

Math 635 Lecture 33

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Today, we'll take the first step towards proving Gauss-Bonnet. Let $M \subseteq \mathbb{R}^{n+1}$ be a compact, oriented manifold of even dimension $\dim M = n = 2m$, with $N : M \rightarrow S^n$ given by the orientation. Define the Gaussian curvature $\mathcal{K} : M \rightarrow \mathbb{R}$ by $\mathcal{K} dV_M = N^* dV_{S^n}$.

Thm: \mathcal{K} is intrinsic to the Riemannian metric of N .

Recall the Weingarten formula: $\forall p \in M$, we have the commutative diagram

$$\begin{array}{ccc} T_p M & \xrightarrow{-dN} & T_{N(p)} S^n \\ & \searrow S_{N(p)} & \uparrow \mathbb{I} \\ & & T_p M \end{array}$$

where $T_{N(p)} S^n \cong T_p M$ isometrically by translation. S_{N_p} is the shape operator by the Weingarten formula, so

$$\mathcal{K} dV_M|_p = S_{N(p)}^* dV_M|_p \quad \Rightarrow \quad \mathcal{K} = \det S_{N(p)} = \prod_{i=1}^n \kappa_i$$

To prove this, we use orthonormal moving frames on M . Let (E_1, \dots, E_n) be a positive orthonormal moving frame. We get the curvature matrix (Ω_j^i) , a matrix of 2-forms.

$$\forall X, Y \in \mathfrak{X}(M), \quad R(X, Y)(E_j) = \Omega_j^i(X, Y)E_i \quad \Rightarrow \quad \Omega_j^i(X, Y) = R(X, Y, E_j, E_i)$$

Also, we have Gauss' formula:

$$0 = R(W, X, Y, Z) + \langle B(W, Y), B(X, Z) \rangle - \langle B(W, Z), B(X, Y) \rangle$$

So

$$\Omega_j^i(E_k, E_\ell) = \langle B(E_i, E_k), B(E_j, E_\ell) \rangle - \langle B(E_i, E_\ell), B(E_j, E_k) \rangle$$

Recall: $S_{ki} = S_{ik} \stackrel{\text{def}}{=} \langle S(E_i), E_k \rangle = \langle B(E_i, E_k), N \rangle$ is the N -component of $B(E_i, E_k)$ (S_{ij}) is the matrix of S . Written all together, we have

$$\Omega_j^i(E_k, E_\ell) = S_{ik} S_{j\ell} - S_{i\ell} S_{jk}$$

Prop: Let $n = 2m$. Then with σ_n the symmetric group,

$$\mathcal{K} dV = \frac{1}{n!} \sum_{\alpha \in \sigma_n} (-1)^\alpha \bigwedge_{i=1}^m \Omega_{\alpha(2i)}^{\alpha(2i-1)} \stackrel{\text{def}}{=} \text{Pf}(\Omega)$$

Defn: $\text{Pf}(\Omega)$ is called the Pfaffian of Ω .

We'll prove that the Pfaffian is independent of choice of moving frame. It's enough to show $\text{Pf}(\Omega)(E_1, \dots, E_n) = \mathcal{K}$. Well, we introduce

$$Q = \{\varphi \in \sigma_n \mid \forall i \in \{1, \dots, n\}, \varphi(2i-1), \varphi(2i) \in \{2i-1, 2i\}\}$$

We then begin to compute

$$\begin{aligned} \text{Pf}(\Omega)(E_1, \dots, E_n) &= \frac{1}{n! 2^m} \sum_{\alpha, \beta \in \sigma_n} (-1)^\alpha (-1)^\beta \prod_{i=1}^m \Omega_{\alpha(2i)}^{\alpha(2i-1)}(E_{\beta(2i-1)}, E_{\beta(2i)}) \\ &= \frac{1}{n! 2^m} \sum_{\alpha, \beta \in \sigma_n} (-1)^\alpha (-1)^\beta \sum_{\varphi \in Q} (-1)^\varphi \prod_{i=1}^m S_{\alpha(2i-1)\beta\varphi(2i-1)} S_{\alpha(2i)\beta\varphi(2i)} \\ &= \frac{1}{n! 2^m} \sum_{\varphi \in Q} \sum_{\alpha, \beta \in \sigma_n} (-1)^\alpha (-1)^\beta (-1)^\varphi \prod_{i=1}^m S_{\alpha(2i-1)\beta\varphi(2i-1)} S_{\alpha(2i)\beta\varphi(2i)} \end{aligned}$$

Eventually, this computation will give us $\det S$.

Defn: (Official definition) For $X = (x_j^i)$ an $n \times n$ matrix of commuting variables (with $n = 2m$ even), we define the Pfaffian

$$\text{Pf}(X) = \frac{1}{n!} \sum_{\alpha \in \sigma_n} (-1)^\alpha \prod_{i=1}^m X_{\alpha(2i)}^{\alpha(2i-1)}$$

Lemma: $\forall X, Y, \text{Pf}(Y^T X Y) = \det(Y) \text{Pf}(X)$.

Proof: Just another direct computation.

Now, go back to moving frames and curvature matrices. Considering local frames, write $E_i = a_i^j F_j$ on $U \subseteq M$. Then $A(p) = (a_i^j(p)) \in \text{SO}(n)$, and we know that $\Omega_F = A^{-1} \Omega_E A$. So $\text{Pf}(\Omega_F) = \det(A) \text{Pf}(\Omega_E) = \text{Pf}(\Omega_E)$.

Thus, $\text{Pf}(\Omega_F) = \text{Pf}(\Omega_E)$. So by the usual arguments, there's a unique global top-degree form on M such that for any moving frame on U , it agrees with $\text{Pf}(\Omega)$. Therefore, by our proposition, $\mathcal{K} dV$ is of that form. \square

Question: Are there other combinations of the Ω_j^i 's that give global forms on M ? We need some polynomial $P : \text{so}(n) \rightarrow \mathbb{R}$ such that $\forall A \in \text{SO}(n), \forall X \in \text{so}(n), P(A^{-1} X A) = P(X)$. Given such a P , repeat the previous argument to show that there's a global form ϖ such that on any U with a moving frame E_1, \dots, E_n , $\varpi|_U = P(\Omega)$.

$P(\Omega_E) = P(\Omega_F)$, so $dP(\Omega) = 0$ always ($\forall P$ invariant). We get the Chern-Weil morphism:

$$\{\text{Ad-invariant polynomials on } \text{so}(n)\} \rightarrow H^* M$$