## CS450

## Structure of Higher Level Languages

Lecture 17: λ<sub>D</sub>

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Press arrow keys  $\vdash$   $\rightarrow$  to change slides.

## Lookout! HW5 ex1

```
(define (s:subst exp var val)
  (match exp
    ; [(s:variable x) (if (equal? exp var) ... ...)]
    [(? s:variable?)
      (if (equal? exp var)
        ; then
        : else
        . . .
    [(? s:number?) ...]
    [(s:lambda x e) (if (equal? x var) \dots ...)]
    [(s:apply ef ea) ...]
```

# Shared "mutable" state with immutable data-structures

# Why immutability?

#### Benefits

- A necessity if we use a language without mutation (such as Haskell)
- Parallelism: A great way to implement fast and safe data-structures in concurrent code (look up <u>copy-on-write</u>)
- Development: Controlled mutation improves code maintainability
- Memory management: counters the problem of circular references (notably, useful in C++ and Rust, see example)

Encoding shared mutable state with immutable data-structures is a great skill to have.



## Heap

We want to design a data-structure that represents a **heap** (a shared memory buffer) that allows us to: **allocate** a new memory cell, **load** the contents of a memory cell, and **update** the contents of a memory cell.

#### Constructors

- empty-heap returns an empty heap
- (heap-alloc h v) creates a new memory cell in heap h whose contents are value v
- (heap-put h r v) updates the contents of memory handle r with value v in heap h

#### Selectors

• (heap-get h r) returns the contents of memory handle r in heap h



## Heap usage

```
(define h empty-heap) ; h is an empty heap
(define r (heap-alloc h "foo")) ; stores "foo" in a new memory cell
```

- What should the return value of heap-alloc?
  - Should heap-alloc return a copy of h extended with "foo"? How do we access the memory cell pointing to "foo"?
  - Should heap-alloc return a handle to the new memory cell? How can we access the new heap?



## Heap usage

```
(define h empty-heap) ; h is an empty heap
(define r (heap-alloc h "foo")) ; stores "foo" in a new memory cell
```

What should the return value of heap-alloc?

- Should heap-alloc return a copy of h extended with "foo"? How do we access the memory cell pointing to "foo"?
- Should heap-alloc return a handle to the new memory cell? How can we access the new heap?

Function heap-alloc must return a *pair* eff that contains the new heap and the memory handle.

```
(struct eff (state result) #:transparent)
```



## Heap usage example

#### Spec

```
(define h1 empty-heap) ; h is an empty heap
(define r (heap-alloc h1 "foo")); stores "foo" in a new memory cell
(define h2 (eff-state r))
(define x (eff-result r));
(check-equal? "foo" (heap-get h2 x)); checks that "foo" is in x
(define h3 (heap-put h2 x "bar")) ; stores "bar" in x
(check-equal? "bar" (heap-get h3 x)); checks that "bar" is in x
```



## Handles must be unique

We want to ensure that the handles we create are **unique**, otherwise allocation could overwrite existing data, which is undesirable.

#### Spec



# How can we implement a memory handle?

# A simple heap implementation

- Let a handle be an integer
- Recall that the heap only grows (no deletions)
- A handle matches the number of elements already present in the heap
- When the heap is empty, the first handle is 0, the second handle is 1, and so on.



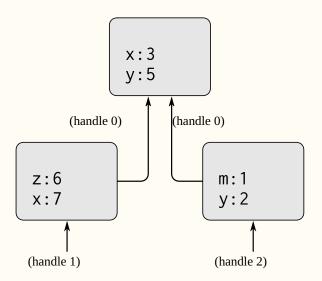
# Heap implementation

- We use a hash-table to represent the heap because it has a faster random-access than a linked-list (where lookup is linear on the size of the list).
- We wrap the hash-table in a struct, and the handle (which is a number) in a struct, for better error messages. And because it helps maintaining the code.

```
(struct heap (data) #:transparent)
(define empty-heap (heap (hash)))
(struct handle (id) #:transparent)
(struct eff (state result) #:transparent)
(define (heap-alloc h v)
  (define data (heap-data h))
  (define new-id (handle (hash-count data)))
  (define new-heap (heap (hash-set data new-id v)))
  (eff new-heap new-id))
(define (heap-get h k)
  (hash-ref (heap-data h) k))
(define (heap-put h k v)
  (define data (heap-data h))
  (cond
    [(hash-has-key? data k) (heap (hash-set data k v))]
    [else (error "Unknown handle!")]))
```

# Visualizing the environment

## Environment visualization

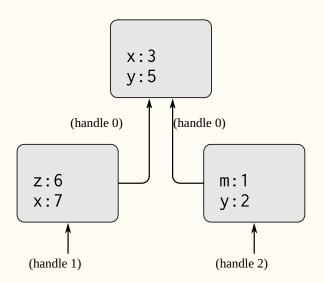


**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

```
; E\theta = (handle \theta)
E0: [
  (x \cdot 3)
 (y.5)
; E1 = (handle 1)
  (z.6)
  (x.7); shadows E\theta.x
 ; (y . 5)
; E2 = (handle 2)
  (m.1)
  (y . 2); shadows E0.y
                                     UMass
  ; (x . 3)
                                     Boston
```

## Environment visualization



**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

### The heap at runtime

- arrows are **references**, or heap handles:
- boxes are *frames*: labelled by their handles
- each frame has local variable bindings (eg, m:1, and y:2)



## Environment visualization

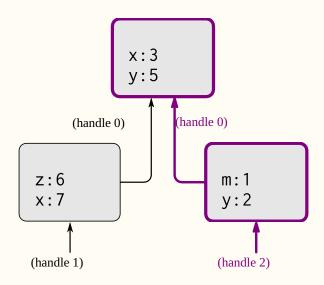


Figure 3.1: A simple environment structure.

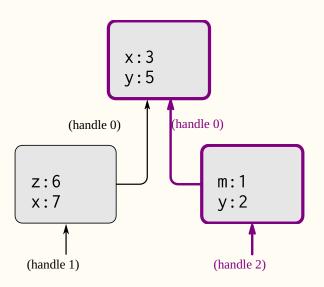
Source: SICP book Section 3.2

### The heap at runtime

- arrows are references, or heap handles:
- boxes are *frames*: labelled by their handles
- each frame has local variable bindings (eg, m:1, and y:2)
- an environment represents a sequence of frames, connected via references.
   For instance, the environment that consists of frame 3 linked to frame 1.
- variable lookup follows the reference order. For instance, lookup a variable in frame 3 and then in frame 1.

**Boston** 

# Quiz



List all variable bindings in environment (handle 1)

**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2



# Implementing mutable environments

# Implementing mutable environments

#### Heap

• A heap contains *frames* 

#### Frame

- a reference to its parent frame (except for the root frame which does not refer any other frame)
- a map of local bindings

```
Example of a frame: [ E0 (y . 1) ]
Example of a root frame: [ (a . 20) (b . (closure E0 (lambda (y) a)) ]
```

```
E0: [
  (a . 20)
  (b . (closure E0 (lambda (y) a)))
]
E1: [ E0
  (y . 1)
]
```



# Let us implement frames...

(demo time)

# Usage examples

```
; (closure E0 (lambda (y) a)
(define c (d:closure (handle 0) (d:lambda (list (d:variable 'y)) (d:variable 'a))))
:Ε0: Γ
; (a . 20)
: (b . (closure E0 (lambda (y) a)))
(define f1
  (frame-put
    (frame-put root-frame (d:variable 'a) (d:number 10))
    (d:variable 'b) c))
(check-equal? f1 (frame #f (hash (d:variable 'a) (d:number 10) (d:variable 'b) c)))
; Lookup a
(check-equal? (d:number 10) (frame-get f1 (d:variable 'a)))
: Lookup b
(check-equal? c (frame-get f1 (d:variable 'b)))
; Lookup c that does not exist
                                                                                    Boston
(check-equal? #f (frame-get f1 (d:variable 'c)))
```

# More usage examples

```
; E1: [E0; (y . 1); ]

(define f2 (frame-push (handle 0) (d:variable 'y) (d:number 1)))

(check-equal? f2 (frame (handle 0) (hash (d:variable 'y) (d:number 1))))

(check-equal? (d:number 1) (frame-get f2 (d:variable 'y)))

(check-equal? #f (frame-get f2 (d:variable 'a)))

;; We can use frame-parse to build frames

(check-equal? (parse-frame '[ (a . 10) (b . (closure E0 (lambda (y) a)))]) f1)

(check-equal? (parse-frame '[ E0 (y . 1) ]) f2))
```



## Frames

```
(struct frame (parent locals))
```

- parent is either #f or is a reference to the parent frame
- locals is a hash-table with the local variables of this frame

#### Constructors

#### Description

- root-frame creates an orphan empty frame (hence #f). This function is needed to represent the top-level environment.
- frame-push takes a reference that points to the parent frame, and initializes a hash-table with one entry (var, val). This function is needed for  $E\leftarrow E'+[x:=v]$
- frame-put updates the current frame with a new binding. This function is needed for  $E \leftarrow [x \stackrel{:}{\underset{\rm des}{=}} v]$

# Summary

Today we implement a mutable environment.

#### Constructors

- Empty: The empty, root environment.
- Put:  $E \leftarrow [x := v]$  updates an existing environment E upon defining a variable. Returns the same frame, and updates the heap.
- Push:  $E_2 \leftarrow E_1 + [x := v]$  creates a new environment  $E_2$  by extending environment  $E_1$  with one binding x = v. Returns the new environment.

#### Selectors

• Variable Lookup: E(x) Looks up variable x in the bindings of the current frame, otherwise recursively looks up the parent frame.



# Environment example

Environment visualization

 $\begin{array}{c} x:3\\y:5\\ \\ \text{(handle 0)} \\ \\ z:6\\x:7\\ \\ \text{(handle 1)} \\ \\ \text{(handle 2)} \\ \end{array}$ 

Environment operations

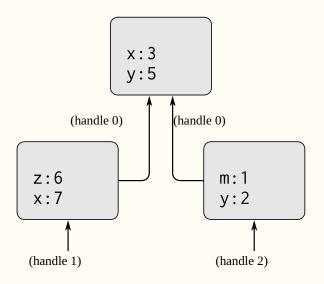
**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2



# Environment example

#### Environment visualization



#### Environment operations

**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2



## Constructors: Root

#### The root environment

```
(define root-alloc (heap-alloc empty-heap root-frame))
(define root-environ (eff-result root-alloc))
(define root-mem (eff-state root-alloc))
```



## Constructors: Put

$$E \leftarrow [x := v]$$

```
(define (environ-put mem env var val)
  (define new-frm (frame-put (heap-get mem env) var val))
  (heap-put mem env new-frm))
```

#### Example

```
E0 <- [x := 3]
E0 <- [y := 5]
```



## Constructors: Put

$$E \leftarrow [x := v]$$

```
(define (environ-put mem env var val)
  (define new-frm (frame-put (heap-get mem env) var val))
  (heap-put mem env new-frm))
```

#### Example

```
E0 <- [x := 3]
E0 <- [y := 5]
```

```
(define E0 root-environ)
(define m1
  (environ-put
      (environ-put root-heap E0 (d:variable 'x) (d:number 3))
      E0 (d:variable 'y) (d:number 5)))
```



## Constructors: Push

$$E_2 \leftarrow E_1 + [x := v]$$

```
(define (environ-push mem env var val)
  (define new-frame (frame env (hash var val)))
  (heap-alloc mem new-frame))
```

Example

```
E1 <- E0 + [z := 6]
E1 <- [x := 7]
```



## Constructors: Push

$$E_2 \leftarrow E_1 + [x := v]$$

```
(define (environ-push mem env var val)
  (define new-frame (frame env (hash var val)))
  (heap-alloc mem new-frame))
```

#### Example

## E1 <- E0 + [z := 6]

```
E1 < -[x := 7]
```

```
(define e1-m2 (environ-push m1 E0 (d:variable 'z) (d:number 6)))
(define E1 (eff-result e1-m2))
(define m2 (eff-state e1-m2))
(define m3 (environ-put m2 E1 (d:variable 'x) (d:number 7)))
```



# Continuing the example

#### Example

```
E0 <- [x := 3]

E0 <- [y := 5]

E1 <- E0 + [z := 6]

E1 <- [x := 7]

E2 <- E0 + [m := 1]

E2 <- [y := 2]
```



# Continuing the example

#### Example

```
E0 <- [x := 3]

E0 <- [y := 5]

E1 <- E0 + [z := 6]

E1 <- [x := 7]

E2 <- E0 + [m := 1]

E2 <- [y := 2]
```

```
(define E0 root-environ)
(define m1
(environ-put
     (environ-put root-heap E0 (d:variable 'x) (d:number 3))
     E0 (d:variable 'v) (d:number 5)))
 (define e1-m2 (environ-push m1 E0 (d:variable 'z) (d:number 6)))
 (define E1 (eff-result e1-m2))
 (define m2 (eff-state e1-m2))
 (define m3 (environ-put m2 E1 (d:variable 'x) (d:number 7)))
 (define e2-m4 (environ-push m3 E0 (d:variable 'm) (d:number 1)))
 (define E2 (eff-result e2-m4))
 (define m4 (eff-state e2-m4))
 (define m5 (environ-put m4 E2 (d:variable 'y) (d:number 2)))
                                                           Boston
```

# Selector: Variable lookup

# E(x)

```
(define (environ-get mem env var)
  (define frm (heap-get mem env))    ;; Load the current frame
  (define parent (frame-parent frm))    ;; Load the parent
  (define result (frame-get frm var)) ;; Lookup locally
  (cond
    [result result] ;; Result is defined, then return it
    [parent (environ-get mem parent var)] ; If parent exists, recurse
    [else (error (format "Variable ~a is not defined" var))]))
```

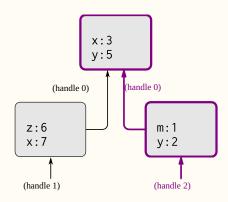
#### Example

```
(check-equal? (environ-get m5 E2 (d:variable 'y)) (d:number 2))
(check-equal? (environ-get m5 E2 (d:variable 'm)) (d:number 1))
(check-equal? (environ-get m5 E2 (d:variable 'x)) (d:number 3)))
```



## A language of environments

#### Environment visualization



**Figure 3.1:** A simple environment structure. Source: SICP book Section 3.2

```
(define parsed-m5
   (parse-mem
    '([E0 . ([x . 3] [y . 5])]
       [E1 . (E0 [x . 7] [z . 6])]
       [E2 . (E0 [m . 1] [y . 2])]))
; Which is the same as creating the following data-structure
(heap
  (hash
    (handle 0)
    (frame #f
      (hash (d:variable 'y) (d:number 5) (d:variable 'x) (d:number 3))
    (handle 2)
    (frame (handle 0)
      (hash (d:variable 'y) (d:number 2) (d:variable 'm) (d:number 1))
    (handle 1)
    (frame (handle 0)
      (hash (d:variable 'z) (d:number 6) (d:variable 'x) (d:number 7))
(check-equal? parsed-m5 m5)
```

$$\frac{\blacktriangleright_{H_1} \ e \Downarrow_E v \quad \blacktriangleright_{H_2} \quad E \leftarrow [x := v] \blacktriangleright_{H_3}}{\blacktriangleright_{H_1} \ (\text{define} \ x \ e) \Downarrow_E \text{void} \blacktriangleright_{H_3}}$$

$$\frac{\blacktriangleright_{H_1} t_1 \Downarrow_E v_1 \blacktriangleright_{H_2} t_2 \Downarrow_E v_2 \blacktriangleright_{H_3}}{\blacktriangleright_{H_1} t_1; t_2 \Downarrow_E v_2 \blacktriangleright_{H_3}}$$

$$\blacktriangleright_H v \Downarrow_E v \blacktriangleright_H$$

$$\blacktriangleright_H x \Downarrow_E E(x) \blacktriangleright_H$$

$$\blacktriangleright_H \lambda x.t \Downarrow_E \{E, \lambda x.t\} \blacktriangleright_H$$

## Tips

- Make sure (d:eval-term) handles expressions by calling (d:eval-exp)
- Make sure the case for d:define? returns the value (d:void) not (void), not d:void, not void
- Make sure the case for d:apply? invokes (d:eval-term) when handling  $t_b$



## Exercise

```
;; e1 \( \mathref{E} \) v1

;; E' <- E + \( [x := v1] \)

;; e2 \( \mathref{E}' \) v2
```



## Exercise

```
;; e1 ↓E v1
(define v1+mem1 (d:eval-exp mem env e1))
(define mem1 (eff-state v1+mem1))
(define v1 (eff-result v1+mem1))
:: E' < - E + [x := v1]
(define env2+mem2 (environ-push mem1 env y v1)
(define env2 (eff-result env2+mem2))
(define mem2 (eff-state env2+mem2))
;; e2 #E' v2
(define v2+mem3 (d:eval-exp mem2 env2 e2))
(define mem3 (eff-state v2+mem3))
(define v2 (eff-result v2+mem3))
```



## Exercise

```
;; e1 ↓E v1
(define v1+mem1 (d:eval-exp mem env e1))
(define mem1 (eff-state v1+mem1))
(define v1 (eff-result v1+mem1))
;; E' \leftarrow E + [x := v1]
(define env2+mem2 (environ-push mem1 env y v1)
(define mem2 (eff-state env2+mem2))
(define env2 (eff-result env2+mem2))
;; e2 #E' v2
(define v2+mem3 (d:eval-exp mem2 env2 e2))
(define mem3 (eff-state v2+mem3))
(define v2 (eff-result v2+mem3))
```



# Tips

In the rules for value, variable, define, and closure. For instance,

$$\blacktriangleright_H v \Downarrow_E v \blacktriangleright_H$$

Given a memory H and an expression is v, the code being returned should be:

```
(eff H v)
```

In short, adapt your solution of HW5/ex3 for value, variable, and lambda, by **wrapping the return value in an eff**.

