# Thomas Cohn

■ tcohn@mit.edu | ★ tommycohn.com

## Education\_

#### **Massachusetts Institute of Technology**

Ph.D. in Computer Science and Engineering

- · Advisor: Russ Tedrake
- GPA 5.00/5.00

#### **University of Michigan**

B.S.E. Computer Science and Engineering B.S. Honors Mathematics

- · Magna Cum Laude
- Engineering Honors Program
- Minors in Statistics and Music
- GPA 3.74/4.00

Cambridge, Massachusetts

Sep. 2022 - Present

Ann Arbor, Michigan Sep. 2017 - May 2022

## Honors and Awards

- 2023 Best Paper Finalist, RSS
- 2022 Outstanding Undergraduate Research Award, University of Michigan
- 2021 **1st Place Award,** University of Michigan Engineering Research Symposium

#### Publications \_\_\_\_\_

#### Conference Publications

- [C2] Thomas Cohn, Mark Petersen, Max Simchowitz, and Russ Tedrake. "Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets". In: *Proceedings of Robotics: Science and Systems*. Daegu, Republic of Korea, 2023. Best Paper Finalist.
- [C1] **Thomas Cohn**, Nikhil Devraj, and Odest Chadwicke Jenkins. "Topologically-informed atlas learning". In: 2022 International Conference on Robotics and Automation (ICRA). IEEE. 2022, pp. 3598–3604.

## Journal Publications

[J1] **Thomas Cohn**, Odest Chadwicke Jenkins, Karthik Desingh, and Zhen Zeng. "TSBP: Tangent Space Belief Propagation for Manifold Learning". In: *IEEE Robotics and Automation Letters* 5.4 (2020), pp. 6694–6701.

#### **Preprints**

[P1] **Thomas Cohn**, Seiji Shaw, Max Simchowitz, and Russ Tedrake. "Constrained Bimanual Planning with Analytic Inverse Kinematics". In: *arXiv preprint arXiv:2309.08770* (2023). **Accepted to ICRA 2024**.

#### Presentations \_\_\_

- 2023 Poster Presentation, "Constrained Bimanual Planning with Analytic Inverse Kinematics" Northeast Robotics Colloquium 2023
- 2023 Paper Presentation, "Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets" RSS 2023
- 2022 Paper Presentation, "Topologically-Informed Atlas Learning"
- 2021 Poster Presentation, "Topologically-Informed Atlas Learning"
  University of Michigan Engineering Research Symposium 1st Place Award
- 2021 Poster Presentation, "Coordinate Chart Particle Filter for Deformable Object Pose Estimation" University of Michigan Engineering Research Symposium
- 2020 Paper Presentation, "TSBP: Tangent Space Belief Propagation for Manifold Learning" *IROS 2020*
- 2019 Poster Presentation, "TSBP: Tangent Space Belief Propagation for Manifold Learning" University of Michigan Engeineering Research Symposium

# Teaching \_\_\_\_\_

2023 (Fall)	<b>6.4210: Robotic Manipulation</b> , Teaching Assistant	Massachusetts Institute of Technology
2022 (Winter)	EECS 367: Introduction to Autonomous Robotics, Teaching Assistant	University of Michigan
2021 (Fall)	ROB 102: Introduction to AI and Programming, Teaching Assistant	University of Michigan
2020 (Winter)	ENGR 100-250: Microprocessors and Toys, Teaching Assistant	University of Michigan
2019 (Winter)	ENGR 100-250: Microprocessors and Toys, Teaching Assistant	University of Michigan

# Work Experience \_\_\_\_\_

2022- Graduate Student Research Assistant, Massachusetts Institute of Technology, PI: Russ Tedrake

2016-2022 Undergraduate Student Research Assistant, University of Michigan, PI: Chad Jenkins

2021 Curriculum Designer, Robotics @ Marygrove

2017-2018 **Software Developer,** Number DNA

# Extracurriculars \_\_\_\_\_

2017-2022 **Michigan Marching Band**, Cymbal Section Leader 2019-2022

2017-2022 Michigan Hockey Pep Band

2018-2020 Michigan Percussion Chamber Ensemble