

CS420

Introduction to the Theory of Computation

Lecture 4: Nondeterministic Finite Automaton

Tiago Cogumbreiro

Revisiting what we learned...

- Operations on words; set theory
- How to draw a state diagram from a DFA?
- A step-by-step union example
- Reduction graphs with ϵ -transitions?
- What is the powerset function?
- How to draw a state diagram from an NFA?
- How to convert an NFA into a DFA?

HW1 heads up

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- Answers should all be given as state diagrams
- Simplification of L_5 :
 - If the resulting DFA is already simplified, then just answer "the same DFA"
 - We have no way of proving that the DFA is the smallest
- After applying the union operator you should **not** simplify the final diagram
- When writing down a diagram from an M (directly using a transition function) you should **not** simplify it

Operations on words; set theory

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■ What is w^n ; L^\star

Operations on words; set theory

What is w^n ; L^*

Answer: (Lecture 1, slides 38 and 39) concatenate w with itself n times. $L^* = \{w^n \mid w \in L \wedge n \geq 0\}$ (Lecture 2; slide 19)

See also **Definition 1.23** in the book.

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Answer: Shorthand notation for $w_1 \in s \wedge w \in s \wedge w_2 \in s$.

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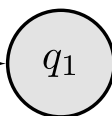
What is $\{w \mid P(w)\}$?

Answer: this is known as the **set-builder notation** (set comprehension). I assume you learned this in CS220 (or prior). It is a way of saying any w such that $P(x)$ holds. For instance, $\{w \mid |w| \text{ is even} \wedge w = ab \cdot w_2 \wedge w, w_2 \in \Sigma^*\}$ means that w is such that: $|w|$ is even (the length of w is even) **AND** $w = ab \cdot w_2$ (w starts with ab followed by w_2), **AND** $w_2 \in \Sigma^*$ (w_2 is a word)

How to draw a state diagram for a DFA

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Give the DFA of $M =$

$(\{q_1, q_2, q_3, q_4, q_5\}, \{a, b\}, \delta, q_1, \{q_4\})$ $\xrightarrow{\text{start}}$ 

where

$$\delta(q_1, a) = q_2$$

$$\delta(q_1, b) = q_3$$

$$\delta(q_2, a) = q_1$$

$$\delta(q_2, b) = q_3$$

$$\delta(q_3, a) = q_5$$

$$\delta(q_4, a) = q_1$$

$$\delta(q_4, b) = q_2$$

$$\delta(q, c) = q \text{ otherwise}$$

1. pick q_1 ; draw edge for each Σ , one for a ; another for b

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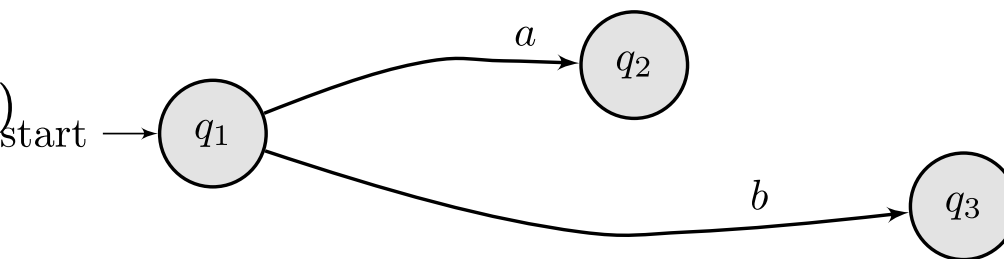
$$\delta(q_2, b) = q_3$$

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1. pick q_1 ; draw outgoing edges

2. pick q_2 (or q_3); draw outgoing edges

How to draw a state diagram for a DFA

Give the DFA of $M =$

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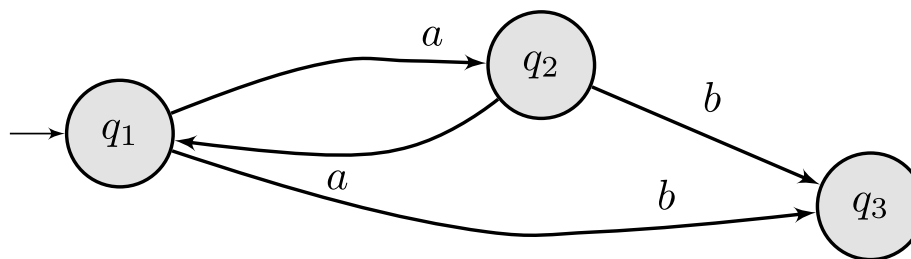
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1. pick q_1 ; draw outgoing edges
2. pick q_2 ; draw outgoing edges
3. pick q_3 ; draw outgoing edges

How to draw a state diagram for a DFA

Give the DFA of $M =$

$(\{q_1, q_2, q_3, q_4, q_5\}, \{a, b\}, \delta, q_1, \{q_4\})$ start $\rightarrow q_1$
where

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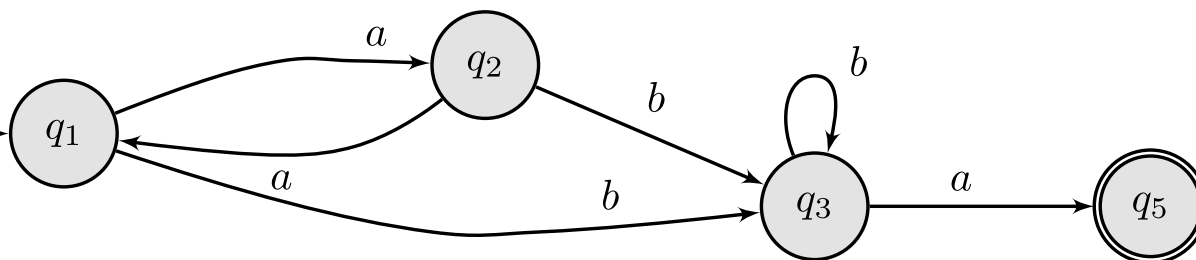
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1. pick q_1 ; draw outgoing edges
2. pick q_2 ; draw outgoing edges
3. pick q_3 ; draw outgoing edges
4. pick q_5 ; draw outgoing edges

How to draw a state diagram for a DFA

Give the DFA of $M =$

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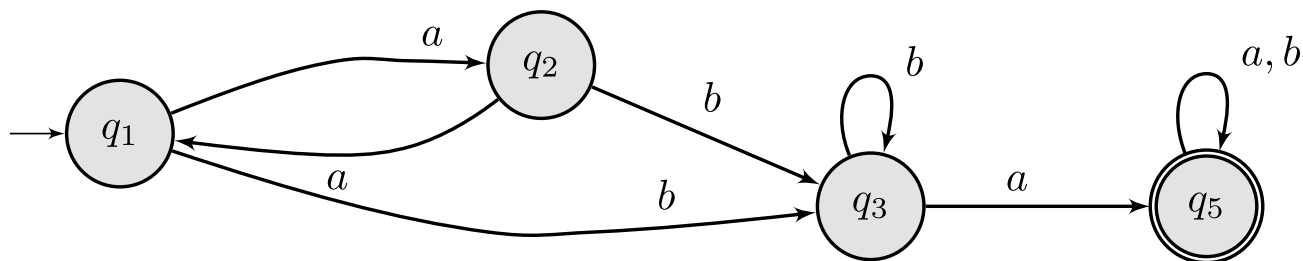
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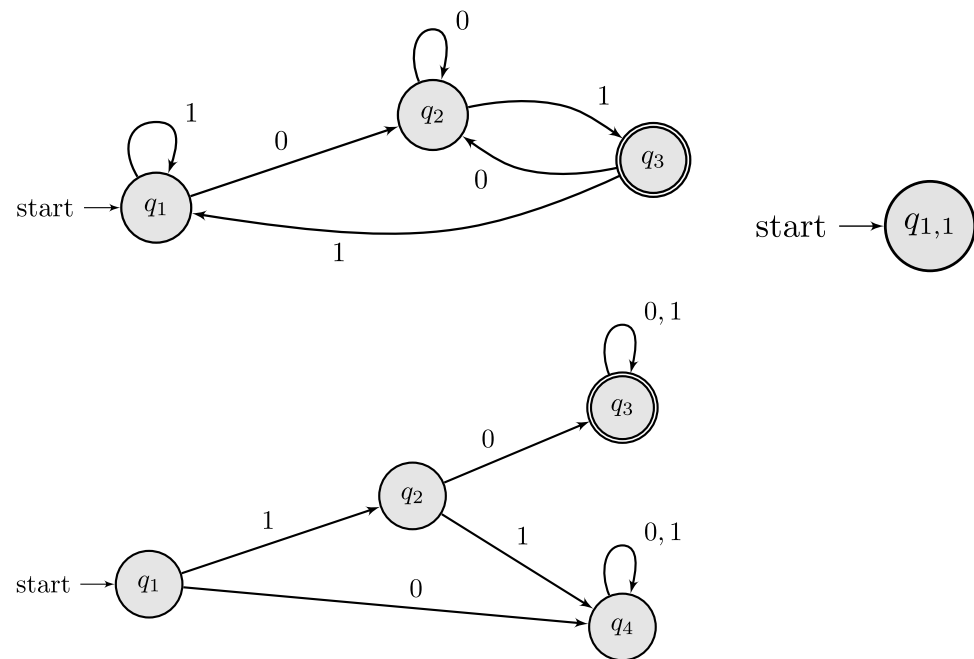
1. pick q_1 ; draw outgoing edges
2. pick q_2 ; draw outgoing edges
3. pick q_3 ; draw outgoing edges
4. pick q_5 ; draw outgoing edges

Note 1: state q_4 is not present in our graph, because it is unreachable. We only render reachable states in our state diagrams.

Note 2: do **not** attempt to simplify the DFA.

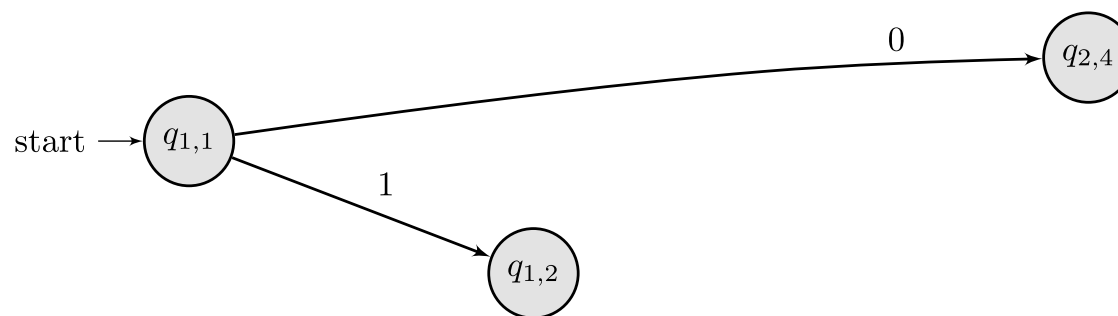
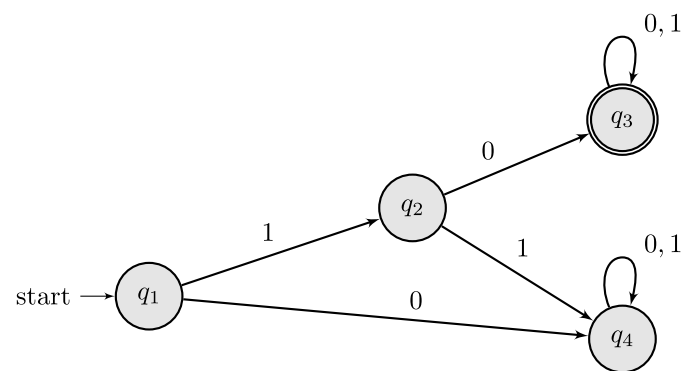
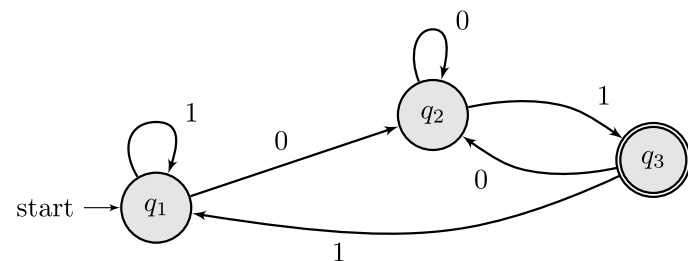
Step-by-step union example

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We start from the pair (q_1, q_1) (the initial state of each DFA) which we denote by $q_{1,1}$.
For each element of Σ draw an edge.

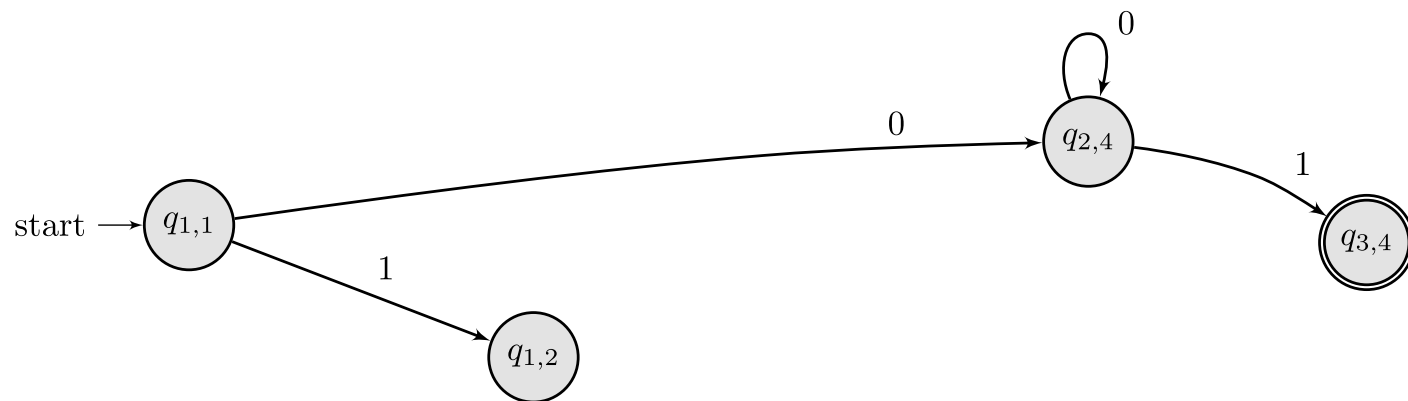
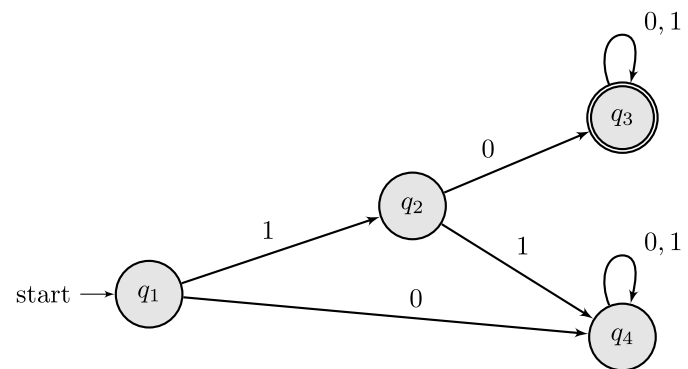
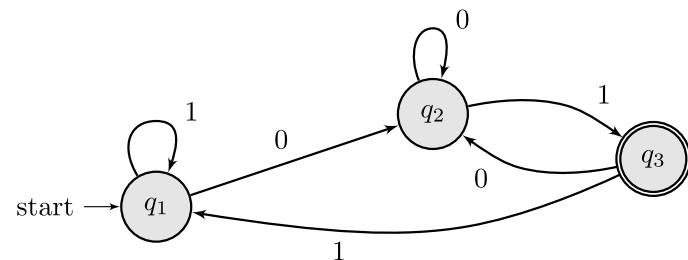
Step-by-step union example



At $q_{1,1}$

- Read 0. (Left) From q_1 we advance to q_2 . (Right) From q_1 we advance to q_4 . Result $q_{2,4}$
- Read 1. (Left) From q_1 we advance to q_1 . (Right) From q_1 we advance to q_2 . Result $q_{1,2}$.

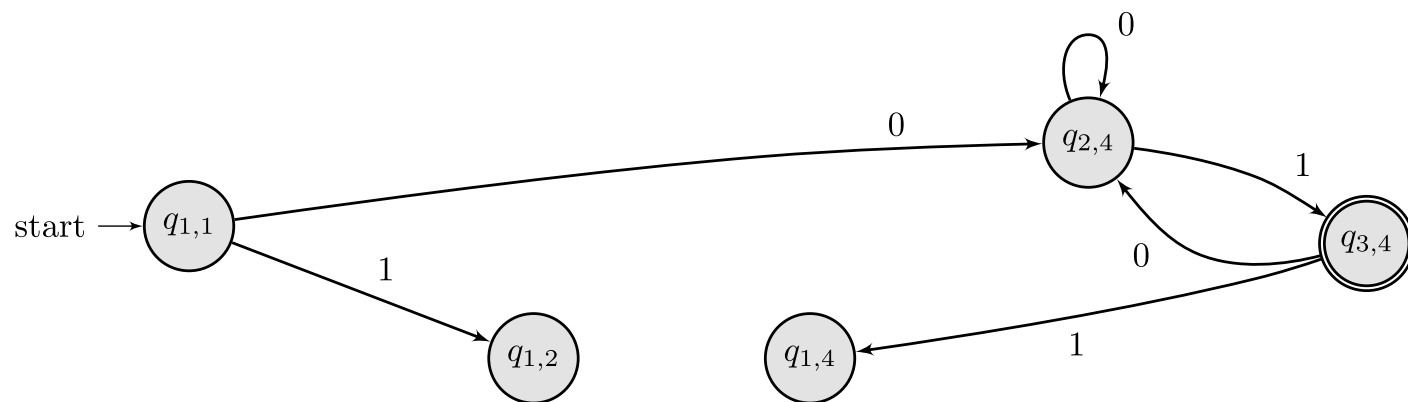
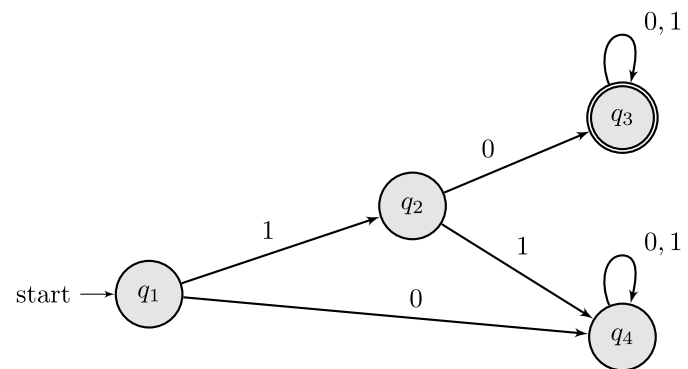
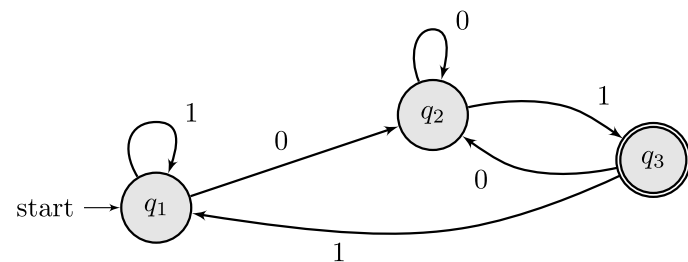
Step-by-step union example



At $q_{2,4}$:

- Read 0. (Left) From q_2 we advance to q_2 . (Right) From q_4 we advance to q_4 . Result $q_{2,4}$
- Read 1. (Left) From q_2 we advance to q_3 . (Right) From q_4 we advance to q_4 . Result $q_{3,4}$.

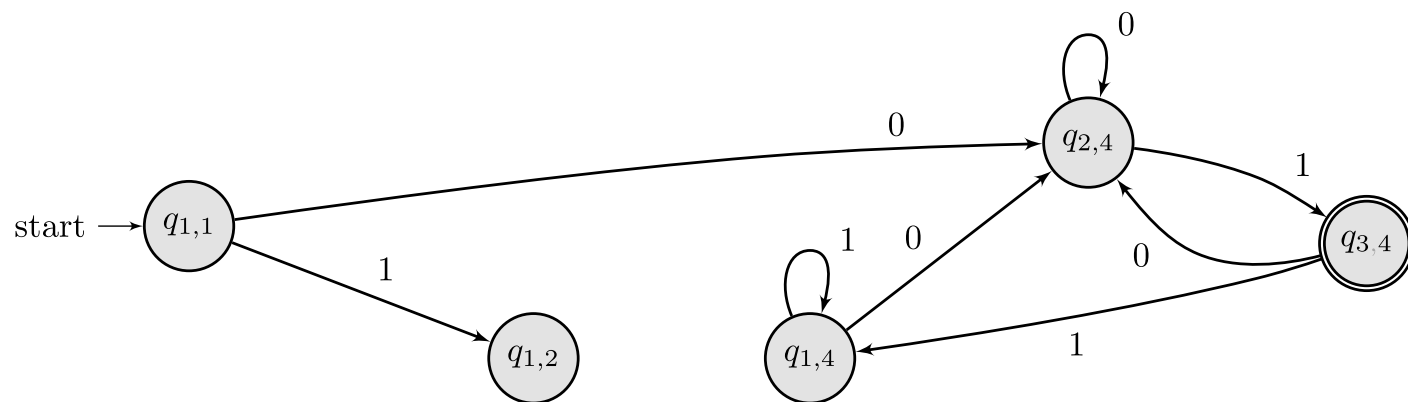
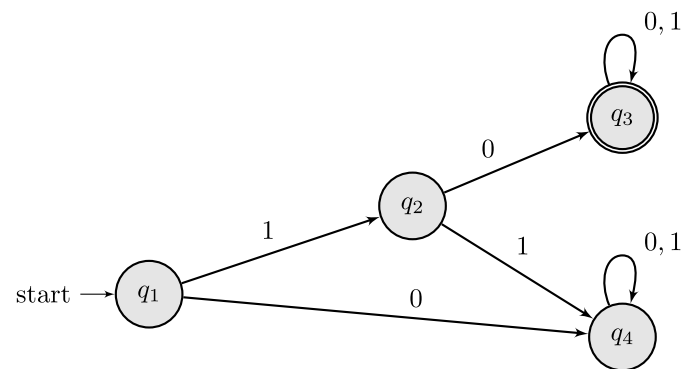
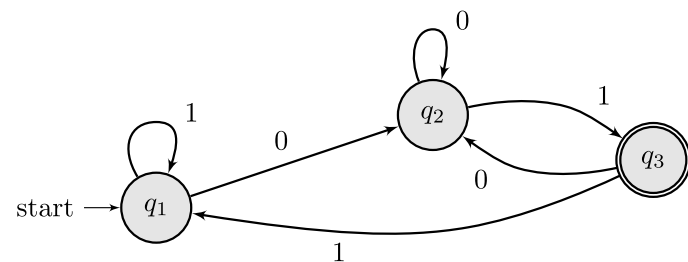
Step-by-step union example



At $q_{3,4}$:

- Read 0. (Left) From q_3 we advance to q_2 . (Right) From q_4 we advance to q_4 . Result $q_{2,4}$
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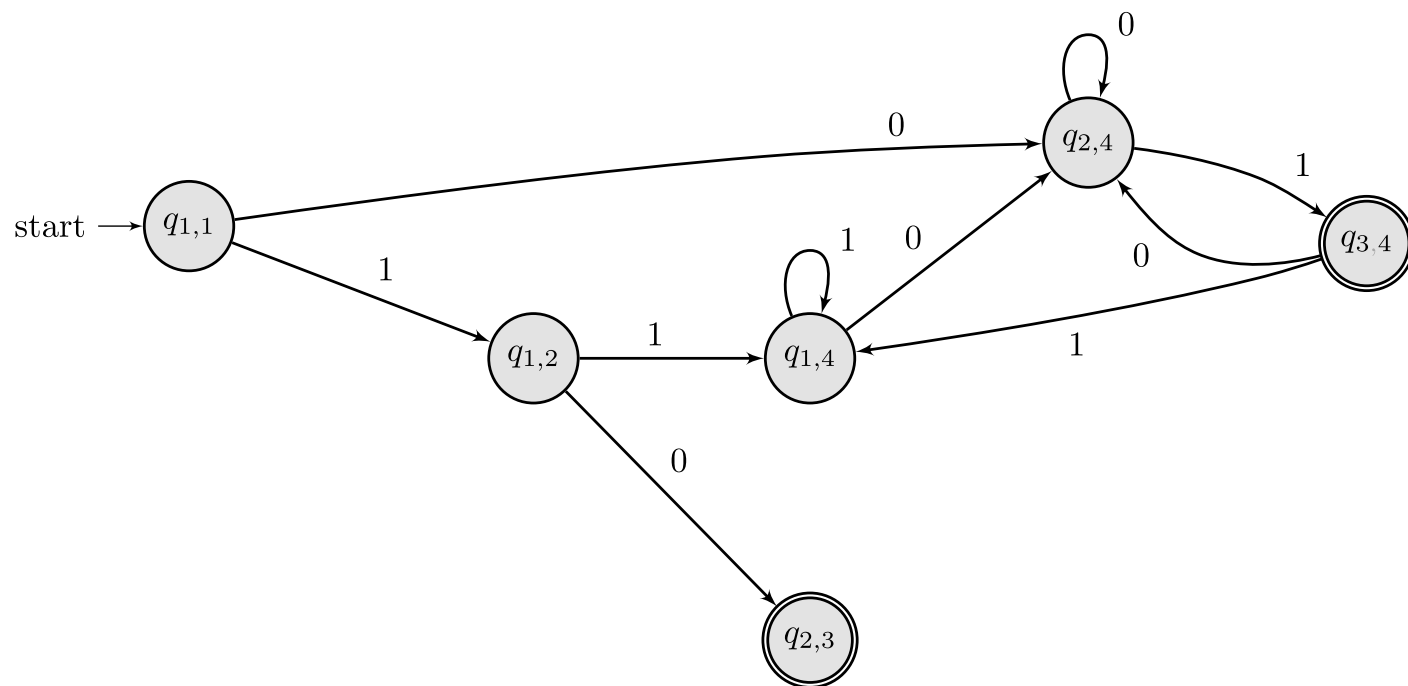
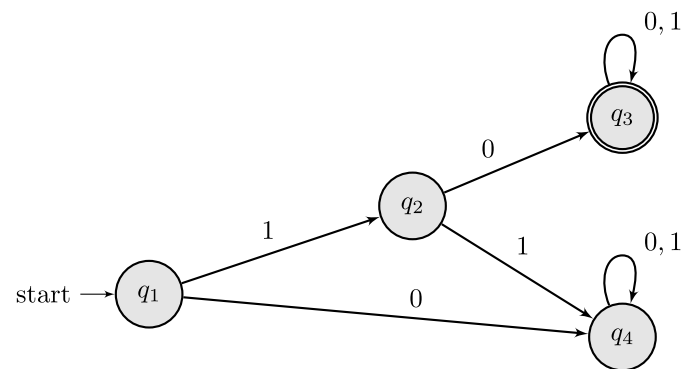
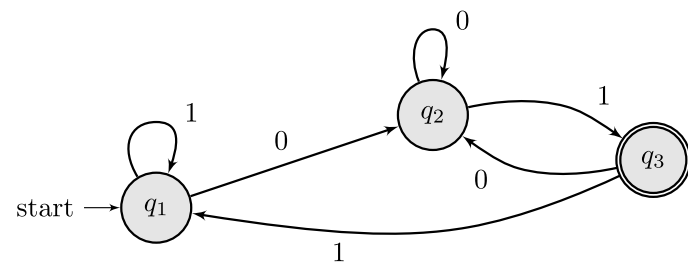
Step-by-step union example



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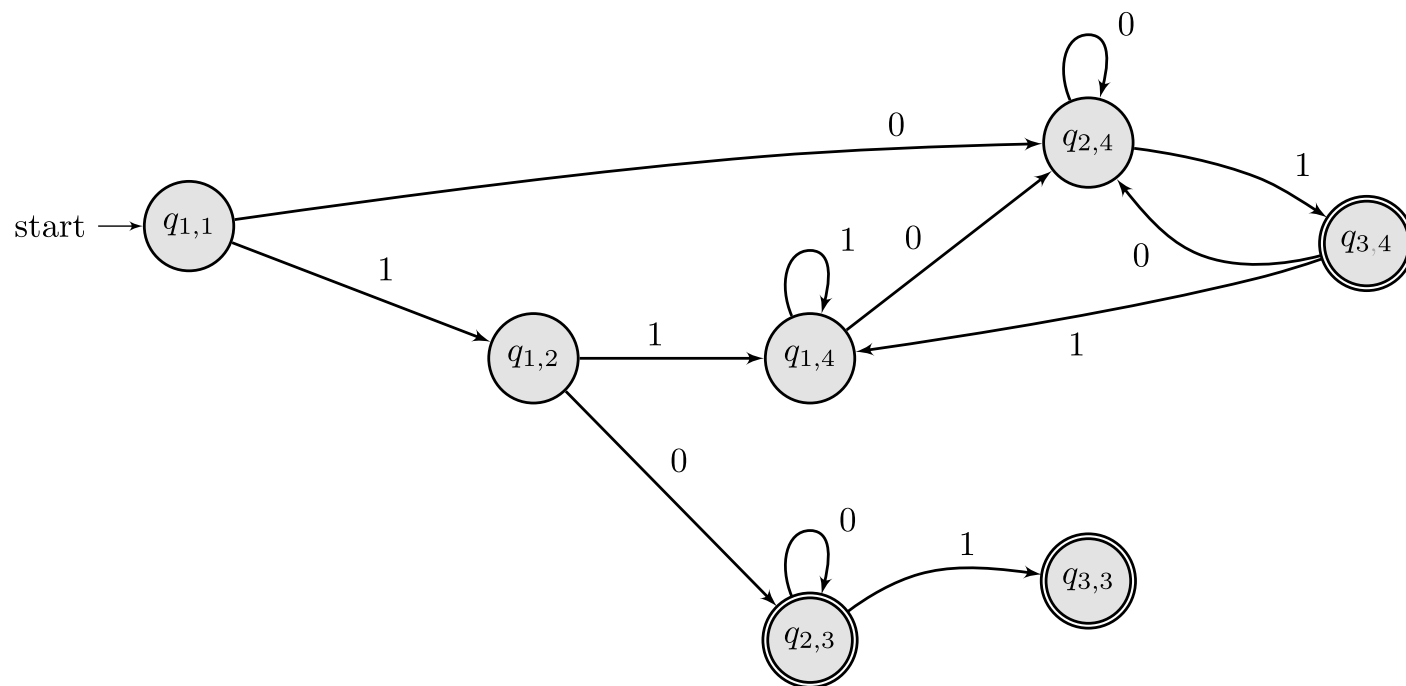
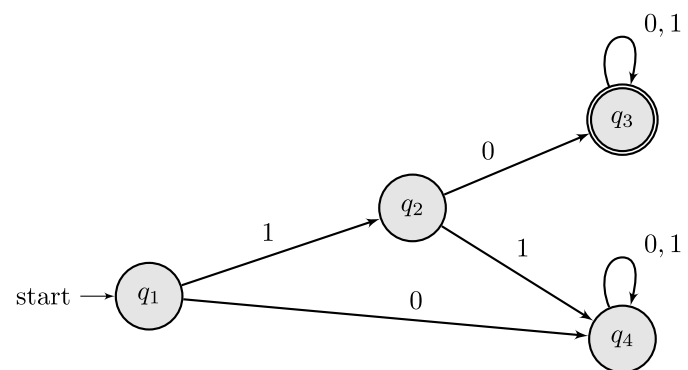
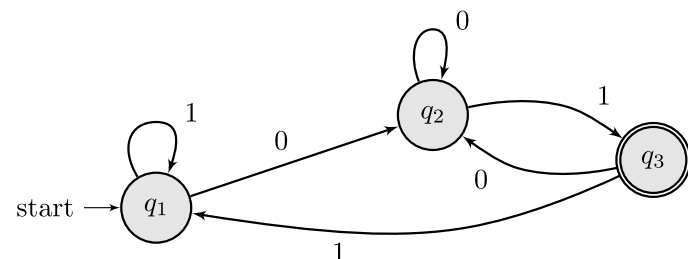
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At $q_{1,2}$:

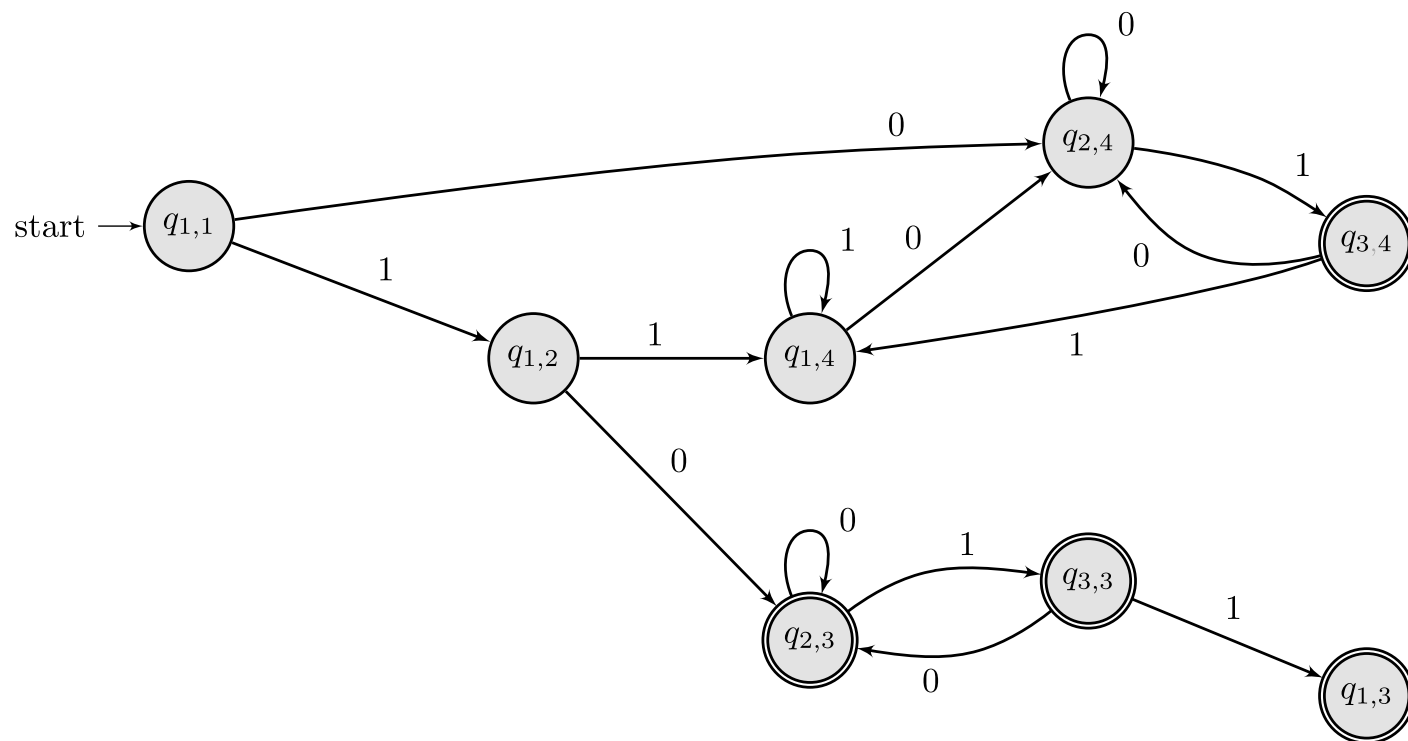
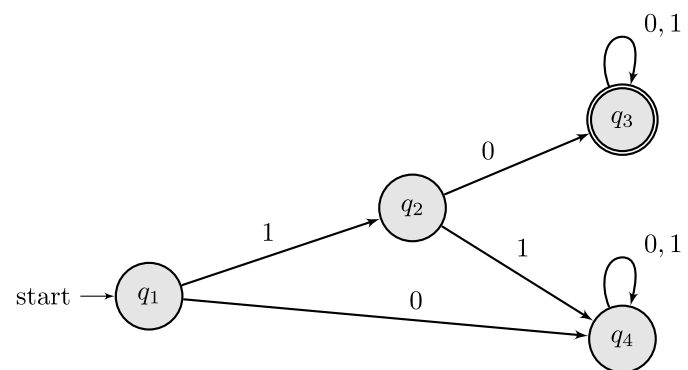
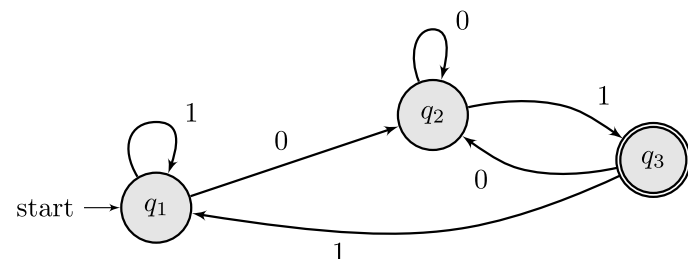
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- Read 1. (Left) From q_1 we advance to q_1 . (Right) From q_2 we advance to q_4 . Result $q_{1,4}$.

Step-by-step union example



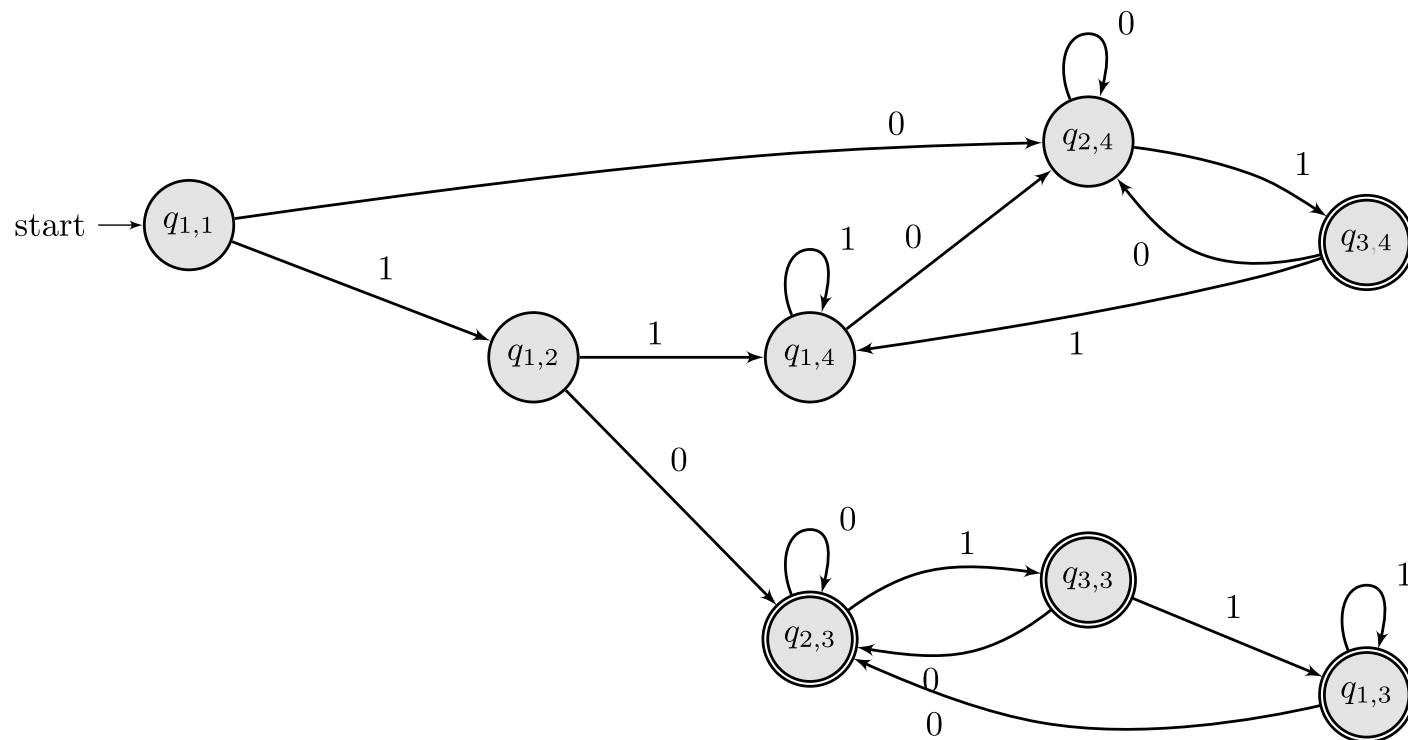
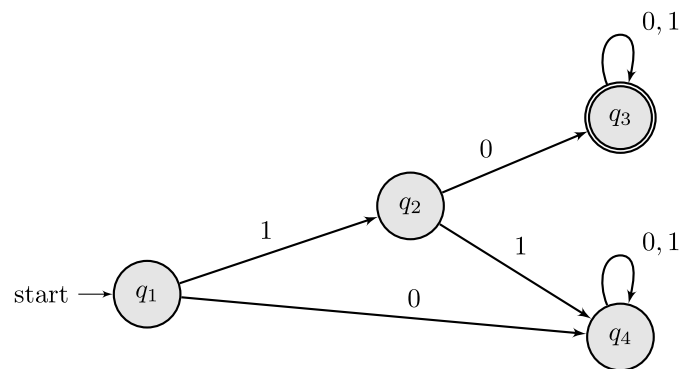
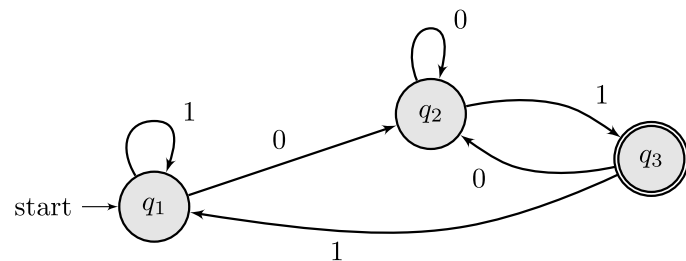
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Step-by-step union example



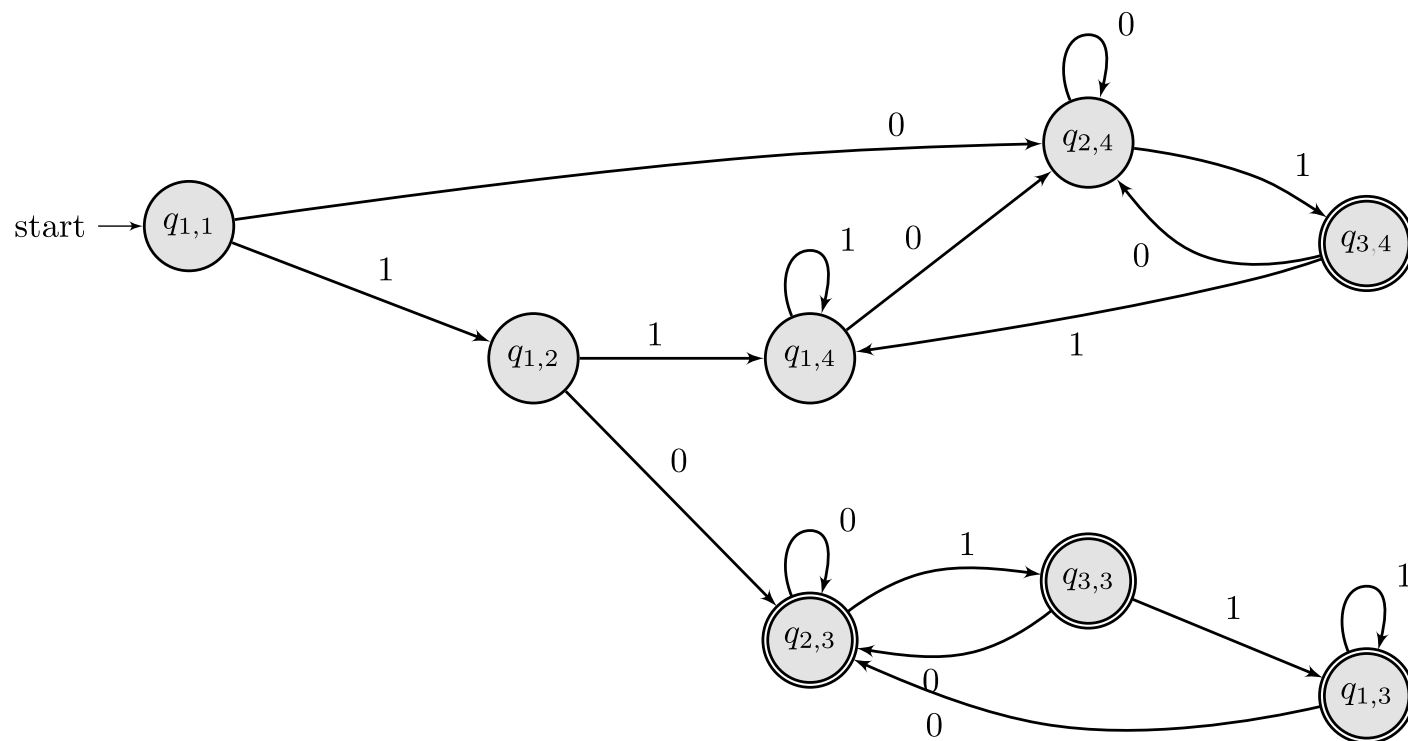
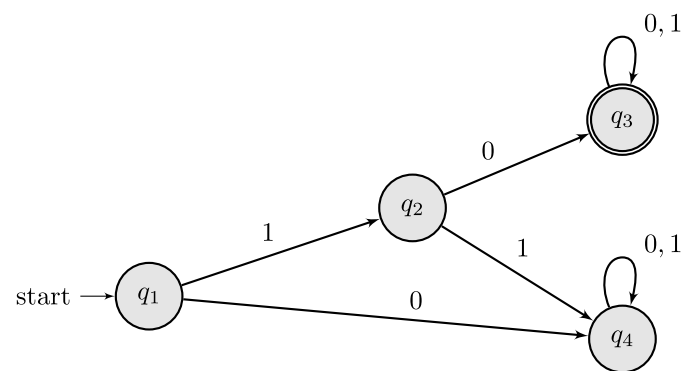
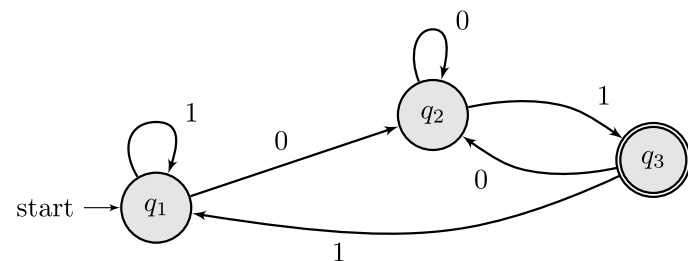
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Step-by-step union example



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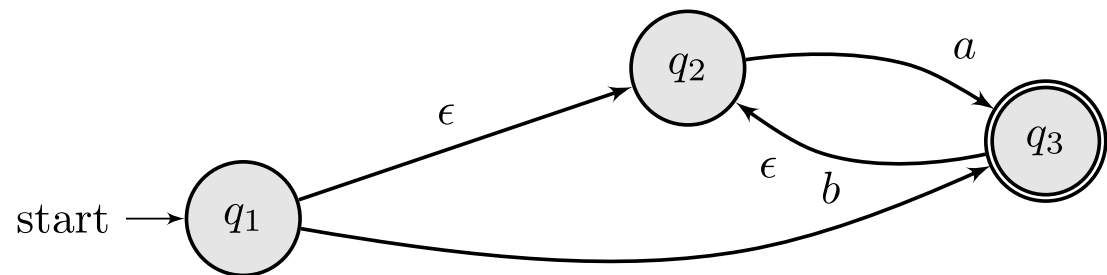
Step-by-step union example



Note: in the HW/mini-tests do **not** attempt to simplify the resulting DFA unless explicitly requested to do so.

Reduction graphs with ϵ -transitions

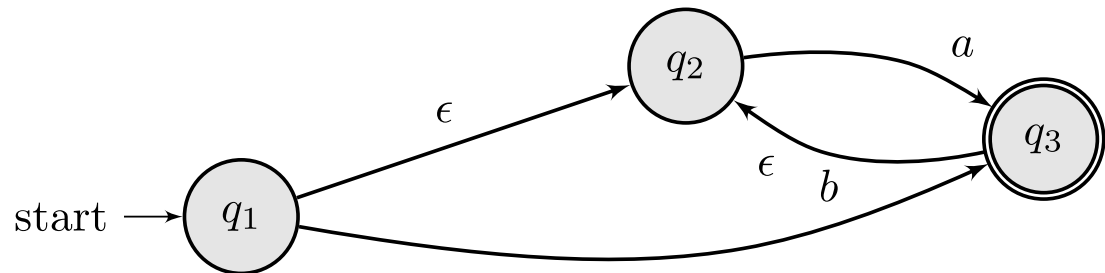
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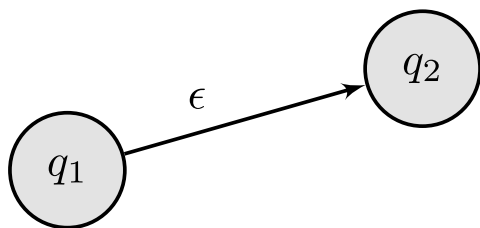
Acceptance for ba: epsilon-step



Reduction graphs with ϵ -transitions

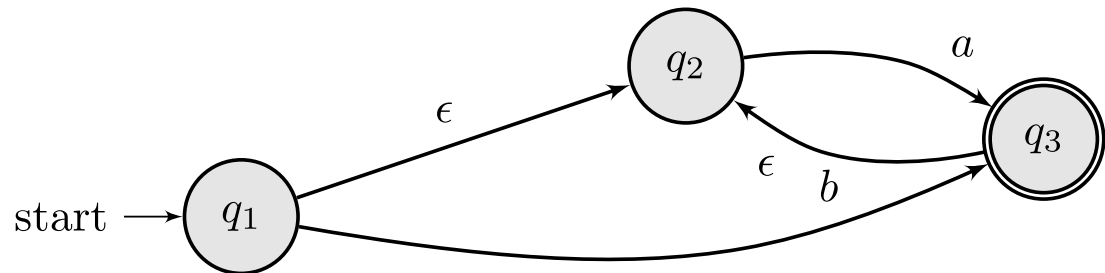


Acceptance for ba: input-step **b**

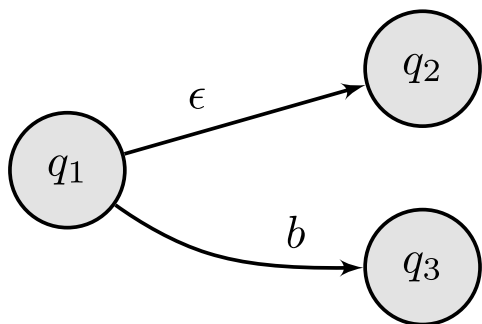


Note: at this point that are two concurrent states: q_1 and q_2 , so we can consume b from either (although we can only do so via q_1).

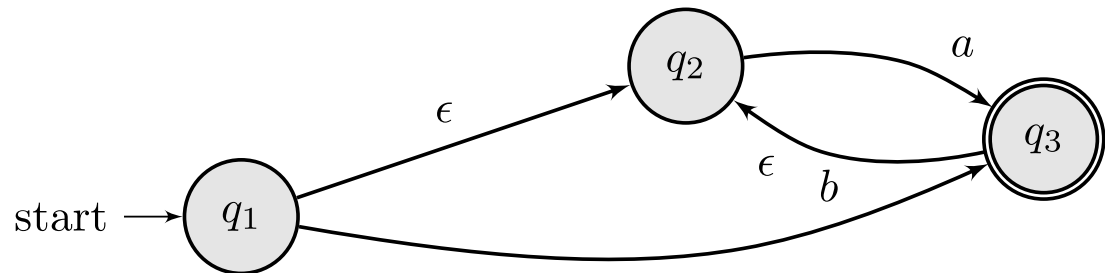
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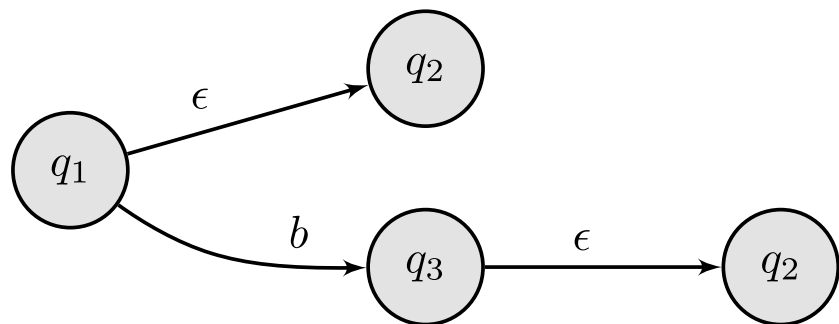
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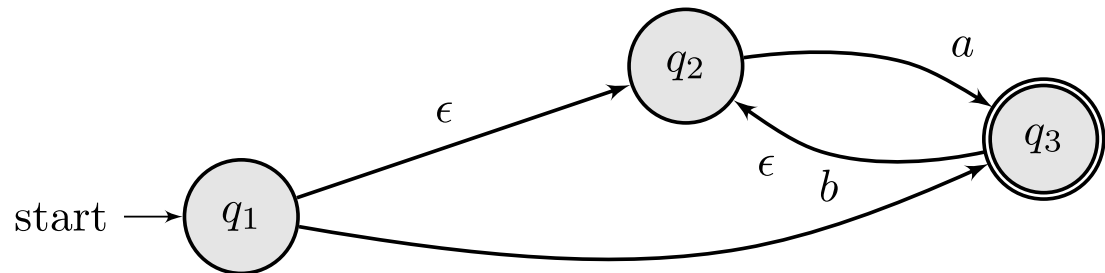
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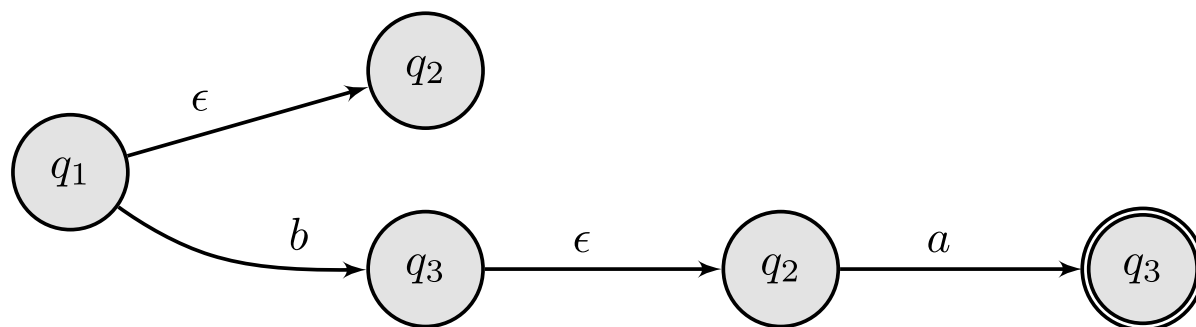
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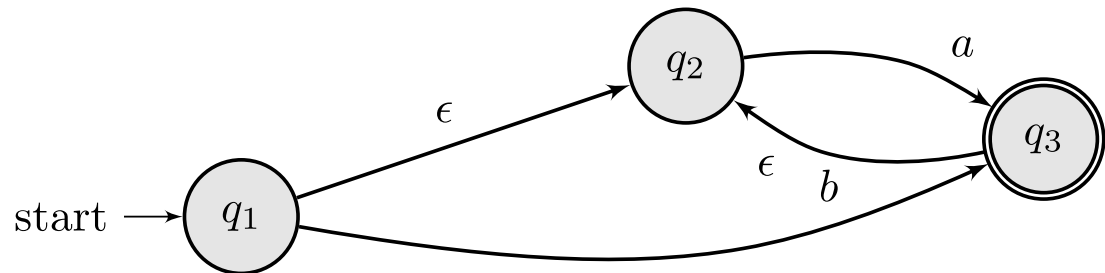
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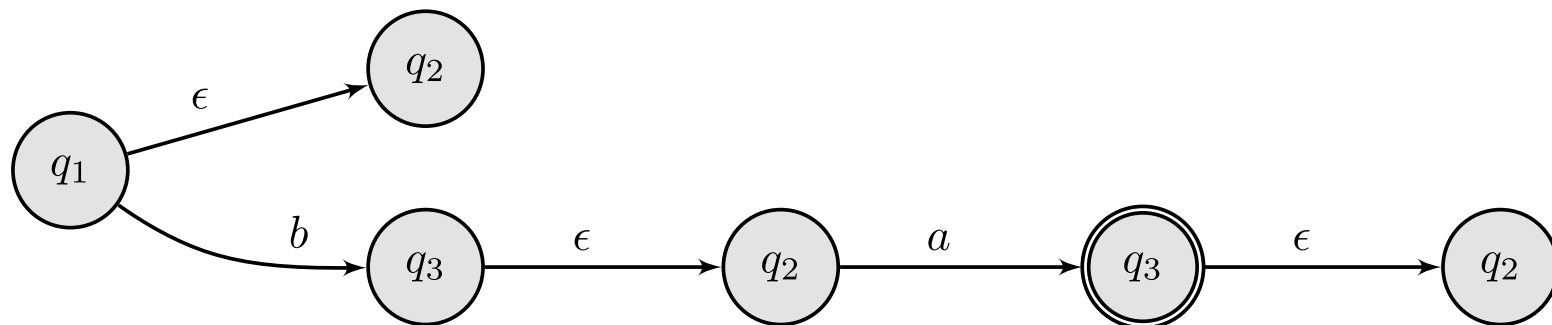
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Reduction graphs with ϵ -transitions



Acceptance for ba



What is the Powerset function?

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Given a set it returns a set that consists of all possible subsets of that set and itself.

$$\mathcal{P}(s) = \{r \mid r \subseteq s\}$$

Example

$$\mathcal{P}(\{q_1, q_2, q_3\}) =$$

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Example

$$\mathcal{P}(\{q_1, q_2, q_3\}) = \{\emptyset, \{q_1\}, \{q_2\}, \{q_3\}, \{q_1, q_2\}, \{q_1, q_3\}, \{q_2, q_3\}, \{q_1, q_2, q_3\}\}$$

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$$\delta(q_1, \mathbf{a}) = \{q_1, q_2, q_3\}$$

$$\delta(q_1, \epsilon) = \{q_3\}$$

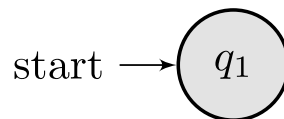
$$\delta(q_2, \mathbf{a}) = \{q_1, q_3\}$$

$$\delta(q_2, \mathbf{b}) = \{q_2\}$$

$$\delta(q_3, \mathbf{b}) = \{q_4\}$$

$$\delta(q_3, \epsilon) = \{q_1\}$$

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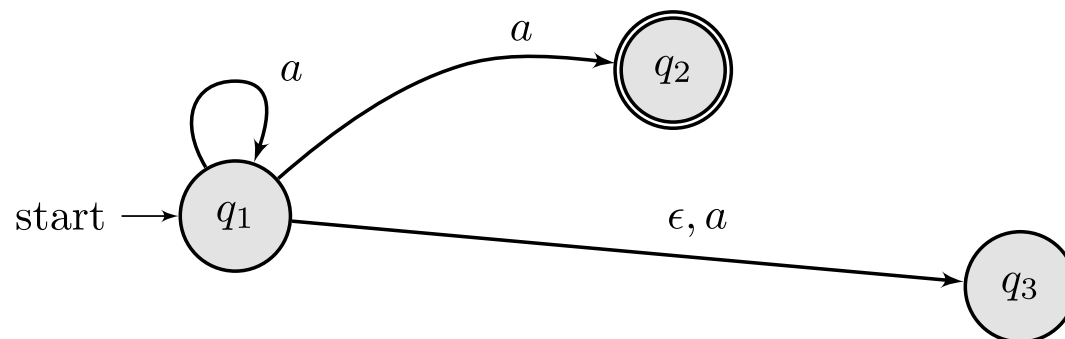
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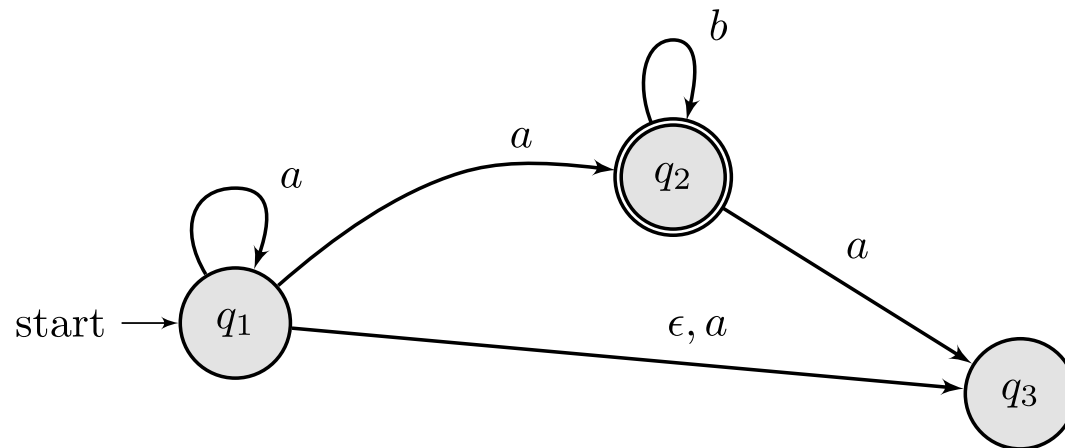
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$$\delta(q_1, a) = \{q_1, q_2, q_3\}$$

$$\delta(q_1, \epsilon) = \{q_3\}$$

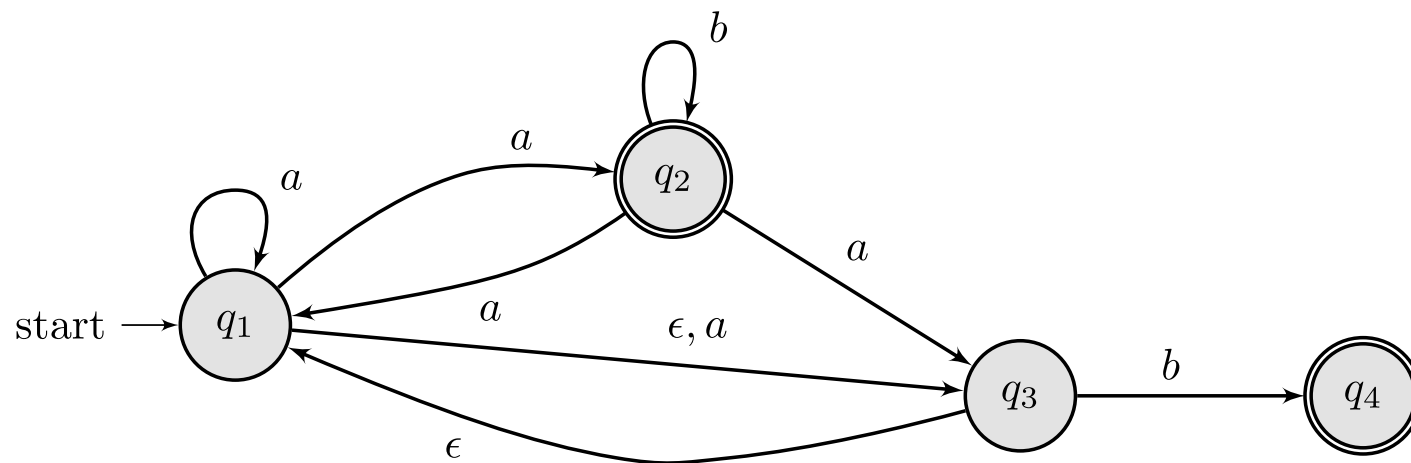
$$\delta(q_2, a) = \{q_1, q_3\}$$

$$\delta(q_2, b) = \{q_2\}$$

$$\delta(q_3, b) = \{q_4\}$$

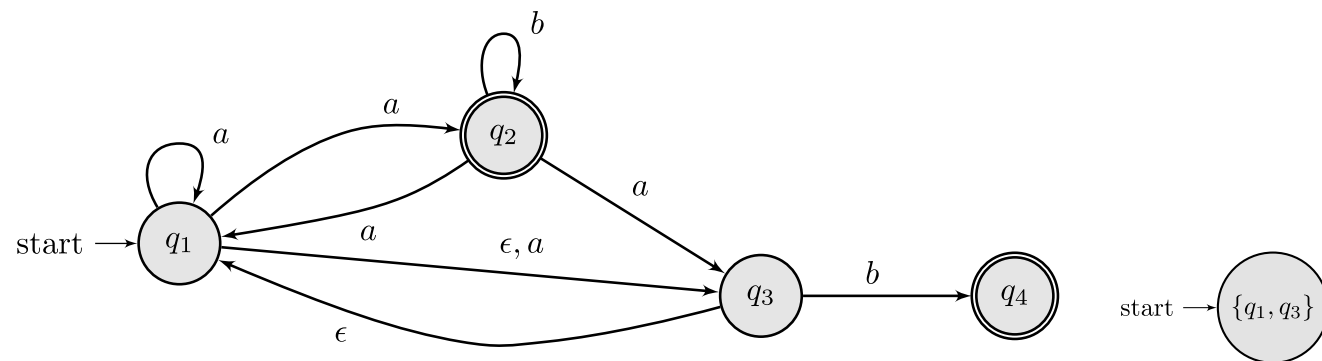
$$\delta(q_3, \epsilon) = \{q_1\}$$

$$\delta(q, c) = \emptyset \text{ otherwise}$$



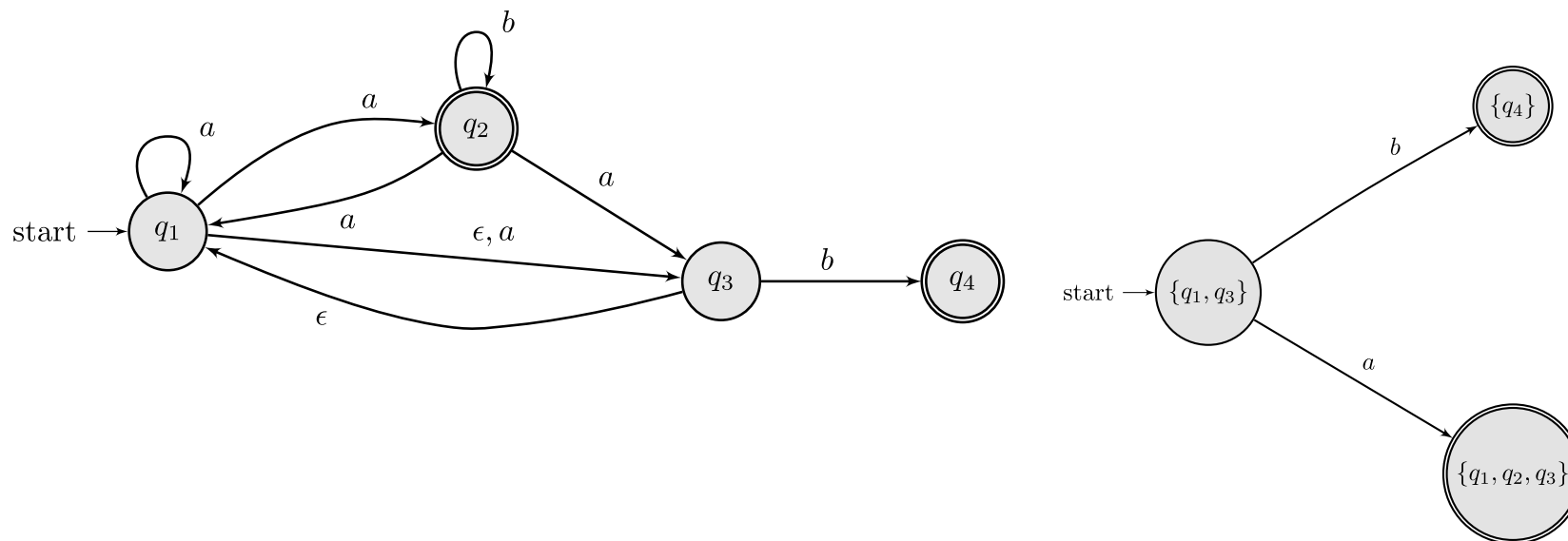
Producing a DFA from an NFA

Producing a DFA from an NFA



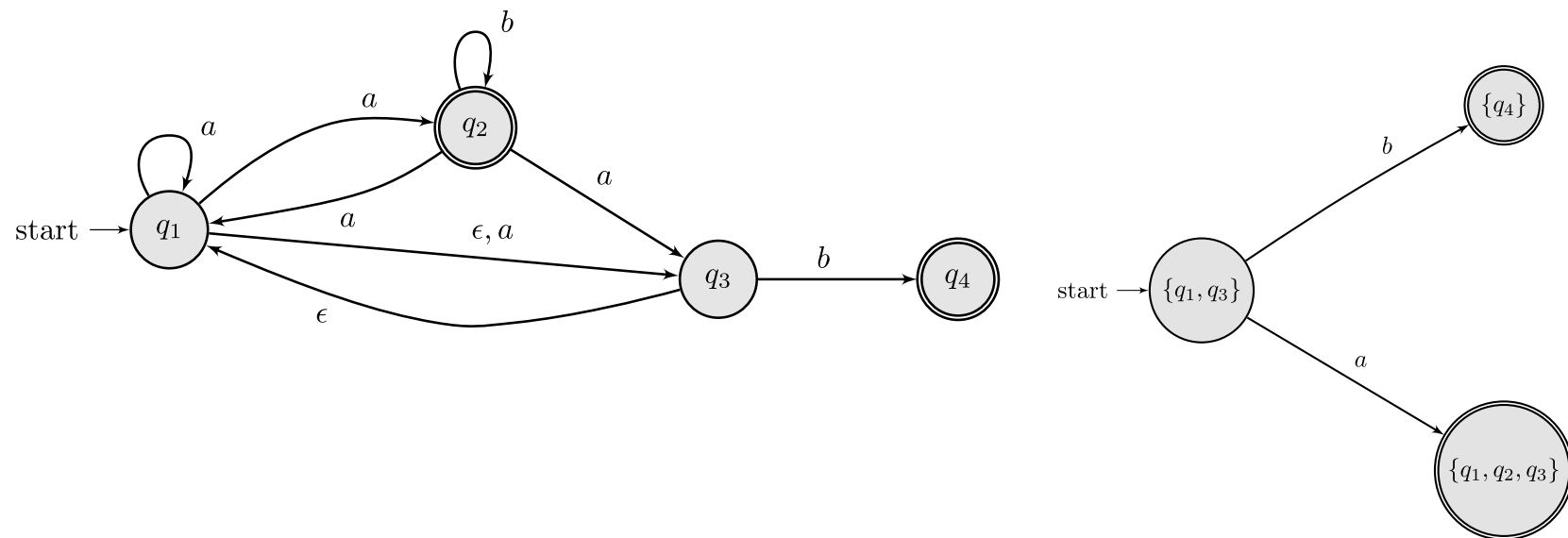
The initial state is the set of all states in the NFA that are reachable from q_1 via ϵ transitions plus q_1 .

Producing a DFA from an NFA



- For each input in Σ range we must draw a transition to a target state.
- A target state is found by taking an input, say a , and doing an input+epsilon step on each sub-state.

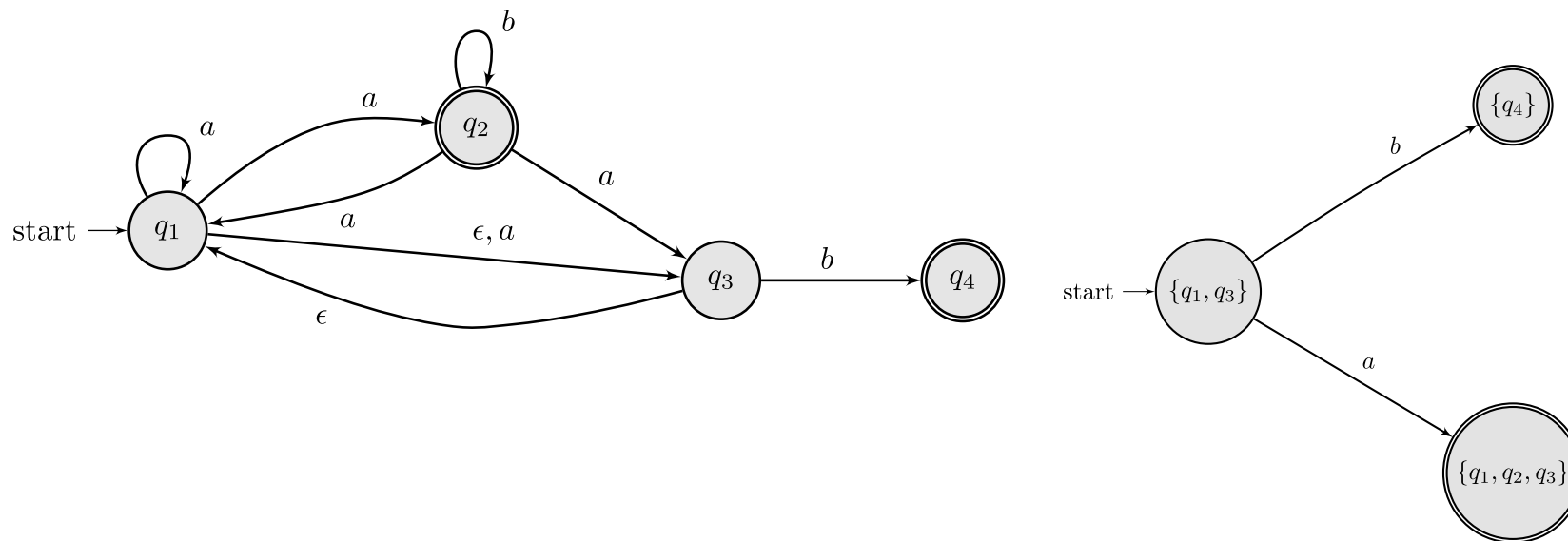
Producing a DFA from an NFA



First, input a we find all reachable states (via input+epsilon state) that start from either q_1 or q_3 .

- From q_1 via a we get $\{q_1, q_2, q_3\}$
- From q_3 via a we get $\{q_1, q_3\}$
- The result is the union of all reachable states, thus $\{q_1, q_2, q_3\}$

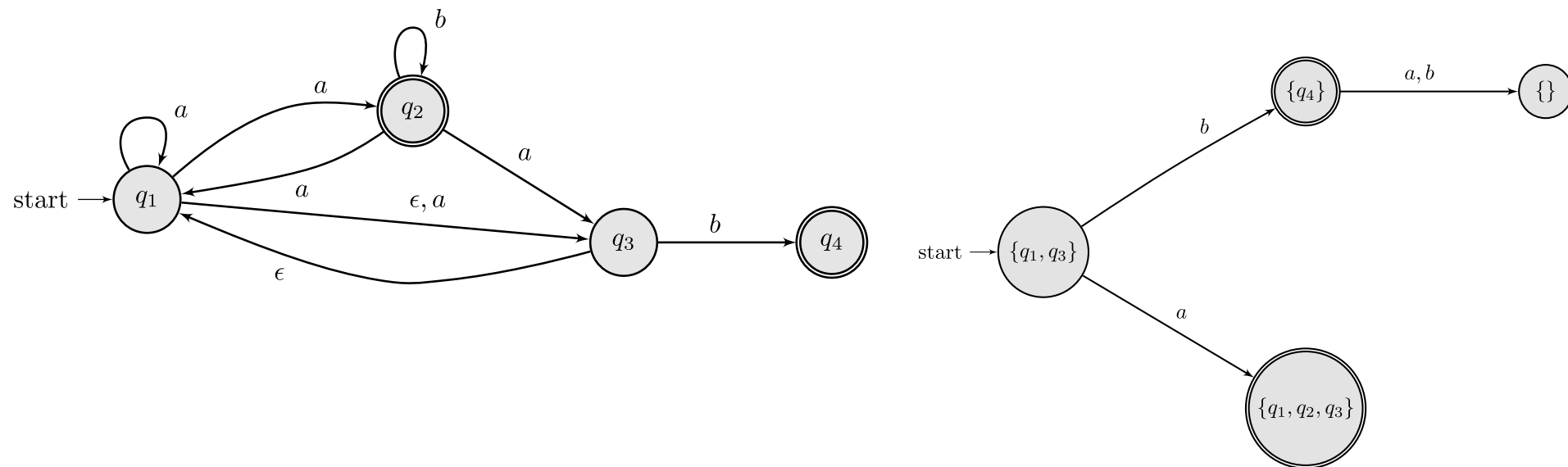
Producing a DFA from an NFA



Second, input **b** we find all reachable states (via input+epsilon state) that start from either q_1 or q_3 .

- From q_1 via **b** we get \emptyset
- From q_3 via **b** we get $\{q_4\}$
- Result state is $\emptyset \cup \{q_4\} = \{q_4\}$

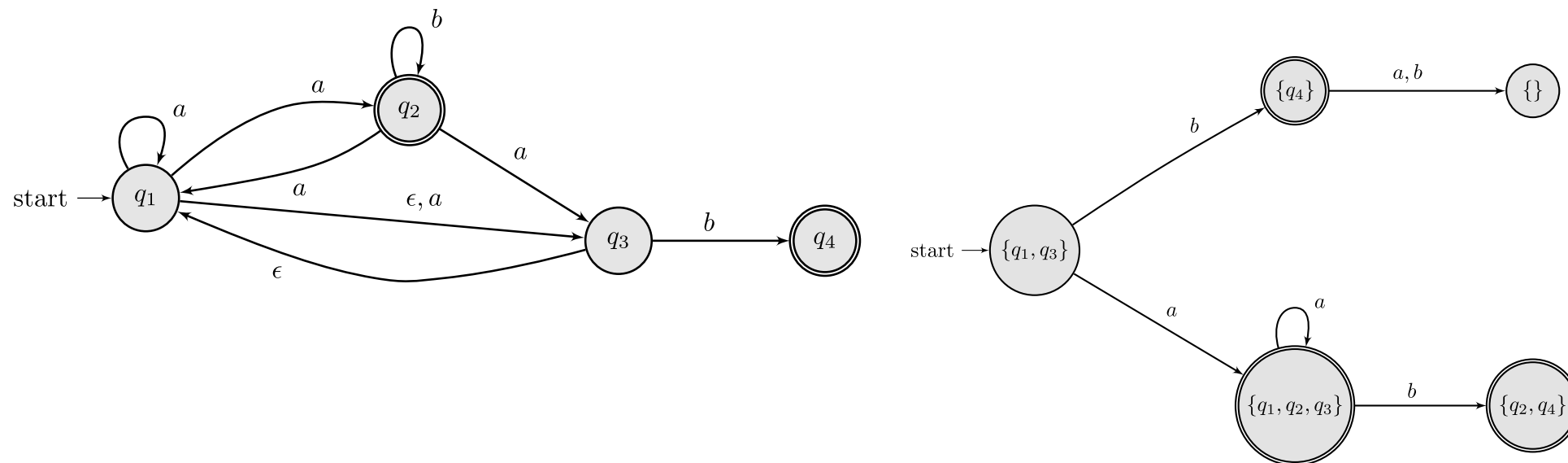
Producing a DFA from an NFA



For inputs **a** and **b** we find all reachable states (via input+epsilon state) that start from q_4 :

- From q_4 via **a** we get \emptyset , so the result state is \emptyset
- From q_4 via **b** we get \emptyset , so the result state is \emptyset

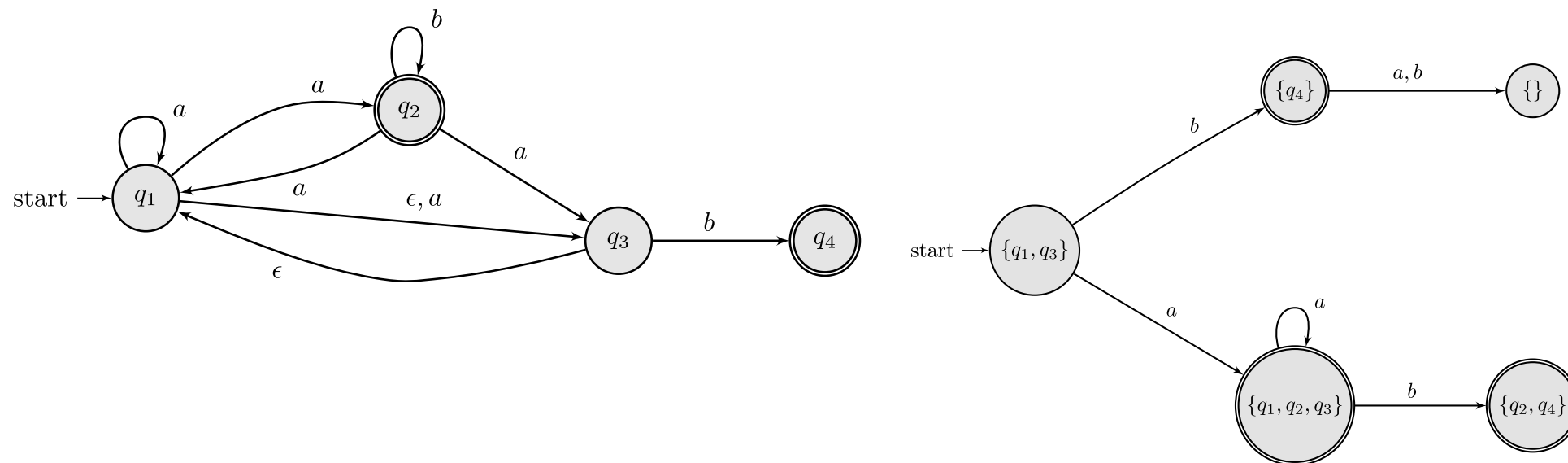
Producing a DFA from an NFA



Transition from $\{q_1, q_2, q_3\}$ via a?

- We know with $\{q_1, q_3\}$ with a we reach $\{q_1, q_2, q_3\}$
- From q_2 with a we reach $\{q_3\}$
- Thus, result state is $\{q_1, q_2, q_3\} \cup \{q_3\} = \{q_1, q_2, q_3\}$ (self-loop)

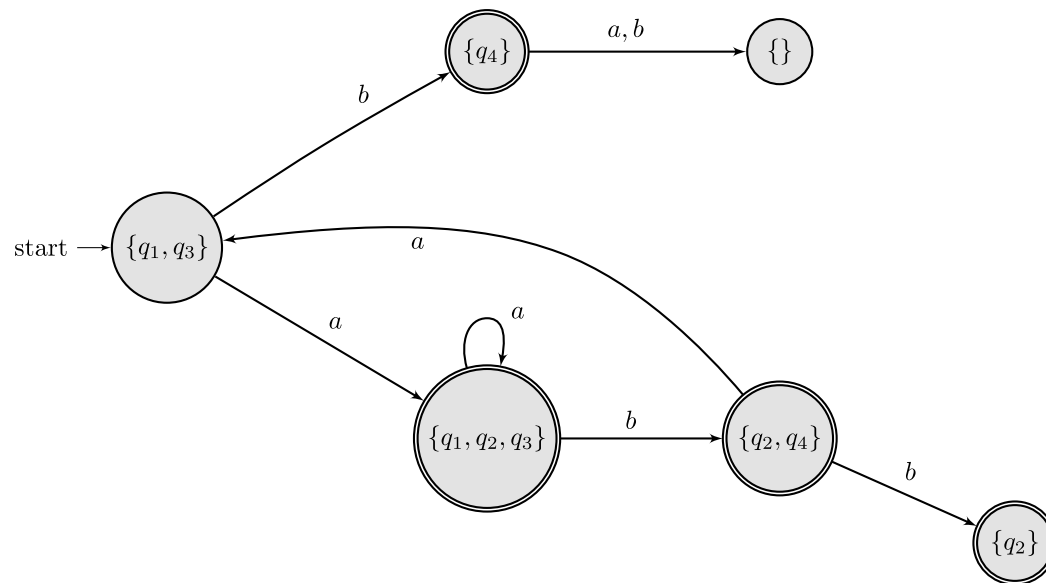
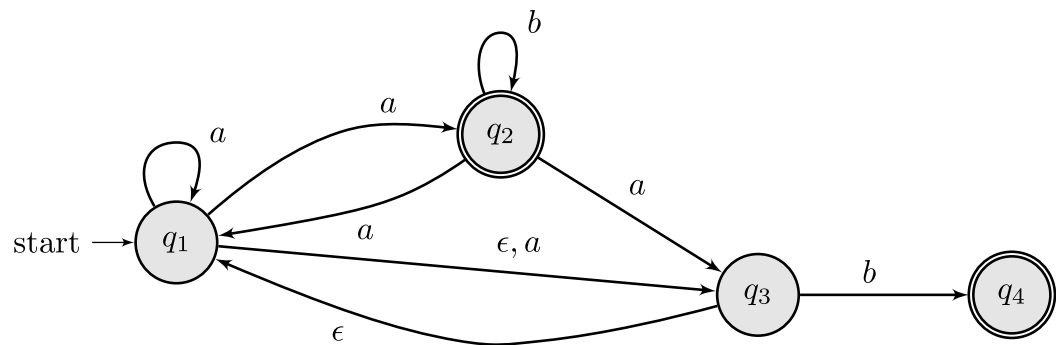
Producing a DFA from an NFA



Transition from $\{q_1, q_2, q_3\}$ via b ?

- We know with $\{q_1, q_3\}$ with b we reach $\{q_4\}$
- From q_2 with b we reach $\{q_2\}$
- Thus, result state is $\{q_4\} \cup \{q_2\} = \{q_2, q_4\}$

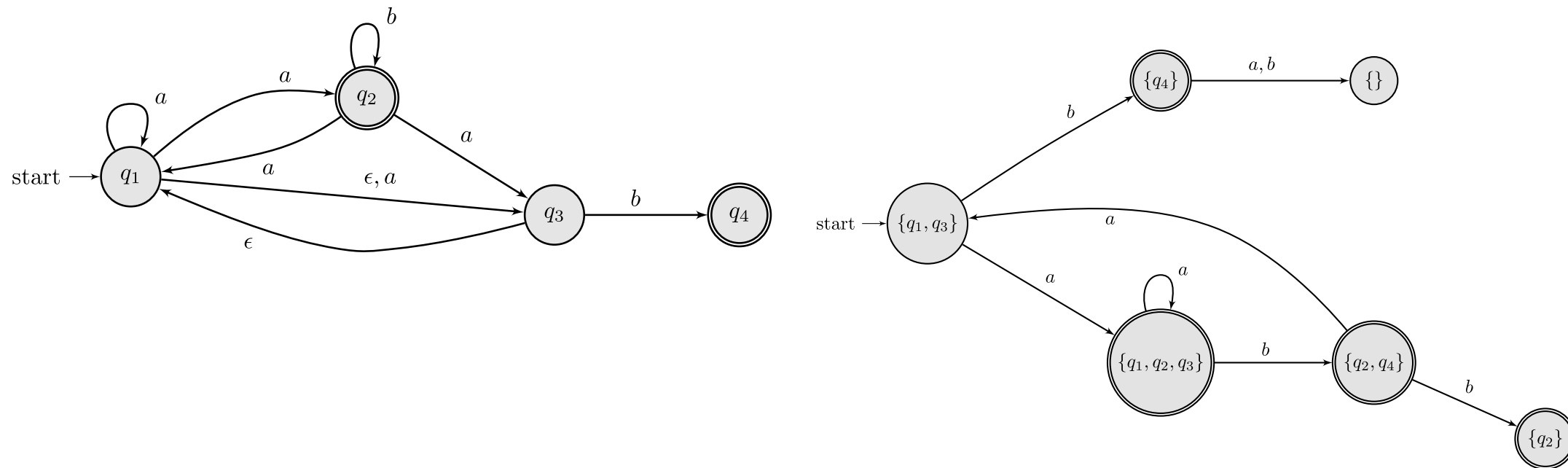
Producing a DFA from an NFA



Transition from $\{q_2, q_4\}$ via a?

- From q_2 with a we reach $\{q_1, q_3\}$
- From q_4 with a we reach \emptyset
- Thus, result state is $\{q_1, q_3\} \cup \emptyset = \{q_1, q_3\}$

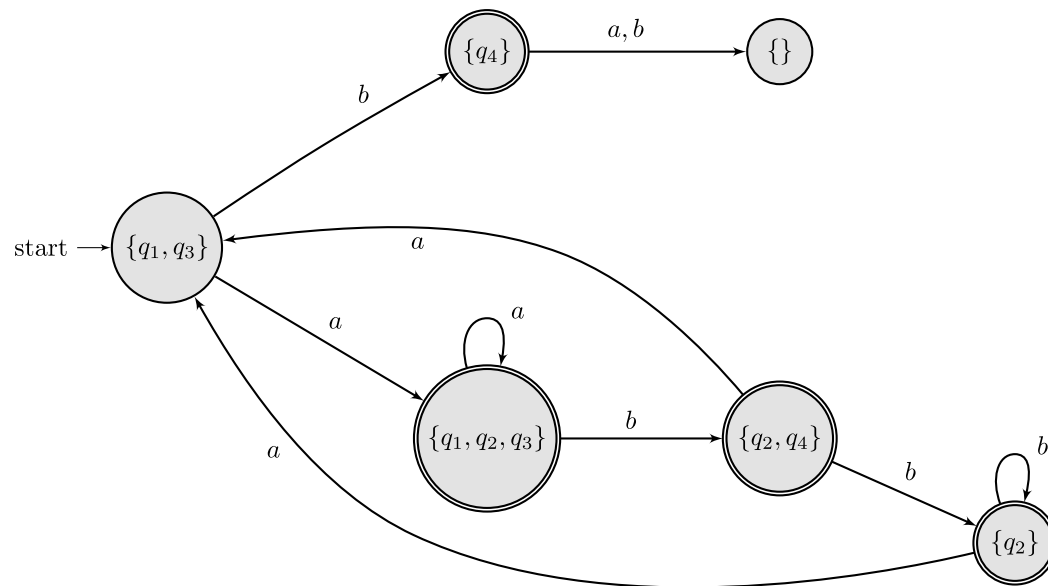
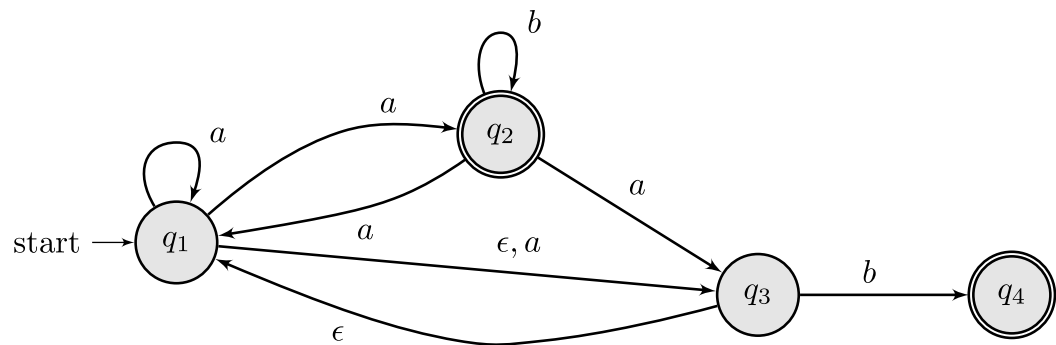
Producing a DFA from an NFA



Transition from $\{q_2, q_4\}$ via b?

- From q_2 with b we reach $\{q_2\}$
- From q_4 with b we reach \emptyset
- Thus, result state is $\{q_2\} \cup \emptyset = \{q_2\}$

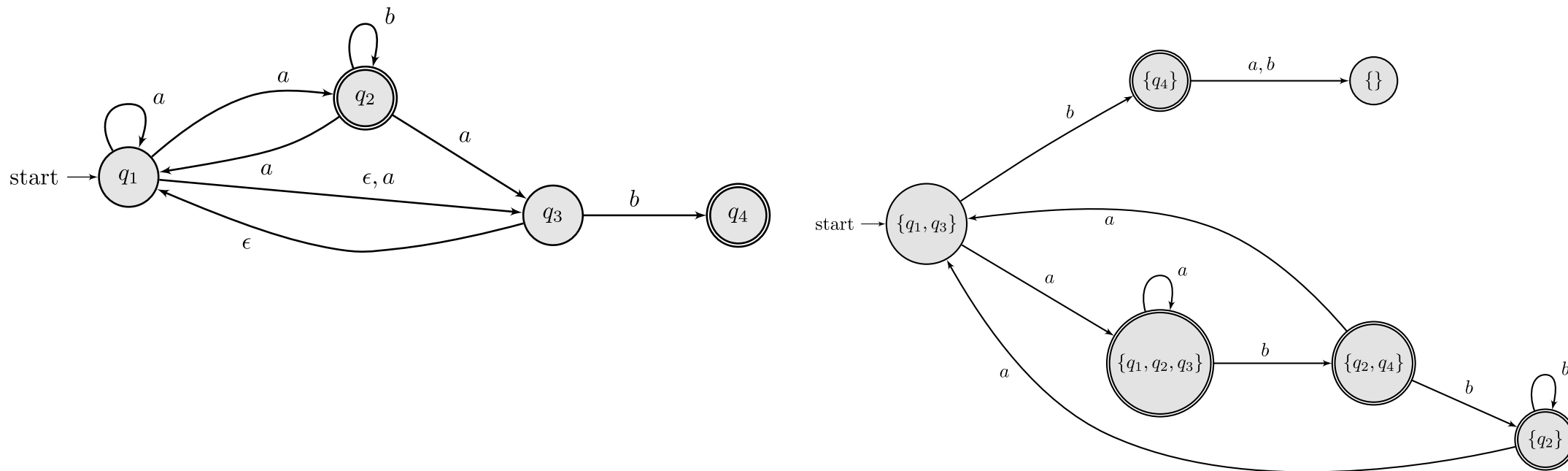
Producing a DFA from an NFA



Transition from $\{q_2\}$ via a?

- From q_2 with a we reach $\{q_1, q_3\}$ (result state)

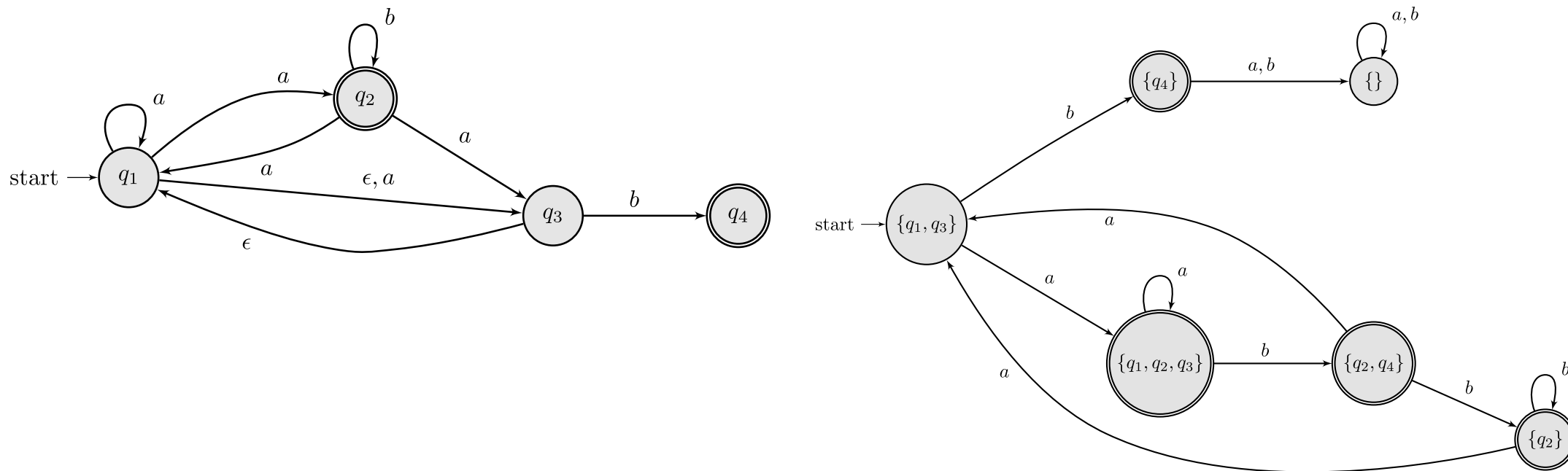
Producing a DFA from an NFA



Transition from $\{q_2\}$ via b?

- From q_2 with b we reach $\{q_2\}$ (result state; self loop)

Producing a DFA from an NFA



State $\{\}$ (also known as \emptyset) is a **sink state**, so we draw a self loop for every input in Σ .

Today we will learn...

- Nil
- Empty
- Character
- Union
- Concatenation
- Star

■ Section 1.2

The \mathbf{nil}_Σ operator

$$L(\mathbf{nil}_\Sigma) = \emptyset$$

The nil_Σ operator

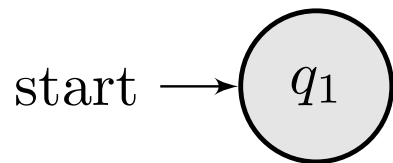
$$L(\text{nil}_\Sigma) = \emptyset$$

Example $\Sigma = \{\mathbf{a}, \mathbf{b}\}$

The nil_Σ operator

$$L(\text{nil}_\Sigma) = \emptyset$$

Example $\Sigma = \{a, b\}$



Implementation

```
def make_nil(alphabet):
    Q1 = 0
    return NFA(
        states=[Q1], alphabet=alphabet, transition_func=lambda q, a: {},
        start_state=Q1, accepted_states=[])
```

The empty_Σ operator

$$L(\text{empty}_\Sigma) = \{\epsilon\}$$

The empty_Σ operator

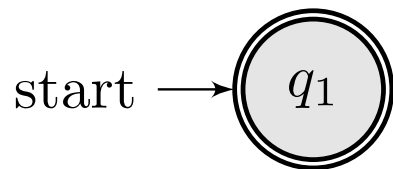
$$L(\text{empty}_\Sigma) = \{\epsilon\}$$

Example $\Sigma = \{a, b\}$

The empty_Σ operator

$$L(\text{empty}_\Sigma) = \{\epsilon\}$$

Example $\Sigma = \{a, b\}$



Implementation

```
def make_empty(cls, alphabet):
    Q1 = 0
    return NFA(
        states = [Q1],
        alphabet = alphabet,
        transition_func = lambda q, a: {},
        start_state = Q1, accepted_states = [Q1])
```

The $\text{char}_\Sigma(c)$ operator

$$L(\text{empty}_\Sigma(c)) = \{[c]\}$$

The $\text{char}_\Sigma(c)$ operator

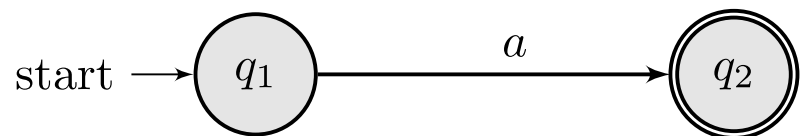
$$L(\text{empty}_\Sigma(c)) = \{[c]\}$$

Example $\Sigma = \{\mathbf{a}, \mathbf{b}\}$

The $\text{char}_\Sigma(c)$ operator

$$L(\text{empty}_\Sigma(c)) = \{[c]\}$$

Example $\Sigma = \{a, b\}$



Implementation

```

def make_char(cls, alphabet, char):
    states = Q1, Q2 = 0, 1
    def transition(q, a):
        return {Q2} if a == char and q == Q1 else {}
    return cls(states, alphabet, transition, Q1, [Q2])
  
```

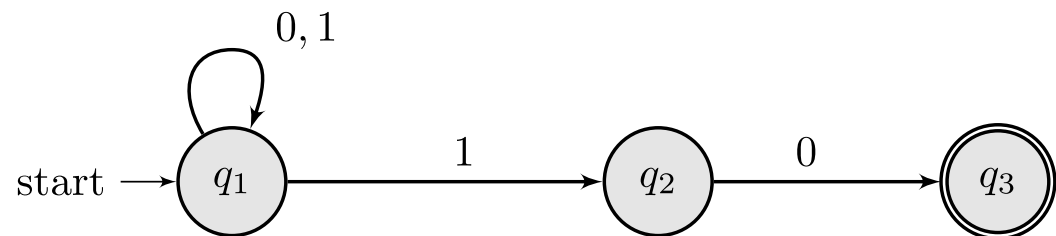
The **union**(M, N) operator

$$L(\text{union}(M, N)) = L(M) \cup L(N)$$

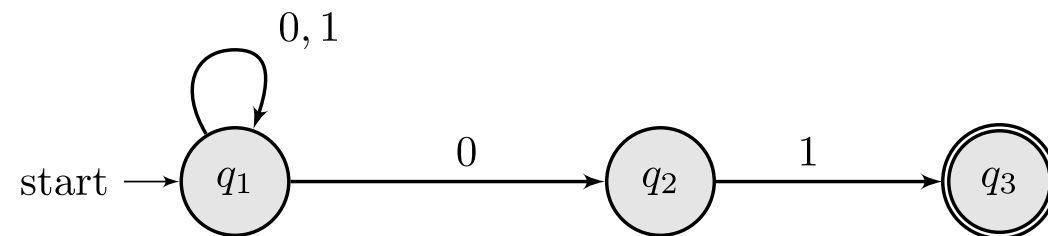
The $\text{union}(M, N)$ operator

$$L(\text{union}(M, N)) = L(M) \cup L(N)$$

N_1



N_2

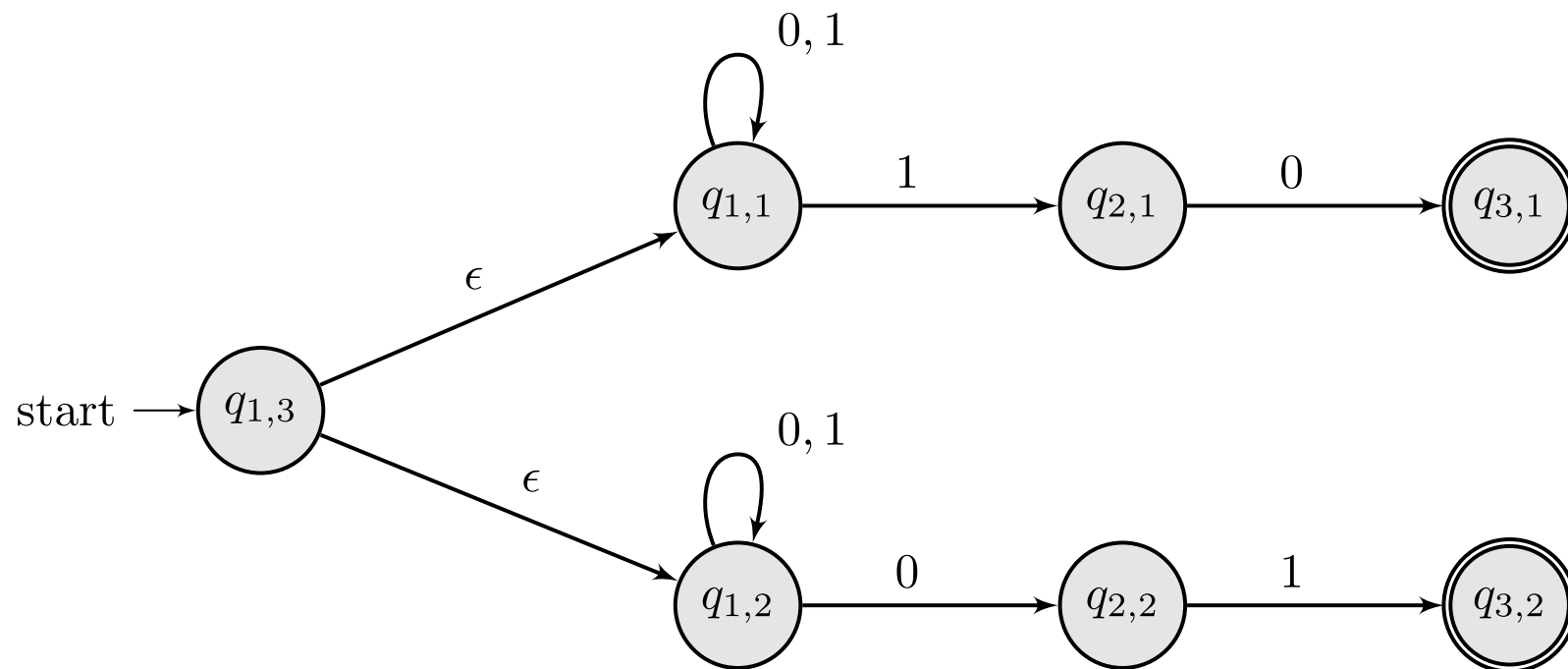


$\text{union}(N_1, N_2) = ?$

The $\text{union}(M, N)$ operator

$$L(\text{union}(M, N)) = L(M) \cup L(N)$$

Example $\text{union}(N_1, N_2)$



- Add a new initial state
- Connect new initial state to the initial states of N_1 and N_2 via ϵ -transitions.

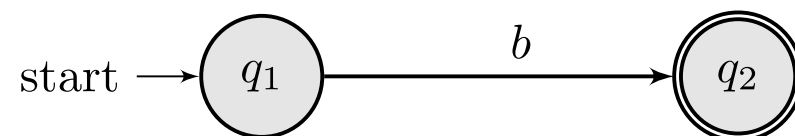
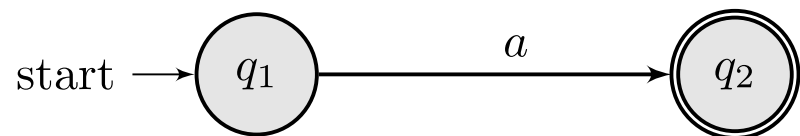
The **concat**(M, N) operator

$$L(\text{concat}(M, N)) = L(M) \cdot L(N)$$

The $\text{concat}(M, N)$ operator

$$L(\text{concat}(M, N)) = L(M) \cdot L(N)$$

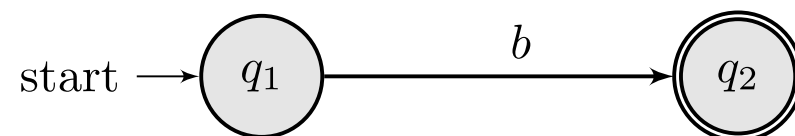
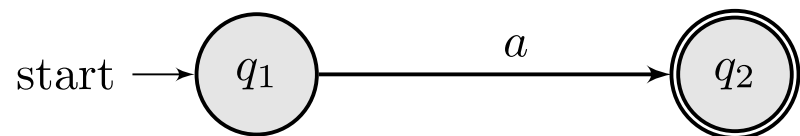
Example 1: $L(\text{concat}(\text{char}(\mathbf{a}), \text{char}(\mathbf{b}))) = \{\mathbf{ab}\}$



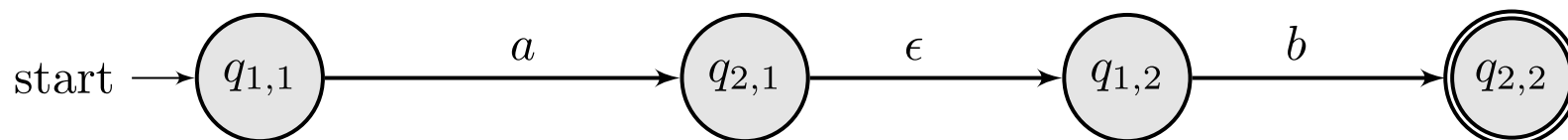
The $\text{concat}(M, N)$ operator

$$L(\text{concat}(M, N)) = L(M) \cdot L(N)$$

Example 1: $L(\text{concat}(\text{char}(\mathbf{a}), \text{char}(\mathbf{b}))) = \{\mathbf{ab}\}$



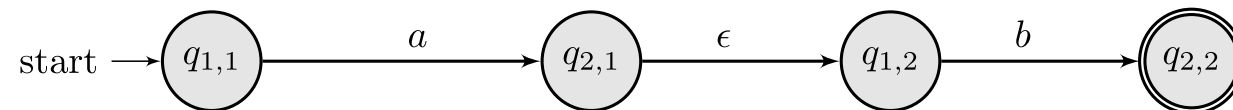
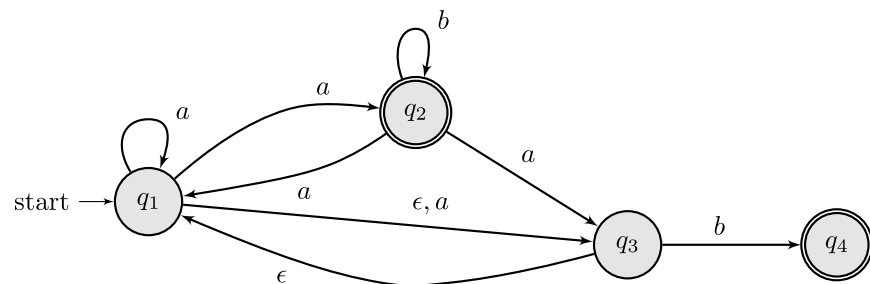
Solution



What did we do? Connect the accepted states of N_1 to the initial state of N_2 via ϵ -transitions.

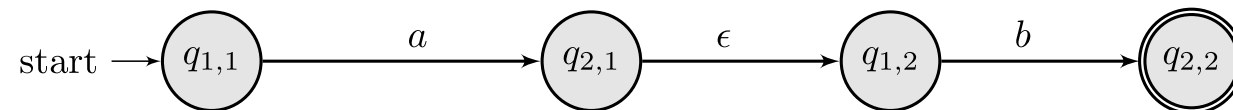
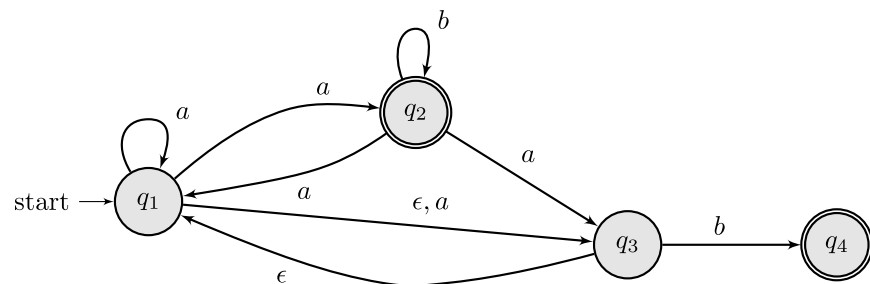
Why not connect directly from $q_{1,1}$ into $q_{1,2}$? See next slide.

Concatenation example 2

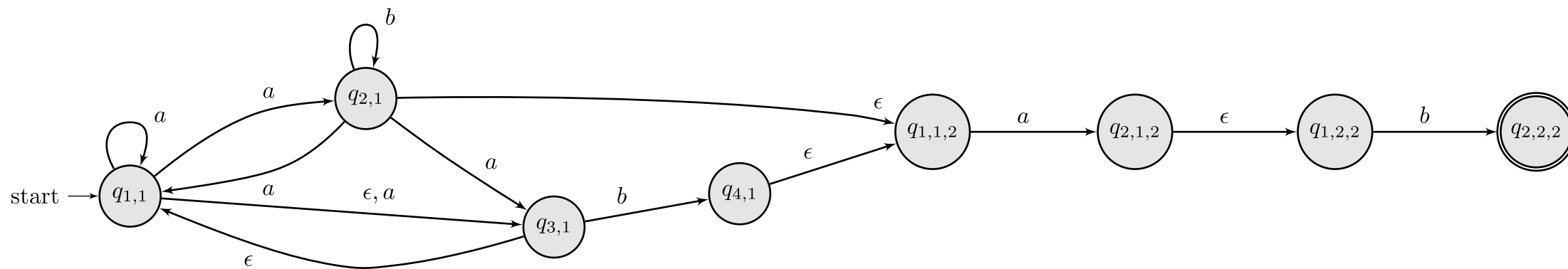


Solution

Concatenation example 2



Solution



Concatenate two NFAs

Let $N_1 = (Q_1, \Sigma_1, \delta_1, q_1, F_1)$, $N_2 = (Q_2, \Sigma_2, \delta_2, q_2, F_2)$, $\text{tag}(Q, n) = \{q^n \mid q \in Q\}$.

We have that $N_1 \cdot N_2 = (Q, \Sigma, \delta, q_1^1, F_2)$ where:

- $Q = \text{tag}(Q_1, 1) \cup \text{tag}(Q_2, 2)$
- $\Sigma = \Sigma_1 \cup \Sigma_2$
- $\delta(q^1, \epsilon) = \{q_2^2\}$ if $q \in F_1$ (Note: q_2^2 represents the starting state of N_2 tagged with 2.)
- $\delta(q^n, a) = \text{tag}(\delta_n(r, a), n)$ if $n \in \{1, 2\}$

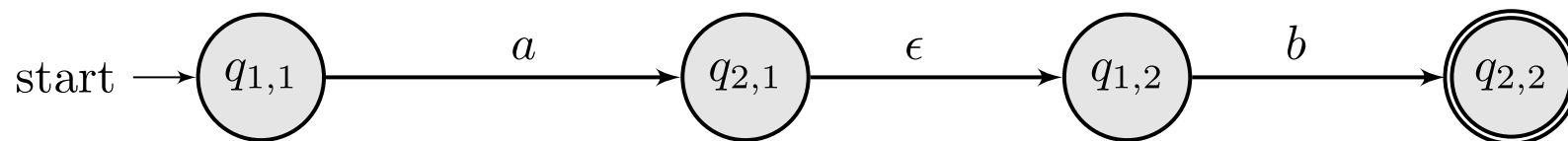
The $\text{star}(N)$ operator

$$L(\text{star}(N)) = L(N)^*$$

The $\text{star}(N)$ operator

$$L(\text{star}(N)) = L(N)^*$$

Example: $L(\text{star}(\text{concat}(\text{char}(\mathbf{a}), \text{char}(\mathbf{b})))) = \{w \mid w \text{ is a sequence of } \mathbf{ab} \text{ or empty}\}$

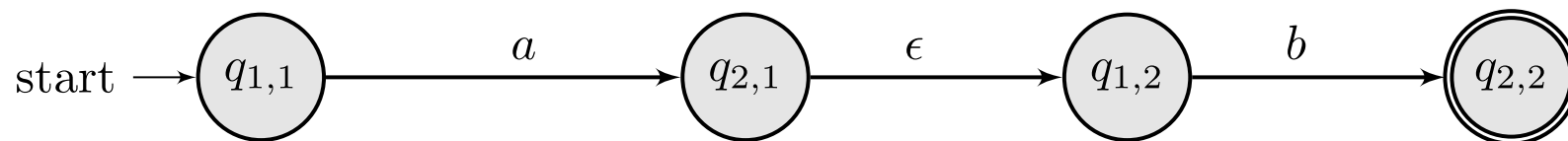


Solution

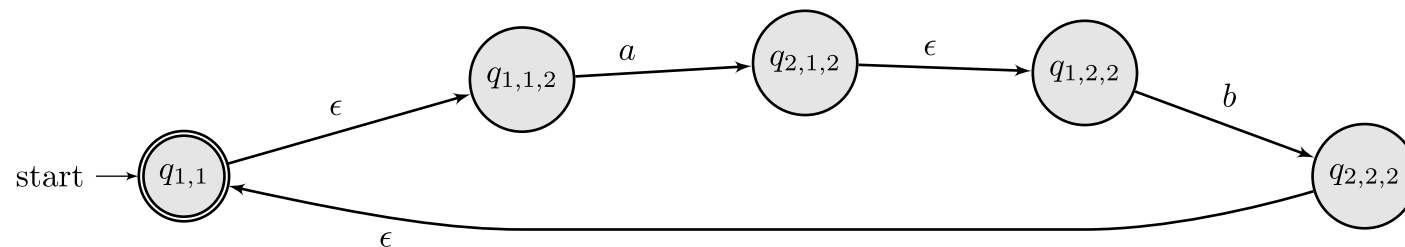
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Example: $L(\text{star}(\text{concat}(\text{char}(\mathbf{a}), \text{char}(\mathbf{b})))) = \{w \mid w \text{ is a sequence of } \mathbf{ab} \text{ or empty}\}$



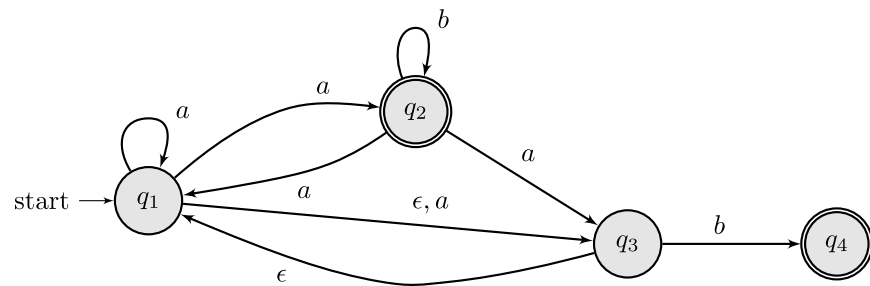
Solution



- create a new state $q_{1,1}$
- ϵ -transitions from $q_{1,1}$ to initial state
- ϵ -transitions from accepted states to $q_{1,1}$
- $q_{1,1}$ is the only accepted state

The $\text{star}(N)$ operator

$$L(\text{star}(N)) = L(N)^*$$



The $\text{star}(N)$ operator

$$L(\text{star}(N)) = L(N)^*$$

