Math 635 Lecture 14

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Hamiltonian Formulation of Geodesic Flow

Defn: A symplectic manifold is a pair (X, ω) where ω is a 2-form on X s.t. $d\omega = 0$ and ω is pointwise non-denerate: $\forall m \in X$, the map

$$\omega_m^{\sharp}: T_m X \to T_m^* X$$

$$v \mapsto -\omega_m(\cdot, v)$$

is an isomorphism.

Note: This implies the dimension of X is even, since skew symmetric forms on odd dimensional spaces are singular.

Ex: Let $X = \mathbb{R}^{2n}$, with coordinates $(x^1, \dots, x^n, p_1, \dots, p_n)$. Then $\omega = \sum_i dp_i \wedge dx^i$, as a matrix, is $\begin{pmatrix} 0 & I_n \\ -I_n & 0 \end{pmatrix}$.

We will see, $\forall M$ smooth manifolds, that $X = T^*M$ is naturally a symplectic manifold. And on symplectic manifolds, we can define Hamiltonian dynamics.

Defn: Given $H \in C^{\infty}(X)$, where (X, ω) is a symplectic manifold, the <u>Hamilton field</u> of $H, \Xi_H \in \mathfrak{X}(X)$, is defined by the condition that $-\iota_{\Xi_H} = \omega(\cdot, \Xi_H) = dH$. Existence is guaranteed by the non-degeneracy of ω .

We want to compute a local formula: In \mathbb{R}^{2n} , $H:\mathbb{R}^{2n}\to\mathbb{R}$. Then $\Xi_H=\frac{\partial H}{\partial p_i}\frac{\partial}{\partial x^i}-\frac{\partial H}{\partial x^i}\frac{\partial}{\partial p_i}$. The flow/trajectory of Ξ_H are

$$\left\{ \begin{array}{l} \dot{x}^i(t) = \frac{\partial H}{\partial p_i}(x(t),p(t)) \\ \dot{p}_i(t) = -\frac{\partial H}{\partial x^i}(x(t),p(t)) \end{array} \right.$$

These are Hamilton's equations.

Exer: $H = \frac{1}{2m} ||p||^2 + V(x)$ is Newton's second law, $\ddot{x} = -\nabla V$.

Properties of Hamiltonian flows (i.e. flows of Ξ_H):

- (a) $\Xi_H(H) = 0$, i.e., H is constant along trajectories of Ξ_H . Proof: $\Xi_H(H) = dH(\Xi_H) = \omega(\Xi_H, \Xi_H) = 0$ by antisymmetry. \square
- (b) $\mathcal{L}_{\Xi_H}\omega = 0$. Proof: Use Cartan's formula. $\mathcal{L}_{\Xi_H}\omega = \iota_{\Xi_H}\underbrace{d\omega}_{=0} + d(\underbrace{\iota_{\Xi_H}\omega}) = -d^2H = 0$. \square

Volume elements (Liouville)

On any symplectic manifold (X, ω) , the form $\frac{\omega^n}{n!}$ is a volume form.

Ex: In \mathbb{R}^{2n} , $\frac{\omega^n}{n!} = dp_1 \wedge dx^1 \wedge dp_2 \wedge dx^2 \wedge \cdots \wedge dp_n \wedge dx^n$.

If we're given a Hamiltonian $H \in C^{\infty}(X)$, and $c \in \mathbb{R}$ is a regular value of H, then let $\Sigma = H^{-1}(c) \hookrightarrow X$, a codim-1 submanifold. We claim that $\exists ! \lambda \in \Omega^{2n-1}(X)$ s.t. in a neighborhood of Σ , $\frac{\omega^n}{n!} = \lambda \wedge dH$, and $\iota^*(\omega)$ is unique. This is a volume form on Σ .

Cor: The Hamilton flow of H preserves $\frac{\omega^n}{n!}$, and its restriction to any regular level set $H^{-1}(c)$ preserves the Liouville measure on that level set.

$$\phi_t^* \left(\frac{\omega^n}{n!} \right) = \frac{\omega^n}{n!}; \qquad \left(\phi_t |_{H^{-1}(c)} \right)^* (\iota^* \lambda) = (\iota^* \lambda)$$

Symmetries

Question: Given $H, G \in C^{\infty}(X)$, the Hamiltonian flows of H and G commute iff $[\Xi_G, \Xi_H] = 0$, which is true iff Ξ_H is ϕ_t^G -related to itself.

Lemma: For X connected, this is equivalent to $(\phi_t^G)^*dH = dH$.

Proof:

$$\begin{split} (\phi_t^G)^*dH &= dH \Leftrightarrow \mathcal{L}_{\Xi_G}(dH) = 0 \\ &\Leftrightarrow \mathcal{L}_{\Xi_G}d^2\mathcal{H} + d(\iota_{\Xi_G}dH) = dH(\Xi_G) = 0 \\ &\Leftrightarrow d(dH(\Xi_G)) = 0 \\ &\Leftrightarrow dH(\Xi_G) = \Xi_G(H) \text{ is locally constant} \\ &\Leftrightarrow \Xi_G(H) \text{ is constant (because X is connected)} \end{split}$$

This is a symmetric condition:

$$dH(\Xi_G) = \omega(\Xi_G, \Xi_H) = -\omega(\Xi_H, \Xi_G) = -dG(\Xi_H)$$

So we conclude that the flows of Ξ_H and Ξ_G commute iff H is constant along the trajectories of G iff G is constant along the trajectories of H. \square

The main example of (X, ω) is T^*M , for some arbitrary smooth manifold M.

Prop: For an arbitrary smooth manifold M, T^*M has a natural symplectic structure.

Proof: We'll show that T^*M has a natural, "tautological" 1-form, α , which is sometimes called a Liouville form, defined by:

For
$$(x,\xi) \in T^*M$$
, $x \in M$, $\xi \in T_x^*M$, let $v \in T_{(x,\xi)}(T^*M)$. Then $\alpha_{(x,\xi)}(v) = \underbrace{\xi(\underline{\pi_*(v)})}_{\in T_xM}$. In coordinates, say we have

 $(x^1,\ldots,x^n) \text{ on } U \subset M, \text{ and } (x^1,\ldots,x^n,p_1,\ldots,p_n) \text{ on } T*U. \text{ Then } \xi = p_i(\xi)dx^i, \text{ so } v = a^i\frac{\partial}{\partial x^i} + b_i\frac{\partial}{\partial p_i}. \ \pi_*(v) = a^i\frac{\partial}{\partial x^i}.$ $\xi(\pi_*(v)) = p_i(\xi)a^i. \text{ Altogether, } \alpha = p_idx^i, \text{ and } \omega + d\alpha = dp_i \wedge dx^i, \text{ just as in } \mathbb{R}^{2n}.$