Shaopeng Guo

EDUCATION

The Hong Kong University of Science and Technology

Bachelor of Engineering - Computer Science

Hong Kong Aug. 2018

RESEARCH EXPERIENCE

The Hong Kong University of Science and Technology

Hong Kong

Supervisor: Prof. Chi-Keung Tang & Dr. Yu-Wing Tai

Aug. 2021 - Present

Email: sguoad@connect.ust.hk Homepage: coeusguo.github.io

- o Conditional Human Motion Prediction. We propose a semi-supervised human motion prediction method. Based on single-frame SMPL input, our model can predict N frames forward and backward, conditioned on the human action input. (In Progress)
- Learning Transferable Part-Level Representations by Language Supervation. We propose a multi-modal training method that instead of training with one-hot labels, we utilize the pre-trained language model to map labels into continuous feature space; with our novel human-part level training pipeline, the model can be trained on multiple fully-labeled dataset simultaneously by supervised learning and partially-labeled datasets by semi-supervised learning. Our method outperforms SOTA by a large margin. (CVPR2022 submission, First Author)

S-Lab, Nanyang Technological University.

Remote

Supervisor: Prof. Ziwei Liu

Jan. 2021 - Mar. 2021 (Part-time)

- o Vision transformer Considering the drawback of visual transformer (ViT) that requires a large amount of pretraining data and high computation cost, we designed an image-to-token module and a locally-enhanced layer. The models achieved similar or better performance with less than 1/3 of training iteration compare to original ViT. (ICCV 2021)
- Differentiable dynamic wiring network We find that a fixed architecture may not be suitable for different data with high diversity. We address this issue by proposing Differentiable Dynamic Wirings, which learns the instance-aware connectivity that creates different wiring patterns for different instances. (ICCV 2021)

SenseTime Group Ltd.

Hong Kong

Supervisor: Dr. Junjie Yan

Sept 2018 - Sept. 2019

• Network Pruning via Differentiable Markov Process. We model the channel pruning of neural networks as a Markov Process, with transition probabilities computed by a set of learnable parameters. The marginal probability of each network channel can be computed and fused into the network; thus, the Markov process could be optimized together with model parameters by gradient descent. Our method achieved SOTA results in various models on ImageNet dataset. (CVPR2020 Oral, First author)

Publications

- Kun Yuan, **Shaopeng Guo**, Ziwei Liu, Xinyu Xu, Aojun Zhou, Fengwei Yu, Wei Wu, "Incorporating Convolution Designs into Visual Transformers", IEEE International Conference on Computer Vision (ICCV) 2021
- Kun Yuan, Quanquan Li, **Shaopeng Guo**, Dapeng Chen, Aojun Zhou, Fengwei Yu, Ziwei Liu, "Differentiable Dynamic Wirings for Neural Networks", IEEE International Conference on Computer Vision (ICCV) 2021
- Shaopeng Guo, Yujie Wang, Quanquan Li, Junjie Yan, "DMCP: Differentiable Markov Channel Pruning for Neural Networks", IEEE Conference on Computer Vision and Patten Recognition (CVPR) 2021, (Oral, 5.03% acceptance rate)

EMPLOYMENT

The Hong Kong University of Science and Technology

Hong Kong

Research Assistant

Aug.2021 - Present

SenseTime Group Ltd.

Research and Development

Hong Kong *May. 2019 - Jul. 2021*

- Large Model Pre-training. Lead a small group with 4 members, work on transferring the knowledge from a large pre-trained model (trained on 400M web images) to variety of small models with few-shot learning and meta-learning.
- Deep Vision Model Training Framework. One of two members that implement and maintain an efficient training framework including all widely used models, SOTA supervised, semi-supervised, and unsupervised training methods.
- Model production Tool Chain. Participate in developing the internal tool chain for "production-ready" model, establish a complete pipeline from model pre-training to hardware deployment.

• R&D Intern

Sept. 2018 - May 2019

• Network Quantization for Efficient Inference. Define network quantization as a convex optimization problem, the information loss from 32bit floating point to 4bit integer was represented by our proposed reconstruction loss, which was convex and could be optimized iteratively by gradient-based method. The quantized models had negligible accuracy loss and 2x faster inference speed on both GPUs and mobile processors.

Tencent YouTu Lab.

Shen Zhen, China

 $R \mathcal{E}D$ Intern

Sept. 2017 - Jan. 2018

• Detection Driven Reinforcement Learning for 3D Game Playing. Formulate the navigation in 3D immersive environment as reinforcement learning problem, and introduced an auxiliary task that learning to distinguish the foreground objects and background. A region proposal network was proposed to be the encoder of auxiliary task.