

Package ‘JSODPsplines’

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Title Resubstitution Method for Derivative Estimation Using P-Splines

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Description Tools for estimating derivatives of functions using P-splines.

The main feature is the 'resub' method, a novel approach developed to improve derivative estimation. The package also includes methods for penalized spline estimation, oracle estimation, and optimization of smoothing parameters using generalized cross-validation (GCV) and Mean Integrated Squared Error (MISE).

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VignetteBuilder knitr

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| | |
|-------|--------------------------------|
| Bbase | <i>B-spline Basis Function</i> |
|-------|--------------------------------|

Description

Creates a B-spline basis for a given set of values.

Usage

```
Bbase(x, xl = min(x), xr = max(x), nseg = 10, bdeg = 3)
```

Arguments

| | |
|------|---------------------------|
| x | Numeric vector of values. |
| xl | Left boundary. |
| xr | Right boundary. |
| nseg | Number of segments. |
| bdeg | Degree of the B-spline. |

Value

A list containing:

| | |
|-------|-------------------------------------|
| x | Numeric vector of input values. |
| xl | Left boundary. |
| xr | Right boundary. |
| nseg | Number of segments. |
| bdeg | Degree of the B-spline. |
| B | Matrix of B-spline basis functions. |
| knots | Vector of knot values. |

Examples

```
# Example for Bbase
x <- seq(0, 1, length.out = 100)
result <- Bbase(x, nseg = 10, bdeg = 3)
matplot(x, result$B, type = "l", lty = 1, main = "B-spline Basis")
```

| | |
|------------|---------------------------------|
| bbase.grid | <i>B-spline Basis on a Grid</i> |
|------------|---------------------------------|

Description

Creates a B-spline basis on a grid.

Usage

```
bbase.grid(x, dx, knots, bdeg)
```

Arguments

| | |
|-------|---------------------------|
| x | Numeric vector of values. |
| dx | Grid spacing. |
| knots | Knot values. |
| bdeg | Degree of the B-spline. |

Value

A matrix representing the B-spline basis on the grid.

Examples

```
# Example for bbase.grid
x <- seq(0, 1, length.out = 100)
dx <- 0.1
knots <- seq(0, 1, length.out = 10)
deg <- 3
result <- bbase.grid(x, dx, knots, deg)
matplot(x, result, type = "l", lty = 1, main = "B-spline Basis on a Grid")
```

| | |
|-----------|---|
| gcvlambda | <i>Generalized Cross-Validation Criterion</i> |
|-----------|---|

Description

Computes the GCV criterion for a given smoothing parameter lambda.

Usage

```
gcvlambda(lambda = 0, x, y, nseg = 35, pord = 3, bdeg = 4)
```

Arguments

| | |
|--------|-----------------------------|
| lambda | Smoothing parameter. |
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |

Value

The GCV criterion value.

Examples

```
# Example for gcvlambda
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
lambda <- 0.1
result <- gcvlambda(lambda, x, y, nseg = 10, pord = 2, bdeg = 3)
print(result)
```

| | |
|-------------------|---------------------------------|
| mise.lambda.optim | <i>MISE Lambda Optimization</i> |
|-------------------|---------------------------------|

Description

Optimizes the Mean Integrated Squared Error (MISE) for a given lambda.

Usage

```
mise.lambda.optim(
  lambda = 0.1,
  x,
  y,
  r = 1,
  sig = 0.1,
  nseg = 35,
  pord = 2,
  bdeg = 35,
  f,
  fr = NULL
)
```

Arguments

| | |
|--------|------------------------------------|
| lambda | Smoothing parameter. |
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| r | Order of the derivative. |
| sig | Standard deviation of the noise. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |
| f | True function values. |
| fr | True derivative values (optional). |

Value

A list containing:

| | |
|----------------------|-------------------------------------|
| <code>mise</code> | Optimized MISE value. |
| <code>var</code> | Variance component of the MISE. |
| <code>sq.bias</code> | Squared bias component of the MISE. |
| <code>H</code> | Matrix of fitted values. |

Examples

```
# Example for mise.lambda.optim
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
lambda <- 0.1
sig <- 0.1
f <- sin(2 * pi * x)
result <- mise.lambda.optim(lambda, x, y, r = 1, sig = sig, nseg = 10, pord = 2, bdeg = 3, f = f)
print(result)
```

| | |
|----------------------------|---|
| <code>naive.est.opt</code> | <i>Naive Estimation of Derivative (Optimized)</i> |
|----------------------------|---|

Description

Estimates the mean and derivative function using optimization to find the optimal smoothing parameter.

Usage

```
naive.est.opt(x, y, r, nseg = 35, bdeg = 4, pord = 2, x.grid)
```

Arguments

| | |
|---------------------|----------------------------------|
| <code>x</code> | Numeric vector of x values. |
| <code>y</code> | Numeric vector of y values. |
| <code>r</code> | Order of the derivative. |
| <code>nseg</code> | Number of segments. |
| <code>bdeg</code> | Degree of the B-spline. |
| <code>pord</code> | Order of the penalty. |
| <code>x.grid</code> | Grid of x values for evaluation. |

Value

A list containing:

| | |
|---------------------|--|
| <code>fr.est</code> | List of estimated derivative values. |
| <code>f.hat</code> | Estimated function values. |
| <code>fg.hat</code> | Estimated function values on the grid. |
| <code>fr.hat</code> | Estimated derivative values. |

| | |
|---------|--|
| frg.hat | Estimated derivative values on the grid. |
| sig.hat | Estimated standard deviation of the noise. |
| lambda | Optimal smoothing parameter. |
| edf | Effective degrees of freedom. |
| tr | Trace of the smoothing matrix. |

Examples

```
# Example for naive.est.opt
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
x.grid <- seq(0, 1, length.out = 200)
result <- naive.est.opt(x, y, r = 1, nseg = 10, bdeg = 3, pord = 2, x.grid = x.grid)
plot(x.grid, result$frg.hat, type = "l", col = "blue", main = "Naive Estimation")
points(x, y, col = "red")
```

oracle.est

Oracle Estimation of Derivative

Description

Performs oracle estimation of the derivative function.

Usage

```
oracle.est(
  initial.lambda = 0.03,
  x,
  y,
  r,
  fr.grid,
  nseg = 35,
  pord = 2,
  bdeg = 5,
  x.grid
)
```

Arguments

| | |
|----------------|--|
| initial.lambda | Initial value for the smoothing parameter. |
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| r | Order of the derivative. |
| fr.grid | True derivative values on the grid. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |
| x.grid | Grid of x values for evaluation. |

Value

A list containing:

| | |
|---------|--|
| x.grid | Grid of x values for evaluation. |
| fr.hat | Estimated derivative values. |
| lambda | Optimal smoothing parameter. |
| frg.hat | Estimated derivative values on the grid. |

Examples

```
# Example for oracle.est
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
x.grid <- seq(0, 1, length.out = 200)
fr.grid <- cos(2 * pi * x.grid) # True derivative
result <- oracle.est(initial.lambda = 0.1, x, y, r = 1, fr.grid = fr.grid, nseg = 10, pord = 2, bdeg = 3, x.grid =
plot(x.grid, result$frg.hat, type = "l", col = "blue", main = "Oracle Estimation")
points(x, y, col = "red")
```

| | |
|-------------|-----------------------------|
| oracle.loss | <i>Oracle Loss Function</i> |
|-------------|-----------------------------|

Description

Computes the loss function for oracle estimation.

Usage

```
oracle.loss(
  lambda = 0.2,
  x,
  y,
  r,
  fr.grid,
  nseg = 35,
  pord = 2,
  bdeg = 5,
  x.grid
)
```

Arguments

| | |
|---------|-------------------------------------|
| lambda | Smoothing parameter. |
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| r | Order of the derivative. |
| fr.grid | True derivative values on the grid. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |
| x.grid | Grid of x values for evaluation. |

Value

The loss function value.

| | |
|-------|---|
| pgams | <i>Penalized Spline Derivative Estimation</i> |
|-------|---|

Description

Estimates the derivative function using penalized splines.

Usage

```
pgams(x, y, lambda = 0.1, r = 0, x.grid, nseg = 35, pord = 2, bdeg = 3)
```

Arguments

| | |
|--------|----------------------------------|
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| lambda | Smoothing parameter. |
| r | Order of the derivative. |
| x.grid | Grid of x values for evaluation. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |

Value

A list containing:

| | |
|---------|--|
| x.grid | Grid of x values for evaluation. |
| f.hat | Estimated function values. |
| fg.hat | Estimated function values on the grid. |
| fr.hat | Estimated derivative values. |
| frg.hat | Estimated derivative values on the grid. |
| K | Matrix of reparametrized parameters. |
| M | Matrix of smoothing parameters. |
| Atilde | Matrix of transformed basis functions. |
| A | Matrix of fitted values. |
| lambda | Smoothing parameter. |

Examples

```
# Example for pgams
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
x.grid <- seq(0, 1, length.out = 200)
result <- pgams(x, y, lambda = 0.1, r = 1, x.grid = x.grid, nseg = 10, pord = 2, bdeg = 3)
plot(x.grid, result$frg.hat, type = "l", col = "blue", main = "Estimated Derivative")
points(x, y, col = "red")
```


plugin.est

*Plug-in Estimation of Derivative***Description**

Performs one-step plug-in estimation of the derivative function.

Usage

```
plugin.est(x, y, r, nseg = 35, pord = 3, bdeg = 4, x.grid, fr = NULL)
```

Arguments

| | |
|--------|----------------------------------|
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| r | Order of the derivative. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |
| x.grid | Grid of x values for evaluation. |
| fr | Optional true derivative values. |

Value

A list containing:

| | |
|---------|--|
| x.grid | Grid of x values for evaluation. |
| f.hat | Estimated function values. |
| fg.hat | Estimated function values on the grid. |
| fr.hat | Estimated derivative values. |
| frg.hat | Estimated derivative values on the grid. |
| lambda | Optimal smoothing parameter. |
| K | Matrix of reparametrized parameters. |
| M | Matrix of smoothing parameters. |
| Atilde | Matrix of transformed basis functions. |
| A | Matrix of fitted values. |
| sig.hat | Estimated standard deviation of the noise. |

Examples

```
# Example for plugin.est
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
x.grid <- seq(0, 1, length.out = 200)
result <- plugin.est(x, y, r = 1, nseg = 10, pord = 2, bdeg = 3, x.grid = x.grid)
plot(x.grid, result$frg.hat, type = "l", col = "blue", main = "Plug-in Estimation")
points(x, y, col = "red")
```

resub.est

*Iterative Re-substitution Estimation***Description**

Performs iterative re-substitution estimation of the derivative function.

Usage

```
resub.est(x, y, r, x.grid, nseg, pord, bdeg, tol = 1e-10, ITs = 10)
```

Arguments

| | |
|--------|----------------------------------|
| x | Numeric vector of x values. |
| y | Numeric vector of y values. |
| r | Order of the derivative. |
| x.grid | Grid of x values for evaluation. |
| nseg | Number of segments. |
| pord | Order of the penalty. |
| bdeg | Degree of the B-spline. |
| tol | Tolerance for convergence. |
| ITs | Maximum number of iterations. |

Value

A list containing:

| | |
|---------|--|
| x.grid | Grid of x values for evaluation. |
| fr.hat | Estimated derivative values. |
| lambda | Optimal smoothing parameter. |
| frg.hat | Estimated derivative values on the grid. |

Examples

```
# Example for resub.est
x <- seq(0, 1, length.out = 100)
y <- sin(2 * pi * x) + rnorm(100, sd = 0.1)
x.grid <- seq(0, 1, length.out = 200)
result <- resub.est(x, y, r = 1, x.grid = x.grid, nseg = 10, pord = 2, bdeg = 3)
plot(x.grid, result$frg.hat, type = "l", col = "blue", main = "Resubstitution Estimation")
points(x, y, col = "red")
```

| | |
|--------|---------------------------------|
| tpower | <i>Truncated Power Function</i> |
|--------|---------------------------------|

Description

Computes the truncated p-th power function.

Usage

```
tpower(x, t, p)
```

Arguments

| | |
|---|---------------------------------------|
| x | Numeric vector of values to evaluate. |
| t | Knot value. |
| p | Degree of the polynomial. |

Value

Numeric vector of evaluated values.

Examples

```
# Example for tpower
x <- seq(0, 1, length.out = 100)
t <- 0.5
p <- 2
result <- tpower(x, t, p)
plot(x, result, type = "l", col = "blue", main = "Truncated Power Function")
```

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