

The Likely Very Long Title Associated with Your Paper

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Overview

- Overview 1
- Overview 2
- Overview 3
- Overview 4

Another block

Block text [1]...

Method

Method details. We formulate... $\mathcal{S} = \{s_1, s_2, s_3, s_4, s_5, s_6\}$
Image example:



Results

Results...

References

[1] Richa Nahata, Daniel Omeiza, Rhys Howard, and Lars Kunze. Assessing and explaining collision risk in dynamic environments for autonomous driving safety. In *2021 IEEE International Intelligent Transportation Systems Conference (ITSC)*, pages 223–230, 2021.