

Thomas Cohn

✉ tcohn@mit.edu | 🏠 tommycohn.com

Education

Massachusetts Institute of Technology

Ph.D. in Computer Science and Engineering

- Advisor: Russ Tedrake
- GPA 5.00/5.00

Cambridge, Massachusetts

Sep. 2022 - Present

University of Michigan

B.S.E. Computer Science and Engineering
B.S. Honors Mathematics

- Magna Cum Laude
- Engineering Honors Program
- Minors in Statistics and Music
- GPA 3.74/4.00

Ann Arbor, Michigan

Sep. 2017 - May 2022

Honors and Awards

- 2024 **Best Paper Award in Robot Manipulation Finalist**, ICRA
- 2023 **Best Paper Award Finalist**, RSS
- 2022 **Outstanding Undergraduate Research Award**, University of Michigan
- 2021 **1st Place Award**, University of Michigan Engineering Research Symposium

Publications

Conference Publications

- [C2] **Thomas Cohn**, Mark Petersen, Max Simchowitz, and Russ Tedrake. “Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets”. In: *Proceedings of Robotics: Science and Systems*. Daegu, Republic of Korea, 2023. **Best Paper Award Finalist**.
- [C1] **Thomas Cohn**, Nikhil Devraj, and Odest Chadwicke Jenkins. “Topologically-informed atlas learning”. In: *2022 International Conference on Robotics and Automation (ICRA)*. IEEE. 2022, pp. 3598–3604.

Journal Publications

- [J1] **Thomas Cohn**, Odest Chadwicke Jenkins, Karthik Desingh, and Zhen Zeng. “TSBP: Tangent Space Belief Propagation for Manifold Learning”. In: *IEEE Robotics and Automation Letters* 5.4 (2020), pp. 6694–6701.

Preprints

- [P1] **Thomas Cohn**, Seiji Shaw, Max Simchowitz, and Russ Tedrake. “Constrained Bimanual Planning with Analytic Inverse Kinematics”. In: *arXiv preprint arXiv:2309.08770* (2023). **Accepted to ICRA 2024. Best Paper in Robot Manipulation Award Finalist**.

Presentations

- 2023 **Poster Presentation**, “Constrained Bimanual Planning with Analytic Inverse Kinematics”
Northeast Robotics Colloquium 2023
- 2023 **Paper Presentation**, “Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets”
RSS 2023
- 2022 **Paper Presentation**, “Topologically-Informed Atlas Learning”
ICRA 2022
- 2021 **Poster Presentation**, “Topologically-Informed Atlas Learning”
University of Michigan Engineering Research Symposium – 1st Place Award
- 2021 **Poster Presentation**, “Coordinate Chart Particle Filter for Deformable Object Pose Estimation”
University of Michigan Engineering Research Symposium
- 2020 **Paper Presentation**, “TSBP: Tangent Space Belief Propagation for Manifold Learning”
IROS 2020
- 2019 **Poster Presentation**, “TSBP: Tangent Space Belief Propagation for Manifold Learning”
University of Michigan Engineering Research Symposium

Teaching

2023 (Fall)	6.4210: Robotic Manipulation , Teaching Assistant	<i>Massachusetts Institute of Technology</i>
2022 (Winter)	EECS 367: Introduction to Autonomous Robotics , Teaching Assistant	<i>University of Michigan</i>
2021 (Fall)	ROB 102: Introduction to AI and Programming , Teaching Assistant	<i>University of Michigan</i>
2020 (Winter)	ENGR 100-250: Microprocessors and Toys , Teaching Assistant	<i>University of Michigan</i>
2019 (Winter)	ENGR 100-250: Microprocessors and Toys , Teaching Assistant	<i>University of Michigan</i>

Work Experience

2022-	Graduate Student Research Assistant , Massachusetts Institute of Technology, PI: Russ Tedrake
2016-2022	Undergraduate Student Research Assistant , University of Michigan, PI: Chad Jenkins
2021	Curriculum Designer , Robotics @ Marygrove
2017-2018	Software Developer , Number DNA

Extracurriculars

2017-2022	Michigan Marching Band , Cymbal Section Leader 2019-2022
2017-2022	Michigan Hockey Pep Band
2018-2020	Michigan Percussion Chamber Ensemble