

# Math 591 Lecture 26

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## Lie Derivatives

The general notion of a Lie derivative with respect to a vector field  $X$  is “pull back by  $\theta_t$ , the time  $t$  map of the flow of  $X$ , and then differentiate with respect to  $t$  at  $t = 0$ ”. We call this  $\mathcal{L}_X$ .

**Ex:** We can pull back functions, so we can have Lie derivatives of functions.

Given  $X$ ,  $\theta_t$ , and  $f \in C^\infty(M)$ ,  $\phi_t^*(f)(p) = f(\phi_t(p))$  (pullback). Now differentiate:

$$\left. \frac{d}{dt} \phi_t^*(f)(p) \right|_{t=0} = \left. \frac{d}{dt} f(\phi_t(p)) \right|_{t=0} = X(f)(p)$$

So  $(\mathcal{L}_X f)(p) = X(f)(p) = df(X_p)$ . So  $\mathcal{L}_X f$  is again a function on  $M$ .

Recall: A 1-form  $\alpha$  is an assignment to each  $p \in M$ , an element  $\alpha_p \in T_p^*M$ . I.e.  $\alpha$  is a section of the cotangent bundle. In local coordinates, we can write  $\alpha = \sum \alpha_i dx^i$ , for  $\alpha_i \in C^\infty(U)$ .

**Ex:** 1-forms can be pulled back by any  $F$ , by  $F^*(\alpha)(v) = \alpha(F_{*,\cdot}(v))$ . So

$$(\mathcal{L}_X \alpha)(p) = \left. \frac{d}{dt} \underbrace{\phi_t^* \alpha_{\phi_t(p)}}_{\substack{\in T_p^*M \\ \text{for each } t}} \right|_{t=0}$$

Thus,  $\mathcal{L}_X \alpha$  is again a 1-form on  $M$ .

Special case:  $\alpha = df$  for some  $f \in C^\infty(M)$ . Then by the chain rule (1)

$$F^*(df)(v) = df(F_{*,\cdot}(v)) \stackrel{(1)}{=} d(f \circ F)(v) = d(F^*f)(v)$$

so  $F^*(df) = d(F^*f)$ .

So, in general,

$$\mathcal{L}_X(df) = \left. \frac{d}{dt} \phi_t^*(df) \right|_{t=0} = \left. \frac{d}{dt} d\phi_t^*(f) \right|_{t=0} \stackrel{(1)}{=} d \left( \left. \frac{d}{dt} \phi_t^* f \right|_{t=0} \right) = d(df(X)) = d(X(f))$$

Where (1) is true because  $\frac{d^2}{\partial t \partial x^i} = \frac{\partial^2}{\partial i \partial t}$ , so the differentiations commute.

In fact, in general,  $\mathcal{L}_X(\alpha) = d(\alpha(X)) + \dots$  (we'll fill in the other term later).

Now, back to vector fields...

Note: Vector fields can be pulled back by diffeomorphisms. This means if  $X, Y \in \mathfrak{X}(M)$ ,  $\mathcal{L}_X Y$  is defined by,  $\forall p \in M$ ,

$$\mathcal{L}_X(Y)(p) = \left. \frac{d}{dt} \underbrace{[(\phi_t)_*, p]^{-1}(Y_{\phi_t(p)})}_{=V_t \in T_p M} \right|_{t=0}$$

**Prop:**  $\mathcal{L}_X Y = [X, Y]$ .

Proof: Compute  $V_t$  in coordinates  $(U, (x^1, \dots, x^n))$ . Restrict to  $V \subseteq U$  such that  $\phi_t(V) \subseteq U$ . Write  $\phi_t = (\phi_t^1, \dots, \phi_t^n)$ . Then

$$J_t = \left( \frac{\partial \phi_t^i}{\partial x^j}(p) \right)_{(i,j)} \quad Y = \sum_{i=1}^n g_i \frac{\partial}{\partial x^i} \quad X = \sum_{i=1}^n f_i \frac{\partial}{\partial x^i}$$

For a fixed  $p$ , let

$$\tilde{Y}_t = Y_{\phi_t(p)} = \begin{pmatrix} g_1(\phi_t(p)) \\ \vdots \\ g_n(\phi_t(p)) \end{pmatrix}$$

Then, let  $\tilde{V}_t$  be the column vector with components of  $V_t$ . We have

$$\tilde{V}_t = J_t^{-1} \tilde{Y}_t$$

Differentiating with  $\frac{d}{dt}$  on both sides, we get

$$\dot{\tilde{V}}_t = J_t^{-1} \dot{\tilde{Y}}_t - J_t^{-1} \dot{J}_t J_t^{-1} \tilde{Y}_t$$

which at  $t = 0$ , yields

$$\underbrace{\dot{\tilde{V}}_t \Big|_{t=0}}_{\substack{\text{components} \\ \text{of } \mathcal{L}_X Y}} = \begin{pmatrix} X(g_1)(p) \\ \vdots \\ X(g_n)(p) \end{pmatrix} - ?$$

Well,

$$\dot{J}_t = \left( \frac{\partial^2 \phi_t^i}{\partial t \partial x^j}(p) \right)_{(i,j)} = \left( \frac{\partial^2 \phi_t^i}{\partial x^j \partial t}(p) \right)_{(i,j)} = \left( \frac{\partial f_i}{\partial x^j}(p) \right)_{(i,j)}$$

since  $\frac{\partial \phi_t^i}{\partial t}(p) = f_i$ . Thus, we have

$$\dot{\tilde{V}}_t \Big|_{t=0} = \begin{pmatrix} X(g_1)(p) \\ \vdots \\ X(g_n)(p) \end{pmatrix} - \left( \frac{\partial f_i}{\partial x^j}(p) \right)_{(i,j)} \begin{pmatrix} g_1(p) \\ \vdots \\ g_n(p) \end{pmatrix}$$

Therefore,

$$\begin{aligned} \mathcal{L}_X Y &= \sum_{i=1}^n X(g_i) \frac{\partial}{\partial x^i} - \sum_{i,j=1}^n \frac{\partial f_i}{\partial x^j} g_j \frac{\partial}{\partial x^i} \\ &= \sum_{i=1}^n X(g_i) \frac{\partial}{\partial x^i} - \sum_{i=1}^n Y(f_i) \frac{\partial}{\partial x^i} \\ &= \sum_{i=1}^n (X(g_i) - Y(f_i)) \frac{\partial}{\partial x^i} \\ &= [X, Y] \end{aligned}$$

□

**Thm:** Using the same notation as last time,  $\forall t \in (-\varepsilon, \varepsilon)$ ,  $V_t = \frac{d}{dt}(\phi_{t,*})^{-1}(Y_{\phi_t}(p)) = (\phi_{t,*})^{-1}[X, Y]_{\phi_t(p)}$ .

Proof: We already have it for  $t = 0$ . Now, consider  $V_{t+s}$ , and use the group law/translation lemma. □

**Cor:** If  $[X, Y] = 0$ , then the flows of  $X$  and  $Y$  commute.