

Constrained Types for Object-Oriented Languages

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Syntax. The syntax for the language is specified as follows. We assume a fixed constraint system, C , with inference relation \vdash_C . However, we require all constraint systems to support conjunction and existential quantification.

(Class)	L	$::=$	$\text{class } T \text{ extends } T \{ \bar{T} \bar{f}; K \bar{M} \}$
(Ctor)	K	$::=$	$T(\bar{T} \bar{x}) \{ \text{super}(\bar{x}); \bar{f} = \bar{x} \}$
(Method)	M	$::=$	$T m(\bar{T} \bar{x}) \{ \text{return } e; \}$
(Expr)	e	$::=$	$x \mid e.f \mid e.m(\bar{e}) \mid \text{new } C(\bar{e}) \mid (T)e$
(C Terms)	t	$::=$	$x \mid \text{self} \mid t.f$
(Constraint)	c, d	$::=$	$a \mid t = t \mid c, c \mid T x; c$
(Type)	S, T, U	$::=$	$C(: d)$

Subtyping Judgements. We let Γ stand for multisets of type assertions, of the form $T x$, and constraints. We define $\sigma(\Gamma)$ to be the set of constraints obtained from Γ by replacing each type assertion $C(: d) x$ with $d[x/\text{self}]$.

$$\frac{\Gamma \vdash T \sqsubseteq T \quad \text{class } C(: c) \text{ extends } D(: d) \{ \dots \}}{\vdash C(: c) \sqsubseteq D(: d)}$$

$$\frac{\Gamma \vdash C \sqsubseteq D \quad \sigma(\Gamma), c \vdash_C d}{\Gamma \vdash C(: c) \sqsubseteq D(: d)} \quad \frac{\Gamma \vdash S \sqsubseteq T \quad \Gamma \vdash T \sqsubseteq U}{\Gamma \vdash S \sqsubseteq U}$$

Type Judgements.

$$\frac{\Gamma, T x \vdash T x \quad \Gamma \vdash C(: c) x \quad \sigma(\Gamma) \vdash_C d[x/\text{self}]}{\Gamma \vdash C(: c, d) x} \text{ (CONSTR)}$$

$$\frac{\Gamma \vdash T_0 e \quad \text{fields}(T_0) = \bar{U}(: \bar{d}) \bar{f}}{\Gamma \vdash \bar{U}_i(: T_0 \text{ this}; \text{this}.f = \text{self}.d_i) e.f_i} \text{ (T-Field)}$$

$$\frac{\Gamma \vdash S e \quad \Gamma \vdash S \sqsubseteq T}{\Gamma \vdash T(T)e} \text{ (T-UCast)} \quad \frac{\Gamma \vdash S e \quad \Gamma \vdash T \sqsubseteq S}{\Gamma \vdash T(T)e} \text{ (T-DCast)}$$

$$\frac{\Gamma \vdash S e \quad \Gamma \not\vdash T \sqsubseteq S \quad \Gamma \not\vdash S \sqsubseteq T}{\Gamma \vdash T(T)e} \text{ (T-SCast)}$$

$$\frac{\Gamma \vdash T_{0:n} e_{0:n} \quad T_0 \triangleright S(: d) m(Z_{1:n} z_{1:n}) \quad \Gamma, T_0 \text{ this}, T_{1:i-1} z_{1:i-1} \vdash T_i \sqsubseteq Z_i \quad (i \in 1:n)}{\Gamma \vdash S(: T_0 \text{ this}; T_{1:n} z_{1:n}; d) e_{0:n} m(e_{1:n})} \text{ (T-INVK)}$$

$$\frac{\Gamma \vdash T_{1:n} e_{1:n} \quad C \triangleright C(: d) (Z_{1:n} f_{1:n}) \quad \Gamma, T_{1:(i-1)} f_{1:(i-1)} \vdash T_i \sqsubseteq Z_i \quad (i \in 1:n) \quad \Gamma, T_{1:n} f_{1:n} \vdash d}{\Gamma \vdash C(: T_{1:n} f_{1:n}; \text{self}.f_{1:n} = f_{1:n}, d) \text{ new } C(e_{1:n})} \text{ (T-NEW)}$$

Method and Class Typing.

$$\frac{\bar{T} \bar{x}, C \text{ this} \vdash S e \quad \bar{T} \bar{x}, C \text{ this} \vdash S \sqsubseteq T}{T m(\bar{T} \bar{x}) \{ \text{return } e; \} \text{ OK in } C} \quad \frac{K = C(\bar{S} \bar{g}, \bar{T} \bar{f}) \{ \text{super}(\bar{g}); \text{this}.\bar{f} = \bar{f}; \} \quad D \triangleright \bar{S} \bar{g} \quad \bar{M} \text{ OK in } C}{\text{class } C \text{ extends } D \{ \bar{T} \bar{f}; K \bar{M} \} \text{ OK}}$$

Table 1. Constrained FJ

THEOREM 0.1 (Subject Reduction). *If $\Gamma \vdash T e$ and $e \longrightarrow e'$ then for some type S , $\Gamma \vdash S e'$ and $\Gamma \vdash S \sqsubseteq T$.*

Let the normal form of expressions be given by *values*, i.e. expressions

$$\text{(Values)} \quad v ::= \text{new } C(\bar{v})$$

THEOREM 0.2 (Type Soundness). *If $\vdash T e$ and $e \longrightarrow^* e' \not\rightarrow$ then e' is either (1) a value with $\vdash S v$ and $\vdash S \sqsubseteq T$, for some type S , or, (2) an expression containing a subexpression $(T) \text{new } C(\bar{v})$ where $\not\vdash C \sqsubseteq T[\text{new } C(\bar{v})/\text{self}]$.*

Computation:

$$\frac{fields(C) = \bar{C} \bar{f}}{(\text{new } C(\bar{e})).f_i \longrightarrow e_i} \text{ (R-FIELD)}$$

$$\frac{mbody(m, C) = \bar{x}.\bar{e}_0}{(\text{new } C(\bar{e})).m(\bar{d}) \longrightarrow [\bar{d}/\bar{x}, \text{new } C(\bar{e})/\text{this}]e_0} \text{ (R-INVK)}$$

$$\frac{\vdash C \sqsubseteq D[\text{new } C(\bar{d})/\text{self}]}{(D)(\text{new } C(\bar{d})) \longrightarrow \text{new } C(\bar{d})} \text{ (R-CAST)}$$

Congruence:

$$\frac{e_0 \longrightarrow e'_0}{e_0.f \longrightarrow e'_0.f} \text{ (RC-FIELD)}$$

$$\frac{e_0 \longrightarrow e'_0}{e.m(\bar{e}) \longrightarrow e'_0.m(\bar{e})} \text{ (RC-INVK-RECV)}$$

$$\frac{e_i \longrightarrow e'_i}{e.m(\dots, e_i, \dots) \longrightarrow e_0.m(\dots, e'_i, \dots)} \text{ (RC-INVK-ARG)}$$

$$\frac{e_i \longrightarrow e'_i}{\text{new } C(\dots, e_i, \dots) \longrightarrow \text{new } C(\dots, e'_i, \dots)} \text{ (RC-NEW-ARG)}$$

$$\frac{e_0 \longrightarrow e'_0}{(C)e_0 \longrightarrow (C)e'_0} \text{ (RC-CAST)}$$

Table 2. Reduction rules for Constrained FJ