111. Minimum Depth of Binary Tree

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Given a binary tree, find its minimum depth.

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The minimum depth is the number of nodes along the shortest path from the root node down to the nearest leaf node.

Note: A leaf is a node with no children.

Given binary tree [3,9,20,null,null,15,7],

```
3
11
9 20
 / /
15 7
```

return its minimum depth = 2.

Tree definition

Solution

First of all, here is the definition of the TreeNode which we would use.

Java Python

```
Copy
1 // Definition for a binary tree node.
2 public class TreeNode {
3 int val;
     TreeNode left;
     TreeNode right;
     TreeNode(int x) {
       val = x;
9
10 }
```

The intuitive approach is to solve the problem by recursion. Here we demonstrate an example with the DFS

Approach 1: Recursion

(Depth First Search) strategy.

Algorithm

Сору Java Python 1 class Solution {

```
public int minDepth(TreeNode root) {
         if (root == null) {
           return 0;
         if ((root.left == null) && (root.right == null)) {
          return 1;
  10
 11
         int min_depth = Integer.MAX_VALUE;
  12
         if (root.left != null) {
  13
          min_depth = Math.min(minDepth(root.left), min_depth);
  14
         if (root.right != null) {
  15
  16
          min_depth = Math.min(minDepth(root.right), min_depth);
  17
 18
 19
         return min_depth + 1;
 20
 21 }
Complexity analysis
```

Space complexity: in the worst case, the tree is completely unbalanced, e.g. each node has only one

number of nodes.

reach the leaf node.

child node, the recursion call would occur N times (the height of the tree), therefore the storage to keep the call stack would be $\mathcal{O}(N)$. But in the best case (the tree is completely balanced), the height of the tree would be $\log(N)$. Therefore, the space complexity in this case would be $\mathcal{O}(\log(N))$.

• Time complexity : we visit each node exactly once, thus the time complexity is $\mathcal{O}(N)$, where N is the

Approach 2: DFS Iteration We could also convert the above recursion into iteration, with the help of stack.

The idea is to visit each leaf with the DFS strategy, while updating the minimum depth when we

So we start from a stack which contains the root node and the corresponding depth which is 1. Then we proceed to the iterations: pop the current node out of the stack and push the child nodes. The minimum

depth is updated at each leaf node. Copy Copy Java Python 1 class Solution {

```
public int minDepth(TreeNode root) {
        LinkedList<Pair<TreeNode, Integer>> stack = new LinkedList<>();
         if (root == null) {
           return 0;
  8
          stack.add(new Pair(root, 1));
 10
  11
         int min_depth = Integer.MAX_VALUE;
        while (!stack.isEmpty()) {
 12
  13
          Pair<TreeNode, Integer> current = stack.pollLast();
          root = current.getKey();
 14
  15
          int current_depth = current.getValue();
  16
          if ((root.left == null) && (root.right == null)) {
            min_depth = Math.min(min_depth, current_depth);
  17
 18
          if (root.left != null) {
  19
            stack.add(new Pair(root.left, current_depth + 1));
  20
  21
 22
           if (root.right != null) {
             stack.add(new Pair(root.right, current_depth + 1));
  23
  24
  25
  26
         return min_depth;
 27
Complexity analysis
  • Time complexity : each node is visited exactly once and time complexity is \mathcal{O}(N).
```

complexity.

Java Python

1 class Solution {

else {

public int minDepth(TreeNode root) {

if (root == null) { return 0;

LinkedList<Pair<TreeNode, Integer>> stack = new LinkedList<>();

Approach 3: BFS Iteration

depth would be found. Therefore, this results in a $\mathcal{O}(N)$ complexity. One way to optimize the complexity is to use the BFS strategy. We iterate the tree level by level, and the first leaf we reach corresponds to the minimum depth. As a result, we do not need to iterate all nodes.

The drawback of the DFS approach in this case is that all nodes should be visited to ensure that the minimum

Сору

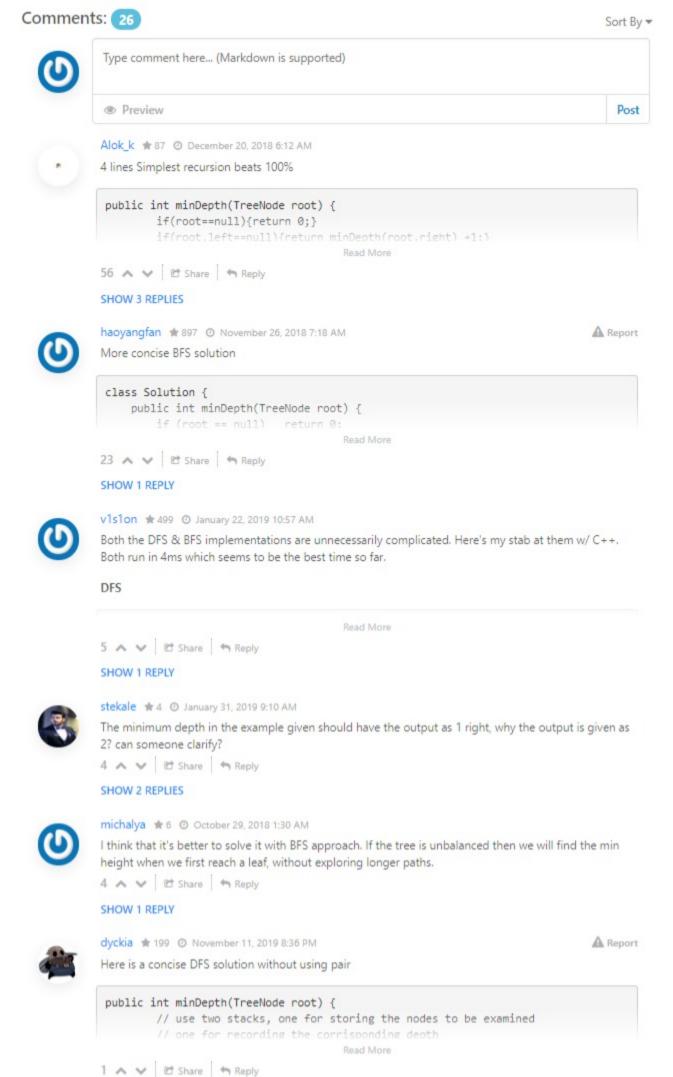
Next

ullet Space complexity : in the worst case we could keep up to the entire tree, that results in $\mathcal{O}(N)$ space

```
stack.add(new Pair(root, 1));
  10
         int current_depth = 0;
  11
         while (!stack.isEmpty()) {
 12
  13
           Pair<TreeNode, Integer> current = stack.poll();
  14
           root = current.getKey();
  15
           current_depth = current.getValue();
           if ((root.left == null) && (root.right == null)) {
  16
  17
  18
  19
           if (root.left != null) {
             stack.add(new Pair(root.left, current_depth + 1));
 20
  21
  22
           if (root.right != null) {
  23
             stack.add(new Pair(root.right, current_depth + 1));
 24
  25
  26
         return current_depth;
 27
Complexity analysis
   . Time complexity: in the worst case for a balanced tree we need to visit all nodes level by level up to the
     tree height, that excludes the bottom level only. This way we visit N/2 nodes, and thus the time
     complexity is \mathcal{O}(N).
   • Space complexity : is the same as time complexity here \mathcal{O}(N).
```

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I think in the worst case of the BFS method, we have a tree like this:

BFS uses queue, right? How is stack solving the problem of BFS here?

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Why so complicated? Why not extend maxDepth to handle the edge cases here?