

Partitions of Unity and Proving the Change of Variables Theorem

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Recall

Type (1) diffeomorphisms: coordinate transposition

$$\text{Type (2) diffeomorphisms: } \begin{pmatrix} x_1 \\ \vdots \\ x_{n-1} \\ x_n \end{pmatrix} \mapsto \begin{pmatrix} x_1 \\ \vdots \\ x_{n-1} \\ \alpha(\vec{x}) \end{pmatrix}$$

We can combine these to obtain type (3) diffeomorphisms: “generalized shears”

$$\begin{pmatrix} x_1 \\ \vdots \\ x_{j-1} \\ x_j \\ x_{j+1} \\ \vdots \\ x_n \end{pmatrix} \mapsto \begin{pmatrix} x_1 \\ \vdots \\ x_{j-1} \\ \eta(\vec{x}) \\ x_{j+1} \\ \vdots \\ x_n \end{pmatrix}$$

Prop: Any invertible affine map may be factored into a composition of affine maps of type (1) or (2) (equivalently, type (1) or (3)).

Proof: For linear maps, use “elementary matrix factorization” (Thm 2.4)

For translations, move coord at a time.

□

Fun fact: type (1) is just the composition of three type (3) maps.

$$\mathbf{Ex:} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$$

Thm: In some neighborhood of \vec{p} , g can be factored into a composition of diffeomorphisms of type (1) or (2) (equivalently (1) or (3)).

Step 1: Pick $T_1, T_2 : \mathbb{R}^n \rightarrow \mathbb{R}^n$ invertible, affine such that $g = T_1 \circ \tilde{g} \circ T_2$ with $T_2(\vec{p}) = \vec{0}$ and $T_1(\vec{0}) = \vec{q}$, $D\tilde{g}(\vec{0}) = \text{Id}$. So $\tilde{g}(\vec{0}) = \vec{0}$, and we can take $DT_2 = Dg(\vec{p})$ and $DT_1 = \text{Id}$.

$$\begin{array}{ccc}
\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} & \mapsto & \begin{pmatrix} \tilde{g}_1(\vec{x}) \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} & \text{So } D\tilde{g}_k(\vec{0}) = \vec{e}_k, \text{ so the derivative at } \vec{0} \text{ is Id, so it's locally diffeomorphic.} \\
& & \downarrow & \text{local diffeomorphism*} \\
\text{Step 2: } \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} & \mapsto & \begin{pmatrix} \tilde{g}_1(\vec{x}) \\ \tilde{g}_2(\vec{x}) \\ x_3 \\ \vdots \\ x_n \end{pmatrix} & \text{Also has derivative at } \vec{0} \text{ is Id, so locally diffeomorphic.} \\
& & \downarrow & \text{local diffeomorphism*} \\
\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} & \mapsto & \begin{pmatrix} \tilde{g}_1(\vec{x}) \\ \tilde{g}_2(\vec{x}) \\ \tilde{g}_3(\vec{x}) \\ \vdots \\ x_n \end{pmatrix} & \text{"} \\
& & \downarrow & \text{local diffeomorphism*} \\
& & \downarrow & \text{local diffeomorphism*}
\end{array}$$

So $\vec{x} \mapsto \tilde{g}(\vec{x})$ has derivative Id at $\vec{0}$, so it's locally diffeomorphic.

* These diffeomorphisms preserve $n - 1$ coordinates, so they're type (3).

And T_1, T_2 are type (1) diffeomorphisms.

□

Defn: Consider $f : X^{\text{metric space}} \rightarrow V^{\text{vector space}}$. $\text{supp } f \stackrel{\text{def}}{=} \overline{\{\vec{x} : f(\vec{x}) \neq \vec{0}\}}$.

So $\vec{x} \notin \text{supp } f \Leftrightarrow \exists \varepsilon > 0$ s.t. $f \equiv \vec{0}$ on $U(\vec{x}, \varepsilon)$.

Cor: (of factorization and results from Monday):

There exists a neighborhood U of \vec{q} such that the COVT holds when $\text{supp } f \subset U$.

Proof: Picture. □

We now have a local version of the COVT!

Thm: (Partition of Unity) Given $\Omega^{\text{open}} \subset \mathbb{R}^n$ with $\Omega = \bigcup_{\alpha \in \Gamma} U_{\alpha}^{\text{open}}$, then $\exists \varphi_1, \varphi_2, \dots \in C^{\infty}(\Omega, [0, +\infty))$ s.t.

- (i) each $\text{supp } \varphi_j \subset \text{some } U_{\alpha_j}$
- (ii) each $\text{supp } \varphi_j$ compact
- (iii) each $\vec{x} \in \Omega$ has a nbd meeting (i.e., non-empty intersection) only finitely many $\text{supp } \varphi_j$
- (iv) $\sum_{j=1}^{\infty} \varphi_j(\vec{x}) = 1$ for al $\vec{x} \in \Omega$ (locally finite sum)

Then $\{\varphi_j\}$ is a “partition of unity dominated by $\{U_{\alpha}\}$ ”.

Proof: Nov 21, or read §16.

Lemma: Given $f \in C(B^{\text{osso}\mathbb{R}^n}, \mathbb{R})$, $\text{ext } \int_B f$ exists, $\{\varphi_j\}$ satisfies (ii), (iii), (iv).

$$\text{Then } \text{ext } \int_B f = \sum_{j=1}^{\infty} \int_B \varphi_j \cdot f.$$

Proof: strategy is tackle $f \geq 0$, then apply previous result to f_+ , f_- , and combine.

Assume $f \geq 0$. Then $E^{\text{cpt}, \text{rect}} \subset B \Rightarrow \exists M$ s.t. $U_j \equiv 0$ on E for $j \geq M$. This is compact using (iii).

$$\text{Thus, } \int_E f = \int_E \sum_{i=1}^M \varphi_i \cdot f = \sum_{i=1}^M \int_E \varphi_i \cdot f \leq \sum_{j=1}^M \int_B \varphi_j \cdot f \leq \sum_{j=1}^{\infty} \int_B \varphi_j \cdot f.$$

$$\text{Take the supremum over } E, \text{ obtain } \text{ext} \int_E f \leq \sum_{j=1}^{\infty} \int_B \varphi_j \cdot f$$

$$\text{Also, } \sum_{j=1}^{\infty} \int_B \varphi_j \cdot f = \lim_{M \rightarrow \infty} \sum_{j=1}^M \int_B \varphi_j \cdot f = \lim_{M \rightarrow \infty} \int_B \sum_{j=1}^M \varphi_j \cdot f \leq \text{ext} \int_B f.$$

Apply to f_+ , f_- .

Combine. \square

Proof of the Change of Variables Theorem: For $\vec{y} \in B$, choose $U_{\vec{y}}$ s.t. g factors on $U_{\vec{y}}$. Choose partition of unity dominated by $\{U_{\vec{y}} : \vec{y} \in B\}$. Then

$$\text{ext} \int_B f_+ \stackrel{\text{lemma}}{=} \sum_B \int_B \varphi_j f_+ = \sum_A \int_A (\varphi_1 \circ g)(f_+ \circ g) |\det Dg| \stackrel{\text{lemma}}{=} \text{ext} \int_A (f_+ \circ g) \cdot |\det Dg|$$

$$\text{Similarly, } \text{ext} \int_A f_- = \text{ext} \int_A (f_- \circ g) \cdot |\det Dg|.$$

Now combine (unless both terms are infinite). \square