**Instructions.** This is practice for a **timed** final. This is meant to be done in **3** hours with access to notes and course material, but no access to collaborators. For best practice I suggest trying to complete it under these conditions. Afterwards please tell me if 3 hours felt like enough.

- 1. Answer true or false. For items **not** marked with \*, if true, provide a concise reason (no rigor necessary) and if false, exhibit a counterexample.
  - (a) Every matching that is not maximum in a graph G has an augmenting path.\*
  - (b) If A, b are integral, then the linear program  $\max\{c^T x : Ax \leq b\}$  has an integral maximizer.
  - (c) The set of matchings in a bipartite graph forms a matroid.
  - (d) Given a bipartite graph, the set of subgraphs of degree at most two is the intersection of two matroids.
  - (e) Given a separation oracle for a polyhedron  $P \subset [0,1]^n$ , it is always possible to test feasibility of P with polynomially many calls to the separation oracle.

## Answers.

- (a) Yes.
- (b) No. For the following program the only maximizer is fractional:

$$\max \left\{ x_1 \mid \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \le \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}.$$

- (c) No. For the complete graph with parts  $\{a_1, a_2\}, \{b_1, b_2\}$  the exchange axiom is violated for the independent sets  $X = \{\{a_1, b_1\}\}, Y = \{\{a_1, b_2\}, \{a_2, b_1\}\}.$
- (d) Yes. For a graph G = (V, E) with bipartition  $V = A \sqcup B$ , the set of subgraphs of degree at most two is the intersection of two partition matroids  $(E, \mathcal{I}_A)$  and  $(E, \mathcal{I}_B)$  defined as follows. Let  $E = \bigsqcup_{a \in A} E_a$  be the partition of edges according to their left endpoint; then  $\mathcal{I}_A = \{E' \subset E \mid |E' \cap E_a| \leq 2 \ \forall a \in A\}$ . Similarly one defines  $\mathcal{I}_B$ .
- (e) No. It is impossible to tell a single point from the empty set, because the separation oracle might output the same.

2. For  $k \leq n$  an integer, define a k-bounded permutation on  $\{1, ..., n\}$  to be a permutation  $\sigma$  such that  $|\sigma(i) - i| \leq k$  for all  $i \in \{1, ..., n\}$ .

Suppose we are given an integer  $k \leq n$  and costs c(i) for  $i \in \{1, ..., n\}$ , and our goal is to find a k-bounded permutation  $\sigma$  on  $\{1, ..., n\}$  minimizing  $\sum_{i=1}^{n} c(i)\sigma(i)$ . Give a polynomial-time algorithm for this problem (there is no need to give the most efficient algorithm, but the algorithm should be polynomial in n and k). (You can refer to any algorithm we have seen in class.)

**Solution:** This can be cast as an instance of the minimum cost perfect matching problem. A permutation  $\sigma$  is none other than a matching in the complete bipartite graph with bipartition  $A \cup B$  equal to two disjoint copies of [n], where there is an edge between i and  $\sigma(i)$ . The restriction that the permutation is k-bounded requires that the permutation correspond to a matching in the subgraph  $G = (A \cup B, E)$  where  $E = \{(i,j) : i \in A, j \in B, |i-j| \le k\}$ . If we set the cost of the edge (i,j) to be  $c_{i,j} = c(i)j$ , then the minimum cost perfect matching in G yields the minimum cost k-bounded permutation. This can be solved in (strongly) polynomial time using the Hungarian algorithm.

- 3. (a) Consider a directed graph G = (V, E) with nonnegative (upper) capacities  $u : E \to \mathbb{R}$  (and no lower capacities). For any two vertices  $s, t \in V$ , define  $\lambda_{st} \in \mathbb{R}$  to be the maximum flow value from s to t. Given any 3 vertices  $s, t, u \in V$ , show that  $\lambda_{su} \geq \min(\lambda_{st}, \lambda_{tu})$ .
  - (b) If the graph is undirected, the previous result still holds:  $\lambda_{su} \geq \min(\lambda_{st}, \lambda_{tu})$  for all s, t, u. Furthermore,  $\lambda_{st} = \lambda_{ts}$ . Now, consider the complete graph  $K_V$  on the vertex set V with weight  $\lambda_{uv}$  on edge  $\{u, v\}$  for all u, v. Let T be a maximum weight spanning tree on  $K_V$  with respect to these weights  $\lambda_{uv}$ . Argue that for every  $\{s, t\} \notin T$ , we have

$$\lambda_{st} = \min_{\{u,v\} \in P_{st}} \lambda_{uv}$$

where  $P_{st}$  denotes (the edges of  $K_V$  of) the unique path in T between s and t. (This implies the somewhat surprising result that, over all pairs (s,t),  $\lambda_{st}$  can take at most |V|-1 values (those along the edges of T).)

## Solution.

- (a) Consider a minimal cut separating s and u, that is, a partition  $V = S \sqcup U$  such that  $s \in S$ ,  $u \in U$ ,  $\lambda_{su} = \sum_{e \in \delta^+(S)} u(e)$ . If  $t \in S$ , then the same cut separates t and u, and so  $\lambda_{su} \geq \lambda_{tu}$ . Otherwise  $t \in U$ , the cut separates s and t, and  $\lambda_{su} \geq \lambda_{st}$ . In either case,  $\lambda_{su} \geq \min(\lambda_{st}, \lambda_{tu})$ .
- (b) Using the previous part, one shows by induction that  $\lambda_{st} \geq \min_{\{u,v\} \in P_{st}} \lambda_{uv}$ . Let  $\{u,v\}$  be a specific edge delivering the minimum in the right-hand side. We'd like to argue that  $\lambda_{st} \leq \lambda_{uv}$ . Indeed, if not, then  $\lambda_{st} > \lambda_{uv}$ , and one can replace the edge  $\{u,v\}$  in the tree T by the edge  $\{s,t\}$ . The resulting subgraph is still a spanning tree, whereas its weight gets increased, which contradicts the choice of T. Therefore,  $\lambda_{st} = \lambda_{uv}$ .

4. Consider a bipartite graph G = (A, B, E) with parts A, B and edges  $E \subseteq A \times B$ . Suppose we have a matroid  $M_A = (A, \mathcal{I}_A)$  on A with rank function  $r_A$ . Define a family of sets  $\mathcal{I}_B$  to be the collection of sets  $T \subseteq B$  such that there exists a matching M of G with vertex set  $V(M) = S \cup T$ , such that  $S \subseteq A$  and  $S \in \mathcal{I}_A$ .

Prove that  $M_B = (B, \mathcal{I}_B)$  is a matroid. (For **half credit**, you can do this in the special case where every vertex of A has degree 1, so that G is the graph of a function from A to B.)

**Solution:** We need to show that  $\mathcal{I}_B$  is downward-closed and satisfies the exchange property. Downward closure follows because if T is matched to independent set  $S \in \mathcal{I}_A$ , then  $T' \subset T$  is matched to a subset of  $S' \subset S$  which is also independent.

For the exchange property, we must show that given  $T', T \in \mathcal{I}_B$  with |T'| > |T|, there is some element  $t \in T' \setminus T$  such that  $T + t \in \mathcal{I}_B$ . That is,  $t \in T' \setminus T$  such that T + t can be matched to an independent set in  $\mathcal{I}_A$ . Let M be a matching between T, S for  $S \in \mathcal{I}_A$ , and let M' be a matching between T', S' for  $S' \in \mathcal{I}_A$ . We'll use alternating paths in  $M \cup M'$  to gradually modify M until we get the matching we want.

As |S'| > |S|, the basis exchange property for  $I_A$  says there is an element a in  $S' \setminus S$  such that S + a is independent. The element a is covered by M' but not M, so has degree 1 in  $M' \cup M$ . As  $M' \cup M$  has maximum degree two, the connected component containing a is a path P. Moreover, it must be alternating in M. If this path ends in B, then we may augment M along P to cover an element t of  $T' \setminus T$ , and we are done. If instead the path ends at some element  $a' \in A$ , then  $a \in S \setminus S'$ . The symmetric difference of  $M \triangle P$  matches T to the independent set S + a - a'. Replace  $S \leftarrow S + a - a'$  and M by  $M \triangle P$ . The size of the intersection  $S \cap S'$  has increased by one. Continue this process until we are done (we have covered an element of  $T' \setminus T$ ) or  $S \subset S'$ . Once  $S \subset S'$ , we can take t to be any element of  $T' \setminus T$ .

**Note:** In retrospect this problem was too hard. It's still good practice, but don't let it scare you.

5. Let  $x \in [0,1]^n$  be an unknown vector, and we suppose have access to a separation oracle for the set  $S = [x_1, x_1 + 0.1] \times \cdots \times [x_n, x_n + 0.1] \subset \mathbb{R}^n$ . Can we find a point in S in time polynomial in n, and if so, how? (You can refer to any algorithm we have seen in class).

## Solution.

We exploit the ellipsoid method. The starting ellipsoid  $E_0$  is the ball of radius  $\sqrt{n}/2$  centered at  $(1/2, \ldots, 1/2)$ . Recall Claim 7.2 from the notes: the volumes of successive ellipsoids  $E_k$  in the method decay exponentially,

$$\operatorname{Vol}(E_k) \le \operatorname{Vol}(E_0) \exp\left(-\frac{k}{2(n+1)}\right).$$

If by  $k^{\text{th}}$  step a point in S is not found, then  $S \subset E_k$ , and

$$0.1^n = \operatorname{Vol}(S) < \operatorname{Vol}(E_k) \le \operatorname{Vol}(E_0) \exp\left(-\frac{k}{2(n+1)}\right).$$

It follows that  $k < 2n(n+1)\log 10$ . Hence, after  $2n(n+1)\log 10$  iterations of the ellipsoid method a point in S will be found.