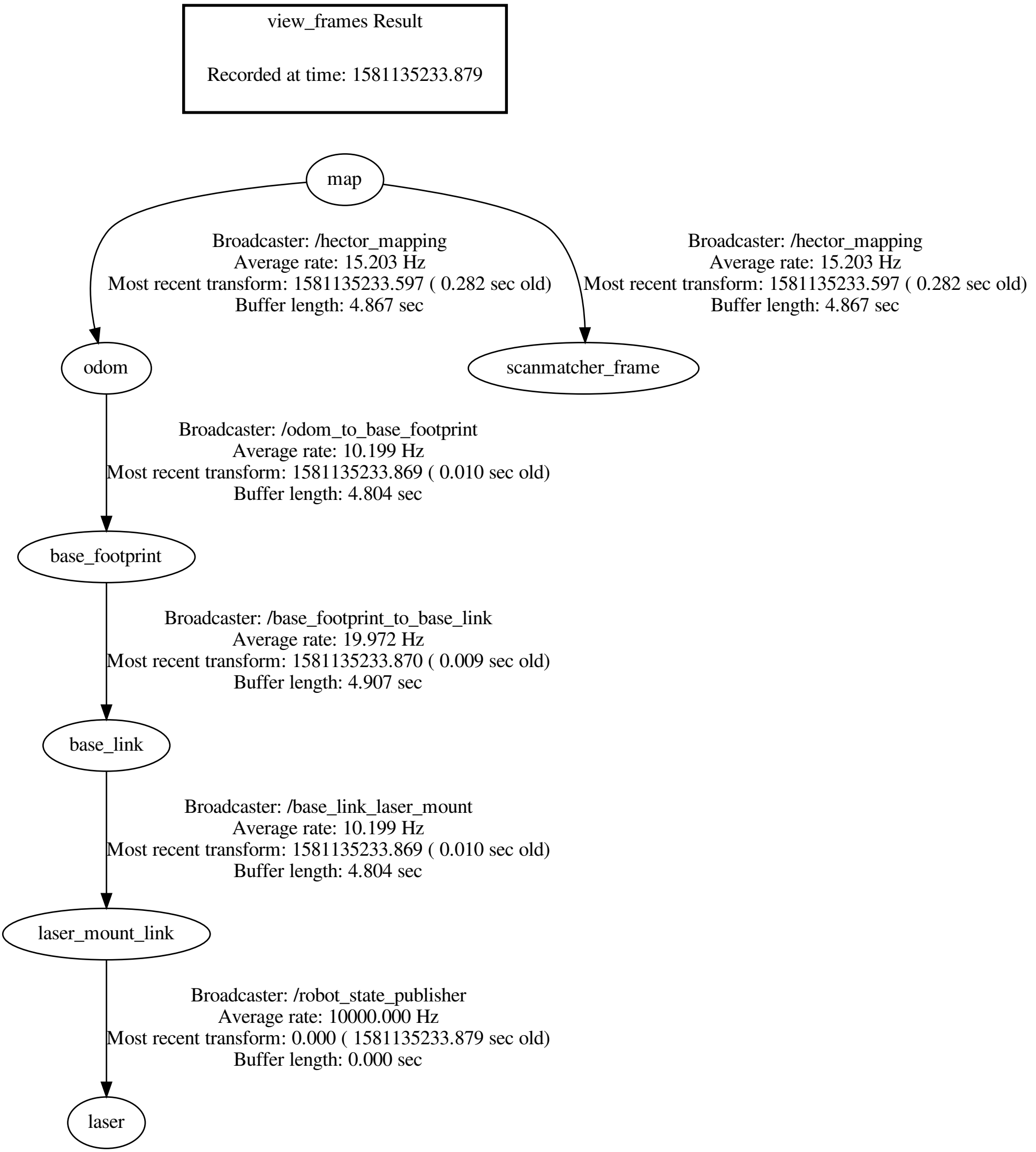
view_frames Result
Recorded at time: 1581135233.879
map
Broadcaster: /hector_mapping
Average rate: 15.203 Hz
Most recent transform: 1581135233.597 (0.282 sec old)
Buffer length: 4.867 sec
Broadcaster: /hector_mapping
Average rate: 15.203 Hz
Most recent transform: 1581135233.597 (0.282 sec old)
Buffer length: 4.867 sec
odom
scanmatcher_frame
Broadcaster: /odom_to_base_footprint
Average rate: 10.199 Hz
Most recent transform: 1581135233.869 (0.010 sec old)
Buffer length: 4.804 sec
base_footprint
Broadcaster: /base_footprint_to_base_link
Average rate: 19.972 Hz
Most recent transform: 1581135233.870 (0.009 sec old)
Buffer length: 4.907 sec
base_link
Broadcaster: /base_link_laser_mount
Average rate: 10.199 Hz
Most recent transform: 1581135233.869 (0.010 sec old)
Buffer length: 4.804 sec
laser_mount_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1581135233.879 sec old)
Buffer length: 0.000 sec
laser