

# Math 591 Lecture 35

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Final remarks on orientation:

Recall: If  $M$  is oriented,  $\exists \{(U_\alpha, \varphi_\alpha)\}$ , a positive atlas of  $M$ . This means all transition functions  $\varphi_\beta \circ \varphi_\alpha^{-1}$  have the determinant of their Jacobian positive at every point, and the coordinate frames are positive.

Conversely, if  $M$  is an atlas satisfying the above property, then one can define an orientation of  $M$  by requiring the coordinate frames are positive.

In general, to show a manifold is orientable, exhibit such an atlas.

**Ex:** Check: The atlas of  $\mathbb{RP}^n$  used in homework has this condition, so it is orientable.

Observe: If  $S \subset M$  is a codim-1 submanifold, and  $M$  is oriented, and there exists a continuous field of normal vectors on  $S$ ,

$$S \ni p \mapsto \vec{n}_p \in T_p M \quad \text{s.t.} \quad T_p M = T_p S \oplus \mathbb{R} \vec{n}_p$$

then  $S$  is orientable, and the convention for its orientation is: a basis  $\{b_1, \dots, b_{n-1}\}$  of  $T_p S$  is positive iff  $\{\vec{n}_p, b_1, \dots, b_{n-1}\}$  is positive w.r.t.  $M$ .

*TL;DR, put the normal vector first.*

**Ex:** We can embed the Klein bottle in a dim-3 manifold  $M$  s.t. there exists a continuous  $\vec{n}$ , but  $M$  is non-orientable.

## Partitions of Unity

This is a very technical, but very useful tool. We begin with point-set topology.

**Defn:** An indexed covering (not necessarily open)  $\{S_\alpha\}_{\alpha \in A}$  of (a manifold)  $M$  (doesn't have to be a manifold) (with  $S_\alpha \subset M$ ) is said to be locally finite iff every  $p \in M$  has a neighborhood  $U$  s.t.  $\{\alpha \in A \mid S_\alpha \cap U \neq \emptyset\}$  is finite. That is, every  $p$  is in only finitely-many  $S_\alpha$ .

**Thm:** (Thm 1.15 in Lee) Any topological manifold is paracompact: every open cover  $\{U_\alpha\}_{\alpha \in A}$  has a countable, locally-finite refinement  $\{V_i\}_{i \in \mathbb{N}}$ . That is,  $\forall i \in \mathbb{N}$ ,  $V_i$  is open, and  $\exists \alpha \in A$  s.t.  $V_i \subset U_\alpha$  and  $M$  is covered by  $\{V_i\}_{i \in \mathbb{N}}$ .

Proof: This proof is long and complex, but it only uses point-set topology. This is the first time we're using the fact that  $M$  is second-countable!

Observe: If  $\mathcal{B}$  is any basis of  $M$ , the  $V_i$  can be chosen to be in  $\mathcal{B}$ .

**Defn:** Let  $M$  be a smooth manifold. A partition of unity on  $M$  is an indexed family  $\{\chi_\alpha\}_{\alpha \in A}$  of  $C^\infty$  functions on  $M$  s.t.

- (1)  $\{\text{supp}(\chi_\alpha)\}_{\alpha \in A}$  is a locally finite cover of  $M$ .
- (2)  $\forall p \in M$ ,  $\sum_{\alpha \in A} \chi_\alpha(p) = 1 \in \mathbb{R}$ . (Note that this is a finite sum by (1).)

**Thm:** Let  $\{U_\alpha\}_{\alpha \in A}$  be an open cover of  $M$ . Then  $\exists \{\chi_\alpha\}_{\alpha \in A}$ , a partition of unity, that is subordinate to  $\{U_\alpha\}_{\alpha \in A}$ , i.e.,  $\forall \alpha \in A$ ,  $\text{supp } \chi_\alpha \subseteq U_\alpha$ .

Proof: We'll use paracompactness. (It may be easier to start by just thinking of a compact manifold.)

Let  $\mathcal{B}$  be the set of normal coordinate balls in  $M$ ; we define  $B \subset M$  to be a normal coordinate ball in  $M$  iff there's a chart  $(U, \phi)$  s.t.  $\overline{B} \subset U$  and  $\phi(B) = B_r(0) \subset \mathbb{R}^n$ , the ball of radius  $r$  centered at 0 in  $\mathbb{R}^n$ , and also  $\exists r' > r$  s.t.  $\overline{B_{r'}(0)} \subset \phi(U)$ .

We claim that  $\mathcal{B}$  is a basis of the topology of  $M$ . Let  $\{U_\alpha\}_{\alpha \in A}$  be any open cover. Use the theorem on paracompactness:  $\exists \{B_i\}_{i \in \mathbb{N}}$ , a locally-finite refinement, and  $\forall i \in \mathbb{N}$ ,  $B_i$  is a normal coordinate ball.  $\forall i \in \mathbb{N}$ , let

$$\phi_i(B_i) = B_{r_i}(0) \subset \overline{B_{r_i}(0)} \subset B_{r'_i}(0)$$

and  $H_i$  be a function on  $\text{Im}(\phi_i)$  such that  $H_i : \text{Im}(\phi_i) \rightarrow \mathbb{R}$  is smooth, with

- $H_i > 0$  on  $B_{r_i}(0)$
- $H_i = 0$  on  $\overline{B_{r_i}(0)}^c$

Thus,  $\text{supp } H_i = \overline{B_{r_i}(0)}$ .

Define  $\psi_i \in C^\infty(M)$  by  $\psi_i = H_i \circ \phi_i$  on  $\text{dom } \phi_i$ , and 0 everywhere else. Then  $\text{supp } \psi_i = \overline{B_i} \subset M$ . We claim that  $\{\overline{B_i}\}_{i \in \mathbb{N}}$ . Observe that  $\forall p$ ,  $\sum_{i \in \mathbb{N}} \psi_i(p) > 0$ , because  $\{B_i\}_{i \in \mathbb{N}}$  forms a cover of  $M$ , and  $\psi_i|_{B_i} > 0$ .

Now, define

$$f_i = \frac{1}{\sum_{j \in \mathbb{N}} \psi_j} \psi_i$$

so that  $\{\text{supp } f_i\}_{i \in \mathbb{N}} = \{\overline{B_i}\}$  is locally finite, and  $\sum_{i \in \mathbb{N}} f_i = 1$ ,  $\forall p \in M$ . Then, we just have to fix it so that the indexing sets are the same as  $\{U_\alpha\}_{\alpha \in A}$  by  $\forall i \in \mathbb{N}$ , pick  $\alpha(i) \in A$  such that  $B_i \subset U_{\alpha(i)}$  and  $\forall \alpha \in A$ , let

$$\chi_\alpha = \sum_{\substack{i \text{ s.t.} \\ \alpha(i) = \alpha}} f_i$$

(Note that  $\chi_\alpha = 0$  if the sum is empty.)

We claim that  $\{\text{supp } \chi_{\alpha(i)}\}_{i \in \mathbb{N}}$  is still locally finite. This follows from  $\{\text{supp } f_i\}_{i \in \mathbb{N}}$  being locally finite.  $\square$

There are many applications of partitions of unity!

**Ex:** Existence of  $C^\infty$  sections of any vector bundle.

Say  $E \rightarrow M$  is a vector bundle of rank  $r$ . Then there exist  $\{(U_\alpha, f_\alpha)\}$  local trivializations:

$$\begin{array}{ccc} \pi^{-1}(U_\alpha) & \xrightarrow{f_\alpha} & U_\alpha \times \mathbb{R}^n \\ \uparrow & \searrow & \swarrow \\ & U_\alpha & \end{array} \quad \begin{array}{c} s_\alpha \\ \text{pick any section } s \end{array}$$

Let  $\{\chi_\alpha\}$  be a partition of unity on  $M$  subordinate to  $\{U_\alpha\}$ . Then let  $s = \sum_{\alpha \in A} \chi_\alpha \cdot s_\alpha$  (we interpret  $\chi_\alpha \cdot s_\alpha$  as a  $C^\infty$  section on  $M$ ).

The main application of partitions of unity is integrating forms.

**Defn:** Let  $M$  be an oriented  $n$ -dimensional manifold. Let  $\mu \in \Omega_0^n(M)$  be a top degree form with compact support. Let  $\{\phi_\alpha\}$  be a positive atlas, and  $\{\chi_\alpha\}$  a subordinate partition of unity (i.e.  $\text{supp } \chi_\alpha \subseteq \text{supp } \phi_\alpha$ ,  $\forall \alpha$ ). Then we define

$$\int_M \mu = \sum_\alpha \int (\phi_\alpha^{-1})^* (\chi_\alpha \mu)$$

We have to check that the right hand side is independent of choice of coordinates. We'll do this next time...