

COMP 2012H Honors Object-Oriented Programming and Data Structures

Topic 20: AVL Trees

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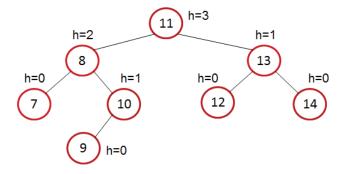
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AVL (Adelson-Velsky and Landis) Trees

- An AVL tree is a BST where the height of the two sub-trees of ANY
 of its nodes may differ by at most one.
- Each node stores a height value, which is used to check if the tree is balanced or not.



Motivation

- A binary search trees (BST) supports efficient searching if it is well balanced — its nodes are fairly evenly distributed on both its left and right sub-trees.
- However, this is not always the case as insertions and deletions of tree nodes will generally make the resulting BST unbalanced.
- In the worst case, the tree is de-generated to a sorted linked list and the searching time is linear time.

Target: A balanced binary search tree

A BST with N nodes and a height of the order of log N.

AVI Trees

AVL Tree Properties

Every sub-tree of an AVL tree is itself an AVL tree. (An empty tree is an AVL tree too.)

- With this property, an AVL tree is balanced and it is guaranteed that its height is logarithmic in the number of nodes, N. i.e., order of log(N).
- Efficiency of its following tree operations can always be guaranteed.
 - ► Searching: order of log(N) in the worst case
 - ► Insertion: order of log(N) in the worst case
 - ▶ Deletion: order of log(N) in the worst case

AVL Tree Implementation I

```
template <typename T>
                             /* File: avl.h */
class AVL
  private:
    struct AVI.node
        T value:
        int height;
                             // Left subtree is also an AVL object
        AVL left:
        AVL right;
                             // Right subtree is also an AVL object
        AVLnode(const T& x) : value(x), height(0), left(), right() { }
   };
    AVLnode* root = nullptr;
    AVL& right_subtree() { return root->right; }
    AVL& left_subtree() { return root->left; }
    const AVL& right_subtree() const { return root->right; }
    const AVL& left_subtree() const { return root->left; }
```

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AVL Tree Searching

• Searching in AVL trees is the same as in BST.

AVL Tree Implementation II

```
int height() const;
                             // Find the height of tree
    int bfactor() const;
                             // Find the balance factor of tree
    void fix height() const; // Rectify the height of each node in tree
    void rotate_left();
                             // Single left or anti-clockwise rotation
    void rotate_right();
                            // Single right or clockwise rotation
    void balance():
                             // AVL tree balancing
  public:
    AVL() = default;
                             // Build an empty AVL tree by default
    ~AVL() { delete root; } // Will delete the whole tree recursively!
    bool is_empty() const { return root == nullptr; }
    const T& find min() const:
                                     // Find the minimum value in an AVL
    bool contains(const T& x) const; // Search an item
    void print(int depth = 0) const; // Print by rotating -90 degrees
    void insert(const T& x); // Insert an item in sorted order
    void remove(const T& x); // Remove an item
}:
```

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AVI Tree Insertion and Rotation

- To insert an item in an AVL tree
 - Search the tree and locate the place where the new item should be inserted to.
 - Create a new node with the item and attach it to the tree.
- The insertion may cause the AVL tree unbalanced
 - ⇒ tree balancing by rotation(s)
- Types of rotation
 - single rotation
 - double rotation (i.e., two single rotations)





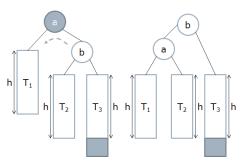
AVL Tree Insertion and Rotation ...

Insertion may violate the AVL tree property in 4 cases:

- 1. Left (anti-clockwise) rotation [single rotation]: Insertion into the right sub-tree of the right child of a node
- 2. Right (clockwise) rotation [single rotation]: Insertion into the left sub-tree of the left child of a node
- 3. Left-right rotation [double rotation]: Insertion into the right sub-tree of the left child of a node
- 4. Right-left rotation [double rotation]: Insertion into the left sub-tree of the right child of a node

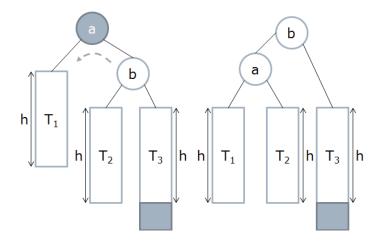
AVL Code: Left Rotation

```
/* Goal: To perform a single left (anti-clocwise) rotation */
template <typename T>
void AVL<T>::rotate_left() // The calling AVL node is node a
    AVLnode* b = right_subtree().root; // Points to node b
    right_subtree() = b->left;
    b->left = *this:
                        // Note: *this is node a
    fix height();
                        // Fix the height of node a
    this->root = b:
                        // Node b becomes the new root
    fix_height();
                        // Fix the height of node b, now the new root
```



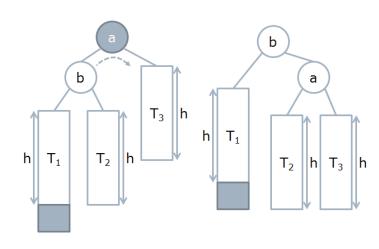
AVL Left (Anti-clockwise) Rotation

Left rotation at node a.



AVL Right (Clockwise) Rotation

Right rotation at node a.



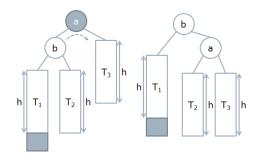
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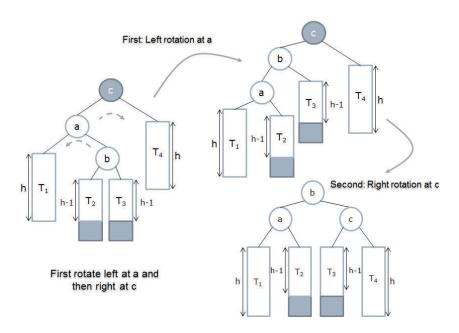
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AVL Code: Right Rotation

```
/* Goal: To perform right (clockwise) rotation */
template <typename T>
void AVL<T>::rotate_right() // The calling AVL node is node a
    AVLnode* b = left_subtree().root; // Points to node b
    left subtree() = b->right;
    b->right = *this; // Note: *this is node a
                        // Fix the height of node a
    fix_height();
    this->root = b;
                        // Node b becomes the new root
    fix_height();
                        // Fix the height of node b, now the new root
```

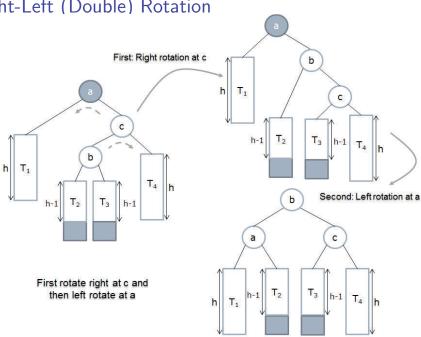


Left-Right (Double) Rotation



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Right-Left (Double) Rotation



AVI Code: Insertion

```
/* To insert an item x to AVL tree and keep the tree balanced */
template <typename T>
void AVL<T>::insert(const T& x)
                                   // Base case
    if (is_empty())
        root = new AVLnode(x);
    else if (x < root->value)
        left_subtree().insert(x); // Recursion on the left sub-tree
    else if (x > root->value)
        right_subtree().insert(x); // Recursion on the left sub-tree
    balance(); // Re-balance the tree at every visited node
}
```

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AVL Code: Balancing

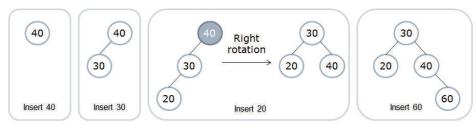
```
/* Goal: To balance an AVL tree */
template <typename T>
void AVL<T>::balance()
    if (is_empty())
        return;
    fix_height();
    int balance_factor = bfactor();
    if (balance_factor == 2)
                                   // Right subtree is taller by 2
        if (right_subtree().bfactor() < 0) // Case 4: insertion to the L of RT
            right_subtree().rotate_right();
        return rotate_left();
                                   // Cases 1 or 4: Insertion to the R/L of RT
    else if (balance_factor == -2) // Left subtree is taller by 2
        if (left_subtree().bfactor() > 0) // Case 3: insertion to the R of LT
            left_subtree().rotate_left();
        return rotate right();
                                   // Cases 2 or 3: insertion to the L/R of LT
    // Balancing is not required for the remaining cases
```

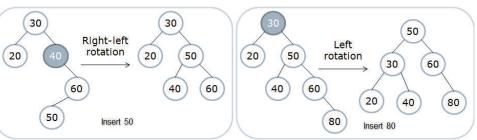
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Example: AVL Tree Insertion





AVL Code: Balancing ..

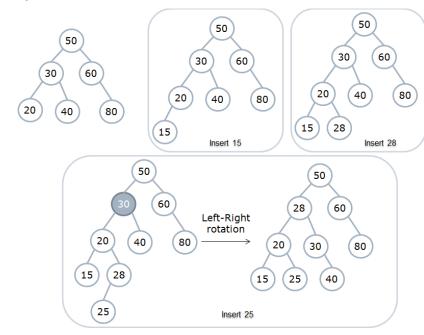
```
/* To find the height of an AVL tree */
template <typename T>
int AVL<T>::height() const { return is_empty() ? -1 : root->height; }
/* Goal: To rectify the height values of each AVL node */
template <typename T>
void AVL<T>::fix height() const
    if (!is_empty())
        int left_avl_height = left_subtree().height();
        int right_avl_height = right_subtree().height();
        root->height = 1 + max(left_avl_height, right_avl_height);
}
/* balance factor = height of right sub-tree - height of left sub-tree */
template <typename T>
int AVL<T>::bfactor() const
    return is_empty() ? 0
        : right_subtree().height() - left_subtree().height();
```

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Example: AVL Tree Insertion ..



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AVL Tree Deletion

To delete an item from an AVL tree.



- 1. Search and locate the node with the required key.
- 2. Delete the node like deleting a node in BST.
- 3. A node deletion may result in a unbalanced tree
 - \Rightarrow Re-balance the tree by rotation(s).
 - ► single rotation
 - double rotation (i.e. two single but different rotations)

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AVL Tree Deletion ..

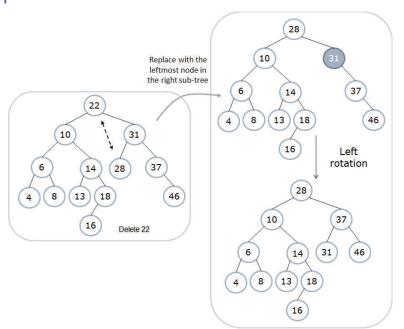
- Similar to node deletion in BST, 3 cases need to be considered
 - 1. The node to be removed is a leaf node
 - ⇒ Delete the leaf node immediately
 - 2. The node to be removed has 1 child
 - ⇒ Adjust a pointer to bypass the deleted node
 - 3. The node to be removed has 2 children
 - ⇒ Replace the node to be removed with either the
 - maximum node in its left sub-tree, or
 - minimum node in its right sub-tree Then remove the max/min node depending on the choice above.
- Removing a node can render multiple ancestors unbalanced
 - \Rightarrow every sub-tree affected by the deletion has to be re-balanced.

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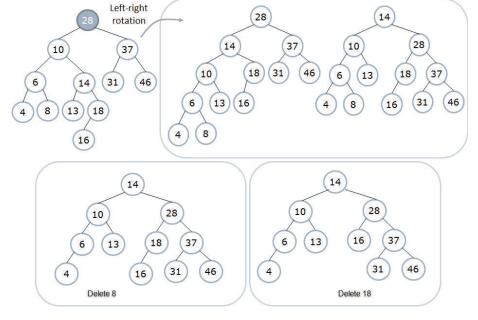
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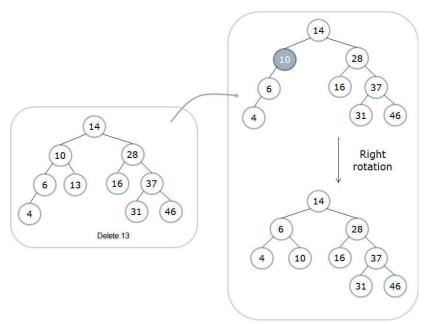
Example: AVL Tree Deletion



Example: AVL Tree Deletion ..

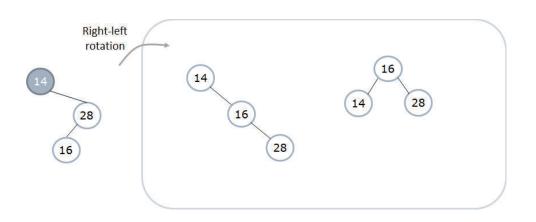


Example: AVL Tree Deletion ...

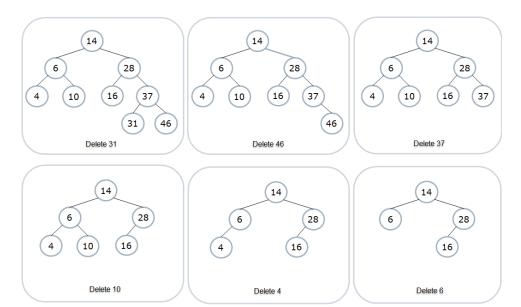


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Example: AVL Tree Deletion



Example: AVL Tree Deletion



AVL Code: Deletion I

```
/* To remove an item x in AVL tree and keep the tree balanced */
template <typename T>
void AVL<T>::remove(const T& x)
    if (is_empty())
                                   // Item is not found; do nothing
        return;
    if (x < root->value)
       left_subtree().remove(x); // Recursion on the left sub-tree
    else if (x > root->value)
        right_subtree().remove(x); // Recursion on the right sub-tree
    else
        AVL& left_avl = left_subtree();
        AVL& right_avl = right_subtree();
```

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AVI Code: Deletion II

```
// Found node has 2 children
        if (!left_avl.is_empty() && !right_avl.is_empty())
        {
            root->value = right_avl.find_min(); // Copy the min value
            right_avl.remove(root->value); // Remove node with min value
        else // Found node has 0 or 1 child
            AVLnode* node_to_remove = root; // Save the node first
            *this = left_avl.is_empty() ? right_avl : left_avl;
            // Reset the node to be removed with empty children
            right_avl.root = left_avl.root = nullptr;
            delete node_to_remove;
    }
    balance(); // Re-balance the tree at every visited node
}
```

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AVI Code: Find the Minimum Value

```
/* To find the minimum value stored in an AVL tree. */
template <typename T>
const T& AVL<T>::find_min() const
    // It is assumed that the calling tree is not empty
    const AVL& left_avl = left_subtree();
    if (left_avl.is_empty())
                                // Base case: Found!
        return root->value;
    return left_avl.find_min(); // Recursion on the left subtree
}
```

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AVL Testing Code

```
/* File: avl.tpp
 * It contains template header and all the template functions
#include "avl.h"
#include "avl-balance.cpp"
#include "avl-bfactor.cpp"
#include "avl-contains.cpp"
#include "avl-find-min.cpp"
#include "avl-fix-height.cpp"
#include "avl-height.cpp"
#include "avl-insert.cpp"
#include "avl-print.cpp"
#include "avl-remove.cpp"
#include "avl-rotate-left.cpp"
#include "avl-rotate-right.cpp"
```

AVL Testing Code .. I

```
#include <iostream>
                         /* File: test-avl.cpp */
using namespace std;
#include "avl.tpp"
int main()
    AVL<int> avl tree;
    while(true)
        char choice; int value;
        cout << "Action: f/i/m/p/q/r (end/find/insert/min/print/remove): ";</pre>
        cin >> choice:
        switch(choice)
                cout << "Value to find: "; cin >> value;
                cout << boolalpha << avl_tree.contains(value) << endl;</pre>
                break;
                cout << "Value to insert: "; cin >> value;
                avl_tree.insert(value);
                break:
```

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AVL Testing Code .. II

```
case 'm':
    if (avl_tree.is_empty())
        cerr << "Can't search an empty tree!" << endl;
    else
        cout << avl_tree.find_min() << endl;
    break;

case 'p':
    avl_tree.print();
    break;

case 'q': default:
    return 0;

case 'r':
    cout << "Value to remove: "; cin >> value;
    avl_tree.remove(value);
    break;
}
```

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AVL Trees: Pros and Cons

Pros:

- Time complexity for searching is in the order of log(N) since AVL trees are always balanced.
- Insertion and deletions are also in the order of log(N) since the operation is dominated by the searching step.
- The tree re-balancing step adds no more than a constant factor to the time complexity of insertion and deletion.

Cons:

• A bit more space for storing the height of an AVL node.

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That's all!

Any questions?

