

# Lagrange Multiplier Theorem

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Given  $f \in C^1(\Omega_{\text{osso}} \mathbb{R}^{k+n}, \mathbb{R})$ ,  $\vec{p} \in E = f^{-1}(\vec{0})$ ,  $\text{rank } Df(\vec{p}) = n$ ,  $h \in C^1(\Omega, \mathbb{R})$ , and  $h|_E$  has a local max or min at  $\vec{p}$ .

Then  $\exists \lambda_1, \dots, \lambda_n$  s.t.  $Dh(\vec{p}) = \lambda_1 Df_1(\vec{p}) + \dots + \lambda_n Df_n(\vec{p})$ .  $\lambda_j$  are called the lagrange multipliers.

**Ex:** What points of  $xyz = 1$  lie closest to  $\vec{0}$ ?

Let  $f(x, y, z) = xyz - 1$  and  $h(x, y, z) = x^2 + y^2 + z^2$ . Minimize  $h$  over  $f^{-1}(\vec{0}) = E$ .

Is the existence of the minimum guaranteed? In this case, yes. Pick  $R$  s.t.  $R > h(x_0, y_0, z_0)$  for some  $(x_0, y_0, z_0) \in E \neq \emptyset$ . Let  $K = \{(x, y, z) : x^2 + y^2 + z^2 \leq R\}$ . Then  $\inf K = \inf E \cap K$ , and  $E \cap K$  is compact. By the extreme value theorem,  $\inf E \cap K = \min E \cap K$ .

$Dh = \begin{bmatrix} 2x & 2y & 2z \end{bmatrix}$  and  $Df = \begin{bmatrix} yz & xz & xy \end{bmatrix}$ . So we have the following system of equations:

$$\begin{cases} 2x = \lambda yz \\ 2y = \lambda xz \\ 2z = \lambda xy \\ xyz = 1 \end{cases}$$

Solving this system of equations gives us  $(1, 1, 1)$ ;  $(-1, -1, 1)$ ;  $(-1, 1, -1)$ , and  $(1, -1, -1)$ .

For extra practice, try  $x^a + y^b + c^z = 1$

**Ex:**  $B \in \text{Mat}(n, n, \mathbb{R})$  symmetric (that is,  $B = B^T$ ).

Let  $h(\vec{x}) = \vec{x}^T B \vec{x}$ . Goal: maximize  $h$  on  $\|\vec{x}\|^2 = 1$ . Use  $f(\vec{x}) = \|\vec{x}\|^2 - 1$ .

Check that  $Df$  has rank 1 when  $\|\vec{x}\|^2 = 1$ .  $Df(\vec{x}) = 2\vec{x}^T$ . Then the max exists, and it occurs at a solution of  $Dh = \lambda Df$ .

Claim:  $Dh(\vec{x}) = 2\vec{x}^T B$ .

Proof:  $h(\vec{x}) = \sum_{j,k} b_{jk} x_j x_k$ . So  $D_m h(\vec{x}) = \sum_k b_{mk} x_k + \sum_j b_{jm} x_j$ .

By symmetry,  $D_m h(\vec{x}) = 2 \sum_j b_{jm} x_j = (2\vec{x}^T B)_m$ . So  $Dh(\vec{x}) = 2\vec{x}^T B$ .

Proof 2:  $Dh(\vec{x}) \cdot \vec{u} = h'(\vec{x}; \vec{u}) = \vec{u}^T B \vec{x} + \vec{x}^T B \vec{u} = 2\vec{x}^T B \vec{u}$ .

We need  $Dh(\vec{x}) = \lambda Df(\vec{x})$ .  $Dh(\vec{x}) = 2\vec{x}^T B$  and  $Df(\vec{x}) = 2\lambda \vec{x}^T$ . So we have  $B\vec{x} = \lambda \vec{x}$ . So  $\lambda$  is an eigenvalue and  $\vec{x}$  is an eigenvector (call it  $\vec{x}_1$ ).

Note that  $h(\vec{x}) = \vec{x}^T B \vec{x} = \lambda$ , i.e.,  $\lambda = \max h$  over the sphere. Rename  $\mu_1$  as the eigenvalue.

We have previously proved that every symmetric matrix has a real eigenvalue.

**Ex:** Followup: Now maximize  $h$  over the sphere intersected with  $\{\vec{x}_1\}^T$ , which is just  $f^{-1}(\vec{0})$ , with

$$f(\vec{x}) = \|\vec{x}\|^2 - 1 = \begin{bmatrix} \vec{x}^T \cdot \vec{x} - 1 \\ \vec{x}_1^T \cdot \vec{x} \end{bmatrix} = \begin{bmatrix} f_1(\vec{x}) \\ f_2(\vec{x}) \end{bmatrix}$$

We need  $Dh(\vec{x}) = \lambda_1 Df_1(\vec{x}) + \lambda_2 Df_2(\vec{x})$ , i.e., we need

$$\begin{cases} \vec{x}^T \cdot \vec{x} = 1 \\ \vec{x}_1^T \cdot \vec{x} = 0 \\ 2\vec{x}^T B = 2\lambda_1 \vec{x}^T + \lambda_2 \vec{x}_1^T \end{cases} \rightarrow (\text{right-multiply by } \vec{x}_1) \rightarrow 2\vec{x}^T B \vec{x}_1 = 0 + \lambda_2$$

So  $\lambda_2 = 0$ , so  $2\vec{x}^T B = 2\lambda_1 \vec{x}^T$ , so  $B\vec{x} = \lambda_1 \vec{x}$ . We get a second real eigenvalue  $\mu_2 = \lambda_1$ , with eigenvector  $\vec{x}_2 \in \{\vec{x}_1\}^\perp$ .

**Ex:** Use induction to prove the spectral theorem:

$B$  symmetric real matrix  $\rightarrow B$  admits an orthonormal basis of eigenvectors  $\vec{x}_1, \dots, \vec{x}_n$  with real eigenvalues  $\mu_1 \geq \mu_2 \geq \dots \geq \mu_n$ .

**Ex:**  $h(c_1 \vec{x}_1 + \dots + c_n \vec{x}_n) = c_1^2 \mu_1 + \dots + c_n^2 \mu_n$ .

All  $\mu_i \geq 0 \Leftrightarrow \vec{x}^T B \vec{x} \geq 0$  for all  $\vec{x} \in \mathbb{R}^n \setminus \{\vec{0}\} \stackrel{\text{def}}{\Leftrightarrow} "B \geq 0"$ . We say that  $B$  is positive semi-definite.

All  $\mu_i > 0 \Leftrightarrow \vec{x}^T B \vec{x} > 0$  for all  $\vec{x} \in \mathbb{R}^n \setminus \{\vec{0}\} \stackrel{\text{def}}{\Leftrightarrow} "B > 0"$ . We say that  $B$  is positive definite.

$B \leq 0 \Leftrightarrow (-B) \geq 0$

$B < 0 \Leftrightarrow (-B) > 0$ .

**Thm:** Given  $\Omega \subset \mathbb{R}^n$  convex and open,  $f \in C^2(\Omega, \mathbb{R})$ .

$Hf(\vec{x}) \stackrel{\text{def}}{=} (D_j D_k f(\vec{x}))_{j,k}$ . This is called the Hessian of  $f$  at  $\vec{x}$ .

$Hf(\vec{x}) \in \text{Symm}(n) \stackrel{\text{def}}{=} \{M \in \text{Mat}(n, n) : M^T = M\}$

$Hf(\vec{x}) \geq 0, \forall \vec{x} \in \Omega, Df(\vec{x}_0) = \vec{0}$ .

Then  $f(\vec{x}) \geq f(\vec{x}_0), \forall \vec{x} \in \Omega$ .