

# Integral Manifolds and Differential Equations

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1/14/19

Recall from Friday/HW 1 #3:

**Defn:**  $M \subset A$  is an integral manifold for  $\omega$  1-form on  $A^{\text{open}} \subset \mathbb{R}^n$  when any of the following conditions are true (TFAE):

- (a)  $\mathcal{T}_{\vec{p}}M \subset \ker \omega(\vec{p}), \forall \vec{p} \in M$
- (b)  $\alpha^* \omega = 0, \forall \alpha$  coordinate patch for  $M$
- (c)  $\int_C \omega = 0, \forall C^{1\text{-mfd}} \subset M$

**Ex:** Consider  $n = 2$ ...

$f \in C^1(A, \mathbb{R}), df \neq 0$  on  $A$ .

Then each level set  $f^{-1}(c)$  is a 1-mfd-wob.

Then each level set of  $f$  is an integral manifold for  $df$ .

Proof:  $\alpha^*(df) \underset{15}{=} d(\alpha^*f) \underset{4}{=} d(f \circ \alpha) \underset{12}{=} d(c) = 0$

Suppose  $\omega = u(x, y)dx + v(x, y)dy$  on  $A^{\text{open}} \subset \mathbb{R}^2$  with  $v$  non-vanishing.

Given  $M$  is a 1-mfd, use a graph parameterization  $\alpha : (a, b) \rightarrow M$   
 $x \mapsto (x, f(x))$

All other coord patches  $\beta$  satisfy  $\beta = \alpha \circ \underbrace{(\alpha^{-1} \circ \beta)}_{\text{transition map}} = \alpha \circ \gamma$  for  $\gamma$   $C^1$  diffeomorphism.

That is,  $\beta^* \omega \stackrel{\gamma}{=} \gamma^*(\alpha^* \omega)$ .

Thus,  $M$  is an integral manifold for  $\omega$  if and only if  $\alpha^* \omega = 0$ .

$\alpha^* \omega = u(x, f(x))dx + v(x, f(x))d(f(x)) = u(x, f(x))dx + v(x, f(x))f'(x)dx$ .

This is 0 if and only if  $f'(x) = \frac{-u(x, f(x))}{v(x, f(x))}$ . This is a differential equation for  $f$ .

Suppose further that  $u, v \in C^1$ , so  $-\frac{u(x, y)}{v(x, y)}$  is  $C^1$ . Consider  $(0, y_0) \in A$ .

Claim:  $\exists \Phi \in C^1(\mathbb{R}^2, \mathbb{R})$  with  $D\Phi : \mathbb{R}^2 \rightarrow \mathbb{R}_{\text{row}}^2 = \text{Hom}(\mathbb{R}^2, \mathbb{R})$  bounded and  $\Phi(x, y) = -\frac{u(x, y)}{v(x, y)}$  for  $(x, y)$  in a neighborhood of  $(0, y_0)$ .

Proof: Pick a  $\Psi \in C^\infty(\mathbb{R}^2, \mathbb{R})$  with  $\Psi \equiv 1$  in a neighborhood around  $(0, y_0)$ , and  $\text{supp } \Psi$  is a compact subset of  $A$  (see notes 11/21 for why we can do this).

Set  $\Phi(x, y) = \begin{cases} -\frac{u(x, y)}{v(x, y)} \cdot \Psi(x, y) & (x, y) \in A \\ 0 & (x, y) \notin A \end{cases}$

**Exer:** Check that this works.

395 HW 3 #2  $\Rightarrow \Phi$  is Lipschitz on  $\mathbb{R}^2 \Rightarrow \Phi$  is partial-Lipschitz on  $\mathbb{R}^2$

395 HW 10 #6  $\Rightarrow \exists \tilde{\varepsilon} > 0$  s.t.  $f'(x) = \Phi(x, f(x))$  with  $f(0) = y_0$  has a unique solution for  $x \in (-\tilde{\varepsilon}, \tilde{\varepsilon})$  (perhaps shrinking  $\tilde{\varepsilon}$  if necessary).

Result:  $\exists \varepsilon > 0$  such that  $f'(x) = -\frac{u(x, f(x))}{v(x, f(x))}$  has a unique solution for  $x \in (-\varepsilon, \varepsilon)$ . So  $\exists!$  local integral curve for  $\omega$  passing through  $(0, y_0)$ .

Claim: Get the same result based at  $(x_0, y_0)$ .

Proof: Use a translation in the  $x$ -direction.

395 HW 11 #6:  $\omega = x^{1/3}dx - dy$  is a  $C^0$  but not  $C^1$  1-form.  $\omega$  does not have unique solutions.

Conversely, given a differential equation  $f'(x) = \Phi(x, f(x))$   $\star$

Then graphs of solutions of  $(\star)$  are integral curves for  $\omega = -B(x, y)\Phi(x, y)dx + B(x, y)dy$ .

I.e. " $0 = -B(x, y)\Phi(x, y) + B(x, y)\frac{dy}{dx}$ ".

Suppose we can choose non-zero  $B$  such that  $B\omega$  is exact, i.e.,  $B\omega = dg$  for some  $g$ .

**Defn:** Then  $B$  is an integrating factor for  $-\Phi(x, y)dx + dy$ .

From earlier in lecture, the level curves  $g^{-1}(c)$  are integral manifolds for  $dg$ , which are integral manifolds for  $-\Phi(x, y)dx + dy$ , which are graphs of solutions of  $(\star)$ .

Conversely,  $f$  solves  $(\star) \Rightarrow \frac{d}{dx}g(x, f(x)) = \begin{pmatrix} -B(x, f(x)) & \Phi(x, f(x)) \end{pmatrix} \begin{pmatrix} 1 \\ \Phi(x, f(x)) \end{pmatrix} = 0$ .

So  $g(x, f(x))$  is (locally) constant!

**Good News 1:** Such a  $B$  always exists!

**Good News 2:** Looking for such a  $B$  is often a useful approach to solving  $(\star)$ !

**Bad News:** It's not always easier to find  $B$  than to solve  $(\star)$ .

Two important classes of examples:

1  $f'(x) = \beta(f(x))$   $(\star\star)$ , an "autonomous differential equation". Solutions are integral curves for  $-\beta(y)dx - dy$ . Use integrating factor  $B(x, y) = \frac{1}{\beta(y)}$  (assume for now that  $\beta$  doesn't vanish).

Solutions: integral curves for  $-dx + \frac{dy}{\beta(y)} = d(-x - \int \frac{dy}{\beta(y)})$ .

Solutions of  $(\star\star)$  satisfy  $-x + \int \frac{dy}{\beta(y)} = C$ , i.e.,  $\int \frac{dy}{\beta(y)} = x + C$ .

**Exer:** Try to solve for  $y$  using implicit function theorem if there's no nice closed form solution as a function of  $y$ .