

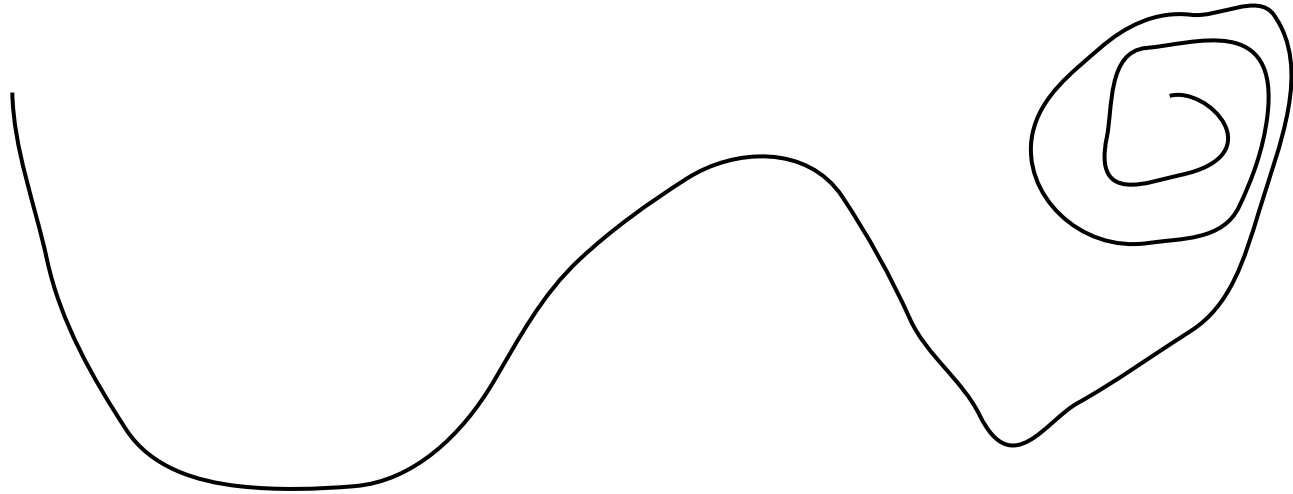
# Integration

Thomas Torsney-Weir

# Streamline

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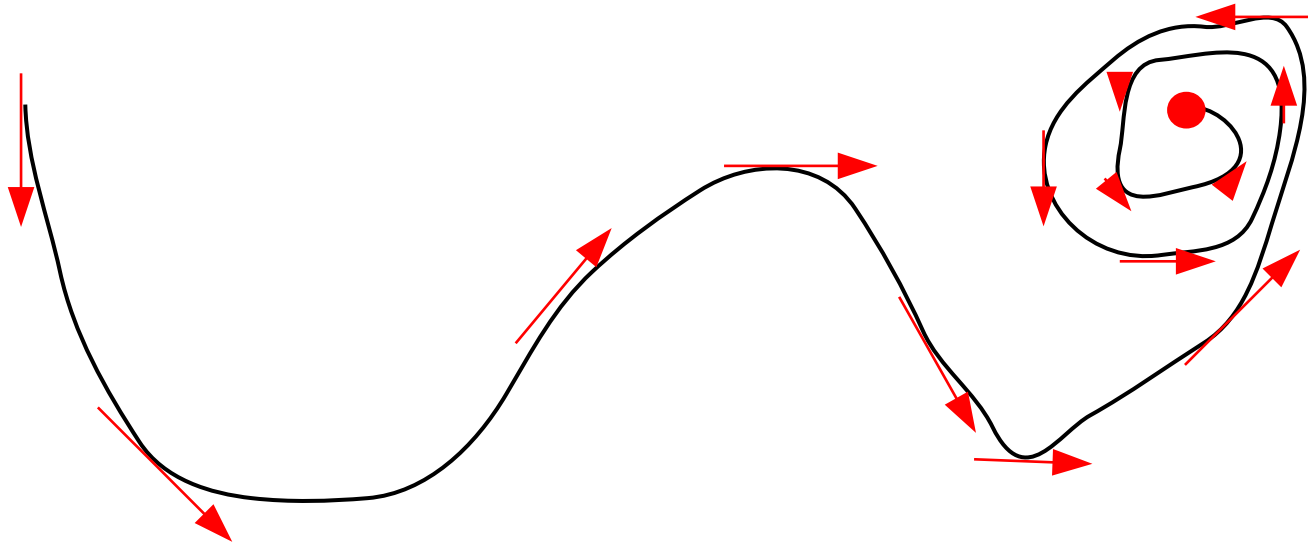
**Streamline:** a curve that is everywhere tangent to the flow



# Streamline

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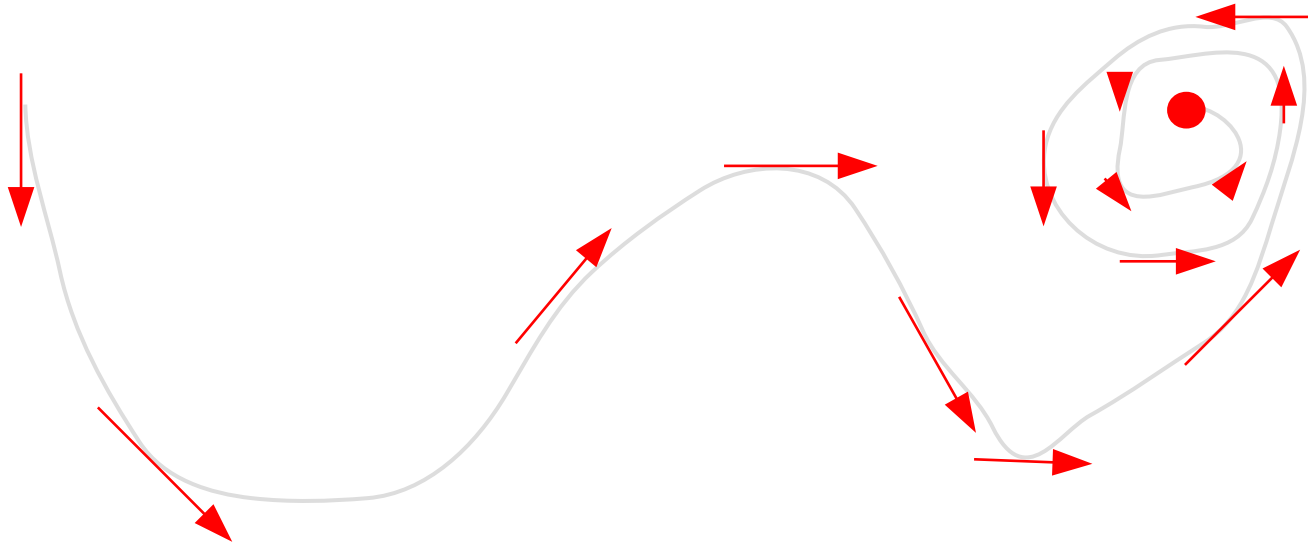
**Streamline:** a curve that is everywhere tangent to the flow



# Streamline

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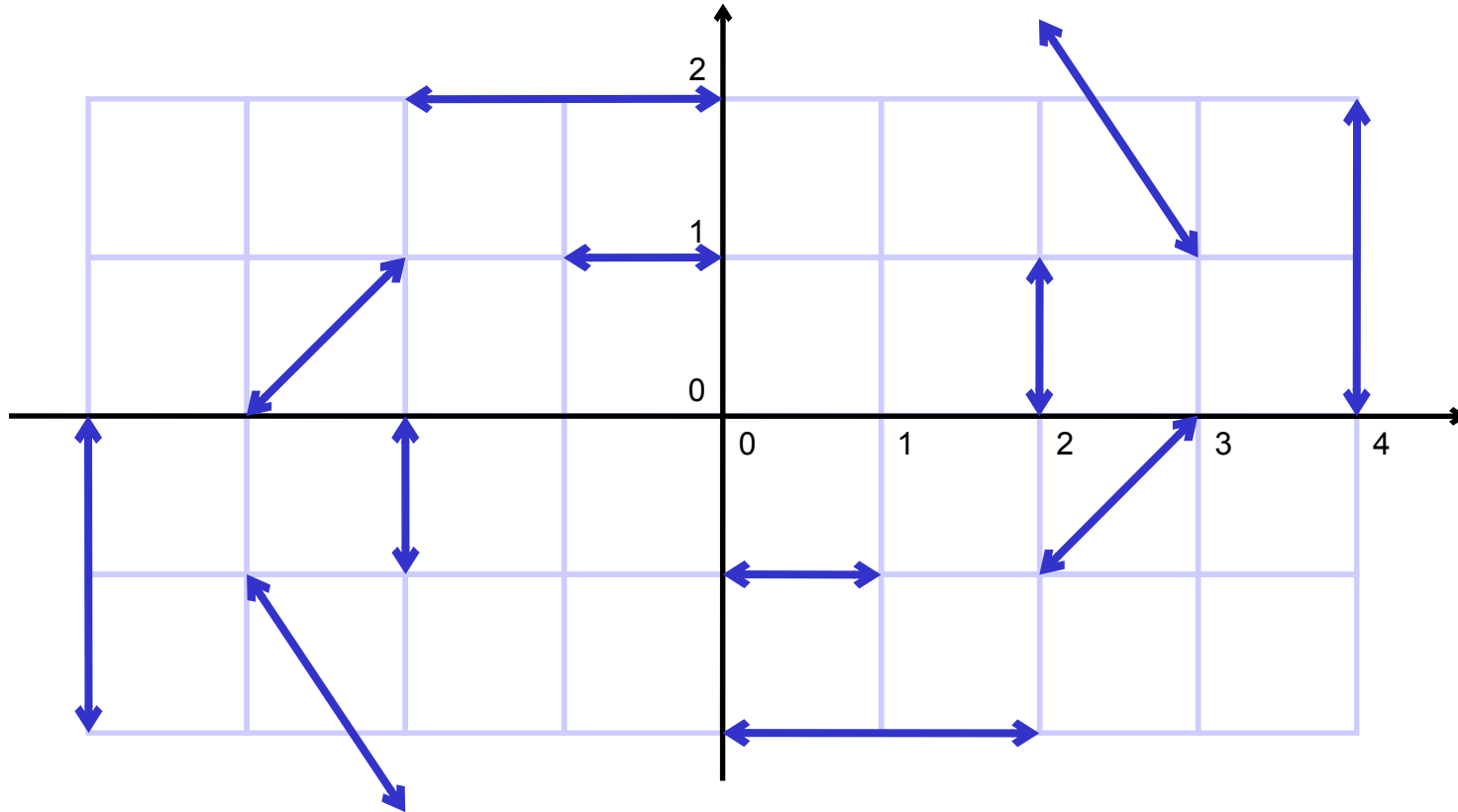
**Streamline:** a curve that is everywhere tangent to the flow



Streamline creation

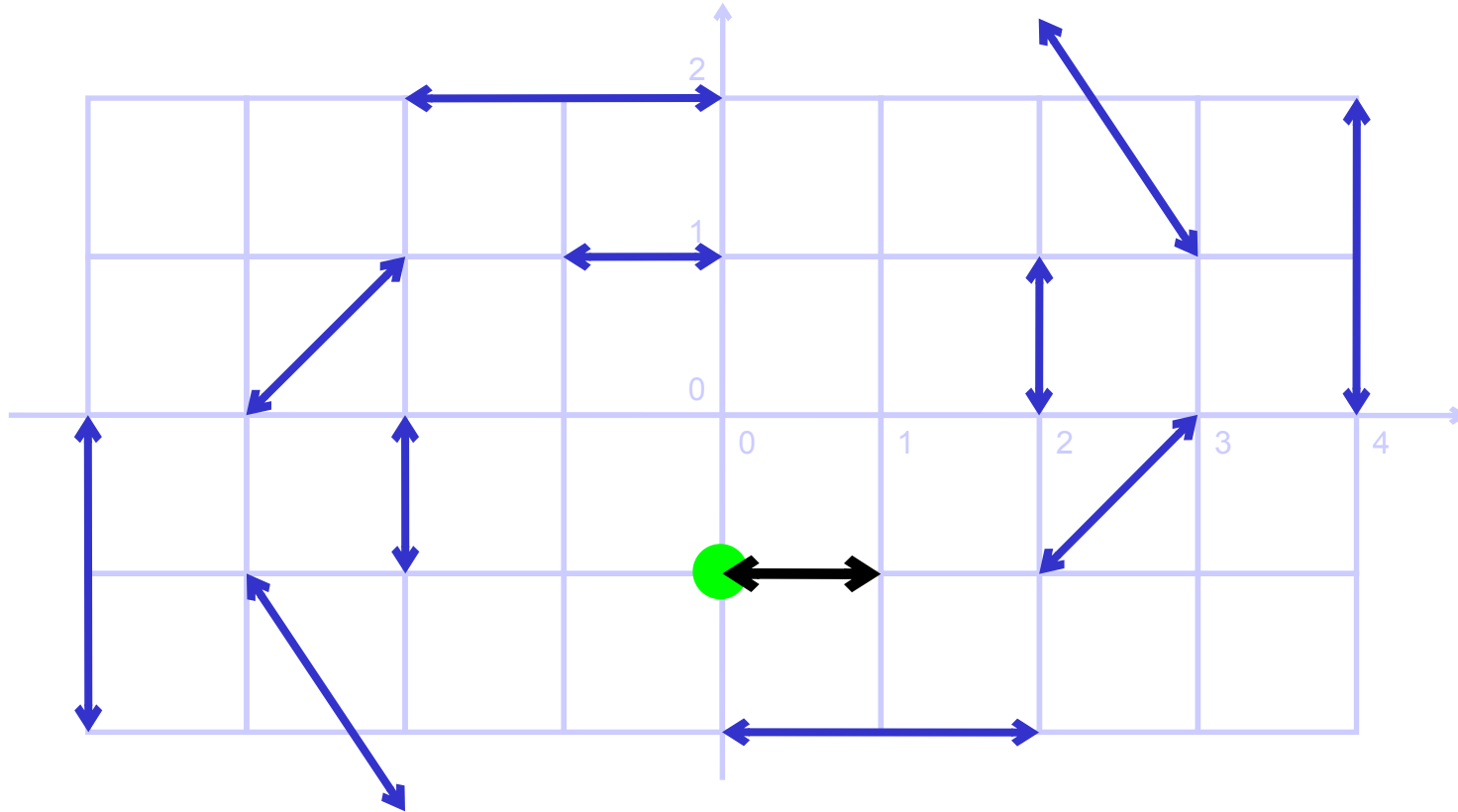
# Streamline creation

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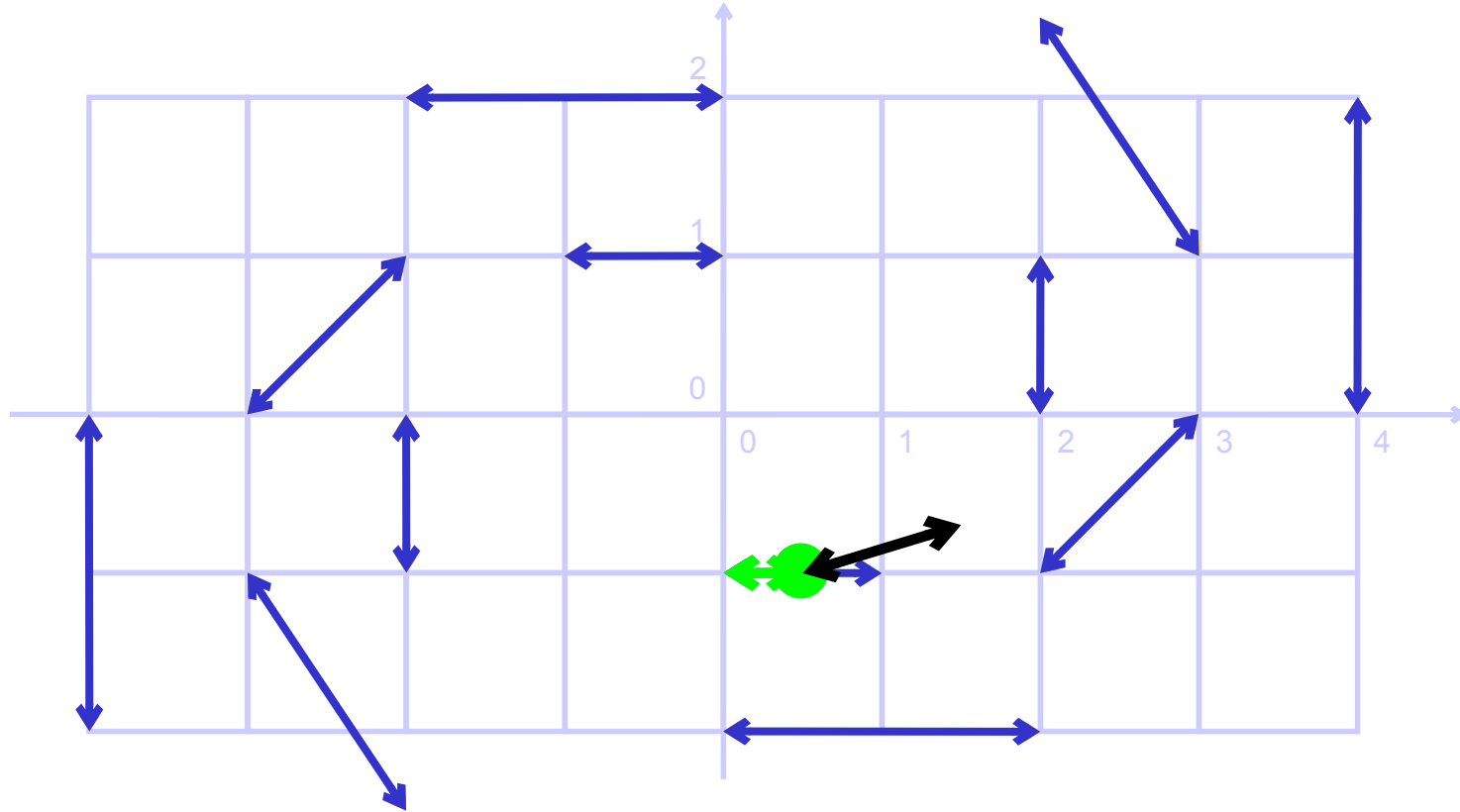
# Streamline creation

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# Streamline creation

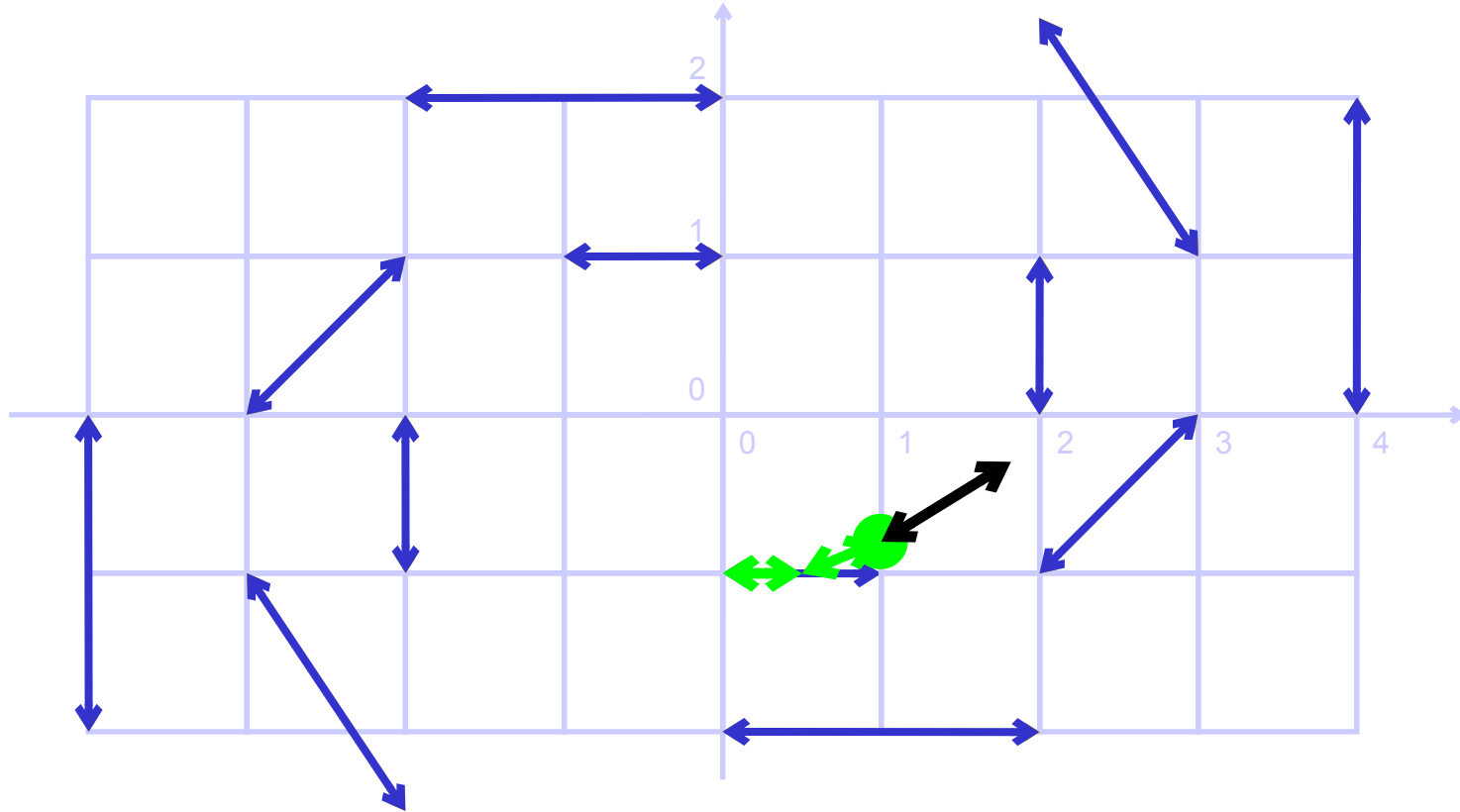
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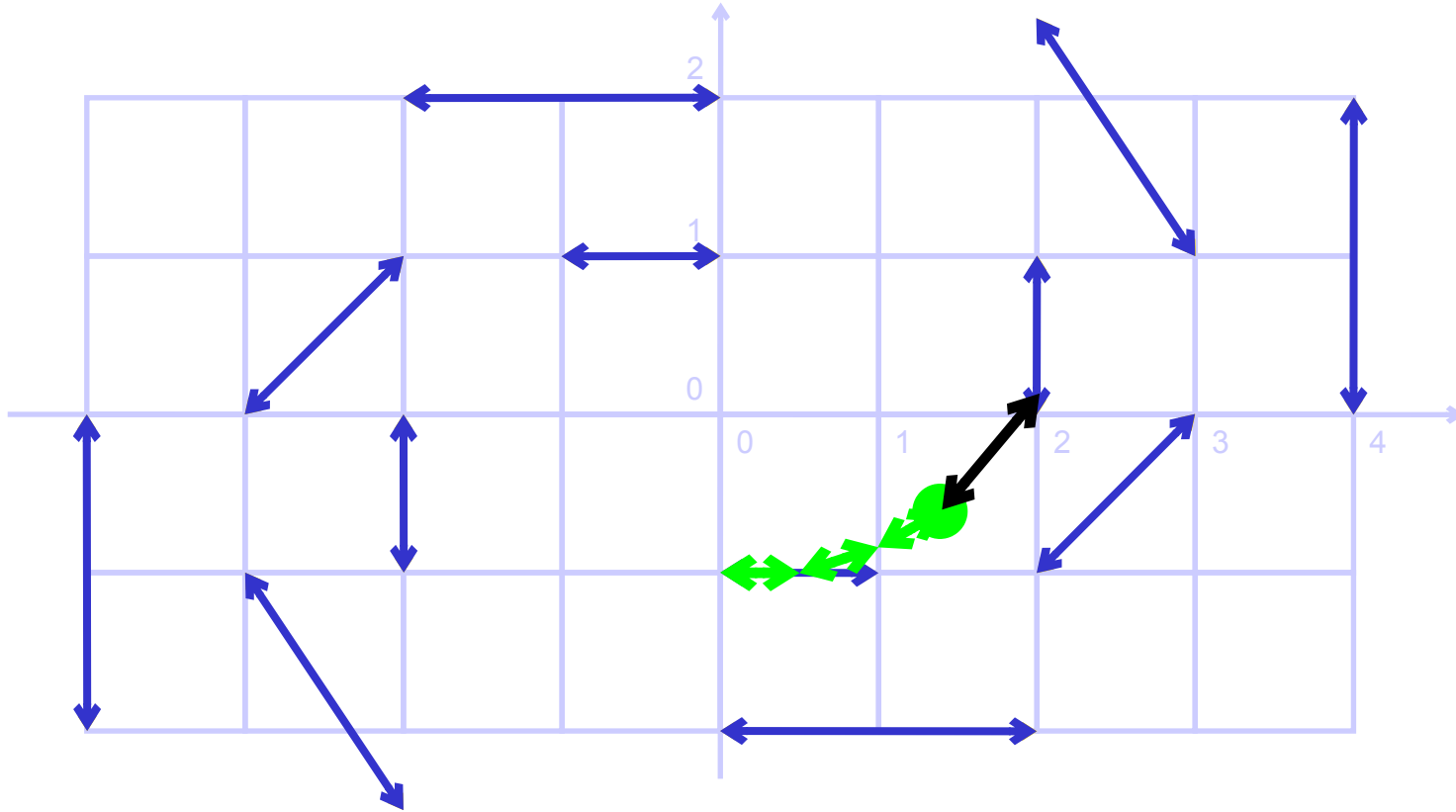
# Streamline creation

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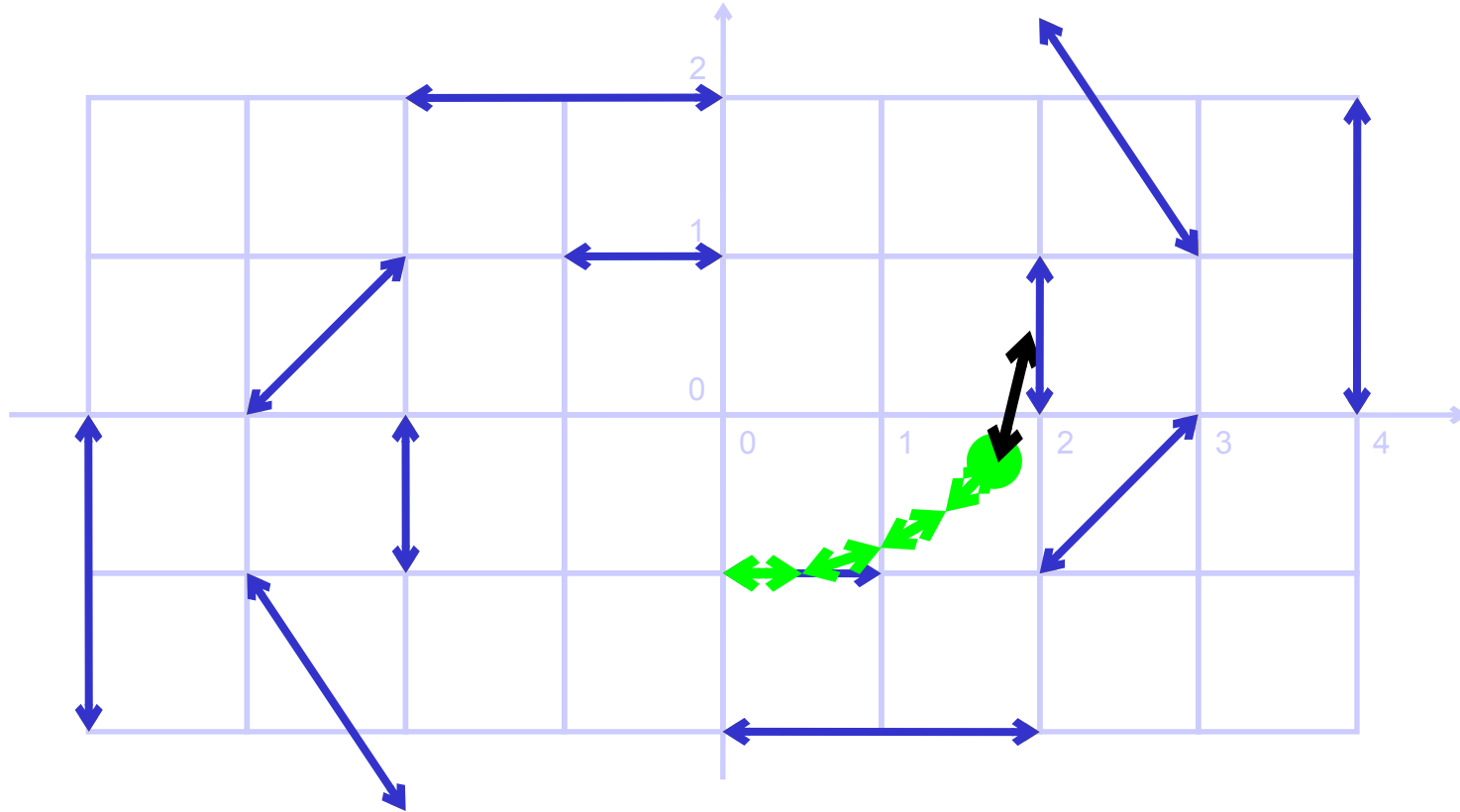
# Streamline creation

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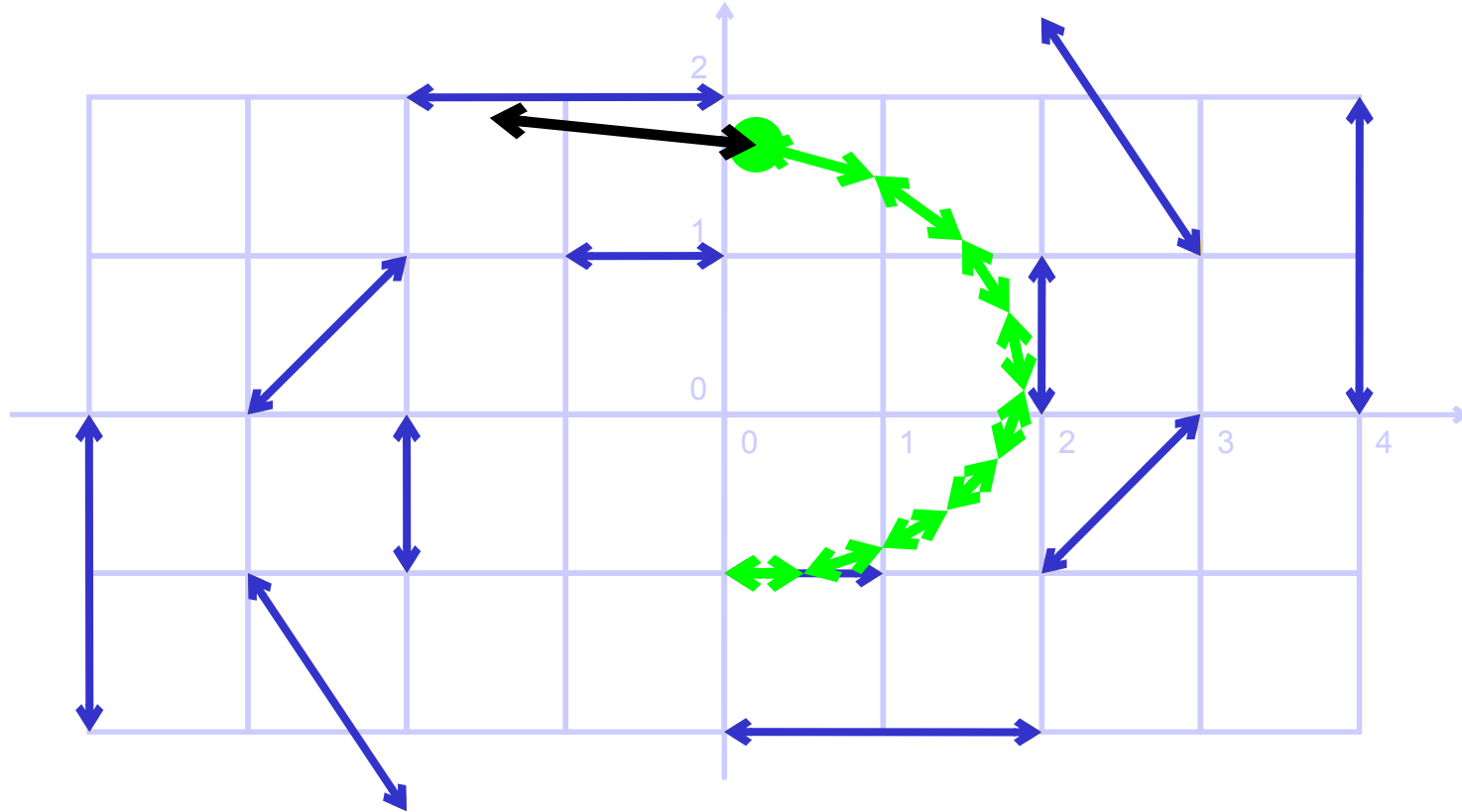
# Streamline creation

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# Streamline creation

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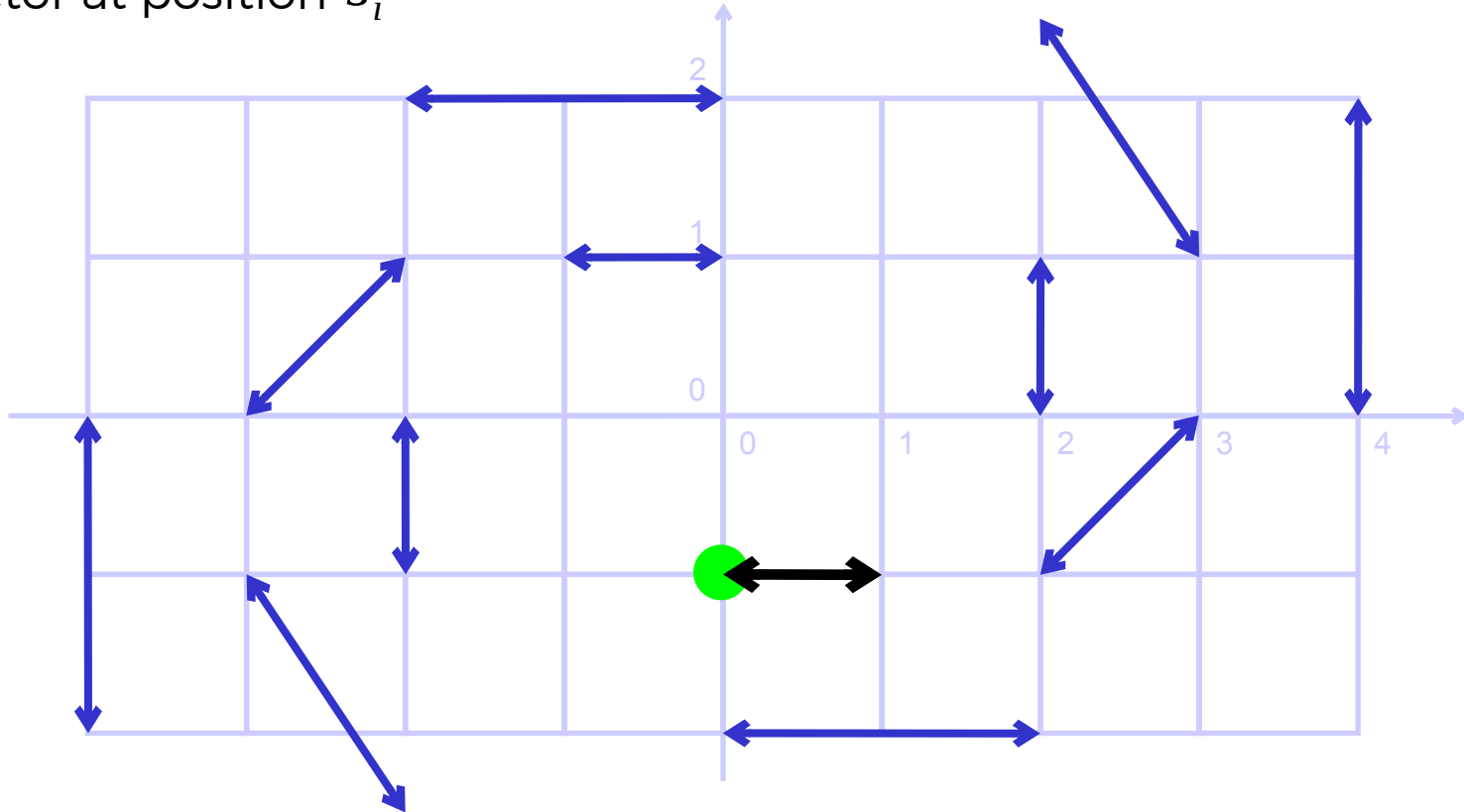


# Mathematics

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$S_i$  Position at time step  $i$

$v(S_i)$  Vector at position  $S_i$

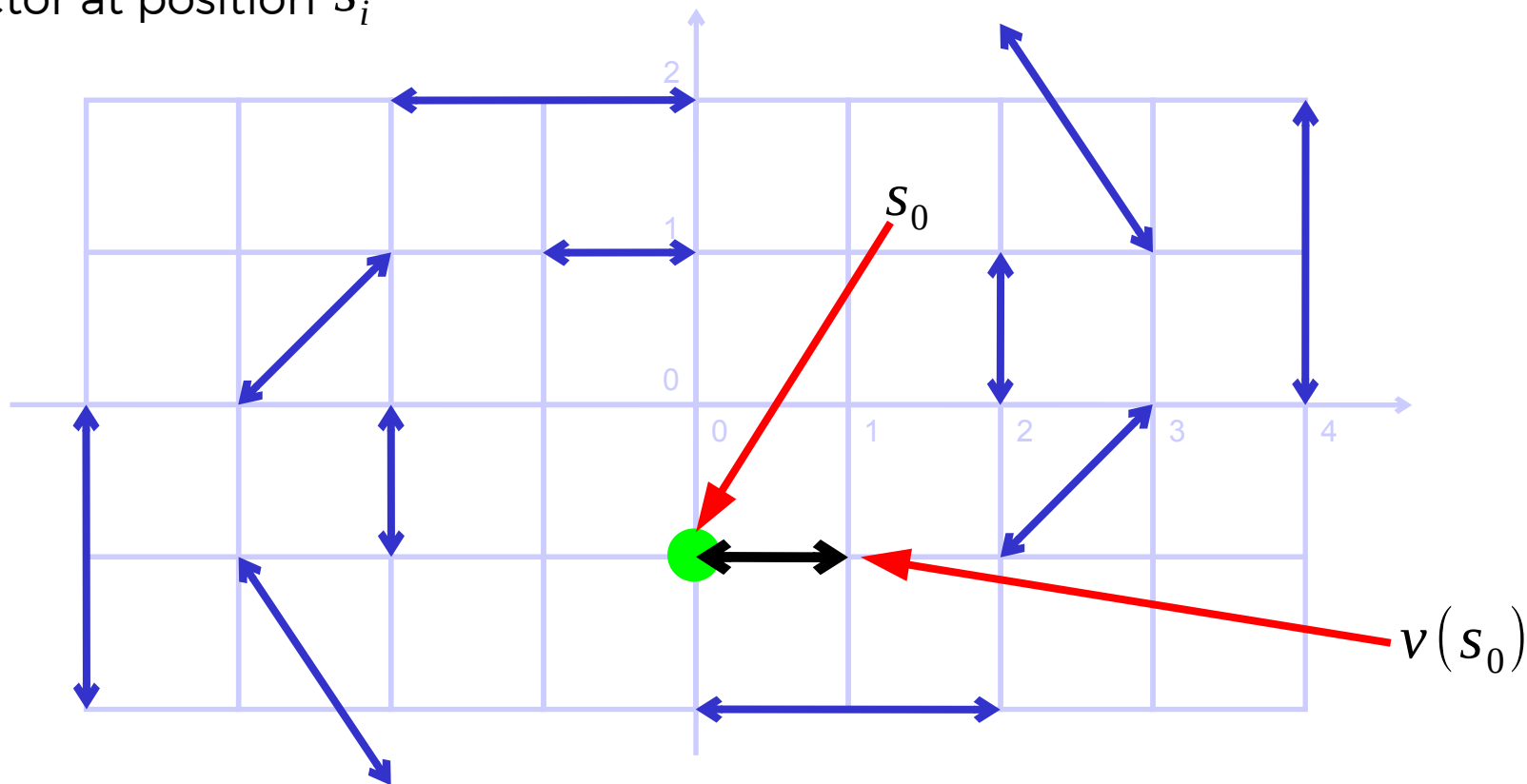


# Position at time 0

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$s_i$  Position at time step  $i$

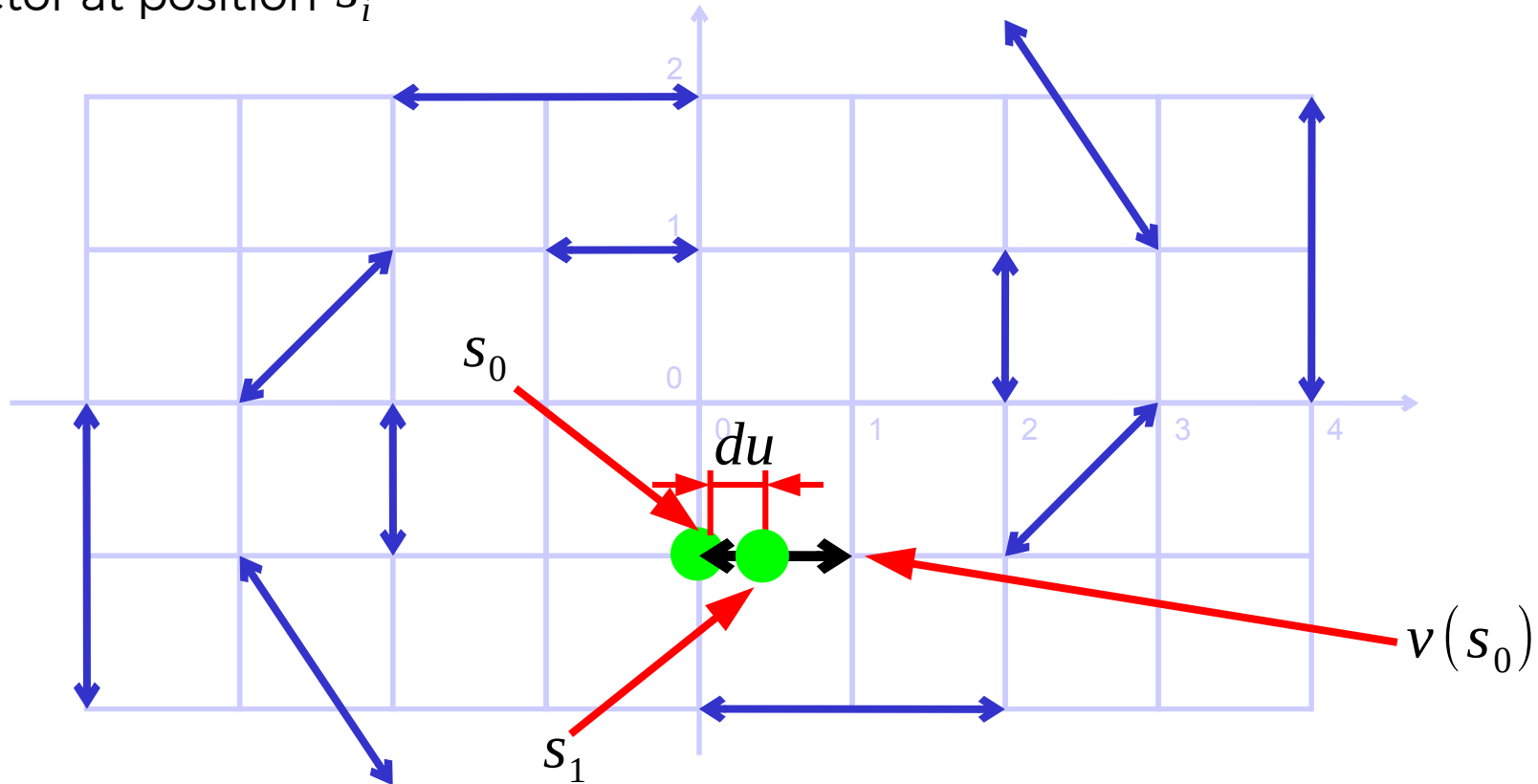
$v(s_i)$  Vector at position  $s_i$



# Position at time 1

$s_i$  Position at time step  $i$   
 $v(s_i)$  Vector at position  $s_i$

$$s_1 = s_0 + v(s_0) du$$



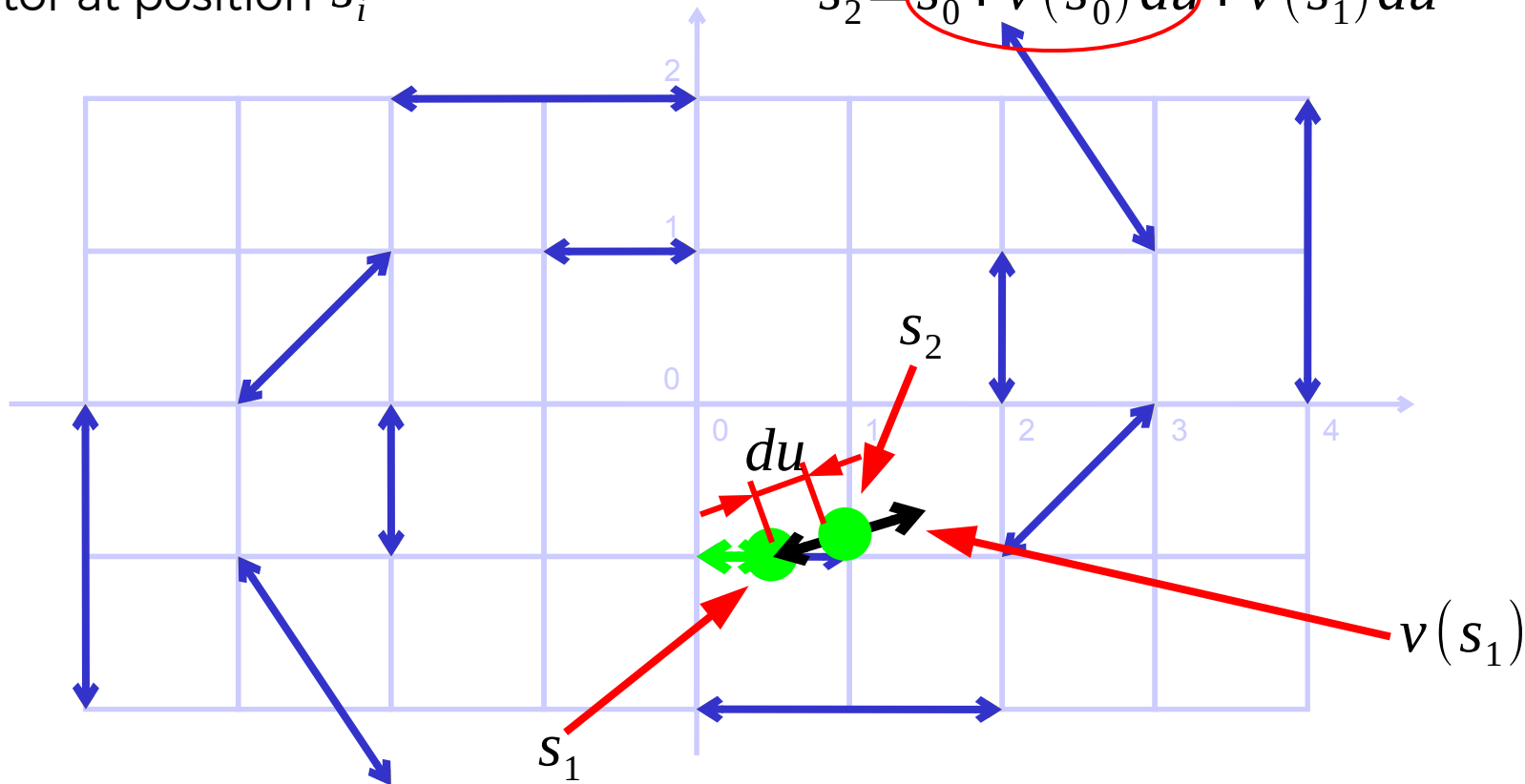
# Position at time 2

$s_i$  Position at time step  $i$

$v(s_i)$  Vector at position  $s_i$

$$s_2 = s_1 + v(s_1) du$$

$$s_2 = s_0 + v(s_0) du + v(s_1) du$$

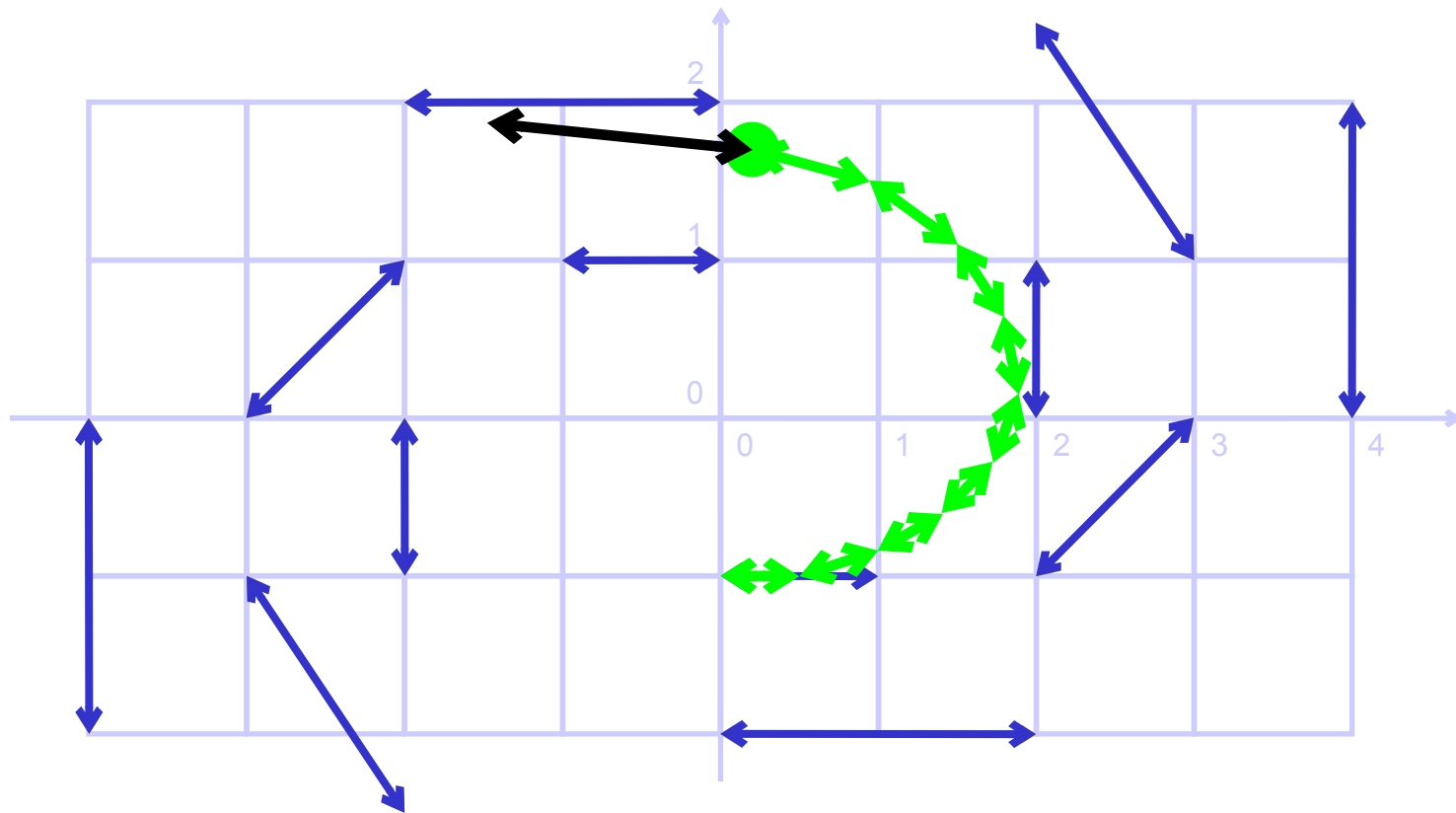




# Position at time $i$

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$$s_i = s_0 + v(s_0)du + v(s_1)du + \cdots + v(s_{i-1})du$$

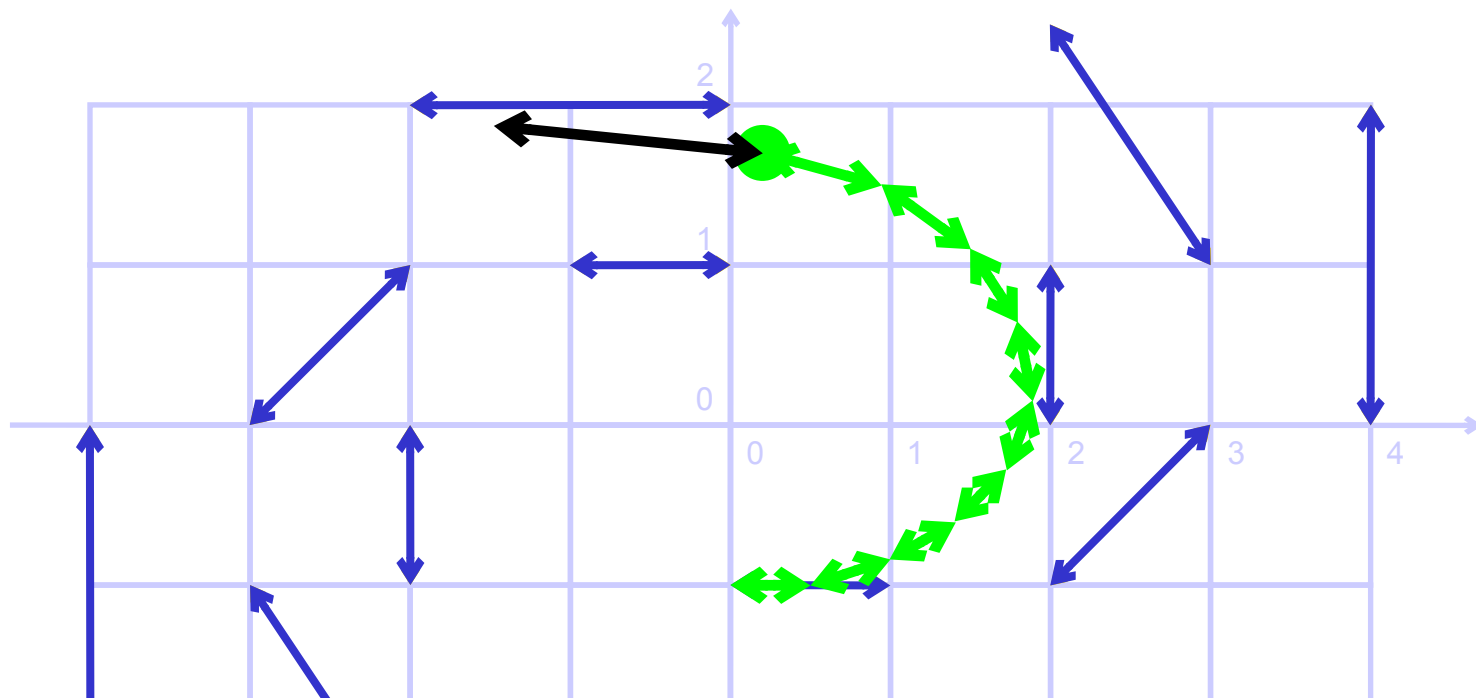


# Position at time $i$

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$$s_i = s_0 + v(s_0)du + v(s_1)du + \cdots + v(s_{i-1})du$$

$$s_i = s_0 + \sum_{u=0}^i v(s_u)du$$



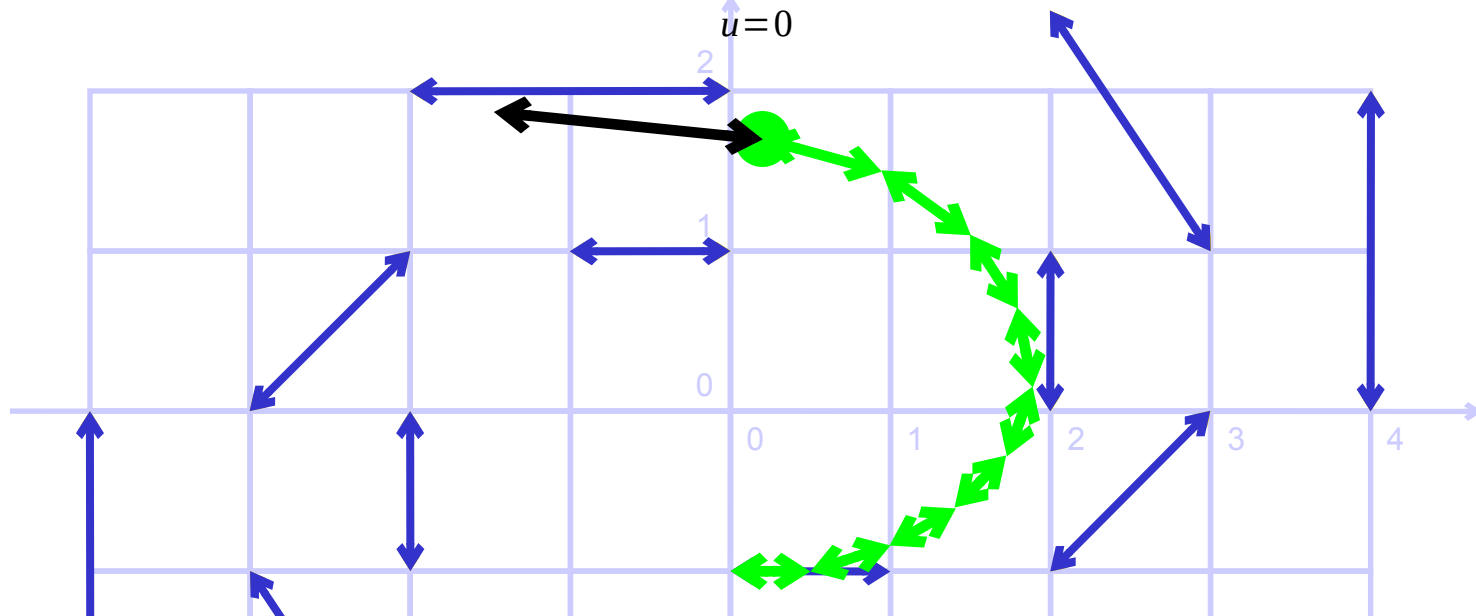
# How does this make a line?

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$$s_i = s_0 + \sum_{u=0}^i v(s_u) du$$

A line is just this at every  $i$  from 0 to  $T$  (the end)

$$f(T) = s_0 + \sum_{u=0}^T v(s_u) du$$




# Discrete to continuous

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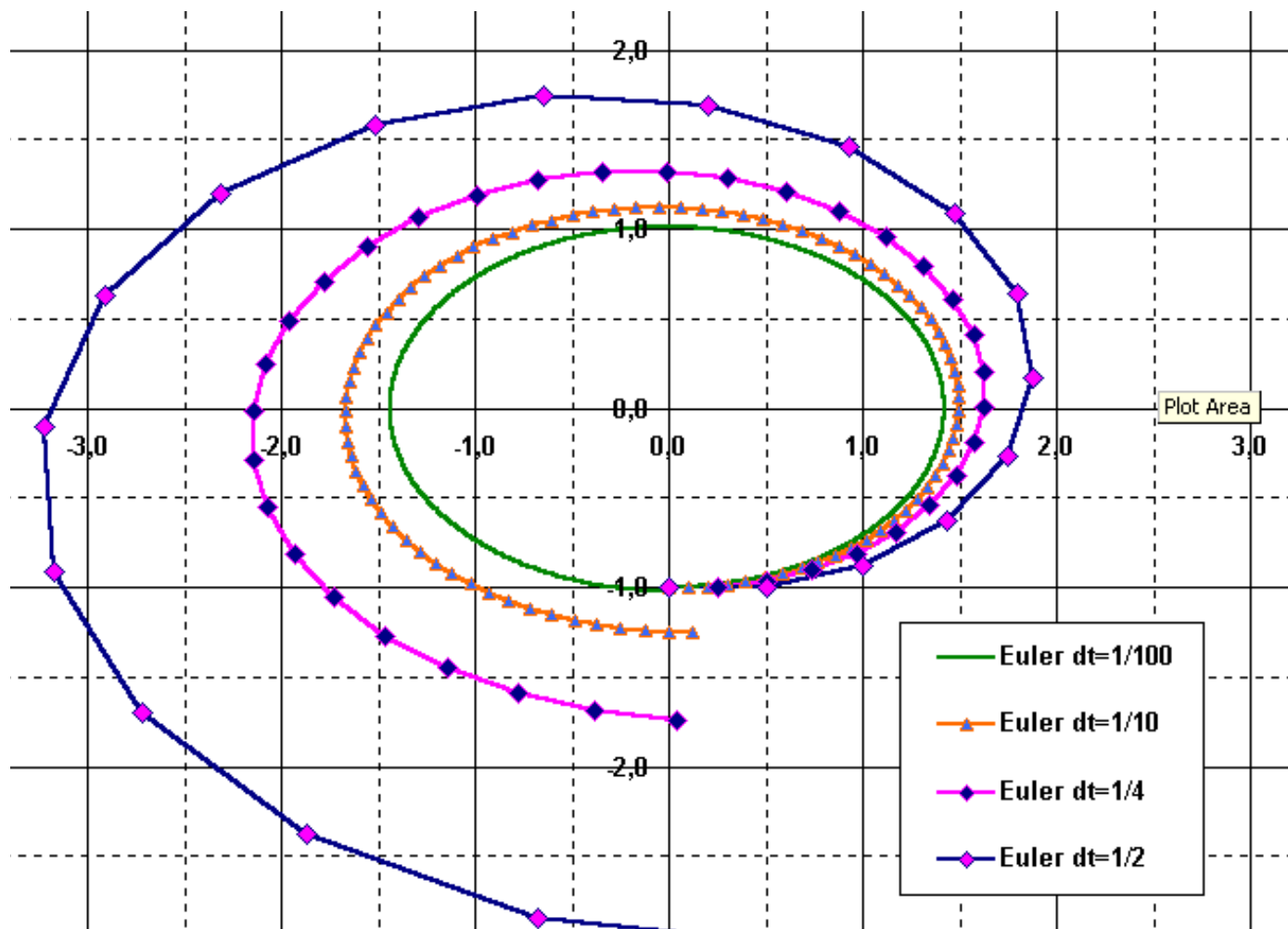
- Computers are discrete
- Continuous version is the correct version of the streamline
- Euler integration

Discrete:  $f(T) = s_0 + \sum_{u=0}^T v(s_u) du$  Fixed, small, number



Continuous:  $f(T) = s_0 + \int_{u=0}^T v(s_u) du$  Infinitesimally small

# Issues with Euler



# Integration methods

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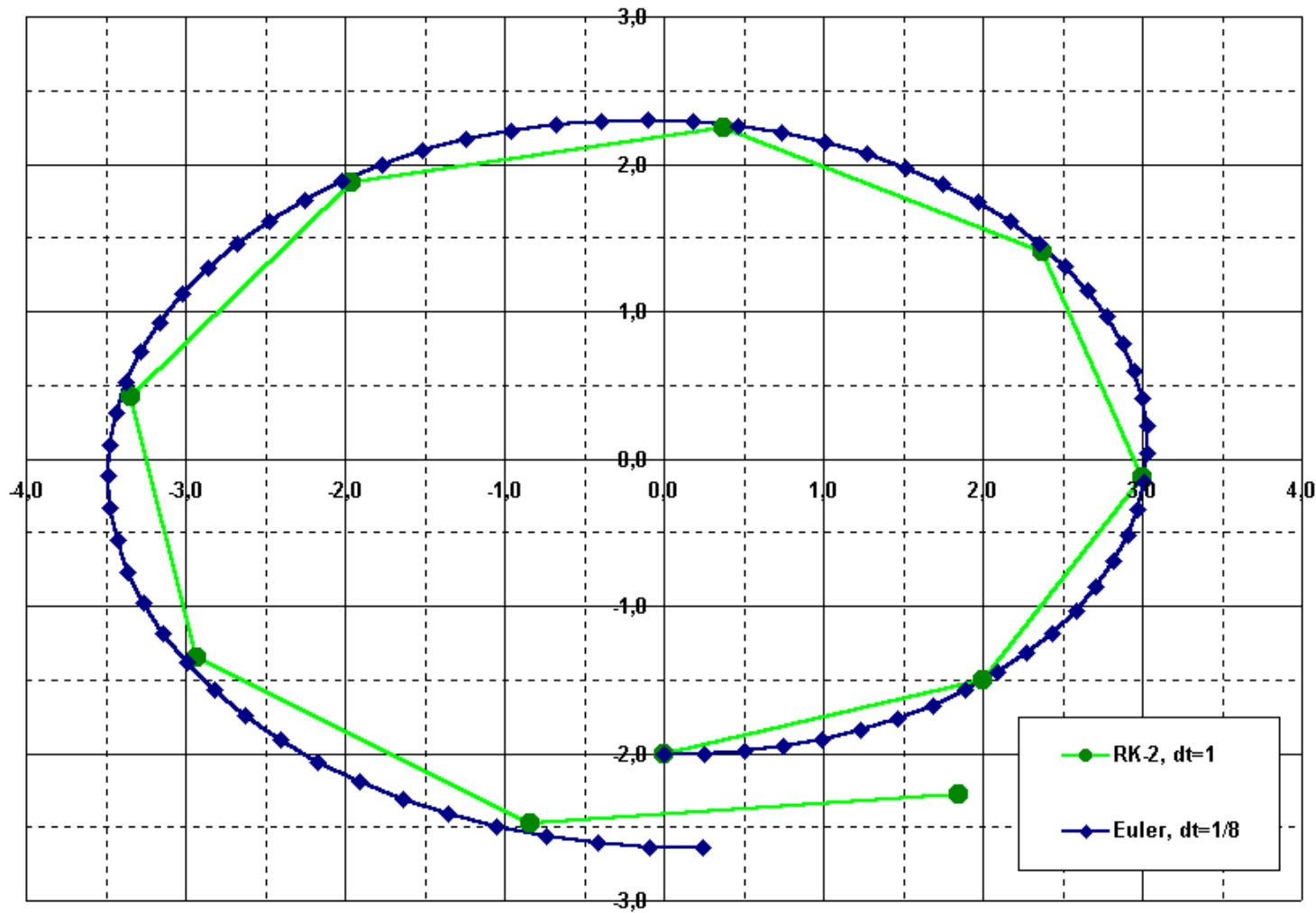
- Analytical
- Euler
- Runge-Kutte

# Runge-Kutte to the rescue!

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- Actually a family of methods
- Developed around 1900
- Idea is to cut the curve arc shorter
- RK-2 and RK-4 most popular

# Runge-Kutte to the rescue!



9 steps (RK-2)  
vs 72 (Euler)



# Runge-Kutte 2

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$$s_i = s_{i-1} + v \left( s_{i-1} + v(s_{i-1}) du / 2 \right) du$$

- 1) Do half an Euler step
- 2) Evaluate the flow vector there
- 3) Use it at the original point
- 4) Average the 2 vectors

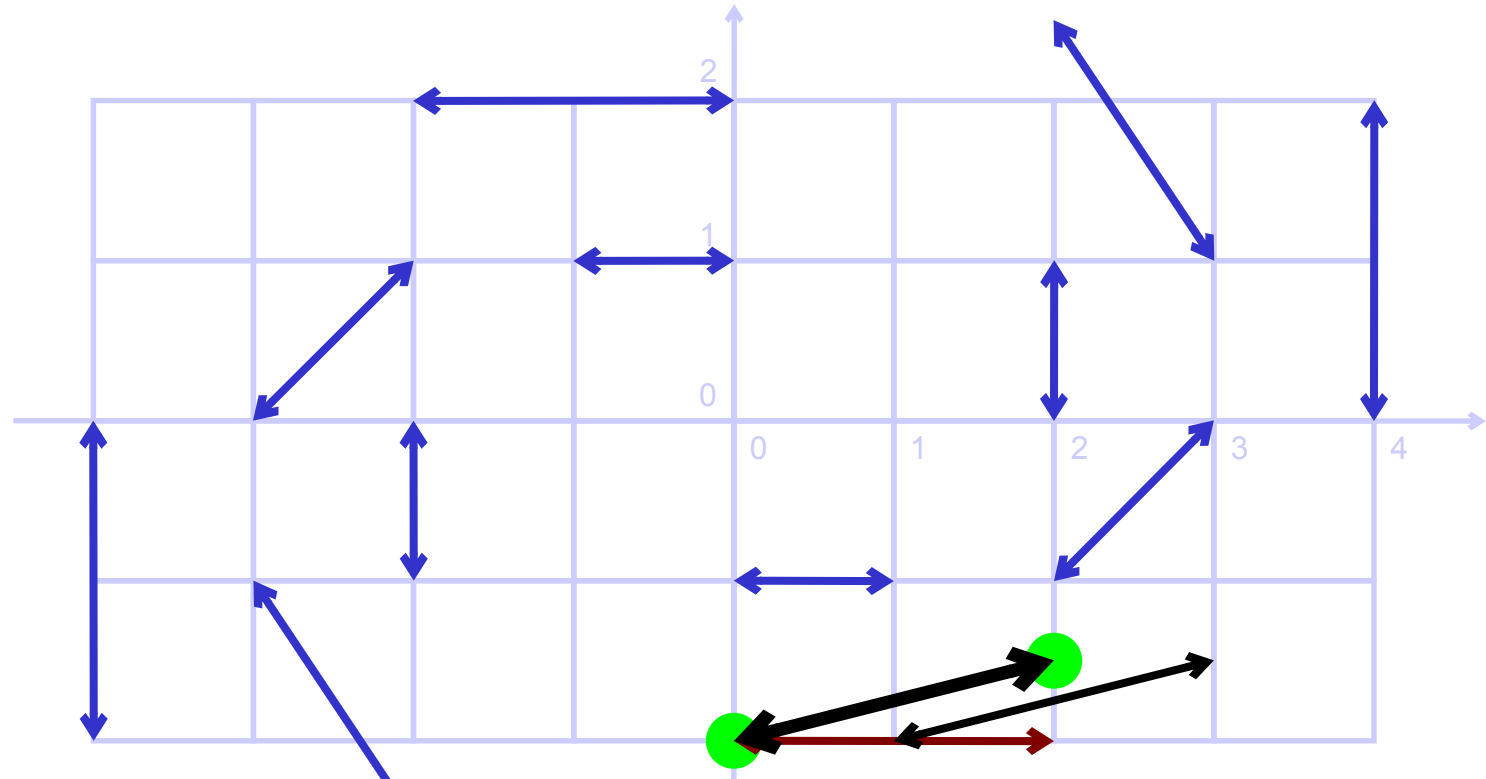
# Runge-Kutte 2

Seed point  $\mathbf{s}_0 = (0, -2)^\top$ ;

current flow vector  $\mathbf{v}(\mathbf{s}_0) = (2, 0)^\top$ ;

preview vector  $\mathbf{v}(\mathbf{s}_0 + \mathbf{v}(\mathbf{s}_0) \cdot du/2) = (2, 0.5)^\top$ ;

$du = 1$



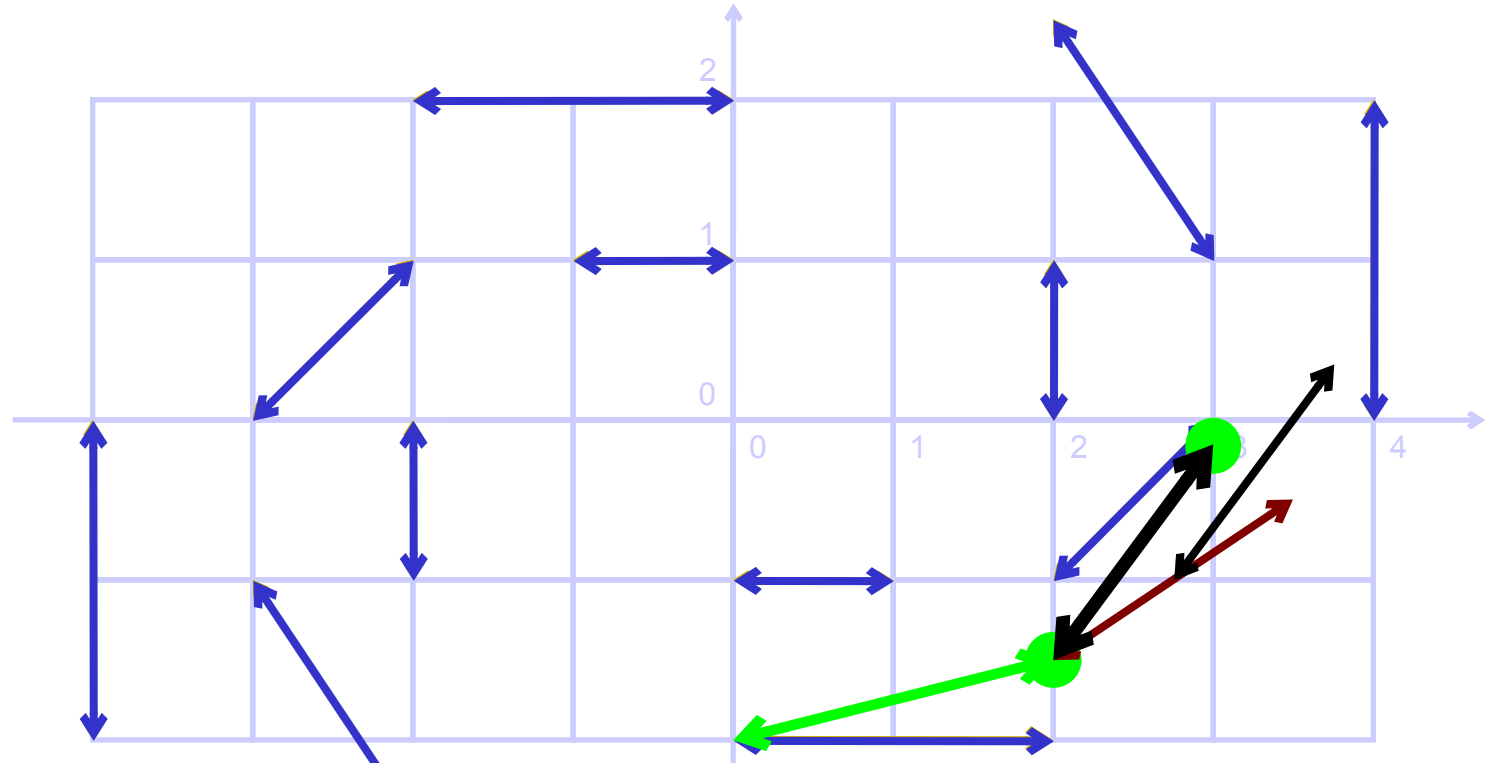
# Runge-Kutte 2

Seed point  $\mathbf{s}_1 = (2, -1.5)^\top$ ;

current flow vector  $\mathbf{v}(\mathbf{s}_1) = (1.5, 1)^\top$ ;

preview vector  $\mathbf{v}(\mathbf{s}_1 + \mathbf{v}(\mathbf{s}_1) \cdot du/2) = (1, 1.4)^\top$ ;

$du = 1$



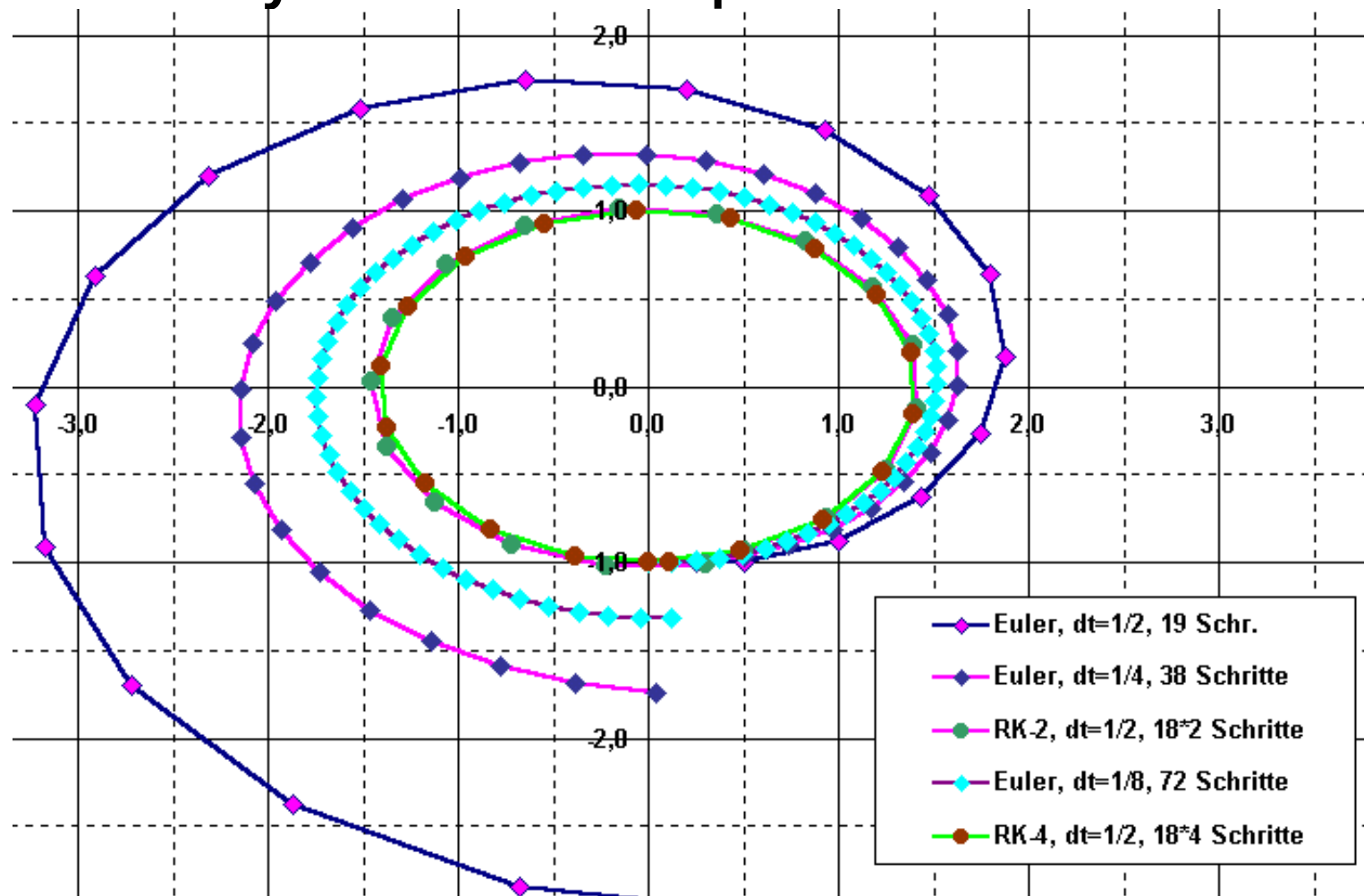
# Runge-Kutte 4

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Even better: fourth order RK:

- four vectors **a**, **b**, **c**, **d**
- one step is a convex combination:  
$$\mathbf{s}_{i+1} = \mathbf{s}_i + (\mathbf{a} + 2 \cdot \mathbf{b} + 2 \cdot \mathbf{c} + \mathbf{d})/6$$
- vectors:
  - $\mathbf{a} = d\mathbf{u} \cdot \mathbf{v}(\mathbf{s}_i)$  ... original vector
  - $\mathbf{b} = d\mathbf{u} \cdot \mathbf{v}(\mathbf{s}_i + \mathbf{a}/2)$  ... RK-2 vector
  - $\mathbf{c} = d\mathbf{u} \cdot \mathbf{v}(\mathbf{s}_i + \mathbf{b}/2)$  ... use RK-2 ...
  - $\mathbf{d} = d\mathbf{u} \cdot \mathbf{v}(\mathbf{s}_i + \mathbf{c})$  ... and again

# RK-4 only for complex flows



# Unsteady flow visualization

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- **Streamline:** a curve that is everywhere tangent to the flow (release 1 massless particle)
- **Pathline:** a curve that is everywhere tangent to an unsteady flow field (release 1 massless particle)
- **Streakline:** a curve traced by the continues release of particles in unsteady flow from the same position in space (release infinitely many massless particles)

$$f(T) = s_0 + \int_{u=0}^T v(s_u, t=\tau) du$$

$$f(T) = s_0 + \int_{u=0}^T v(s_u, t=u) du$$

- 1) Pick an  $s_0$
- 2) Find all pathlines that pass through that point
- 3) Get the end points of each of these lines at time  $T$
- 4) Connect all the points from step 3

# Conclusion

# Summary

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- analytic determination of streamlines usually not possible
- Euler: simple, imprecise, esp. with small  $\Delta t$
- RK: more accurate in higher orders
- Other lines are integrations over time/space



# Acknowledgements

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- Robert S. Laramée
- Torsten Möller
- Bruno Jobard
- Malte Zöckler
- Georg Fischel
- Frits H. Post
- Roger Crawfis
- Helwig Hauser