

# Miao Sun

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## CONTACT INFORMATION

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## RESEARCH INTERESTS

Computer vision with special interests in object detection, image classification, and activity analysis;  
Machine learning with special interests in local learning and transfer learning.

## EDUCATION

### University of Missouri, Columbia, MO USA

Ph.D. Candidate in Electrical and Computer Engineering  
GPA: 4.0/4.0

- Thesis Topic: “Adaptive Object Detection in Large Scale Database”
- Advisor: Prof. Tony X. Han

### University of Science and Technology of China, Hefei China

Bachelor of Engineering, Dept. of Automation, July, 2011  
Weighted score: 88.94/100

## RESEARCH EXPERIENCE

### University of Missouri, Columbia, MO USA

*Research Assistant of Professor Tony X. Han*

**Aug. 2011 - present**

- **Object Detection for PASCAL VOC Challenge**

Under the direction of Professor Tony X. Han, I was the key personnel of the MU object detection team for the PASCAL VOC challenge. We ranked 7th worldwide. In our team, I was in charge of:

- 1.HOG-LBP feature extraction;
- 2.Deformable model training using latent SVM;
- 3.Post-processing through context re-scoring to boost the final performance.

- **Action Recognition Using Bag of HOG Variations**

We developed a mid-level feature, Histogram of Oriented Gradient Variations(HOGV), for action recognition with the bag-of-visual-words model. The HOGV feature is the temporal variation of the stable HOG feature, which is not only stable due to its cell-block structure, but is also capable of capturing the static and dynamic characteristics of human actions. This work has been submitted to the International Conference on Image Processing 2012(ICIP 2012).

- **The Implementation of Convolutional Neural Network(CNN)**

I implemented a Convolutional Neural Network for object recognition based on the paper: *Gradient-Based Learning Applied to Document Recognition*. I tested the CNN on the UMIST Database, which contains 574 images of 20 individuals. We achieved a testing accuracy of 99.13%. This component has been used for the face localization demo of our lab.

Now, I am focusing on learning hierarchical models which simultaneously represent multiple levels including pixel intensities, edges, object parts, objects, and beyond. Geoffrey E. Hinton’s work about using a Restricted Boltzmann Machine to model each new layer of higher level features and Andrew Y. Ng’s work about Convolutional Deep Belief Networks, which designs a generative version of the pooling / subsampling units, inspires me to apply a modified Convolutional Neural Network on Deep Architectures. Work will be submitted to the Conference on Computer Vision and Pattern Recognition 2013(CVPR2013)

- **Investigating the Possibility of Combining AdaBoost with Sparse Linear SVM**

I wrote a Linux C++ version of RealBoost based on the paper: *Additive Logistic Regression: a*

*Statistical View of Boosting.* I am currently investigating the learning scheme of using RealBoost to select features and combine with sparse linear SVM to improve the performance.

**University of Science and Technology of China**, Hefei China

*Research Assistant of Professor Zhigang Zheng.*

**Oct. 2009 - Apr. 2011**

- **Automatic Number Plate Recognition System**

I developed an automatic plate recognition System. The basic steps were as follows:

1. Locate license plate using the shape feature;
2. Orientation and scale normalization;
3. Character segmentation using adaptive histogram-based method;
4. Shape feature extraction to recognize the license plate.

- **Robo-game Competition**

**Jun. 2009 - Sep. 2009**

I took part in the robo-game competition in 2009. We were asked to manufacture a biped robot as a boxer. The biped robot was required to have human-like shape and to walk as human beings. The whole process of making such a robot and car can be divided into three parts: mechanical structure, circuit design and programming. I was in charge of the programming part; I developed the control program on the Single-Chip Microcomputer to control the whole system including walking, communication between operators and robots.

PUBLICATIONS      Xutao Lv **Miao Sun**, Tony X. Han, Zhihai He and Shihong Lao, "Action recognition using bag of HOG variations", submitted to **ICIP2012**.

COMPUTER SKILLS    *Languages & Software: C/C++, Python, and Matlab.*  
*Platform: Windows, Linux, Hadoop-based map-reduced clusters.*  
*Software package: OpenCV, STL, LTI-LIB.*

AWARDS              

- Outstanding Student Scholarship (Grade 1), USTC, China, 2010
- Shanghai Institute of Microsystem and Information Scholarship, USTC, China, 2009
- Outstanding Student Scholarship (Grade 1), USTC, China, 2008

REFERENCE            **Tony X.Han**  
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