

# Thomas Cohn

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## Education

### Massachusetts Institute of Technology

Cambridge, Massachusetts

Ph.D. in Computer Science and Engineering

Sep. 2022 - Present

- Advisor: Russ Tedrake
- GPA 5.00/5.00

S.M. in Electrical Engineering and Computer Science

Sep. 2022 - May 2024

- Advisor: Russ Tedrake
- Thesis Title: [Motion Planning along Manifolds with Geodesic Convexity and Analytic Inverse Kinematics](#)

### University of Michigan

Ann Arbor, Michigan

B.S.E. Computer Science and Engineering

Sep. 2017 - May 2022

B.S. Honors Mathematics

- Magna Cum Laude
- Engineering Honors Program
- Minors in Statistics and Music
- GPA 3.74/4.00

## Honors and Awards

- 2024 **Best Paper Award in Robot Manipulation Finalist**, ICRA
- 2023 **Best Paper Award Finalist**, RSS
- 2022 **Outstanding Undergraduate Research Award**, University of Michigan
- 2021 **1st Place Award**, University of Michigan Engineering Research Symposium

## Publications

### Conference Publications

- [C3] **Thomas Cohn**, Seiji Shaw, Max Simchowitz, and Russ Tedrake. “Constrained bimanual planning with analytic inverse kinematics”. In: *2024 IEEE International Conference on Robotics and Automation (ICRA)*. IEEE. 2024, pp. 6935–6942. **Best Paper in Robot Manipulation Award Finalist**.
- [C2] **Thomas Cohn**, Mark Petersen, Max Simchowitz, and Russ Tedrake. “Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets”. In: *Proceedings of Robotics: Science and Systems*. Daegu, Republic of Korea, July 2023. **Best Paper Award Finalist**.
- [C1] **Thomas Cohn**, Nikhil Devraj, and Odest Chadwicke Jenkins. “Topologically-informed atlas learning”. In: *2022 International Conference on Robotics and Automation (ICRA)*. IEEE. 2022, pp. 3598–3604.

### Journal Publications

- [J1] **Thomas Cohn**, Odest Chadwicke Jenkins, Karthik Desingh, and Zhen Zeng. “TSBP: Tangent Space Belief Propagation for Manifold Learning”. In: *IEEE Robotics and Automation Letters* 5.4 (2020), pp. 6694–6701.

### Preprints

- [P2] Shruti Garg, **Thomas Cohn**, and Russ Tedrake. “Planning Shorter Paths in Graphs of Convex Sets by Undistorting Parametrized Configuration Spaces”. In: *arXiv preprint arXiv:2411.18913* (2024).
- [P1] Peter Werner, Thomas Cohn\*, Rebecca H. Jiang\*, Tim Seyde, Max Simchowitz, Russ Tedrake, and Daniela Rus. “Faster Algorithms for Growing Collision-Free Convex Polytopes in Robot Configuration Space”. In: *arXiv preprint arXiv:2410.12649* (2024). **Accepted for Publication at ISRR 2024. \*Denotes equal contribution.**

## Presentations

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- 2024 **Oral + Poster Presentation**, “Constrained Bimanual Planning with Analytic Inverse Kinematics”  
*ICRA 2024*
- 2023 **Poster Presentation**, “Constrained Bimanual Planning with Analytic Inverse Kinematics”  
*Northeast Robotics Colloquium 2023*
- 2023 **Oral + Poster Presentation**, “Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets”  
*RSS 2023*
- 2022 **Oral + Poster Presentation**, “Topologically-Informed Atlas Learning”  
*ICRA 2022*
- 2021 **Poster Presentation**, “Topologically-Informed Atlas Learning”  
*University of Michigan Engineering Research Symposium – 1st Place Award*
- 2021 **Poster Presentation**, “Coordinate Chart Particle Filter for Deformable Object Pose Estimation”  
*University of Michigan Engineering Research Symposium*
- 2020 **Oral Presentation**, “TSBP: Tangent Space Belief Propagation for Manifold Learning”  
*IROS 2020*
- 2019 **Poster Presentation**, “TSBP: Tangent Space Belief Propagation for Manifold Learning”  
*University of Michigan Engineering Research Symposium*

## Grants and Fellowships

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- 2024 **Graduate Research Fellowship**, National Science Foundation
- 2022 **Frederick and Barbara Cronin Fellowship**, Massachusetts Institute of Technology
- 2020 **Raab Family Scholarship**, University of Michigan Marching Band
- 2019 **Wanda W. Lincoln Scholarship**, University of Michigan Marching Band
- 2017 **The Gloria Wille Bell and Carlos R. Bell Scholarship**
- 2017 **Regents Merit Scholarship**, University of Michigan

## Teaching

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| 2024 (Spring) | <b>CSCI 5551: Introduction to Intelligent Robotic Systems</b> , <a href="#">Guest Lecture</a><br><i>Faculty Instructor: Karthik Desingh</i> | <i>University of Minnesota</i>               |
| 2023 (Fall)   | <b>6.4210: Robotic Manipulation</b> , Teaching Assistant<br><i>Faculty Instructor: Russ Tedrake</i>   | <i>Massachusetts Institute of Technology</i> |
| 2022 (Winter) | <b>EECS 367: Introduction to Autonomous Robotics</b> , Teaching Assistant<br><i>Faculty Instructor: Chad Jenkins</i>                        | <i>University of Michigan</i>                |
| 2021 (Fall)   | <b>ROB 102: Introduction to AI and Programming</b> , Teaching Assistant<br><i>Faculty Instructor: Chad Jenkins</i>                          | <i>University of Michigan</i>                |
| 2020 (Winter) | <b>ENGR 100-250: Microprocessors and Toys</b> , Teaching Assistant<br><i>Faculty Instructor: Peter Chen</i>                                 | <i>University of Michigan</i>                |
| 2019 (Winter) | <b>ENGR 100-250: Microprocessors and Toys</b> , Teaching Assistant<br><i>Faculty Instructor: Peter Chen</i>                                 | <i>University of Michigan</i>                |

## Work Experience

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- 2022-  
2016-2022 **Graduate Student Research Assistant**, Massachusetts Institute of Technology, PI: [Russ Tedrake](#)
- 2021 **Undergraduate Student Research Assistant**, University of Michigan, PI: [Chad Jenkins](#)
- 2021 **Curriculum Designer**, Robotics @ Marygrove
- 2017-2018 **Software Developer**, Number DNA

## Extracurriculars

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- 2022-Present **MIT Graduate Hillel**, President 2024-Present
- 2017-2022 **Michigan Marching Band**, Cymbal Section Leader 2019-2022
- 2017-2022 **Michigan Hockey Pep Band**
- 2018-2020 **Michigan Percussion Chamber Ensemble**

## Service

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- 2024-Present **Reviewer**, ICRA, RA-L
- 2024-Present **Graduate School Application Mentor**, MIT GAAP Program