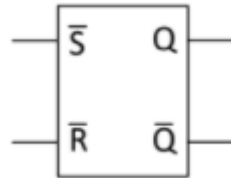
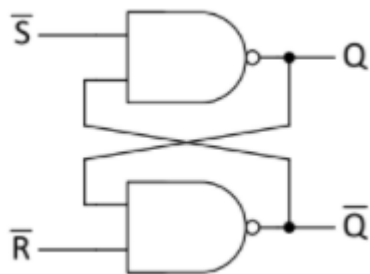
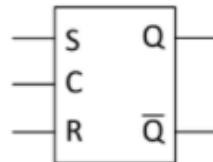
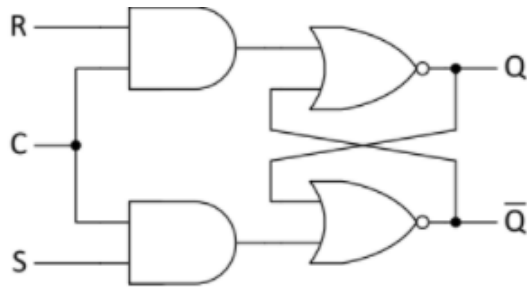


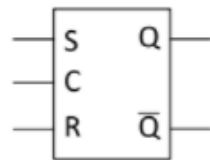
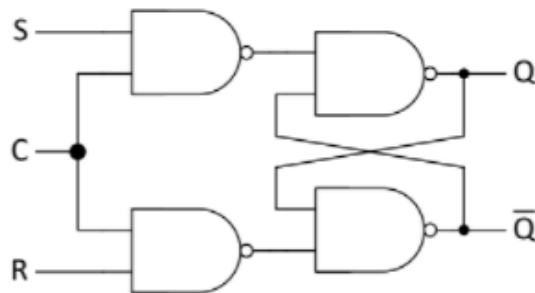
S	R	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	0	$Q_t$	$\bar{Q}_t$
0	1	0	1
1	0	1	0
1	1	0	0



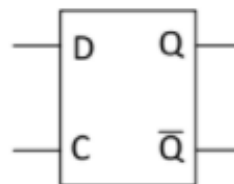
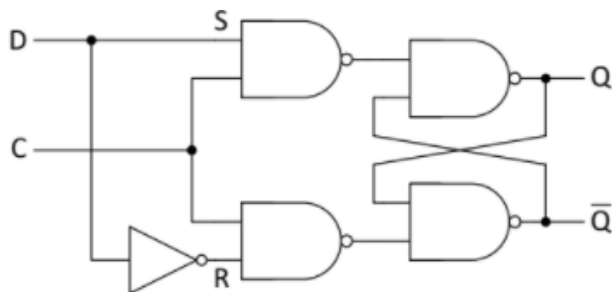
$\bar{S}$	$\bar{R}$	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	0	1	1
0	1	1	0
1	0	0	1
1	1	$Q_t$	$\bar{Q}_t$



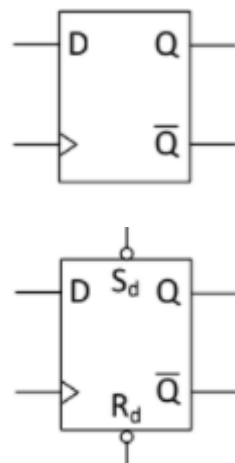
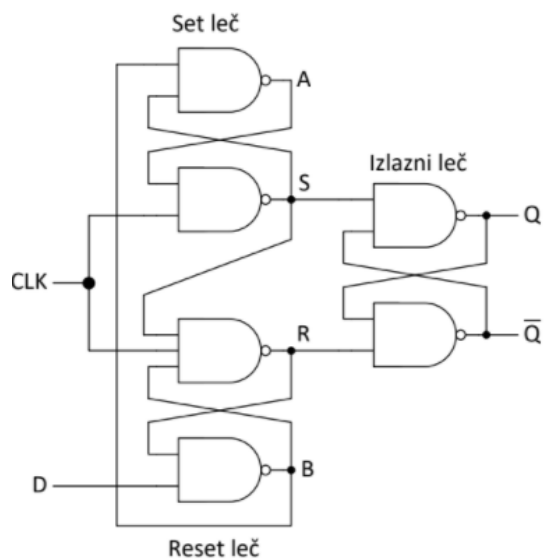
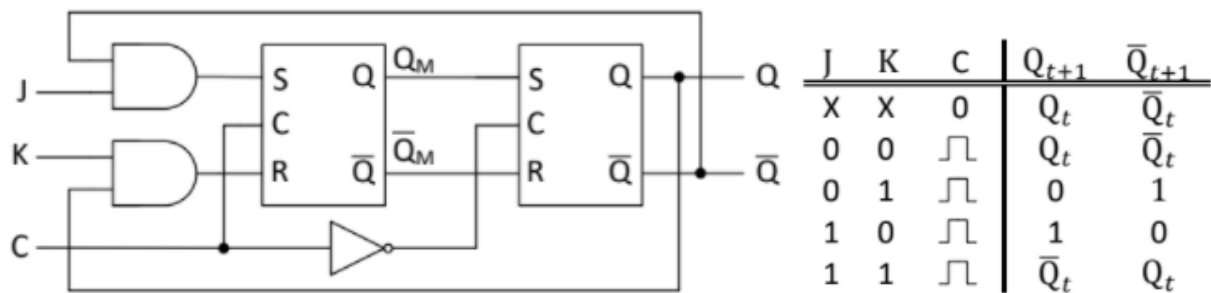
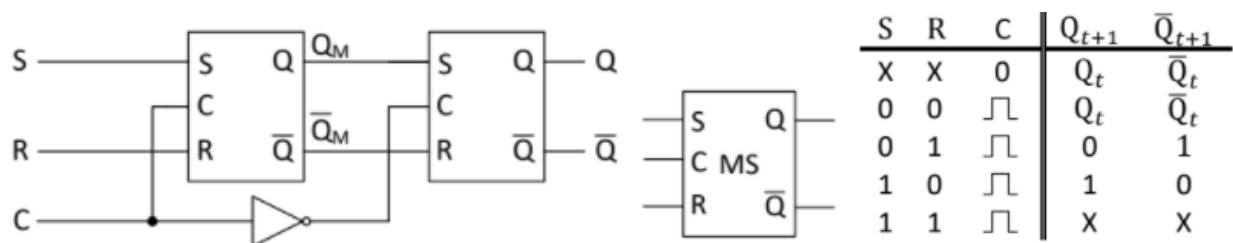
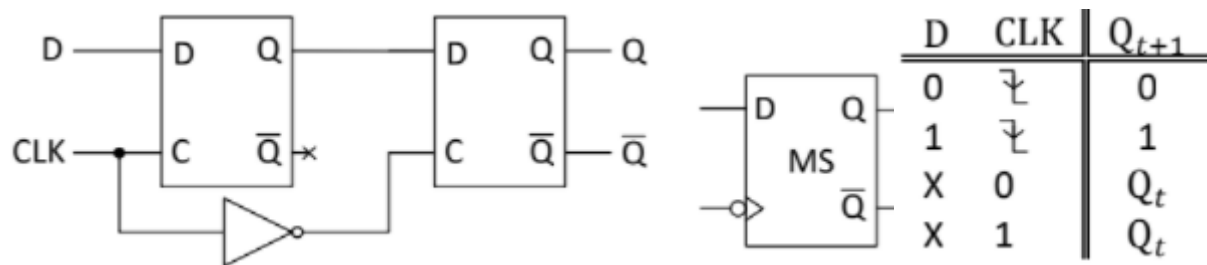
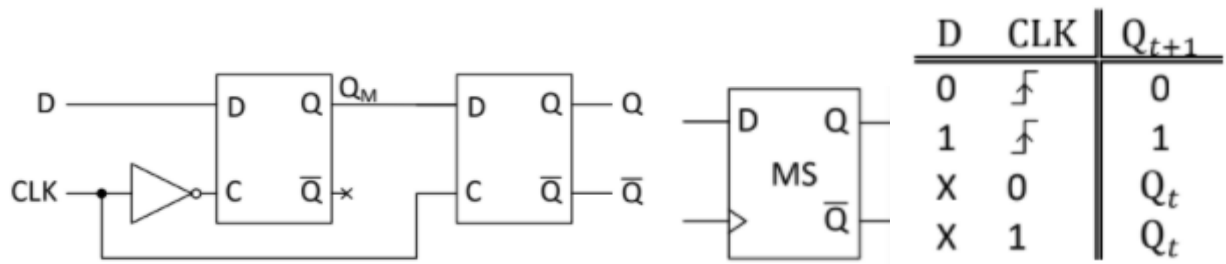
C	S	R	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	X	X	$Q_t$	$\bar{Q}_t$
1	0	0	$Q_t$	$\bar{Q}_t$
1	0	1	0	1
1	1	0	1	0
1	1	1	0	0

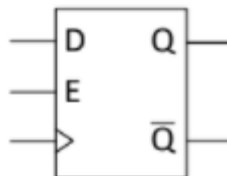
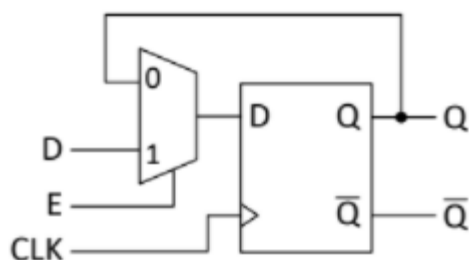


C	S	R	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	X	X	$Q_t$	$\bar{Q}_t$
1	0	0	$Q_t$	$\bar{Q}_t$
1	0	1	0	1
1	1	0	1	0
1	1	1	1	1

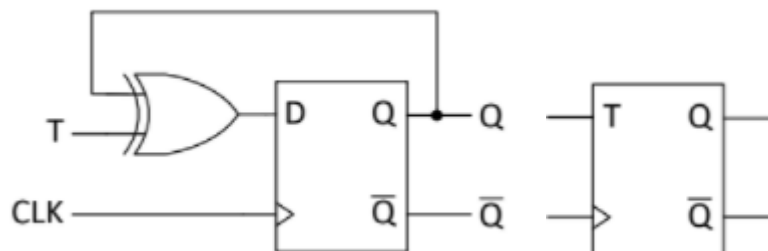


C	D	$Q_{t+1}$
0	X	$Q_t$
1	0	0
1	1	1

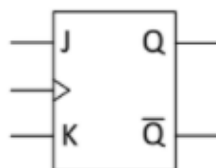
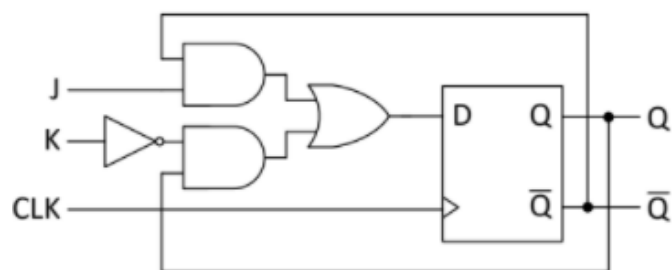
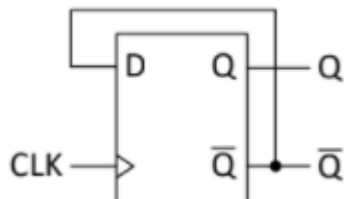




D	E	CLK	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	1	↓	0	1
1	1	↓	1	0
X	0	↓	$Q_t$	$\bar{Q}_t$
X	X	0	$Q_t$	$\bar{Q}_t$
X	X	1	$Q_t$	$\bar{Q}_t$



T	CLK	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	↓	$Q_t$	$\bar{Q}_t$
1	↓	$\bar{Q}_t$	$Q_t$
X	0	$Q_t$	$\bar{Q}_t$
X	1	$Q_t$	$\bar{Q}_t$



J	K	CLK	$Q_{t+1}$	$\bar{Q}_{t+1}$
0	0	↓	$Q_t$	$\bar{Q}_t$
0	1	↓	0	1
1	0	↓	1	0
1	1	↓	$\bar{Q}_t$	$Q_t$
X	X	0	$Q_t$	$\bar{Q}_t$
X	X	1	$Q_t$	$\bar{Q}_t$

Tip	Karakteristična jednačina
SR leč SR MS flip-flop	$Q_{t+1} = S + \bar{R} \cdot Q_t$ uz ograničenje $S \cdot R = 0$
D leč; D MS flip-flop i D flip-flop sa ivičnim okidanjem	$Q_{t+1} = D$
D flip-flop sa dozvolom	$Q_{t+1} = E \cdot D + \bar{E} \cdot Q_t$
JK MS flip-flop i JK flip-flop sa ivičnim okidanjem	$Q_{t+1} = J \cdot \bar{Q}_t + \bar{K} \cdot Q_t$
T flip-flop	$Q_{t+1} = \bar{Q}_t$
T flip-flop sa dozvolom	$Q_{t+1} = E \cdot \bar{Q}_t + \bar{E} \cdot Q_t$