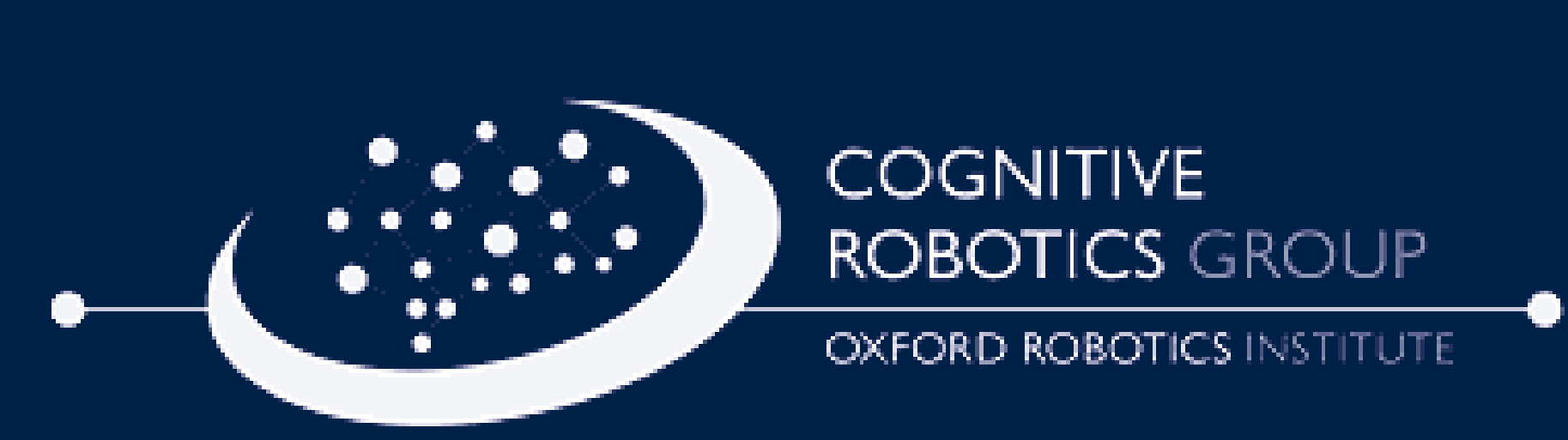


# The Likely Very Long Title Associated with Your Paper

## Conference Title

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### Overview

- Overview 1
- Overview 2
- Overview 3
- Overview 4

### Another block

Block text [1]...

### Method

**Method details.** We formulate...  $\mathcal{S} = \{s_1, s_2, s_3, s_4, s_5, s_6\}$   
Image example:



### Results

Results...

### References

[1] Richa Nahata, Daniel Omeiza, Rhys Howard, and Lars Kunze. Assessing and explaining collision risk in dynamic environments for autonomous driving safety. In *2021 IEEE International Intelligent Transportation Systems Conference (ITSC)*, pages 223–230, 2021.