

# Comparison of Exterior and Vector Calculus

Thomas Cohn

2/8/19

From Wednesday, we have an orientation of manifold  $M$  induces an orientation of  $\partial M$ .

$(x_1, \dots, x_k) \mapsto (x_1, \dots, x_k)$  orientation-preserving on  $\mathbb{H}^k$ .

$(x_1, \dots, x_{k-1}) \mapsto (x_1, \dots, x_{k-1}, 0)$  orientation-preserving on  $\partial\mathbb{H}^k$ .

Exterior Calculus in $\mathbb{R}^3$	Vector Calculus in $\mathbb{R}^3$
Works well with diffeomorphisms	Works well with isometries (translations and rotations)
0-form $f$	Scalar Field $f$
1-form $\alpha dx + \beta dy + \gamma dz$	Vector Field $\vec{F} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$
2-form $\alpha(dy \wedge dz) + \beta(dx \wedge dz) + \gamma(dx \wedge dy)$	Vector Field $\vec{F} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$
3-form $f(dx \wedge dy \wedge dz)$	Scalar Field $f$
1-form $\wedge$ 2-form	$\langle \vec{F}_1, \vec{F}_2 \rangle$ inner product
1-form $\wedge$ 1-form	$\vec{F}_1 \times \vec{F}_2$ cross product
1-form $\wedge$ 1-form $\wedge$ 1-form	$\det(\vec{F}_1, \vec{F}_2, \vec{F}_3)$ scalar field
$d$	$\nabla = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$
$df$	$\nabla f = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$
$d(\alpha dx + \beta dy + \gamma dz)$	$\text{curl } \vec{F} = \nabla \times \vec{F}$
$d(\alpha dy \wedge dz + \beta dx \wedge dz + \gamma dx \wedge dy)$	$\text{div } \vec{F} = \langle \nabla, \vec{F} \rangle$
$\int_M \omega$	$k = 1$ work, circulation $k = 2$ flux across $M$

Notation clarification: vector field  $V : A \rightarrow \mathbb{R}^n$ .

For a local diffeomorphism,  $\alpha^*V(\vec{x}) \stackrel{\text{def}}{=} (D\alpha(\vec{x}))^*V(\alpha(\vec{x}))$

Vector field  $\leftrightarrow$  1-form

$$\begin{array}{ccc} \alpha^*(V^T)(\vec{x}) & \stackrel{?}{=} & (\alpha^*V)^T(\vec{x}) \\ \parallel & & \parallel \\ V^*(\alpha(\vec{x}))D\alpha(\vec{x}) & & V^T(\alpha(\vec{x}))(D\alpha(\vec{x})^{-1})^T \end{array}$$

This only works if  $D\alpha = ((D\alpha)^{-1})^T \Leftrightarrow D\alpha$  orthonormal  $\Leftrightarrow D\alpha$  is an isometry.

So if the coordinate patches are isometries, the distinction between vector fields and 1-forms (exterior and vector calculus) collapses since the pullback rules are the same.