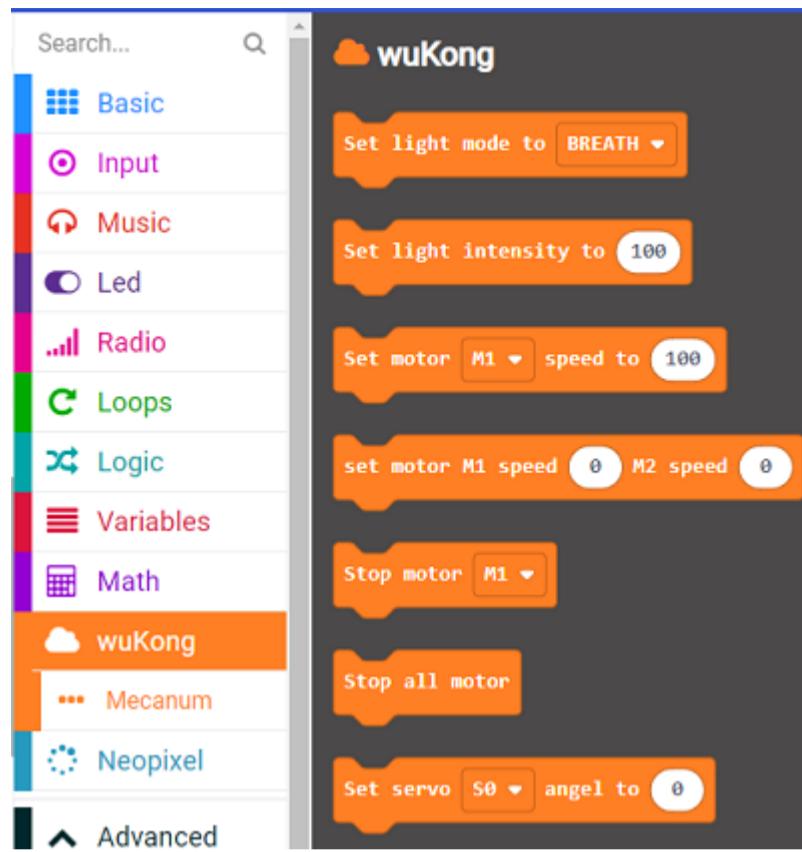
5.7. Coding

Add extensions

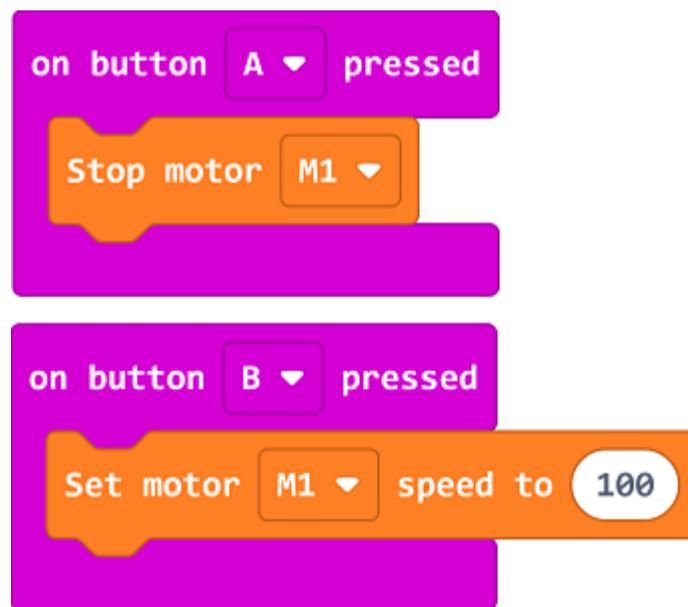
Click “Advanced” in the MakeCode to see more choices.



Search with Wukong in the dialogue box to download it.



Program



Link:https://makecode.microbit.org/_FFibega47Hwy

Result

Press the button B and the motor connecting to M1 starts driving, put the gyroscope base on the swirling yellow connectors, when the accelerate speed meets the standard, release your hands and it will not fall off; press button A to stop driving the motor.

By ELECFREAKS Team

© Copyright 2022, ELECFREAKS Team.