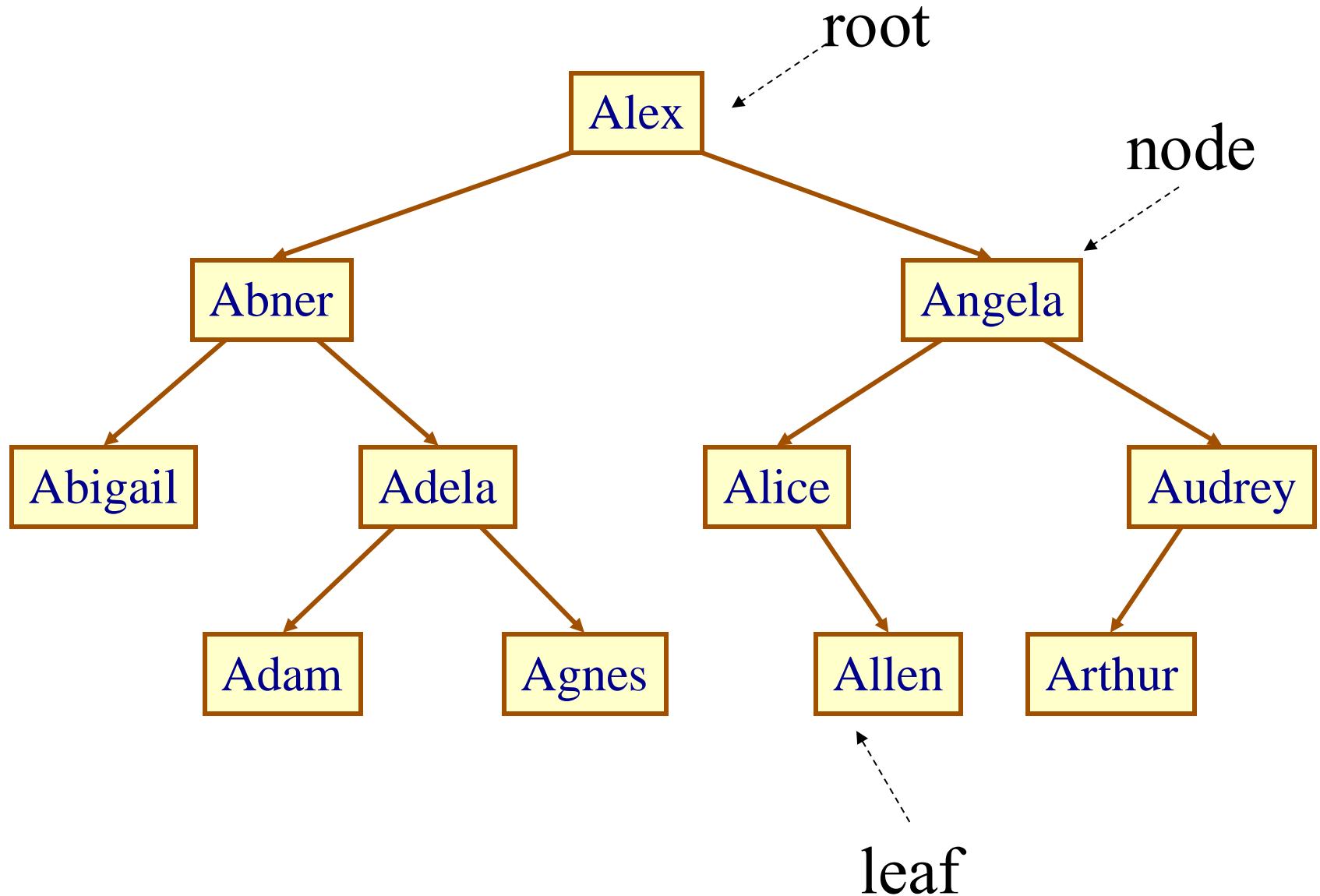


CS 261: Data Structures

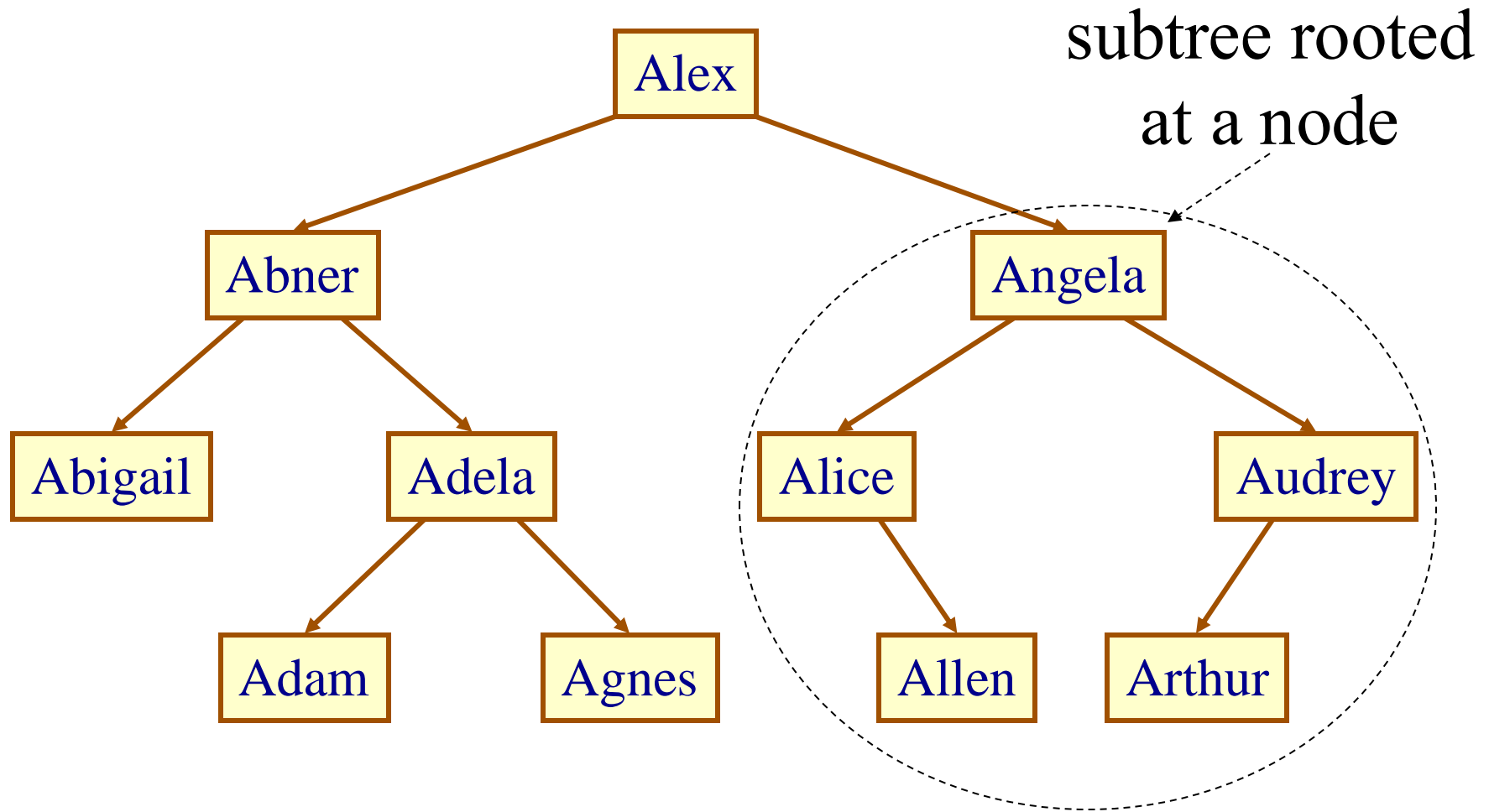
Binary Tree Traversals

Binary Search Trees

Binary Trees



Binary Trees



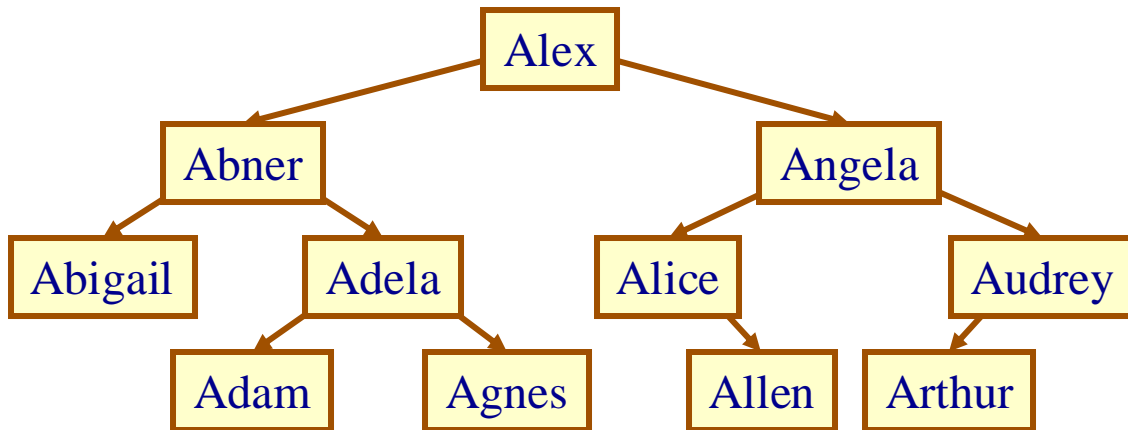
Node Structure Type

```
struct Node {  
    TYPE val;  
    struct Node *left;    /* Left child */  
    struct Node *right;   /* Right child */  
};
```

Like the **Link** structure in a linked list

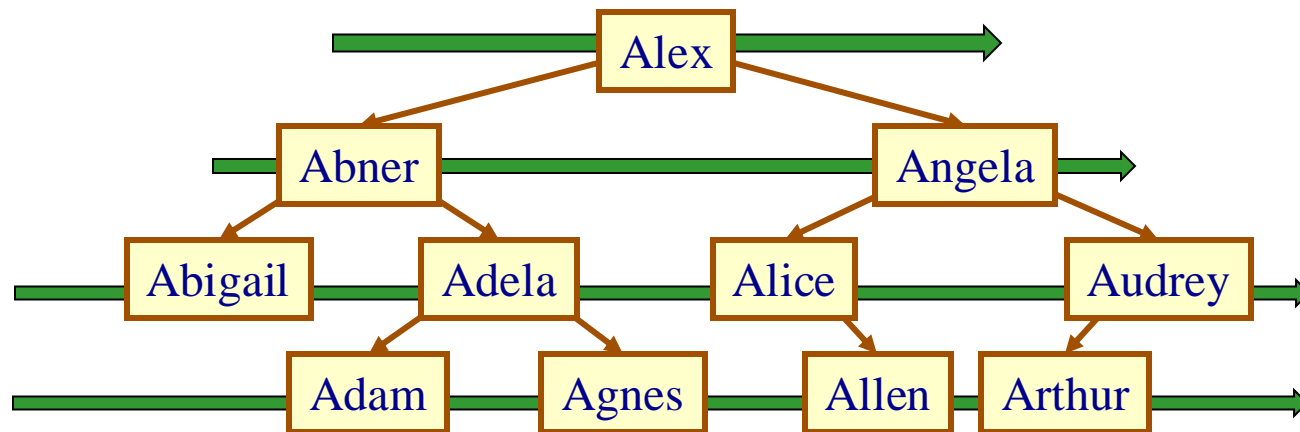
Tree Traversals

- How to access nodes in a tree?
- What order do we visit nodes in a tree?
 - Example:



Tree Traversals: Breadth-First

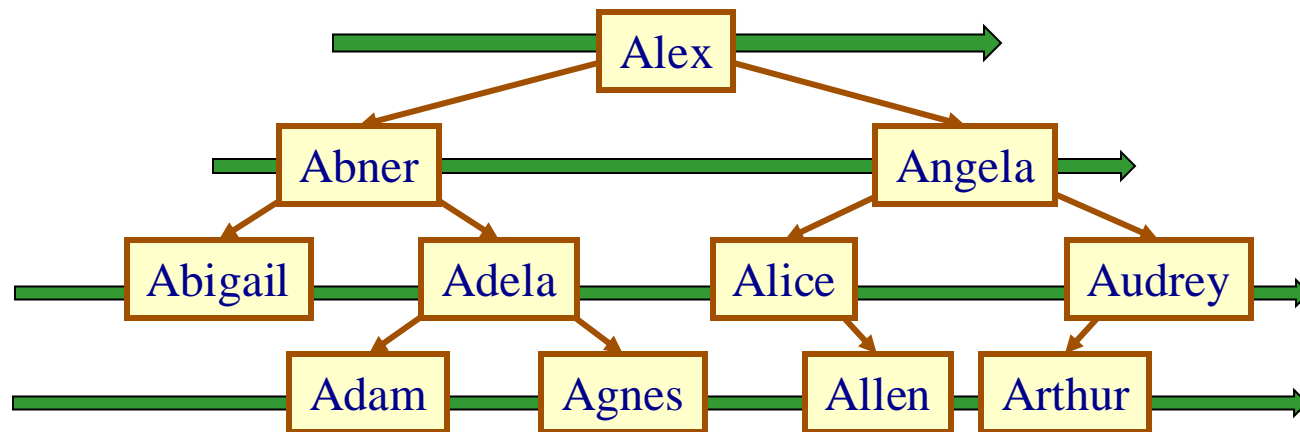
- Level-order or breadth-first traversals
 - **top-down**, or bottom-up
 - **left-to-right**, or right-to-left



Output: {Alex, Abner, Angela, Abigail, Adela, Alice, Audrey, Adam, Agnes, Allen, Arthur}

Tree Traversals: Breadth-First

- Level-order or breadth-first traversals
 - top-down, or **bottom-up**
 - **left-to-right**, or right-to-left



Output: {Adam, Agnes, Allen, Arthur, Abigail, Adela, Alice, Audrey, Abner, Angela, Alex}

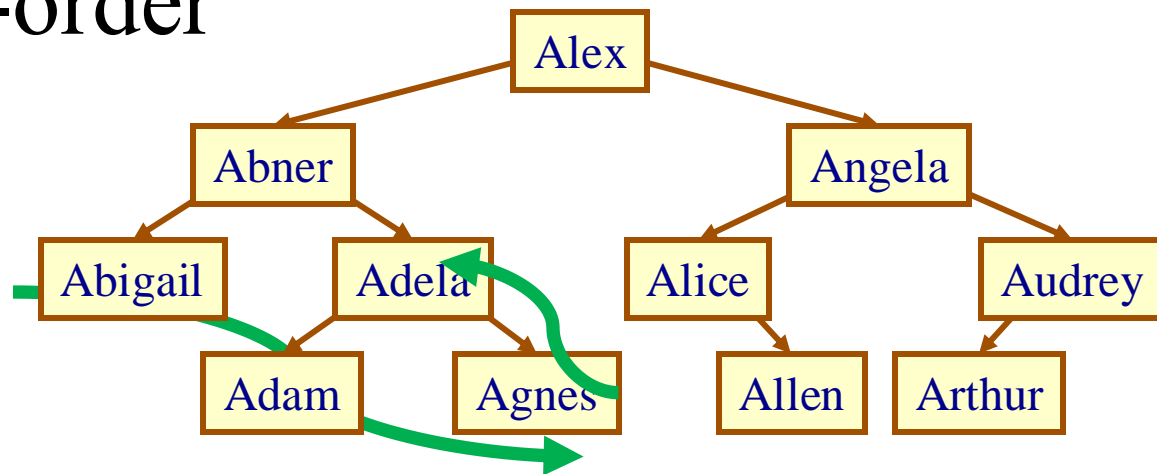
Tree Traversals: Depth-First

- Depth-first traversals:

- pre-order

- post-order**

- in-order



Output: {Abigail, Adam, Agnes, Adela, Abner, Allen, Alice, Arthur, Audrey, Angela, Alex}

Tree Traversals

- Recursive algorithms
- Iterative algorithms

You need to know how to implement both types of traversals in C.

Recursive Functions: Important Checks

1. Must have a **stopping criterion**.
2. The recursive call uses a **different input**.

```
TYPE recursive_f(input1) {  
    if( stop ) {  
        process_stop;  
    }  
    else {  
        process(input1);  
        recursive_f(input2);  
    }  
    return some_result;  
}
```

Depth-First Traversals

1. Node, left, right → Pre-order
2. Left, node, right → In-order
3. Left, right, node → Post-order

Pre-Order Traversal

Processing order: Node \rightarrow Left \rightarrow Right

```
void preorder(struct Node *node) {  
    if (node != NULL) {  
        process (node->val) ;  
        preorder (node->left) ;  
        preorder (node->right) ;  
    }  
}
```

Check correctness!

Pre-Order Traversal

Processing order: Node \rightarrow Left \rightarrow Right

```
void preorder(struct Node *node) {  
    if (node != NULL) {  
        process (node->val) ;  
        preorder (node->left) ;  
        preorder (node->right) ;  
    }  
}
```

Stopping criterion



different input

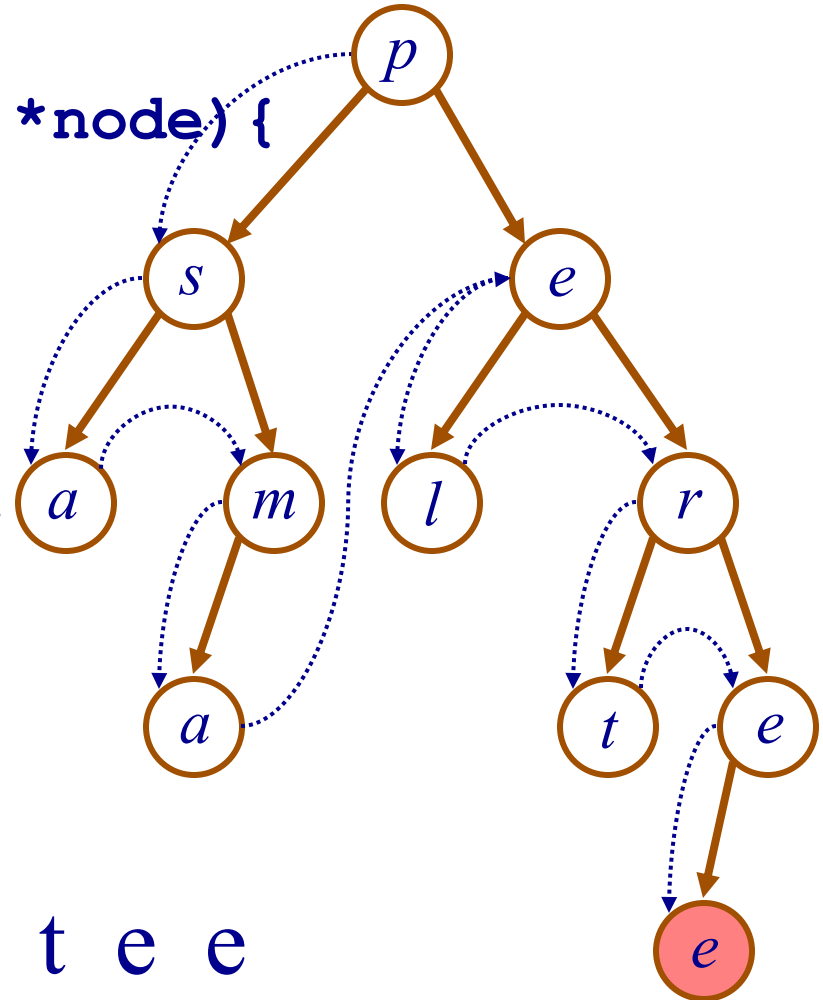


Pre-Order Traversal

Processing order: Node \rightarrow Left \rightarrow Right

```
void preorder(struct Node *node) {  
    if (node != NULL) {  
        process (node->val);  
        preorder (node->left);  
        preorder (node->right);  
    }  
}
```

COMPLEXITY?

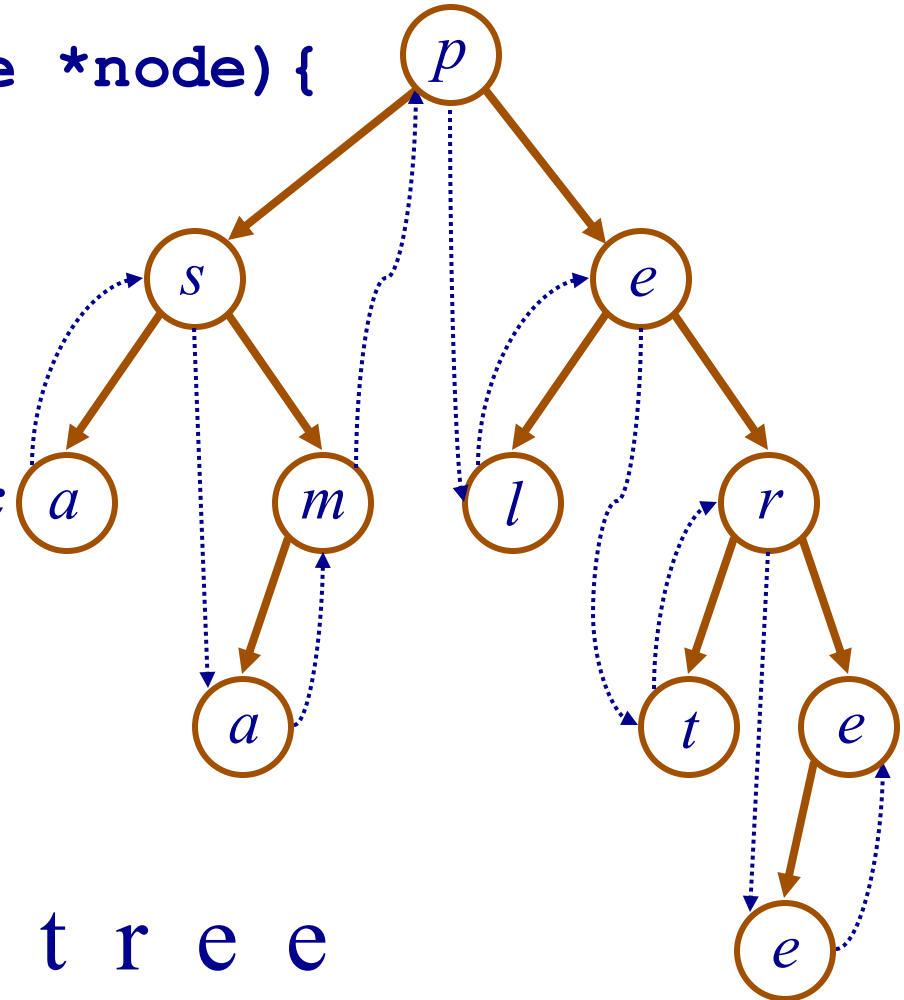


Result: p s a m a e l r t e e

In-Order Traversal

Processing order: Left \rightarrow Node \rightarrow Right

```
void inorder(struct Node *node) {  
    if (node != NULL) {  
        inorder(node->left);  
        process(node->val);  
        inorder(node->right);  
    }  
}
```



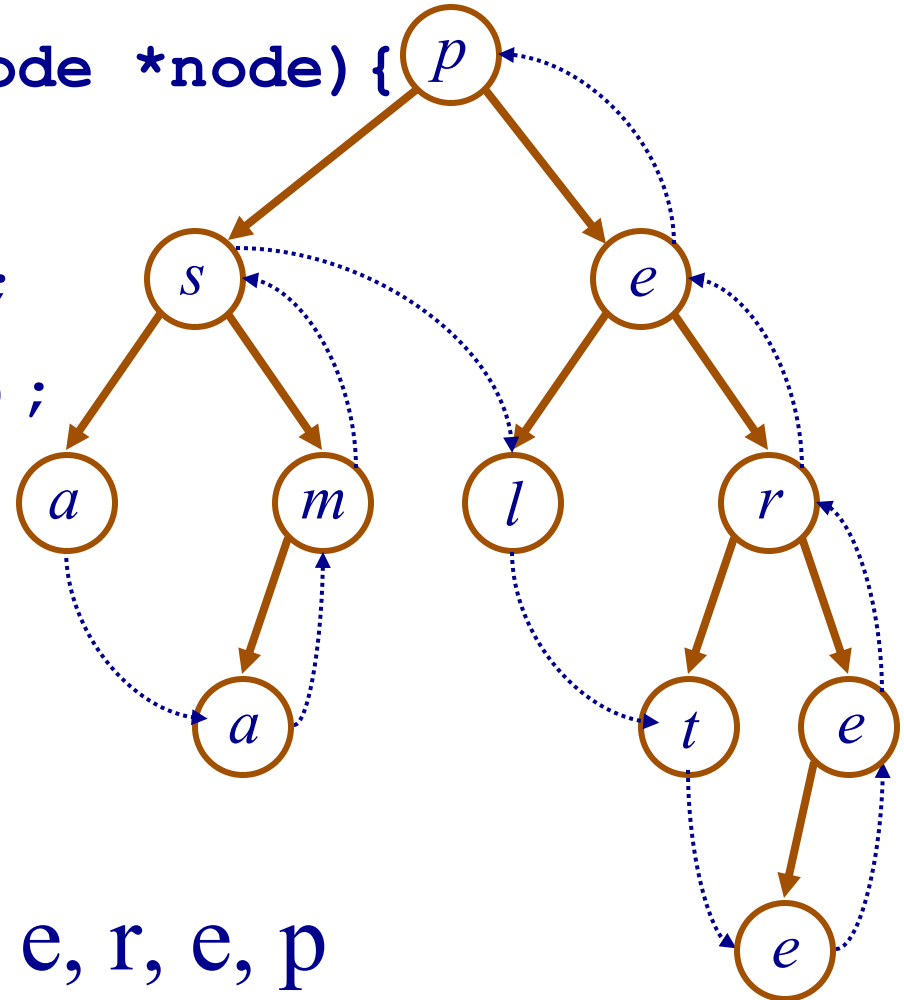
COMPLEXITY?

Result: a s a m p l e t r e e

Post-Order Traversal

Processing order: Left \rightarrow Right \rightarrow Node

```
void postorder(struct Node *node) {  
    if (node != NULL) {  
        postorder(node->left);  
        postorder(node->right);  
        process(node);  
    }  
}
```



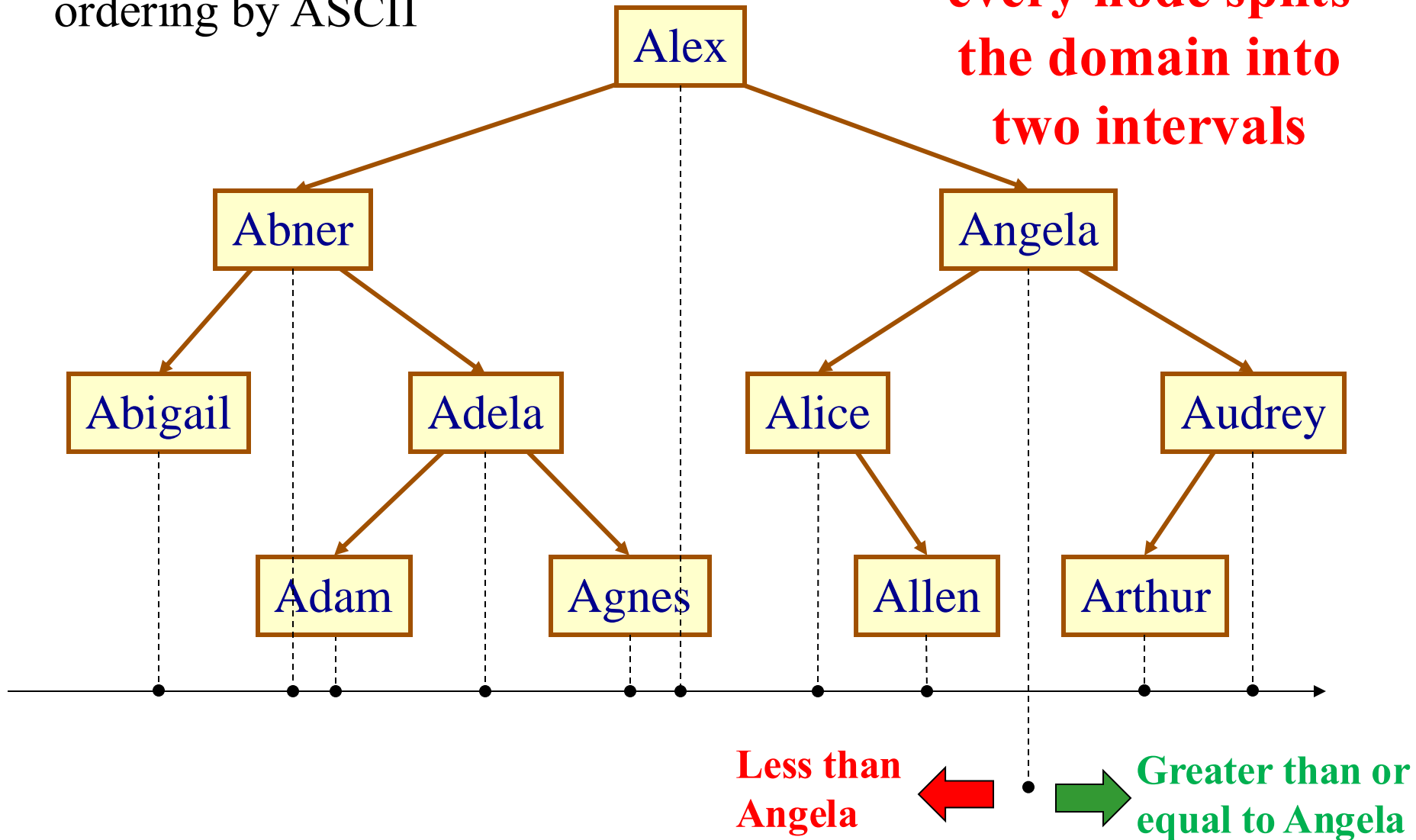
COMPLEXITY?

Result: a, a, m, s, l, t, e, e, r, e, p

Binary Search Tree: Example

ordering by ASCII

**every node splits
the domain into
two intervals**



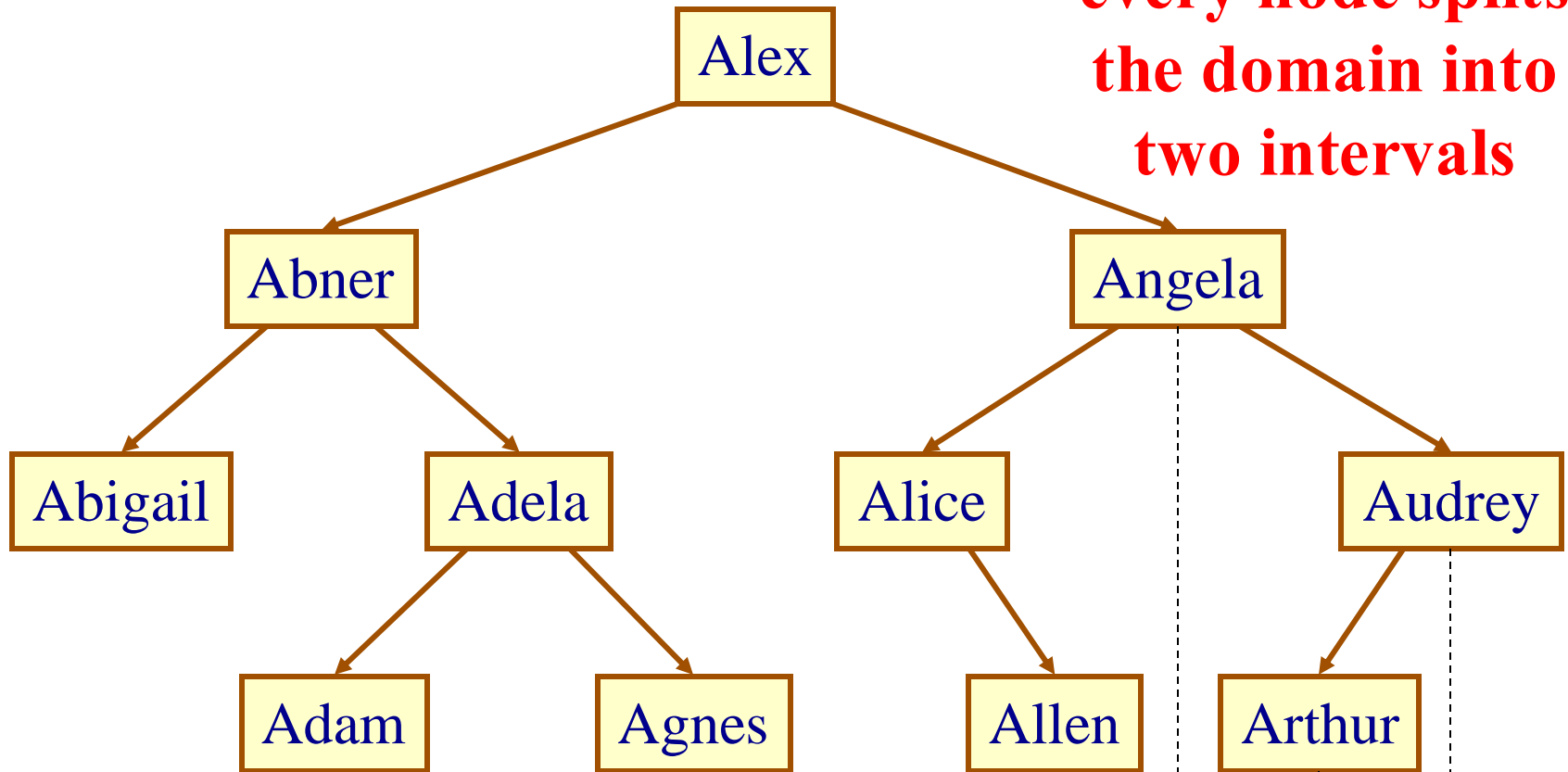
Binary Search Tree (BST)

A binary tree where every node value is:

- **Greater than** all of its **left** descendants
- **Less than or equal to** all of its **right** descendants

Binary Search Tree: Example

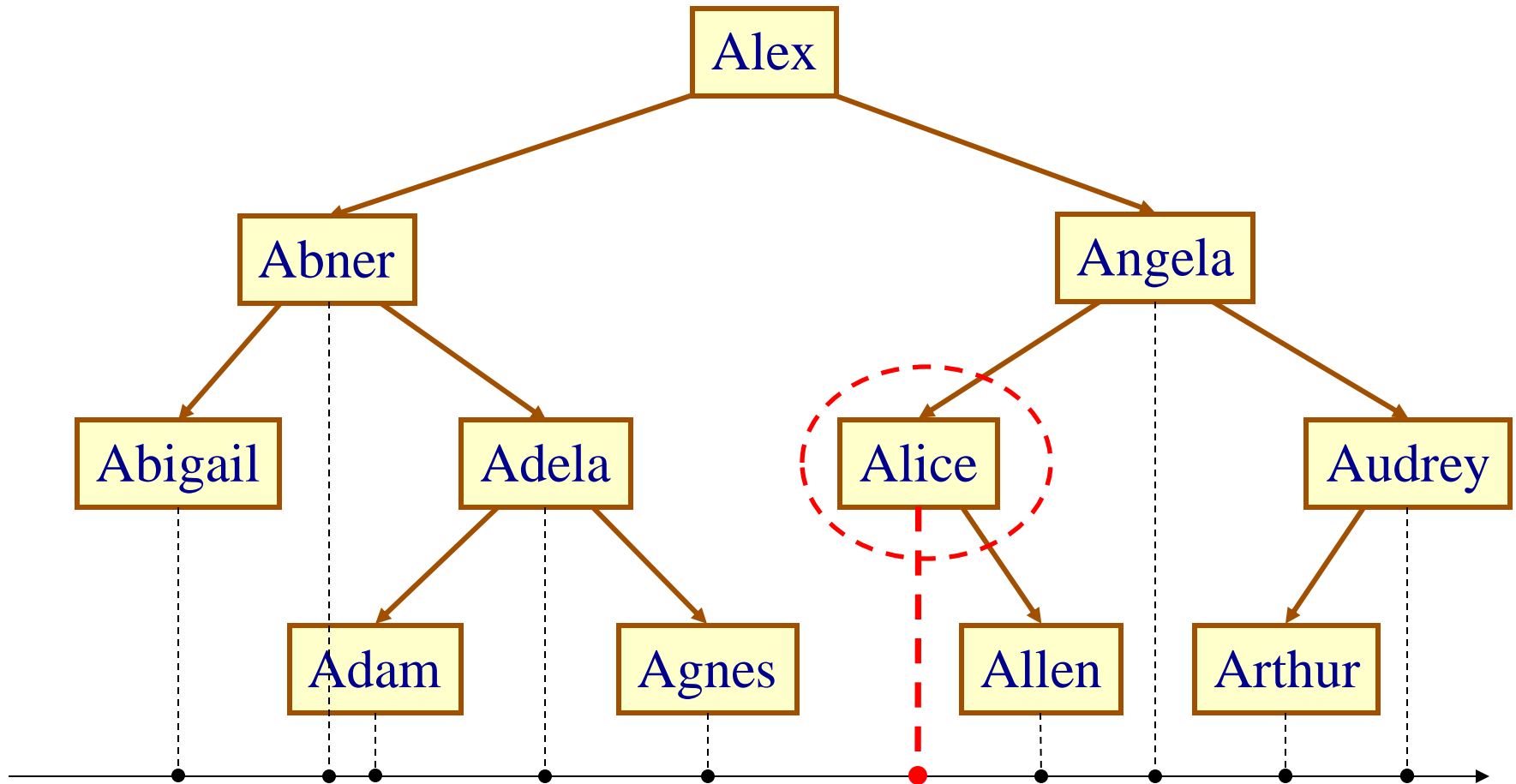
every node splits
the domain into
two intervals



Where is Author relative
to Audrey on the axis?

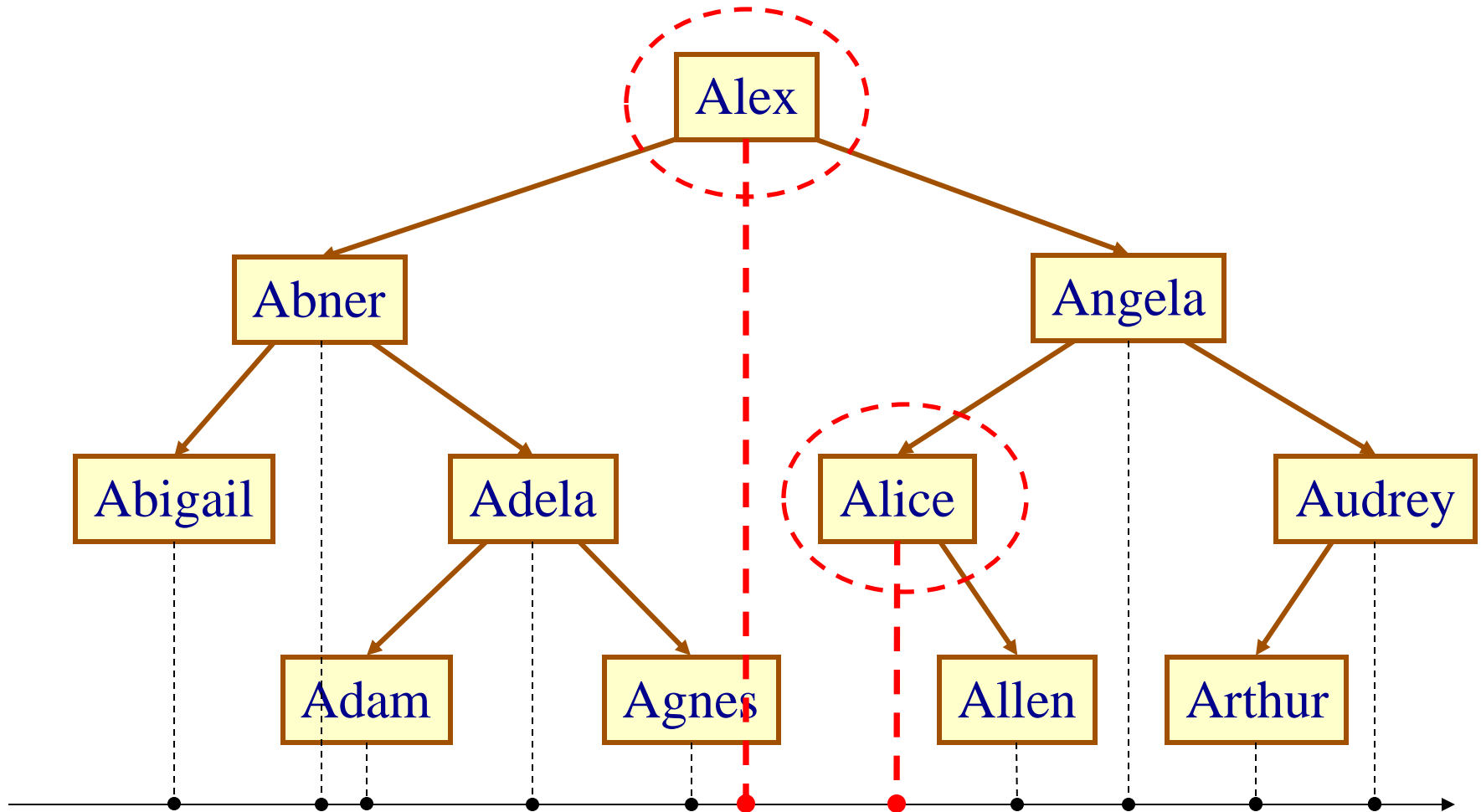
Angela < Arthur < Audrey

Binary Search Tree: Example



What is the leftmost descendant of Angela?

Binary Search Tree: Example



The leftmost descendant of my right child is my next higher node!

BST: Interface

```
void initBST(struct BST *tree);  
int  containsBST(struct BST *tree, TYPE val);  
void addBST(struct BST *tree, TYPE val);  
void removeBST(struct BST *tree, TYPE val);
```

BST Uses Two Struct Types

```
struct Node {  
    TYPE    val; /*value*/  
    struct Node *left; /*left child*/  
    struct Node *right; /*right child*/  
};
```

```
struct BST {  
    struct Node *root;  
    int size; /*number of nodes*/  
};
```

Initialize BST

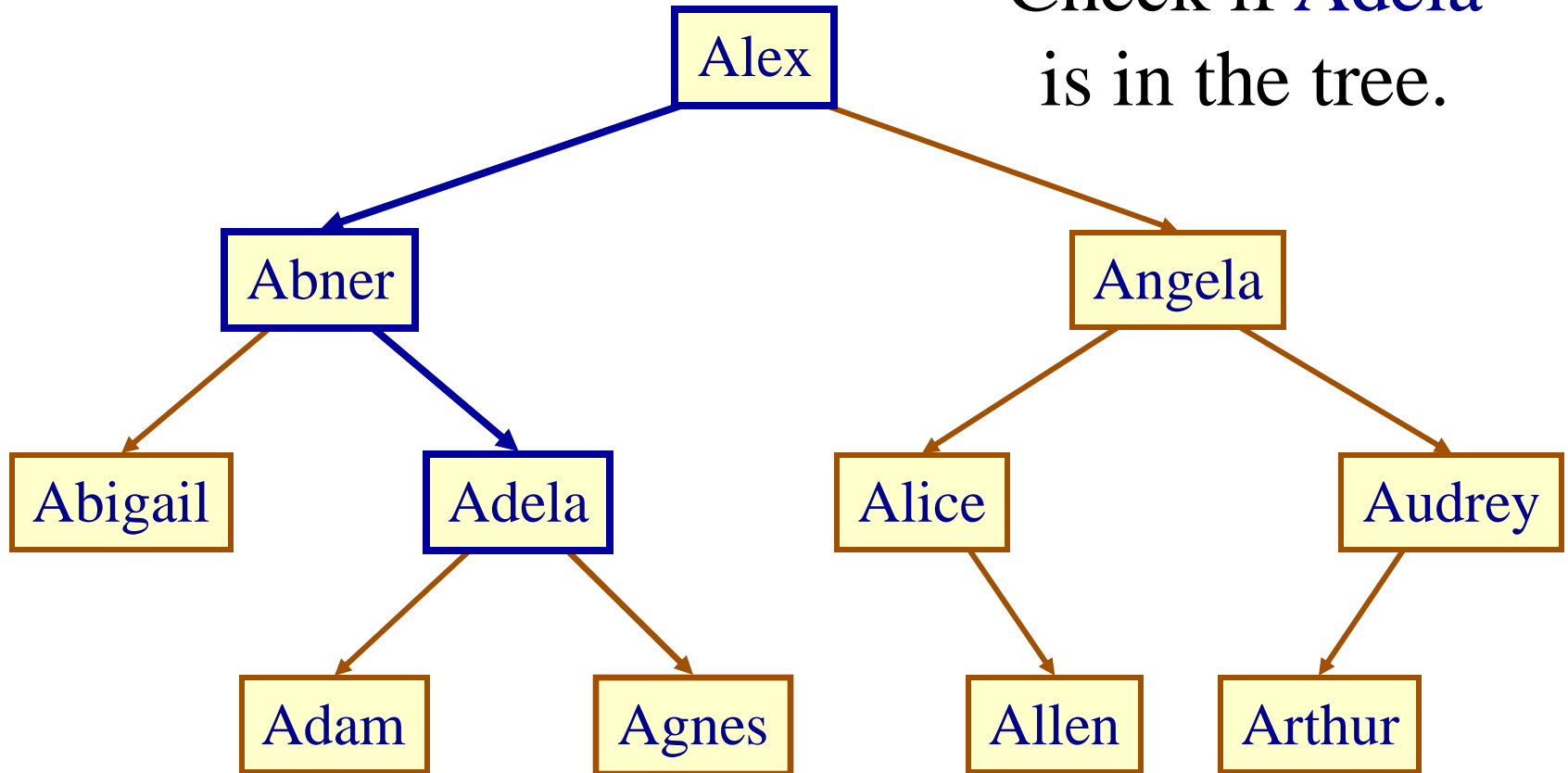
```
struct Node {  
    TYPE val;  
    struct Node *left;  
    struct Node *right;  
};
```

```
struct BST {  
    struct Node *root;  
    int size;  
};
```

```
void initBST(struct BST *tree) {  
    assert(tree);  
  
    /*initially, the tree is empty */  
    tree->root = NULL; /* important */  
    tree->size = 0;  
  
}
```


Contains BST

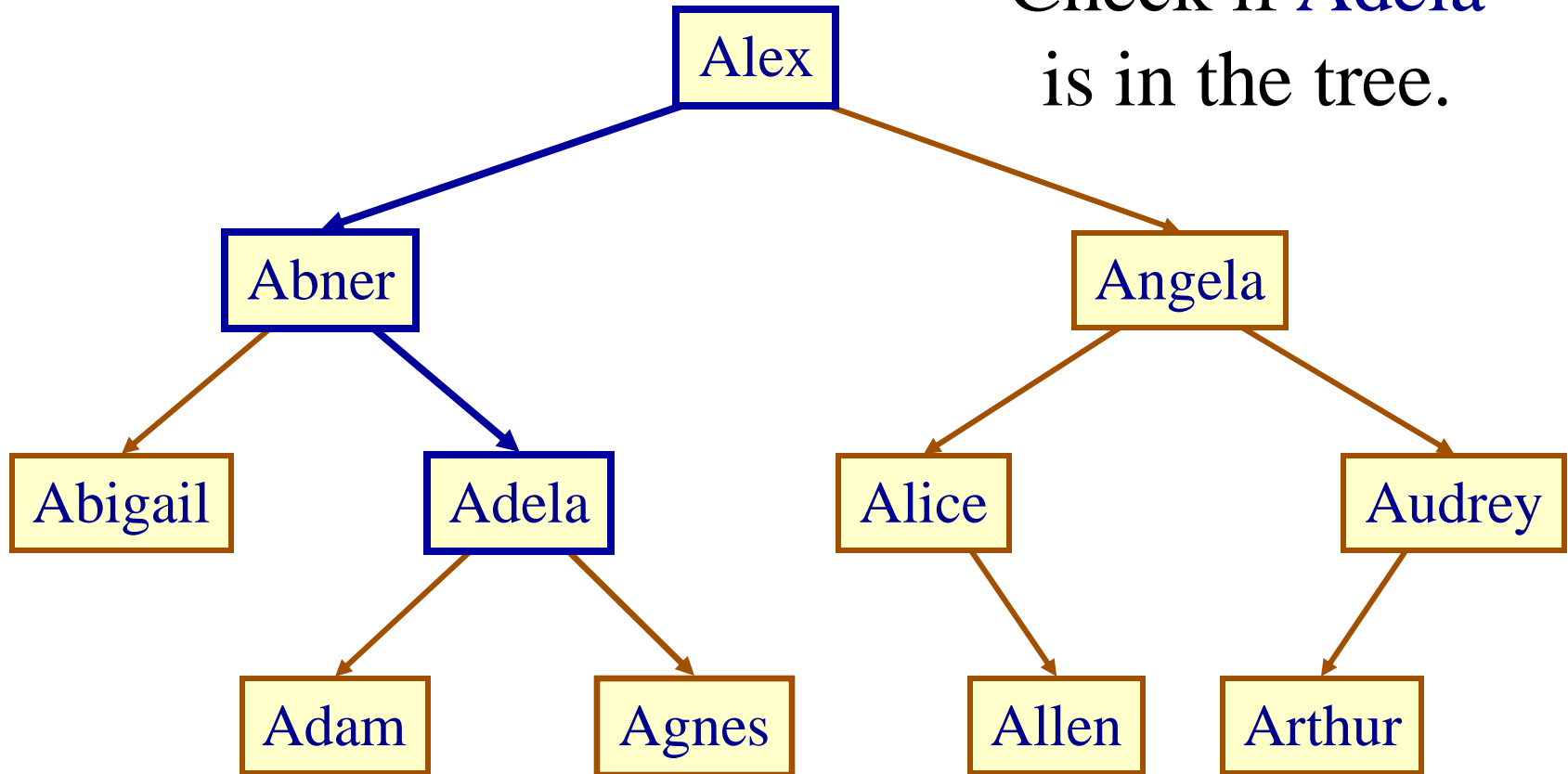
Check if **Adela** is in the tree.



We will leverage the BST property to efficiently traverse the tree to the node containing **Adela**.

Contains BST

Check if **Adela** is in the tree.



If BST is balanced, complexity of **containsBST** is proportional to the tree height $O(\log n)$

Contains BST

```
struct BST {
    struct Node *root;
    int size;
};
```

```
/* returns 1 or 0 */
```

```
int containsBST(struct BST *tree, TYPE val){
    assert(tree);
```

}


Contains BST

```
struct BST {  
    struct Node *root;  
    int size;  
};
```

```
/* returns 1 or 0 */  
int containsBST(struct BST *tree, TYPE val) {  
    assert(tree);  
    if (tree->root)  
        return containsNode(tree->root, val);  
    else  
        return 0; /* tree is empty */  
}
```

Keep in mind, we will always need a helper function for a recursive tree traversal.

```
int containsNode(struct Node *node, TYPE val) {  
    /*Ensure the stopping criterion exists*/  
    if(!node) return 0;  
}
```



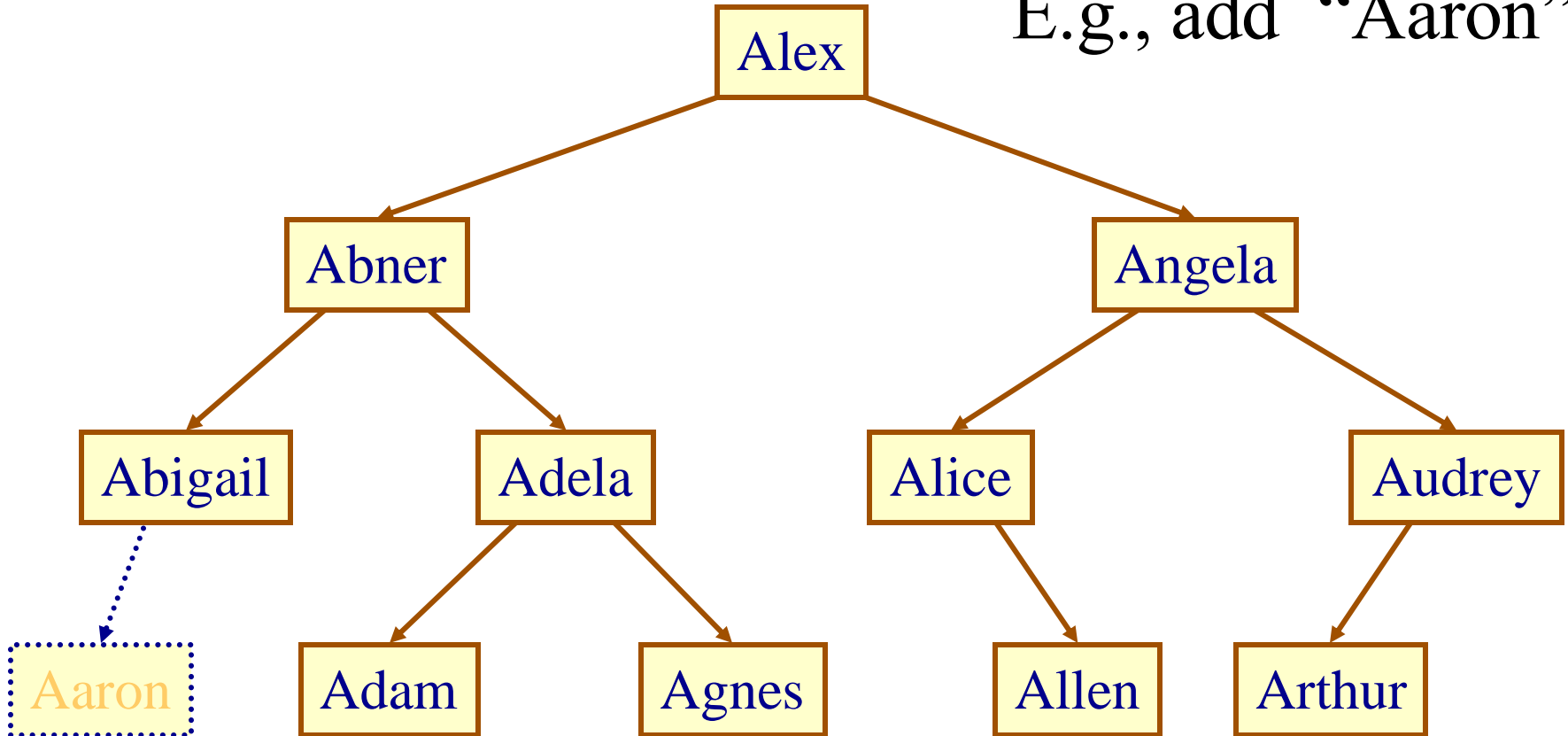
In our top-down traversal, we reached beyond the leaf node, so we couldn't find val in the tree.

```
int containsNode(struct Node *node, TYPE val) {  
    /*Ensure the stopping criterion exists*/  
    if(!node) return 0;  
    if( EQ(val, node->val) )  
        return 1; /* found it */  
    else  
        /* Recursive calls of containsNode() */  
  
}
```

```
int containsNode(struct Node *node, TYPE val) {  
    /*Ensure the stopping criterion exists*/  
    if(!node) return 0;  
    if( EQ(val, node->val) )  
        return 1; /* found it */  
    else if( LT(val, node->val) )  
        /*Recursion must use different input*/  
        return containsNode(node->left, val);  
    else  
        return containsNode(node->right, val);  
}
```

Add BST

E.g., add “Aaron”

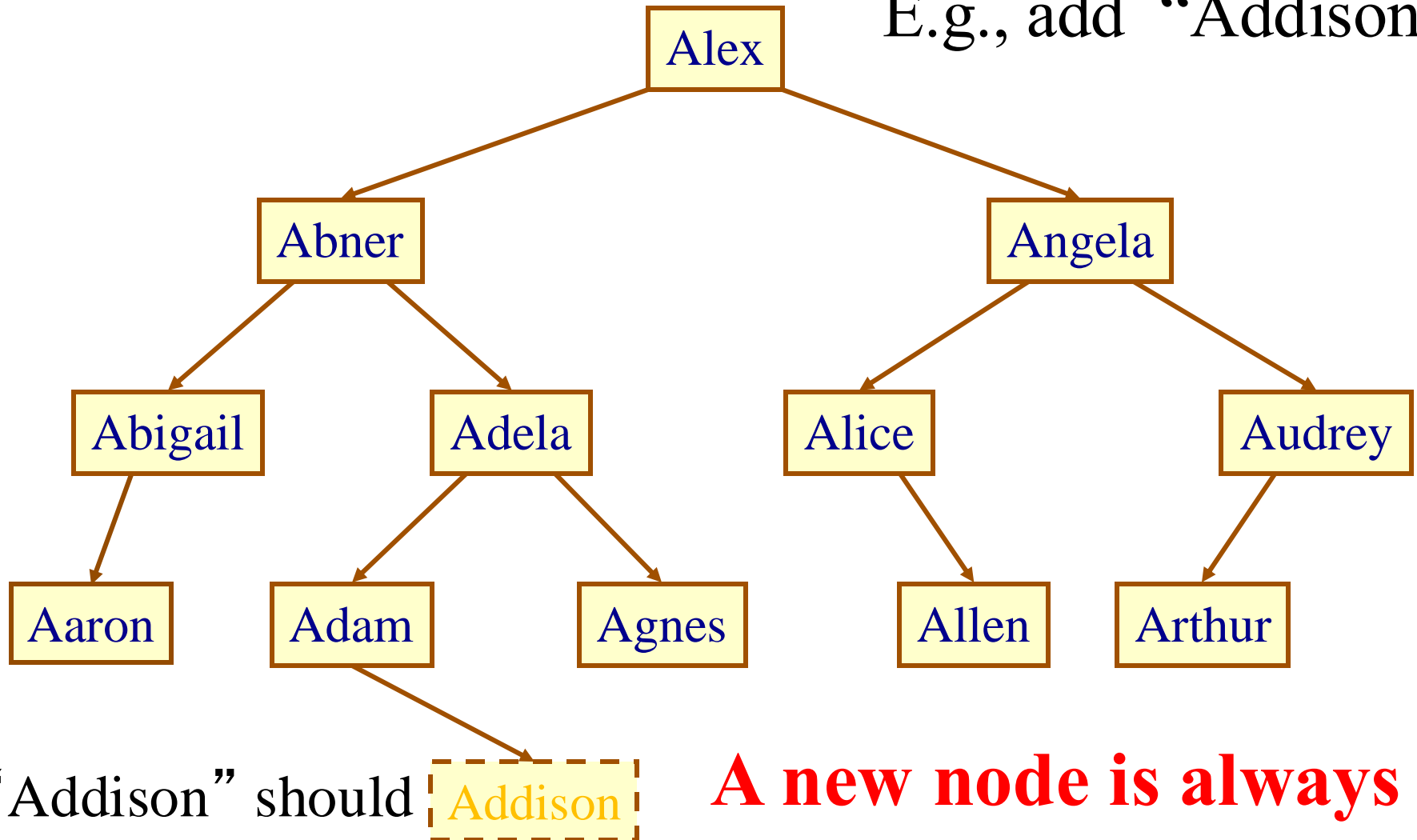


“Aaron” should
be added here

**A new node is always
inserted as a leaf !**

Add BST

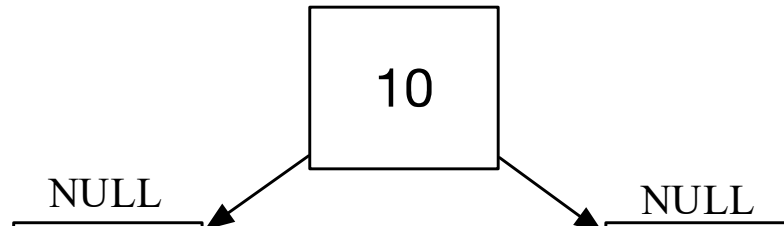
E.g., add “Addison”



A new node is always inserted as a leaf !

Example

Add the sequence:



10,

3,

11,

2,

10,

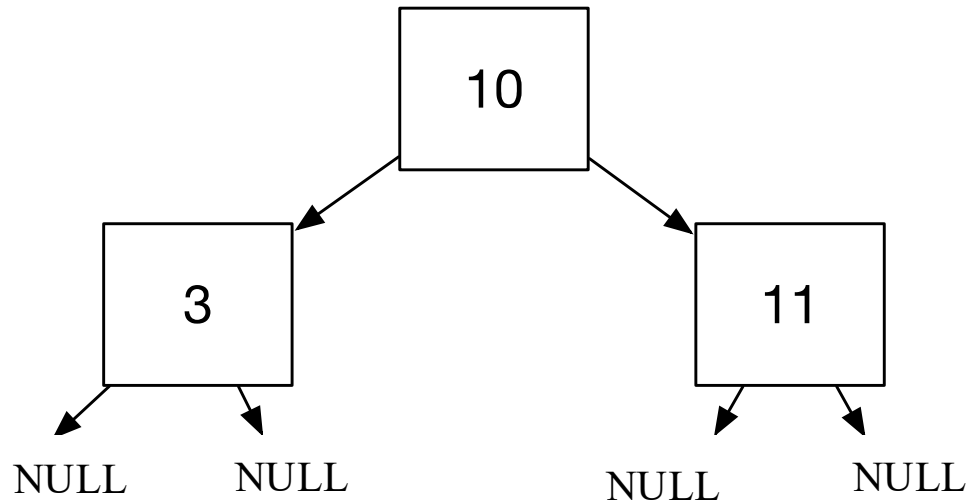
5,

6

Example

Add the sequence:

10,
3,
11,
2,
10,
5,
6



Example

Add the sequence:

10,

3,

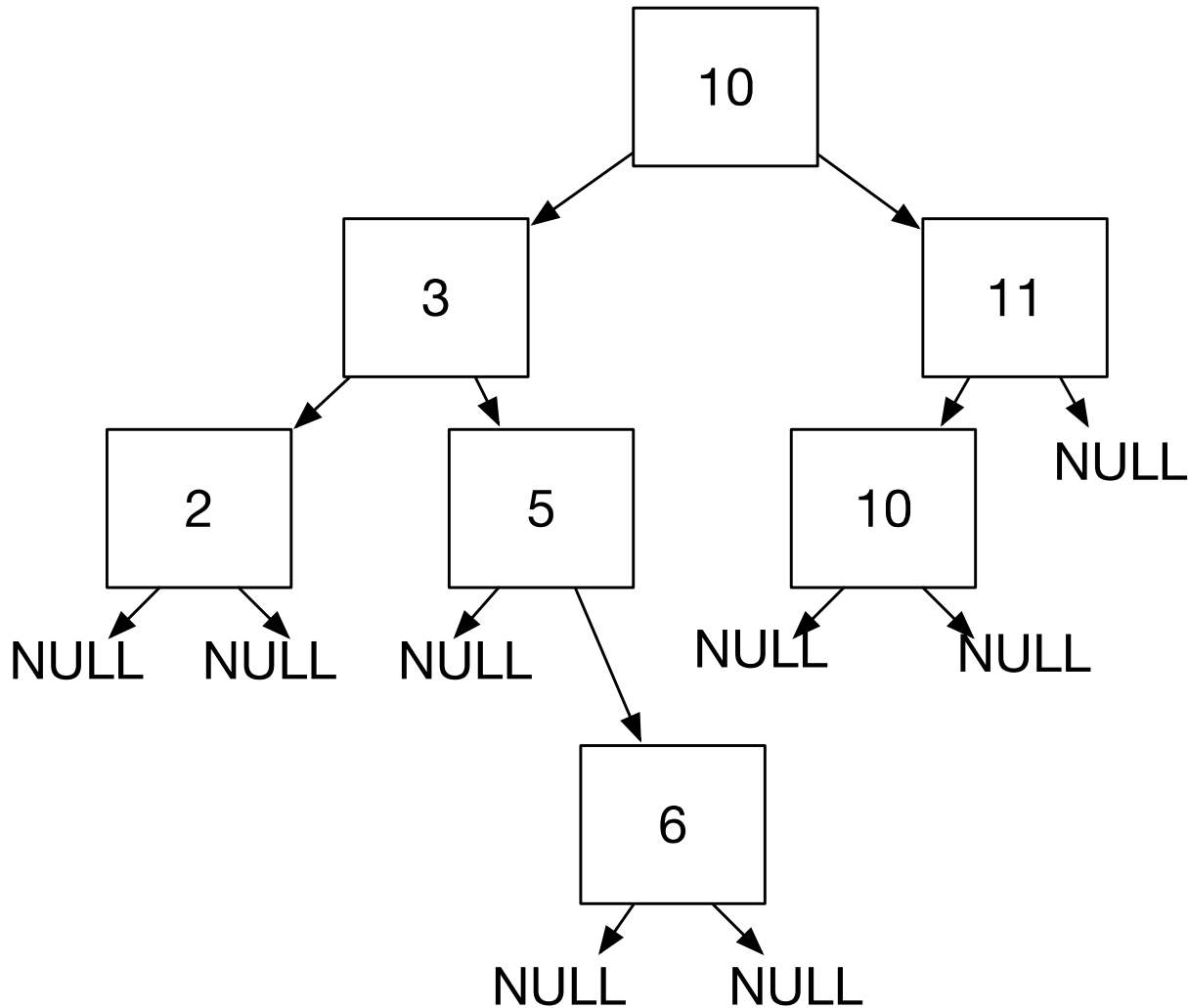
11,

2,

10,

5,

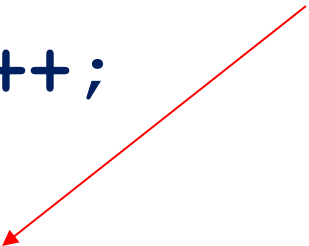
6



Add BST

```
struct BST {  
    struct Node *root;  
    int size;  
};
```

```
void addBST(struct BST *tree, TYPE val)  
{  
    assert(tree);  
    tree->root = addNode(tree->root, val);  
    tree->size++;  
}
```




Keep in mind, we will always need a helper function for a recursive tree traversal.

What is complexity of addBST? $O(??)$

```
void initBST(struct BST *tree){  
    tree->root = NULL;  
    tree->size = 0;  
}
```

```
void addBST(struct BST *tree, TYPE val)  
{  
    assert(tree);  
    tree->root = addNode(tree->root, val);  
    tree->size++;  
}
```



**The function returns a pointer to
the specified input node to
propagate the changes up the tree.**

```
#define NODE struct Node
```

```
NODE *addNode(NODE *node, TYPE val) {
```

```
...
```

```
return node;
```

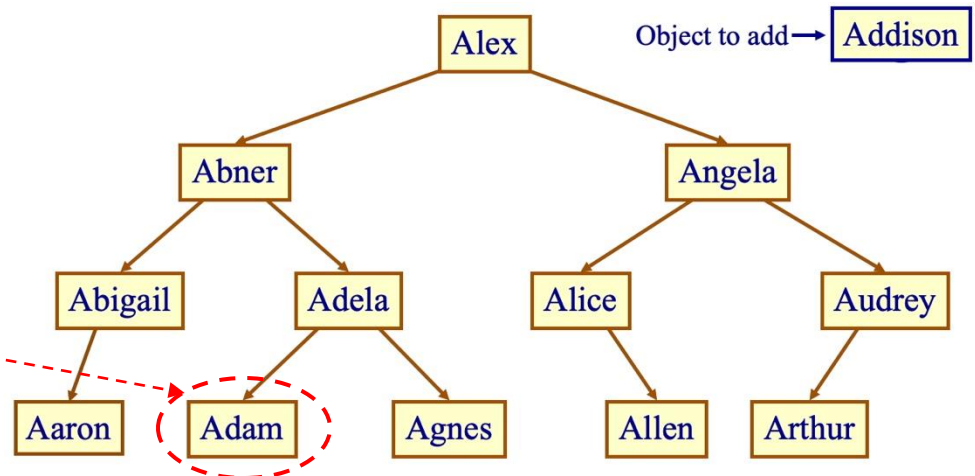
```
}
```

return the same pointer

```
#define NODE struct Node
```

```
NODE *addNode(NODE *node, TYPE val){  
    if(!node){ /* stopping criterion */  
        /*reached beyond a leaf, insert a new node*/  
    }  
    else{  
        /* recursion left or right to find  
           where we can insert val */  
    }  
    return node;  
}
```

“Addison” should
be added here




```

#define NODE struct Node

NODE *addNode(NODE *node, TYPE val){
    if(!node){ /* stopping criterion */
        /* insert a new node */
    }
    else{ /* recursion left or right */
        if (LT(val, node->val))
            node->left = addNode(node->left, val);
        else
            node->right = addNode(node->right, val);
    }
    return node;
}

```

```
#define NODE struct Node
```

```
NODE *addNode(NODE *node, TYPE val){
```

```
    if(!node){ /* stopping criterion */
```

```
        /* insert a new node */
```

```
    }
```

```
    else{/* recursion left or right */
```

```
        if (LT(val, node->val))
```

```
            node->left = addNode(node->left, val);
```



```
    else
```

```
        node->right = addNode(node->right, val);
```



```
    }
```

```
    return node;
```

```
}
```

The function returns a pointer to the specified input node to propagate the changes up the tree.

```
#define NODE struct Node

NODE *addNode(NODE *node, TYPE val){
    if(!node){ /* stopping criterion */
        /* insert a new node */
    }
    else{ /* recursion left or right */
        if (LT(val, node->val))
            node->left = addNode(node->left, val);
        else
            node->right = addNode(node->right, val);
    }
    return node;
}
```

**the recursion must
use a different input**

```

#define NODE struct Node

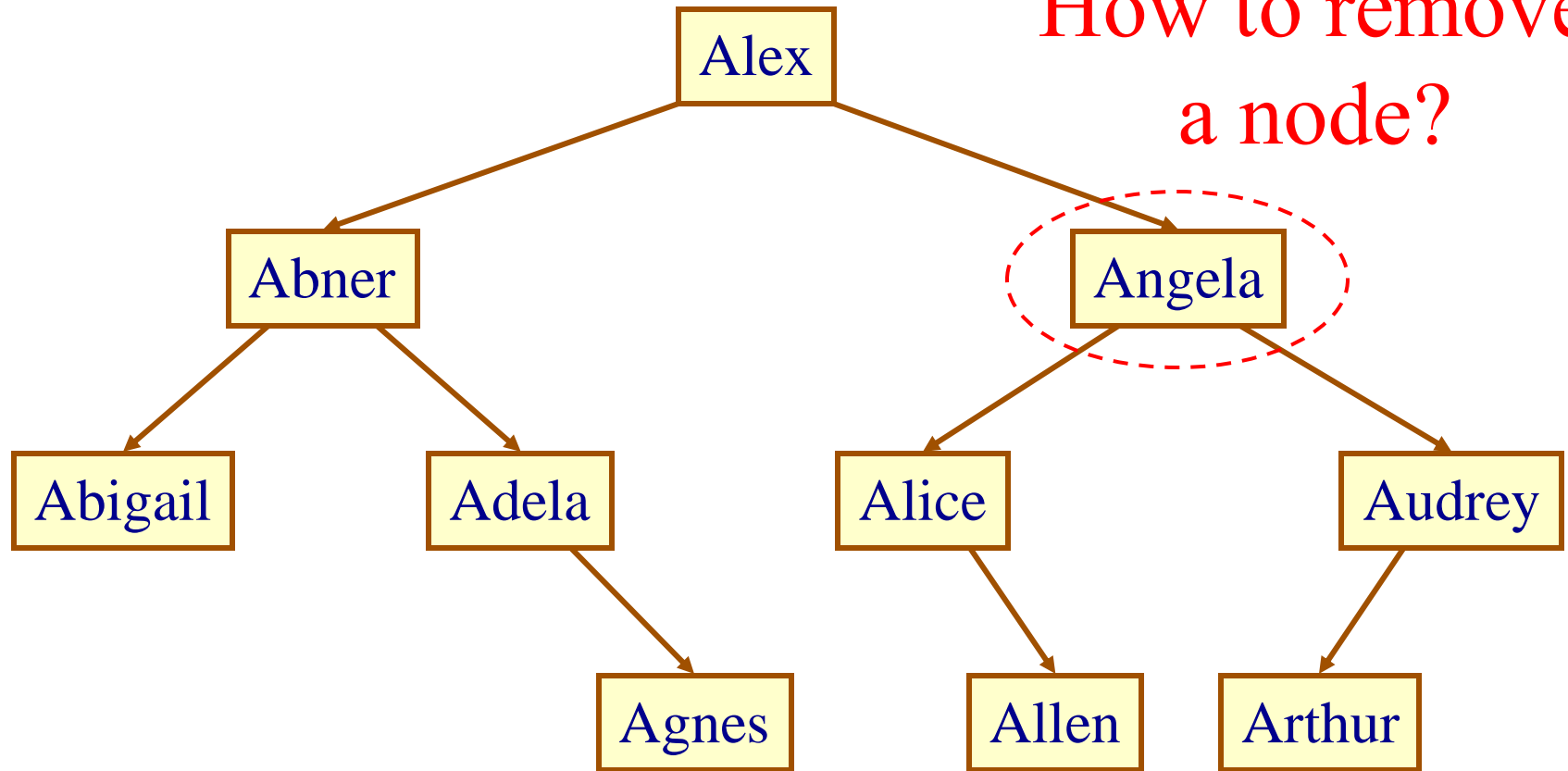
NODE *addNode(NODE *node, TYPE val){
    if(!node){ /* stopping criterion */

        NODE *new = (NODE *) malloc(sizeof(NODE)) ;
        assert(new) ;
        new->val = val;
        new->left = new->right = NULL; /*leaf*/
        return new; /*propagate the changes up*/
    }
    else{ /* recursion left or right */
        return node;
    }
}

```

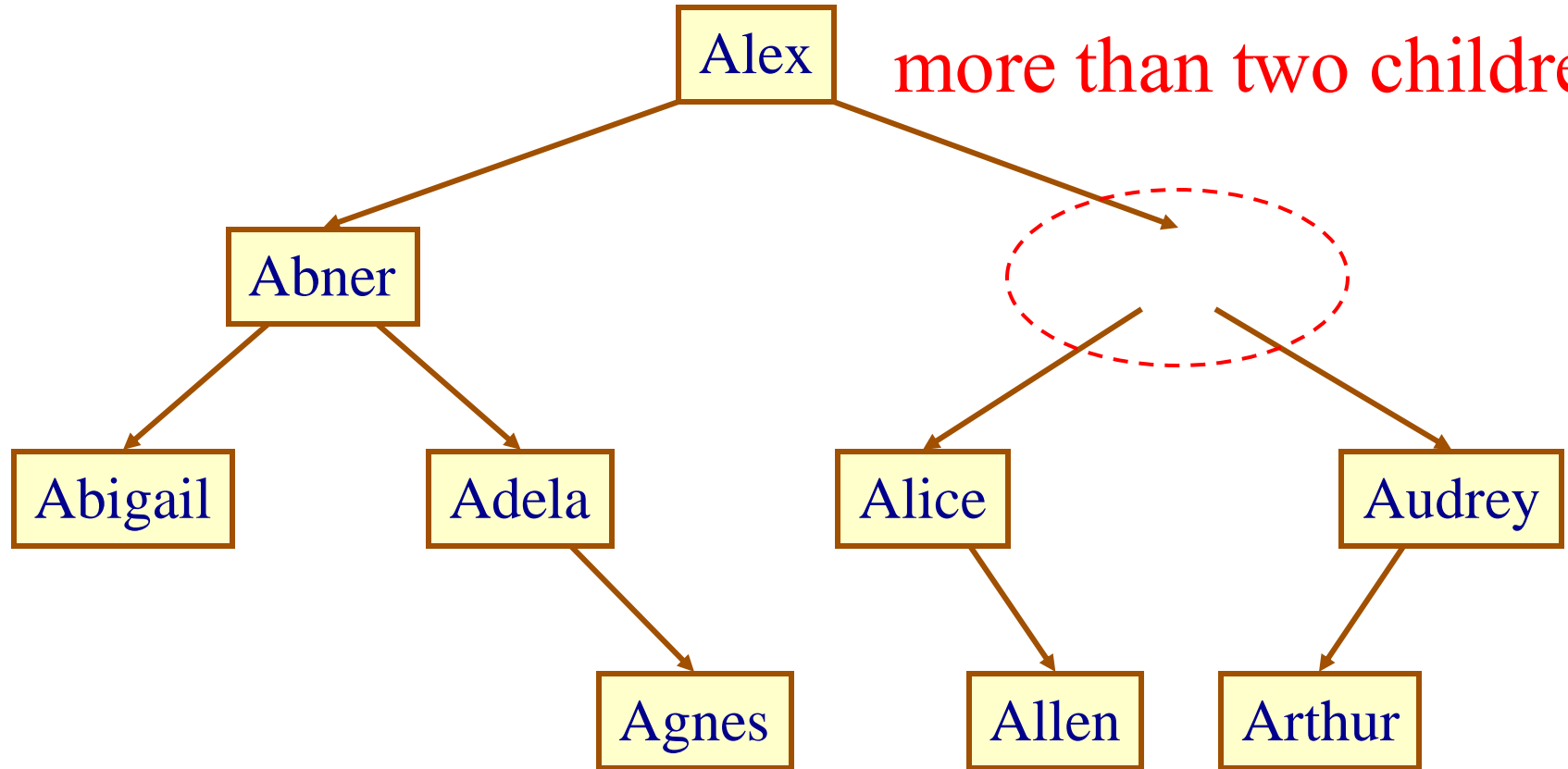
BST: Remove

How to remove
a node?

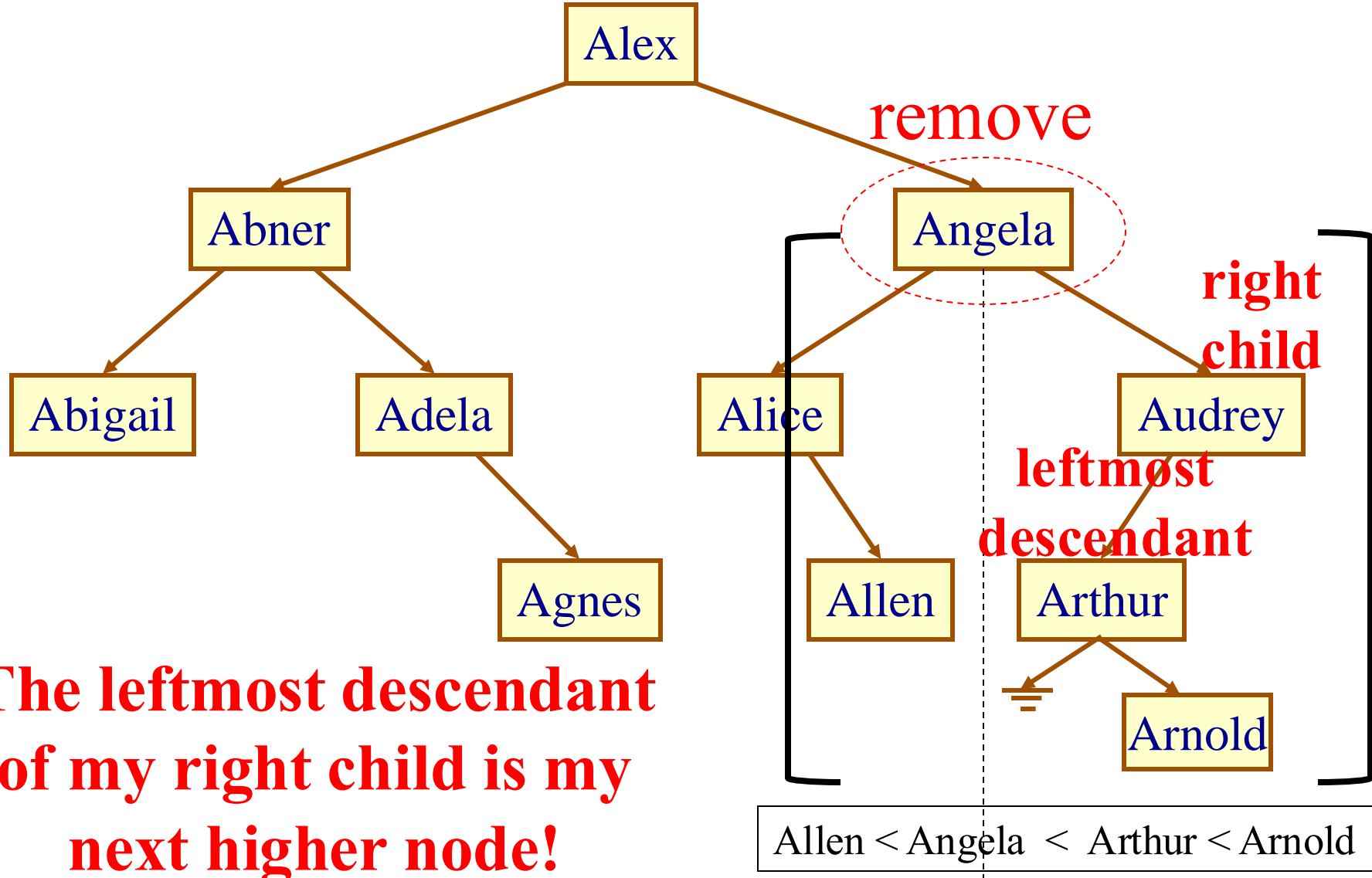


BST: Remove

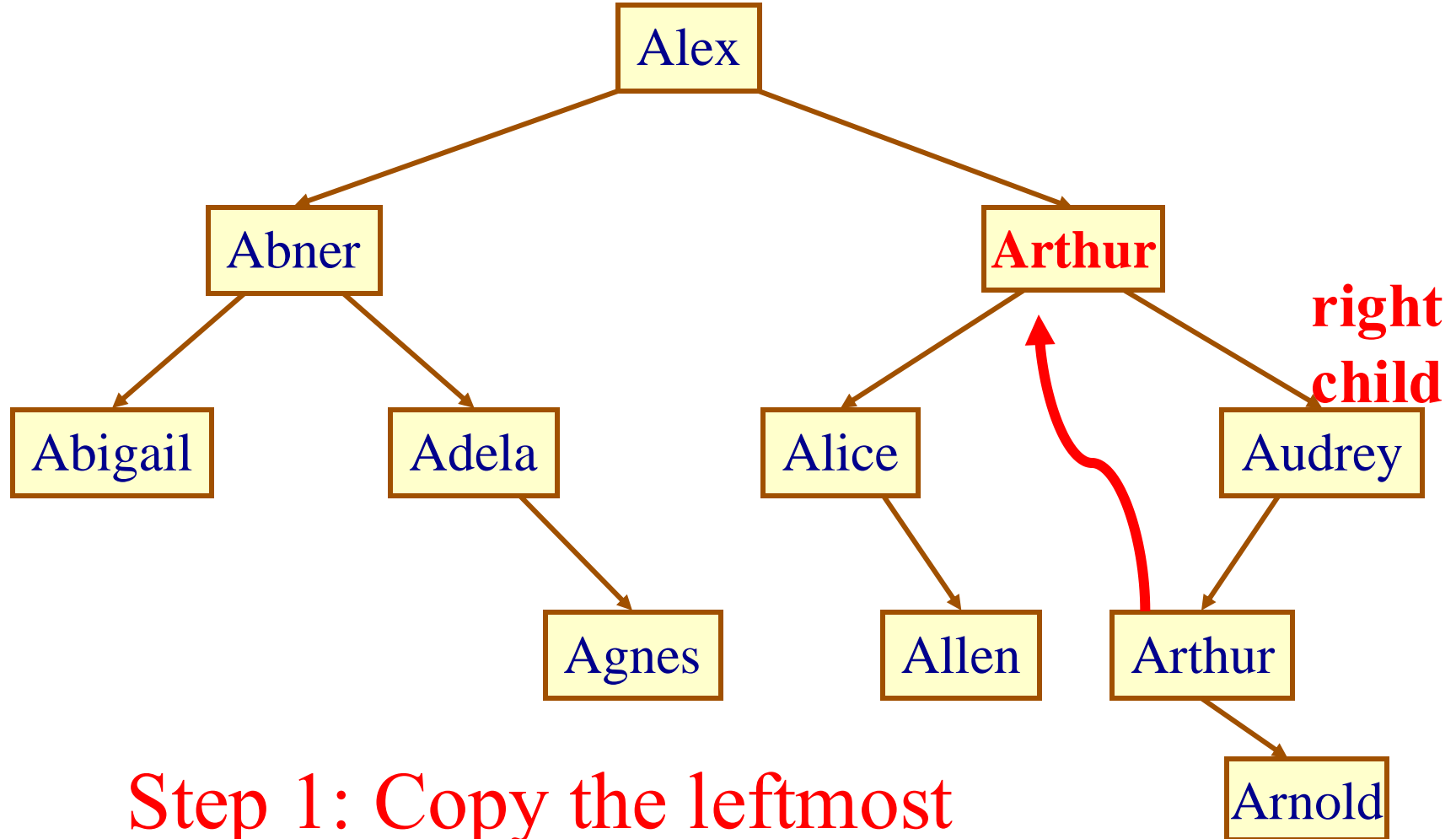
A node cannot have more than two children



Case 1: Both the right child and its leftmost descendant exist

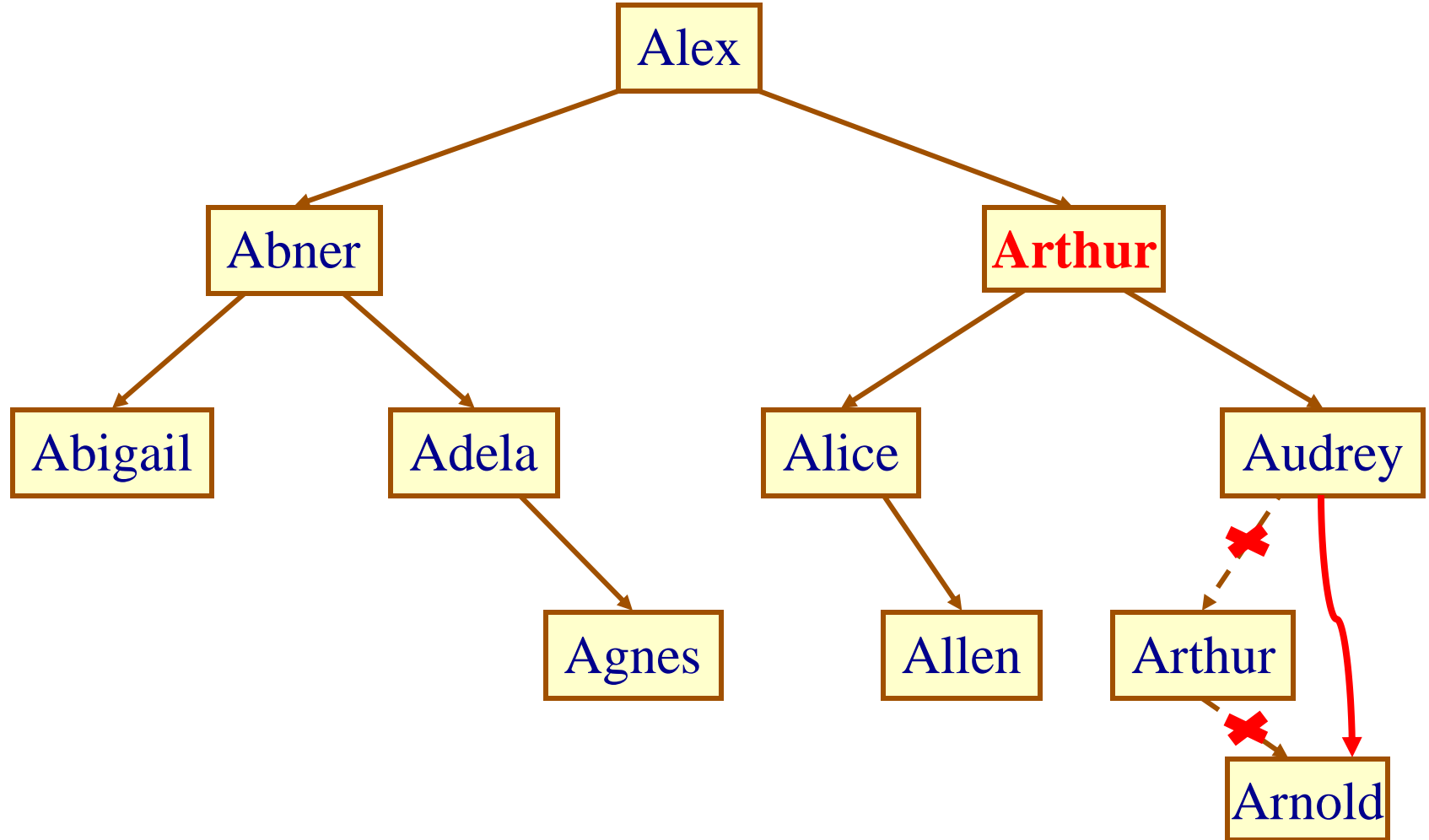


Case 1: Both the right child and its leftmost descendant exist



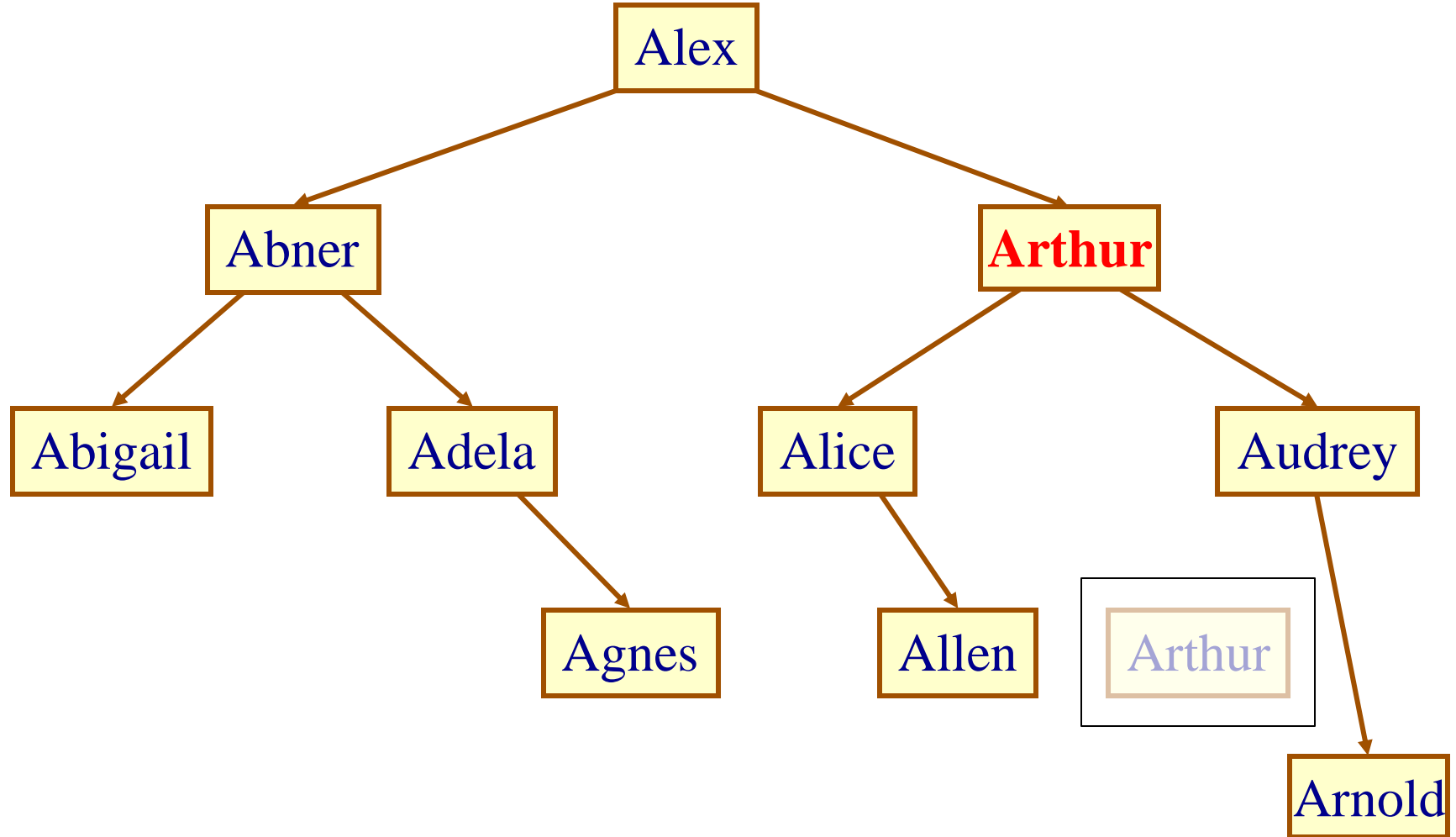
Step 1: Copy the leftmost descendant of the right child

Case 1: Both the right child and its leftmost descendant exist



Step 2: Disconnect the leftmost descendant

Case 1: Both the right child and its leftmost descendant exist



Step 3: Free the leftmost descendant

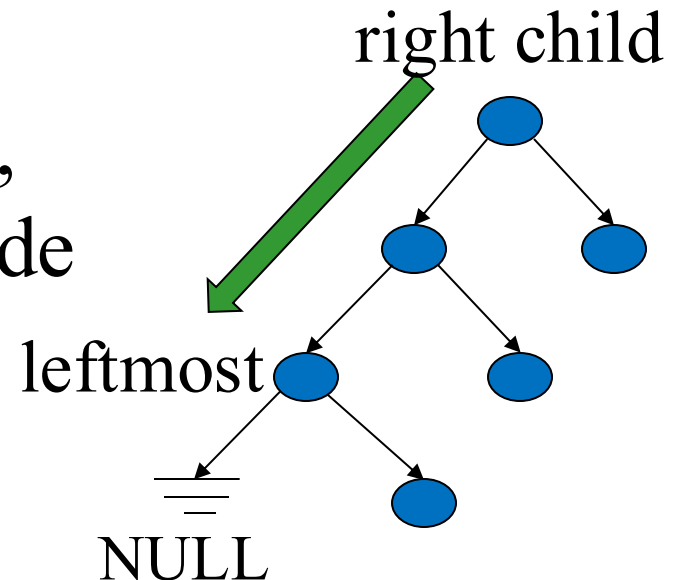
Leftmost Value: Iterative

*/*Returns value of the leftmost child*/*

```
TYPE _leftmostVal(struct Node *node) {  
    while(node->left != NULL) node=node->left;  
    return node->val;  
}
```

If the left child does not exist,
return the value of the input node

We can use this function
for Step 1 in Case 1



Remove Leftmost: Recursive

```
struct Node *_removeLeftmost(struct Node *node)
{   /* find the leftmost descendant */

    if(node->left != NULL) {

        node->left = _removeLeftmost(node->left);

        return node;

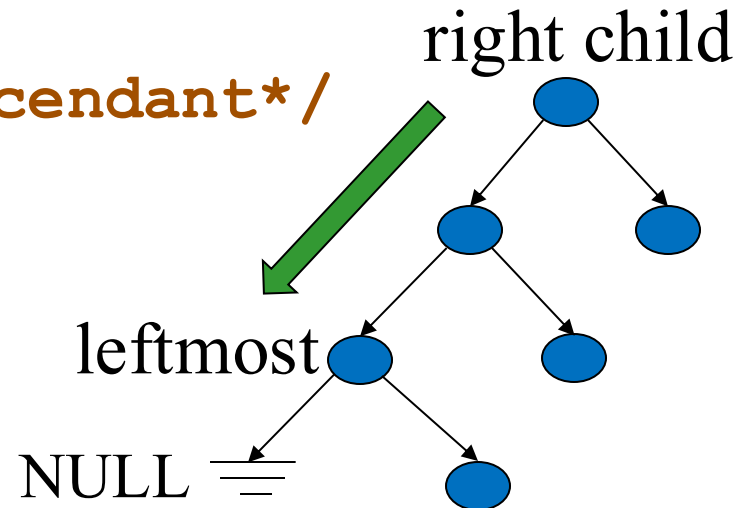
    }
}
```

recursively slide
down to the left

```
/*remove the leftmost descendant*/
```

• • •

}



Remove Leftmost: Recursive

```
struct Node *_removeLeftmost(struct Node *node)
{ /* find the leftmost descendant */

    if(node->left != NULL) {

        node->left = _removeLeftmost(node->left) ;

        return node;

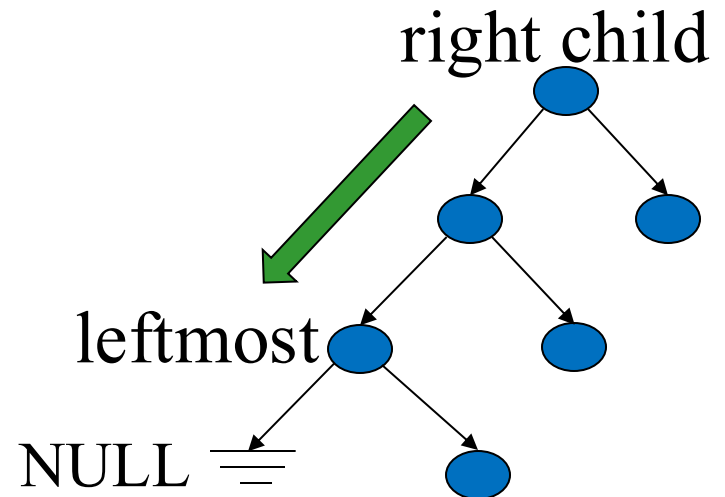
    }

    /*remove*/

}
```

recursively slide
down to the left

propagate the
changes up the tree



Remove Leftmost: Recursive

```
struct Node *_removeLeftmost(struct Node *node)
{
    if (node->left != NULL) {
        node->left = _removeLeftmost(node->left);
        return node;
    }
```

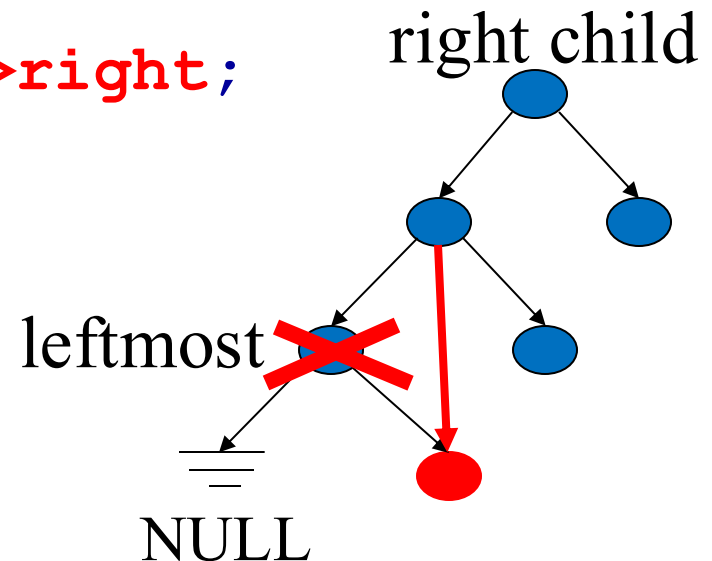
```
    struct Node *temp = node->right;
```

```
    free(node);
```

```
    return temp;
```

```
}
```

**return the right child of
the leftmost descendant**

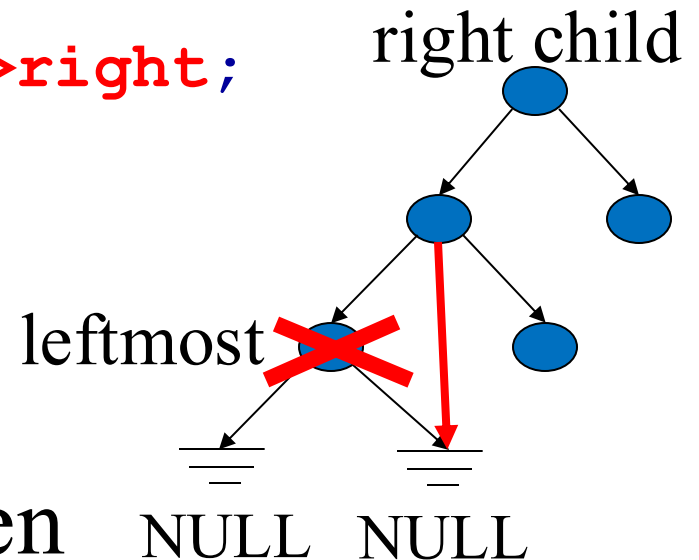


Remove Leftmost: Recursive

```
struct Node *_removeLeftmost(struct Node *node)
{
    if (node->left != NULL) {
        node->left = _removeLeftmost(node->left);
        return node;
    }

    struct Node *temp = node->right;
    free(node);
    return temp;
}
```

Special case: no children

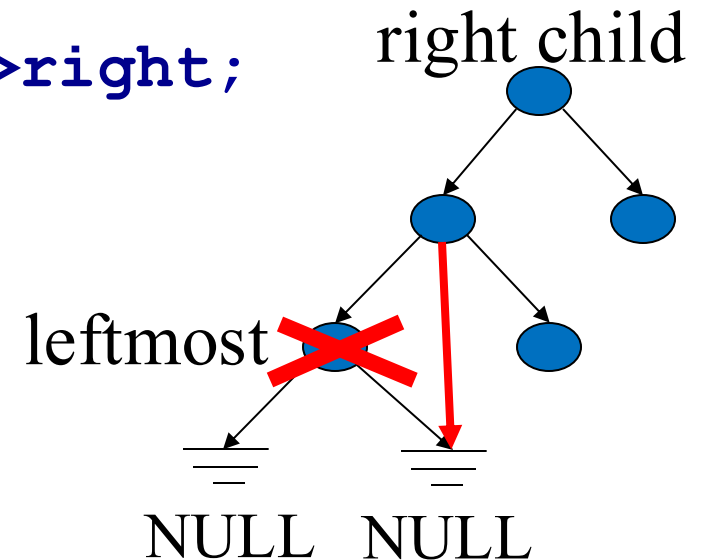


Remove Leftmost: Recursive

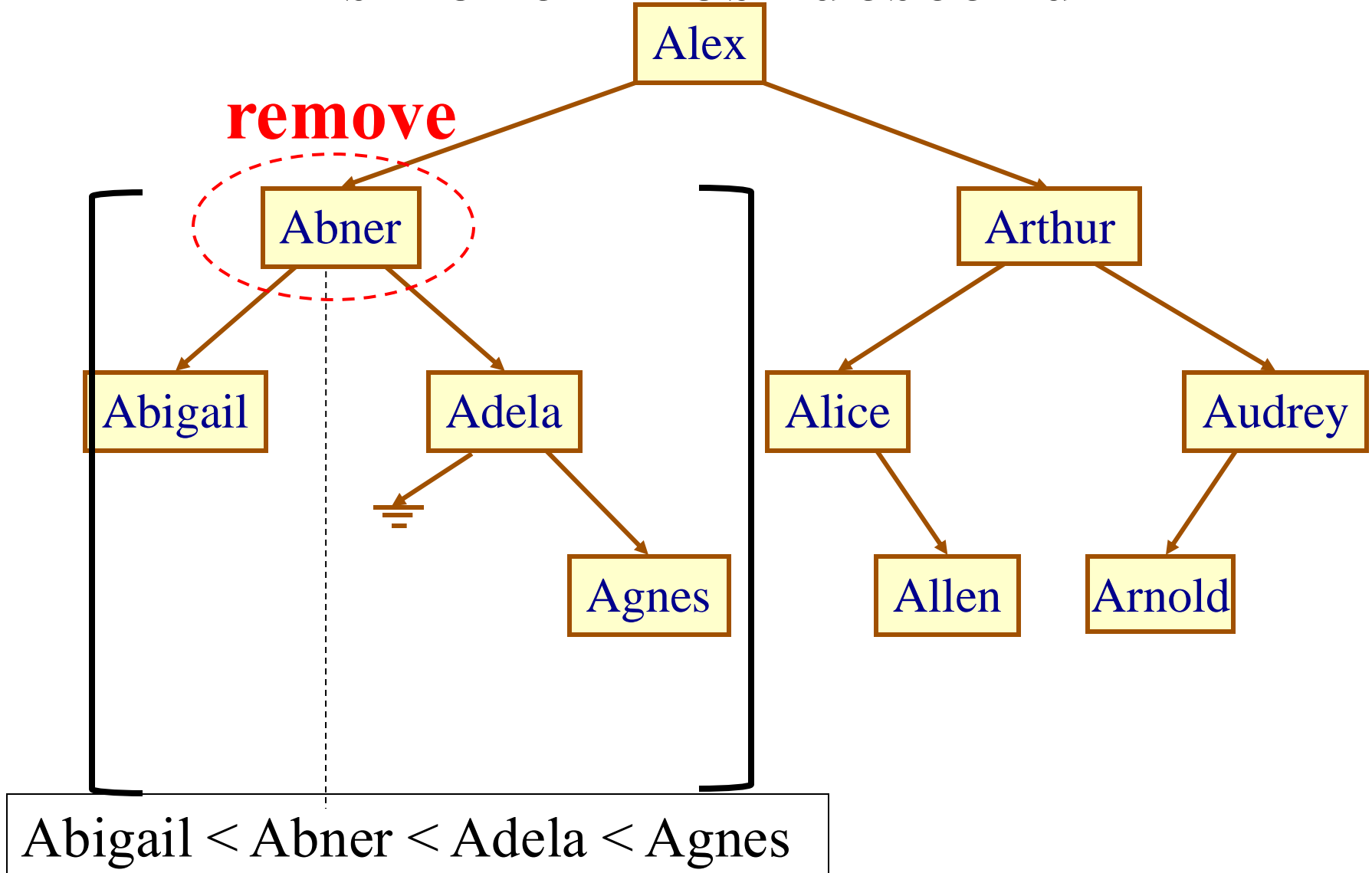
```
struct Node *_removeLeftmost(struct Node *node)
{
    if (node->left != NULL) {
        node->left = _removeLeftmost(node->left);
        return node;
    }

    struct Node *temp = node->right;
    free(node);
    return temp;
}
```

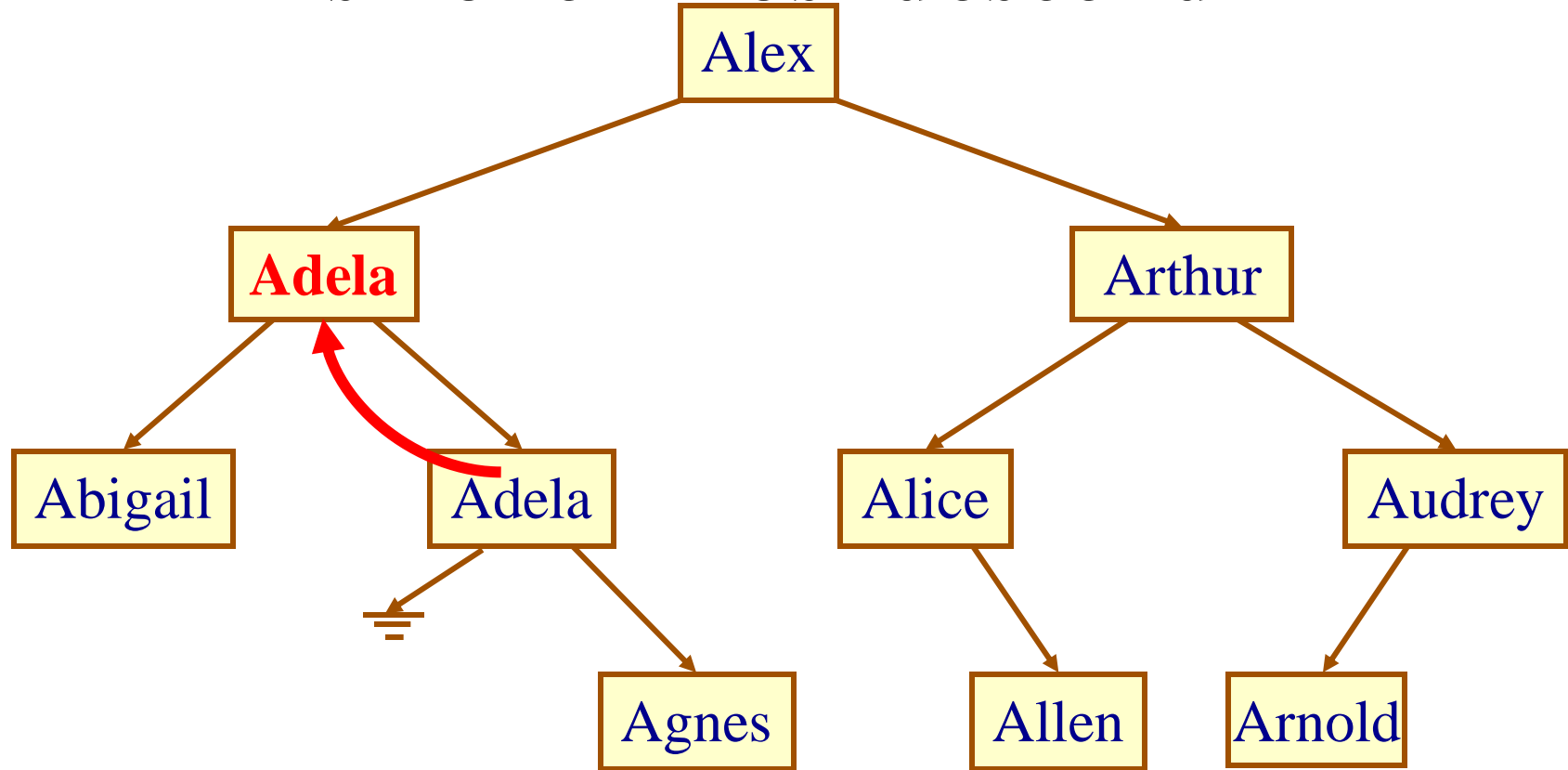
We can use this function
for Steps 2-3 in Case 1



Case 2: The right child exists but has no leftmost descendant



Case 2: The right child exists but has no leftmost descendant



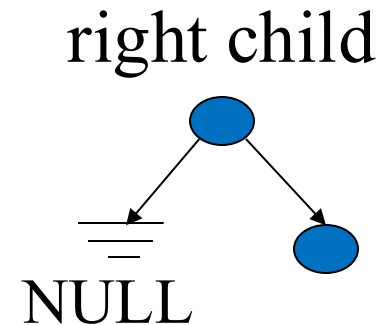
Step 1: Copy the right child

Use the Same Function in Case 2

*/*Returns value of the leftmost child*/*

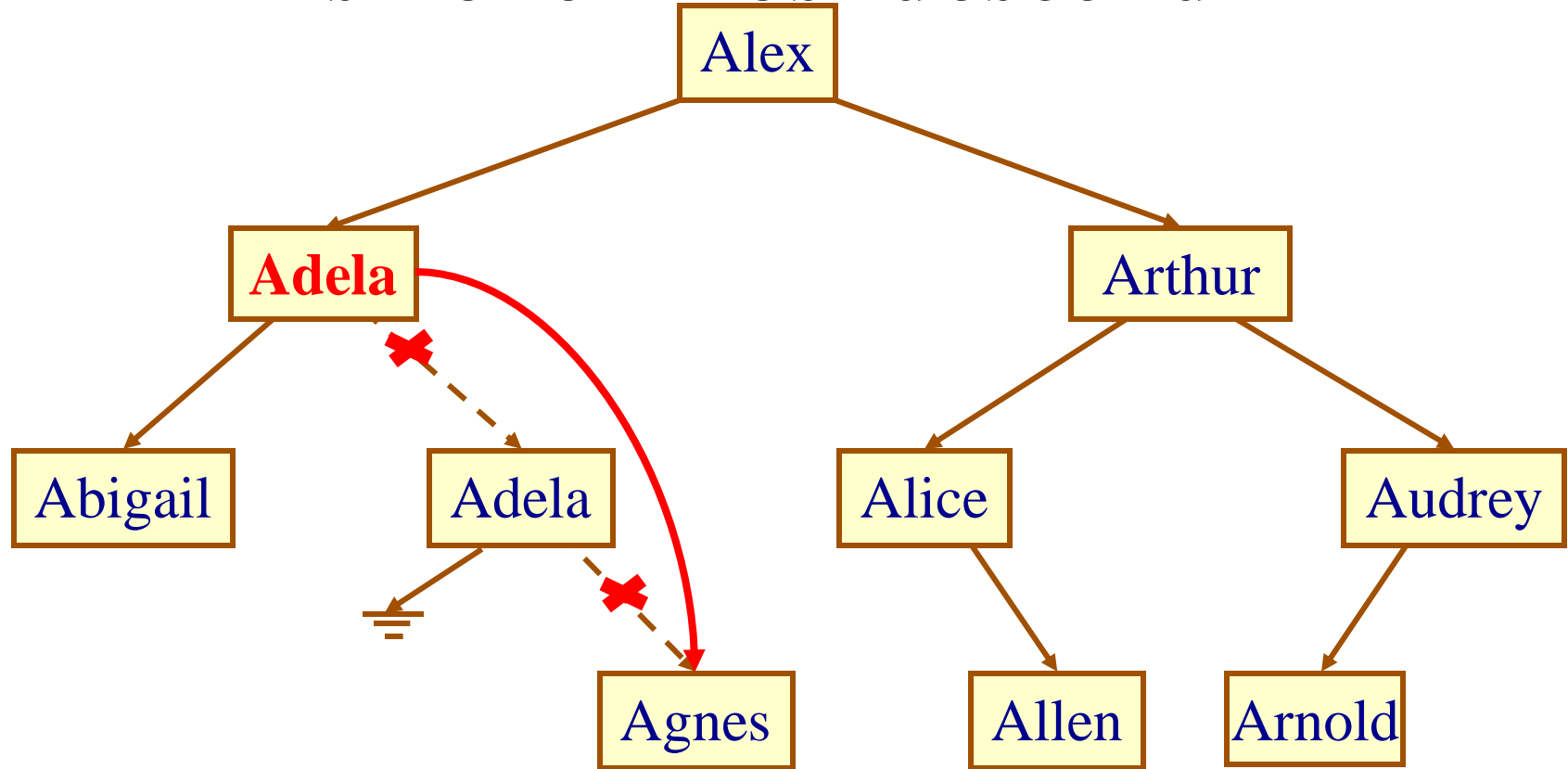
```
TYPE _leftmostVal(struct Node *node) {  
    while(node->left != NULL) node=node->left;  
    return node->val;  
}
```

If the leftmost descendant of the right child does not exist, we will return the value of the right child



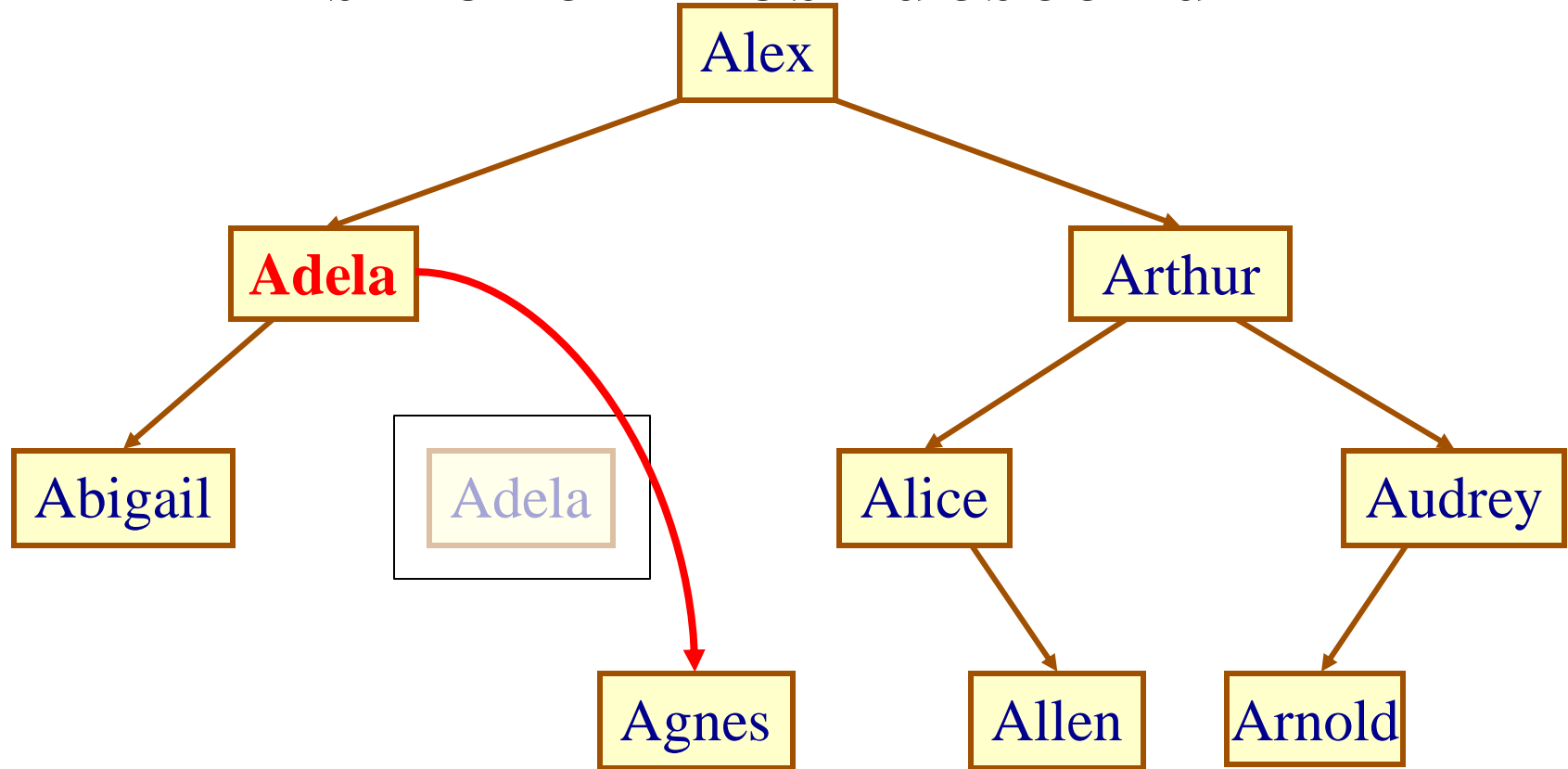
We can use this function for Step 1 in Case 2

Case 2: The right child exists but has no leftmost descendant



Step 2: Disconnect the right child

Case 2: The right child exists but has no leftmost descendant



Step 3: Free the right child

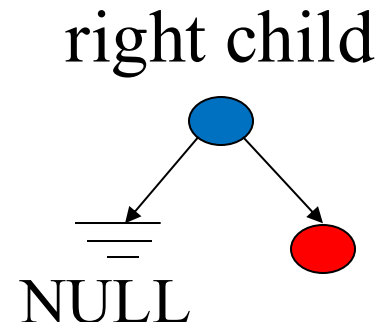
Use the Same Function in Case 2

```

NODE *_removeLeftmost(NODE *node) {
    if(node->left != NULL){
        node->left = _removeLeftmost(node->left);
        return node;
    }
    struct Node *temp = node->right;
    free(node);
    return temp;
}

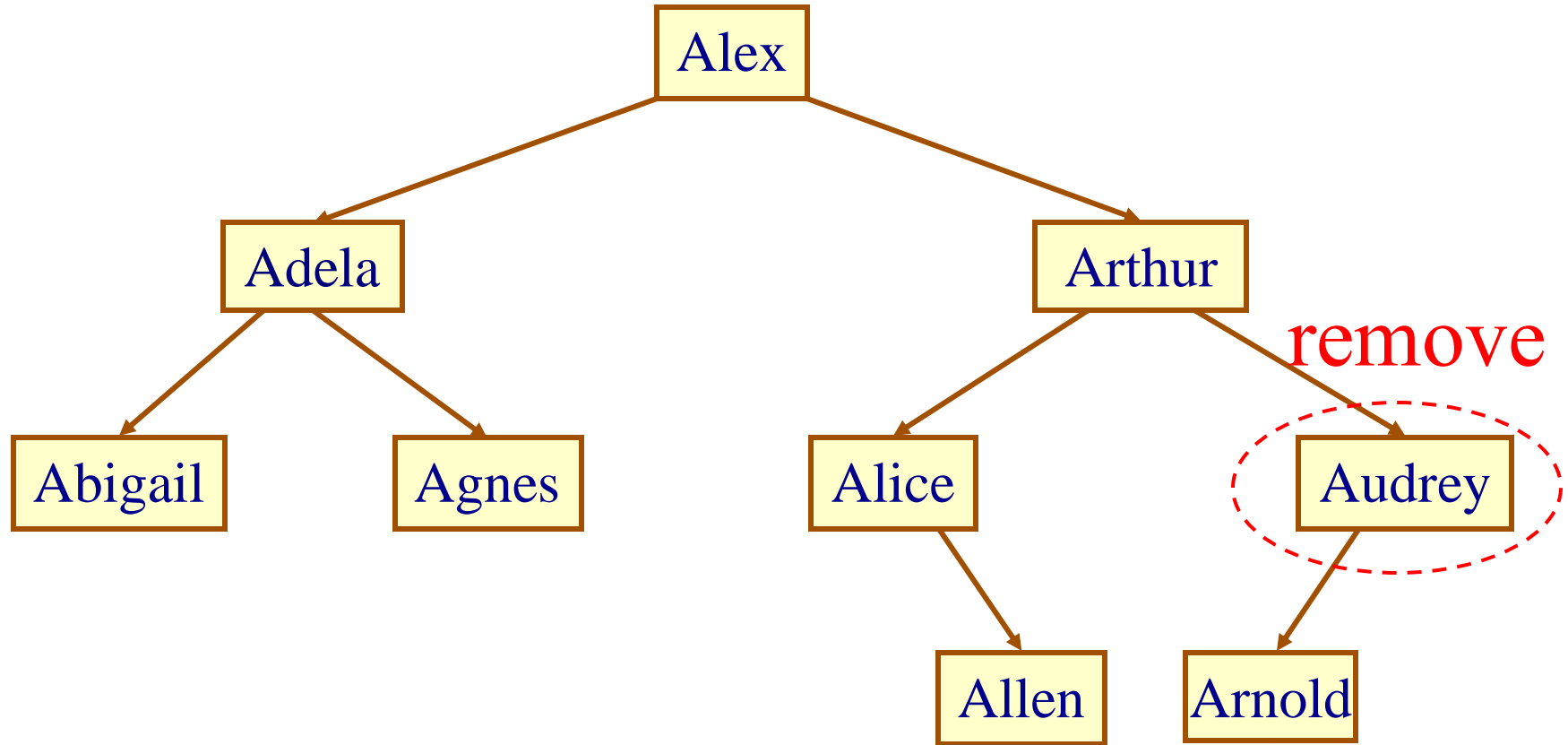
```

If the leftmost descendant of the right child does not exist, we will return the **right grandchild**

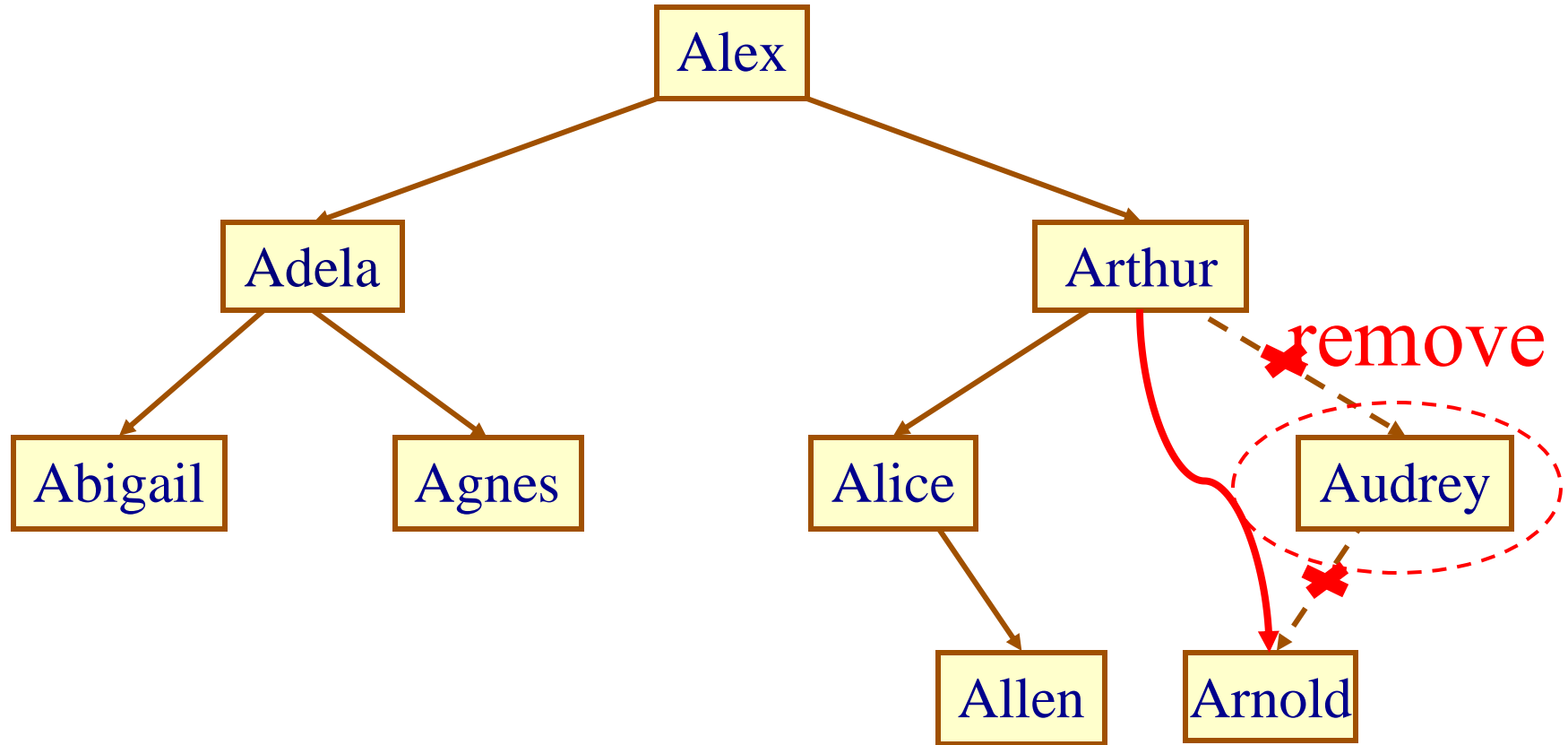


We can use this function for Steps 2-3 in Case 2

Case 3: The right child does not exist

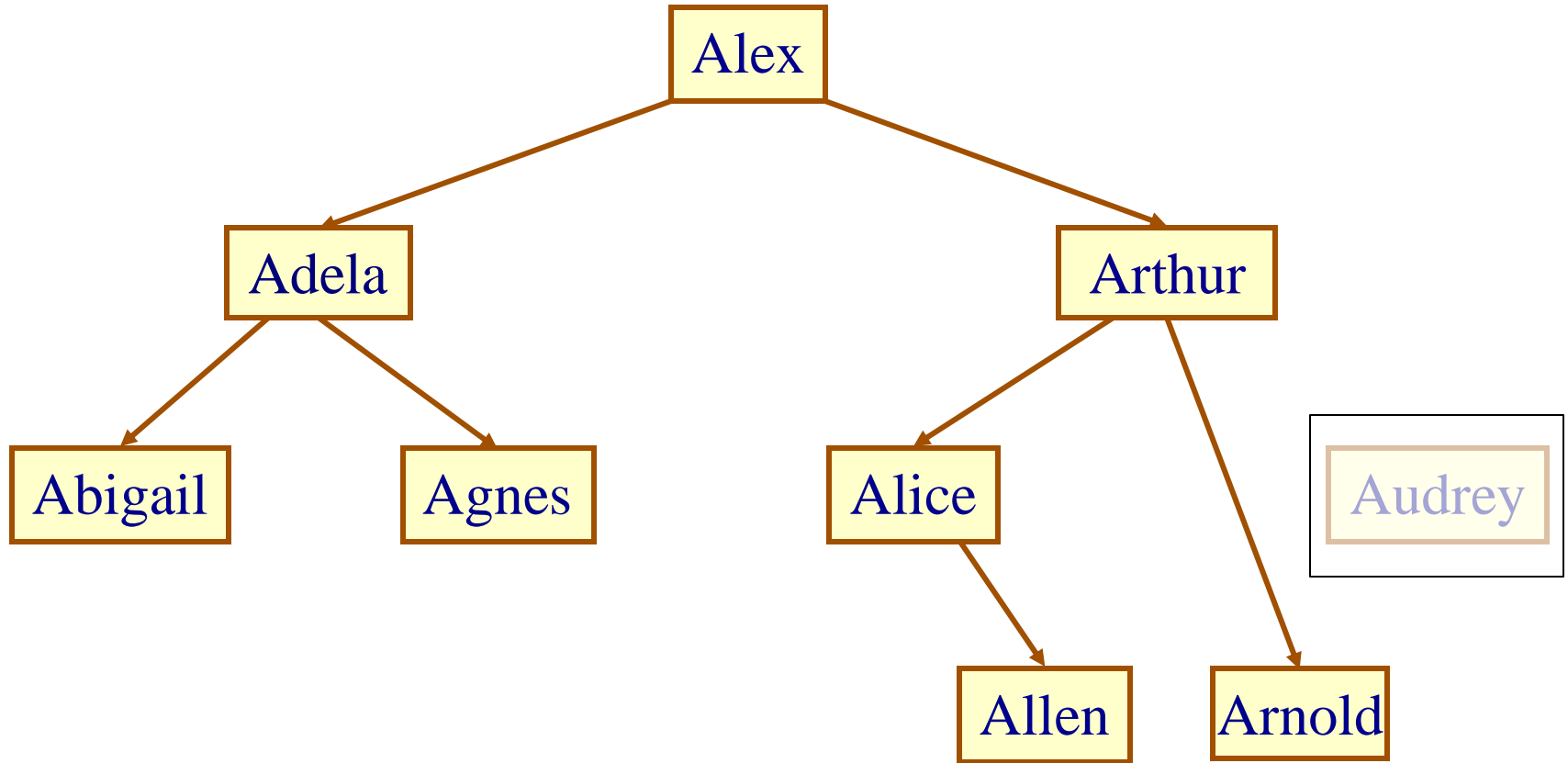


Case 3: The right child does not exist



Step 1: Disconnect the node

Case 3: The right child does not exist



We Need Two Functions for Remove

```
struct BST {  
    struct Node *root;  
    int size;  
};
```

```
void removeBST(struct BST *tree, TYPE e)  
{  
    if(containsBST(tree, e)) {  
        tree->root = removeNode(tree->root, e);  
        tree->size--; same pointer  
    }  
}
```

Complexity: $O(?)$

We Need Two Functions for Remove

```
struct BST {  
    struct Node *root;  
    int size;  
};
```

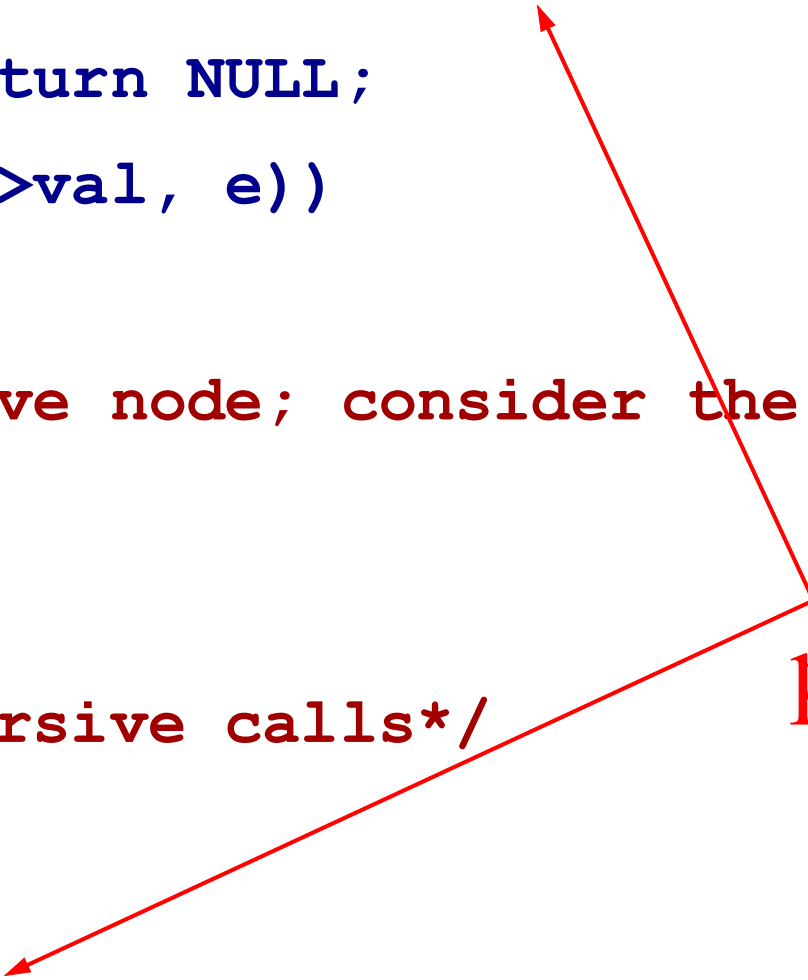
```
void removeBST(struct BST *tree, TYPE e)  
{  
    if (tree->root) {  
        tree->root = removeNode(tree->root, e);  
        tree->size--;  
    }  
}
```

same pointer

In case, if **containsBST()** is not available

```
#define NODE struct Node

NODE *removeNode(NODE *node, TYPE e) {
    if(!node) return NULL;
    if (EQ(node->val, e))
    {
        ... /*remove node; consider the 3 cases*/
    }
    else{
        ... /*recursive calls*/
    }
    return node;
}
```



same
pointer

```

NODE *removeNode(NODE *node, TYPE e) {
    if(!node) return NULL;
    struct Node *temp;
    if (EQ(e, node->val))
        /* remove node; consider the 3 cases */
    else
        /* not found, so recursive calls */
        if(LT(e, node->val))
            node->left = removeNode(node->left, e);
        else
            node->right = removeNode(node->right, e);
    return node;
}

```

same pointer

```
/* val is in the node, remove the node */
if (EQ(e, node->val)) {
    if (node->right == NULL)

        /* Case 3: no right child */

else

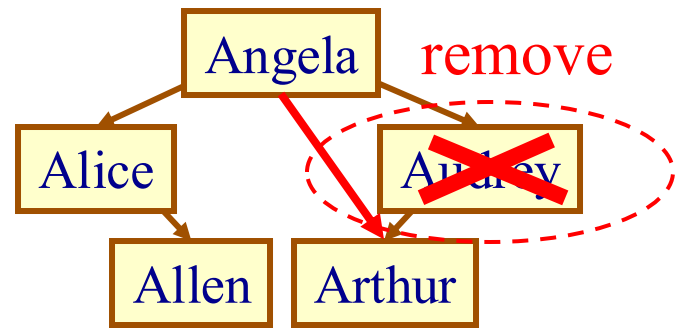
    /* Cases 1 & 2: right child exists */

}
else{
    /* not found, so recursive calls */
    ...
}
```

```

if (EQ(e, node->val)) { /*val found*/
    if (node->right == NULL) {
        /* Case 3: no right child*/
        /* return the left child */
        temp = node->left;
        free(node);
        return temp;
    }
    else
    {
        /*Cases 1 & 2: right child exists*/
    }
}
...

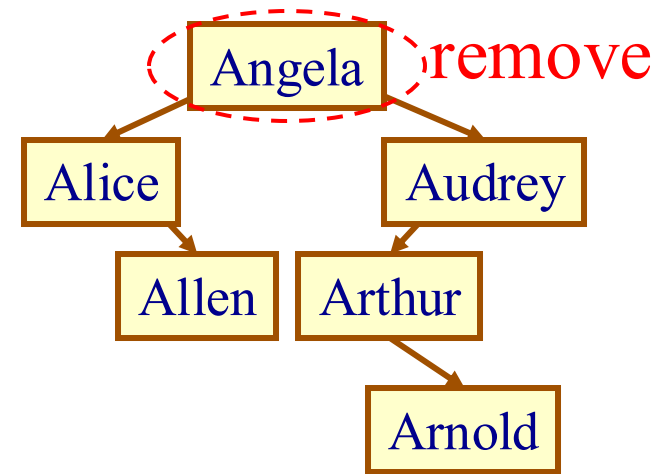
```



```

if (EQ(e, node->val)) { /*val found*/
    if (node->right == NULL) { /*Case 3*/
        temp = node->left;
        free(node);
        return temp;
    }
    else { /*Cases 1 & 2*/
        /*copy the leftmost descendant*/
        node->val = _leftmostVal(node->right);
        /*remove the leftmost descendant*/
        node->right =
            _removeLeftmost(node->right);
    } ...
}

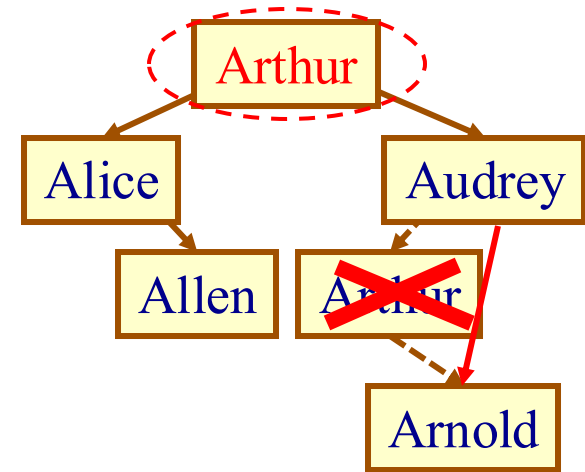
```




```

if (EQ(e, node->val)) { /*val found*/
    if (node->right == NULL) { /*Case 3*/
        temp = node->left;
        free(node);
        return temp;
    }
    else { /*Cases 1 & 2*/
        /*copy the leftmost descendant*/
        node->val = _leftmostVal(node->right);
        /*remove the leftmost descendant*/
        node->right =
            _removeLeftmost(node->right);
    } ...
}

```



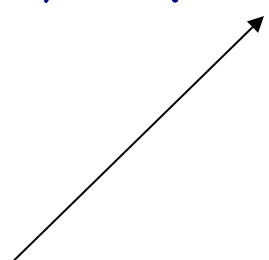
Remove All BST

```
void removeBST(BST *tree, TYPE e){
    if(tree->root){
        tree->root = removeNode(tree->root,e);
        tree->size--;
    }
}
```

```
typedef struct BST{
    struct Node *root;
    int size;
} BST;
```

```
void removeAllBST(BST *tree, TYPE e){
    assert(tree);


    if(tree->root) /*check if tree is empty*/
        tree->root =
            removeAllNode(tree->root, e, &(tree->size));
}
```



We must maintain tree size for each node removal

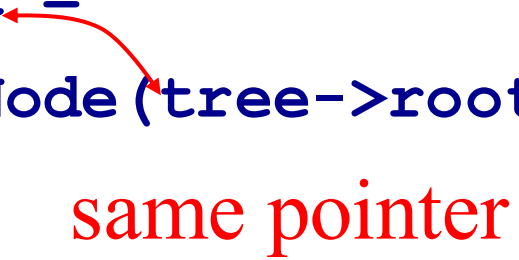
Remove All BST

```
void removeBST(BST *tree, TYPE e){  
    if(tree->root){  
        tree->root = removeNode(tree->root,e);  
        tree->size--;  
    }  
}
```



```
typedef struct BST{  
    struct Node *root;  
    int size;  
} BST;
```

```
void removeAllBST(BST *tree, TYPE e){  
    assert(tree);  
    if(tree->root) /*check if tree is empty*/  
        tree->root =  
        removeAllNode(tree->root, e, &(tree->size));  
}
```



Recursive Remove All Node

```
struct Node *removeAllNode
```

```
(struct Node *node, TYPE e, int *treesize){
```


```
/* We'll use the pre-order depth-first  
traversal to search for e top-down,  
until the node == NULL. */
```

```
if(node == NULL) return NULL;
```

```
...
```

```
return node;
```

```
}
```



to maintain
tree size for
each node
removal

Recursive Remove All Node

```
struct Node *removeAllNode
```

```
(struct Node *node, TYPE e, int *treesize){
```

```
/* We'll use the pre-order depth-first  
traversal to search for e top-down,  
until the node == NULL. */
```

```
if(node == NULL) return NULL;
```

```
...
```

to propagate the changes
up to the parent node

```
return node;
```

```
}
```

```

Node *removeAllNode(Node *node, TYPE e, int *treesize){
    while(node != NULL && EQ(e, node->val)){

        /*remove this node; consider all edge cases*/

        (*treesize)--; /* for each removal */
    }
    if( node != NULL && LT(e, node->val))
        node->left = removeAllNode(node->left, e, treesize);
    else if (node != NULL)
        node->right = removeAllNode(node->right, e, treesize);

    return node;
}

```

```

struct Node *temp;
while(node != NULL && EQ(e, node->val)){
    /*remove this node; consider all edge cases*/
    if(node->right == NULL){
        /* Case 3: there is no right child */
        temp = node->left;
        free(node);
        node = temp;
    }
    else
        /* Cases 1 & 2: the right child exists */

    (*treesize)--; /* for each removal */
}

```

```

struct Node *temp;
while(node != NULL && EQ(e, node->val)){
    /*remove this node; consider all edge cases*/
    if(node->right == NULL){/* Case 3 */
        temp = node->left;
        free(node);
        node = temp;
    }
    else{/* Cases 1 & 2 */
        node->val = _leftmostVal(node->right);
        node->right = _removeLeftmost(node->right);
    }
    (*treesize)--; /* for each removal */
}/* end while loop */

```