Thomas Cohn

■ tcohn@mit.edu | ★ tommycohn.com

Education_

Massachusetts Institute of Technology

Ph.D. in Computer Science and Engineering

· Advisor: Russ Tedrake

• GPA 5.00/5.00

University of Michigan

B.S.E. Computer Science and Engineering B.S. Honors Mathematics

- Magna Cum Laude
- Engineering Honors Program
- · Minors in Statistics and Music
- GPA 3.74/4.00

Cambridge, Massachusetts Sep. 2022 - Present

> Ann Arbor, Michigan Sep. 2017 - May 2022

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Honors and Awards _

- 2024 Best Paper Award in Robot Manipulation Finalist, ICRA
- 2023 Best Paper Award Finalist, RSS
- 2022 Outstanding Undergraduate Research Award, University of Michigan
- 2021 1st Place Award, University of Michigan Engineering Research Symposium

Publications_

Conference Publications

- [C2] Thomas Cohn, Mark Petersen, Max Simchowitz, and Russ Tedrake. "Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets". In: *Proceedings of Robotics: Science and Systems*. Daegu, Republic of Korea, 2023. Best Paper Award Finalist.
- [C1] Thomas Cohn, Nikhil Devraj, and Odest Chadwicke Jenkins. "Topologically-informed atlas learning". In: 2022 International Conference on Robotics and Automation (ICRA). IEEE. 2022, pp. 3598–3604.

Journal Publications

[J1] **Thomas Cohn**, Odest Chadwicke Jenkins, Karthik Desingh, and Zhen Zeng. "TSBP: Tangent Space Belief Propagation for Manifold Learning". In: *IEEE Robotics and Automation Letters* 5.4 (2020), pp. 6694–6701.

Preprints

[P1] **Thomas Cohn**, Seiji Shaw, Max Simchowitz, and Russ Tedrake. "Constrained Bimanual Planning with Analytic Inverse Kinematics". In: *arXiv preprint arXiv:2309.08770* (2023). **Accepted to ICRA 2024. Best Paper in Robot Manipulation Award Finalist**.

Presentations_

- Poster Presentation, "Constrained Bimanual Planning with Analytic Inverse Kinematics"
 - Northeast Robotics Colloquium 2023
- 2023 Paper Presentation, "Non-Euclidean Motion Planning with Graphs of Geodesically-Convex Sets"
- 2022 **Paper Presentation,** "Topologically-Informed Atlas Learning"
- Poster Presentation, "Topologically-Informed Atlas Learning"
 - University of Michigan Engineering Research Symposium 1st Place Award
- 2021 Poster Presentation, "Coordinate Chart Particle Filter for Deformable Object Pose Estimation" University of Michigan Engineering Research Symposium
- 2020 Paper Presentation, "TSBP: Tangent Space Belief Propagation for Manifold Learning"
- 2019 Poster Presentation, "TSBP: Tangent Space Belief Propagation for Manifold Learning" University of Michigan Engeineering Research Symposium

Grants and Fellowships _____

2024 **Graduate Research Fellowship**, National Science Foundation

2022 Frederick and Barbara Cronin Fellowship, Massachuetts Institute of Technology

2020 Raab Family Scholarship, University of Michigan Marching Band

2019 Wanda W. Lincoln Scholarship, University of Michigan Marching Band

2017 The Gloria Wille Bell and Carlos R. Bell Scholarship

2017 Regents Merit Scholarship, University of Michigan

Teaching_____

2023 (Fall)	6.4210: Robotic Manipulation, Teaching Assistant	Massachusetts Institute of Technology
2022 (Winter)	EECS 367: Introduction to Autonomous Robotics, Teaching Assistant	University of Michigan
2021 (Fall)	ROB 102: Introduction to Al and Programming, Teaching Assistant	University of Michigan
2020 (Winter)	ENGR 100-250: Microprocessors and Toys, Teaching Assistant	University of Michigan
2019 (Winter)	ENGR 100-250: Microprocessors and Toys, Teaching Assistant	University of Michigan

Work Experience _____

2022- Graduate Student Research Assistant, Massachusetts Institute of Technology, Pl: Russ Tedrake

2016-2022 Undergraduate Student Research Assistant, University of Michigan, PI: Chad Jenkins

2021 **Curriculum Designer**, Robotics @ Marygrove

2017-2018 **Software Developer**, Number DNA

Extracurriculars_

2017-2022 Michigan Marching Band, Cymbal Section Leader 2019-2022

2017-2022 Michigan Hockey Pep Band

2018-2020 Michigan Percussion Chamber Ensemble