GOOGLE COLAB:

CODE:

```
# Mount Google Drive to access the dataset
from google.colab import drive
drive.mount('/content/drive')
# Install necessary libraries
!pip install tensorflow
# Import libraries
import os
import numpy as np
import tensorflow as tf
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
from tensorflow.keras.models import Sequential
# Define paths to the dataset
base dir = '/content/drive/MyDrive/Colab
Notebooks/forest fire detection/dataset'
train dir = os.path.join(base dir, 'train')
validation dir = os.path.join(base dir, 'validation')
# Preprocess and augment data
train datagen = ImageDataGenerator(
rescale=1./255,
rotation range=40,
width shift range=0.2,
height shift range=0.2,
shear range=0.2,
zoom range=0.2,
horizontal flip=True,
fill mode='nearest'
validation datagen = ImageDataGenerator(rescale=1./255)
train generator = train datagen.flow from directory(
train dir,
target size=(150, 150),
batch size=20,
class mode='binary'
validation generator = validation datagen.flow from directory(
validation dir,
target size=(150, 150),
```

```
batch size=20,
class mode='binary'
# Define the CNN model
model = Sequential([
Conv2D(32, (3, 3), activation='relu', input shape=(150, 150, 3)),
MaxPooling2D(2, 2),
Conv2D(64, (3, 3), activation='relu'),
MaxPooling2D(2, 2),
Conv2D(128, (3, 3), activation='relu'),
MaxPooling2D(2, 2),
Conv2D(128, (3, 3), activation='relu'),
MaxPooling2D(2, 2),
Flatten(),
Dense (512, activation='relu'),
Dense(1, activation='sigmoid')
1)
# Compile the model
model.compile(loss='binary crossentropy',
optimizer=tf.keras.optimizers.RMSprop(lr=1e-4),
metrics=['accuracy'])
# Train the model
history = model.fit(
train generator,
steps per epoch=100,
epochs=20,
validation data=validation generator,
validation steps=50
# Save the model
model.save('/content/drive/MyDrive/Colab
Notebooks/forest fire detection/forest fire detection model.h5')
```

OUTPUT