# CS450

### Structure of Higher Level Languages

Lecture 24: Implementing  $\lambda_D$ 

Tiago Cogumbreiro

# Today we will learn...



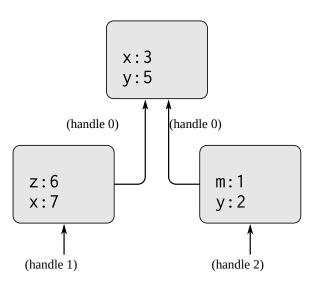
- Introduce mutable environments, composed of frames
- Implement frames

Section 3.2 of the SICP book. The interactive version of Section 3.2.

# Visualizing the environment

## Environment visualization



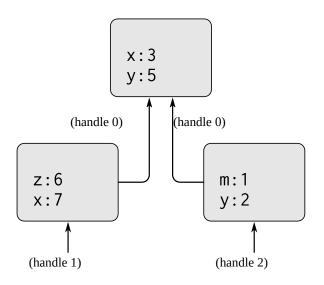


**Figure 3.1:** A simple environment structure. Source: SICP book Section 3.2

```
; E0 = (handle 0)
E0: [
; E1 = (handle 1)
 (x.7); shadows E0.x
; E2 = (handle 2)
  (y . 2); shadows E0.y
 ; (x . 3)
```

## Environment visualization





**Figure 3.1:** A simple environment structure.

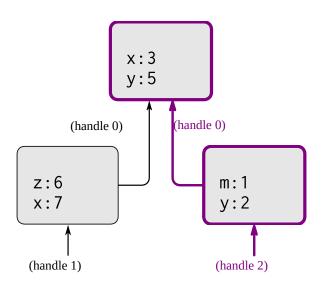
Source: SICP book Section 3.2

### The heap at runtime

- arrows are **references**, or heap handles:
- boxes are *frames*: labelled by their handles
- each frame has local variable bindings (eg, m:1, and y:2)

## Environment visualization





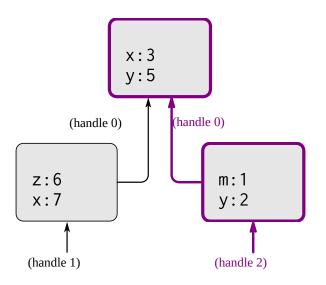
**Figure 3.1:** A simple environment structure. Source: SICP book Section 3.2

### The heap at runtime

- arrows are **references**, or heap handles:
- boxes are *frames*: labelled by their handles
- each frame has local variable bindings (eg, m:1, and y:2)
- an environment represents a sequence of frames, connected via references.
   For instance, the environment that consists of frame 3 linked to frame 1.
- variable lookup follows the reference order. For instance, lookup a variable in frame 3 and then in frame 1.

# Quiz





List all variable bindings in environment (handle 1)

**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

# Implementing mutable environments

# Implementing mutable environments



### Heap

• A heap contains *frames* 

### Frame

- a reference to its parent frame (except for the root frame which does not refer any other frame)
- a map of local bindings

```
Example of a frame: [ E0 (y . 1) ]
Example of a root frame: [ (a . 20) (b . (closure E0 (lambda (y) a)) ]
```

```
E0: [
  (a . 20)
  (b . (closure E0 (lambda (y) a)))
]
E1: [ E0
  (y . 1)
]
```

# Let us implement frames...

(demo time)

# Usage examples



```
; (closure E0 (lambda (y) a)
(define c (d:closure (handle 0) (d:lambda (list (d:variable 'y)) (d:variable 'a))))
:E0: [
: (a . 20)
; (b . (closure E0 (lambda (y) a)))
(define f1
  (frame-put
    (frame-put root-frame (d:variable 'a) (d:number 10))
    (d:variable 'b) c))
(check-equal? f1 (frame #f (hash (d:variable 'a) (d:number 10) (d:variable 'b) c)))
; Lookup a
(check-equal? (d:number 10) (frame-get f1 (d:variable 'a)))
; Lookup b
(check-equal? c (frame-get f1 (d:variable 'b)))
: Lookup c that does not exist
(check-equal? #f (frame-get f1 (d:variable 'c)))
```





```
; E1: [ E0
; (y . 1)
; ]
(define f2 (frame-push (handle 0) (d:variable 'y) (d:number 1)))
(check-equal? f2 (frame (handle 0) (hash (d:variable 'y) (d:number 1))))
(check-equal? (d:number 1) (frame-get f2 (d:variable 'y)))
(check-equal? #f (frame-get f2 (d:variable 'a)))
;; We can use frame-parse to build frames
(check-equal? (parse-frame '[ (a . 10) (b . (closure E0 (lambda (y) a)))]) f1)
(check-equal? (parse-frame '[ E0 (y . 1) ]) f2))
```

## Frames



```
(struct frame (parent locals))
```

- parent is either #f or is a reference to the parent frame
- locals is a hash-table with the local variables of this frame

#### Constructors

### Description

- root-frame creates an orphan empty frame (hence #f). This function is needed to represent the toplevel environment.
- frame-push takes a reference that points to the parent frame, and initializes a hash-table with one entry (var, val). This function is needed for  $E\leftarrow E'+[x:=v]$
- frame-put updates the current frame with a new binding. This function is needed for  $E \leftarrow [x := v]$