



DS90UB948-Q1 1080p FPD-Link III 至 OpenLDI 解串器

1 特性

- 支持高达 170MHz 的像素时钟频率，支持 WUXGA (1920x1200) 和 1080p60 分辨率（24 位色深）
- 具有偏移补偿能力的单通道或双通道 FPD-Link III 接口
- 单通道或双通道 OpenLDI (LVDS) 发送器
 - 单通道：高达 96MHz 的像素时钟
 - 双通道：高达 170MHz 的像素时钟
 - 可配置的 18 位红-绿-蓝三色 (RGB) 或 24 位 RGB
- 速度高达 2.0Mbps 的通用输入输出 (GPIO)
- 具有自动温度和老化补偿功能，支持长达 15 米的电缆
- 速率高达 3.3Mbps 的串行外设接口 (SPI) 控制接口
- 具有 1Mbps 快速模式+的 I²C（主/从）
- 自适应接收均衡
- 图像增强功能（白平衡和抖动）
- 支持多条 I2S（4 个数据）通道
- 向后兼容 DS90UB925/925AQ-Q1 和 DS90UB927Q-Q1 FPD-Link III 串行器
- 汽车应用级产品：符合 AEC-Q100 2 级要求

2 应用

- 汽车信息娱乐：
 - 中央信息显示屏
 - 后座娱乐系统
 - 数字仪表盘

3 说明

DS90UB948-Q1 是一款 FPD-Link III 解串器，与 DS90UB949/947/929-Q1 串行器配合使用时可将单通道或双通道 FPD-Link III 流转换成 FPD-Link (OpenLDI) 接口格式。该解串器能够在经济高效的 50Ω 单端同轴或 100Ω 差分屏蔽双绞线 (STP) 电缆上运行。它能够从单通道或双通道 FPD-Link III 串行流中恢复数据，然后将其转换为双像素 FPD-Link（8 个 LVDS 数据通道 + 时钟），最高可支持 WUXGA 和 1080p60 视频分辨率（24 位色深）。这可为各个支持 HDMI 的源（例如 CPU）间提供桥接，以便连接到现有 LVDS 显示器或应用处理器。

FPD-Link III 接口支持通过同一条差分链路进行视频和音频数据传输以及全双工控制（包括 I²C 和 SPI 通信）。通过两个差分对实现视频数据和控制的整合可减少互连线尺寸和重量，并简化了系统设计。通过使用低压差分信令、数据换序和随机生成最大限度地减少了电磁干扰 (EMI)。在向后兼容模式下，该器件在单一差分链路上最高可支持 WXGA 和 720p 分辨率（24 位色深）。

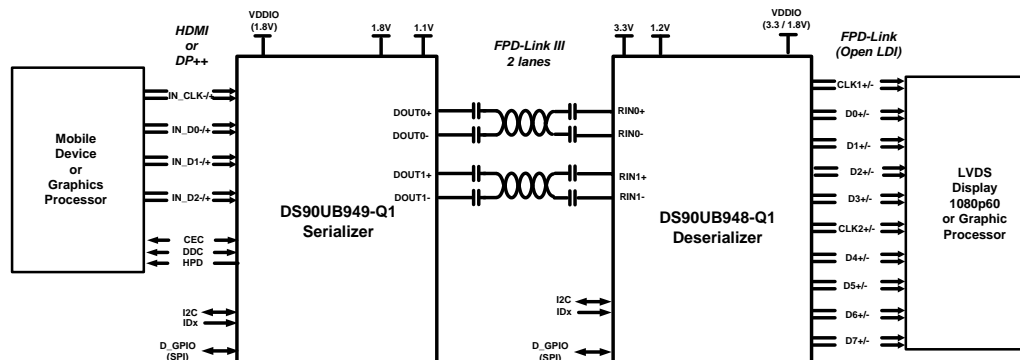
该器件将自动检测 FPD-Link III 通道并提供一种时钟对齐和偏移补偿功能，无需任何特殊的训练模式。这可在互连线路（例如，印刷电路板 (PCB) 布线）中出现不匹配问题、电缆线对长度存在差异以及连接器不平衡时确保相位偏移在容差范围内。

器件信息(1)

| 器件型号 | 封装 | 封装尺寸（标称值） |
|--------------|---------------------------|-----------------|
| DS90UB948-Q1 | 超薄四方扁平无引线 (WQFN) NKD (64) | 9.00mm x 9.00mm |

(1) 如需了解所有可用封装，请见数据表末尾的可订购产品附录。

4 应用图



目录

| | | | | | |
|------|--|----|------|---|----|
| 1 | 特性 | 1 | 8.2 | Functional Block Diagram | 21 |
| 2 | 应用 | 1 | 8.3 | Feature Description | 22 |
| 3 | 说明 | 1 | 8.4 | Device Functional Modes | 36 |
| 4 | 应用 图 | 1 | 8.5 | Image Enhancement Features | 44 |
| 5 | 修订历史记录 | 2 | 8.6 | Programming | 47 |
| 6 | Pin Configurations and Functions | 4 | 8.7 | Register Maps | 50 |
| 7 | Specifications | 9 | 9 | Application and Implementation | 71 |
| 7.1 | Absolute Maximum Ratings | 9 | 9.1 | Application Information | 71 |
| 7.2 | ESD Ratings—JEDEC | 9 | 9.2 | Typical Applications | 71 |
| 7.3 | ESD Ratings—IEC and ISO | 9 | 10 | Power Supply Recommendations | 76 |
| 7.4 | Recommended Operating Conditions | 9 | 10.1 | Power Up Requirements and PDB Pin | 76 |
| 7.5 | Thermal Information | 10 | 11 | Layout | 76 |
| 7.6 | DC Electrical Characteristics | 10 | 11.1 | Layout Guidelines | 76 |
| 7.7 | AC Electrical Characteristics | 13 | 11.2 | Layout Example | 78 |
| 7.8 | Timing Requirements for the Serial Control Bus | 14 | 12 | 器件和文档支持 | 80 |
| 7.9 | Switching Characteristics | 15 | 12.1 | 文档支持 | 80 |
| 7.10 | Timing Diagrams and Test Circuits | 15 | 12.2 | 社区资源 | 80 |
| 7.11 | Power Sequence | 19 | 12.3 | 商标 | 80 |
| 7.12 | Typical Characteristics | 20 | 12.4 | 静电放电警告 | 80 |
| 8 | Detailed Description | 21 | 12.5 | Glossary | 80 |
| 8.1 | Overview | 21 | 13 | 机械、封装和可订购信息 | 80 |

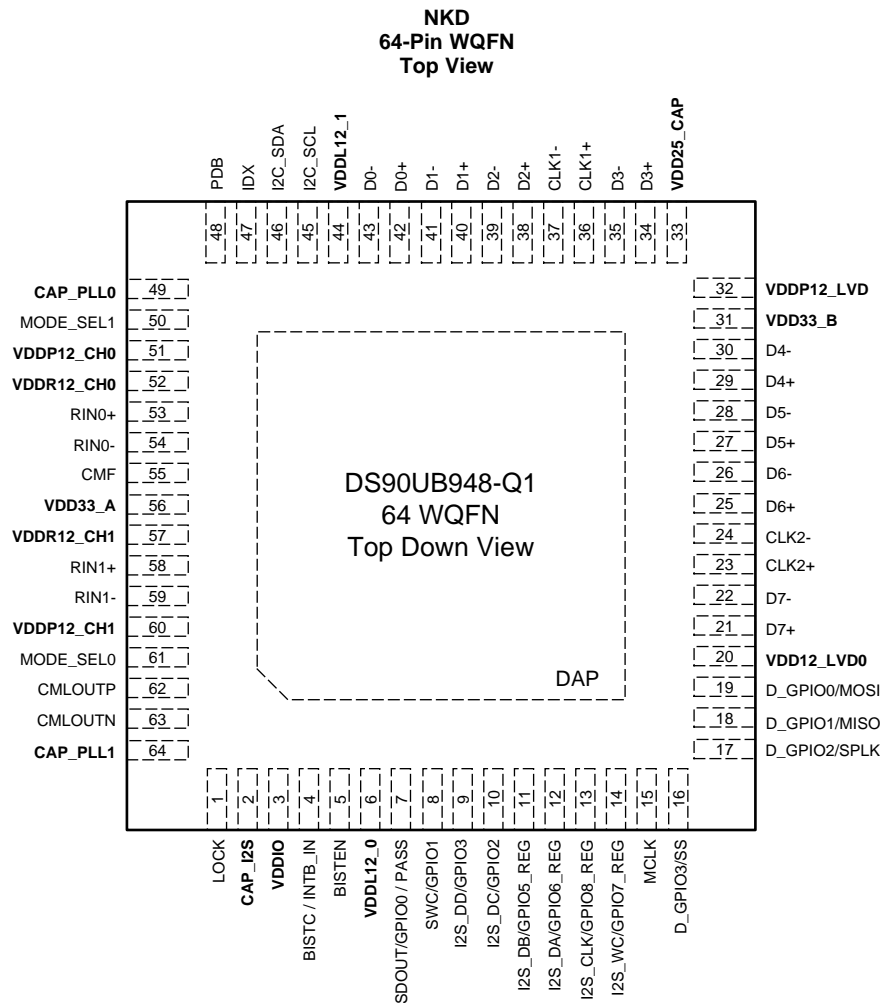
5 修订历史记录

| Changes from Original (October 2014) to Revision A | Page |
|---|------|
| • Added shared pins description on SPI pins | 5 |
| • Added shared pins description on GPIO pins | 6 |
| • Added shared pins description on D_GPIO pins | 6 |
| • Added shared pins description on register only GPIO pins. Changed "Local register control only" to "I2C register control only" | 6 |
| • Added shared pins description on slave mode I2S pins | 7 |
| • Added shared pins description on master mode I2S pins | 7 |
| • Added legend on I/O TYPE | 8 |
| • Moved Storage Temperature Range from ESD to Absolute Maximum Ratings table | 9 |
| • Added ESD Ratings table | 9 |
| • Changed V_{OS} from 1.0V to 1.125V | 12 |
| • Changed V_{OS} from 1.5V to 1.375V | 12 |
| • Changed IDD12Z limit from 8mA to 30mA per PE re-characterization | 12 |
| • Changed Fast Plus Mode t_{SP} maximum from 20ns to 50ns | 14 |
| • Added Power Sequence section | 19 |
| • Added Image Enhancement Features section | 44 |
| • Changed default value from "0" to "1" in register 0x01[2] | 50 |
| • Added description to register 0x01[1] "Registers which are loaded by pin strap will be restored to their original strap value when this bit is set. These registers show 'Strap' as their default value in this table." | 50 |
| • Added to 0x02[7] in Description column "A Digital reset 0x01[0] should be asserted after toggling Output Enable bit LOW to HIGH" | 50 |
| • Added "Loaded from remote SER" in register 0x07[7:1] function column | 52 |
| • Changed signal detect bit to reserved | 55 |
| • Changed from Reserved to Rev-ID in register 0x1D Function column | 56 |

修订历史记录 (continued)

| | |
|---|----|
| • On register 0x22 added "(Loaded from remote SER)" | 59 |
| • Corrected in register 0x24[3] 0: Bist configured through "bit 0" to "bits 2:0" in description | 61 |
| • Added in register 0x24[2:1] additional description..... | 61 |
| • Changed in register 0x24[1] description to "internal" | 61 |
| • Changed in register 0x24[2] description to "internal" | 61 |
| • On register 0x28 added "Loaded from remote SER" | 62 |
| • Added clarification description on register 0x37 MODE_SEL | 65 |
| • Merged on 0x45 bits[7:4] and bits[3:0] default value: 0x08..... | 66 |

6 Pin Configurations and Functions



Pin Functions

| PIN | | I/O, TYPE | DESCRIPTION |
|---|----------|-----------|---|
| NAME | NUMBER | | |
| FPD-LINK OPENLDI OUTPUT PINS - <i>Layout note: for unused LVDS outputs, terminate with a single external 100 Ω termination at the end of the transmission line.</i> | | | |
| CLK1- CLK1+ | 37 36 | O, LVDS | Clock Differential Output This pair requires an external 100 Ω termination for LVDS |
| CLK2- CLK2+ | 24 23 | O, LVDS | Clock Differential Output This pair requires an external 100 Ω termination for LVDS |
| D0- D0+ | 43 42 | O, LVDS | Channel 0 Differential Output This pair requires an external 100 Ω termination for LVDS |
| D1- D1+ | 41 40 | O, LVDS | Channel 1 Differential Output This pair requires an external 100 Ω termination for LVDS |
| D2- D2+ | 39 38 | O, LVDS | Channel 2 Differential Output This pair requires an external 100 Ω termination for LVDS |
| D3- D3+ | 35 34 | O, LVDS | Channel 3 Differential Output This pair requires an external 100 Ω termination for LVDS |
| D4- D4+ | 30 29 | O, LVDS | Channel 4 Differential Output This pair requires an external 100 Ω termination for LVDS |
| D5- D5+ | 28 27 | O, LVDS | Channel 5 Differential Output This pair requires an external 100 Ω termination for LVDS |

Pin Functions (continued)

| PIN | | I/O, TYPE | DESCRIPTION |
|---|----------|--|--|
| NAME | NUMBER | | |
| D6- D6+ | 26 25 | O, LVDS | Channel 6 Differential Output This pair requires an external 100 Ω termination for LVDS |
| D7- D7+ | 22 21 | O, LVDS | Channel 7 Differential Output This pair requires an external 100 Ω termination for LVDS |
| FPD-LINK III INTERFACE - Layout note: for unused FPD-LinkIII inputs, float those pins (do not connect to an external pullup or pulldown) | | | |
| RIN0- | 54 | I/O, CML | FPD-Link III Inverting Input/Output The output must be AC-coupled with a 33 nF capacitor. |
| RIN0+ | 53 | I/O, CML | FPD-Link III True Input/Output The output must be AC-coupled with a 33 nF capacitor. |
| RIN1- | 59 | I/O, CML | FPD-Link III Inverting Input/Output The output must be AC-coupled with a 33 nF capacitor. |
| RIN1+ | 58 | I/O, CML | FPD-Link III True Input/Output The output must be AC-coupled with a 33 nF capacitor. |
| CMF | 55 | I/O, CML | Common Mode Filter. Connect 0.1 μ F capacitor to GND |
| I2C PINS | | | |
| I2C_SDA | 46 | I/O, Open-Drain | I2C Data Input / Output interface Open drain. Must have an external pull-up resistor to VDDIO DO NOT FLOAT . Recommended pull-up: 4.7 k Ω . |
| I2C_SCL | 45 | I/O, Open-Drain | I2C Clock Input / Output Interface Open drain. Must have an external pull-up resistor to VDDIO DO NOT FLOAT . Recommended pull-up: 4.7 k Ω . |
| IDx | 47 | I, Analog Configuration Pin | Analog input. I2C Serial Control Bus Device ID Address. Table 10 |
| SPI PINS (Pin function programmed through register) - Layout note: for unused SPI pins, tie to an external pulldown | | | |
| MOSI (D_GPIO0) | 19 | Multi-function pin I/O, LVCMOS w/ weak internal PD | Master Out, Slave In. (Pin is shared with D_GPIO0) |
| MISO (D_GPIO1) | 18 | Multi-function pin I/O, LVCMOS w/ weak internal PD | Master In, Slave Out. (Pin is shared with D_GPIO1) |
| SPLK (D_GPIO2) | 17 | Multi-function pin I/O, LVCMOS w/ weak internal PD | Serial clock. (Pin is shared with D_GPIO2) |
| SS (D_GPIO3) | 16 | Multi-function pin I/O, LVCMOS w/ weak internal PD | Slave select. (Pin is shared with D_GPIO3) |
| CONTROL PINS | | | |
| MODE_SELO | 61 | I, Analog Configuration Pin | Analog input. Mode Select 0. Connect to external pull-up to VDD33 and pull-down to GND to create a voltage divider. See Configuration Select (MODE_SELO) Table 8 |
| MODE_SEL1 | 50 | I, Analog Configuration Pin | Analog input. Mode Select 1. Connect to external pull-up to VDD33 and pull-down to GND to create a voltage divider. See Configuration Select (MODE_SEL1) Table 9 |

Pin Functions (continued)

| PIN | | I/O, TYPE | DESCRIPTION |
|--|--------|--|--|
| NAME | NUMBER | | |
| PDB | 48 | I, LVCMOS Configuration Pin w/ weak internal PD | Power-Down Mode Input Pin PDB = 1, device is enabled (normal operation) PDB = 0, device is powered down. When the device is in the POWER DOWN state, the LVCMOS outputs are in tri-state, the PLL is shutdown and IDD is minimized. Note: PDB pin requires minimum ramp time of 200us |
| BISTEN | 5 | I, LVCMOS Configuration Pin w/ weak internal PD | Bist Enable Pin 0: BIST Mode is disabled. 1: BIST Mode is enabled. See Built-In Self Test (BIST) for more information |
| BISTC (INTB_IN) | 4 | I, LVCMOS Configuration Pin w/ weak internal PD | Bist Clock Select. 0: PCLK 1: 33MHz (Pin is shared with INTB_IN) |
| INTB_IN (BISTC) | 4 | I, LVCMOS w/ weak internal PD | Interrupt input. (Pin is shared with BISTC) |
| BIDIRECTIONAL CONTROL CHANNEL (BCC) GPIO PINS (default pin function) - Layout note: for unused GPIO(s), tie to an external pulldown | | | |
| GPIO0 (SDOUT) | 7 | Multi-function pin I/O, LVCMOS | BCC GPIO0. default state: logic LOW (Pin is shared with SDOUT) |
| GPIO1 (SWC) | 8 | Multi-function pin I/O, LVCMOS | BCC GPIO1. default state: logic LOW (Pin is shared with SWC) |
| GPIO2 (I2S_DC) | 10 | Multi-function pin I/O, LVCMOS | BCC GPIO2. default state: logic LOW (Pin is shared with I2S_DC) |
| GPIO3 (I2S_DD) | 9 | Multi-function pin I/O, LVCMOS | BCC GPIO3. default state: logic LOW (Pin is shared with I2S_DD) |
| HIGH-SPEED GPIO PINS HIGH-SPEED GPIO PINS (default pin function) - Layout note: for unused D_GPIO(s), tie to an external pulldown | | | |
| D_GPIO0 (MOSI) | 19 | I/O, LVCMOS | General Purpose I/O in 2-lane FPD-Link III mode default state: tri-state (Pin is shared with MOSI) |
| D_GPIO1 (MISO) | 18 | I/O, LVCMOS | General Purpose I/O in 2-lane FPD-Link III mode default state: tri-state (Pin is shared with MISO) |
| D_GPIO2 (SPLK) | 17 | I/O, LVCMOS | General Purpose I/O in 2-lane FPD-Link III mode default state: tri-state (Pin is shared with SPLK) |
| D_GPIO3 (SS) | 16 | I/O, LVCMOS | General Purpose I/O in 2-lane FPD-Link III mode default state: tri-state (Pin is shared with SS) |
| REGISTER READ/Writes ONLY GPIO PINS (default pin function) - Layout note: for unused GPIO(s), tie to an external pulldown | | | |
| GPIO5_REG (I2S_DB) | 11 | Multi-function pin I/O, LVCMOS | General Purpose Input/Output 5 I2C register control only. default state: logic LOW (Pin is shared with I2S_DB) |
| GPIO6_REG (I2S_DA) | 12 | Multi-function pin I/O, LVCMOS | General Purpose Input/Output 6 I2C register control only. default state: logic LOW (Pin is shared with I2S_DA) |

Pin Functions (continued)

| PIN | | I/O, TYPE | DESCRIPTION |
|--|----------|--------------------------------------|---|
| NAME | NUMBER | | |
| GPIO7_REG (I2S_WC) | 14 | Multi-function pin I/O, LVCMOS | General Purpose Input/Output 7 I2C register control only. default state: logic <i>LOW</i> (Pin is shared with I2S_WC) |
| GPIO8_REG (I2S_CLK) | 13 | Multi-function pin I/O, LVCMOS | General Purpose Input/Output 8 I2C register control only. default state: logic <i>LOW</i> (Pin is shared with I2S_CLK) |
| SLAVE MODE LOCAL I2S CHANNEL PINS (Pin function programmed through register) - Layout note: for unused I2S outputs, tie to an external pulldown | | | |
| I2S_WC (GPIO7_REG) | 14 | Multi-function pin O, LVCMOS | Slave Mode I2S Word Clock Output. (Pin is shared with GPIO7_REG) |
| I2S_CLK (GPIO8_REG) | 13 | Multi-function pin O, LVCMOS | Slave Mode I2S Clock Output. (Pin is shared with GPIO8_REG) |
| I2S_DA (GPIO6_REG) | 12 | Multi-function pin O, LVCMOS | Slave Mode I2S Data Output. (Pin is shared with GPIO6_REG) |
| I2S_DB (GPIO5_REG) | 11 | Multi-function pin O, LVCMOS | Slave Mode I2S Data Output. (Pin is shared with GPIO5_REG) |
| I2S_DC (GPIO2_REG) | 10 | Multi-function pin O, LVCMOS | Slave Mode I2S Data Output. (Pin is shared with GPIO2) |
| I2S_DD (GPIO3_REG) | 9 | Multi-function pin O, LVCMOS | Slave Mode I2S Data Output. (Pin is shared with GPIO3) |
| MASTER MODE LOCAL I2S CHANNEL PINS (Pin function programmed through register) - Layout note: for unused GPIO(s), tie to an external pulldown | | | |
| SWC (GPIO1) | 8 | Multi-function pin O, LVCMOS | Master Mode I2S Word Clock Output. (Pin is shared with GPIO1) |
| SDOUT (GPIO0) | 7 | Multi-function pin O, LVCMOS | Master Mode I2S Data Output. (Pin is shared with GPIO0) |
| MCLK (GPIO9) | 15 | Multi-function pin O, LVCMOS | Master Mode I2S System Clock Output. (Pin is shared with GPIO9) |
| STATUS PINS - Layout note: add a test point (TP) on these pins | | | |
| LOCK | 1 | O, LVCMOS | Lock Status Output LOCK = 1: PLL acquired lock to the reference clock input LOCK = 0: PLL is unlocked |
| PASS | 7 | O, LVCMOS | BIST mode status output pin (BISTEN = 1) PASS = 1: No error detected PASS = 0: Error detected |
| POWER & GROUND ⁽¹⁾ | | | |
| VDD33_A, VDD33_B | 56 31 | Power | 3.3V ($\pm 10\%$) supply. Power to on-chip regulator. Requires 10 μ F, 1 μ F, 0.1 μ F, and 0.01 μ F capacitors to GND |
| VDDIO | 3 | Power | LVCMOS I/O power supply, 1.8V ($\pm 5\%$) OR 3.3V ($\pm 10\%$). Requires 10 μ F, 1 μ F, 0.1 μ F, and 0.01 μ F capacitors to GND |

(1) The VDD (VDD12, VDD33, and VDDIO) supply ramp should be faster than 1.5ms with a monotonic rise

Pin Functions (continued)

| PIN | | I/O, TYPE | DESCRIPTION |
|---|---|-----------|--|
| NAME | NUMBER | | |
| VDD12_LVDS VDDP12_LVDS VDDL12_0 VDDL12_1 VDDP12_CH0 VDDR12_CH0 VDDP12_CH1 VDDR12_CH1 | 20 32 6 44 51 52 60 57 | Power | 1.2V (±5%) supplies. Requires 10 μ F, 1 μ F, 0.1 μ F, and 0.01 μ F capacitors to GND at each VDD pin. |
| CAP_PLL0 CAP_PLL1 CAP_I2S VDD25_CAP | 49 64 2 33 | CAP | Decoupling capacitor connection for on-chip regulator. Each requires a 0.1 μ F decoupling capacitor to GND. |
| VSS | DAP | Ground | DAP is the large metal contact at the bottom side, located at the center of the WQFN package. Connect to the ground plane (GND) with at least 32 vias. |
| OTHER PINS | | | |
| CMLOUTP CMLOUTN | 62 63 | O, CML | Monitor point for equalized differential signal. Layout recommendation: 1) place 0.1 μ F series capacitor on CMLOUTP and CMLOUTN 2) place 100ohm termination between 0.1 μ F away from CMLOUTP and CMLOUTN pins 3) place test points from 0.1 μ F capacitors |

The definitions below define the functionality of the I/O cells for each pin.

I/O TYPE:

- P = Power Supply
- G = Ground
- CML = CML Interface
- DPHY = MIPI DPHY Interface
- Analog = Analog Interface
- LVCMOS = LVCMOS pin; Referenced to VDDIO IO supply
- I = Input
- O = Output
- I/O = Input/Output
- PD, PU = Internal Pull-Down/Pull-Up (All strap pins have weak internal pull-ups or pull-downs. If the default strap value is needed to be changed then an external resistor should be used.)
- Multi-function pin

7 Specifications

7.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)^{(1) (2)}

| PARAMETER | | MIN | MAX | UNIT |
|------------------|----------------------------|------|-------------|------|
| VDD33 | Supply voltage | −0.3 | 4.0 | V |
| VDD12 | Supply voltage | −0.3 | 1.8 | V |
| VDDIO | Supply voltage | −0.3 | 4.0 | V |
| | LVC MOS I/O voltage | −0.3 | VDDIO + 0.3 | V |
| | FPD-Link III input voltage | −0.3 | 2.75 | V |
| T _J | Junction temperature | | 150 | °C |
| T _{stg} | Storage temperature range | −65 | 150 | °C |

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) For soldering specifications, see product folder at www.ti.com and [SNOA549](#)

7.2 ESD Ratings—JEDEC

| | | VALUE | UNIT |
|--------------------|-------------------------|---|------|
| V _(ESD) | Electrostatic discharge | Human-body model (HBM), per AEC Q100-002 ⁽¹⁾ | V |
| | | Charged-device model (CDM), per AEC Q100-011 | |

- (1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

7.3 ESD Ratings—IEC and ISO

| | | | VALUE | UNIT |
|--|---|---|--------|------|
| V _(ESD) Electrostatic discharge | R _D = 330 Ω, C _S = 150 pF | IEC, powered-up only contact discharge (R _{IN0+} , R _{IN0-} , R _{IN1+} , R _{IN1-}) | ±8000 | V |
| | | IEC, powered-up only air-gap discharge (R _{IN0+} , R _{IN0-} , R _{IN1+} , R _{IN1-}) | ±15000 | |
| | R _D = 330 Ω, C _S = 150 and 330 pF | ISO10605 contact discharge (R _{IN0+} , R _{IN0-} , R _{IN1+} , R _{IN1-}) | ±8000 | V |
| | | ISO10605 air-gap discharge (R _{IN0+} , R _{IN0-} , R _{IN1+} , R _{IN1-}) | ±15000 | |
| | R _D = 2 kΩ, C _S = 150 and 330 pF | ISO10605 contact discharge (R _{IN0+} , R _{IN0-} , R _{IN1+} , R _{IN1-}) | ±8000 | V |
| | | ISO10605 air-gap discharge (R _{IN0+} , R _{IN0-} , R _{IN1+} , R _{IN1-}) | ±15000 | |

7.4 Recommended Operating Conditions

| | MIN | NOM | MAX | UNIT |
|--|------|-----|------|-------------------|
| Supply Voltage (VDD33) | 3.0 | 3.3 | 3.6 | V |
| Supply Voltage (VDD18) | 1.71 | 1.8 | 1.89 | V |
| Supply Voltage (VDD12) | 1.14 | 1.2 | 1.26 | V |
| Operating Free Air Temperature (T _A) | −40 | 25 | 105 | °C |
| OpenLDI Clock Frequency (Single Link) | 25 | | 96 | MHz |
| OpenLDI Clock Frequency (Dual Link) | 50 | | 170 | MHz |
| Supply Noise -- VDD33 (DC-50MHz) | | | 100 | mV _{p-p} |
| Supply Noise -- VDD18 (DC-50MHz) | | | 50 | mV _{p-p} |
| Supply Noise -- VDD12 (DC-50MHz) | | | 25 | mV _{p-p} |

7.5 Thermal Information

| THERMAL METRIC ⁽¹⁾ | | DS90UB948-Q1 | UNIT |
|-------------------------------|--|--------------|------|
| | | WQFN (NKD) | |
| | | 64 PINS | |
| R _{θJA} | Junction-to-ambient thermal resistance | 24.8 | °C/W |
| R _{θJC(top)} | Junction-to-case (top) thermal resistance | 6.2 | |
| R _{θJB} | Junction-to-board thermal resistance | 3.6 | |
| ψ _{JT} | Junction-to-top characterization parameter | 0.1 | |
| ψ _{JB} | Junction-to-board characterization parameter | 3.6 | |
| R _{θJC(bot)} | Junction-to-case (bottom) thermal resistance | 0.6 | |

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

7.6 DC Electrical Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.

| PARAMETER | | TEST CONDITIONS | PIN/FREQ. | MIN | TYP | MAX | UNIT |
|--|------------------------------|--|---|-----------------|-----|-----------------|------|
| 3.3V LVCMOS I/O (VDDIO = 3.3V ± 10%) | | | | | | | |
| V _{IH} | High Level Input Voltage | | PDB, BISTEN, BISTC, GPIO[3:0], D_GPIO[3:0], I2S_DA, I2S_DB, I2S_DC, I2S_DD, I2S_CLK, I2S_WC, LOCK, PASS | 2.0 | | VDDIO | V |
| V _{IL} | Low Level Input Voltage | | | 0 | | 0.8 | V |
| I _{IN} | Input Current | V _{IN} = 0V or VDDIO | | -10 | | 10 | μA |
| V _{OH} | High Level Output Voltage | I _{OH} = -4mA | | 2.4 | | VDDIO | V |
| V _{OL} | Low Level Output Voltage | I _{OL} = +4mA | | 0 | | 0.4 | V |
| I _{OS} | Output Short Circuit Current | V _{OUT} = 0V | | | -55 | | mA |
| I _{OZ} | Tri-state Output Current | PDB = 0V V _{OUT} = 0V or VDDIO | | -20 | | 20 | μA |
| C _{IN} | Input Capacitance | | | | | 10 | pF |
| 1.8V LVCMOS I/O (VDDIO = 1.8V ± 5%) | | | | | | | |
| V _{IH} | High Level Input Voltage | | PDB, BISTEN, BISTC, GPIO[3:0], D_GPIO[3:0], I2S_DA, I2S_DB, I2S_DC, I2S_DD, I2S_CLK, I2S_WC, LOCK, PASS | 0.65 * VDDIO | | VDDIO | V |
| V _{IL} | Low Level Input Voltage | | | 0 | | 0.35 * VDDIO | V |
| I _{IN} | Input Current | V _{IN} = 0V or VDDIO | | -10 | | 10 | μA |
| V _{OH} | High Level Output Voltage | I _{OH} = -4mA | | VDDIO- 0.45 | | VDDIO | V |
| V _{OL} | Low Level Output Voltage | I _{OL} = +4mA | | 0 | | 0.45 | V |
| I _{OS} | Output Short Circuit Current | V _{OUT} = 0V | | | -35 | | mA |
| I _{OZ} | Tri-state Output Current | PDB = 0V V _{OUT} = 0V or VDDIO | | -20 | | 20 | μA |
| C _{IN} | Input Capacitance | | | | | 10 | pF |
| SERIAL CONTROL BUS (VDDIO = 1.8V ± 5% OR 3.3V ± 10%) | | | | | | | |
| V _{IH} | Input High Level | | I2C_SDA, I2C_SCL | 0.7 * VDDIO | | VDD33 | V |
| V _{IL} | Input Low Level | | | GND | | 0.3 * VDDIO | V |
| V _{HY} | Input Hysteresis | | | | >50 | | mV |
| V _{OL} | Output Low Level | I _{OL} = +4mA | | 0 | | 0.4 | V |
| I _{IN} | Input Current | V _{IN} = 0V or VDDIO | | -10 | | 10 | μA |

DC Electrical Characteristics (continued)

Over recommended operating supply and temperature ranges unless otherwise specified.

| PARAMETER | | TEST CONDITIONS | PIN/FREQ. | MIN | TYP | MAX | UNIT |
|-------------------------------|--|--|------------------------------|-----|-----|-----|----------|
| FPD-LINK III CML INPUT | | | | | | | |
| V_{TH} | Differential Threshold High Voltage | $V_{CM} = 2.1V$ (Internal V_{BIAS}) | RIN0+, RIN0- RIN1+, RIN1- | | | 50 | mV |
| V_{TL} | Differential Threshold Low Voltage | | | -50 | | | mV |
| V_{ID} | Input Differential Threshold | | | 100 | | | mV |
| V_{CM} | Differential Common-mode Voltage | | | | 2.1 | | V |
| R_T | Internal Termination Resistor - Differential | | | 80 | 100 | 120 | Ω |

DC Electrical Characteristics (continued)

Over recommended operating supply and temperature ranges unless otherwise specified.

| PARAMETER | | TEST CONDITIONS | PIN/FREQ. | MIN | TYP | MAX | UNIT |
|-----------------------------|---|--|--|-------|-----|-------|-------------------|
| LVDS DRIVER | | | | | | | |
| V _{OD} | Output voltage swing (differential) | R _L = 100Ω. VOD Setting 1. See Figure 10 . See Table 11 Register 0x4B for configuration details. | D0±, D1±, D2±, D3±, D4±, D5±, D6±, D7±, CLK1±, CLK2± | 220 | 380 | 540 | mV _{P-P} |
| | | R _L = 100Ω. VOD Setting 2. See Figure 10 . See Table 11 Register 0x4B for configuration details. | | 370 | 550 | 730 | mV _{P-P} |
| | | R _L = 100Ω. VOD Setting 3. See Figure 10 . See Table 11 Register 0x4B for configuration details. | | 460 | 650 | 840 | mV _{P-P} |
| | | R _L = 100Ω. VOD Setting 4. See Figure 10 . See Table 11 Register 0x4B for configuration details. | | 530 | 750 | 970 | mV _{P-P} |
| ΔV _{OD} | Change in V _{OD} between complimentary Output States | R _L = 100Ω | | | 1 | 50 | mV |
| V _{OS} | Offset Voltage | R _L = 100Ω. See Figure 10 . | | 1.125 | 1.2 | 1.375 | V |
| ΔV _{OS} | Change in V _{OS} between complimentary Output States | R _L = 100Ω | | | 1 | 50 | mV |
| I _{OS} | Output Short Circuit Current | | | | -20 | | mA |
| I _{OZ} | Output Tri-state LVDS Driver Current | PDB = 0V | | -500 | | 500 | μA |
| LOOP-THROUGH MONITOR OUTPUT | | | | | | | |
| V _{ODp-p} | Differential Output Voltage | R _L = 100Ω | CMLOUTP, CMLOUTN | | 360 | | mV |
| SUPPLY CURRENT | | | | | | | |
| P _T | Total Power Consumption, Normal Operation | Checkerboard Pattern, 170MHz. See Figure 1 . 2-lane FPD-Link III Input, Dual Link OLDI Output | VDD | | 858 | 1146 | mW |
| P _Z | Total Power Consumption, Power-Down Mode | PDB = 0V | | | 40 | 70 | mW |
| IDD12 | Supply Current, Normal Operation | Checkerboard Pattern, 170MHz. See Figure 1 . 2-lane FPD-Link III Input, Dual Link OLDI Output | VDD12 = 1.2 V | | | 223 | mA |
| IDD33 | | | VDD33 = 3.6 V | | | 222 | mA |
| IDDIO | | | VDDIO = 1.89 V | | | 19 | mA |
| | | | VDDIO = 3.6 V | | | 19 | mA |
| IDD12 | Supply Current, Normal Operation | Random Pattern (PRBS7) 2-lane FPD-Link III Input, Dual Link OLDI Output | VDD12 = 1.2 V | | 169 | | mA |
| IDD33 | | | VDD33 = 3.6 V | | 168 | | mA |
| IDDIO | | | VDDIO = 1.89 V | | 14 | | mA |
| | | | VDDIO = 3.6 V | | 14 | | mA |
| IDD12Z | Supply Current, Power Down Mode | PDB = 0 V | VDD12 = 1.2 V | | 2 | 30 | mA |
| IDD33Z | | | VDD33 = 3.6 V | | 2 | 8 | mA |
| IDDIOZ | | | VDDIO = 1.89 V | | 0.1 | 1 | mA |
| | | | VDDIO = 3.6 V | | 0.1 | 1 | mA |

7.7 AC Electrical Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.

| PARAMETER | | TEST CONDITIONS | PIN/FREQ. | MIN | TYP | MAX | UNIT |
|-----------------------------|---------------------------------------|---|--------------------------------|------------------------|-------------------|------------------|------|
| GPIO BIT RATE | | | | | | | |
| R _{b,FC} | Forward Channel Bit Rate | Single OLDI Output. OLDI Clock = 25 - 96MHz | GPIO[3:0] | 0.25 * OLDI Clock | | Mbps | |
| | | Dual OLDI Output. OLDI Clock = 25 - 85MHz | | 0.25 * OLDI Clock | | Mbps | |
| R _{b,BC} | Back Channel Bit Rate | | | 133 | | kbps | |
| R _{b,BC} | Back Channel Bit Rate | High Speed (2-lane Mode), 1 D_GPIO active. See Table 4 . | D_GPIO[3:0] | 2.0 | | Mbps | |
| | | High Speed (2-lane Mode), 2 D_GPIO's active. See Table 4 . | | 1.33 | | Mbps | |
| | | High Speed (2-lane Mode), 4 D_GPIO's active. See Table 4 . | | 800 | | kbps | |
| | | Normal mode. See Table 4 . | | 133 | | kbps | |
| t _{GPIO,FC} | GPIO Pulse Width, Forward Channel | | GPIO[3:0] | >2 / OLDI Clock | | s | |
| t _{GPIO,BC} | GPIO Pulse Width, Back Channel | | GPIO[3:0] | 20 | | μs | |
| RESET | | | | | | | |
| t _{LRST} | PDB Reset Low Pulse | | PDB | 2 | | ms | |
| LOOP-THROUGH MONITOR OUTPUT | | | | | | | |
| E _W | Differential Output Eye Opening Width | RL = 100Ω, Jitter frequency >OLDI Clock / 40 | CMLOUTP, CMLOUTN | 0.4 | | UI | |
| E _H | Differential Output Eye Height | See Figure 2 . | | >300 | | mV | |
| FPD-LINK III CML INPUT | | | | | | | |
| t _{DDLT} | Lock Time | See Figure 6 . | RIN0+, RIN0-, RIN1+, RIN1- | 5 | 10 ⁽¹⁾ | ms | |
| I2S TRANSMITTER | | | | | | | |
| t _{J,I2S} | Clock Output Jitter | | I2S_CLK | 2 | | ns | |
| t _{I2S} | I2S Clock Period ⁽²⁾ | See Figure 14 . | | >2 / OLDI Clock or >77 | | ns | |
| t _{HC,I2S} | I2S Clock High Time ⁽²⁾ | See Figure 14 . | | 0.48 | | t _{I2S} | |
| t _{LC,I2S} | I2S Clock Low Time ⁽²⁾ | See Figure 14 . | | 0.48 | | t _{I2S} | |
| t _{SR,I2S} | I2S Set-up Time | See Figure 14 . | I2S_DA, I2S_DB, I2S_DC, I2S_DD | 0.4 | | t _{I2S} | |
| t _{HR,I2S} | I2S Hold Time | See Figure 14 . | | 0.4 | | t _{I2S} | |

(1) This parameter is specified by characterization and is not tested in production.

(2) I2S specifications for $t_{LC,I2S}$ and $t_{HC,I2S}$ pulses must each be greater than 1 OLDI clock period to ensure sampling and supersedes the $0.35 \cdot t_{I2S}$ requirement. $t_{LC,I2S}$ and $t_{HC,I2S}$ must be longer than the greater of either $0.35 \cdot t_{I2S}$ or $2 \cdot \text{OLDI Clock}$.

7.8 Timing Requirements for the Serial Control Bus

Over I²C supply and temperature ranges unless otherwise specified.

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------|--|-----------------|------|-----|---------------------|------|
| f _{SCL} | SCL Clock Frequency | Standard Mode | >0 | | 100 | kHz |
| | | Fast Mode | >0 | | 400 | kHz |
| | | Fast Plus Mode | >0 | | 1 | MHz |
| t _{LOW} | SCL Low Period | Standard Mode | 4.7 | | | μs |
| | | Fast Mode | 1.3 | | | μs |
| | | Fast Plus Mode | 0.5 | | | μs |
| t _{HIGH} | SCL High Period | Standard Mode | 4.0 | | | μs |
| | | Fast Mode | 0.6 | | | μs |
| | | Fast Plus Mode | 0.26 | | | μs |
| t _{HD;STA} | Hold time for a start or a repeated start condition Figure 13 | Standard Mode | 4.0 | | | μs |
| | | Fast Mode | 0.6 | | | μs |
| | | Fast Plus Mode | 0.26 | | | μs |
| t _{SU;STA} | Set Up time for a start or a repeated start condition Figure 13 | Standard Mode | 4.7 | | | μs |
| | | Fast Mode | 0.6 | | | μs |
| | | Fast Plus Mode | 0.26 | | | μs |
| t _{HD;DAT} | Data Hold Time Figure 13 | Standard Mode | 0 | | | μs |
| | | Fast Mode | 0 | | | μs |
| | | Fast Plus Mode | 0 | | | μs |
| t _{SU;DAT} | Data Set Up Time Figure 13 | Standard Mode | 250 | | | ns |
| | | Fast Mode | 100 | | | ns |
| | | Fast Plus Mode | 50 | | | ns |
| t _{SU;STO} | Set Up Time for STOP Condition Figure 13 | Standard Mode | 4.0 | | | μs |
| | | Fast Mode | 0.6 | | | μs |
| | | Fast Plus Mode | 0.26 | | | μs |
| t _{BUF} | Bus Free Time Between STOP and START Figure 13 | Standard Mode | 4.7 | | | μs |
| | | Fast Mode | 1.3 | | | μs |
| | | Fast Plus Mode | 0.5 | | | μs |
| t _r | SCL & SDA Rise Time, Figure 13 | Standard Mode | | | 1000 ⁽¹⁾ | ns |
| | | Fast Mode | | | 300 ⁽¹⁾ | ns |
| | | Fast Plus Mode | | | 120 ⁽¹⁾ | ns |
| t _f | SCL & SDA Fall Time, Figure 13 | Standard Mode | | | 300 ⁽¹⁾ | ns |
| | | Fast mode | | | 300 ⁽¹⁾ | ns |
| | | Fast Plus Mode | | | 120 ⁽¹⁾ | ns |
| C _b | Capacitive Load for Each Bus Line | Standard Mode | | | 400 | pF |
| | | Fast Mode | | | 400 | pF |
| | | Fast Plus Mode | | | 550 | pF |
| t _{SP} | Input Filter | Fast Mode | | | 50 | ns |
| | | Fast Plus Mode | | | 50 | ns |

(1) Parameter is specified by bench characterization and is not tested in production.

7.9 Switching Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.

| PARAMETER | | TEST CONDITIONS | PIN/FREQ. | MIN | TYP | MAX | UNIT |
|---------------------------------------|---|---|--|---------|---------|---------------------|------|
| LVDS DRIVER SWITCHING CHARACTERISTICS | | | | | | | |
| t _{LVLHT} | LVDS Low-to-High Transition Time | 20% to 80% transition. 5pF load. See Figure 9 . | D0±, D1±, D2±, D3±, D4±, D5±, D6±, D7±, CLK1±, CLK2± | | 0.15 | 0.25 ⁽¹⁾ | ns |
| t _{LVHLT} | LVDS High-to-Low Transition Time | 80% to 20% transition. 5pF load. See Figure 9 . | | | 0.15 | 0.25 ⁽¹⁾ | ns |
| t _{BIT} | Transmitter Output Bit Width | T = 1 / OLDI Clock frequency. See Figure 11 . | | | 1/7 * T | | ns |
| t _{PPOS0} | Transmitter Output Pulse Positions Normalized for Bit 0 | | | | 1 | UI ⁽²⁾ | |
| t _{PPOS1} | Transmitter Output Pulse Positions Normalized for Bit 1 | | | | 2 | UI ⁽²⁾ | |
| t _{PPOS2} | Transmitter Output Pulse Positions Normalized for Bit 2 | | | | 3 | UI ⁽²⁾ | |
| t _{PPOS3} | Transmitter Output Pulse Positions Normalized for Bit 3 | | | | 4 | UI ⁽²⁾ | |
| t _{PPOS4} | Transmitter Output Pulse Positions Normalized for Bit 4 | | | | 5 | UI ⁽²⁾ | |
| t _{PPOS5} | Transmitter Output Pulse Positions Normalized for Bit 5 | | | | 6 | UI ⁽²⁾ | |
| t _{PPOS6} | Transmitter Output Pulse Positions Normalized for Bit 6 | | | | 7 | UI ⁽²⁾ | |
| t _{PPOS} | Transmitter Output Pulse Positions (Bit 6 - Bit 0) Normalized | | | | <0.1 | UI ⁽²⁾ | |
| t _{CCS} | Channel-to-Channel Skew | | | 100 | ps | | |
| t _{JCC} | Transmitter Jitter Cycle-to-Cycle | 2-lane FPD-Link III Input, Dual OpenLDI Output | | | 0.16 | UI ⁽²⁾ | |
| | | 2-lane FPD-Link III Input, Single OpenLDI Output | | | 0.18 | UI ⁽²⁾ | |
| | | 1-lane FPD-Link III Input, Dual OpenLDI Output | | | 0.04 | UI ⁽²⁾ | |
| | | 1-lane FPD-Link III Input, Single OpenLDI Output | | | 0.04 | UI ⁽²⁾ | |
| t _{PDD} | Transmitter Power Down Delay | See Figure 5 . | | 100 | ns | | |
| t _{DD} | Deserializer Propagation Delay | T = 1 / OLDI Clock frequency. See Figure 4 . | | 147 * T | ns | | |

(1) Parameter is specified by bench characterization and is not tested in production.

(2) UI - Unit Interval is equal to 1 / (7 * OLDI Clock).

7.10 Timing Diagrams and Test Circuits

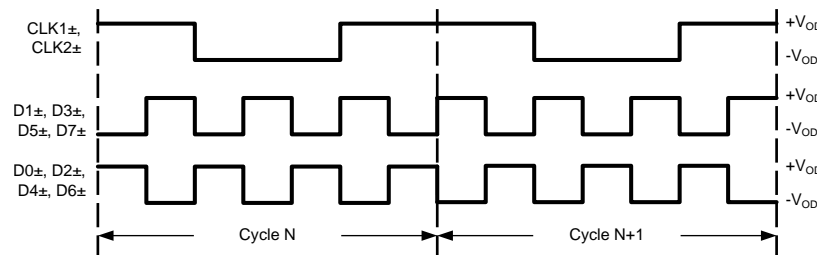


Figure 1. Checkerboard Data Pattern

Timing Diagrams and Test Circuits (continued)

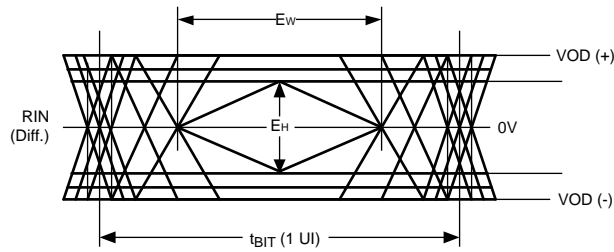


Figure 2. CML Output Driver



Figure 3. LVCMOS Transition Times

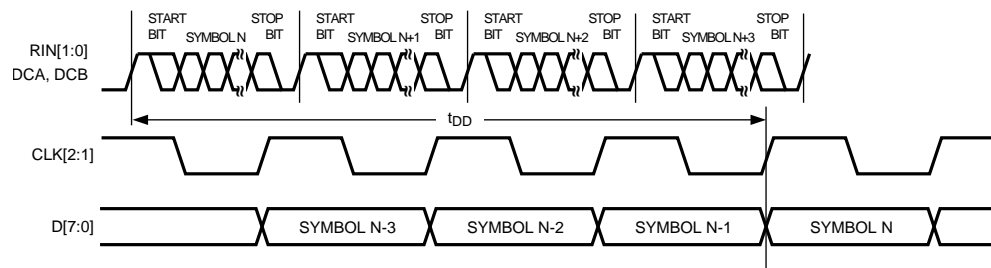


Figure 4. Latency Delay

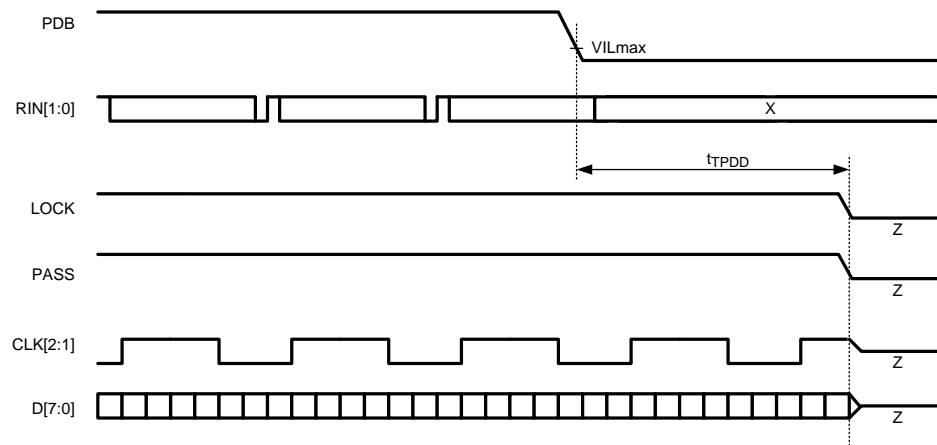


Figure 5. FPD-Link & LVCMOS Power Down Delay

Timing Diagrams and Test Circuits (continued)

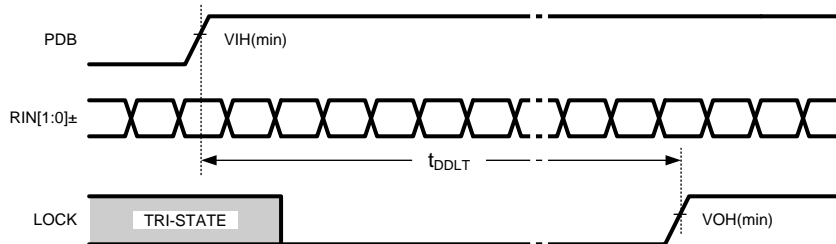


Figure 6. CML PLL Lock Time

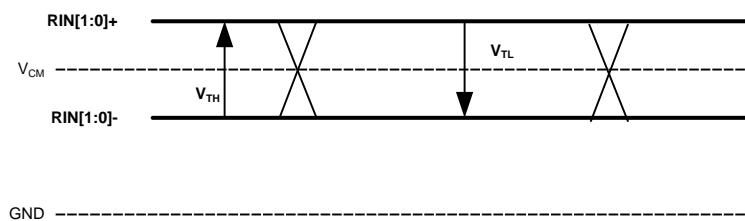


Figure 7. FPD-Link III Receiver DC V_{TH}/V_{TL} Definition

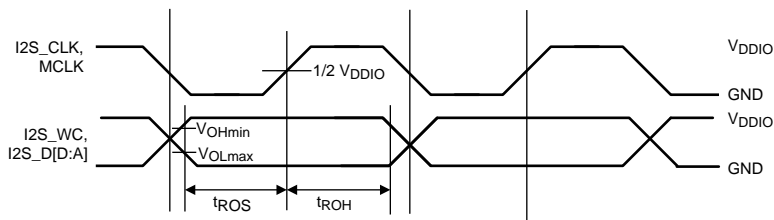


Figure 8. Output Data Valid (Setup and Hold) Times

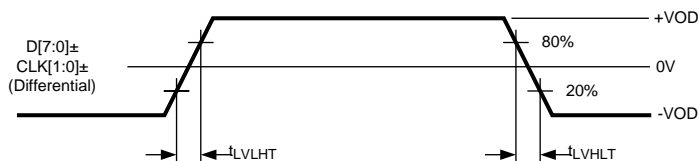


Figure 9. Input Transition Times

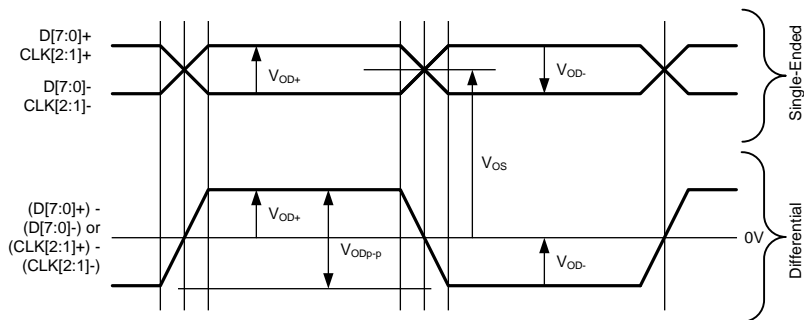


Figure 10. FPD-Link Single-Ended and Differential Waveforms

Timing Diagrams and Test Circuits (continued)

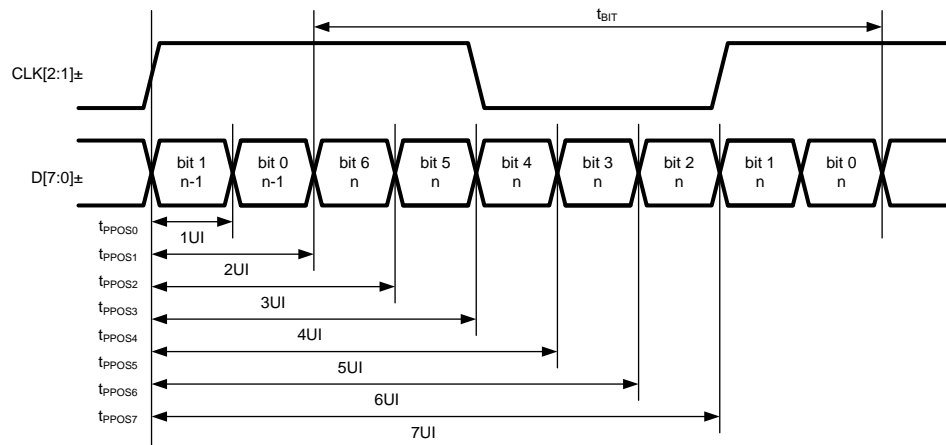


Figure 11. FPD-Link Transmitter Pulse Positions

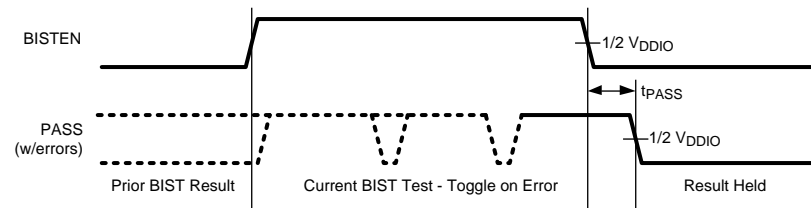


Figure 12. BIST PASS Waveform

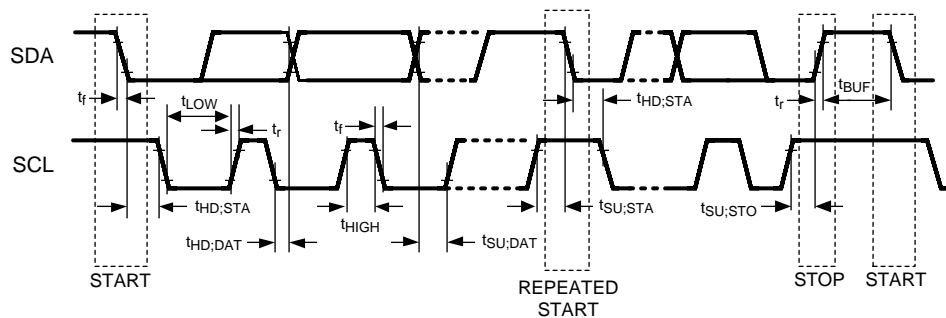


Figure 13. Serial Control Bus Timing Diagram

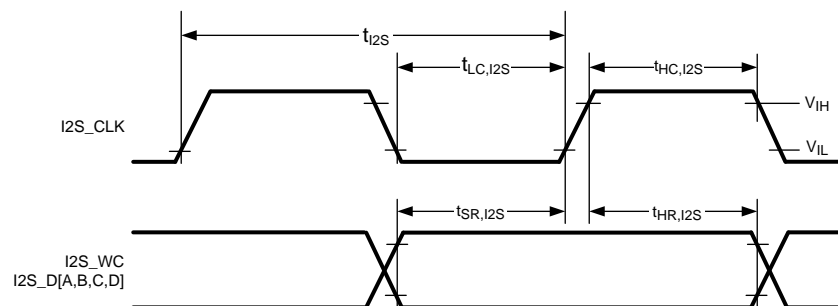
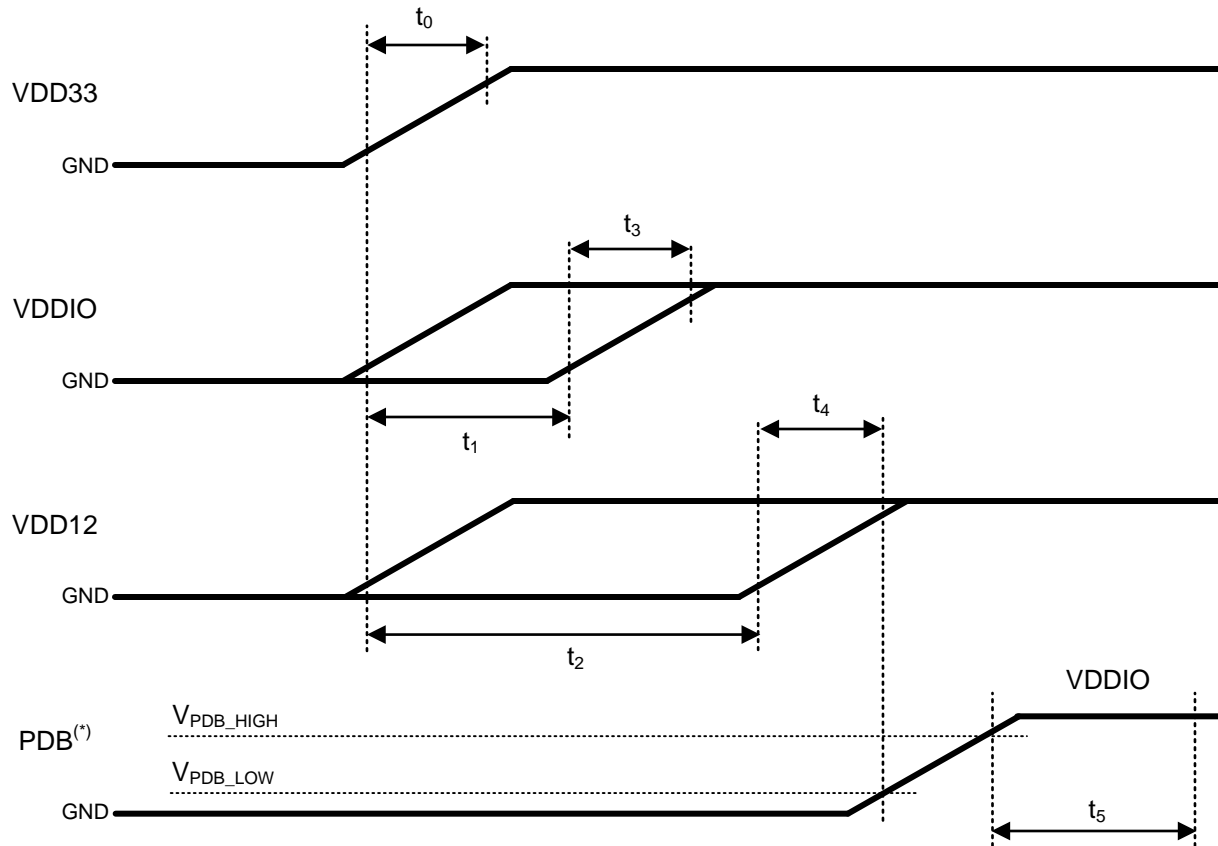


Figure 14. I2S Timing

7.11 Power Sequence



(*) It is recommended to assert PDB (active High) with a microcontroller rather than an RC filter network to help ensure proper sequencing of PDB pin after settling of power supplies.

Figure 15. Power Sequence

Table 1. Power-Up Sequencing Constraints

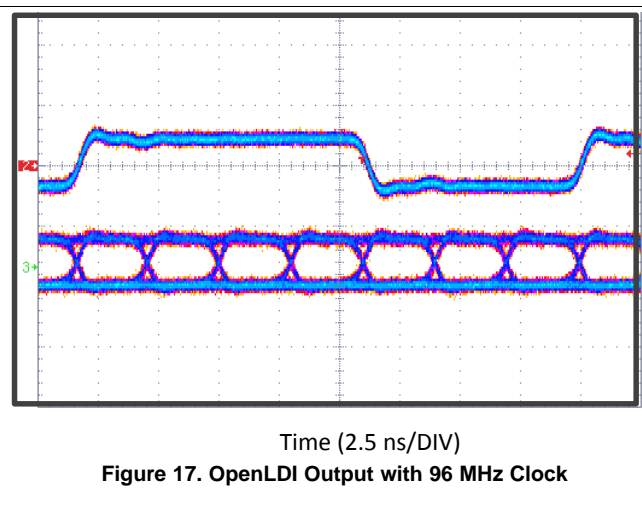
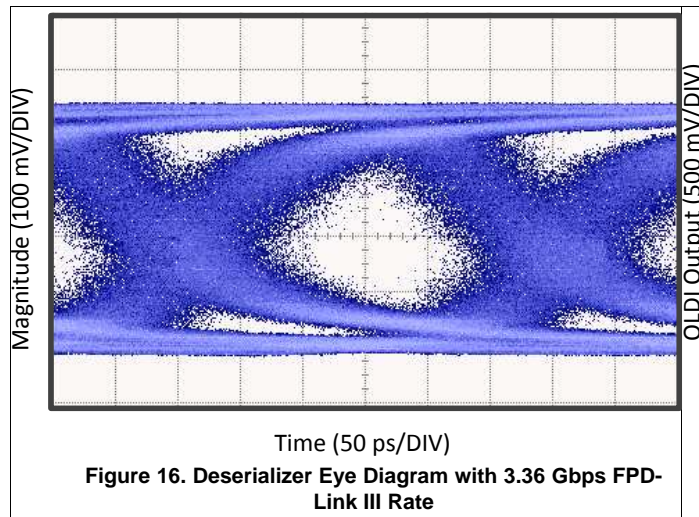
| Symbol | Description | Test Conditions | Min | Typ | Max | Units |
|-----------------|---|---|--------------|-----|--------------|-------|
| VDDIO | VDDIO voltage range | | 3.0 | | 3.6 | V |
| | | | 1.71 | | 1.89 | V |
| VDD33 | VDD33 voltage range | | 3.0 | | 3.6 | V |
| VDD12 | VDD12 voltage range | | 1.14 | | 1.26 | V |
| V_{PDB_LOW} | PDB LOW threshold Note: V_{PDB} should not exceed limit for respective I/O voltage before 90% voltage of VDD12 | VDDIO = 3.3V \pm 10% | 0.8 | | | V |
| | | VDDIO = 1.8V \pm 5% | 0.35 * VDDIO | | | |
| V_{PDB_HIGH} | PDB HIGH threshold | VDDIO = 3.3V \pm 10% | | | 2.0 | V |
| | | VDDIO = 1.8V \pm 5% | | | 0.65 * VDDIO | |
| t_0 | VDD33 rise time | These time constants are specified for rise time of power supply voltage ramp (10% - 90%) | | | <1.5 | ms |
| t_3 | VDDIO rise time | These time constants are specified for rise time of power supply voltage ramp (10% - 90%) | | | <1.5 | ms |

Power Sequence (continued)

Table 1. Power-Up Sequencing Constraints (continued)

| Symbol | Description | Test Conditions | Min | Typ | Max | Units |
|--------|------------------|---|-----|-----|------|-------|
| t_4 | VDD12 rise time | These time constants are specified for rise time of power supply voltage ramp (10% - 90%) | | | <1.5 | ms |
| t_1 | VDDIO delay time | V _{IL} of rising edge (VDDIO) to V _{IL} of rising edge (VDD_N) The power supplies may be ramped simultaneously. If sequenced, VDD33 should be first, either by itself or with VDDIO (1.8V or 3.3V) or VDD12, with the other rail(s) following in any order. | >0 | | | ms |
| t_2 | VDD12 delay time | | | | | |
| t_5 | Startup time | The part is powered up after the startup time has elapsed from the moment PDB goes HIGH. Local I2C is available to read/write 948/940 registers after this time. | | | <1 | ms |

7.12 Typical Characteristics



8 Detailed Description

8.1 Overview

The DS90UB948-Q1 receives a 35-bit symbol over single or dual serial FPD-Link III pairs operating at up to 3.36 Gbps line rate in 1-lane FPD-Link III mode and 2.975 Gbps per lane in 2-lane FPD-Link III mode. The DS90UB948-Q1 converts this stream into a single or dual FPD-Link Interface (4 LVDS data channels + 1 LVDS clock, or 8 LVDS data channels + 2 LVDS clocks). The FPD-Link III serial stream contains an embedded clock, video control signals, and the DC-balanced video data and audio data which enhance signal quality to support AC coupling.

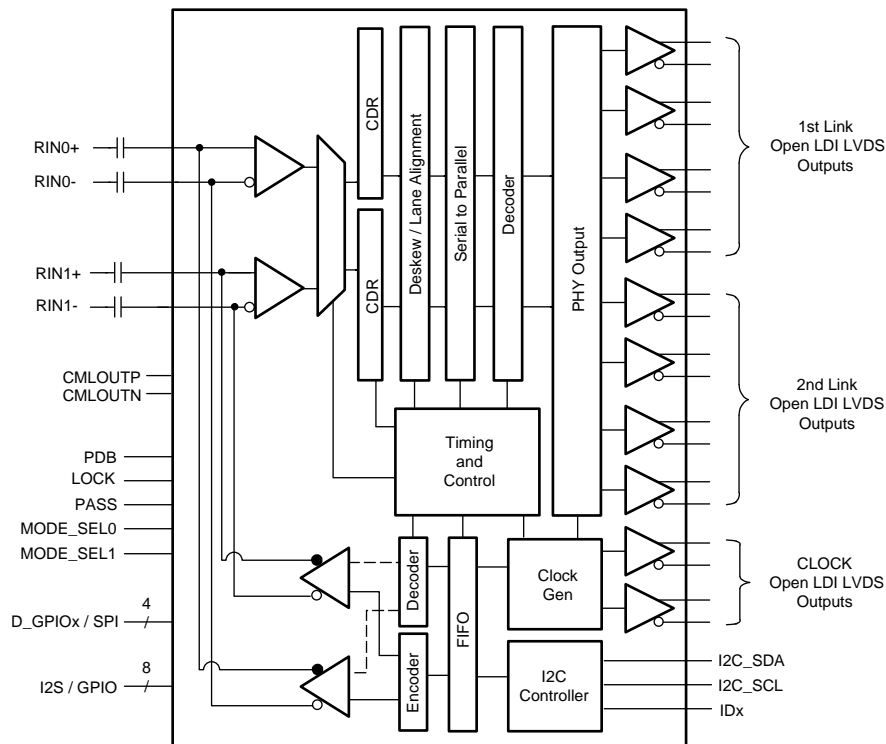
The DS90UB948-Q1 is intended for use with the DS90UB949-Q1 or DS90UB947-Q1 Serializers, but is also backward compatible to the DS90UB925Q-Q1, DS90UB925AQ-Q1, and DS90UB927Q-Q1 FPD-Link III Serializers.

The DS90UB948-Q1 deserializer attains lock to a data stream without the use of a separate reference clock source, which greatly simplifies system complexity and overall cost. The deserializer also synchronizes to the serializer regardless of the data pattern, delivering true automatic “plug and lock” performance. It can lock to the incoming serial stream without the need of special training patterns or sync characters. The deserializer recovers the clock and data by extracting the embedded clock information, validating then deserializing the incoming data stream.

The DS90UB948-Q1 deserializer incorporates an I2C compatible interface. The I2C compatible interface allows programming of serializer or deserializer devices from a local host controller. In addition, the devices incorporate a bidirectional control channel (BCC) that allows communication between serializer/deserializer as well as remote I2C slave devices.

The bidirectional control channel (BCC) is implemented via embedded signaling in the high-speed forward channel (serializer to deserializer) combined with lower speed signaling in the reverse channel (deserializer to serializer). Through this interface, the BCC provides a mechanism to bridge I2C transactions across the serial link from one I2C bus to another. The implementation allows for arbitration with other I2C compatible masters at either side of the serial link.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 High Speed Forward Channel Data Transfer

The High Speed Forward Channel is composed of 35 bits of data containing RGB data, sync signals, I2C, GPIOs, and I2S audio transmitted from serializer to deserializer. [Figure 18](#) illustrates the serial stream per clock cycle. This data payload is optimized for signal transmission over an AC coupled link. Data is randomized, balanced and scrambled.



Figure 18. FPD-Link III Serial Stream

The DS90UB948-Q1 supports clocks in the range of 25 MHz to 96 MHz over a 1-lane, or 50MHz to 170MHz over 2-lanes. The FPD-Link III serial stream rate is 3.36 Gbps maximum (875 Mbps minimum) or 2.975 Gbps maximum per lane (875 Mbps minimum) respectively.

8.3.2 Low Speed Back Channel Data Transfer

The Low-Speed Backward Channel provides bidirectional communication between the display and host processor. The information is carried from the deserializer to the serializer as serial frames. The back channel control data is transferred over both serial links along with the high-speed forward data, DC balance coding and embedded clock information. This architecture provides a backward path across the serial link together with a high speed forward channel. The back channel contains the I2C, CRC and 4 bits of standard GPIO information with 5 or 20 Mbps line rate (configured by MODE_SEL1).

8.3.3 FPD-Link III Port Register Access

Since the DS90UB948-Q1 contains two ports, some registers need to be duplicated to allow control and monitoring of the two ports. To facilitate this, PORT1_SEL and PORT0_SEL bits (0x34[1:0]) register controls access to the two sets of registers. Registers that are shared between ports (not duplicated) will be available independent of the settings in the PORT_SEL register.

Setting the PORT1_SEL and PORT0_SEL bit will allow a read of the register for the selected port. If both bits are set, port1 registers will be returned. Writes will occur to ports for which the select bit is set, allowing simultaneous writes to both ports if both select bits are set.

8.3.4 Oscillator Output

The deserializer provides an optional CLK[2:1]± output when the input clock (serial stream) has been lost. This is based on an internal oscillator and may be controlled from register 0x02, bit 5 (OSC Clock Output Enable). See [Table 11](#).

8.3.5 Clock and Output Status

When PDB is driven HIGH, the CDR PLL begins locking to the serial input and LOCK is tri-state or LOW (depending on the value of the OUTPUT ENABLE setting). After the deserializer completes its lock sequence to the input serial data, the LOCK output is driven HIGH, indicating valid data and clock recovered from the serial input is available on the LVCMOS and LVDS outputs. The State of the outputs is based on the OUTPUT ENABLE and OUTPUT SLEEP STATE SELECT register settings. See register 0x02 in [Table 11](#).

Table 2. Output State Table

| Inputs | | | | Outputs | | | |
|--------------|-----|-------------------------------|--|---------|------|------------------------------|----------------------|
| Serial Input | PDB | OUTPUT ENABLE Reg 0x02 [7] | OUTPUT SLEEP STATE SELECT Reg 0x02 [4] | LOCK | PASS | Data GPIO / D_GPIO I2S | D[7:0] / CLK[2:1] |
| X | L | X | X | Z | Z | Z | Z |
| X | H | L | L | L | L | L | L |
| X | H | L | H | L or H | Z | Z | Z |

Feature Description (continued)

Table 2. Output State Table (continued)

| Inputs | | | | Outputs | | | |
|--------------|-----|-------------------------------|--|---------|-----------------|------------------------------|----------------------|
| Serial Input | PDB | OUTPUT ENABLE Reg 0x02 [7] | OUTPUT SLEEP STATE SELECT Reg 0x02 [4] | LOCK | PASS | Data GPIO / D_GPIO I2S | D[7:0] / CLK[2:1] |
| Static | H | H | L | L | L | L | L/OSC (Register EN) |
| Static | H | H | H | L | Previous Status | L | L |
| Active | H | H | L | L | L | L | L |
| Active | H | H | H | H | Valid | Valid | Valid |

8.3.6 LVCMOS VDDIO Option

The 1.8V or 3.3V Inputs and Outputs are powered from a separate VDDIO supply to offer compatibility with external system interface signals.

NOTE

When configuring the VDDIO power supplies, all the single-ended data and control input pins for device need to scale together with the same operating VDDIO levels.

8.3.7 Power Down (PDB)

The deserializer has a PDB input pin to ENABLE or POWER DOWN the device. This pin can be controlled by the host or through the VDDIO, where VDDIO = 3.0V to 3.6 V or VDD33. To save power, disable the link when the display is not needed (PDB = LOW). When the pin is driven by the host, make sure to release it after VDD33 and VDDIO have reached final levels; no external components are required. In the case of driven by the VDDIO = 3.0 V to 3.6 V or VDD33 directly, a 10kΩ resistor to the VDDIO = 3.0 V to 3.6 V or VDD33, and a >10 μF capacitor to the GND are required (see [Figure 47](#) Typical Connection Diagram).

8.3.8 Interrupt Pin — Functional Description and Usage (INTB_IN)

The INTB_IN pin is an active low interrupt input pin. This interrupt signal, when configured, will propagate to the paired serializer. Consult the appropriate Serializer datasheet for details of how to configure this interrupt functionality.

1. On the Serializer, set register 0xC6[5] = 1 and 0xC6[0] = 1
2. Deserializer INTB_IN (pin 4) is set *LOW* by some downstream device.
3. Serializer pulls INTB pin *LOW*. The signal is active *LOW*, so a *LOW* indicates an interrupt condition.
4. External controller detects INTB = *LOW*; to determine interrupt source, read ISR register.
5. A read to ISR will clear the interrupt at the Serializer, releasing INTB.
6. The external controller typically must then access the remote device to determine downstream interrupt source and clear the interrupt driving the Deserializer INTB_IN. This would be when the downstream device releases the INTB_IN (pin 4) on the Deserializer. The system is now ready to return to step (2) at next falling edge of INTB_IN.

8.3.9 General-purpose I/O

8.3.9.1 GPIO[3:0] and D_GPIO[3:0] Configuration

In normal operation, GPIO[3:0] may be used as general purpose IOs in either forward channel (outputs) or back channel (inputs) mode. GPIO and D_GPIO modes may be configured from the registers ([Table 10](#)). The same registers configure either GPIO or D_GPIO, depending on the status of PORT1_SEL and PORT0_SEL bits (0x34[1:0]). D_GPIO operation requires 2-lane FPD-Link III mode. Consult the appropriate Serializer datasheet for details on D_GPIO configuration. Note: if paired with a DS90UB925Q-Q1serializer, the devices must be configured into 18-bit mode to allow usage of GPIO pins on the serializer. To enable 18-bit mode, set serializer register 0x12[2] = 1. 18-bit mode will be auto-loaded into the deserializer from the serializer. See [Table 3](#) for GPIO enable and configuration.

Table 3. GPIO Enable and Configuration

| Description | Device | Forward Channel | Back Channel |
|-----------------|--------------|-----------------|-----------------|
| GPIO3 / D_GPIO3 | Serializer | 0x0F[3:0] = 0x3 | 0x0F[3:0] = 0x5 |
| | Deserializer | 0x1F[3:0] = 0x5 | 0x1F[3:0] = 0x3 |
| GPIO2 / D_GPIO2 | Serializer | 0x0E[7:4] = 0x3 | 0x0E[7:4] = 0x5 |
| | Deserializer | 0x1E[7:4] = 0x5 | 0x1E[7:4] = 0x3 |
| GPIO1 / D_GPIO1 | Serializer | 0x0E[3:0] = 0x3 | 0x0E[3:0] = 0x5 |
| | Deserializer | 0x1E[3:0] = 0x5 | 0x1E[3:0] = 0x3 |
| GPIO0 / D_GPIO0 | Serializer | 0x0D[3:0] = 0x3 | 0x0D[3:0] = 0x5 |
| | Deserializer | 0x1D[3:0] = 0x5 | 0x1D[3:0] = 0x3 |

The input value present on GPIO[3:0] or D_GPIO[3:0] may also be read from register, or configured to local output mode (Table 10).

8.3.9.2 Back Channel Configuration

The D_GPIO[3:0] pins can be configured to obtain different sampling rates depending on the mode as well as back channel frequency. The mode is controlled by register 0x43 (Table 10). The back channel frequency can be controlled several ways:

1. Register 0x23[6] sets the divider that controls the back channel frequency based on the internal oscillator. 0x23[6] = 0 sets the divider to 4 and 0x23[6] = 1 sets the divider to 2. As long as BC_HS_CTL (0x23[4]) is set to 0, the back channel frequency would be either 5 Mbps or 10Mbps based on this bit.
2. Register 0x23[4] enables the high-speed back channel. This can also be pin-strapped via MODE_SEL1 (See Table 4). This bit overrides 0x23[6], and sets the divider for the back channel frequency to 1. Setting this bit to 1 sets the back channel frequency to 20 Mbps.

The back channel frequency has variation of $\pm 20\%$. Note: The back channel frequency must be set to 5 Mbps when paired with a DS90UB925Q-Q1, DS90UB925AQ-Q1, or DS90UB927Q-Q1. See Table 4 for details about configuring the D_GPIOs in various modes.

Table 4. Back Channel D_GPIO Effective Frequency

| HSCC_MODE (0x43[2:0]) | Mode | Number of D_GPIOs | Samples per Frame | D_GPIO Effective Frequency ⁽¹⁾ (kHz) | | | D_GPIOs Allowed |
|--------------------------|--------|----------------------|----------------------|---|---------------------------|---------------------------|--------------------|
| | | | | 5 Mbps BC ⁽²⁾ | 10 Mbps BC ⁽³⁾ | 20 Mbps BC ⁽⁴⁾ | |
| 000 | Normal | 4 | 1 | 33 | 66 | 133 | D_GPIO[3:0] |
| 011 | Fast | 4 | 6 | 200 | 400 | 800 | D_GPIO[3:0] |
| 010 | Fast | 2 | 10 | 333 | 666 | 1333 | D_GPIO[1:0] |
| 001 | Fast | 1 | 15 | 500 | 1000 | 2000 | D_GPIO0 |

(1) The effective frequency assumes the worst case back channel frequency ($\sim 20\%$) and a 4X sampling rate.

(2) 5 Mbps corresponds to BC_FREQ_SELECT = 0 & BC_HS_CTL = 0

(3) 10 Mbps corresponds to BC_FREQ_SELECT = 1 & BC_HS_CTL = 0

(4) 20 Mbps corresponds to BC_FREQ_SELECT = X & BC_HS_CTL = 1

8.3.9.3 GPIO_REG[8:5] Configuration

GPIO_REG[8:5] are register-only GPIOs and may be programmed as outputs or read as inputs through local register bits only. Where applicable, these bits are shared with I2S pins and will override I2S input if enabled into GPIO_REG mode. See Table 5 for GPIO enable and configuration.

Note: Local GPIO value may be configured and read either through local register access, or remote register access through the Low-Speed Bidirectional Control Channel. Configuration and state of these pins are not transported from serializer to deserializer as is the case for GPIO[3:0].

Table 5. GPIO_REG and GPIO Local Enable and Configuration

| Description | Register Configuration | Function |
|-------------|------------------------|----------------------|
| GPIO_REG8 | 0x21[7:4] = 0x1 | Output, L |
| | 0x21[7:4] = 0x9 | Output, H |
| | 0x21[7:4] = 0x3 | Input, Read: 0x6F[0] |

Table 5. GPIO_REG and GPIO Local Enable and Configuration (continued)

| Description | Register Configuration | Function |
|-------------|------------------------|----------------------|
| GPIO_REG7 | 0x21[3:0] = 0x1 | Output, L |
| | 0x21[3:0] = 0x9 | Output, H |
| | 0x21[3:0] = 0x3 | Input, Read: 0x6E[7] |
| GPIO_REG6 | 0x20[7:4] = 0x1 | Output, L |
| | 0x20[7:4] = 0x9 | Output, H |
| | 0x20[7:4] = 0x3 | Input, Read: 0x6E[6] |
| GPIO_REG5 | 0x20[3:0] = 0x1 | Output, L |
| | 0x20[3:0] = 0x9 | Output, H |
| | 0x20[3:0] = 0x3 | Input, Read: 0x6E[5] |
| GPIO3 | 0x1F[3:0] = 0x1 | Output, L |
| | 0x1F[3:0] = 0x9 | Output, H |
| | 0x1F[3:0] = 0x3 | Input, Read: 0x6E[3] |
| GPIO2 | 0x1E[7:4] = 0x1 | Output, L |
| | 0x1E[7:4] = 0x9 | Output, H |
| | 0x1E[7:4] = 0x3 | Input, Read: 0x6E[2] |
| GPIO1 | 0x1E[3:0] = 0x1 | Output, L |
| | 0x1E[3:0] = 0x9 | Output, H |
| | 0x1E[3:0] = 0x3 | Input, Read: 0x6E[1] |
| GPIO0 | 0x1D[3:0] = 0x1 | Output, L |
| | 0x1D[3:0] = 0x9 | Output, H |
| | 0x1D[3:0] = 0x3 | Input, Read: 0x6E[0] |

8.3.10 SPI Communication

The SPI Control Channel utilizes the secondary link in a 2-lane FPD-Link III implementation. Two possible modes are available, Forward Channel and Reverse Channel modes. In Forward Channel mode, the SPI Master is located at the Serializer, such that the direction of sending SPI data is in the same direction as the video data. In Reverse Channel mode, the SPI Master is located at the Deserializer, such that the direction of sending SPI data is in the opposite direction as the video data.

The SPI Control Channel can operate in a high speed mode when writing data, but must operate at lower frequencies when reading data. During SPI reads, data is clocked from the slave to the master on the SPI clock falling edge. Thus, the SPI read must operate with a clock period that is greater than the round trip data latency. On the other hand, for SPI writes, data can be sent at much higher frequencies where the MISO pin can be ignored by the master.

SPI data rates are not symmetrical for the two modes of operation. Data over the forward channel can be sent much faster than data over the reverse channel.

Note: SPI cannot be used to access Serializer / Deserializer registers.

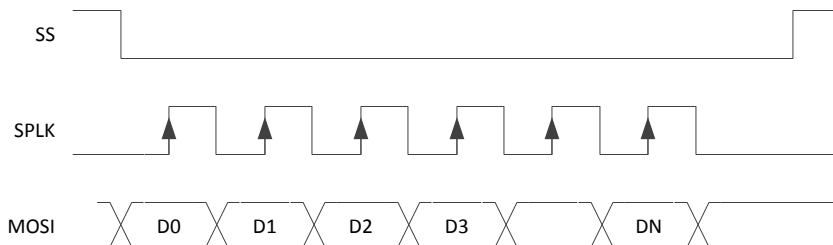
8.3.10.1 SPI Mode Configuration

SPI is configured over I2C using the High-Speed Control Channel Configuration (HSCC_CONTROL) register, 0x43 (Table 11). HSCC_MODE (0x43[2:0]) must be configured for either High-Speed, Forward Channel SPI mode (110) or High-Speed, Reverse Channel SPI mode (111).

8.3.10.2 Forward Channel SPI Operation

In Forward Channel SPI operation, the SPI master located at the Serializer generates the SPI Clock (SPLK), Master Out / Slave In data (MOSI), and active low Slave Select (SS). The Serializer oversamples the SPI signals directly using the video pixel clock. The three sampled values for SPLK, MOSI, and SS are each sent on data bits in the forward channel frame. At the Deserializer, the SPI signals are regenerated using the pixel clock. In order to preserve setup and hold time, the Deserializer will hold MOSI data while the SPLK signal is high. In addition, it delays SPLK by one pixel clock relative to the MOSI data, increasing setup by one pixel clock.

SERIALIZER



DESERIALIZER

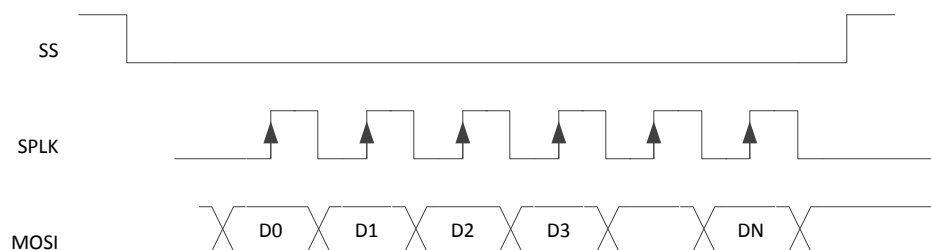
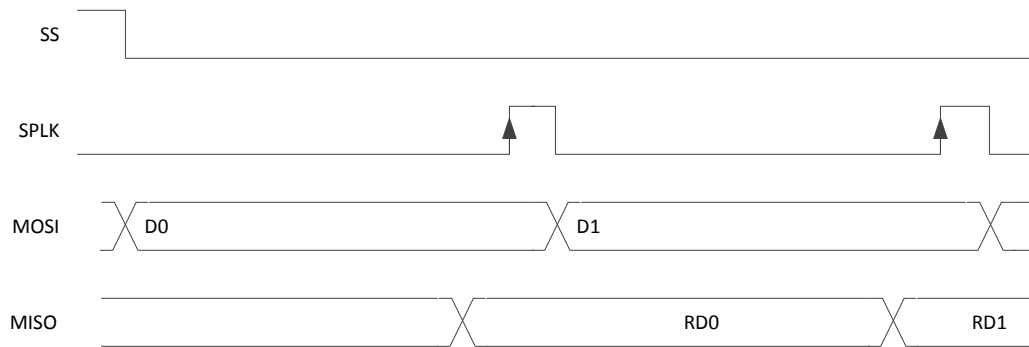


Figure 19. Forward Channel SPI Write

SERIALIZER



DESERIALIZER

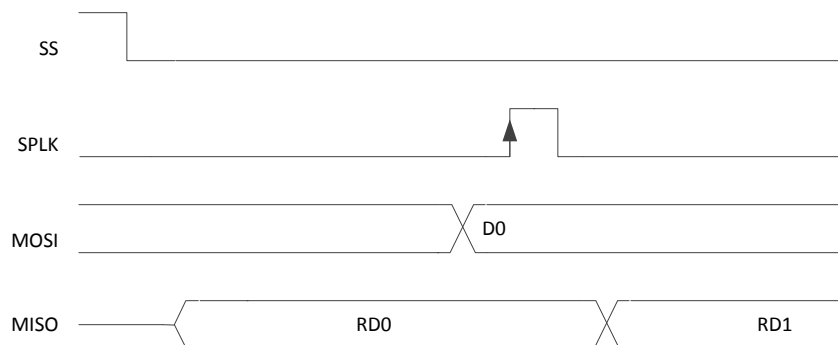
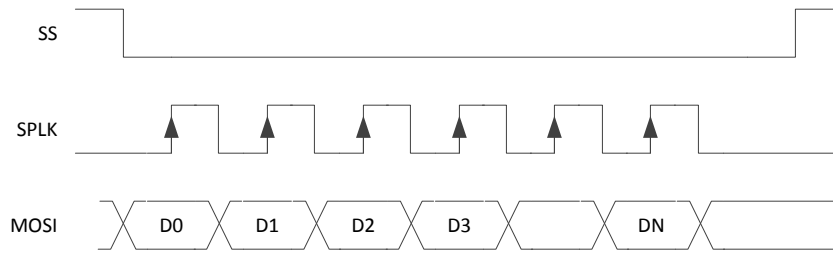
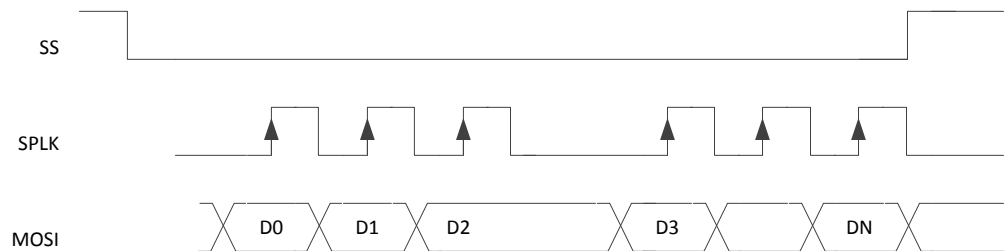


Figure 20. Forward Channel SPI Read

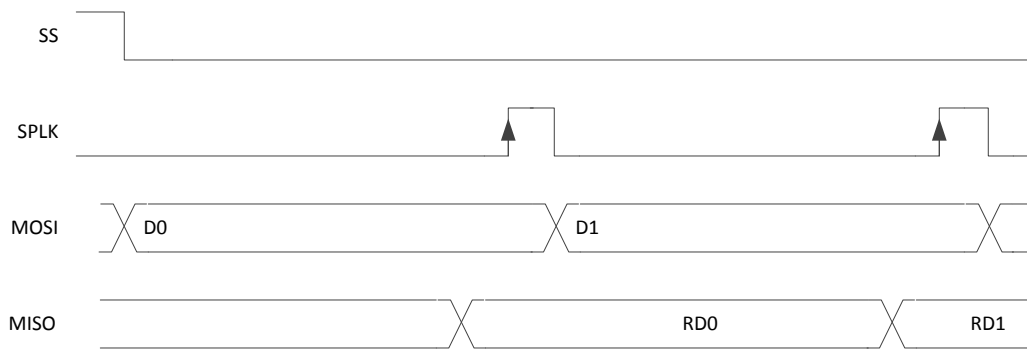
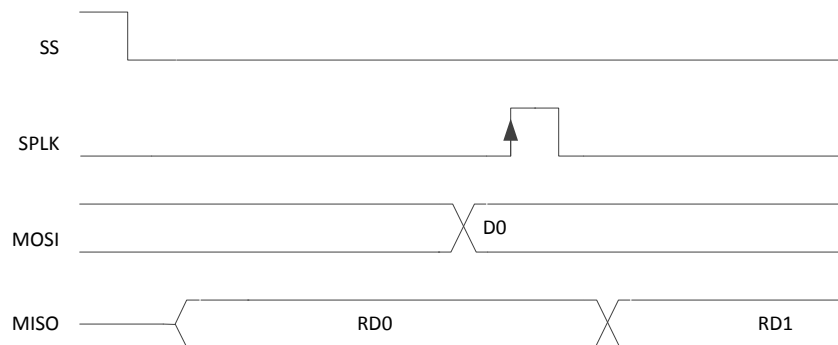
8.3.10.3 Reverse Channel SPI Operation

In Reverse Channel SPI operation, the Deserializer samples the Slave Select (SS), SPI clock (SCLK) into the internal oscillator clock domain. In addition, upon detection of the active SPI clock edge, the Deserializer samples the SPI data (MOSI). The SPI data samples are stored in a buffer to be passed to the Serializer over the back channel. The Deserializer sends SPI information in a back channel frame to the Serializer. In each back channel frame, the Deserializer sends an indication of the Slave Select value. The Slave Select should be inactive (high) for at least one back-channel frame period to ensure propagation to the Serializer.

Because data is delivered in separate back channel frames and buffered, the data may be regenerated in bursts. The following figure (Figure 21) shows an example of the SPI data regeneration when the data arrives in three back channel frames. The first frame delivered the SS active indication, the second frame delivered the first three data bits, and the third frame delivers the additional data bits.

DESERIALIZER

SERIALIZER

Figure 21. Reverse Channel SPI Write

For Reverse Channel SPI reads, the SPI master must wait for a round-trip response before generating the sampling edge of the SPI clock. This is similar to operation in Forward channel mode. Note that at most one data/clock sample will be sent per back channel frame.

DESERIALIZER

SERIALIZER

Figure 22. Reverse Channel SPI Read

For both Reverse Channel SPI writes and reads, the SPI_SS signal should be deasserted for at least one back channel frame period.

Table 6. SPI SS Deassertion Requirement

| Back Channel Frequency | Deassertion Requirement |
|------------------------|-------------------------|
| 5 Mbps | 7.5 μ s |
| 10 Mbps | 3.75 μ s |
| 20 Mbps | 1.875 μ s |

8.3.11 Backward Compatibility

The DS90UB948-Q1 is also backward compatible to the DS90UB925Q-Q1, DS90UB925AQ-Q1, and DS90UB927Q-Q1 for PCLK frequencies ranging from 25MHz to 85MHz. Backward compatibility does not need to be enabled. When paired with a backward compatible device, the Deserializer will auto-detect to 1-lane FPD-Link III on the primary channel (RIN0 \pm).

8.3.12 Input Equalization

An FPD-Link III input adaptive equalizer provides compensation for transmission medium losses and reduces medium-induced deterministic jitter. It equalizes up to 15m STP or 50 Ω Coaxial cables with 3 connection breaks at maximum serializer stream payload of 3.36 Gbps.

8.3.13 I2S Audio Interface

This Deserializer features six I2S output pins that, when paired with a compatible serializer, supports surround sound audio applications. The bit clock (I2S_CLK) supports frequencies between 1MHz and the smaller of <PCLK/2 or <13MHz. Four I2S data outputs carry two channels of I2S-formatted digital audio each, with each channel delineated by the word select (I2C_WC) input.

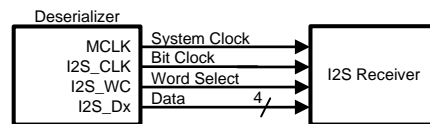


Figure 23. I2S Connection Diagram

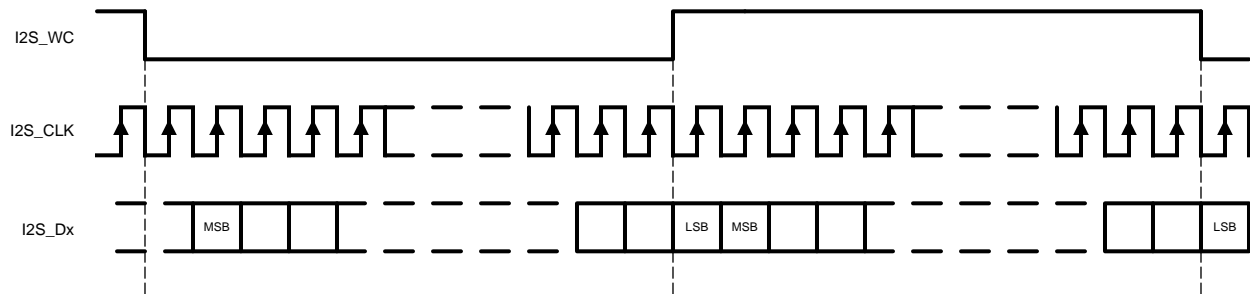


Figure 24. I2S Frame Timing Diagram

When paired with a DS90UB925Q, the Deserializer I2S interface supports a single I2S data output through I2S_DA (24-bit video mode), or two I2S data outputs through I2S_DA and I2S_DB (18-bit video mode).

8.3.13.1 I2S Transport Modes

By default, packetized audio is received during video blanking periods in dedicated Data Island Transport frames. The transport mode is set in the serializer and auto-loaded into the deserializer by default. The audio configuration may be disabled from control registers if Forward Channel Frame Transport of I2S data is desired. In frame transport, only I2S_DA is received to the Deserializer. Surround Sound Mode, which transmits all four I2S data inputs (I2S_D[D:A]), may only be operated in Data Island Transport mode. This mode is only available when connected to a DS90UB927Q, DS90UB949-Q1, DS90UB947-Q1, or DS90UB929-Q1 serializer. If connected to a DS90UB925Q serializer, only I2S_DA and I2S_DB may be received.

8.3.13.2 I2S Repeater

I2S audio may be fanned-out and propagated in the repeater application. By default, data is propagated via Data Island Transport on the FPD-Link interface during the video blanking periods. If frame transport is desired, then the I2S pins should be connected from the deserializer to all serializers. Activating surround sound at the top-level serializer automatically configures downstream serializers and deserializers for surround sound transport utilizing Data Island Transport. If 4-channel operation utilizing I2S_DA and I2S_DB only is desired, this mode must be explicitly set in each serializer and deserializer control register throughout the repeater tree (Table 11).

A DS90UB948-Q1 deserializer configured in repeater mode may also regenerate I2S audio from its I2S input pins in lieu of Data Island frames. See the Repeater Connection Diagram (Figure 27) and the I2C Control Registers (Table 11) for additional details.

8.3.13.3 I2S Jitter Cleaning

This device features a standalone PLL to clean the I2S data jitter, supporting high-end car audio systems. If I2S_CLK frequency is less than 1MHz, this feature must be disabled through register 0x2B[7]. See Table 11.

8.3.13.4 MCLK

The deserializer has an I2S Master Clock Output (MCLK). It supports x1, x2, or x4 of I2S CLK Frequency. When the I2S PLL is disabled, the MCLK output is off. Table 7 covers the range of I2S sample rates and MCLK frequencies. By default, all the MCLK output frequencies are x2 of the I2S CLK frequencies. The MCLK frequencies can also be enabled through the register bits 0x3A[6:4] (I2S_DIVSEL), shown in Table 11. To select desired MCLK frequency, write 0x3A[7], then write to bit [6:4] accordingly.

Table 7. Audio Interface Frequencies

| Sample Rate (kHz) | I2S Data Word Size (bits) | I2S_CLK (MHz) | MCLK Output (MHz) | Register 0x3A[6:4] |
|-------------------|---------------------------|---------------|-------------------|--------------------|
| 32 | 16 | 1.024 | I2S_CLK x1 | 000 |
| | | | I2S_CLK x2 | 001 |
| | | | I2S_CLK x4 | 010 |
| 44.1 | | 1.4112 | I2S_CLK x1 | 000 |
| | | | I2S_CLK x2 | 001 |
| | | | I2S_CLK x4 | 010 |
| 48 | | 1.536 | I2S_CLK x1 | 000 |
| | | | I2S_CLK x2 | 001 |
| | | | I2S_CLK x4 | 010 |
| 96 | | 3.072 | I2S_CLK x1 | 001 |
| | | | I2S_CLK x2 | 010 |
| | | | I2S_CLK x4 | 011 |
| 192 | 6.144 | I2S_CLK x1 | 010 | |
| | | I2S_CLK x2 | 011 | |
| | | I2S_CLK x4 | 100 | |

Table 7. Audio Interface Frequencies (continued)

| Sample Rate (kHz) | I2S Data Word Size (bits) | I2S_CLK (MHz) | MCLK Output (MHz) | Register 0x3A[6:4] |
|-------------------|---------------------------|---------------|-------------------|--------------------|
| 32 | 24 | 1.536 | I2S_CLK x1 | 000 |
| | | | I2S_CLK x2 | 001 |
| | | | I2S_CLK x4 | 010 |
| 44.1 | | 2.117 | I2S_CLK x1 | 001 |
| | | | I2S_CLK x2 | 010 |
| | | | I2S_CLK x4 | 011 |
| 48 | | 2.304 | I2S_CLK x1 | 001 |
| | | | I2S_CLK x2 | 010 |
| | | | I2S_CLK x4 | 011 |
| 96 | | 4.608 | I2S_CLK x1 | 010 |
| | | | I2S_CLK x2 | 011 |
| | | | I2S_CLK x4 | 100 |
| 192 | | 9.216 | I2S_CLK x1 | 011 |
| | | | I2S_CLK x2 | 100 |
| | | | I2S_CLK x4 | 101 |
| 32 | 32 | 2.048 | I2S_CLK x1 | 001 |
| | | | I2S_CLK x2 | 010 |
| | | | I2S_CLK x4 | 011 |
| 44.1 | | 2.8224 | I2S_CLK x1 | 001 |
| | | | I2S_CLK x2 | 010 |
| | | | I2S_CLK x4 | 011 |
| 48 | | 3.072 | I2S_CLK x1 | 001 |
| | | | I2S_CLK x2 | 010 |
| | | | I2S_CLK x4 | 011 |
| 96 | | 6.144 | I2S_CLK x1 | 010 |
| | | | I2S_CLK x2 | 011 |
| | | | I2S_CLK x4 | 100 |
| 192 | | 12.288 | I2S_CLK x1 | 011 |
| | | | I2S_CLK x2 | 100 |
| | | | I2S_CLK x4 | 110 |

8.3.14 Repeater

The supported Repeater application provides a mechanism to extend transmission over multiple links to multiple display devices.

8.3.14.1 Repeater Configuration

In the repeater application, this document refers to the DS90UB947-Q1 Serializer or as the Transmitter (TX), and refers to the DS90UB948-Q1 as the Receiver (RX). [Figure 25](#) shows the maximum configuration supported for Repeater implementations. Two levels of Repeaters are supported with a maximum of three Transmitters per Receiver.

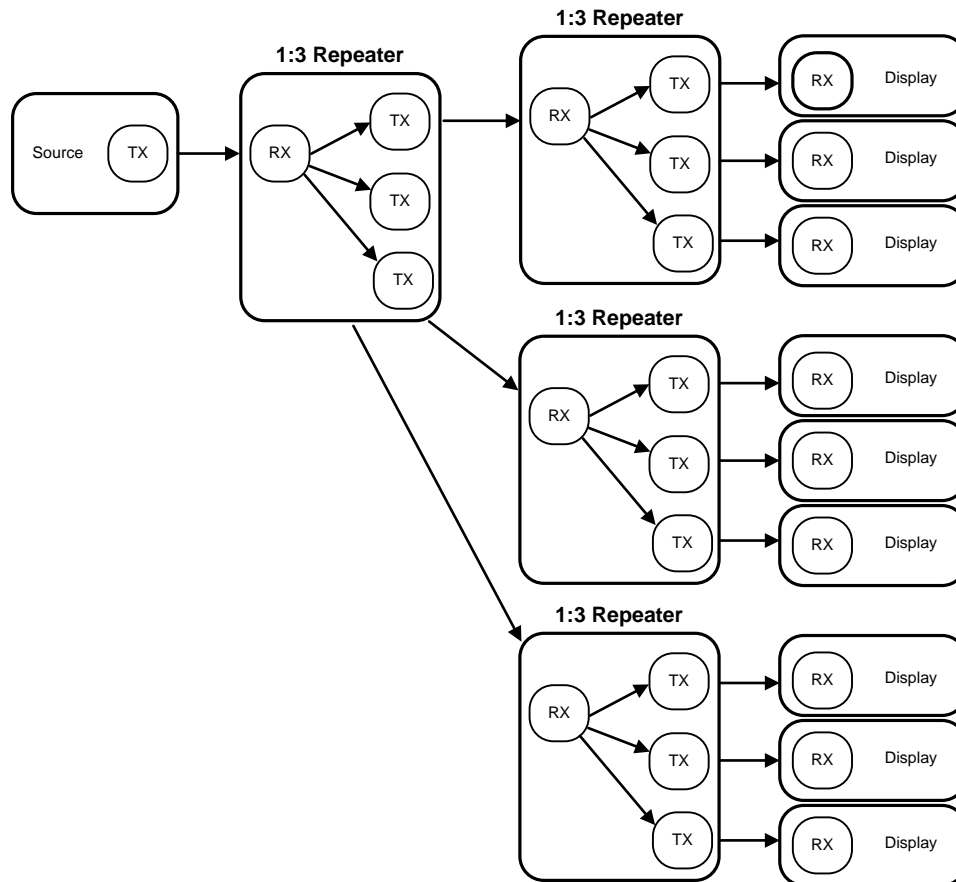
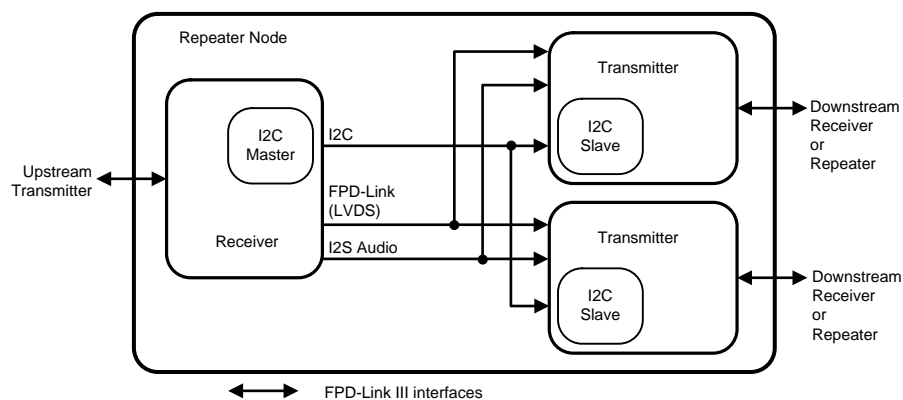


Figure 25. Maximum Repeater Application

In a repeater application, the I2C interface at each TX and RX is configured to transparently pass I2C communications upstream or downstream to any I2C device within the system. This includes a mechanism for assigning alternate IDs (Slave Aliases) to downstream devices in the case of duplicate addresses.



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Figure 26. 1:2 Repeater Configuration

8.3.14.2 Repeater Connections

The Repeater requires the following connections between the Receiver and each Transmitter [Figure 27](#).

1. Video Data – Connect all FPD-Link data and clock pairs. Single FPD-Link (D[3:0]) or Dual FPD-Link (D[7:0])

- are both possible, provided the Deserializer and all Serializers are configured in the same mode.
2. I2C – Connect SCL and SDA signals. Both signals should be pulled up to VDD33 or VDDIO = 3.0 V to 3.6 V with 4.7kΩ resistors.
 3. Audio (optional) – Connect I2S_CLK, I2S_WC, and I2S_Dx signals. Audio is normally transported on the FPD-Link interface.
 4. IDx pin – Each Transmitter and Receiver must have an unique I2C address.
 5. REPEAT & MODE_SEL pins — All Transmitters and Receivers must be set into Repeater Mode.
 6. Interrupt pin – Connect DS90UB948-Q1 INTB_IN pin to the DS90UB947-Q1 INTB pin. The signal must be pulled up to VDDIO with a 10kΩ resistor.

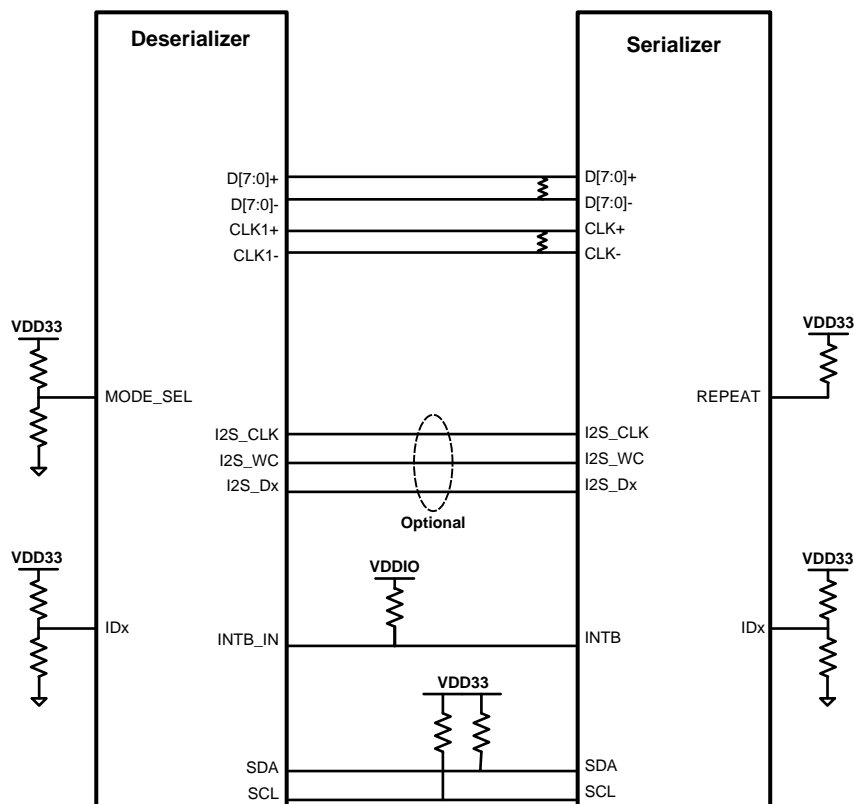


Figure 27. Repeater Connection Diagram

8.3.14.2.1 Repeater Fan-out Electrical Requirements

Repeater applications requiring fan-out from one DS90UB948-Q1 Deserializer to up to three DS90UB947-Q1 Serializers requires special considerations for routing and termination of the FPD-Link differential traces. [Figure 28](#) details the requirements that must be met for each signal pair:

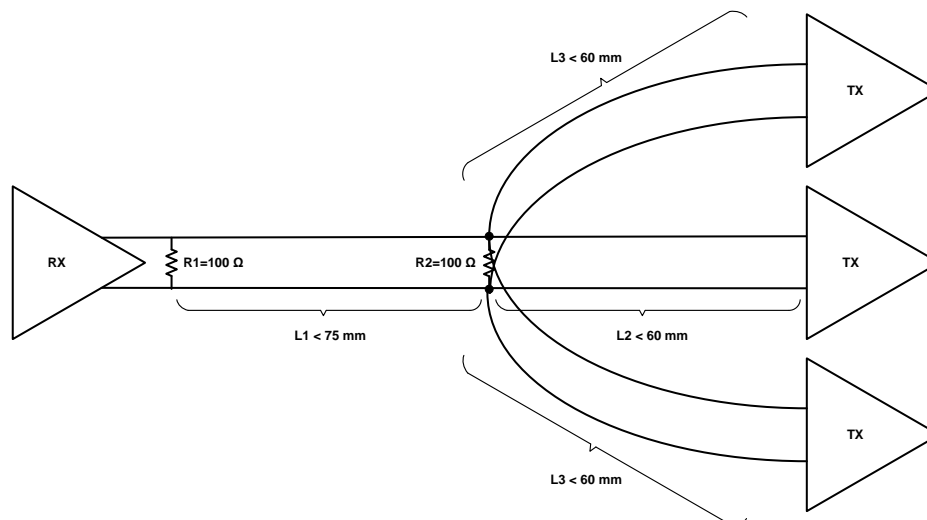


Figure 28. FPD-Link Fan-Out Electrical Requirements

8.3.15 Built-In Self Test (BIST)

An optional At-Speed Built-In Self Test (BIST) feature supports testing of the high speed serial link and the low-speed back channel without external data connections. This is useful in the prototype stage, equipment production, in-system test, and system diagnostics.

8.3.15.1 BIST Configuration And Status

The BIST mode is enabled at the deserializer by pin (BISTEN) or BIST configuration register. The test may select either an external PCLK or the 33 MHz internal Oscillator clock (OSC) frequency in the Serializer. In the absence of PCLK, the user can select the internal OSC frequency at the deserializer through the BISTC pin or BIST configuration register.

When BIST is activated at the deserializer, a BIST enable signal is sent to the serializer through the Back Channel. The serializer outputs a test pattern and drives the link at speed. The deserializer detects the test pattern and monitors it for errors. The deserializer PASS output pin toggles to flag each frame received containing one or more errors. The serializer also tracks errors indicated by the CRC fields in each back channel frame.

The BIST status can be monitored real time on the deserializer PASS pin, with each detected error resulting in a half pixel clock period toggled LOW. After BIST is deactivated, the result of the last test is held on the PASS output until reset (new BIST test or Power Down). A high on PASS indicates NO ERRORS were detected. A Low on PASS indicates one or more errors were detected. The duration of the test is controlled by the pulse width applied to the deserializer BISTEN pin. LOCK status is valid throughout the entire duration of BIST.

See [Figure 29](#) for the BIST mode flow diagram.

8.3.15.1.1 Sample BIST Sequence

Note: Before BIST can be enabled, D_GPIO0 (pin 19) must be strapped HIGH and D_GPIO[3:1] (pins 16, 17, and 18) must be strapped LOW.

1. BIST Mode is enabled via the BISTEN pin of Deserializer. The desired clock source is selected through the deserializer BISTC pin.
2. The serializer is awakened through the back channel if it is not already on. An all-zeros pattern is balanced, scrambled, randomized, and sent through the FPD-Link III interface to the deserializer. Once the serializer and the deserializer are in BIST mode and the deserializer acquires LOCK, the PASS pin of the deserializer goes high and BIST starts checking the data stream. If an error in the payload (1 to 35) is detected, the PASS pin will switch low for one half of the clock period. During the BIST test, the PASS output can be monitored and counted to determine the payload error rate per 35 bits.
3. To Stop BIST mode, set the BISTEN pin LOW. The deserializer stops checking the data, and the final test

result is held on the PASS pin. If the test ran error free, the PASS output will remain HIGH. If there one or more errors were detected, the PASS output will output constant LOW. The PASS output state is held until a new BIST is run, the device is RESET, or the device is powered down. BIST duration is user-controlled and may be of any length.

The link returns to normal operation after the deserializer BISTEN pin is low. Figure 30 shows the waveform diagram of a typical BIST test for two cases. Case 1 is error free, and Case 2 shows one with multiple errors. In most cases it is difficult to generate errors due to the robustness of the link (differential data transmission etc.), thus they may be introduced by greatly extending the cable length, faulting the interconnect medium, or reducing signal condition enhancements (Rx Equalization).

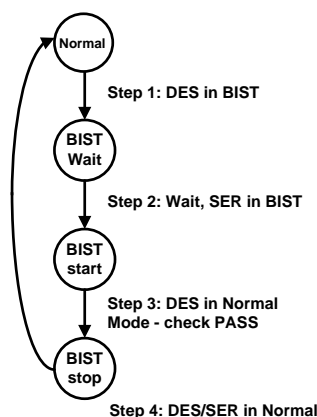


Figure 29. BIST Mode Flow Diagram

8.3.15.2 Forward Channel and Back Channel Error Checking

The Deserializer, on locking to the serial stream, compares the recovered serial stream with all-zeroes and records any errors in status registers. Errors are also dynamically reported on the PASS pin of the deserializer. Forward channel errors may also be read from register 0x25 (Table 11).

The back-channel data is checked for CRC errors once the serializer locks onto the back-channel serial stream, as indicated by link detect status (register bit 0x0C[0] - Table 11). CRC errors are recorded in an 8-bit register in the serializer. The register is cleared when the serializer enters the BIST mode. As soon as the serializer enters BIST mode, the functional mode CRC register starts recording any back channel CRC errors. The BIST mode CRC error register is active in BIST mode only and keeps the record of the last BIST run until cleared or the serializer enters BIST mode again.

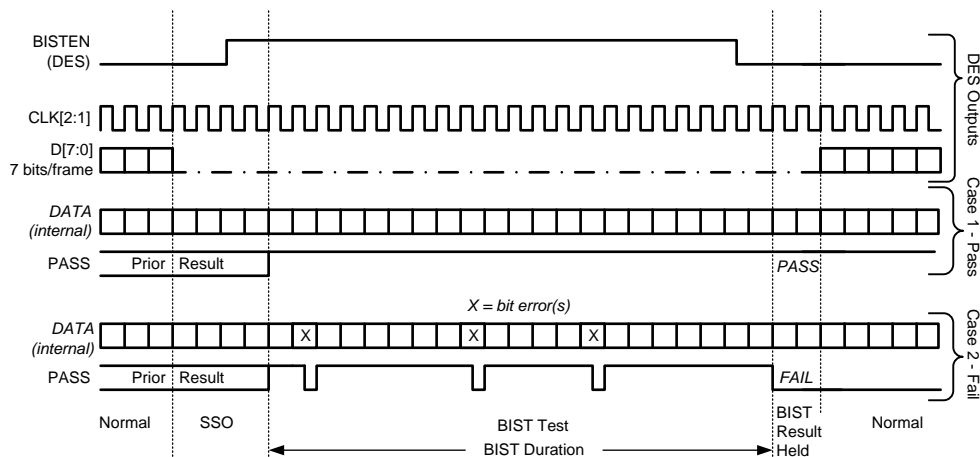


Figure 30. BIST Waveforms

8.3.16 Internal Pattern Generation

The deserializer supports the internal pattern generation feature. It allows basic testing and debugging of an integrated panel. The test patterns are simple and repetitive and allow for a quick visual verification of panel operation. As long as the device is not in power down mode, the test pattern will be displayed even if no parallel input is applied. If no PCLK is received, the test pattern can be configured to use a programmed oscillator frequency. For detailed information, refer to Application Note AN-2198 ([SNLA132](#)).

8.4 Device Functional Modes

8.4.1 Configuration Select MODE_SEL[1:0]

The DS90UB948-Q1 is capable of operating in either in 1-lane or 2-lane mode for FPD-Link III. By default, the FPD-Link III receiver automatically configures the input based on 1- or 2-lane mode operation. Programming register 0x34 [4:3] settings will override the automatic detection. For each FPD-Link III pair, the serial datastream is composed of a 35-bit symbol.

The DS90UB948-Q1 recovers the FPD-Link III serial datastream(s) and produces video data driven to the OpenLDI (LVDS) interface. OpenLDI Single Link and Dual Link are supported with color depths of 18 bits per pixel or 24 bits per pixel. There are 8 differential data pairs (D0 through D7) and two clock pairs (CLK1 and CLK2) on the OpenLDI interface. The number of data lines may vary, depending on the pixel formats supported. For Single Link output the pixel clock is limited to 96 MHz. In the case of Dual Link, the pixel clock is limited to 170 MHz (or 85 MHz per LVDS port). When in a Dual Link configuration, LVDS channels D0 to D3 carry ODD pixel data, and LVDS channels D4 to D7 carry EVEN pixel data.

The device can be configured in following modes:

- 1-lane FPD-Link III Input, Single Link OpenLDI Output
- 1-lane FPD-Link III Input, Dual Link OpenLDI Output
- 2-lane FPD-Link III Input, Dual Link OpenLDI Output
- 2-lane FPD-Link III Input, Single Link OpenLDI Output
- 2-lane FPD-Link III Input, Single Link OpenLDI Output (Replicate)

8.4.1.1 1-lane FPD-Link III Input, Single Link OpenLDI Output

In this configuration the PCLK rate embedded within the 1-lane FPD-Link III frame can range from 25 MHz to 96 MHz, resulting in a link rate of 875 Mbps (35 bit * 25 MHz) to 3.36 Gbps (35 bit * 96 MHz). Each LVDS data lane will operate at a speed of 7 bits per LVDS clock cycle; resulting in a serial line rate of 175 Mbps to 672 Mbps. CLK1 will operate at the same rate as PCLK with a duty cycle ratio of 57:43.

8.4.1.2 1-lane FPD-Link III Input, Dual Link OpenLDI Output

The input RGB data is split into odd and even pixels starting with the ODD (first) pixel outputs D0 to D3 and then the EVEN (second) pixel outputs D4 to D7. The splitting of the data signals starts with DE (data enable) transitioning from logic LOW to HIGH indicating active data.

In this configuration the PCLK rate embedded within the 1-lane FPD-Link III frame can range from 50 MHz to 96 MHz, resulting in a link rate of 1.75 Gbps (35 bit * 50 MHz) to 3.36 Gbps (35 bit * 96 MHz). Each LVDS data lane will operate at a speed of 7 bits per 2 LVDS clock cycles, resulting in a serial line rate of 175 Mbps to 336 Mbps. CLK1 and CLK2 will operate at half the rate as PCLK with a duty cycle ratio of 57:43.

8.4.1.3 2-lane FPD-Link III Input, Dual Link OpenLDI Output

The input RGB data is split into odd and even pixels starting with the ODD (first) pixel outputs D0 to D3 and then the EVEN (second) pixel outputs D4 to D7. The splitting of the data signals starts with DE (data enable) transitioning from logic LOW to HIGH indicating active data.

In this configuration the PCLK rate embedded within 2-lane FPD-Link III frame can range from 50 MHz to 170 MHz, resulting in a link rate of 875 Mbps (35 bit * 25 MHz) to 2.975 Gbps (35 bit * 85 MHz). Each LVDS data lane will operate at a speed of 7 bits per 2 LVDS clock cycles, resulting in a serial line rate of 175 Mbps to 595 Mbps. CLK1 and CLK2 will operate at half the rate as PCLK with a duty cycle ratio of 57:43.

Device Functional Modes (continued)

8.4.1.4 2-lane FPD-Link III Input, Single Link OpenLDI Output

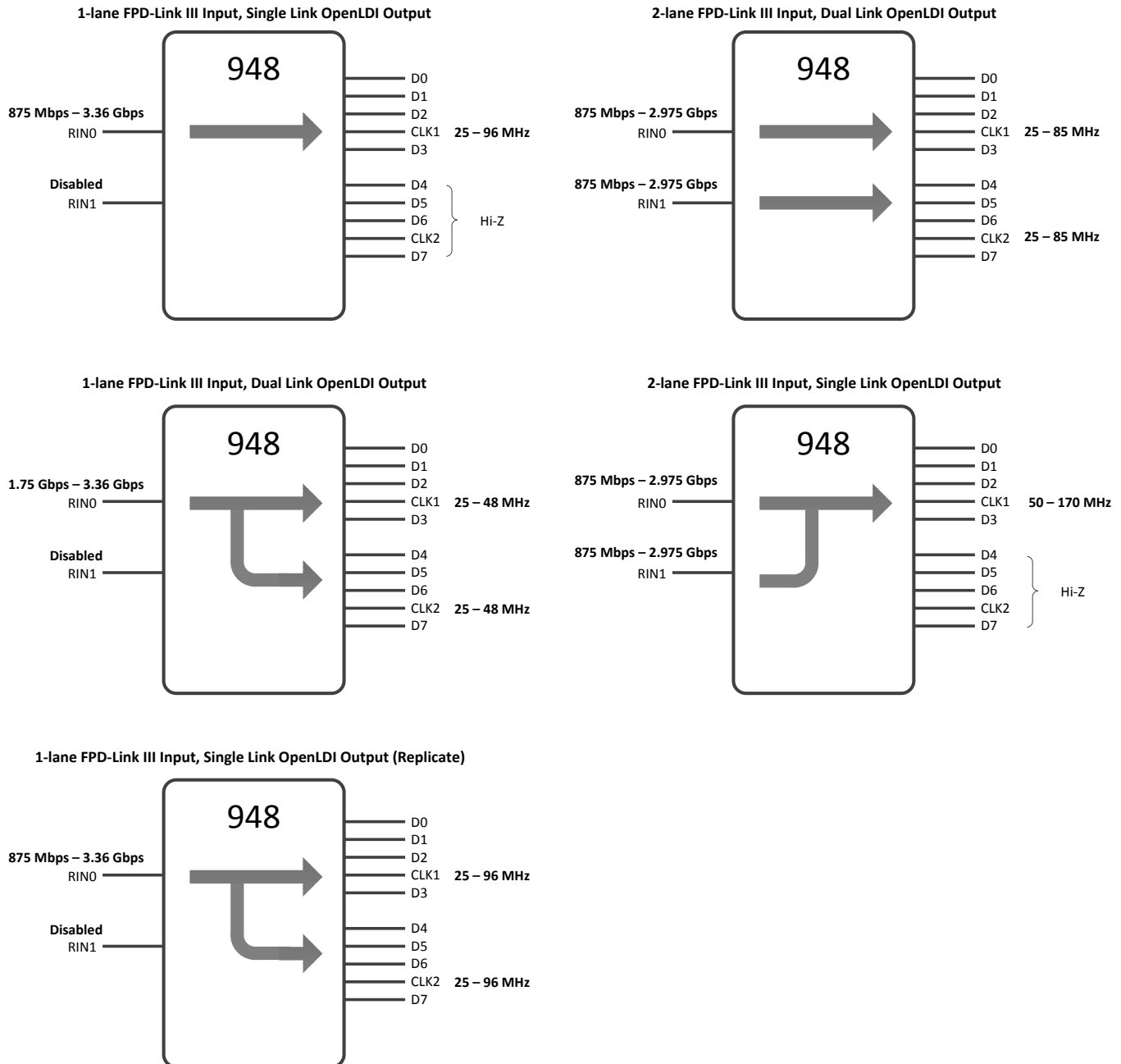
In this configuration the PCLK rate embedded within 2-lane FPD-Link III frame can range from 50 MHz to 170 MHz, resulting in a link rate of 875 Mbps (35 bit * 25 MHz) to 2.975 Gbps (35 bit * 85 MHz). Each LVDS data lane will operate at a speed of 7 bits per LVDS clock cycle; resulting in a serial line rate of 350 Mbps to 1190 Mbps. CLK1 will operate at the twice the rate as PCLK with a duty cycle ratio of 57:43.

8.4.1.5 1-lane FPD-Link III Input, Single Link OpenLDI Output (Replicate)

Same as 1-lane FPD-Link III Input, Single Link OpenLDI Output mode and duplicates the LVDS signal on D4 to D7 outputs.

8.4.2 MODE_SEL[1:0]

Possible configurations are shown in [Figure 31](#). These are described above ([Configuration Select MODE_SEL\[1:0\]](#)).

Device Functional Modes (continued)

Figure 31. Datapath Configurations

Configuration of the device may be done via the MODE_SEL[1:0] input pins, or via the configuration register bits. A pull-up resistor and a pull-down resistor of suggested values may be used to set the voltage ratio of the MODE_SEL[1:0] inputs (V_{R1}) and VDD33 to select one of the other 8 possible selected modes. See [Table 8](#) and [Table 9](#).

Device Functional Modes (continued)

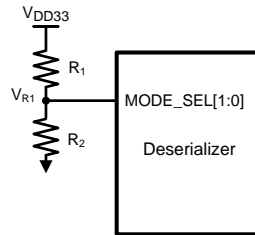


Figure 32. MODE_SEL[1:0] Connection Diagram

Table 8. Configuration Select (MODE_SEL0)

| # | Ideal Ratio V_{R1}/V_{DD33} | Target V_{R1} (V) | Suggested Resistor R1 k Ω (1% tol) | Suggested Resistor R2 k Ω (1% tol) | MAP_SEL | OUTPUT_MODE [1:0] | Output Mode |
|---|----------------------------------|------------------------|---|---|---------|----------------------|--------------------|
| 1 | 0 | 0 | Open | 40.2 or Any | 0 | 00 | Dual OLDI output |
| 2 | 0.169 | 0.559 | 232 | 47.5 | 0 | 01 | Dual SWAP output |
| 3 | 0.230 | 0.757 | 107 | 31.6 | 0 | 10 | Single OLDI output |
| 4 | 0.295 | 0.974 | 113 | 47.5 | 0 | 11 | Replicate |
| 5 | 0.376 | 1.241 | 113 | 68.1 | 1 | 00 | Dual OLDI output |
| 6 | 0.466 | 1.538 | 107 | 93.1 | 1 | 01 | Dual SWAP output |
| 7 | 0.556 | 1.835 | 90.9 | 113 | 1 | 10 | Single OLDI output |
| 8 | 0.801 | 2.642 | 45.3 | 182 | 1 | 11 | Replicate |

Table 9. Configuration Select (MODE_SEL1)

| # | Ideal Ratio V_{R1}/V_{DD33} | Target V_{R1} (V) | Suggested Resistor R1 k Ω (1% tol) | Suggested Resistor R2 k Ω (1% tol) | Repeater | MODE | High Speed Back Channel | Input Mode |
|---|----------------------------------|------------------------|---|---|----------|------|----------------------------|---------------|
| 1 | 0 | 0 | Open | 40.2 or Any | 0 | 00 | 5 Mbps | STP |
| 2 | 0.169 | 0.559 | 232 | 47.5 | 0 | 01 | 5 Mbps | Coax |
| 3 | 0.230 | 0.757 | 107 | 31.6 | 0 | 10 | 20 Mbps | STP |
| 4 | 0.295 | 0.974 | 113 | 47.5 | 0 | 11 | 20 Mbps | Coax |
| 5 | 0.376 | 1.241 | 113 | 68.1 | 1 | 00 | 5 Mbps | STP |
| 6 | 0.466 | 1.538 | 107 | 93.1 | 1 | 01 | 5 Mbps | Coax |
| 7 | 0.556 | 1.835 | 90.9 | 113 | 1 | 10 | 20 Mbps | STP |
| 8 | 0.801 | 2.642 | 45.3 | 182 | 1 | 11 | 20 Mbps | Coax |

8.4.3 OpenLDI Output Frame and Color Bit Mapping Select

The DS90UB948-Q1 can be configured to output 24-bit color (RGB888) or 18-bit color (RGB666) with 2 different mapping schemes, shown in [Figure 33](#) and [Figure 34](#). Each frame corresponds to a single pixel clock (PCLK) cycle. The LVDS clock output from CLK1 \pm and CLK2 \pm follows a 4:3 duty cycle scheme, with each 28-bit pixel frame starting with two LVDS bit clock periods high, three low, and ending with two high. The mapping scheme is controlled by MODE_SEL0 pin or by Register ([Table 11](#)).

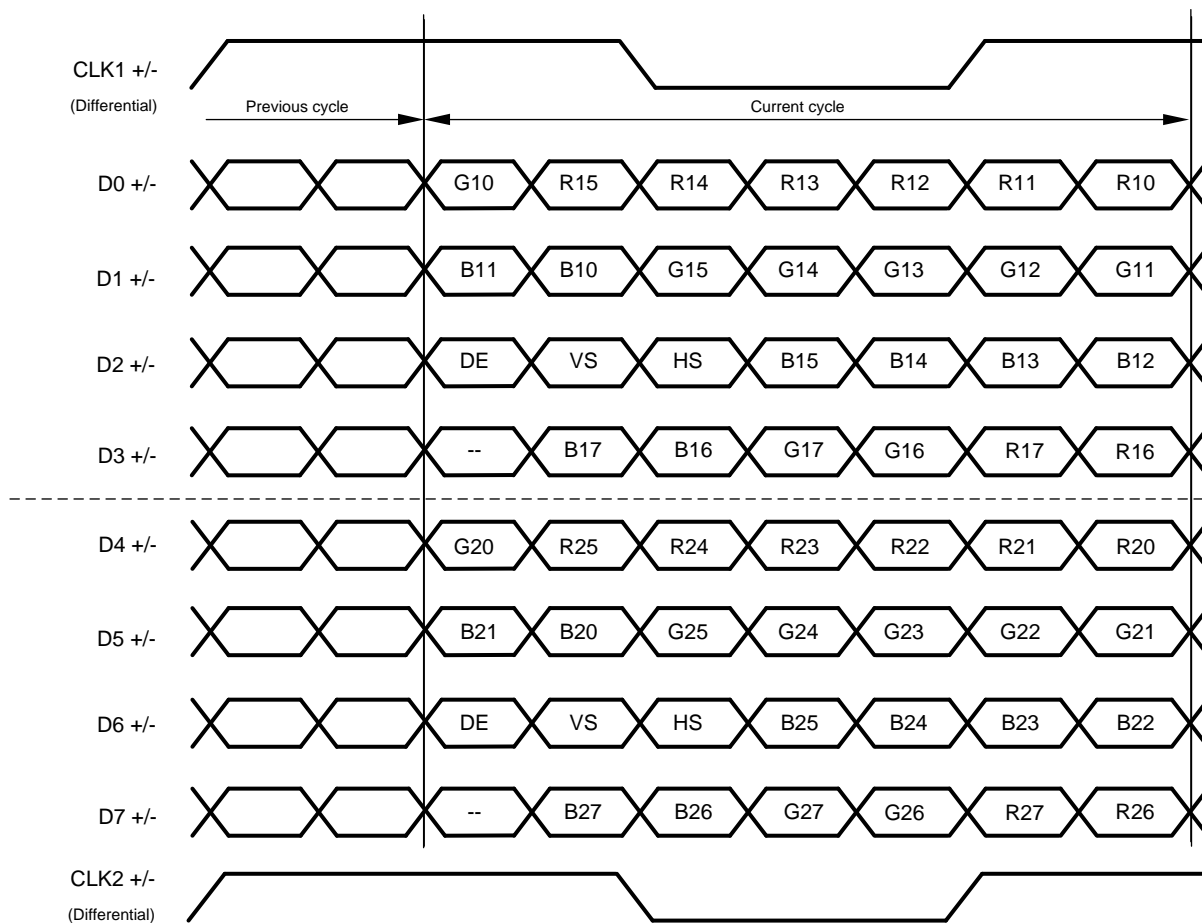


Figure 33. 24-bit Color Dual FPD-Link Mapping: MSBs on D3/D7 (MAPSEL=H)

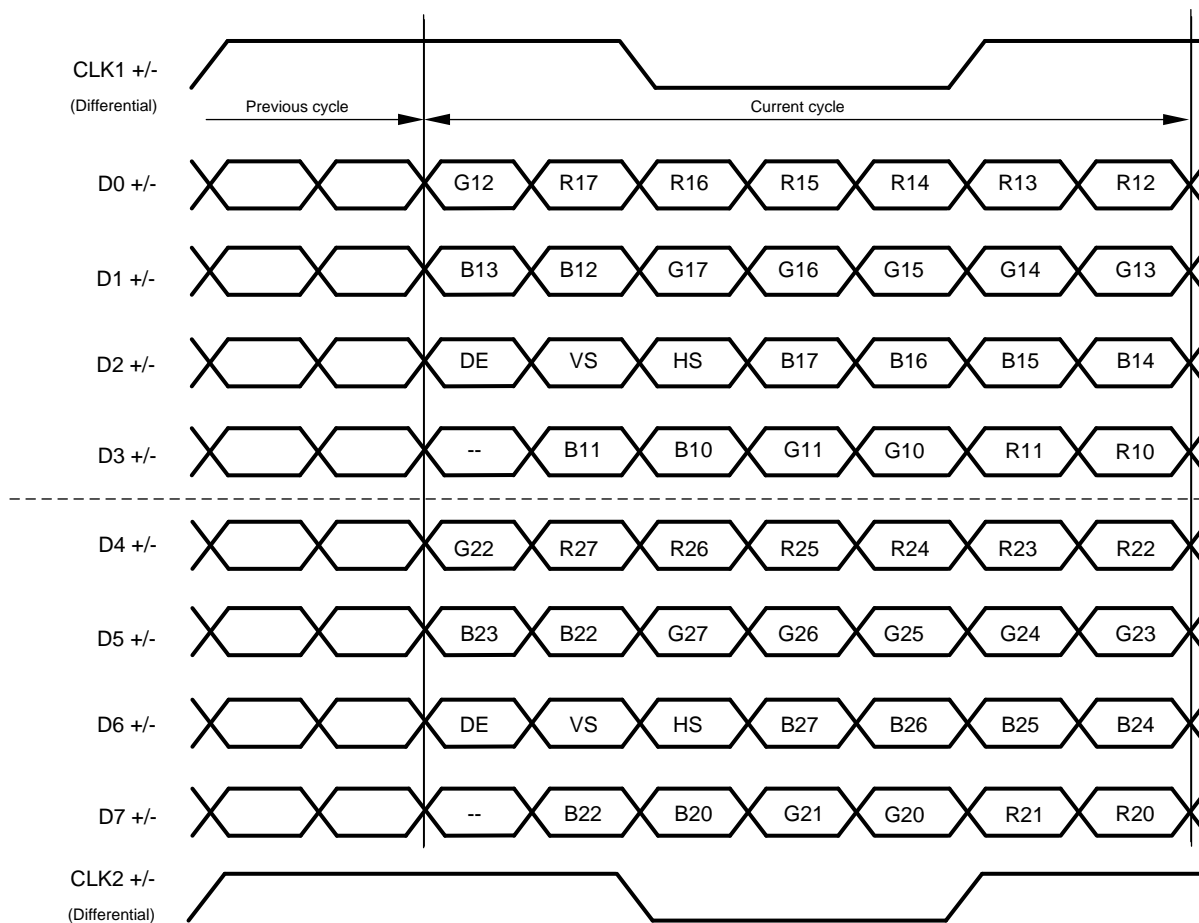


Figure 34. 24-bit Color Dual FPD-Link Mapping: LSBs on D3/D7 (MAPSEL=L)

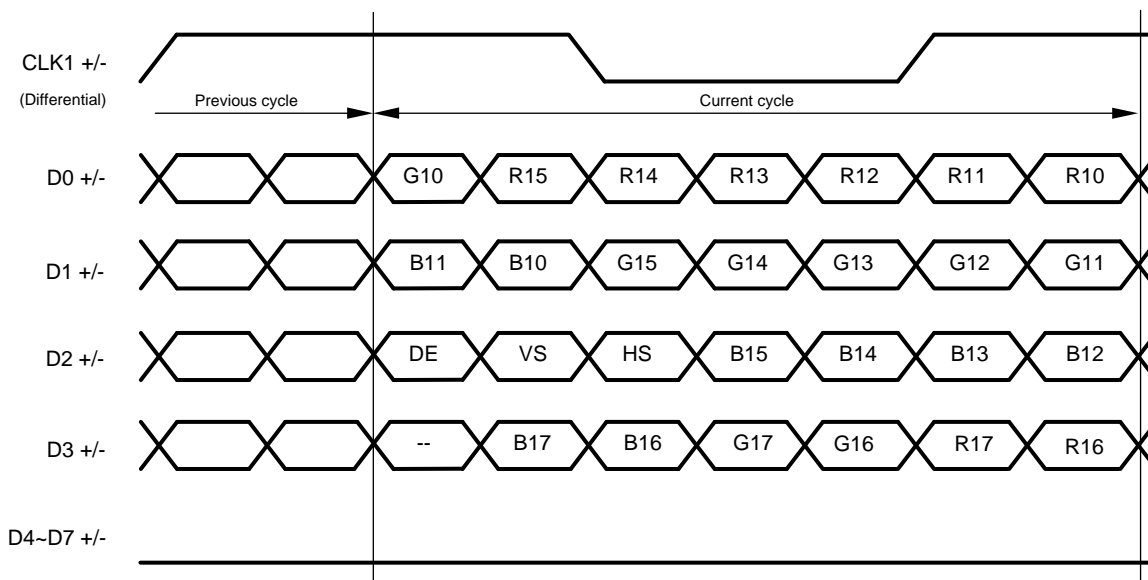


Figure 35. 24-bit Color Single FPD-Link Mapping: MSBs on D3 (MAPSEL=H)

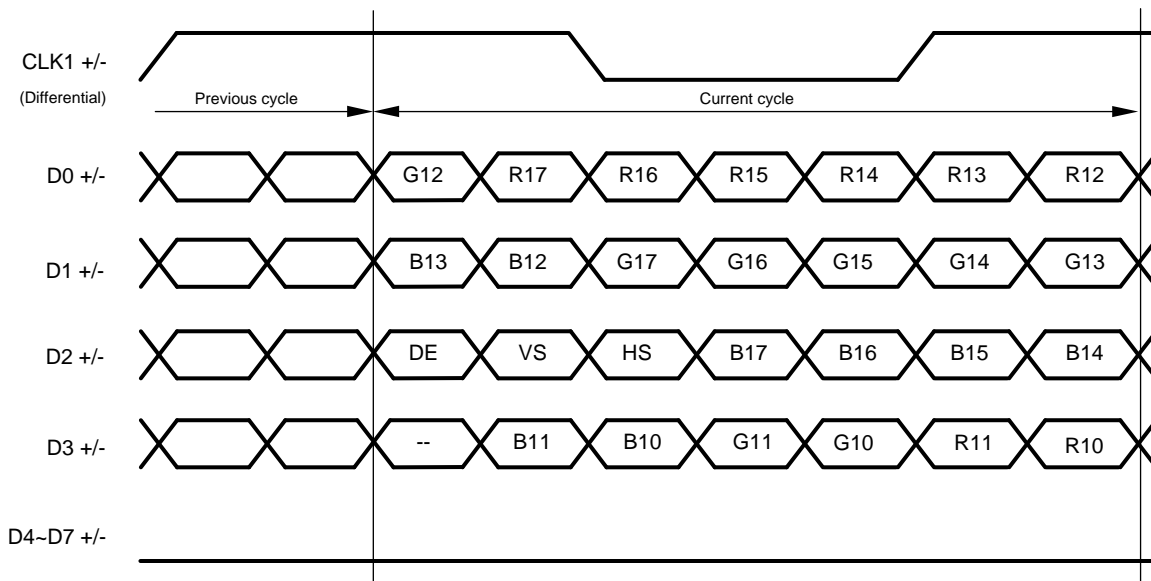


Figure 36. 24-bit Color Single FPD-Link Mapping: LSBs on D3 (MAPSEL=L)

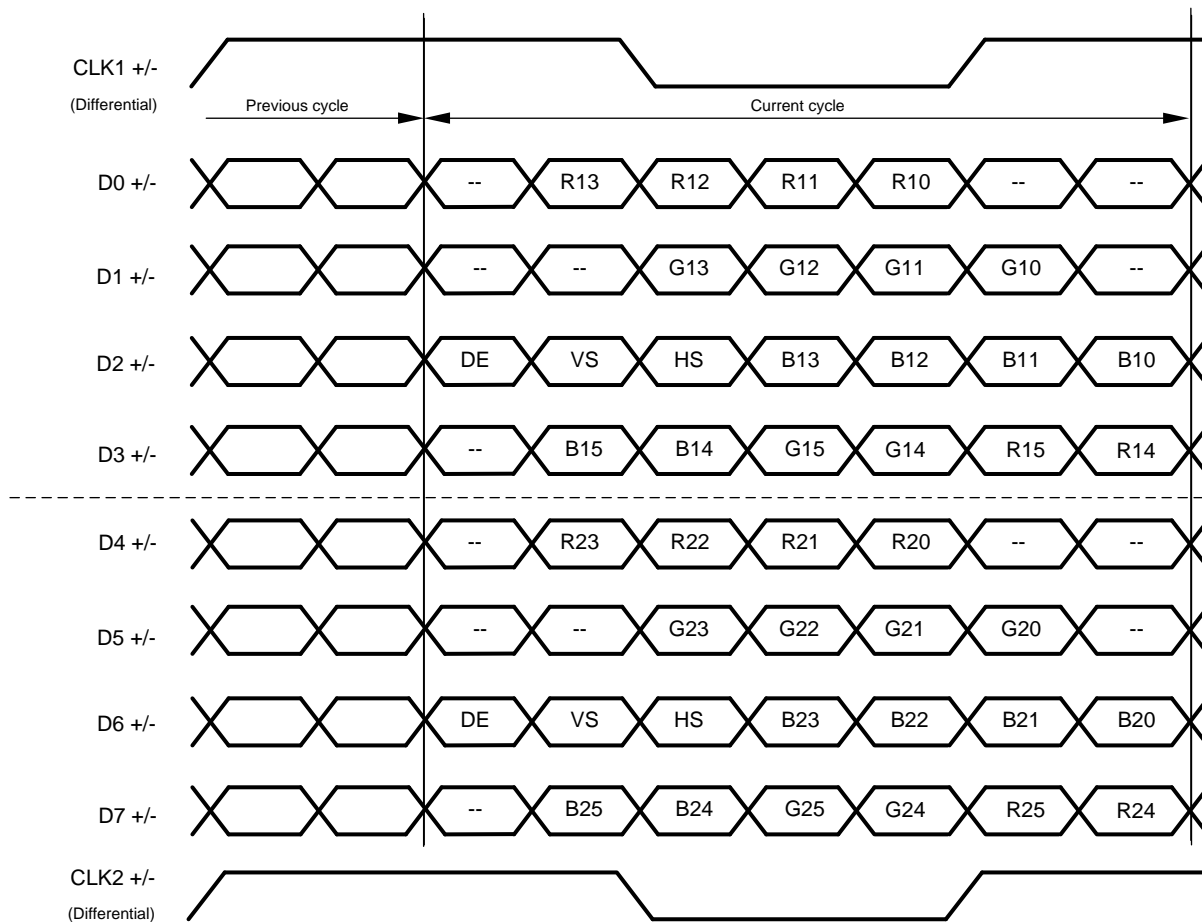


Figure 37. 18-bit Color Dual FPD-Link Mapping (MAPSEL=H)

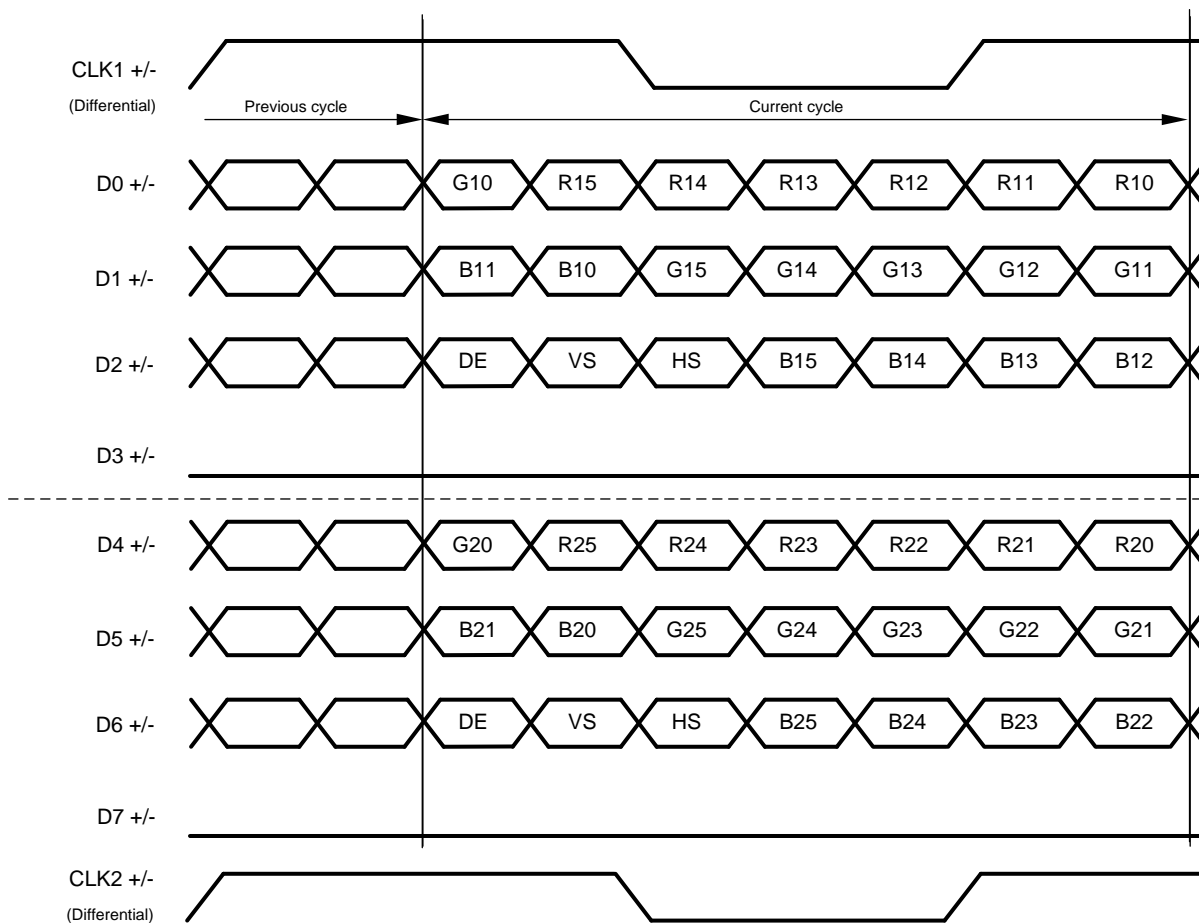


Figure 38. 18-bit Color Dual FPD-Link Mapping (MAPSEL=L)

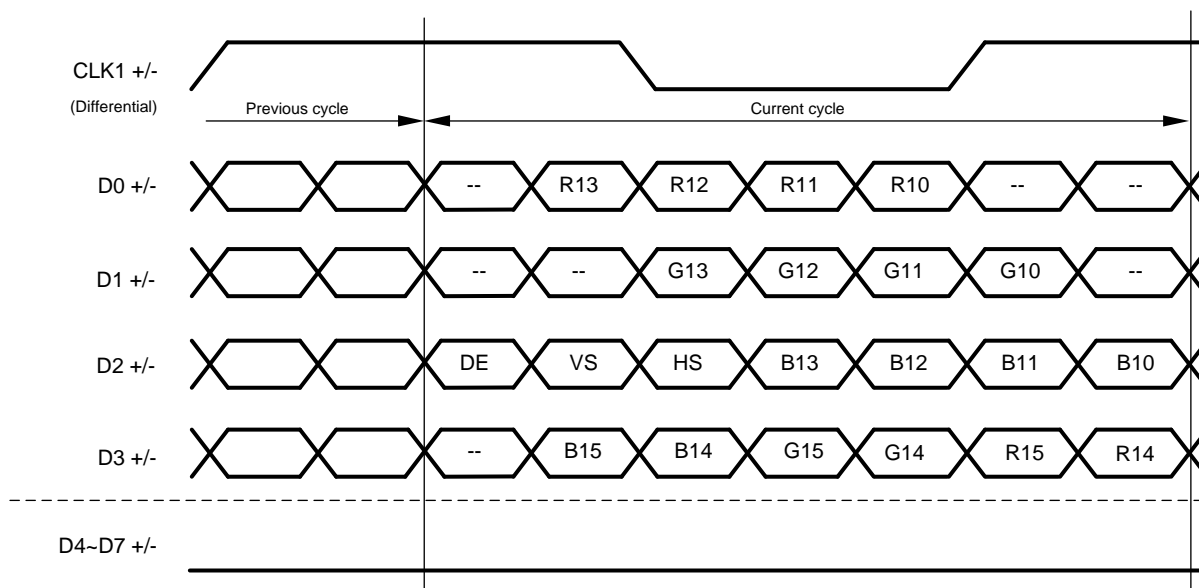


Figure 39. 18-bit Color Single FPD-Link Mapping (MAPSEL=H)

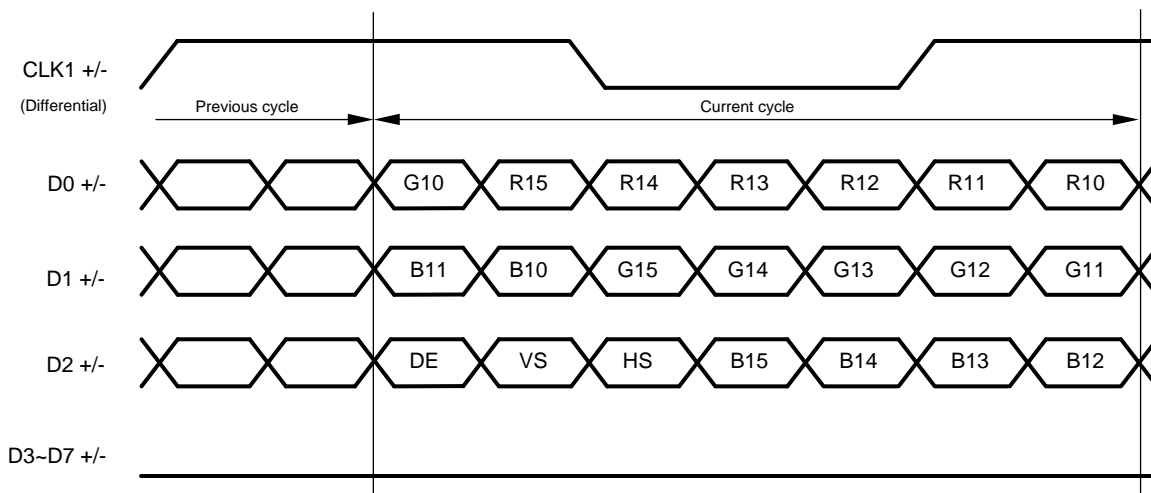


Figure 40. 18-bit Color Single FPD-Link Mapping (MAPSEL=L)

8.5 Image Enhancement Features

Several image enhancement features are provided. The White Balance LUTs allow the user to define and map the color profile of the display. Adaptive Hi-FRC Dithering enables the presentation of 'true color' images on an 18-bit display.

8.5.1 White Balance

The White Balance feature enables similar display appearance when using LCD's from different vendors. It compensates for native color temperature of the display, and adjusts relative intensities of R, G, and B to maintain specified color temperature. Programmable control registers are used to define the contents of three LUTs (8-bit color value for Red, Green and Blue) for the White Balance Feature. The LUTs map input RGB values to new output RGB values. There are three LUTs, one LUT for each color. Each LUT contains 256 entries, 8-bits per entry with a total size of 6144 bits (3 x 256 x 8). All entries are readable and writable. Calibrated values are loaded into registers through the I2C interface (deserializer is a slave device). This feature may also be applied to lower color depth applications such as 18-bit (666) and 16-bit (565). White balance is enabled and configured via serial control bus register.

8.5.2 LUT Contents

The user must define and load the contents of the LUT for each color (R,G,B). Regardless of the color depth being driven (888, 666, 656), the user must always provide contents for 3 complete LUTs - 256 colors x 8 bits x 3 tables. Unused bits - LSBs -shall be set to "0" by the user.

When 24-bit (888) input data is being driven to a 24-bit display, each LUT (R, G and B) must contain 256 unique 8-bit entries. The 8-bit white balanced data is then available at the output of the deserializer, and driven to the display.

The user must define and load the contents of the LUT for each color (R,G,B). Regardless of the color depth being driven (888, 666, 656), the user must always provide contents for 3 complete LUTs - 256 colors x 8 bits x 3 tables. Unused bits - LSBs -shall be set to "0" by the user. When 24-bit (888) input data is being driven to a 24-bit display, each LUT (R, G and B) must contain 256 unique 8-bit entries. The 8-bit white balanced data is then available at the output of the deserializer, and driven to the display.

Alternatively, with 6-bit input data the user may choose to load complete 8-bit values into each LUT. This mode of operation provides the user with finer resolution at the LUT output to more closely achieve the desired white point of the calibrated display. Although 8-bit data is loaded, only 64 unique 8-bit white balance output values are available for each color (R, G and B). The result is 8-bit white balanced data. Before driving to the output of the deserializer, the 8-bit data must be reduced to 6-bit with an FRC dithering function. To operate in this mode, the user must configure the deserializer to enable the FRC2 function.

Examples of the three types of LUT configurations described are shown in [Figure 41](#).

Image Enhancement Features (continued)

8.5.3 Enabling White Balance

The user must load all 3 LUTs prior to enabling the white balance feature. The following sequence must be followed by the user.

To initialize white balance after power-on:

1. Load contents of all 3 LUTs . This requires a sequential loading of LUTs - first RED, second GREEN, third BLUE. 256, 8-bit entries must be loaded to each LUT. Page registers must be set to select each LUT.
2. Enable white balance. By default, the LUT data may not be reloaded after initialization at power-on.

An option does exist to allow LUT reloading after power-on and initial LUT loading (as described above). This option may only be used after enabling the white balance reload feature via the associated serial control bus register. In this mode the LUTs may be reloaded by the master controller via I2C. This provides the user with the flexibility to refresh LUTs periodically , or upon system requirements to change to a new set of LUT values. The host controller loads the updated LUT values via the serial bus interface. There is no need to disable the white balance feature while reloading the LUT data. Refreshing the white balance to the new set of LUT data will be seamless - no interruption of displayed data.

It is important to note that initial loading of LUT values requires that all 3 LUTs be loaded sequentially. When reloading, partial LUT updates may be made. Note, the LUT cannot be read.

| 8-bit in / 8 bit out | | 6-bit in / 6 bit out | | 6-bit in / 8 bit out | |
|----------------------|-------------------|----------------------|-------------------|----------------------|-------------------|
| Gray level Entry | Data Out (8-bits) | Gray level Entry | Data Out (8-bits) | Gray level Entry | Data Out (8-bits) |
| 0 | 00000000b | 0 | 00000000b | 0 | 00000001b |
| 1 | 00000001b | 1 | N/A | 1 | N/A |
| 2 | 00000011b | 2 | N/A | 2 | N/A |
| 3 | 00000011b | 3 | N/A | 3 | N/A |
| 4 | 00000110b | 4 | 00000100b | 4 | 00000110b |
| 5 | 00000110b | 5 | N/A | 5 | N/A |
| 6 | 00000111b | 6 | N/A | 6 | N/A |
| 7 | 00000111b | 7 | N/A | 7 | N/A |
| 8 | 00001000b | 8 | 00001000b | 8 | 00001011b |
| 9 | 00001010b | 9 | N/A | 9 | N/A |
| 10 | 00001001b | 10 | N/A | 10 | N/A |
| 11 | 00001011b | 11 | N/A | 11 | N/A |
| ⋮ | ⋮ | ⋮ | ⋮ | ⋮ | ⋮ |
| 248 | 11111010b | 248 | 11111000b | 248 | 11111010b |
| 249 | 11111010b | 249 | N/A | 249 | N/A |
| 250 | 11111011b | 250 | N/A | 250 | N/A |
| 251 | 11111011b | 251 | N/A | 251 | N/A |
| 252 | 11111110b | 252 | 11111100b | 252 | 11111111b |
| 253 | 11111110b | 253 | N/A | 253 | N/A |
| 254 | 11111110b | 254 | N/A | 254 | N/A |
| 255 | 11111111b | 255 | N/A | 255 | N/A |

Figure 41. White Balance LUT Configuration

8.5.4 Adaptive Hi-FRC Dithering

The Adaptive FRC Dithering Feature delivers product-differentiating image quality. It reduces 24-bit RGB (8 bits per sub-pixel) to 18-bit RGB (6 bits per sub-pixel), smoothing color gradients, and allowing the flexibility to use lower cost 18-bit displays. FRC (Frame Rate Control) dithering is a method to emulate “missing” colors on a lower color depth LCD display by changing the pixel color slightly with every frame. FRC is achieved by controlling on and off pixels over multiple frames (Temporal). Static dithering regulates the number of on and off pixels in a small defined pixel group (Spatial). The FRC module includes both Temporal and Spatial methods and also Hi-FRC. Conventional FRC can display only 16,194,277 colors with 6-bit RGB source. “Hi-FRC” enables full (16,777,216) color on an 18-bit LCD panel. The “adaptive” FRC module also includes input pixel detection to apply specific Spatial dithering methods for smoother gray level transitions. When enabled, the lower LSBs of each RGB output are not active; only 18 bit data (6 bits per R,G and B) are driven to the display. This feature is enabled via serial control bus register. Two FRC functional blocks are available, and may be independently

Image Enhancement Features (continued)

enabled. FRC1 precedes the white balance LUT, and is intended to be used when 24-bit data is being driven to an 18-bit display with a white balance LUT that is calibrated for an 18-bit data source. The second FRC block, RC2, follows the white balance block and is intended to be used when fine adjustment of color temperature is required on an 18-bit color display, or when a 24-bit source drives an 18-bit display with a white balance LUT calibrated for 24-bit source data.

For proper operation of the FRC dithering feature, the user must provide a description of the display timing control signals. The timing mode, “sync mode” (HS, VS) or “DE only” must be specified, along with the active polarity of the timing control signals. All this information is entered to device control registers via the serial bus interface.

Adaptive Hi-FRC dithering consists of several components. Initially, the incoming 8-bit data is expanded to 9-bit data. This allows the effective dithered result to support a total of 16.7 million colors. The incoming 9-bit data is evaluated, and one of four possible algorithms is selected. The majority of incoming data sequences are supported by the default dithering algorithm. Certain incoming data patterns (black/white pixel, full on/off sub-pixel) require special algorithms designed to eliminate visual artifacts associated with these specific gray level transitions. Three algorithms are defined to support these critical transitions.

An example of the default dithering algorithm is illustrated in [Figure 42](#). The 1 or 0 value shown in the table describes whether the 6-bit value is increased by 1 (“1”) or left unchanged (“0”). In this case, the 3 truncated LSBs are “001”.

| | | | | | | | | |
|-----------------------|---|--|--|--|--|--|--|--|
| F0L0 | Frame = 0, Line = 0 | | | | | | | |
| PD1 | Pixel Data one | | | | | | | |
| Cell Value 010 | R[7:2]+0, G[7:2]+1, B[7:2]+0 | | | | | | | |
| LSB=001 | three lsb of 9 bit data (8 to 9 for Hi-Frc) | | | | | | | |

| Pixel Index | PD1 | PD2 | PD3 | PD4 | PD5 | PD6 | PD7 | PD8 | |
|------------------|-----|-----|-----|-----|-----|-----|-----|-----|----------------------------------|
| LSB = 001 | | | | | | | | | |
| F0L0 | 010 | 000 | 000 | 000 | 000 | 000 | 010 | 000 | R = 4/32 G = 4/32 B = 4/32 |
| F0L1 | 101 | 000 | 000 | 000 | 000 | 101 | 000 | 000 | |
| F0L2 | 000 | 000 | 010 | 000 | 000 | 010 | 000 | 000 | |
| F0L3 | 000 | 000 | 101 | 000 | 000 | 000 | 101 | 000 | |
| F1L0 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | R = 4/32 G = 4/32 B = 4/32 |
| F1L1 | 000 | 111 | 000 | 000 | 000 | 111 | 000 | 000 | |
| F1L2 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | |
| F1L3 | 000 | 000 | 000 | 111 | 000 | 000 | 000 | 111 | |
| F2L0 | 000 | 000 | 010 | 000 | 010 | 000 | 000 | 000 | R = 4/32 G = 4/32 B = 4/32 |
| F2L1 | 000 | 000 | 101 | 000 | 000 | 000 | 101 | 000 | |
| F2L2 | 010 | 000 | 000 | 000 | 000 | 000 | 010 | 000 | |
| F2L3 | 101 | 000 | 000 | 000 | 101 | 000 | 000 | 000 | |
| F3L0 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | R = 4/32 G = 4/32 B = 4/32 |
| F3L1 | 000 | 000 | 000 | 111 | 000 | 000 | 000 | 111 | |
| F3L2 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | 000 | |
| F3L3 | 000 | 111 | 000 | 000 | 000 | 111 | 000 | 000 | |

Figure 42. Default FRC Algorithm

8.6 Programming

8.6.1 Serial Control Bus

The device may also be configured by the use of a I2C compatible serial control bus. Multiple devices may share the serial control bus (up to 8 device addresses supported). The device address is set via a resistor divider (R1 and R2 — see Figure 43 below) connected to the IDx pin.

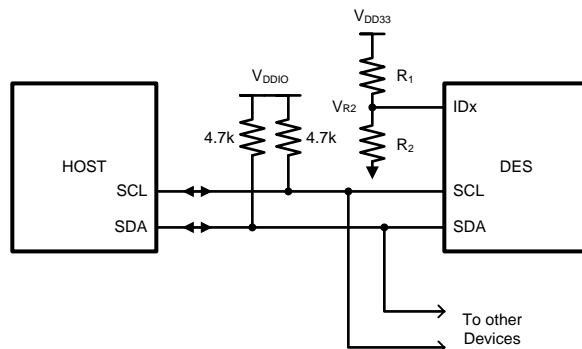


Figure 43. Serial Control Bus Connection

The serial control bus consists of two signals, SCL and SDA. SCL is a Serial Bus Clock Input. SDA is the Serial Bus Data Input / Output signal. Both SCL and SDA signals require an external pull-up resistor to 1.8 V or 3.3 V VDDIO. For most applications, a 4.7kΩ pull-up resistor to VDD33 is recommended. However, the pull-up resistor value may be adjusted for capacitive loading and data rate requirements. The signals are either pulled High, or driven Low.

The IDx pin configures the control interface to one of 8 possible device addresses. A pull-up resistor and a pull-down resistor may be used to set the appropriate voltage ratio between the IDx input pin (V_{R2}) and VDD33, each ratio corresponding to a specific device address. See Table 10 below.

Table 10. Serial Control Bus Addresses for IDx

| # | Ideal Ratio V_{R2} / V_{DD33} | Ideal V_{R2} (V) | Suggested Resistor R1 kΩ (1% tol) | Suggested Resistor R2 kΩ (1% tol) | 7-bit Address | 8-bit Address |
|---|---------------------------------|--------------------|-----------------------------------|-----------------------------------|---------------|---------------|
| 1 | 0 | 0 | Open | 40.2 or >10 | 0x2C | 0x58 |
| 2 | 0.169 | 0.559 | 232 | 47.5 | 0x2E | 0x5C |
| 3 | 0.230 | 0.757 | 107 | 31.6 | 0x30 | 0x60 |
| 4 | 0.295 | 0.974 | 113 | 47.5 | 0x32 | 0x64 |
| 5 | 0.376 | 1.241 | 113 | 68.1 | 0x34 | 0x68 |
| 6 | 0.466 | 1.538 | 107 | 93.1 | 0x36 | 0x6C |
| 7 | 0.556 | 1.835 | 90.9 | 113 | 0x38 | 0x70 |
| 8 | 0.801 | 2.642 | 45.3 | 182 | 0x3C | 0x78 |

The Serial Bus protocol is controlled by START, START-Repeated, and STOP phases. A START occurs when SCL transitions Low while SDA is High. A STOP occurs when SDA transitions High while SCL is also HIGH. See Figure 44

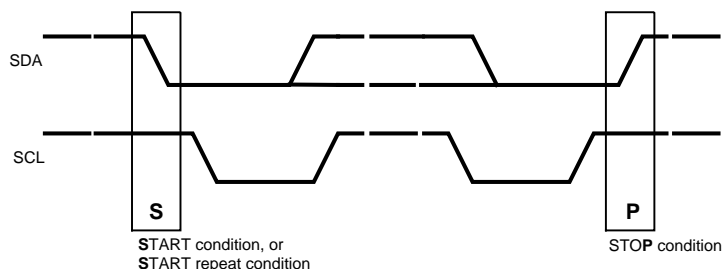


Figure 44. START and STOP Conditions

To communicate with a remote device, the host controller (master) sends the slave address and listens for a response from the slave. This response is referred to as an acknowledge bit (ACK). If a slave on the bus is addressed correctly, it Acknowledges (ACKs) the master by driving the SDA bus low. If the address doesn't match a device's slave address, it Not-acknowledges (NACKs) the master by letting SDA be pulled High. ACKs also occur on the bus when data is being transmitted. When the master is writing data, the slave ACKs after every data byte is successfully received. When the master is reading data, the master ACKs after every data byte is received to let the slave know it wants to receive another data byte. When the master wants to stop reading, it NACKs after the last data byte and creates a stop condition on the bus. All communication on the bus begins with either a Start condition or a Repeated Start condition. All communication on the bus ends with a Stop condition. A READ is shown in Figure 45 and a WRITE is shown in Figure 46.

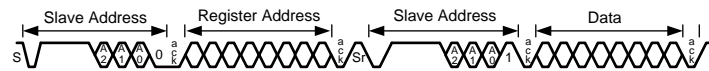


Figure 45. Serial Control Bus — READ

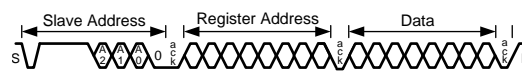


Figure 46. Serial Control Bus — WRITE

The I2C Master located at the Deserializer must support I2C clock stretching. For more information on I2C interface requirements and throughput considerations, please refer to TI Application Note SNLA131.

8.6.2 Multi-Master Arbitration Support

The Bidirectional Control Channel in the FPD-Link III devices implements I2C compatible bus arbitration in the proxy I2C master implementation. When sending a data bit, each I2C master senses the value on the SDA line. If the master is sending a logic 1 but senses a logic 0, the master has lost arbitration. It will stop driving SDA, retrying the transaction when the bus becomes idle. Thus, multiple I2C masters may be implemented in the system.

For example, there might also be a local I2C master at each camera. The local I2C master could access the Image Sensor and EEPROM. The only restriction would be that the remote I2C master at the camera should not attempt to access a remote slave through the BCC that is located at the host controller side of the link. In other words, the control channel should only operate in camera mode for accessing remote slave devices to avoid issues with arbitration across the link. The remote I2C master should also not attempt to access the deserializer registers to avoid a conflict in register access with the Host controller.

If the system does require master-slave operation in both directions across the BCC, some method of communication must be used to ensure only one direction of operation occurs at any time. The communication method could include using available read/write registers in the deserializer to allow masters to communicate with each other to pass control between the two masters. An example would be to use register 0x18 or 0x19 in the deserializer as a mailbox register to pass control of the channel from one master to another.

8.6.3 I2C Restrictions on Multi-Master Operation

The I2C specification does not provide for arbitration between masters under certain conditions. The system should make sure the following conditions cannot occur to prevent undefined conditions on the I2C bus:

- One master generates a repeated Start while another master is sending a data bit.
- One master generates a Stop while another master is sending a data bit.
- One master generates a repeated Start while another master sends a Stop.

Note that these restrictions mainly apply to accessing the same register offsets within a specific I2C slave.

8.6.4 Multi-Master Access to Device Registers for Newer FPD-Link III Devices

When using the latest generation of FPD-Link III devices (DS90UB94x-Q1), serializers or deserializer registers may be accessed simultaneously from both local and remote I2C masters. These devices have internal logic to properly arbitrate between sources to allow proper read and write access without risk of corruption.

Access to remote I2C slaves would still be allowed in only one direction at a time (Camera or Display mode).

8.6.5 Multi-Master Access to Device Registers for Older FPD-Link III Devices

When using older FPD-Link III devices (in backward compatible), simultaneous access to serializer or deserializer registers from both local and remote I2C masters may cause incorrect operation, thus restrictions should be imposed on accessing of serializer and deserializer registers. The likelihood of an error occurrence is relatively small, but it is possible for collision on reads and writes to occur, resulting in an errored read or write.

Two basic options are recommended. The first is to allow device register access only from one controller. In a Display mode system, this would allow only the Host controller to access the serializer registers (local) and the deserializer registers (remote). A controller at the deserializer (local to the Display) would not be allowed to access the deserializer or serializer registers.

The second basic option is to allow local register access only with no access to remote serializer or deserializer registers. The Host controller would be allowed to access the serializer registers while a controller at the deserializer could access those register only. Access to remote I2C slaves would still be allowed in one direction (Camera or Display mode).

In a very limited case, remote and local access could be allowed to the deserializer registers at the same time. Register access is ensured to work correctly if both local and remote masters are accessing the same deserializer register. This allows a simple method of passing control of the Bidirectional Control Channel from one master to another.

8.6.6 Restrictions on Control Channel Direction for Multi-Master Operation

Only Display or Camera mode operation should be active at any time across the Bidirectional Control Channel. If both directions are required, some method of transferring control between I2C masters should be implemented.

8.7 Register Maps

Table 11. Serial Control Bus Registers

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|-------------------------|--------|---|------|---------------------|---|
| 0x00 | I2C Device ID | 7:1 | DEVICE ID | RW | Strap | 7-bit address of Deserializer; Defaults to the address configured by the IDx strap pin. See Table 10 . |
| | | 0 | DES ID | RW | 0 | 0: Device ID is from IDx strap 1: Register I2C Device ID overrides IDx strap |
| 0x01 | Reset | 7:3 | RESERVED | RW | 0 | Reserved |
| | | 2 | RESERVED | R | 1 | Reserved |
| | | 1 | DIGITAL RESET0 | RW | 0 | Digital Reset. Resets the entire digital block including registers. This bit is self-clearing. 1: Reset 0: Normal operation. Registers which are loaded by pin strap will be restored to their original strap value when this bit is set. These registers show 'Strap' as their default value in this table. |
| | | 0 | DIGITAL RESET1 | RW | 0 | Digital Reset. Resets the entire digital block except registers. This bit is self-clearing. 1: Reset 0: Normal operation |
| 0x02 | General Configuration 0 | 7 | OUTPUT ENABLE | RW | 1 | Output Enable Override Value (in conjunction with Output Sleep State Select) If the Override control is not set, the Output Enable will be set to 1. A Digital reset 0x01[0] should be asserted after toggling Output Enable bit <i>LOW</i> to <i>HIGH</i> |
| | | 6 | OUTPUT ENABLE OVERRIDE | RW | 0 | Overrides Output Enable and Output Sleep State default 0: Disable override 1: Enable override |
| | | 5 | OSC CLOCK OUTPUT ENABLE (AUTO_CLOCK_EN) | RW | 0 | OSC clock output enable If loss of lock OSC clock is output onto PCLK. The frequency is selected in register 0x24. 1: Enable 0: Disable |
| | | 4 | OUTPUT SLEEP STATE SELECT | RW | 0 | OSS Select Override value to control output state when LOCK is low (used in conjunction with Output Enable) If the Override control is not set, the Output Sleep State Select will be set to 1. |
| | | 3:0 | RESERVED | RW | 0 | Reserved |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|-------------------------|--------|----------------------------|------|---------------------|---|
| 0x03 | General Configuration 1 | 7 | RESERVED | RW | 1 | Reserved |
| | | 6 | BC CRC GENERATOR ENABLE | RW | 1 | Back Channel CRC Generator Enable 0: Enable 1: Disable (Default) |
| | | 5 | FAILSAFE LOW | RW | 1 | Controls the pull direction for undriven LVCMOS inputs 1: Pull down 0: Pull up |
| | | 4 | FILTER ENABLE | RW | 1 | HS,VS,DE two clock filter When enabled, pulses less than two full PCLK cycles on the DE, HS, and VS inputs will be rejected. 1: Filtering enable 0: Filtering disable |
| | | 3 | I2C PASS-THROUGH | RW | 0 | I2C Pass-Through to Serializer if decode matches 0: Pass-Through Disabled 1: Pass-Through Enabled |
| | | 2 | AUTO ACK | RW | 0 | Automatically Acknowledge I2C writes independent of the forward channel lock state 1: Enable 0: Disable |
| | | 1 | DE GATE RGB | RW | 0 | Gate RGB data with DE signal. RGB data is gated with DE in order to allow packetized audio and block unencrypted data when paired with a serializer that supports HDCP. When paired with a serializer that does not support HDCP, RGB data is not gated with DE by default. However, to enable packetized audio this bit must be set. 1: Gate RGB data with DE (has no effect when paired with a serializer that supports HDCP) 0: Pass RGB data independent of DE (has no effect when paired with a serializer that does not support HDCP) |
| | | 0 | RESERVED | RW | 0 | Reserved |
| 0x04 | BCC Watchdog Control | 7:1 | BCC WATCHDOG TIMER | RW | 0x7F | The watchdog timer allows termination of a control channel transaction if it fails to complete within a programmed amount of time. This field sets the Bidirectional Control Channel Watchdog Timeout value in units of 2 milliseconds. This field should not be set to 0. |
| | | 0 | BCC WATCHDOG TIMER DISABLE | RW | 0 | Disable Bidirectional Control Channel Watchdog Timer 1: Disables BCC Watchdog Timer operation 0: Enables BCC Watchdog Timer operation |
| 0x05 | I2C Control 1 | 7 | I2C PASS THROUGH ALL | RW | 0 | I2C Pass-Through All Transactions 0: Disabled 1: Enabled |
| | | 6:4 | I2C SDA HOLD | RW | 0x1 | Internal SDA Hold Time This field configures the amount of internal hold time provided for the SDA input relative to the SCL input. Units are 50 nanoseconds. |
| | | 3:0 | I2C FILTER DEPTH | RW | 0xE | I2C Glitch Filter Depth This field configures the maximum width of glitch pulses on the SCL and SDA inputs that will be rejected. Units are 5 nanoseconds. |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|------------------------------------|------|---------------------|---|
| 0x06 | I2C Control 2 | 7 | FORWARD CHANNEL SEQUENCE ERROR | R | 0 | Control Channel Sequence Error Detected This bit indicates a sequence error has been detected in forward control channel. If this bit is set, an error may have occurred in the control channel operation. |
| | | 6 | CLEAR SEQUENCE ERROR | RW | 0 | Clears the Sequence Error Detect bit |
| | | 5 | RESERVED | R | 0 | Reserved. |
| | | 4:3 | SDA Output Delay | RW | 0 | SDA Output Delay This field configures output delay on the SDA output. Setting this value will increase output delay in units of 50ns. Nominal output delay values for SCL to SDA are: 00 : 250ns 01: 300ns 10: 350ns 11: 400ns |
| | | 2 | LOCAL WRITE DISABLE | RW | 0 | Disable Remote Writes to Local Registers Setting this bit to a 1 will prevent remote writes to local device registers from across the control channel. This prevents writes to the Deserializer registers from an I2C master attached to the Serializer. Setting this bit does not affect remote access to I2C slaves at the Deserializer. |
| | | 1 | I2C BUS TIMER SPEEDUP | RW | 0 | Speed up I2C Bus Watchdog Timer 1: Watchdog Timer expires after approximately 50 microseconds 0: Watchdog Timer expires after approximately 1 second. |
| 0x07 | REMOTE ID | 7:1 | REMOTE ID (Loaded from remote SER) | RW | 0x00 | 7-bit Serializer Device ID Configures the I2C Slave ID of the remote Serializer. A value of 0 in this field disables I2C access to the remote Serializer. This field is automatically loaded from the Serializer once RX Lock has been detected. Software may overwrite this value, but should also assert the FREEZE DEVICE ID bit to prevent loading by the Bidirectional Control Channel. |
| | | 0 | FREEZE DEVICE ID | RW | 0 | Freeze Serializer Device ID Prevent auto-loading of the Serializer Device ID from the Forward Channel. The ID will be frozen at the value written. |
| 0x08 | SlaveID[0] | 7:1 | SLAVE ID0 | RW | 0 | 7-bit Remote Slave Device ID 0 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID0, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x09 | SlaveID[1] | 7:01 | SLAVE ID1 | RW | 0 | 7-bit Remote Slave Device ID 1 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID1, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|-----------------|------|---------------------|--|
| 0x0A | SlaveID[2] | 7:1 | SLAVE ID2 | RW | 0 | 7-bit Remote Slave Device ID 2 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID2, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x0B | SlaveID[3] | 7:1 | SLAVE ID3 | RW | 0 | 7-bit Remote Slave Device ID 3 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID3, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x0C | SlaveID[4] | 7:1 | SLAVE ID4 | RW | 0 | 7-bit Remote Slave Device ID 4 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID4, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x0D | SlaveID[5] | 7:1 | SLAVE ID5 | RW | 0 | 7-bit Remote Slave Device ID 5 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID5, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x0E | SlaveID[6] | 7:1 | SLAVE ID6 | RW | 0 | 7-bit Remote Slave Device ID 6 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID6, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x0F | SlaveID[7] | 7:1 | SLAVE ID7 | RW | 0 | 7-bit Remote Slave Device ID 7 Configures the physical I2C address of the remote I2C Slave device attached to the remote Serializer. If an I2C transaction is addressed to the Slave Alias ID7, the transaction will be remapped to this address before passing the transaction across the Bidirectional Control Channel to the Serializer. |
| | | 0 | RESERVED | RW | 0 | Reserved. |
| 0x10 | SlaveAlias[0] | 7:1 | SLAVE ALIAS ID0 | RW | 0 | 7-bit Remote Slave Device Alias ID 0 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID0 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x11 | SlaveAlias[1] | 7:1 | SLAVE ALIAS ID1 | RW | 0 | 7-bit Remote Slave Device Alias ID 1 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID1 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|-----------------|------|---------------------|--|
| 0x12 | SlaveAlias[2] | 7:1 | SLAVE ALIAS ID2 | RW | 0 | 7-bit Remote Slave Device Alias ID 2 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID2 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x13 | SlaveAlias[3] | 7:1 | SLAVE ALIAS ID3 | RW | 0 | 7-bit Remote Slave Device Alias ID 3 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID3 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x14 | SlaveAlias[4] | 7:1 | SLAVE ALIAS ID4 | RW | 0 | 7-bit Remote Slave Device Alias ID 4 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID4 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x15 | SlaveAlias[5] | 7:1 | SLAVE ALIAS ID5 | RW | 0 | 7-bit Remote Slave Device Alias ID 5 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID5 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x16 | SlaveAlias[6] | 7:1 | SLAVE ALIAS ID6 | RW | 0 | 7-bit Remote Slave Device Alias ID 6 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID6 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x17 | SlaveAlias[7] | 7:1 | SLAVE ALIAS ID7 | RW | 0 | 7-bit Remote Slave Device Alias ID 7 Configures the decoder for detecting transactions designated for an I2C Slave device attached to the remote Serializer. The transaction will be remapped to the address specified in the Slave ID7 register. A value of 0 in this field disables access to the remote I2C Slave. |
| | | 0 | RESERVED | | 0 | Reserved. |
| 0x18 | MAILBOX_18 | 7:0 | MAILBOX_18 | RW | 0 | Mailbox Register This register is an unused read/write register that can be used for any purpose such as passing messages between I2C masters on opposite ends of the link. |
| 0x19 | MAILBOX_19 | 7:0 | MAILBOX_19 | RW | 0x01 | Mailbox Register This register is an unused read/write register that can be used for any purpose such as passing messages between I2C masters on opposite ends of the link. |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|--------------------------------|--------|--------------------------|------|---------------------|--|
| 0x1A | GPIO[9] and Global GPIO Config | 7 | GLOBAL GPIO OUTPUT VALUE | RW | 0 | Global GPIO Output Value This value is output on each GPIO pin when the individual pin is not otherwise enabled as a GPIO and the global GPIO direction is Output |
| | | 6 | RESERVED | RW | 0 | Reserved |
| | | 5 | GLOBAL GPIO FORCE DIR | RW | 0 | The GLOBAL GPIO DIR and GLOBAL GPIO EN bits configure the pad in input direction or output direction for functional mode or GPIO mode. The GLOBAL bits are overridden by the individual GPIO DIR and GPIO EN bits. {GLOBAL GPIO DIR, GLOBAL GPIO EN} 00: Functional mode; output 10: Tri-state 01: Force mode; output 11: Force mode; input |
| | | 4 | GLOBAL GPIO FORCE EN | RW | 0 | |
| | | 3 | GPIO9 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 2 | RESERVED | RW | 0 | Reserved |
| | | 1 | GPIO9 DIR | RW | 0 | The GPIO DIR and GPIO EN bits configure the pad in input direction or output direction for functional mode or GPIO mode. {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 0 | GPIO9 EN | RW | 0 | |
| 0x1B | Frequency Counter | 7:0 | Frequency Count | RW | 0 | Frequency Counter control A write to this register will enable a frequency counter to count the number of pixel clock during a specified time interval. The time interval is equal to the value written multiplied by the oscillator clock period (nominally 50ns). A read of the register returns the number of pixel clock edges seen during the enabled interval. The frequency counter will freeze at 0xff if it reaches the maximum value. The frequency counter will provide a rough estimate of the pixel clock period. If the pixel clock frequency is known, the frequency counter may be used to determine the actual oscillator clock frequency. |
| 0x1C | General Status | 7:6 | RESERVED | R | 0 | Reserved. |
| | | 5 | DUAL_TX_STS | R | 0 | Transmitter Dual Link Status: This bit indicates the current operating mode of the FPD-Link Transmit port 1: Dual Link mode active 0: Single Link mode active |
| | | 4 | DUAL_RX_STS | R | 0 | Receiver Dual Link Status: This bit indicates the current operating mode of the FPD-Link III Receive port 1: 2-lane mode active 0: 1-lane mode active |
| | | 3 | I2S LOCKED | R | 0 | I2S LOCK STATUS 0: I2S PLL controller not locked 1: I2S PLL controller locked to input I2S clock |
| | | 2 | RESERVED | R | 0 | Reserved. |
| | | 1 | RESERVED | R | 0/1 | Reserved. |
| | | 0 | LOCK | R | 0 | De-Serializer CDR, PLL's clock to recovered clock frequency 1: De-Serializer locked to recovered clock 0: De-Serializer not locked In Dual Link mode, this indicates both channels are locked. |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|----------------|--------|--|------|---------------------|--|
| 0x1D | GPIO0 Config | | | | | GPIO0 and D_GPIO0 Configuration If PORT1_SEL is set, this register controls the D_GPIO0 pin |
| | | 7:4 | Rev-ID | R | | Revision ID |
| | | 3 | GPIO0 OUTPUT VALUE D_GPIO0 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 2 | GPIO0 REMOTE ENABLE D_GPIO0 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 1 | GPIO0 DIR D_GPIO0 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. |
| | | 0 | GPIO0 EN D_GPIO0 EN | RW | 0 | {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| 0x1E | GPIO1_2 Config | | | | | GPIO1/GPIO2 and D_GPIO1/D_GPIO2 Configuration If PORT1_SEL is set, this register controls the D_GPIO1 and D_GPIO2 pins |
| | | 7 | GPIO2 OUTPUT VALUE D_GPIO2 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 6 | GPIO2 REMOTE ENABLE D_GPIO2 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 5 | GPIO2 DIR D_GPIO2 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. |
| | | 4 | GPIO2 EN D_GPIO2 EN | RW | 0 | {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 3 | GPIO1 OUTPUT VALUE D_GPIO1 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 2 | GPIO1 REMOTE ENABLE D_GPIO1 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 1 | GPIO1 DIR D_GPIO1 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. |
| | | 0 | GPIO1 EN D_GPIO1 EN | RW | 0 | {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|----------------|--------|--|------|---------------------|--|
| 0x1F | GPIO3 Config | | | | | GPIO3 and D_GPIO3 Configuration If PORT1_SEL is set, this register controls the D_GPIO3 pin |
| | | 7:4 | RESERVED | RW | 0 | Reserved (No GPIO 4) |
| | | 3 | GPIO3 OUTPUT VALUE D_GPIO3 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 2 | GPIO3 REMOTE ENABLE D_GPIO3 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 1 | GPIO3 DIR D_GPIO3 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 0 | GPIO3 EN D_GPIO3 EN | RW | 0 | |
| 0x20 | GPIO5_6 Config | 7 | GPIO6 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 6 | GPIO6 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 5 | GPIO6 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 4 | GPIO6 EN | RW | 0 | |
| | | 3 | GPIO5 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 2 | GPIO5 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 1 | GPIO5 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 0 | GPIO5 EN | RW | 0 | |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|----------------|--------|---------------------|------|---------------------|--|
| 0x21 | GPIO7_8 Config | 7 | GPIO8 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 6 | GPIO8 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 5 | GPIO8 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 4 | GPIO8 EN | RW | 0 | |
| | | 3 | GPIO7 OUTPUT VALUE | RW | 0 | Local GPIO Output Value This value is output on the GPIO pin when the GPIO function is enabled, the local GPIO direction is Output, and remote GPIO control is disabled. |
| | | 2 | GPIO7 REMOTE ENABLE | RW | 0 | Remote GPIO Control 1: Enable GPIO control from remote Serializer. The GPIO pin will be an output, and the value is received from the remote Serializer. 0: Disable GPIO control from remote Serializer. |
| | | 1 | GPIO7 DIR | RW | 0 | The GPIO DIR and GPIO EN configures the pad in input direction or output direction for functional mode or GPIO mode. {GPIO DIR, GPIO EN} 00: Functional mode; output 10: Tri-state 01: GPIO mode; output 11: GPIO mode; input |
| | | 0 | GPIO7 EN | RW | 0 | |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|------------------|--------|--|------|---------------------|--|
| 0x22 | Datapath Control | 7 | OVERRIDE FC CONFIG | RW | 0 | 1: Disable loading of this register from the forward channel, keeping locally written values intact 0: Allow forward channel loading of this register |
| | | 6 | PASS RGB (Loaded from remote SER) | RW | 0 | Setting this bit causes RGB data to be sent independent of DE. This allows operation in systems which may not use DE to frame video data or send other data when DE is deasserted. Note that this bit prevents HDCP operation and blocks packetized audio. This bit has no effect when paired with a serializer that does not support HDCP. 1: Pass RGB independent of DE 0: Normal operation Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |
| | | 5 | DE POLARITY (Loaded from remote SER) | RW | 0 | This bit indicates the polarity of the DE (Data Enable) signal. 1: DE is inverted (active low, idle high) 0: DE is positive (active high, idle low) Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |
| | | 4 | I2S_RPTR_REG EN (Loaded from remote SER) | RW | 0 | Regenerate I2S Data from Repeater I2S pins. 1: Don't output packetized audio data on RGB video output pins 0: Output packetized audio on RGB video output pins (Default). Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |
| | | 3 | I2S 4-CHANNEL ENABLE OVERRIDE (Loaded from remote SER) | RW | 0 | 1: Set I2S 4-Channel Enable from bit of this register 0: Set I2S 4-Channel disabled Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |
| | | 2 | 18-BIT VIDEO SELECT (Loaded from remote SER) | RW | 0 | 1: Select 18-bit video mode 0: Select 24-bit video mode Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |
| | | 1 | I2S TRANSPORT SELECT (Loaded from remote SER) | RW | 0 | 1: Enable I2S In-Band Transport 0: Enable I2S Data Island Transport Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |
| | | 0 | I2S 4-CHANNEL ENABLE (Loaded from remote SER) | RW | 0 | I2S 4-Channel Enable 1: Enable I2S 4-Channel 0: Disable I2S 4-Channel Note: this bit is automatically loaded from the remote serializer unless bit 7 of this register is set. |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|----------------|--------|----------------|------|---------------------|---|
| 0x23 | RX Mode Status | 7 | RESERVED | RW | 0 | Reserved |
| | | 6 | BC FREQ SELECT | RW | 0 | Back Channel Frequency Select 0: Divide-by-4 frequency based on the internal oscillator 1: Divide-by-2 frequency based on the internal oscillator This bit will be ignored if BC_HIGH_SPEED is set to a 1. Note that changing this setting will result in some errors on the back channel for a short period of time. If set over the control channel, the Serializer should first be programmed to Auto-Ack operation (Serializer register 0x03, bit 5) to avoid a control channel timeout due to lack of response from the Deserializer. |
| | | 5 | AUTO_I2S | RW | 1 | Auto I2S Determine I2S mode from the AUX data codes. |
| | | 4 | BC_HS_CTL | RW | 0 | Back-Channel High-Speed control Enables high-speed back-channel at 20Mbps. This bit will override the BC_FREQ_SELECT setting. Note that changing this setting will result in some errors on the back channel for a short period of time. If set over the control channel, the Serializer should first be programmed to Auto-Ack operation (Serializer register 0x03, bit 5) to avoid a control channel timeout due to lack of response from the Deserializer. BC_HIGH_SPEED is loaded from the MODE_SEL1 pin strap options. |
| | | 3 | COAX_MODE | RW | 0 | Coax Mode Configures the FPD3 Receiver for operation over Coax or STP cabling: 0 : Shielded Twisted pair (STP) 1 : Coax Coax Mode is loaded from the MODE_SEL1 pin strap options. |
| | | 2 | REPEATER_MODE | RW | 0 | Repeater Mode Indicates device is strapped to repeater mode. Repeater Mode is loaded from the MODE_SEL1 pin strap options. |
| | | 1 | RESERVED | RW | 0 | Reserved |
| | | 0 | RESERVED | RW | 0 | Reserved |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|------------------|--------|-------------------|------|---------------------|---|
| 0x24 | BIST Control | 7:6 | BIST_OUT_MODE | RW | 0 | BIST Output Mode 00 : No toggling 01 : Alternating 1/0 toggling 1x : Toggle based on BIST data |
| | | 5:4 | AUTO_OSC_FREQ | RW | 0 | When register 0x02 bit 5 (AUTO)CLOCK_EN is set, this field controls the nominal frequency of the oscillator-based receive clock. 00: 50 MHz 01: 25 MHz 10: 10 MHz 11: Reserved |
| | | 3 | BIST_PIN_CONFIG | RW | 1 | Bist Configured through Pin. 1: Bist configured through pin. 0: Bist configured through bits 2:0 in this register |
| | | 2:1 | BIST_CLOCK_SOURCE | RW | 0 | BIST Clock Source This register field selects the BIST Clock Source at the Serializer. These register bits are automatically written to the CLOCK_SOURCE bits (register offset 0x14) in the Serializer after BIST is enabled. See the appropriate Serializer register descriptions for details. 00: External Pixel Clock 01: Internal Pixel Clock 1x: Internal Pixel Clock |
| | | 0 | BIST_EN | RW | 0 | BIST Control 1: Enabled 0: Disabled |
| 0x25 | BIST ERROR COUNT | 7:0 | BIST ERROR COUNT | R | 0 | Bist Error Count Returns BIST error count for selected port. Port selected is based on the PORT_SEL control in the DUAL_RX_CTL register 0x34 [1:0]. |
| 0x26 | SCL High Time | 7:0 | SCL HIGH TIME | RW | 0x83 | I2C Master SCL High Time This field configures the high pulse width of the SCL output when the De-Serializer is the Master on the local I2C bus. Units are 50 ns for the nominal oscillator clock frequency. The default value is set to provide a minimum 5us SCL high time with the internal oscillator clock running at 26MHz rather than the nominal 20MHz. |
| 0x27 | SCL Low Time | 7:0 | SCL LOW TIME | RW | 0x84 | I2C SCL Low Time This field configures the low pulse width of the SCL output when the De-Serializer is the Master on the local I2C bus. This value is also used as the SDA setup time by the I2C Slave for providing data prior to releasing SCL during accesses over the Bidirectional Control Channel. Units are 50 ns for the nominal oscillator clock frequency. The default value is set to provide a minimum 5us SCL low time with the internal oscillator clock running at 26MHz rather than the nominal 20MHz. |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|--------------------|--------|---|------|---------------------|---|
| 0x28 | Datapath Control 2 | 7 | OVERRIDE FC CONFIG | RW | 0 | 1: Disable loading of this register from the forward channel, keeping locally written values intact 0: Allow forward channel loading of this register |
| | | 6 | RESERVED | RW | 0 | Reserved |
| | | 5 | VIDEO_DISABLED (Loaded from remote SER) | RW | 0 | Forward channel video disabled 0 : Normal operation 1 : Video is disabled, control channel is enabled This is a status bit only, indicating the forward channel is not sending active video. In this mode, the control channel and GPIO functions are enabled. Setting OVERRIDE_FC_CONFIG will prevent this bit from changing. |
| | | 4 | DUAL_LINK (Loaded from remote SER) | R | | 1: Dual Link mode enabled 0: Single Link mode enabled This bit will always be loaded from forward channel and cannot be written locally. To force DUAL_LINK receive mode, use the RX_PORT_SEL register (address 0x34) |
| | | 3 | ALTERNATE I2S ENABLE (Loaded from remote SER) | RW | 0 | 1: Enable alternate I2S output on GPIO1 (word clock) and GPIO0 (data) 0: Normal Operation |
| | | 2 | I2S DISABLED (Loaded from remote SER) | RW | 0 | 1: I2S DISABLED 0: Normal Operation |
| | | 1 | 28BIT VIDEO (Loaded from remote SER) | RW | 0 | 1: 28 bit Video enable. i.e. HS, VS, DE are present in forward channel. 0: Normal Operation |
| | | 0 | I2S SURROUND (Loaded from remote SER) | RW | 0 | 1: I2S Surround enabled 0: I2S Surround disabled |
| 0x29 | FRC Control | 7 | Timing Mode Select | RW | 0 | Select display timing mode 0: DE only Mode 1: Sync Mode (VS,HS) |
| | | 6 | HS Polarity | RW | 0 | 0: Active High 1: Active Low |
| | | 5 | VS Polarity | RW | 0 | 0: Active High 1: Active Low |
| | | 4 | DE Polarity | RW | 0 | 0: Active High 1: Active Low |
| | | 3 | FRC2 Enable | RW | 0 | 0: FRC2 disable 1: FRC2 enable |
| | | 2 | FRC1 Enable | RW | 0 | 0: FRC1 disable 1: FRC1 enable |
| | | 1 | Hi-FRC2 Disable | RW | 0 | 0: Hi-FRC2 enable 1: Hi-FRC2 disable |
| | | 0 | Hi-FRC1 Disable | RW | 0 | 0: Hi-FRC1 enable 1: Hi-FRC1 disable |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|-----------------------|--------|--------------------------|------|---------------------|--|
| 0x2A | White Balance Control | 7:6 | Page Setting | RW | 0 | Page setting 00: Configuration Registers 01: Red LUT 10: Green LUT 11: Blue LUT |
| | | 5 | White Balance Enable | RW | 0 | 0: White Balance Disable 1: White Balance Enable |
| | | 4 | LUT Reload Enable | RW | 0 | 0: Reload Disable 1: Reload Enable |
| | | 3:0 | RESERVED | RW | 0 | Reserved |
| 0x2B | I2S Control | 7:4 | RESERVED | RW | 0 | Reserved |
| | | 3 | I2S FIFO OVERRUN STATUS | R | 0 | I2S FIFO Overrun Status |
| | | 2 | I2S FIFO UNDERRUN STATUS | R | 0 | I2S FIFO Underrun Status |
| | | 1 | I2S FIFO ERROR RESET | RW | 0 | I2S Fifo Error Reset 1: Clears FIFO Error |
| | | 0 | I2S DATA FALLING EDGE | RW | 0 | I2S Clock Edge Select 1: I2S Data is strobed on the Rising Clock Edge. 0: I2S Data is strobed on the Falling Clock Edge. |
| 0x2E | PCLK Test Mode | 7 | EXTERNAL PCLK | RW | 0 | Select pixel clock from BISTC input |
| | | 6:0 | RESERVED | RW | 0 | Reserved |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|--------------------|------|---------------------|--|
| 0x34 | DUAL_RX_CTL | 7 | RESERVED | R | 0 | Reserved |
| | | 6 | RX_LOCK_MODE | RW | 0 | RX Lock Mode: Determines operating conditions for indication of RX_LOCK and generation of video data. 0 : RX_LOCK asserted only when receiving active video (Forward channel VIDEO_DISABLED bit is 0) 1 : RX_LOCK asserted when device is linked to a Serializer even if active video is not being sent. This allows indication of valid link where Bidirectional Control Channel is enabled, but Deserializer is not receiving Audio/Video data. |
| | | 5 | RAW_2ND_BC | RW | 0 | Enable Raw Secondary Back channel If this bit is set to a 1, the secondary back channel will operate in a raw mode, passing D_GPIO0 from the Deserializer to the Serializer, without any oversampling or filtering. |
| | | 4:3 | FPD3 INPUT MODE | RW | 0 | FPD-Link III Input Mode Determines operating mode of FPD-Link III Receive interface 00: Auto-detect based on received data 01: Forced Mode: 2-lane 10: Forced Mode: 1-lane, primary input 11: Forced Mode: 1-lane, secondary input |
| | | 2 | RESERVED | RW | 0 | Reserved |
| | | 1 | PORT1_SEL | RW | 0 | Selects Port 1 for Register Access from primary I2C Address For writes, port1 registers and shared registers will both be written. For reads, port1 registers and shared registers will be read. This bit must be cleared to read port0 registers. |
| | | 0 | PORT0_SEL | RW | 1 | Selects Port 0 for Register Access from primary I2C Address For writes, port0 registers and shared registers will both be written. For reads, port0 registers and shared registers will both be read. Note that if PORT1_SEL is also set, then port1 registers will be read. |
| 0x35 | AEQ TEST | | | | | AEQ Test register If PORT1_SEL is set, this register sets port1 AEQ controls |
| | | 7 | RESERVED | RW | 0 | Reserved |
| | | 6 | AEQ_RESTART | RW | 0 | Set high to restart AEQ adaptation from initial value. Method is write HIGH then write LOW - not self clearing. Adaption will be restarted on both ports. |
| | | 5 | OVERRIDE_AEQ_FLOOR | RW | 0 | Enable operation of SET_AEQ_FLOOR |
| | | 4 | SET_AEQ_FLOOR | RW | 0 | AEQ adaptation starts from a pre-set floor value rather than from zero - recommended for long cable situations |
| | | 3:0 | RESERVED | RW | 0x0 | Reserved |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|----------------|------|---------------------|---|
| 0x37 | MODE_SEL | 7 | MODE_SEL1 DONE | RW | 0 | MODE_SEL1 Done: 0: indicates the MODE_SEL1 decode has not been latched into the MODE_SEL1 status bits. 1: indicates the MODE_SEL1 decode has completed and latched into the MODE_SEL1 status bits. |
| | | 6:4 | MODE_SEL1 | RW | 0 | MODE_SEL1 Decode 3-bit decode from MODE_SEL1 pin, see MODE_SEL1 table first column "#" for mode selection: 000: CSI0 / 5 Mbps / STP (#1 on MODE_SEL1) 001: CSI0 / 5 Mbps / coax (#2 on MODE_SEL1) 010: CSI0 / 20 Mbps / STP (#3 on MODE_SEL1) 011: CSI0 / 20 Mbps / coax (#4 on MODE_SEL1) 100: CSI1 / 5 Mbps / STP (#5 on MODE_SEL1) 101: CSI1 / 5 Mbps / coax (#6 on MODE_SEL1) 110: CSI1 / 20 Mbps / STP (#7 on MODE_SEL1) 111: CSI1 / 20 Mbps / coax (#8 on MODE_SEL1) <i>Note: 0x37[6] is the MSB; 0x37[4] is the LSB</i> |
| | | 3 | MODE_SELO DONE | RW | 0 | MODE_SELO Done: 0: indicates the MODE_SELO decode has not been latched into the MODE_SELO status bits. 1: indicates the MODE_SELO decode has completed and latched into the MODE_SELO status bits. |
| | | 2:0 | MODE_SELO | RW | 0 | MODE_SELO Decode 3-bit decode from MODE_SELO pin, see MODE_SELO table first column "#" for mode selection: 000: 4 data lanes, 1 CSI port activeActive CSI port determined by MODE_SEL1 CSI_SEL bit. (#1 on MODE_SELO) 001: 4 data lanes, both CSI ports activeoverrides MODE_SEL1. (#2 on MODE_SELO) 010: 2 data lanes, 1 CSI port activeActive CSI port determined by MODE_SEL1 CSI_SEL bit. (#3 on MODE_SELO) 011: 2 data lanes, both CSI port activeoverrides MODE_SEL1. (#4 on MODE_SELO) 100: RESERVED (#5 on MODE_SELO) 101: RESERVED (#6 on MODE_SELO) 110: RESERVED (#7 on MODE_SELO) 111: RESERVED (#8 on MODE_SELO) <i>Note: 0x37[2] is the MSB; 0x37[0] is the LSB</i> |
| 0x3A | I2S_DIVSEL | 7 | reg_ov_mdiv | RW | 0x0 | 0: No override for MCLK divider 1: Override divider select for MCLK |
| | | 6:4 | reg_mdiv | RW | 0x0 | Divide ratio select for VCO output (32*REF/M) 000: Divide by 32 (=REF/M) 001: Divide by 16 (=2*REF/M) 010: Divide by 8 (=4*REF/M) 011: Divide by 4 (=8*REF/M) 100: Reserved 101: Divide by 2 (=16*REF/M) 110: Reserved 111: Divide by 1 (32*REF/M) |
| | | 3 | RESERVED | R | 0x0 | |
| | | 2 | reg_ov_mselect | RW | 0x0 | 0: Divide ratio of reference clock VCO selected by PLL-SM 1: Override divide ratio of clock to VCO |
| | | 1:0 | reg_mselect | RW | 0x0 | Divide ratio select for VCO input (M) 00: Divide by 1 01: Divide by 2 10: Divide by 4 11: Divide by 8 |
| | | | | | | |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------------|--------|-------------------------|------|---------------------|--|
| 0x41 | LINK ERROR COUNT | 7:5 | RESERVED | RW | 0 | Reserved |
| | | 4 | LINK ERROR COUNT ENABLE | RW | 0 | Enable serial link data integrity error count 1: Enable error count 0: DISABLE |
| | | 3:0 | LINK ERROR COUNT | RW | 0x3 | Link error count threshold. Counter is pixel clock based. clk0, clk1 and DCA are monitored for link errors, if error count is enabled, deserializer loose lock once error count reaches threshold. If disabled deserializer loose lock with one error. |
| 0x43 | HSCC_CONTROL | 7:5 | RESERVED | RW | 0 | Reserved |
| | | 4 | SPI_MISO_MODE | RW | 0 | SPI MISO pin mode during Reverse SPI mode During Reverse SPI mode, SPI_MISO is typically an output signal. For bused SPI applications, it may be necessary to tri-state the SPI_MISO output if the device is not selected (SPI_SS = 0). 0 : Always enable SPI_MISO output driver 1 : Tri-state SPI_MISO output if SPI_SS is not asserted (low) |
| | | 3 | SPI_CPOL | RW | 0 | SPI Clock Polarity Control 0 : SPI Data driven on Falling clock edge, sampled on Rising clock edge 1 : SPI Data driven on Rising clock edge, sampled on Falling clock edge |
| | | 2:0 | HSCC_MODE | RW | 0 | High-Speed Control Channel Mode Enables high-speed modes for the secondary link back-channel, allowing higher speed signaling of GPIOs or SPI interface: These bits indicates the High Speed Control Channel mode of operation: 000: Normal frame, GPIO mode 001: High Speed GPIO mode, 1 GPIO 010: High Speed GPIO mode, 2 GPIOs 011: High Speed GPIO mode: 4 GPIOs 100: Reserved 101: Reserved 110: High Speed, Forward Channel SPI mode 111: High Speed, Reverse Channel SPI mode |
| 0x44 | ADAPTIVE EQ BYPASS | | | | | Adaptive Equalizer Bypass register If PORT1_SEL is set, this register sets port1 AEQ controls |
| | | 7:5 | EQ STAGE 1 SELECT VALUE | RW | 0x3 | EQ select value[5:3] - Used if adaptive EQ is bypassed. |
| | | 4 | RESERVED | RW | 0 | Reserved |
| | | 3:1 | EQ STAGE 2 SELECT VALUE | RW | 0 | EQ select value [2:0] - Used if adaptive EQ is bypassed. |
| | | 0 | ADAPTIVE EQ BYPASS | RW | 0 | 1: Disable adaptive EQ 0: Enable adaptive EQ |
| 0x45 | ADAPTIVE EQ MIN MAX | | | | | Adaptive Equalizer Configuration If PORT1_SEL is set, this register sets port1 AEQ configuration |
| | | 7:4 | RESERVED | RW | 0x08 | Reserved |
| | | 3:0 | ADAPTIVE EQ FLOOR VALUE | RW | | When AEQ floor is enabled by mode-sel pin or register (reg_35[5:4]) the starting setting is given by this register. |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|-------------------|--------|----------------------|------|---------------------|---|
| 0x49 | FPD_TX_MODE | 7 | MAPSEL MODE | R | Strap | Mapsel Pin Status Strap option on the MODE_SEL0 pin |
| | | 6 | MAPSEL OVER WRITE | RW | 0 | Mapsel Over Write enable from register configuration |
| | | 5 | MAPSEL REG BIT | RW | 0 | Register setting of MAPSEL mode if MAPSEL OVER WRITE is set |
| | | 4:2 | RESERVED | R | 0 | Reserved |
| | | 1:0 | FPD_OUT_MODE | RW | Strap | FPD/OLDI output mode Controls single/dual operation of the FPD Transmit ports 00 : Dual FPD/OLDI output 01 : Dual SWAP FPD/OLDI output 10 : Single FPD/OLDI output 11 : Replicate FPD/OLDI output The FPD_OUT_MODE register bits are loaded at reset from the MODE_SEL0 pin strap options. |
| 0x4B | LVDS CONTROL | 7:2 | RESERVED | RW | 0x02 | Reserved |
| | | 1:0 | LVDS VOD CONTROL | RW | 0 | FPD/OLDI Output VOD Setting 00: Setting 1 - 190mV typical voltage swing (single-ended) 01: Setting 2 - 275mV typical voltage swing (single-ended) 10: Setting 3 - 325mV typical voltage swing (single-ended) 11: Setting 4 - 375mV typical voltage swing (single-ended) |
| 0x52 | CML OUTPUT CTL1 | 7 | CML CHANNEL SELECT 1 | RW | 0 | Selects between PORT0 and PORT1 to output onto CMLOUT±. 0: Recovered forward channel data from RIN0± is output on CMLOUT± 1: Recovered forward channel data from RIN1± is output on CMLOUT± CMLOUT driver must be enabled by setting 0x56[3] = 1. Note: This bit must match 0x57[2:1] setting for PORT0 or PORT1. |
| | | 6:0 | RESERVED | RW | 0 | Reserved |
| 0x56 | CML OUTPUT ENABLE | 7:4 | RESERVED | RW | 0 | Reserved |
| | | 3 | CMLOUT ENABLE | RW | 0 | Enable CMLOUT± Loop-through Driver 0: Disabled (Default) 1: Enabled |
| | | 2:0 | RESERVED | RW | 0 | Reserved |
| 0x57 | CML OUTPUT CTL2 | 7:3 | RESERVED | RW | 0 | Reserved |
| | | 2:1 | CML CHANNEL SELECT 2 | RW | 0 | Selects between PORT0 and PORT1 to output onto CMLOUT±. 01: Recovered forward channel data from RIN0± is output on CMLOUT± 10: Recovered forward channel data from RIN1± is output on CMLOUT± CMLOUT driver must be enabled by setting 0x56[3] = 1. Note: This must match 0x52[7] setting for PORT0 or PORT1. |
| | | 0 | RESERVED | RW | 0 | Reserved |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|-----------------|------|---------------------|---|
| 0x64 | PGCTL | 7:4 | PATGEN_SEL | RW | 1 | Fixed Pattern Select This field selects the pattern to output when in Fixed Pattern Mode. Scaled patterns are evenly distributed across the horizontal or vertical active regions. This field is ignored when Auto-Scrolling Mode is enabled. The following table shows the color selections in non-inverted followed by inverted color mode: 0000: Reserved 0001: White/Black 0010: Black/White 0011: Red/Cyan 0100: Green/Magenta 0101: Blue/Yellow 0110: Horizontally Scaled Black to White/White to Black 0111: Horizontally Scaled Black to Red/White to Cyan 1000: Horizontally Scaled Black to Green/White to Magenta 1001: Horizontally Scaled Black to Blue/White to Yellow 1010: Vertically Scaled Black to White/White to Black 1011: Vertically Scaled Black to Red/White to Cyan 1100: Vertically Scaled Black to Green/White to Magenta 1101: Vertically Scaled Black to Blue/White to Yellow 1110: Custom color (or its inversion) configured in PGRS, PGGS, PGBS registers 1111: Reserved See TI App Note AN-2198 |
| | | 3 | PATGEN_UNH | RW | 0 | Enables the UNH-IOL compliance test pattern: 0: Pattern type selected by PATGEN_SEL 1: Compliance test pattern is selected. Value of PATGEN_SEL is ignored. |
| | | 2 | PATGEN_COLOR | RW | 0 | Enable Color Bars Pattern 0: Color Bars disabled (default) 1: Color bars enabled Overrides the selection from bits [7:4] |
| | | 1 | PATGEN_VCOM_REV | RW | 0 | Reverse the order of color bands in VCOM pattern 0: Color sequence from top left is (YCBY) (default) 1: Color sequence from top left is (RBCY) |
| | | 0 | PATGEN_EN | RW | 0 | Pattern Generator Enable: 1: Enable Pattern Generator 0: Disable Pattern Generator |

Register Maps (continued)

Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|---------------|--------|-----------------|------|---------------------|---|
| 0x65 | PGCFG | 7:5 | RESERVED | R | 0 | Reserved |
| | | 4 | PATGEN_18B | RW | 0 | 18-bit Mode Select: 1: Enable 18-bit color pattern generation. Scaled patterns will have 64 levels of brightness and the R, G, and B outputs use the six most significant color bits. 0: Enable 24-bit pattern generation. Scaled patterns use 256 levels of brightness. This bit has no effect in external timing mode (PATGEN_TSEL = 0). |
| | | 3 | PATGEN_EXTCLK | RW | 0 | Select PCLK of Pattern generator 1: Selects the external pixel clock when using internal timing. 0: Selects the internal divided clock when using internal timing. This bit has no effect in external timing mode (PATGEN_TSEL = 0). |
| | | 2 | PATGEN_TSEL | RW | 0 | Timing Select Control: 1: The Pattern Generator creates its own video timing as configured in the Pattern Generator Total Frame Size, Active Frame Size, Horizontal Sync Width, Vertical Sync Width, Horizontal Back Porch, Vertical Back Porch, and Sync Configuration registers. 0: the Pattern Generator uses external video timing from the pixel clock, Data Enable, Horizontal Sync, and Vertical Sync signals. |
| | | 1 | PATGEN_INV | RW | 0 | Enable Inverted Color Patterns: 1: Invert the color output. 0: Do not invert the color output. |
| | | 0 | PATGEN_ASCRL | RW | 0 | Auto-Scroll Enable: 1: The Pattern Generator will automatically move to the next enabled pattern after the number of frames specified in the Pattern Generator Frame Time (PGFT) register. 0: The Pattern Generator retains the current pattern. |
| 0x66 | PGIA | 7:0 | PATGEN_IA | RW | 0 | Indirect Address: This 8-bit field sets the indirect address for accesses to indirectly-mapped registers. It should be written prior to reading or writing the Pattern Generator Indirect Data register. See TI App Note AN-2198 . |
| 0x67 | PGID | 7:0 | PATGEN_ID | RW | 0 | Indirect Data: When writing to indirect registers, this register contains the data to be written. When reading from indirect registers, this register contains the readback value. See TI App Note AN-2198 . |
| 0x68 | PGDBG | 7:4 | RESERVED | RW | 0 | Reserved |
| | | 3 | PATGEN_BIST_EN | RW | 0 | Pattern Generator BIST Enable: Enables Pattern Generator in BIST mode. Pattern Generator will compare received video data with local generator pattern. Upstream device must be programmed to the same pattern. |
| | | 2:0 | RESERVED | RW | 0 | Reserved |
| 0x69 | PGTSTDAT | 7 | PATGEN_BIST_ERR | R | 0 | Pattern Generator BIST Error Flag During Pattern Generator BIST mode, this bit indicates if the BIST engine has detected errors. If the BIST Error Count (available in the Pattern Generator indirect registers) is non-zero, this flag will be set. |
| | | 6:0 | RESERVED | R | 0 | |

Register Maps (continued)
Table 11. Serial Control Bus Registers (continued)

| ADD (hex) | Register Name | Bit(s) | Function | Type | Default Value (hex) | Description |
|-----------|------------------|--------|-----------------|------|---------------------|---|
| 0x6E | GPI Pin Status 1 | 7 | GPI7 Pin Status | R | 0 | GPI7/I2S_WC pin status |
| | | 6 | GPI6 Pin Status | R | 0 | GPI6/I2S_DA pin status |
| | | 5 | GPI5 Pin Status | R | 0 | GPI5/I2S_DB pin status |
| | | 4 | RESERVED | R | 0 | Reserved for future use |
| | | 3 | GPI3 Pin Status | R | 0 | GPI3 / I2S_DD pin status |
| | | 2 | GPI2 Pin Status | R | 0 | GPI2 / I2S_DC pin status |
| | | 1 | GPI1 Pin Status | R | 0 | GPI1 pin status |
| | | 0 | GPI0 Pin Status | R | 0 | GPI0 pin status |
| 0x6F | GPI Pin Status 2 | 7:1 | RESERVED | R | 0 | Reserved for future use |
| | | 0 | GPI8 Pin Status | R | 0 | GPI8/I2S_CLK pin status |
| 0xF0 | RX ID | 7:0 | ID0 | R | 0x5F | First byte ID code, '_' |
| 0xF1 | | 7:0 | ID1 | R | 0x55 | 2nd byte of ID code, 'U' |
| 0xF2 | | 7:0 | ID2 | R | 0x48 | 3rd byte of ID code. Value will be either 'B' or 'H'. 'H' indicates an HDCP capable device. |
| 0xF3 | | 7:0 | ID3 | R | 0x39 | 4th byte of ID code: '9' |
| 0xF4 | | 7:0 | ID4 | R | 0x34 | 5th byte of ID code: '4' |
| 0xF5 | | 7:0 | ID5 | R | 0x38 | 6th byte of ID code: '8' |

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The DS90UB948-Q1 is a FPD-Link III Deserializer which, in conjunction with the DS90UB949/947-Q1 Serializers, converts 1-lane or 2-lane FPD-Link III streams into a FPD-Link (OpenLDI) interface. The Deserializer is capable of operating over cost-effective 50Ω single-ended coaxial or 100Ω differential shielded twisted-pair (STP) cables. It recovers the data from two FPD-Link III serial streams and translates it into dual pixel FPD-Link (data lanes + clock) supporting video resolutions up to WUXGA and 1080p60 with 24-bit color depth. This provides a bridge between HDMI enabled sources such as GPUs to connect to existing LVDS displays or Application Processors.

9.2 Typical Applications

Bypass capacitors should be placed near the power supply pins. At a minimum, four (4) 10μF capacitors should be used for local device bypassing. Ferrite beads are placed on the two sets of supply pins (VDD33 and VDDIO) for effective noise suppression. The interface to the graphics source is LVDS. The VDDIO pins may be connected to 3.3V or 1.8V. A capacitor and resistor are placed on the PDB pin to delay the enabling of the device until power is stable. See [Figure 47](#) for a typical STP connection diagram and [Figure 48](#) for a typical coax connection diagram.

Typical Applications (continued)

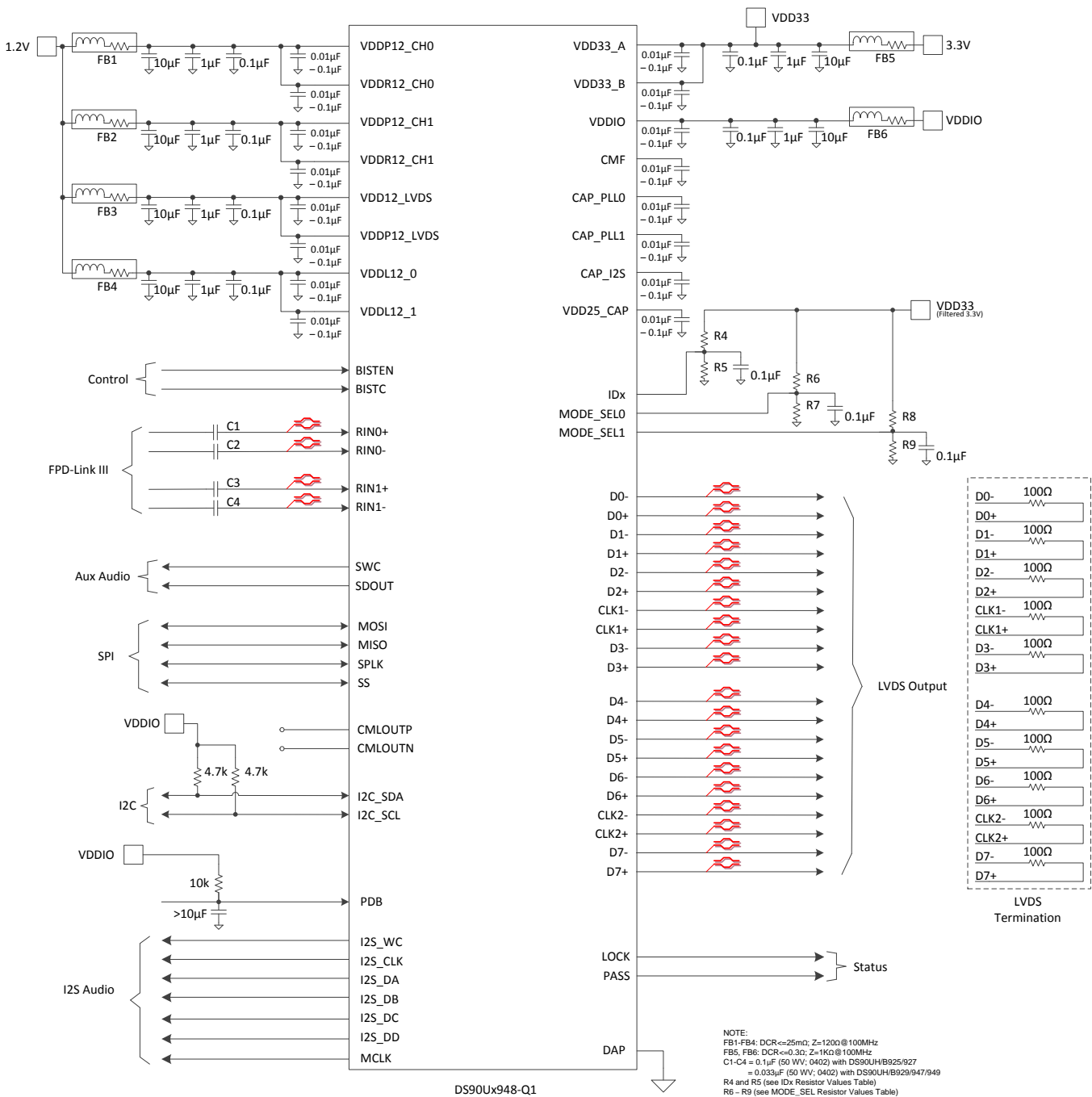


Figure 47. Typical Connection Diagram (STP)

Typical Applications (continued)

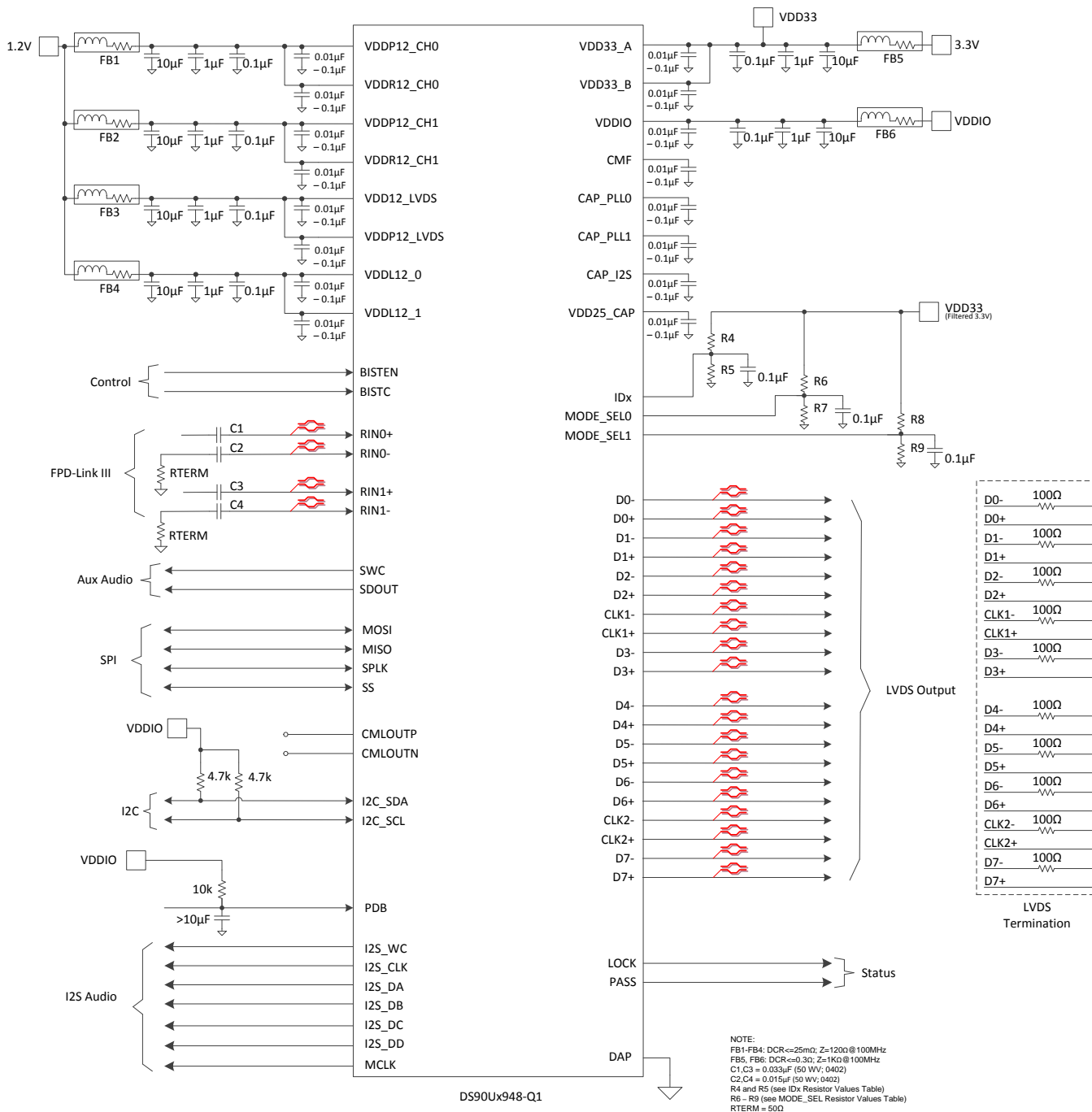
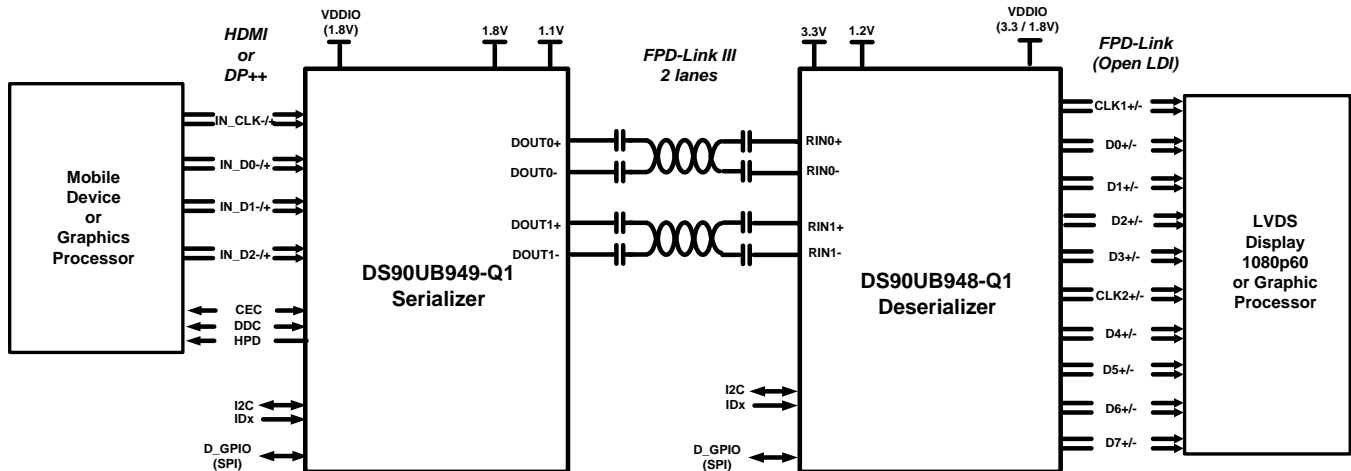


Figure 48. Typical Connection Diagram (Coax)


Figure 49. Typical Display System Diagram

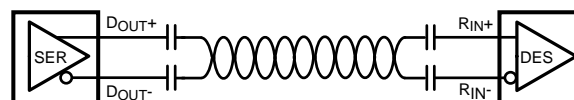
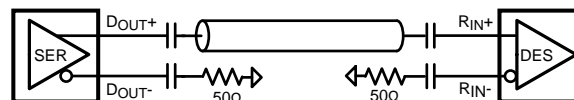
9.2.1 Design Requirements

For the typical design application, use the following as input parameters.

Table 12. Design Parameters

| Design Parameter | Example Value |
|---|---------------|
| VDDIO | 1.8V or 3.3V |
| VDD12 | 1.2V |
| VDD33 | 3.3V |
| AC Coupling Capacitor for RIN0± and RIN1± | 33 nF |

The SER/DES supports only AC-coupled interconnects through an integrated DC-balanced decoding scheme. External AC coupling capacitors must be placed in series in the FPD-Link III signal path as illustrated in [Figure 50](#). For applications utilizing single-ended 50 Ω coaxial cable, the unused data pins (RIN0-, RIN1-) should utilize a 15 nF capacitor and should be terminated with a 50 Ω resistor.


Figure 50. AC-Coupled Connection (STP)

Figure 51. AC-Coupled Connection (Coaxial)

For high-speed FPD-Link III transmissions, the smallest available package should be used for the AC coupling capacitor. This will help minimize degradation of signal quality due to package parasitics. The I/O's require 33 nF AC coupling capacitors to the line.

9.2.2 Detailed Design Procedure

9.2.2.1 PCB Layout and Power System Considerations

Circuit board layout and stack-up for the LVDS serializer and deserializer devices should be designed to provide low-noise power to the device. Good layout practice will also separate high frequency or high-level inputs and outputs to minimize unwanted stray noise, feedback and interference. Power system performance may be greatly improved by using thin dielectrics (2 to 4 mil) for power / ground sandwiches. This arrangement utilizes the plane capacitance for the PCB power system and has low-inductance, which has proven effectiveness especially at high frequencies, and makes the value and placement of external bypass capacitors less critical. External bypass capacitors should include both RF ceramic and tantalum electrolytic types. RF capacitors may use values in the range of 0.01 μ F to 10 μ F. Tantalum capacitors may be in the 2.2 μ F to 10 μ F range. The voltage rating of the tantalum capacitors should be at least 5X the power supply voltage being used.

MLCC surface mount capacitors are recommended due to their smaller parasitic properties. When using multiple capacitors per supply pin, locate the smaller value closer to the pin. A large bulk capacitor is recommended at the point of power entry. This is typically in the 50 μ F to 100 μ F range and will smooth low frequency switching noise. It is recommended to connect power and ground pins directly to the power and ground planes with bypass capacitors connected to the plane with via on both ends of the capacitor. Connecting power or ground pins to an external bypass capacitor will increase the inductance of the path. A small body size X7R chip capacitor, such as 0603 or 0805, is recommended for external bypass. A small body sized capacitor has less inductance. The user must pay attention to the resonance frequency of these external bypass capacitors, usually in the range of 20MHz-30MHz. To provide effective bypassing, multiple capacitors are often used to achieve low impedance between the supply rails over the frequency of interest. At high frequency, it is also a common practice to use two vias from power and ground pins to the planes, reducing the impedance at high frequency.

Use at least a four layer board with a power and ground plane. Locate LVCMOS signals away from the LVDS lines to prevent coupling from the LVCMOS lines to the LVDS lines. Closely coupled differential lines of 100 Ω are typically recommended for LVDS interconnect. The closely coupled lines help to ensure that coupled noise will appear as common mode and thus is rejected by the receivers. The tightly coupled lines will also radiate less.

At least 32 thermal vias are necessary from the device center DAP to the ground plane. They connect the device ground to the PCB ground plane, as well as conduct heat from the exposed pad of the package to the PCB ground plane. More information on the WQFN style package, including PCB design and manufacturing requirements, is provided in TI Application Note: AN-1187.

9.2.2.2 CML Interconnect Guidelines

See AN-1108 and AN-905 for full details.

- Use 100 Ω coupled differential pairs
- Use the S/2S/3S rule in spacings
 - S = space between the pair
 - 2S = space between pairs
 - 3S = space to LVCMOS signal
- Minimize the number of Vias
- Use differential connectors when operating above 500Mbps line speed
- Maintain balance of the traces
- Minimize skew within the pair
- Terminate as close to the TX outputs and RX inputs as possible

Additional general guidance can be found in the LVDS Owner's Manual - available in PDF format from the Texas Instruments web site at: [SNLA187](#)

9.2.3 Application Performance Plots

The plots below correspond to 1080p60 video application with 2-lane FPD-Link III input and dual OpenLDI output.

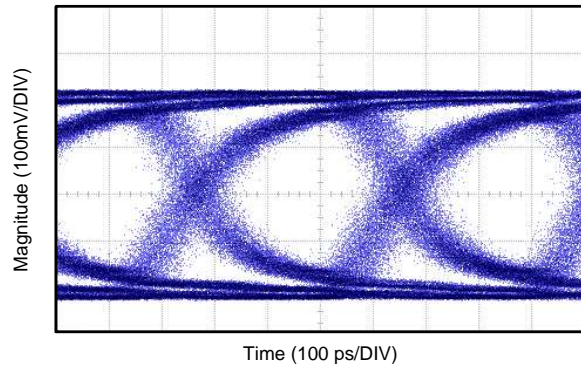


Figure 52. Loop-through CML Output at 2.6 Gbps Serial Line Rate

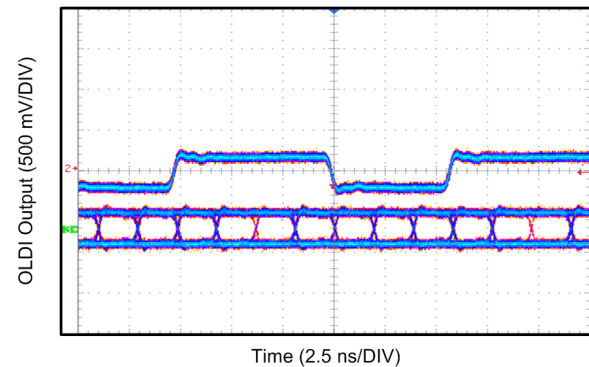


Figure 53. OpenLDI Clock and Data Output at 74.25 MHz Pixel Clock

10 Power Supply Recommendations

This device provides separate power and ground pins for different portions of the circuit. This is done to isolate switching noise effects between different sections of the circuit. Separate planes on the PCB are typically not required. Pin Description table provide guidance on which circuit blocks are connected to which power pin pairs. In some cases, an external filter may be used to provide clean power to sensitive circuits such as PLLs.

10.1 Power Up Requirements and PDB Pin

When power is applied, power from the highest voltage rail to the lowest voltage rail on any of the supply pins. For 3.3V IO operation, VDDIO and VDD33 can be powered by the same supply and ramped simultaneously. The power supply ramp (VDD12, VDD33, and VDDIO) should be faster than 1.5ms with a monotonic rise. A large capacitor on the PDB pin is needed to ensure PDB arrives after all the supply pins have settled to the recommended operating voltage. When PDB pin is pulled up to VDD33, a 10 k Ω pull-up and a >10 μ F capacitor to GND are required to delay the PDB input signal rise. All inputs must not be driven until both VDD33 and VDDIO has reached steady state. Pins VDD33_A and VDD33_B should both be externally connected, bypassed, and driven to the same potential (they are not internally connected).

11 Layout

11.1 Layout Guidelines

Circuit board layout and stack-up for the FPD-Link III devices should be designed to provide low-noise power feed to the device. Good layout practice will also separate high frequency or high-level inputs and outputs to minimize unwanted stray noise pickup, feedback and interference. Power system performance may be greatly improved by using thin dielectrics (2 to 4 mils) for power/ground sandwiches. This arrangement provides plane capacitance for the PCB power system with low-inductance parasitics, which has proven especially effective at high frequencies, and makes the value and placement of external bypass capacitors less critical. External bypass capacitors should include both RF ceramic and tantalum electrolytic types. RF capacitors may use values in the range of 0.01 μ F to 0.1 μ F. Tantalum capacitors may be in the 2.2 μ F to 10 μ F range. Voltage rating of the tantalum capacitors should be at least 5X the power supply voltage being used.

Surface mount capacitors are recommended due to their smaller parasitics. When using multiple capacitors per supply pin, locate the smaller value closer to the pin. A large bulk capacitor is recommend at the point of power entry. This is typically in the 50 μ F to 100 μ F range and will smooth low frequency switching noise. It is recommended to connect power and ground pins directly to the power and ground planes with bypass capacitors connected to the plane with via on both ends of the capacitor. Connecting power or ground pins to an external bypass capacitor will increase the inductance of the path.

Layout Guidelines (continued)

A small body size X7R chip capacitor, such as 0603 or 0402, is recommended for external bypass. Its small body size reduces the parasitic inductance of the capacitor. The user must pay attention to the resonance frequency of these external bypass capacitors, usually in the range of 20MHz to 30 MHz. To provide effective bypassing, multiple capacitors are often used to achieve low impedance between the supply rails over the frequency of interest. At high frequency, it is also a common practice to use two vias from power and ground pins to the planes, reducing the impedance at high frequency.

Some devices provide separate power and ground pins for different portions of the circuit. This is done to isolate switching noise effects between different sections of the circuit. Separate planes on the PCB are typically not required. Pin Description tables typically provide guidance on which circuit blocks are connected to which power pin pairs. In some cases, an external filter may be used to provide clean power to sensitive circuits such as PLLs.

Use at least a four layer board with a power and ground plane. Locate LVCMOS signals away from the CML lines to prevent coupling from the LVCMOS lines to the CML lines. Closely-coupled differential lines of 100 Ω are typically recommended for CML interconnect. The closely coupled lines help to ensure that coupled noise will appear as common-mode and thus is rejected by the receivers. The tightly coupled lines will also radiate less.

Information on the WQFN style package is provided in TI Application Note: [AN-1187](#).

11.2 Layout Example

Stencil parameters such as aperture area ratio and the fabrication process have a significant impact on paste deposition. Inspection of the stencil prior to placement of the WQFN package is highly recommended to improve board assembly yields. If the via and aperture openings are not carefully monitored, the solder may flow unevenly through the DAP. Stencil parameters for aperture opening and via locations are shown in [Figure 54](#):

Table 13. No Pullback WQFN Stencil Aperture Summary

| Device | Pin Count | Mkt Dwg | PCB I/O Pad Size (mm) | PCB Pitch (mm) | PCB DAP Size(mm) | Stencil I/O Aperture (mm) | Stencil DAP Aperture (mm) | Number OF DAP Aperture Openings | Gap between DAP Aperture (Dim A mm) |
|--------------|-----------|---------|-----------------------|----------------|------------------|---------------------------|---------------------------|---------------------------------|-------------------------------------|
| DS90UB948-Q1 | 64 | NKD | 0.25 x 0.6 | 0.5 | 7.2 x 7.2 | 0.25 x 0.6 | 1.16 x 1.16 | 25 | 0.2 |

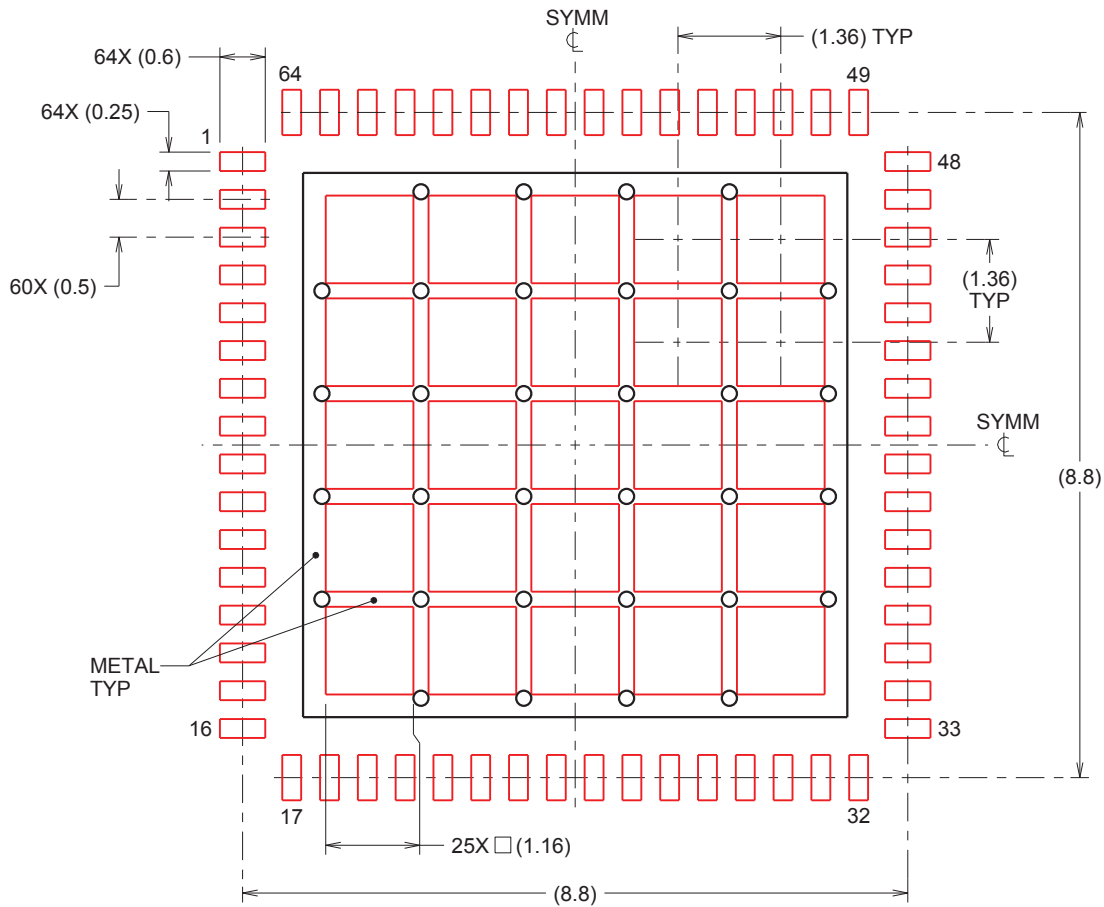


Figure 54. 64-Pin WQFN Stencil Example of Via and Opening Placement (dimensions in mm)

Figure 55 (PCB layout example) is derived from a layout design of the DS90UB948-Q1. This graphic and additional layout description are used to demonstrate both proper routing and proper solder techniques when designing in the Deserializer.

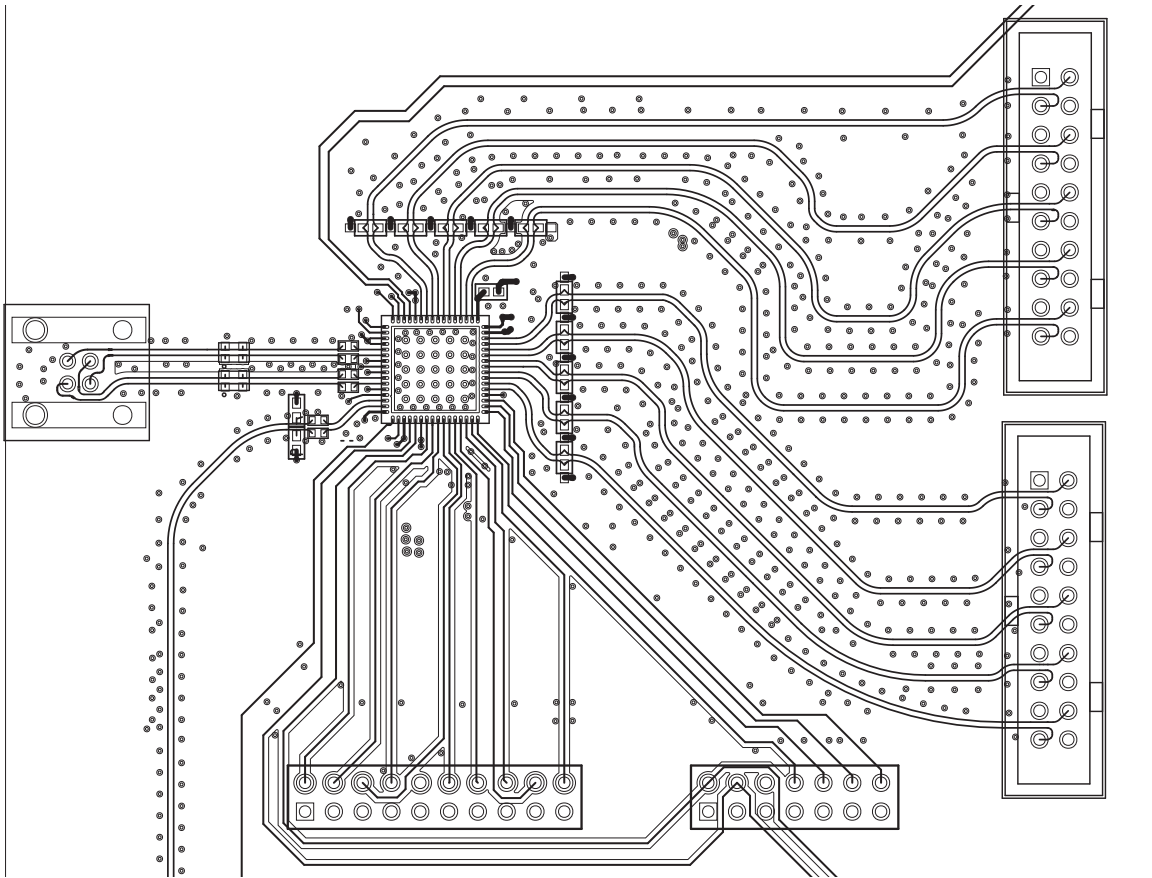


Figure 55. DS90UB948-Q1 Deserializer Example Layout

12 器件和文档支持

12.1 文档支持

12.1.1 相关文档

相关文档如下：

- 《焊接规范应用报告》， [SNOA549](#)
- 《IC 封装热指标应用报告》， [SPRA953](#)
- 《通道链路 PCB 和互连设计指南》， [SNLA008](#)
- 《传输线路 RAPIDESIGNER 操作和应用指南》， [SNLA035](#)
- 《无引线框架封装 (LLP) 应用报告》， [SNOA401](#)
- 《LVDS 所有者手册》， [SNLA187](#)
- 《通过具有双向控制通道的 FPD-Link III 进行 I2C 通信》， [SNLA131](#)
- 《使用 DS90Ux92x FPD-Link III 器件的 I2S 音频接口》， [SNLA221](#)
- 《探索 720p FPD-Link III 器件的内部测试图案生成特性》， [SNLA132](#)

12.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

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12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。这些信息是针对指定器件可提供的最新数据。这些数据会在无通知且不对本文档进行修订的情况下发生改变。欲获得该数据表的浏览器版本，请查阅左侧的导航栏。

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| 放大器和线性器件 | www.ti.com.cn/amplifiers | 计算机及周边 | www.ti.com.cn/computer |
| 数据转换器 | www.ti.com.cn/dataconverters | 消费电子 | www.ti.com.cn/consumer-apps |
| DLP® 产品 | www.dlp.com | 能源 | www.ti.com.cn/energy |
| DSP - 数字信号处理器 | www.ti.com.cn/dsp | 工业应用 | www.ti.com.cn/industrial |
| 时钟和计时器 | www.ti.com.cn/clockandtimers | 医疗电子 | www.ti.com.cn/medical |
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邮寄地址: 上海市浦东新区世纪大道1568号, 中建大厦32楼邮政编码: 200122
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PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead/Ball Finish (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|---------------|--------------|--------------------|------|----------------|----------------------------|-------------------------|----------------------|--------------|-------------------------|-------------------------|
| DS90UB948TNKDRQ1 | ACTIVE | WQFN | NKD | 64 | 2000 | Green (RoHS & no Sb/Br) | CU SN | Level-3-260C-168 HR | -40 to 105 | 90UB948Q1 | Samples |
| DS90UB948TNKDTQ1 | ACTIVE | WQFN | NKD | 64 | 250 | Green (RoHS & no Sb/Br) | CU SN | Level-3-260C-168 HR | -40 to 105 | 90UB948Q1 | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|------------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| DS90UB948TNKDRQ1 | WQFN | NKD | 64 | 2000 | 330.0 | 16.4 | 9.3 | 9.3 | 1.3 | 12.0 | 16.0 | Q1 |
| DS90UB948TNKDTQ1 | WQFN | NKD | 64 | 250 | 178.0 | 16.4 | 9.3 | 9.3 | 1.3 | 12.0 | 16.0 | Q1 |

TAPE AND REEL BOX DIMENSIONS



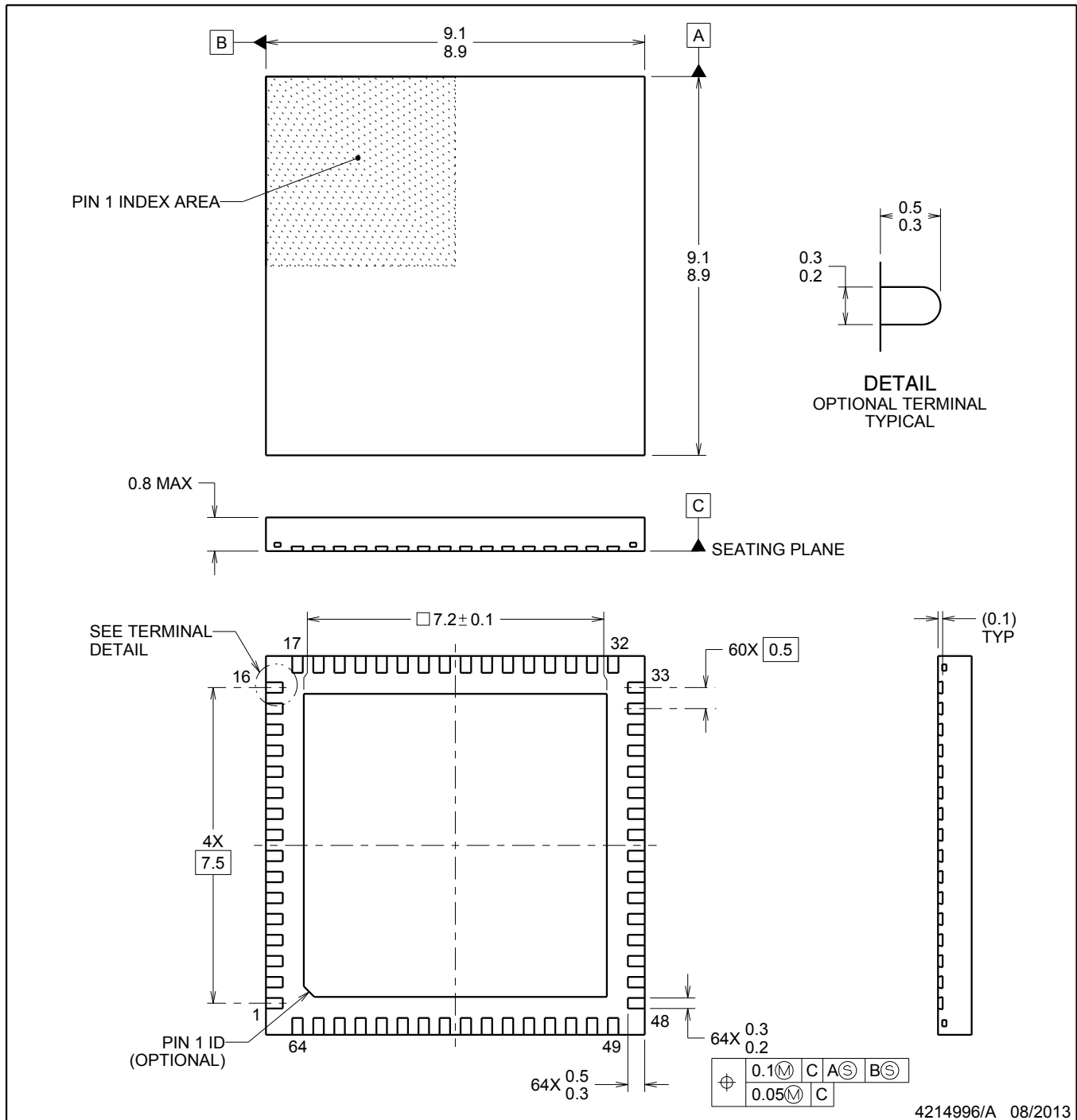
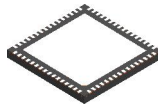
*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|------------------|--------------|-----------------|------|------|-------------|------------|-------------|
| DS90UB948TNKDRQ1 | WQFN | NKD | 64 | 2000 | 367.0 | 367.0 | 38.0 |
| DS90UB948TNKDTQ1 | WQFN | NKD | 64 | 250 | 210.0 | 185.0 | 35.0 |

NKD0064A

WQFN - 0.8 mm max height

WQFN



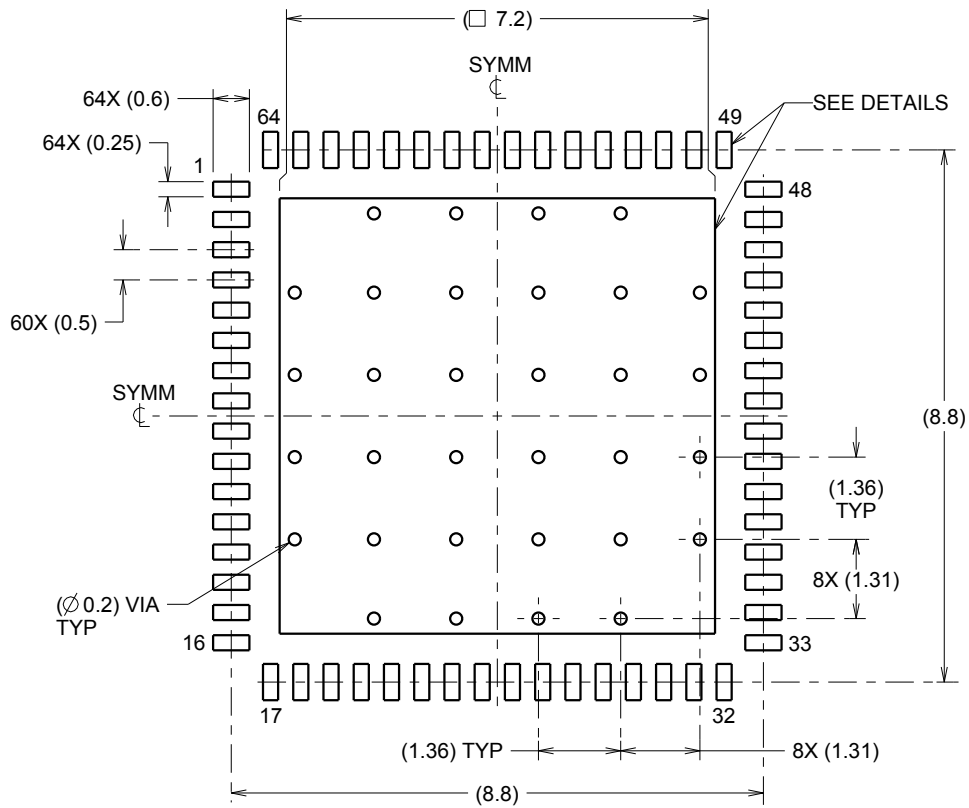
NOTES:

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

NKD0064A

WQFN - 0.8 mm max height

WQFN



LAND PATTERN EXAMPLE
SCALE:8X

0.07 MAX
ALL AROUND



METAL

SOLDER MASK
OPENING

NON SOLDER MASK
DEFINED
(PREFERRED)

0.07 MIN
ALL AROUND



SOLDER MASK
OPENING

METAL

SOLDER MASK
DEFINED

SOLDER MASK DETAILS

4214996/A 08/2013

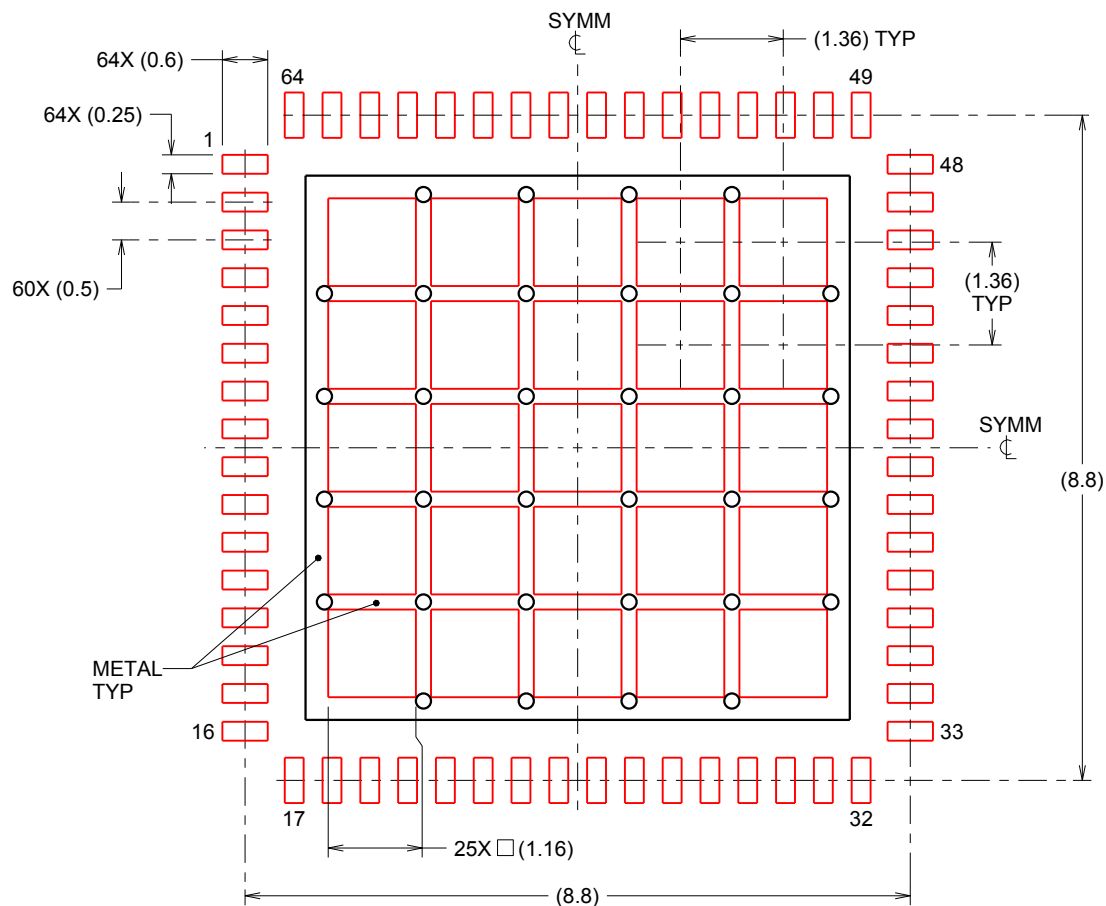
NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, refer to QFN/SON PCB application note in literature No. SLUA271 (www.ti.com/lit/sluea271).

NKD0064A

WQFN - 0.8 mm max height

WQFN



SOLDERPASTE EXAMPLE
BASED ON 0.125mm THICK STENCIL

EXPOSED PAD
65% PRINTED SOLDER COVERAGE BY AREA
SCALE:10X

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NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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