

Math 635 Lecture 35

Professor Alejandro Uribe-Ahumada

Transcribed by Thomas Cohn

4/12/21

Degree Theory

Given $F : M_1 \rightarrow M_2$, where M_1 and M_2 are compact, connected, oriented manifolds of dimension $n = \dim M_1 = \dim M_2$. Then $\exists \deg(F) \in \mathbb{Z}$ such that

- a) $F^* : H^n(M_2) \rightarrow H^n(M_1)$ is “multiplication by $\deg F$ ”.
- b) $\forall \alpha \in \Omega^n(M_2)$, $\int_{M_1} F^* \alpha = \deg(F) \int_{M_2} \alpha$.
- c) If $q \in M_2$ is a regular value of F , so $F^{-1}(q) = \bigcup_{i=1}^N \{p_i\}$, then $\deg(F) = \sum_{i=1}^N (-1)^{p_i}$, where

$$(-1)^{p_i} = \begin{cases} 1 & dF_p \text{ preserves orientation} \\ -1 & \text{otherwise} \end{cases}$$

Application:

Thm: If $M_1 = \partial W$, and $f : M_1 \rightarrow M_2$ extends to a smooth function $\tilde{F} : W \rightarrow M_2$, then $\deg(F) = 0$.

$$\begin{array}{ccc} M_1 & \xrightarrow{F} & M_2 \\ \iota \downarrow & \nearrow \tilde{F} & \\ W & & \end{array}$$

Proof: Let $\alpha \in \Omega^p(M_2)$. Then

$$\int_{M_1} F^* \alpha = \int_{M_1} \iota^* \tilde{F}^* \alpha \stackrel{(1)}{=} \int_W d\tilde{F}^* \alpha = \int_W \tilde{F}^* d\alpha = 0$$

because α is a top-degree form, and (1) because of Stokes' theorem. \square

Cor: There is no C^∞ map $\overline{B}^n \rightarrow S^n$ (where \overline{B}^n is the closed unit ball in \mathbb{R}^n) which is the identity on $S^n = \partial \overline{B}^n$.

Proof: $\deg(I_{S^n}) = 1 \neq 0$. \square

(We presented some examples of Gauss-Bonnet and degree theory, but I'm not yet talented enough with TikZ to reproduce them.)

The Laplacian and Hodge Theory

Let (M, g) be a Riemannian manifold.

Defn: The gradient is

$$\begin{aligned} \nabla : C^\infty(M) &\rightarrow \mathfrak{X}(M) \\ f &\mapsto \nabla f \end{aligned}$$

where ∇f is metric-dual to df . That is, $\forall v \in T_p M$, $\langle \nabla f(p), v \rangle = df_p(v)$.

∇ has a product rule: $\nabla(fg) = f\nabla g + g\nabla f$.

Defn: The divergence $\operatorname{div} : \mathfrak{X}(M) \rightarrow C^\infty(M)$ is defined by $\forall X \in \mathfrak{X}(M)$, $\mathcal{L}_X \operatorname{Vol} = (\operatorname{div} X) \operatorname{Vol}$, where $\operatorname{Vol} \in \Omega^n(M)$ is a volume form.

Observe: This is really a local definition, and div is independent of orientation.

Properties:

- (a) In coordinate, $X = f^i \frac{\partial}{\partial x^i}$, then $\text{div } X = \frac{1}{\sqrt{g}} \frac{\partial}{\partial x^i} (\sqrt{g} f^i)$. (Note: we're using the shorthand $\sqrt{g} = \sqrt{\det(g_{ij})}$).
- (b) $\text{div}(fX) = f \text{div } X + X(f)$.
- (c) $(\text{div } X)(p) = \text{tr}(T_p M \ni v \mapsto (\nabla_v X)(p) \in T_p M)$.

Thm: (Divergence Theorem) Let M be a manifold-with-boundary, with the boundary ∂M oriented by ν , an outward point unit normal vector field so that $\text{Vol}_{\partial M} = \iota_\nu \text{Vol}_M$. Then $\forall X \in \mathfrak{X}(M)$,

$$\int_M (\text{div } X) \text{Vol}_M = \int_{\partial M} \langle X, \nu \rangle \text{Vol}_{\partial M}$$

The right-hand side is the flux of X out of M .

Cor: $(\text{div } X)(p) = \lim_{\varepsilon \searrow 0} \frac{1}{\text{Vol } B_\varepsilon(p)} \int_{B_\varepsilon(p)} (\text{div } X) d\text{Vol}_M \stackrel{\text{Thm}}{=} \lim_{\varepsilon \searrow 0} \frac{1}{\text{Vol } B_\varepsilon(p)} \int_{S_\varepsilon(p)} \langle X, \nu \rangle \text{Vol}_{S_\varepsilon(p)}$
“(div X)(p) is the infinitesimal flux per unit volume at p .”

Observe: If $\partial M = \emptyset$, then we get $\int_M (\text{div } X) \text{Vol}_M = 0$. Proof: The left-hand side is simply

$$\int_M \mathcal{L}_X \text{Vol}_M = \int_M d(\iota_X \text{Vol}_M) = \int_{\partial M} j^*(\iota_X \text{Vol}_M)$$

where $j : \partial M \hookrightarrow M$. Then, we check that $j^*(\iota_X \text{Vol}_M) = \langle X, \nu \rangle \text{Vol}_{\partial M}$. Use that $X = \langle X, \nu \rangle + \eta$, where η is tangent to ∂M . \square

Defn: The laplacian on functions is

$$\begin{aligned} \Delta : C^\infty(M) &\rightarrow C^\infty(M) \\ f &\mapsto \Delta f = -\text{div}(\nabla f) \end{aligned}$$

Note that some people don't use the negative sign.

Combining the previous formulas, in coordinates, we get

$$\begin{aligned} \Delta f &= -\frac{1}{\sqrt{g}} \frac{\partial}{\partial x^i} \left(\sqrt{g} g^{ij} \frac{\partial f}{\partial x^j} \right) \\ &= -\frac{1}{\sqrt{g}} \left(\sqrt{g} g^{ij} \frac{\partial^2 f}{\partial x^i \partial x^j} + \text{lower order terms} \right) \\ &= -g^{ij} \frac{\partial^2 f}{\partial x^i \partial x^j} + \text{lower order terms} \end{aligned}$$

So the highest order term only depend on the metric, not derivatives of the metric.

Next time, we'll consider the following commutative diagram:

$$\begin{array}{ccc} C^\infty(M) & \xrightleftharpoons[\text{-div}]{\nabla} & \mathfrak{X}(M) \\ \parallel & & \parallel \text{ metric dual} \\ C^\infty(M) & \xrightleftharpoons[\delta]{d} & \Omega^1(M) \end{array}$$

We'll see that $\delta = d^*$ (the adjoint) if we use ℓ^2 inner products on $C^\infty(M)$ and $\Omega^1(M)$. On functions, $\Delta = \delta d = d^* d$.