January 23, 2024

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[]: %pylab inline
     import torch
     from torch.nn.parameter import Parameter
[]: x = torch.rand([1000,2])
     x_{in}_{circle} = ((x**2).sum(1) < 1)
     def accuracy(pred_label):
         return (pred_label==x_in_circle).float().mean()
     def show(pred_label):
         scatter(*x.numpy().T, c=pred_label.numpy())
         axis('equal')
     def loss(prediction):
         return -(x_in_circle.float() * (prediction+1e-10).log() +
                  (1-x_in_circle.float()) * (1-prediction+1e-10).log() ).mean()
     class Linear(torch.nn.Module):
         def __init__(self, input_dim):
             super().__init__()
             self.w = Parameter(torch.zeros(input_dim))
             self.b = Parameter(-torch.zeros(1))
         def forward(self, x):
             return (x * self.w[None,:]).sum(dim=1) + self.b
     class LinearClassifier(torch.nn.Module):
         def __init__(self, input_dim):
             super().__init__()
             self.linear = Linear(input_dim)
         def forward(self, x):
             logit = self.linear(x)
             return 1/(1+(-logit).exp())
     show(x_in_circle)
```

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[]: import torch.utils.tensorboard as tb
     %load_ext tensorboard
     import tempfile
     log_dir = tempfile.mkdtemp()
     %tensorboard --logdir {log_dir} --reload_interval 1
[]: logger = tb.SummaryWriter(log_dir+'/linear1')
     classifier = LinearClassifier(2)
     for iteration in range(10000):
        p_y = classifier(x)
         pred_y = p_y > 0.5
         1 = loss(p_y)
         logger.add_scalar("loss", 1, global_step=iteration)
         logger.add_scalar("accuracy", accuracy(pred_y), global_step=iteration)
         if iteration % 100 == 0:
             fig = figure()
             show(pred_y)
             logger.add_figure('pred_y', fig, global_step=iteration)
             del fig
         1.backward()
         for p in classifier.parameters():
             p.data[:] -= 0.5 * p.grad
             p.grad.zero_()
     show(pred_y)
[]: class NonLinearClassifier(torch.nn.Module):
         def __init__(self, input_dim):
             super().__init__()
             self.linear1 = torch.nn.Linear(input_dim, 100)
             torch.nn.init.normal_(self.linear1.weight, std=0.01)
             torch.nn.init.normal_(self.linear1.bias, std=0.01)
             self.linear2 = Linear(100)
         def forward(self, x):
             logit = self.linear2( torch.relu(self.linear1(x)) )
             return 1/(1+(-logit).exp())
     classifier = NonLinearClassifier(2)
     show(classifier(x).detach() > 0.5)
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[]: logger = tb.SummaryWriter(log_dir+'/nonlinear1')
     classifier = NonLinearClassifier(2)
     for iteration in range(10000):
        p_y = classifier(x)
         pred_y = p_y > 0.5
         1 = loss(p_y)
         logger.add_scalar("loss", 1, global_step=iteration)
         logger.add_scalar("accuracy", accuracy(pred_y), global_step=iteration)
         if iteration % 100 == 0:
             fig = figure()
             show(pred_y)
             logger.add_figure('pred_y', fig, global_step=iteration)
             del fig
         1.backward()
        for p in classifier.parameters():
             p.data[:] -= 0.5 * p.grad
             p.grad.zero_()
     show(pred_y)
```

[]: