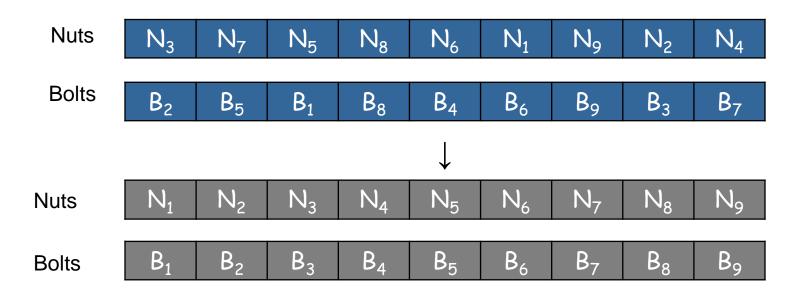


You are given n pairs of nuts and bolts

$$(N_1, B_1), (N_2, B_2), \dots, (N_n, B_n)$$

Each pair is a different size than the others. Someone has unscrewed all of the nuts out of the bolts and mixed them up.

Problem: Match all nuts up with their corresponding bolts.

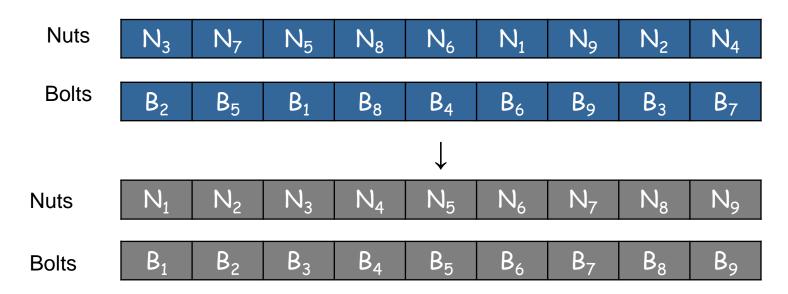


If we could separately

- (i) sort all the bolts by increasing size and then
- (ii) sort all the nuts by increasing thread size
- => problem would be easily solvable in O (n log n) time.

After sorting, just match them up in order from smallest to largest.

We can't do this because we can't compare the sizes of two nuts directly or the sizes of two bolts **directly.**



Only operation available is to try to screw a bolt B into a nut N and then, by seeing whether the bolt

(a) goes loosely in, (b) perfectly fits or (c) can't go in at all, decide whether their thread sizes satisfy

(a)
$$B < N$$
, (b) $B = N$ or (c) $B > n$.

Observation:

Given bolt B, above permits finding all NUTS bigger/=/less than B in O(N) time. Given nut N, above permits finding all BOLTS bigger/=/less than N in O(N) time

Hint: Try to use a modified Quicksort

Let
$$X = \{B_1, B_2, ..., B_n\}; Y = \{N_1, N_2, ..., N_n\};$$

MATCH(X;Y)

- 1. If |X| = |Y| = 1 match the unique nut with the unique bolt. Otherwise
- 2. Choose a nut N at random from Y
- 3. Compare ALL bolts in X with N; After doing this Let B be unique bolt that fits NSplit the remaining bolts into two sets B_S = Bolts smaller than B; B_L = Bolts larger than N.
- 4. Compare ALL nuts in Y except for N with B; Set N_S = Nuts smaller than B; N_L = Nuts larger than B.
- 5. Match $B \leftrightarrow N$.
- 6. Recursively call MATCH(B_s , N_s), MATCH(B_L , N_L).

```
MATCH(X;Y)
1. If |X| = |Y| = 1 match the unique nut with the unique bolt.
   Otherwise
     Choose a nut N at random from Y
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           Compare ALL bolts in X with N; After doing this, Let B be unique bolt that fits N
             Split the remaining bolts into two sets
             B_s = Bolts smaller than B; B_L = Bolts larger than N.
         Compare ALL nuts in Y except for N with B; Set
4.
             N_s = Nuts smaller than B; N_L = Nuts larger than B.
5.
        Match B \leftrightarrow N and recursively call
             MATCH(B_s, N_s), MATCH(B_L, N_L),
6.
```

Visualize X and Y as being stored in two separate ARRAYS.

- Choosing the random nut in 2 is like choosing a random pivot upon which to partition X array (the bolts) in Quicksort.
- Steps 3-4 can be implemented in O (n) time using almost exactly the same code as partition in Quicksort.

After Steps 3,4,5 the X and Y arrays have been partitioned around their pivots and the recursive calls are done into the two pairs of subarrays.

The analysis is then EXACTLY like Quicksort and this algorithm takes O (n log n) Expected time to match the nuts and bolts.

```
MATCH(X;Y)
1. If |X| = |Y| = 1 match the unique nut with the unique bolt.
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             MATCH(B_s, N_s), MATCH(B_L, N_L),
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```

Visualize X and Y as being stored in two separate ARRAYS.

The analysis is then EXACTLY like Quicksort and this algorithm takes O (n log n) Expected time to match the nuts and bolts.

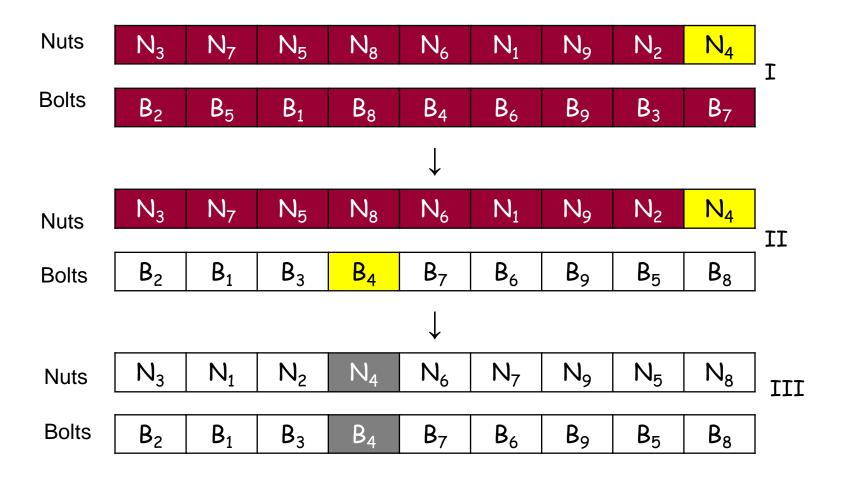
To see why this analysis is the same as Quicksort's, forget about the nuts and bolts and consider the algorithm from the point of view of sorting Y.

Step 2 chooses a random nut N as a pivot. Steps 3-4 does O(n) work and partitions Y around N. Step 6 then recursively calls the algorithm on the subarrays to left and right of N. This exactly mimics Quicksort!

Worked Example

We will see how to transform the top into the bottom

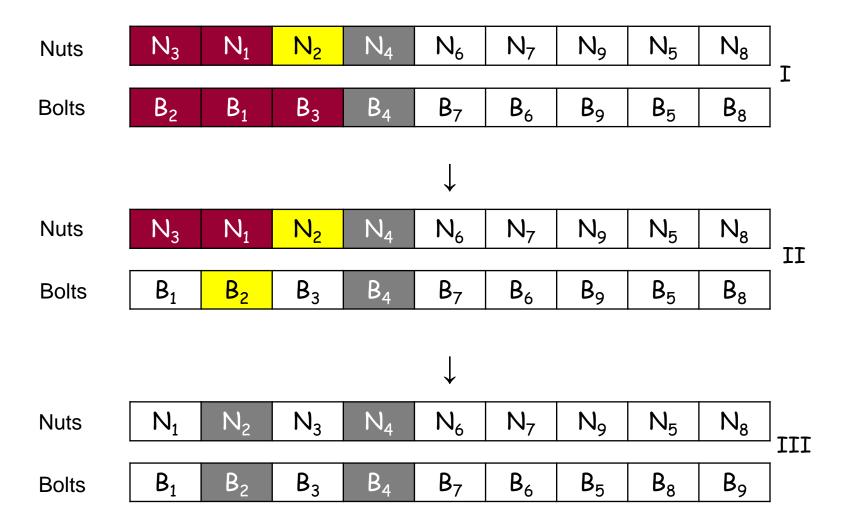
Nuts	N_3	N ₇	N_5	N ₈	N ₆	N_1	N ₉	N ₂	N ₄
Bolts	B ₂	B ₅	B_1	B ₈	B ₄	B ₆	B ₉	B ₃	B ₇
					\downarrow				
Nuts	N_1	N ₂	N_3	N ₄	N_5	N_6	N ₇	N ₈	N_9
Bolts	B ₁	B ₂	B ₃	B ₄	B ₅	B ₆	B ₇	B ₈	B_9



Step I: Starting Position. Pivot Nut is Yellow. Nuts & Bolts to be partitioned are Red Step II: Compare Red bolts to Pivot Nut, finding Matching Bolt (Yellow) and Partitioning remaining Red Bolts

Step III: Partition Red Nuts around Matching Yellow Bolt. Set matching Nut/Bolt as Gray,

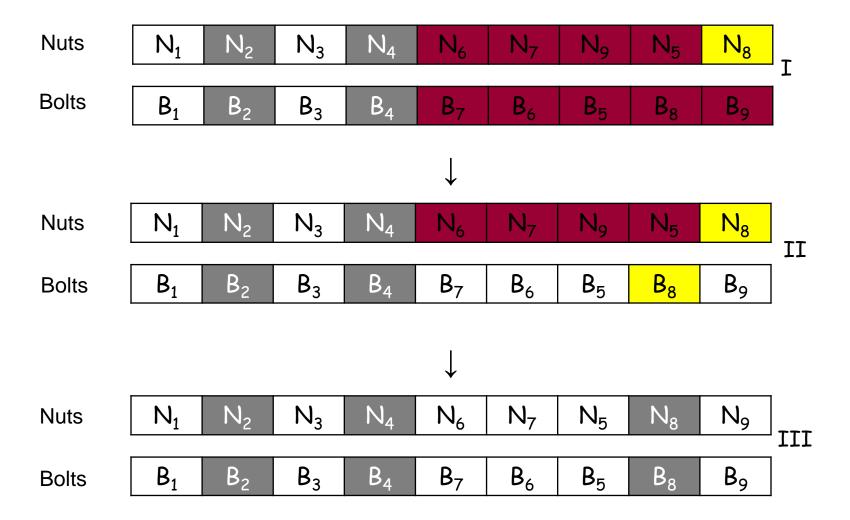
2nd Call



Step I: Starting Position. Pivot Nut is Yellow. Nuts & Bolts to be partitioned are Red

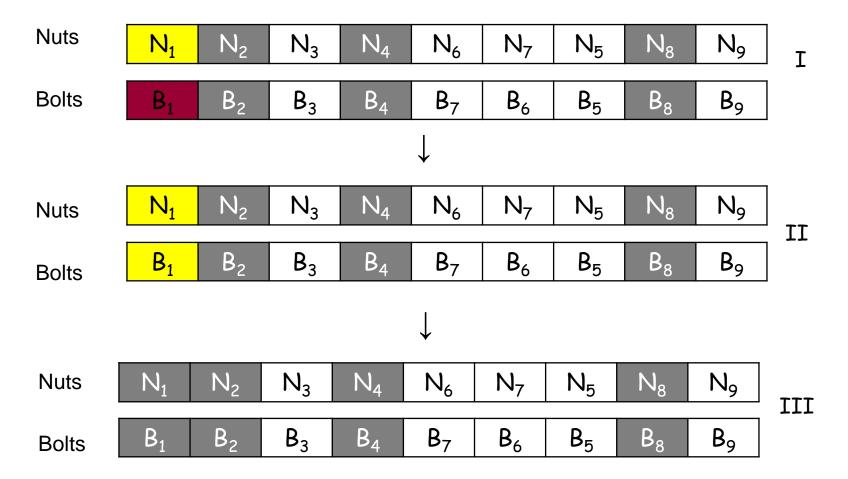
Step II: Compare Red bolts to Pivot Nut, finding Matching Bolt (Yellow) and Partitioning remaining Red Bolts

3rd Call



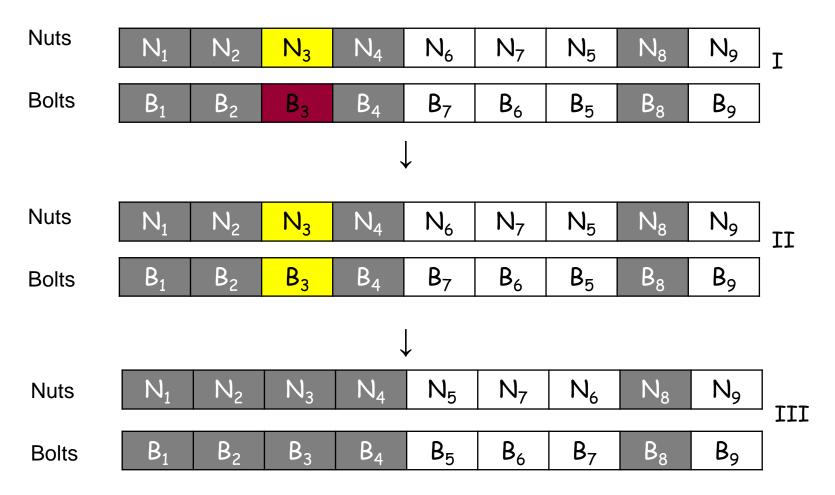
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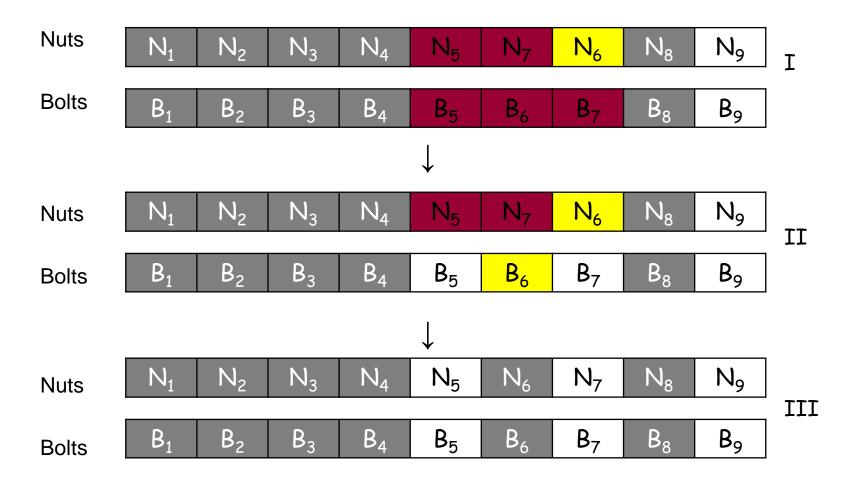
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Step III: Partition Red Nuts around Matching Yellow Bolt. Set matching Nut/Bolt as Gray₁₂

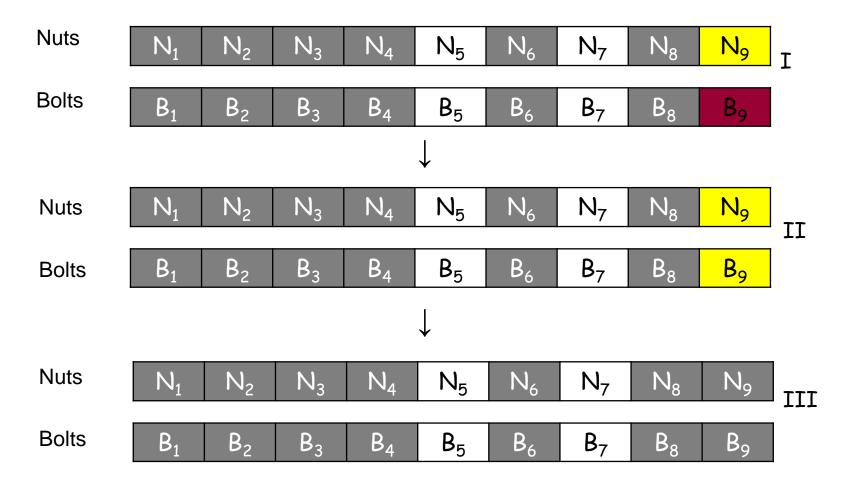


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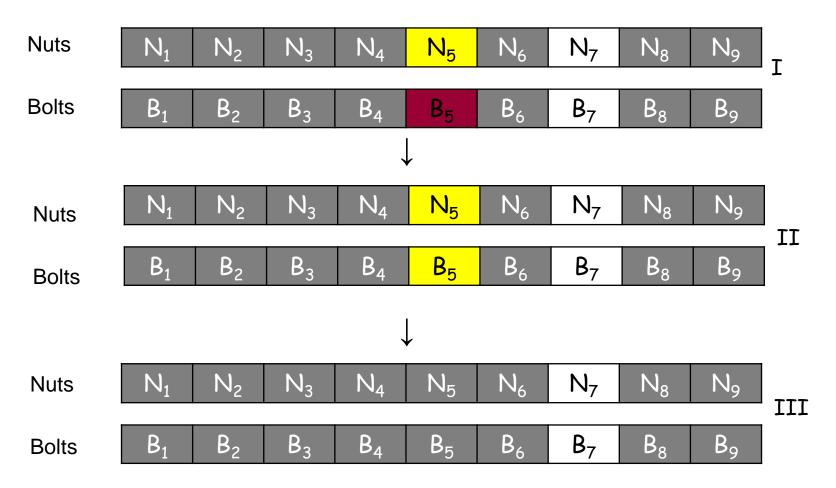


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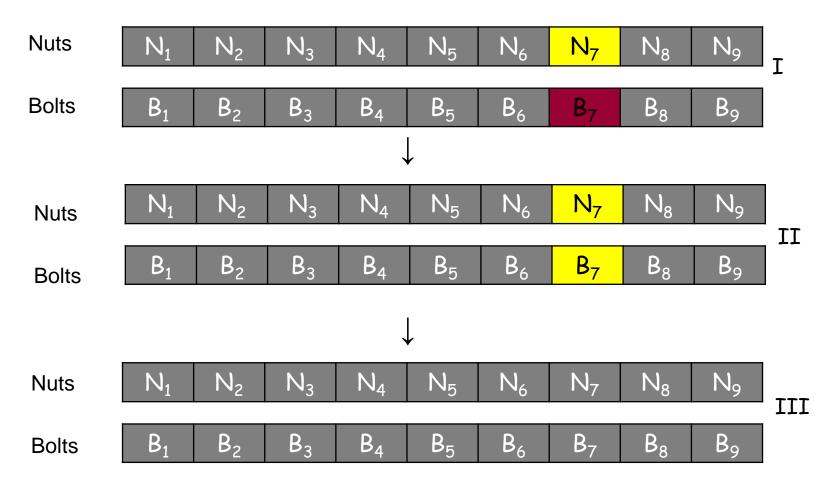


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More

The randomized algorithm from the previous pages was discovered quite early but it took a long time for researchers to find a good deterministic (non-randomized) one.

For a while, the best known deterministic algorithm ran in $O(n(\log n)^4)$ time.

O(n log n) worst case time algorithms are now known to exist but, unlike in the case of sorting, these deterministic algorithms are MUCH more complicated than the randomized one.

For more information about this problem, Google the phrase Matching Nuts and Bolts Algorithms.