

Petra: Simplified, scalable verification using an object-oriented, compositional process calculus

Extended Abstract

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ABSTRACT

Formal methods are yet to be utilized in mainstream software development due to issues in scaling and implementation costs. This work is about developing a scalable, simplified, pragmatic, formal software development method with strong correctness properties and guarantees that are easy to prove. The method aims to be easy to learn, use and apply without extensive training and experience in formal methods. Petra is proposed as an object-oriented, process calculus with composable data types and sequential/parallel processes. Petra has a simple denotational semantics, which includes a definition of Correct by Construction. The aim is for Petra to be standard which can be implemented to execute on various mainstream programming platforms such as Java. Work towards an implementation of Petra as a Java EDSL (Embedded Domain Specific Language) is also discussed.

KEYWORDS

AICC; EDSL, Abstraction; Composition; Correct by Construction; Deterministic; Embedded Domain Specific Language; Parallelism; Refinement; Software Verification; Total Correctness; \LaTeX

1 INTRODUCTION

Object-oriented programming (OOP) has been a popular paradigm for many years in mainstream programming. OOP languages such as Java, C#, C++ and Python have consistently occupied top spots in the TIOBE language index [1]. This is largely due to OOP being a natural way for humans to model the real world, hence OOP helps to validate desired behaviour. Validation proves existence of errors in expected behaviour. Verification proves absence of logical errors, which affect expected behavior. Both verification and validation are key in systems engineering. Validation is a human activity and requires domain expertise in order to review designs and create tests. For large systems it is impractical to perform exhaustive checking of expected behaviours, through validation alone. Verification can be automated as it involves checking the logical structure of a system, independent of a particular domain.

Our solution is a language (Petra) which aims for the strongest possible verification checks (whilst being expressive enough for

deterministic systems). Petra aims to be easy to program, efficient to check automatically for large systems and easy to validate through both testing and code reviews. This allows developers to spend more time on human activities i.e. coding and validating desired behaviour, with respect to a particular domain. Petra consists of an OO, compositional, process calculus, with an abstract syntax (section 3), a denotational semantics (section 4.2). In addition work has been developed towards a pragmatic implementation of Petra as a Java EDSL. This consists of a concrete Java syntax (section 3.1) and Java implementation of a syntax rewriting system, which gives rise to an operational semantics. The syntax rewriting system rewrites valid Petra programs into programs of sequential transformations only. This simplifies reasoning and automation of reachability checks. In addition this allows for an operational semantics of Petra to be understood as a sequence of transformations on a concrete input state. Please note only the denotational semantics will be discussed in detail. Work towards the rewriting system and implementation can be accessed at [2].

2 METHOD

We prototype a language as an embedded Java DSL, in order to leverage our experience in a mainstream platform and reduce the effort needed to develop tooling such as compilers and IDEs. This means ideas can be tested out quickly, therefore the overall programming experience can be feedback into decision making more frequently. Abstraction, composition and refinement are the key concepts used to develop Petra's programming model.

2.1 State Abstraction & Composition

OOP objects are required to have symbolic abstractions for their underlying state-space. This reduces the cognitive and computational complexity when reasoning about possible states. E.g below we can see below the underlying states space of Pixel is a tuple of 3 bytes i.e. 255 x 255 x 255 values (via the Cartesian product of 3 sets each which represent a byte), however the use-case only requires the pixel to be in either pink or yellow and so we can abstract it using two symbolic states. These capture only these states using predicates over the underlying states space. Only these abstractions are publicly accessible to other objects and this allows the states we are not interested in to be encapsulated.

$$\begin{aligned} & \text{object Pixel}\{\text{Byte } R, \text{Byte } G, \text{Byte } B, \\ \text{pink} &= R \text{ eq } 255 \wedge G \text{ eq } 192 \wedge B \text{ eq } 203, \\ \text{yell} &= R \text{ eq } 255 \wedge G \text{ eq } 255 \wedge B \text{ eq } 0\} \end{aligned} \quad (1)$$

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This allows us to compose objects and to formally reason about the overall state space. For example consider the composition of two pixels below.

$$\begin{aligned} \text{object Pixels} \{ & \text{Pixels } p1, \text{ Pixels } p2, \\ & \text{bothPink} = p1.\text{pink} \wedge p2.\text{pink}, \\ & \text{bothYell} = p1.\text{yellow} \wedge p2.\text{yellow} \} \end{aligned} \quad (2)$$

The overall states pace of this object is given by the Cartesian product of pixels abstracted symbolic states. E.g.

$$\{(pink, pink), (pink, yell), (yell, pink), (yell, yell)\} \quad (3)$$

Then we can resolve the bothPink and bothYellow symbolic states into concrete states by substituting the symbols with sets of symbols recursively using the predicates over the underlying state space, until we arrive at primitive values.

$$\begin{aligned} \text{bothPink} &= \{((255, 192, 203), (255, 192, 203))\} \\ \text{bothYell} &= \{((255, 255, 0), (255, 255, 0))\} \end{aligned} \quad (4)$$

2.2 Process Composition

Petra objects can contain steps which are processes either composed of other steps or are primitive steps on primitive data types. Steps are provided with pre/post conditions thus forming a contract (which interpreted as a total function signature) which describes the behaviour of the steps process over a specified state space. The contract is split into one or more kase statements (sub-contracts), each with pre/post-condition pairs, with pre-conditions that represent disjoint states. Steps are composed using these contracts. Currently basic sequential and parallel composition supported (see appendix 3, SEQ_RULE, SEP_SEQ_PAR_RULE), with the aim of supporting various types of parallel and sequential iteration in the future. All computations in Petra are deterministic and terminating thus providing Total Correctness [3]. Each step is interpreted as a total function and both sequential/parallel composition (see SEQ_RULE, SEP_SEQ_PAR_RULE) are defined using operators that ensure only total functions are produced.

2.3 Process Abstraction & Refinement

Each kase sub-contract is an abstraction of the underlying composition of steps within the kase. This abstraction is only valid if the steps composition (also a total function) refines the contract's function (see STEP_RULE and ??).

2.4 Light System Example

Below we have an example system written in Petra's abstract syntax (Appendix 3). This will be used in simple a proof of refinement using the rules from Petra's denotational semantics (Appendix 4.2) over the abstract syntax. The example will show that the step within the kase statement refines the kase's contract.

2.4.1 Definitions.

$$\begin{aligned} \text{object Pwr} \{ & \text{Bool } b \text{ on} = t, \text{ off} = f \\ & \text{on} = \text{kases}(\text{kase}(\text{on} \vee \text{off}, \text{on}, p.b.\text{setTrue})) \\ & \text{off} = \text{kases}(\text{kase}(\text{on} \vee \text{off}, \text{off}, p.b.\text{setFalse})) \} \end{aligned} \quad (5)$$

$$\begin{aligned} \text{object Btn} \{ & \text{Bool } b \text{ on} = t, \text{ off} = f \\ & \text{on} = \text{kases}(\text{kase}(\text{on} \vee \text{off}, \text{on}, b.b.\text{setTrue})) \\ & \text{off} = \text{kases}(\text{kase}(\text{on} \vee \text{off}, \text{off}, b.b.\text{setFalse})) \} \end{aligned} \quad (6)$$

$$\begin{aligned} \text{object Lht} \{ & \text{Btn } b, \text{ Pwr } p, \\ & \text{on} = p.\text{on} \wedge b.\text{on}, \\ & \text{off} = p.\text{off} \vee b.\text{off}, \\ & \text{toggle} = \text{kases}(\text{kase}(\text{off}, \text{on}, \text{Pwr.on} \parallel \text{Btn.on}), \\ & \text{kase}(\text{on}, \text{off}, \text{Pwr.off}; \text{Btn.off})) \} \end{aligned} \quad (7)$$

2.5 Example proof: Refinement of 1st kase statement in Light

$$\begin{aligned} \text{Apply STEP_RULE :} \\ \llbracket \text{kase}(\text{off}, \text{on}, \text{Pwr.on} \parallel \text{Btn.on}) \rrbracket = \\ \llbracket \text{Btn.on} \parallel \text{Pwr.on} \rrbracket^{Lht} \upharpoonright_R \text{ if } \llbracket \text{Btn.on} \parallel \text{Pwr.on} \rrbracket^{Lht} \upharpoonright_R \subseteq \llbracket \text{off}, \text{on} \rrbracket^{Lht} \\ \text{where } R = \text{dom}(\llbracket \text{off}, \text{on} \rrbracket^{Lht}) \end{aligned} \quad (8)$$

$$\begin{aligned} \text{Apply RESOLVE_CONTRACT_RULE :} \\ \llbracket \text{off}, \text{on} \rrbracket^{Lht} = \llbracket \text{off} \rrbracket^{Lht} \rightarrow \llbracket \text{on} \rrbracket^{Lht} = \{(t, f), (f, f), (f, t)\} \rightarrow \{(t, t)\} \end{aligned} \quad (9)$$

$$\begin{aligned} \text{Apply ASSUME_STEP_RULE :} \\ \llbracket \text{Btn.on} \rrbracket = \llbracket \text{on} \vee \text{off} \rrbracket^{Bnt} \rightarrow \llbracket \text{on} \rrbracket^{Bnt} = \{t, f\} \rightarrow \{t\} = \{t \mapsto t, f \mapsto t\} \\ \llbracket \text{Pwr.on} \rrbracket = \llbracket \text{on} \vee \text{off} \rrbracket^{Pwr} \rightarrow \llbracket \text{on} \rrbracket^{Pwr} = \{t, f\} \rightarrow \{t\} = \{t \mapsto t, f \mapsto t\} \end{aligned} \quad (10)$$

$$\begin{aligned} \text{Apply SEP_SEQ_PAR_RULE :} \\ \llbracket \text{Btn.on} \parallel \text{Pwr.on} \rrbracket = \llbracket \text{Btn.on} \rrbracket \times \llbracket \text{Pwr.on} \rrbracket \\ \llbracket \text{Btn.on} \parallel \text{Pwr.on} \rrbracket = \\ \{(t, t) \mapsto (t, t), \\ (t, f) \mapsto (t, t), \\ (f, t) \mapsto (t, t), \\ (f, f) \mapsto (t, t)\} \end{aligned} \quad (11)$$

$$\begin{aligned} \llbracket \text{Btn.on} \parallel \text{Pwr.on} \rrbracket^{Lht} \upharpoonright_R \subseteq \llbracket \text{off}, \text{on} \rrbracket^{Lht} \\ \text{where } R = \text{dom}(\llbracket \text{off}, \text{on} \rrbracket^{Lht}) = \\ \{(t, t) \mapsto (t, t), \\ (t, f) \mapsto (t, t), \\ (f, t) \mapsto (t, t), \\ (f, f) \mapsto (t, t)\} \\ \subseteq \end{aligned}$$

$$\{(t, f), (f, f), (f, t)\} \rightarrow \{(t, t)\}$$

$$\begin{aligned} &= \\ &\{(t, t) \mapsto (t, t), \\ &(t, f) \mapsto (t, t), \\ &(f, t) \mapsto (t, t), \\ &(f, f) \mapsto (t, t)\} \\ &\subseteq \\ &\{(t, f) \mapsto (t, t), \\ &(f, f) \mapsto (t, t), \\ &(f, t) \mapsto (t, t)\} \\ &\Rightarrow \end{aligned}$$

$$\begin{aligned} \llbracket \text{kase}(\text{off}, \text{on}, \text{Pwr.on} \parallel \text{Btn.on}) \rrbracket = \llbracket \text{Btn.on} \parallel \text{Pwr.on} \rrbracket^{Lht} \upharpoonright_R = \\ \{(t, f) \mapsto (t, t), \\ (f, t) \mapsto (t, t), \\ (f, f) \mapsto (t, t)\} \end{aligned} \quad (12)$$

■

3 APPENDIX: SYNTAX

3.1 Abstract Syntax

$\text{obj} ::= \text{object } A \{ \bar{\beta} \bar{\gamma} \bar{\delta} \}$
 $\bar{\beta} ::= B_i b_i$
 $\bar{\gamma} ::= p_j = e_j$
 $\bar{\delta} ::= m_k = ks_k$
 $e ::= b_i.p_j \mid e \wedge e \mid e \vee e \mid e + e \mid \neg e$
 $ks ::= kases(k_i)$
 $k ::= kase(v, w)$
 $c ::= p_j \mid e$
 $v ::= c_p, c_q$
 $s ::= A.m_k$
 $w ::= w; z \mid z$
 $z ::= s \mid \text{parc}$
 $\text{parc} ::= \text{parc} \parallel s \mid s$

3.2 Concrete Syntax (Java)

$\text{obj} ::= \text{interface } A \{ \bar{\beta} \bar{\gamma} \bar{\delta} \}$
 $\bar{\beta} ::= B_i b_i;$
 $\bar{\gamma} ::= \text{default boolean } p_j \{ \text{return } e_j; \}$
 $\bar{\delta} ::= \text{static void } m(A a) \{ ks; \}$
 $e ::= b_i.p_j \mid e \&\& e \mid e \parallel e \mid e^{\wedge} e \mid !e$
 $ks ::= kases(a, \bar{k})$
 $\bar{k} ::= kase_i(v, a \rightarrow w)$
 $v ::= p, q$
 $c ::= a.p_j \mid e$
 $p ::= a \rightarrow c_p$
 $q ::= a \rightarrow c_q$
 $w ::= w; z; \mid z;$
 $z ::= \text{seqc} \mid \text{join}(\text{parc})$
 $r ::= a \mid a.b_i$
 $\text{seqc} ::= \text{seqc}; \text{seq}(r, s) \mid \text{seq}(r, s)$
 $\text{parc} ::= \text{parc}, \text{par}(a \rightarrow a.b_i, s) \mid \text{par}(a \rightarrow a.b_i, s)$
 $s ::= A :: m$

4 APPENDIX: FORMAL SEMANTICS

A formal semantics of Petra is provided here using a denotational style over an abstract syntax (3) which captures the core concepts and behaviour of the Petra programming language and paradigm. The idea is that Petra programs should only be composed of total functions (transforms) between the observable states of program data. Both the functions and data are stored within objects, similar to objects in OOP. At a high-level the semantics describes an object as a mathematical structure that captures the observable states of the object's data, and the possible transitions between subsets of the observable states. Petra steps are interpreted as total functions, which compose sequentially and in parallel to produce total functions. This simplifies reasoning and programming as total functions are deterministic, terminating and have all their inputs mapped, which means the developer does not have to worry about random behaviours, that can be possibly be non-terminating (which are harder to compose) and about values that which will not be mapped. A description for each part of the syntax will be provided in the next section.

4.1 Explanation of Abstract Syntax

Petra's abstract syntax provides a means of describing objects with state and steps which cause state transitions.

obj, is the entry point into the syntax which provides the structure of an objects definition.

$\bar{\beta}$, is a collection field declarations (indexed over i for use in the denotation semantics that will follow this section).

\bar{y} , is a predicate (e) with a label (p). The predicate represents an observable state within the object, if the predicate evaluates to true then the state described by the predicate is the current state of the object.

$\bar{\delta}$, is a collection of steps each of which are a kases statement (ks), labeled by m (indexed over k for use in the denotation semantics).

e, is a boolean expression language for predicates (where the field terms are indexed by i and the predicate labels are indexed by j, for use in the denotation semantics).

ks, is a kases statement which contains multiple kase statements (k, indexed by i for use in the denotational semantics).

k, is a kase statement which contains the contract (v) and the step composition (w).

c, is a condition used within the kase contract, c can be either a local predicate (p) or a predicate (e).

v, is the kase contract which contains a precondition (c_p) and post-condition (c_q).

s, is a step which is named by the object it is contained within (A) and then by a name for the step within this object (m).

w, is a number of sequentially composed steps (z).

z, is either a named step (s) or a parallel composed step (parc).

parc, is any number of parallel composed named steps (s).

4.2 Denotational Semantics

Definition 4.1. Petra Program.

A petra program is a tuple $\langle A.m, A, \overline{obj} \rangle$, where A.m is the root object step (the entry point), A is the root object, \overline{obj} is the set of object definitions.

Definition 4.2. Correct by Construction.

A Petra program is correct by construction if:

$$\llbracket A.m \rrbracket : X \rightarrow X$$

where $X = \llbracket A \rrbracket_1 \cup \{\perp\}$ and

$\llbracket A.m \rrbracket$ is a total function with the codomain is restricted to $\llbracket A \rrbracket_1$

4.3 Objects

The structure of objects is a tuple containing a set of observable states, a record of predicate labels mapping to subsets of the observable states, and finally a record of step labels which map to total functions.

$$\begin{aligned} \llbracket A \rrbracket &= (A, \llbracket \bar{y} \rrbracket, \llbracket \bar{\delta} \rrbracket) \\ \text{where each } P_j &\subseteq A \\ \text{and each } f_k &: A \rightarrow A \end{aligned} \tag{13}$$

where

$$\begin{aligned} \llbracket \bar{y} \rrbracket &= \{p_j = P_j\} \\ \llbracket \bar{\delta} \rrbracket &= \{m_k = f_k\} \end{aligned}$$

$$\begin{aligned} \llbracket \text{object } A \{ B_i \ b_i, \ p_j = e_j, \ m_k = ks_k \} \rrbracket &= \\ (\llbracket B_1 \rrbracket_1 \times \llbracket B_2 \rrbracket_1 \dots \times \llbracket B_I \rrbracket_1) & \\ , \{p_j = \llbracket e_j \rrbracket^A\}, \{m_k = \llbracket ks_k \rrbracket^A\} & \\ \text{(COMPUTE_OBJECT_RULE)} & \end{aligned}$$

The compute objects rule below shows how the set of observable states is the product of all the sets of observable states of the objects fields. Also shown here is how predicate and step labels map to predicate expressions and total function (given by the meaning of kases statements), respectively.

Each primitive type has a corresponding primitive object e.g.

$$\begin{aligned} \llbracket Bool \rrbracket &= \\ (B, \{isTrue = \{t\}, isFalse = \{f\}\} & \\ , \{setTrue = \{t, f\} \rightarrow \{t\}\}, setFalse = \{t, f\} \rightarrow \{f\}\}) & \\ \text{(ASSUME_PRIMITIVE_RULE)} & \end{aligned}$$

The assume primitive rule allows the semantics of primitive objects to be assumed primitive. Note objects are either primitive or non-primitive.

4.4 Predicates

$$\llbracket b_i.p_j \rrbracket^A = \llbracket B_1 \rrbracket_1 \times \llbracket B_2 \rrbracket_1 \times \dots \times (\llbracket e_j \rrbracket^A \cap \llbracket B_i \rrbracket_1) \times \llbracket B_{i+1} \rrbracket_1 \times \dots \times \llbracket B_I \rrbracket_1$$

$$\begin{aligned} \text{where } \llbracket b_i.p_1 \rrbracket^A \cap \llbracket b_i.p_2 \rrbracket^A \dots \cap \llbracket b_i.p_j \rrbracket^A &= \emptyset \\ \text{(PREDICATE_RULE)} & \end{aligned}$$

The predicate rule shows how the terminal term ($b_i.p_j$) of the predicate expression language (e) is interpreted as a product of all

the sets of observable states of the objects fields but with the i^{th} set of observable states effectively filtered (through set intersection) by the set of states represented by the predicate e_j . There is also a constrain that none of the predicates in an object can overlap, i.e. they must be disjoint. This is due to...

$$\llbracket p_j \rrbracket^A = \llbracket e_j \rrbracket^A \quad (\text{RESOLVE_PREDICATE_RULE})$$

The resolve predicate rule allows a predicate label to be equated to the set which is constructed by the predicates expression.

The rules below construct sets of observable states using the logical connectives within the predicate expression language, in natural ways using set intersection, union and set difference.

$$\llbracket e \wedge e' \rrbracket^A = \llbracket e \rrbracket^A \cap \llbracket e' \rrbracket^A \quad (\text{AND_RULE})$$

$$\llbracket e \vee e' \rrbracket^A = \llbracket e \rrbracket^A \cup \llbracket e' \rrbracket^A \quad (\text{OR_RULE})$$

$$\llbracket e + e' \rrbracket^A = \llbracket e \rrbracket^A \cup \llbracket e' \rrbracket^A \setminus \llbracket e \rrbracket^A \cap \llbracket e' \rrbracket^A \quad (\text{XOR_RULE})$$

$$\llbracket \neg e \rrbracket^A = \llbracket A \rrbracket_1 \setminus \llbracket e \rrbracket^A \quad (\text{NOT_RULE})$$

*Note that $\llbracket B_i \rrbracket_1$ can either be unpacked recursively down to primitive objects, or can be interpreted as the set of predicate labels within B i.e. $\llbracket B_i \rrbracket_1 = \{p_j\}$. The former provides a full concrete description of $\llbracket B_i \rrbracket_1$. The downside is that the complexity of the product and intersection operations required by COMPUTE_OBJECT_RULE and PREDICATE_RULE would be too large to perform in practice for large systems. However this approach has been taken in the proofs 2.4.1 and 4.6, in order to provide a concrete description of state transitions. The latter allows for a symbolic approach which limits the complexity by only allowing set operations to be computed at the level of abstraction provided by $\llbracket B_i \rrbracket$'s predicates labels and the addition of a concretion function would allow the "symbolic" predicate labels to be interpreted as a set of concrete states. This function is provided by the developer through programming the predicates formula, which is built up through layers of sound abstractions from primitive types at the lowest level. The other benefit is that reasoning becomes more explainable as it is performed over names as apposed to fully resolved primitive states.

4.5 Steps

$$\llbracket A.m \rrbracket = \llbracket ks \rrbracket^A \quad (\text{RESOLVE_KASES})$$

The resolve kases rule allows a step label i.e. a kases statement label, to be equated to the total function constructed by the interpretation of the kases statement.

$$\llbracket A.m ; A.m' \rrbracket^A = \llbracket A.m \rrbracket \circ \llbracket A.m' \rrbracket \quad (\text{SEQ_RULE})$$

Sequential step composition is achieved simply through standard function composition of the total functions formed by interpreting the named steps.

$$\llbracket B_x.m ; B_{x+c}.m' \rrbracket^A = \llbracket B_x.m \parallel B_{x+c}.m' \rrbracket^A = z$$

where

$$z = id_1 \times id_2 \dots id_{x-2} \times id_{x-1} \times \llbracket B_x.m \rrbracket \times id_{x+1} \times id_{x+2} \dots id_{x+c-1} \times \llbracket B_{x+c}.m' \rrbracket \times id_{x+c+1} \times id_{x+c+2} \dots id_{I-2} \times id_{I-1} \times id_I,$$

$$dom(\llbracket B_x.m \rrbracket^A) \cap dom(\llbracket B_{x+c}.m' \rrbracket^A) = \emptyset,$$

$$\llbracket B_x \rrbracket_1 * \llbracket B_{x+c} \rrbracket_1,$$

$$s, h \models P_1 * P_2 \text{ where there exist } h_1, h_2$$

$$\text{such that } h_1 \perp h_2 \text{ and } h = h_1 \cup h_2 \text{ and } s, h_1 \models P_1 \text{ and } s, h_2 \models P_2,$$

where $*$ is a separating conjunction which asserts that the heap can be split into two disjoint parts where its two arguments hold.

(SEP_SEQ_PAR_RULE)

Separated sequential and parallel composition is achieved through take the product of a sequence of functions. Where the sequence contains a function for each field in the object in which the composition is taking place. For each field the function is either an identity function over the set of observable states in the field or the interpretation of a named step which acts on the field. For this to work the domains of the functions within the product need to be disjoint. Implementations will use separate memory regions to ensure that the observable states will be disjoint and the parallel composed steps can only mutate separate regions hence they cannot interfere with one another. The function product (which can be understood as a generalized version of equation 14, for any number of functions) and there is an identity function id_i for every field not used by any of the steps in the composition. This provides composition and lifting of transforms on separate state spaces, into the state space of the parent object A.

$$\begin{aligned} f &: X \rightarrow Y, g : U \rightarrow V \\ f \times g &: X \times U \rightarrow Y \times V \\ (f \times g)(x, u) &= (f(x), g(u)) \end{aligned} \quad (14)$$

4.6 Kases

$$\begin{aligned}
\llbracket ks \rrbracket^A &: \llbracket A \rrbracket_1 \cup \{\perp\} \rightarrow \llbracket A \rrbracket_1 \cup \{\perp\} \\
\llbracket ks \rrbracket^A &= \llbracket k_1 \rrbracket^A \cup \llbracket k_2 \rrbracket^A \dots \llbracket k_I \rrbracket^A \text{ if} \\
\text{dom}(\llbracket k_1 \rrbracket^A) \cap \text{dom}(\llbracket k_2 \rrbracket^A) \dots \text{dom}(\llbracket k_I \rrbracket^A) &= \emptyset \text{ and} \\
\llbracket k_1 \rrbracket^A, \llbracket k_2 \rrbracket^A, \dots, \llbracket k_I \rrbracket^A &\dots \neq \text{error} \\
\text{else } \llbracket ks \rrbracket^A &= \text{error, error} = \{\perp \mapsto \perp\}
\end{aligned}$$

(COMBINE_KASES_RULE)

The combine kases rule provides a kases statement with function interpretation with a signature that is a total transform of the set of observations within the kases object, with the addition of the bottom value, in order to allow for error conditions. The interpretation function definition is the union of all the functions which come from the interpretation of each kase within the kases statement. For this to work the domains of each kase's function must be disjoint, as the union of two functions which map the same inputs does not produce a function.

$$\begin{aligned}
\llbracket k \rrbracket^A &: \llbracket A \rrbracket_1 \cup \{\perp\} \rightarrow \llbracket A \rrbracket_1 \cup \{\perp\} \\
\llbracket k \rrbracket^A &= \llbracket kase(v, w) \rrbracket^A
\end{aligned}$$

(15)

The function signature and definition above provides an interpretation of kase statements.

$$\llbracket kase(v, w) \rrbracket^A = \llbracket v \rrbracket^A \text{ if } w \text{ is a primitive step } \wedge \llbracket v \rrbracket^A \text{ is a total function}$$

(ASSUME_STEP_RULE)

The assume step rule interprets a primitive kase as the interpretation of its contract, where the contract must be equivalent to a total function.

$$\begin{aligned}
\llbracket kase(v, w) \rrbracket^A &= \llbracket w \rrbracket^A \upharpoonright_R \text{ if } w \text{ is a non-primitive step } \wedge \\
\llbracket w \rrbracket^A \upharpoonright_R &\subseteq \llbracket v \rrbracket^A
\end{aligned}$$

$$\begin{aligned}
\llbracket kase(v, w) \rrbracket^A &= \text{error if } w \text{ is a non-primitive step } \wedge \\
\llbracket w \rrbracket^A \upharpoonright_R &\not\subseteq \llbracket v \rrbracket^A
\end{aligned}$$

$$\text{where } R = \text{dom}(\llbracket v \rrbracket^A)$$

(STEP_RULE)

The step rule interprets non-primitive kase as the function which results from the interpretation of the kases step composition (w), which has been restricted by the domain of the kases contract, only if the interpreted function fits within the relation provided by the kase contract. Otherwise error returned which is a total function which maps bottom to bottom.

$$\begin{aligned}
\llbracket v \rrbracket^A &= \llbracket c_p, c_q \rrbracket^A = \llbracket c_p \rrbracket^A \rightarrow \llbracket c_q \rrbracket^A \\
\llbracket c_p \rrbracket^A &= \text{set of observable input states described by the pre-condition} \\
\llbracket c_q \rrbracket^A &= \text{set of observable output states described by the post-condition} \\
\text{note } v &\text{ is the kases contract, (see section 3)}
\end{aligned}$$

(RESOLVE_CONTRACT_RULE)

The resolve contract rule takes the pre/post condition pair and interprets it as a relation between the sets of observable states captured by the pre and post conditions according to the PREDICATE_RULE.

5 APPENDIX: FULL PROOF OF LIGHT SYSTEM

5.0.1 Setup.

$$\begin{aligned}
\text{Apply ASSUME_PRIMITIVE_RULE :} \\
\llbracket Pwr \rrbracket_1 &= \{t, f\} \\
\llbracket Btn \rrbracket_1 &= \{t, f\}
\end{aligned}$$

(16)

$$\begin{aligned}
\text{Apply COMPUTE_OBJECT_RULE :} \\
\llbracket Lht \rrbracket_1 &= \llbracket Pwr \rrbracket_1 \times \llbracket Btn \rrbracket_1 = \{(t, t), (t, f), (f, t), (f, f)\}
\end{aligned}$$

(17)

$$\begin{aligned}
\text{Apply RESOLVE_KASES :} \\
\llbracket Lht.toggle \rrbracket^{Lht} &= \llbracket kases(kase(off, on, Pwr.on \parallel Btn.on), \\
&\quad kase(on, off, Pwr.off; Btn.off)) \rrbracket^{Lht}
\end{aligned}$$

(18)

$$\begin{aligned}
\text{Apply COMBINE_KASES_RULE :} \\
\llbracket kases(kase(off, on, Pwr.on \parallel Btn.on), \\
&\quad kase(on, off, Pwr.off; Btn.off)) \rrbracket^{Lht} = \\
\llbracket kase(off, on, Pwr.on \parallel Btn.on) \rrbracket^{Lht} \cup \llbracket kase(off, on, Pwr.on; Btn.on) \rrbracket^{Lht}
\end{aligned}$$

(19)

5.0.2 Prove Toggle object kase 1.

$$\begin{aligned}
\text{Apply STEP_RULE :} \\
\llbracket kase(off, on, Pwr.on \parallel Btn.on) \rrbracket &= \\
\llbracket Btn.on \parallel Pwr.on \rrbracket^{Lht} \upharpoonright_R \text{ if } \llbracket Btn.on \parallel Pwr.on \rrbracket^{Lht} \upharpoonright_R &\subseteq \llbracket off, on \rrbracket^{Lht} \\
\text{where } R &= \text{dom}(\llbracket off, on \rrbracket^{Lht})
\end{aligned}$$

(20)

$$\begin{aligned}
\text{Apply RESOLVE_CONTRACT_RULE :} \\
\llbracket off, on \rrbracket^{Lht} &= \llbracket off \rrbracket^{Lht} \rightarrow \llbracket on \rrbracket^{Lht}
\end{aligned}$$

(21)

$$\begin{aligned}
\text{Apply RESOLVE_PREDICATE_RULE :} \\
\llbracket off \rrbracket^{Lht} &= \llbracket p.off \vee b.off \rrbracket^{Lht}
\end{aligned}$$

(22)

$$\begin{aligned}
\text{Apply OR_RULE :} \\
\llbracket p.off \vee b.off \rrbracket^{Lht} &= \llbracket p.off \rrbracket^{Lht} \cup \llbracket b.off \rrbracket^{Lht}
\end{aligned}$$

(23)

$$\begin{aligned}
\text{Apply PREDICATE_RULE :} \\
\llbracket p.off \rrbracket^{Lht} &= \{t, f\} \times \{f\} = \{(t, f), (f, f)\} \\
\llbracket b.off \rrbracket^{Lht} &= \{f\} \times \{t, f\} = \{(f, t), (f, f)\}
\end{aligned}$$

(24)

$$\llbracket off \rrbracket^{Lht} = \llbracket p.off \rrbracket^{Lht} \cup \llbracket b.off \rrbracket^{Lht} = \{(t, f), (f, f), (f, t)\}$$

(25)

$$\begin{aligned}
\text{Apply RESOLVE_PREDICATE_RULE :} \\
\llbracket on \rrbracket^{Lht} &= \llbracket p.on \wedge b.on \rrbracket^{Lht}
\end{aligned}$$

(26)

$$\begin{aligned}
\text{Apply AND_RULE :} \\
\llbracket p.on \wedge b.on \rrbracket^{Lht} &= \llbracket p.on \rrbracket^{Lht} \cap \llbracket b.on \rrbracket^{Lht}
\end{aligned}$$

(27)

$$\begin{aligned}
\text{Apply PREDICATE_RULE :} \\
\llbracket p.on \rrbracket^{Lht} &= \{t, f\} \times \{t\} = \{(t, t), (f, t)\} \\
\llbracket b.on \rrbracket^{Lht} &= \{t\} \times \{t, f\} = \{(t, t), (t, f)\}
\end{aligned}$$

(28)

$$\llbracket on \rrbracket^{Lht} = \llbracket p.on \rrbracket^{Lht} \cap \llbracket b.on \rrbracket^{Lht} = \{(t, t)\}$$

(29)

5.0.3 Prove Toggle object kase 2.

$$\llbracket off, on \rrbracket^{Lht} = \llbracket off \rrbracket^{Lht} \rightarrow \llbracket on \rrbracket^{Lht} = \{(f, t), (f, f), (t, f)\} \rightarrow \{(t, t)\} \quad (30)$$

$$\begin{aligned} & \text{Apply SEP_SEQ_PAR_RULE :} \\ & \llbracket Btn.on \rrbracket \llbracket Pwr.on \rrbracket = \llbracket Btn.on \rrbracket \times \llbracket Pwr.on \rrbracket \\ & \llbracket Btn.on \rrbracket \llbracket Pwr.on \rrbracket = \\ & \quad \{(t, t) \mapsto (t, t), \\ & \quad (t, f) \mapsto (t, t), \\ & \quad (f, t) \mapsto (t, t), \\ & \quad (f, f) \mapsto (t, t)\} \end{aligned} \quad (31)$$

$$\begin{aligned} & \llbracket Btn.on \rrbracket \llbracket Pwr.on \rrbracket^{Lht} \upharpoonright_R \subseteq \llbracket off, on \rrbracket^{Lht} \\ & \text{where } R = \text{dom}(\llbracket off, on \rrbracket^{Lht}) = \\ & \quad \{(t, t) \mapsto (t, t), \\ & \quad (t, f) \mapsto (t, t), \\ & \quad (f, t) \mapsto (t, t), \\ & \quad (f, f) \mapsto (t, t)\} \\ & \subseteq \\ & \quad \{(t, f), (f, f), (f, t)\} \rightarrow \{(t, t)\} \\ & = \\ & \quad \{(t, t) \mapsto (t, t), \\ & \quad (t, f) \mapsto (t, t), \\ & \quad (f, t) \mapsto (t, t), \\ & \quad (f, f) \mapsto (t, t)\} \\ & \subseteq \\ & \quad \{(t, f) \mapsto (t, t), \\ & \quad (f, f) \mapsto (t, t), \\ & \quad (f, t) \mapsto (t, t)\} \\ & \Rightarrow \end{aligned}$$

$$\begin{aligned} & \llbracket kase(off, on, Pwr.on \rrbracket \llbracket Btn.on \rrbracket) \rrbracket = \llbracket Btn.on \rrbracket \llbracket Pwr.on \rrbracket^{Lht} \upharpoonright_R = \\ & \quad \{(t, f) \mapsto (t, t), \\ & \quad (f, t) \mapsto (t, t), \\ & \quad (f, f) \mapsto (t, t)\} \\ & \quad \blacksquare \end{aligned} \quad (32)$$

Apply STEP_RULE :

$$\begin{aligned} & \llbracket kase(on, off, Pwr.off; Btn.off) \rrbracket = \\ & \llbracket Btn.off; Pwr.off \rrbracket^{Lht} \upharpoonright_S \text{ if } \llbracket Pwr.off; Btn.off \rrbracket^{Lht} \upharpoonright_S \subseteq \llbracket on, off \rrbracket^{Lht} \\ & \text{where } S = \text{dom}(\llbracket on, off \rrbracket^{Lht}) \end{aligned} \quad (33)$$

Apply RESOLVE_CONTRACT_RULE :

$$\llbracket on, off \rrbracket^{Lht} = \llbracket on \rrbracket^{Lht} \rightarrow \llbracket off \rrbracket^{Lht} \quad (34)$$

Apply RESOLVE_PREDICATE_RULE :

$$\llbracket off \rrbracket^{Lht} = \llbracket p.off \vee b.off \rrbracket^{Lht} \quad (35)$$

Apply OR_RULE :

$$\llbracket p.off \vee b.off \rrbracket^{Lht} = \llbracket p.off \rrbracket^{Lht} \cup \llbracket b.off \rrbracket^{Lht} \quad (36)$$

Apply PREDICATE_RULE :

$$\begin{aligned} & \llbracket p.off \rrbracket^{Lht} = \{t, f\} \times \{f\} = \{(t, f), (f, f)\} \\ & \llbracket b.off \rrbracket^{Lht} = \{f\} \times \{t, f\} = \{(f, t), (f, f)\} \end{aligned} \quad (37)$$

$$\llbracket off \rrbracket^{Lht} = \llbracket p.off \rrbracket^{Lht} \cup \llbracket b.off \rrbracket^{Lht} = \{(f, t), (f, f), (t, f)\} \quad (38)$$

Apply RESOLVE_PREDICATE_RULE :

$$\llbracket on \rrbracket^{Lht} = \llbracket p.on \wedge b.on \rrbracket^{Lht} \quad (39)$$

Apply AND_RULE :

$$\llbracket p.on \wedge b.on \rrbracket^{Lht} = \llbracket p.on \rrbracket^{Lht} \cap \llbracket b.on \rrbracket^{Lht} \quad (40)$$

Apply PREDICATE_RULE :

$$\begin{aligned} & \llbracket p.on \rrbracket^{Lht} = \{t, f\} \times \{t\} = \{(t, t), (f, t)\} \\ & \llbracket b.on \rrbracket^{Lht} = \{t\} \times \{t, f\} = \{(t, t), (t, f)\} \end{aligned} \quad (41)$$

$$\llbracket on \rrbracket^{Lht} = \llbracket p.on \rrbracket^{Lht} \cap \llbracket b.on \rrbracket^{Lht} = \{(t, t)\} \quad (42)$$

Apply ASSUME_STEP_RULE :

$$\begin{aligned} & \llbracket Pwr.off \rrbracket^{Pwr} = \llbracket on \vee off, off \rrbracket^{Pwr} = \llbracket on \vee off \rrbracket^{Pwr} \rightarrow \llbracket off \rrbracket^{Pwr} \\ & \llbracket Btn.off \rrbracket^{Btn} = \llbracket on \vee off, off \rrbracket^{Btn} = \llbracket on \vee off \rrbracket^{Btn} \rightarrow \llbracket off \rrbracket^{Btn} \end{aligned} \quad (43)$$

Apply OR_RULE :

$$\begin{aligned} & \llbracket on \vee off \rrbracket^{Btn} = \llbracket on \rrbracket^{Btn} \cup \llbracket off \rrbracket^{Btn} \\ & \llbracket on \vee off \rrbracket^{Pwr} = \llbracket on \rrbracket^{Pwr} \cup \llbracket off \rrbracket^{Pwr} \end{aligned} \quad (44)$$

Apply PREDICATE_RULE :

$$\begin{aligned} & \llbracket on \rrbracket^{Btn} = \{t\}, \llbracket off \rrbracket^{Btn} = \{f\} \\ & \llbracket on \rrbracket^{Pwr} = \{t\}, \llbracket off \rrbracket^{Pwr} = \{f\} \end{aligned} \quad (45)$$

$$\begin{aligned} & \llbracket Btn.off \rrbracket^{Btn} = \{t, f\} \rightarrow \{f\} = \{t \mapsto f, f \mapsto f\} \\ & \llbracket Pwr.off \rrbracket^{Pwr} = \{t, f\} \rightarrow \{f\} = \{t \mapsto f, f \mapsto f\} \end{aligned} \quad (46)$$

$$\begin{aligned}
& \text{Apply SEP_SEQ_PAR_RULE :} \\
& \llbracket \text{Btn.off}; \text{Pwr.off} \rrbracket^{Lht} = \llbracket \text{Btn.off} \rrbracket \times \llbracket \text{Pwr.off} \rrbracket \\
& \llbracket \text{Btn.off}; \text{Pwr.off} \rrbracket = \\
& \quad \{(t, t) \mapsto (f, f), \\
& \quad (t, f) \mapsto (f, f), \\
& \quad (f, t) \mapsto (f, f), \\
& \quad (f, f) \mapsto (f, f)\} \\
& \llbracket \text{Btn.off}; \text{Pwr.off} \rrbracket^{Lht} \upharpoonright_S \subseteq \llbracket \text{on, off} \rrbracket^{Lht} = \\
& \quad \{(t, t) \mapsto (f, f), \\
& \quad (t, f) \mapsto (f, f), \\
& \quad (f, t) \mapsto (f, f), \\
& \quad (f, f) \mapsto (f, f)\} \\
& \quad \subseteq \\
& \quad \{(t, t) \mapsto (f, f), \\
& \quad (t, f) \mapsto (f, f), \\
& \quad (f, t) \mapsto (f, f), \\
& \quad (f, f) \mapsto (f, f)\} \\
& \quad \subseteq \\
& \quad \{(t, t) \mapsto (t, f), \\
& \quad (t, t) \mapsto (f, f), \\
& \quad (t, t) \mapsto (f, t)\} \\
& \quad \implies \\
& \llbracket \text{kase(off, on, Pwr.off; Btn.off)} \rrbracket = \llbracket \text{Btn.off}; \text{Pwr.off} \rrbracket^{Lht} \upharpoonright_S = \\
& \quad \{(t, t) \mapsto (f, f)\} \\
& \quad \blacksquare
\end{aligned} \tag{47}$$

5.0.4 Proof of root step.

$$\begin{aligned}
& 32, 48 \implies \\
& \llbracket \text{Lht.toggle} \rrbracket = \llbracket \text{Btn.on} \rrbracket \llbracket \text{Pwr.on} \rrbracket^{Lht} \upharpoonright_R \cup \llbracket \text{Btn.off}; \text{Pwr.off} \rrbracket^{Lht} \upharpoonright_S
\end{aligned} \tag{49}$$

$$\begin{aligned}
& \llbracket \text{Lht.toggle} \rrbracket \\
& = \\
& \llbracket \text{Btn.on} \rrbracket \llbracket \text{Pwr.on} \rrbracket^{Lht} \upharpoonright_R \cup \llbracket \text{Btn.off}; \text{Pwr.off} \rrbracket^{Lht} \upharpoonright_S \\
& = \\
& \quad \{(t, f) \mapsto (t, t), \\
& \quad (f, t) \mapsto (t, t), \\
& \quad (f, f) \mapsto (t, t)\} \\
& \quad \cup \\
& \quad \{(t, t) \mapsto (f, f)\} \\
& = \\
& \quad \{(t, f) \mapsto (t, t), \\
& \quad (f, t) \mapsto (t, t), \\
& \quad (f, f) \mapsto (t, t), \\
& \quad (t, t) \mapsto (f, f)\} \\
& \quad \implies
\end{aligned} \tag{50}$$

The light system program is
Correct by Construction as per definition 4.2.

■

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