

Lecture 13: Plz do survey!

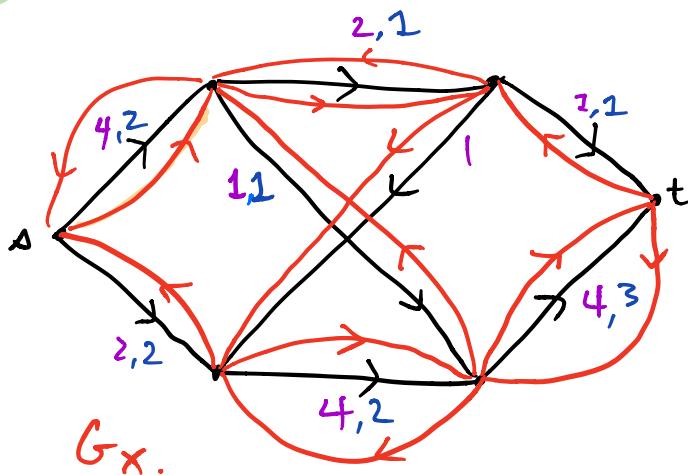
Plan:

- 1) algorithm for max flow
- 2) global min cut.

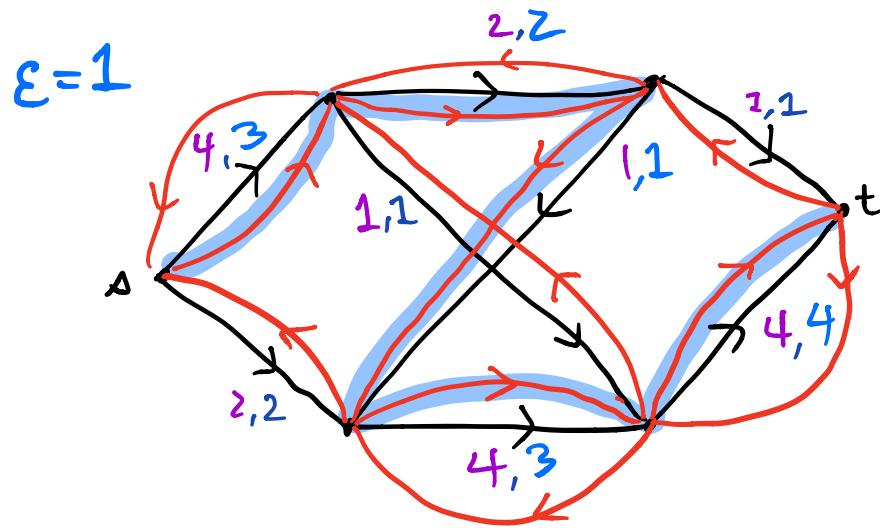
Recap: Augmenting flows:

- Given a flow X , compute residual graph G_X .

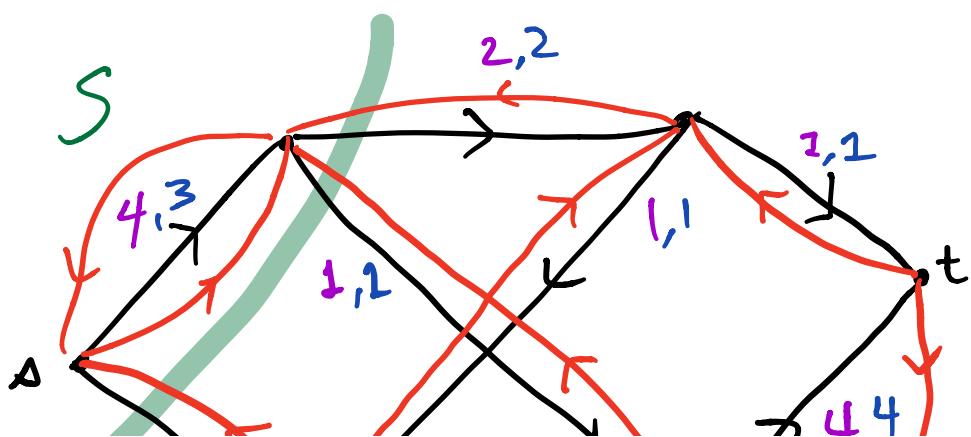
e.g. $l=0, u, x$

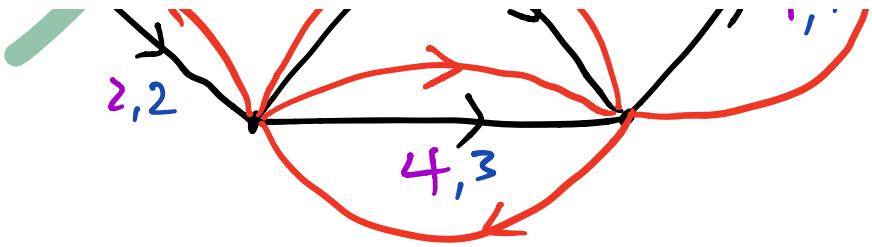


- Clf $\exists s-t$ path in residual,
 ε - more units of flow can
be sent along it.



- if no $s-t$ path, is cut S with capacity
 $C(S) = |X|$, terminate.





Problem: might not terminate!

- if irrational may run forever.
- if rational, can multiply capacities by s.g. to make integers.
- If capacities integral, can take $\epsilon > 0$ to be integral, so must terminate.
 - in integral case, # steps

naively bounded by

$$\sum_e |l(u) - l(e)|$$

but this is not polynomial
in input size!

Remember: need only
 $(1 + \log_2 |l(e)|)$ bits to represent
 $l(e)$.

remedy:

Edmonds-Karp alg.

- variant of aug. flows.

- terminates in $\text{poly}(m, n)$ steps, $m = |E|$, $n = |V|$, regardless of the capacities

"strongly polynomial time".

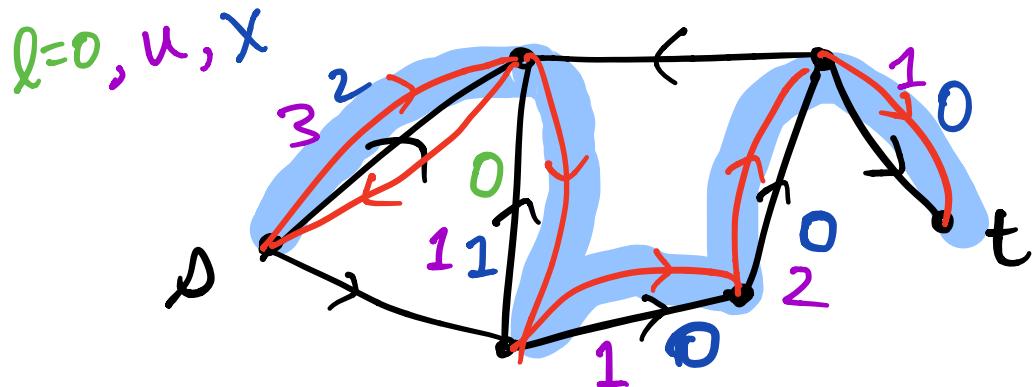
- Works even if capacities irrational
- Unknown if \exists strongly polynomial time for general LP's.
- Algorithm: same as before, but use shortest s-t path in residual. $\log \# \text{edges}$.

Analysis idea: show iterations increase s-t distance in residual.

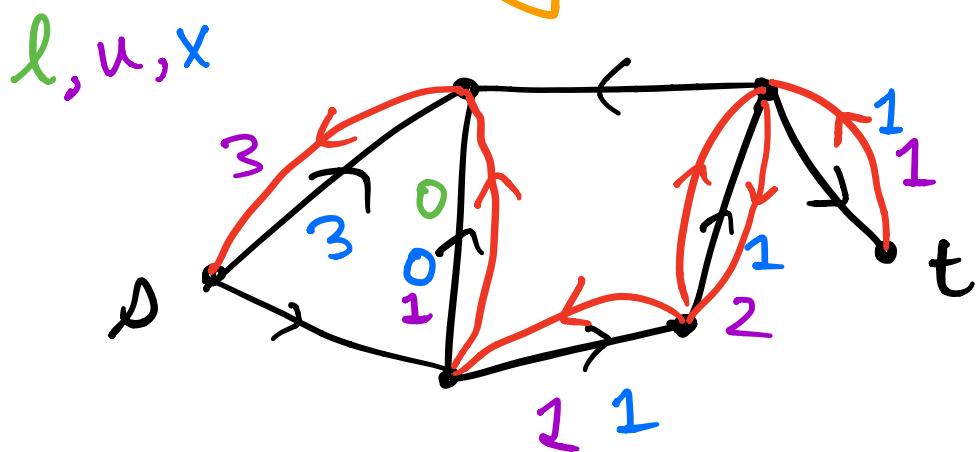
... +

- For $v \in V$, let $ds(v)$ denote distance from s to v in G_x (length of shortest $s-v$ path in G_x).
- Let P shortest $s-t$ path in G_x .
 $P = s - v_1 - v_2 - \dots - t$, $ds(v_j) = j$
- x' flow after augmenting along P .
 (as much as possible).
- Let ds' be distance labels for $G_{x'}$.
- Note: any edge (i,j) added to G_x goes opposite direction in $G_{x'}$.
 $\Delta = n - \max\{ds(i), ds(j)\} + 1$

i.e. $ds(j) - ds(i) \leq 1$



} augment.



- After augmentation,

$$ds(j) - ds(i) \leq 1 \quad \star$$

for every edge (i, j) in $E_{x'}$.

$\left\{ \begin{array}{l} ((i,j) \in E_X \Rightarrow \text{automatically } \star \\ (i,j) \notin ds(j) - ds(i) = - |\Delta| \text{ in } G_X. \end{array} \right.$

- for any $j \in V$, Sum \star
along edges of shortest
 $s-j$ path P' in $G_{X'}$,

$$ds(j) = \sum_{(i,j) \in P'} ds(j) - ds(i) \leq |P'| = ds'(j).$$

In particular, for $j = t$

$$ds(t) \leq ds'(t)$$

- Distance to t can

increase $\leq n-1$ times.

- But how often must it increase?

Each iteration, some edge with $ds(j) = ds(i) + 1$

is removed from G_x .

(P shortest path, & some edge along P must get removed).

- Thus after $\leq m$ iterations must get $ds(t) < ds'(t)$.
(one ineq. in telescope becomes strict.).

- In summary:

(i) # augmentations $\leq m(n-1)$

(ii) time to build G_x , find $P = \Theta(m)$.

\Rightarrow running time $O(m^2 n)$ \square

Best: $O(mn \cdot \log(m \dots n))$ *not tight.*

Goldberg - Tarjan

The initial feasible flow

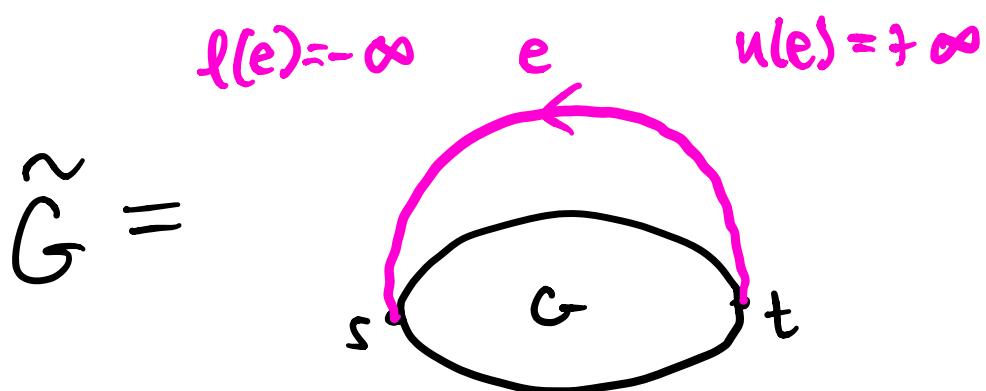
we still need to find flow to start with!

- if $l(e) \leq o \leq u(e)$ $\forall e$, use $x=0$.

- if not, feasible flow is max flow for another network
that's easy to initialize.

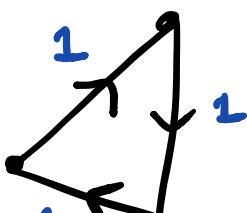
Circulations

- first reduce finding feasible flow to finding "circulation" in new graph \tilde{G} :



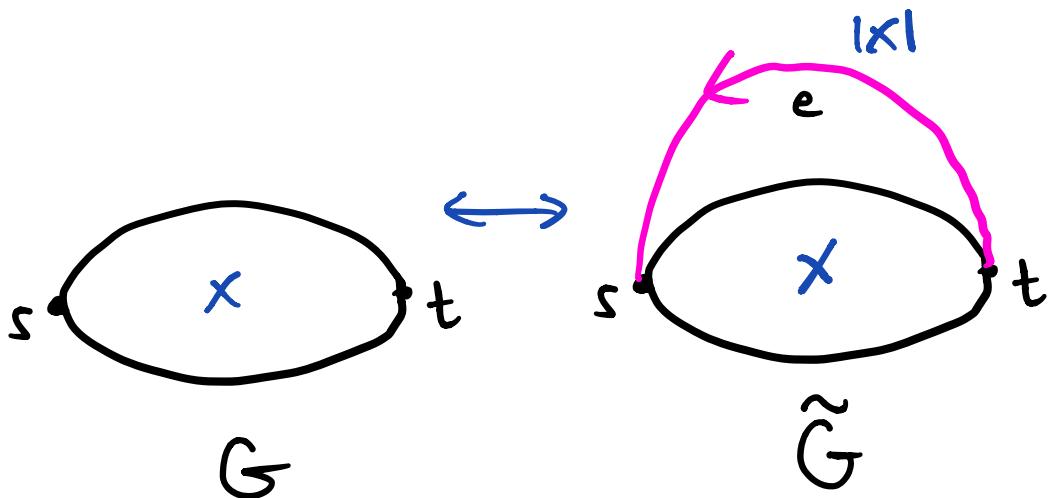
- Define circulation of G, u, l as flow satisfying conservation at all $v \in V$ (s, t no longer special).

e.g.



1 ..

- Bijection between flows in G & circulations in \tilde{G} :



(add $|x|$ to new edge).

finding Circulations:

Let $G=(V,E)$ arbitrary digraph
w/ capacities l, u . $l \leq u$

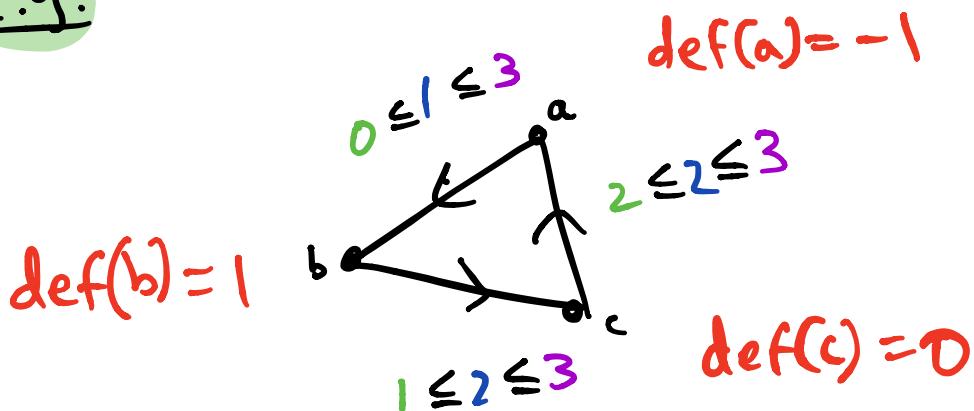
- First, choose arbitrary y_e
with $\dots - \dots - \dots - \dots$

$$l(e) \leq y_e \leq u(e)$$

- y_e need not be flow; define deficit at v

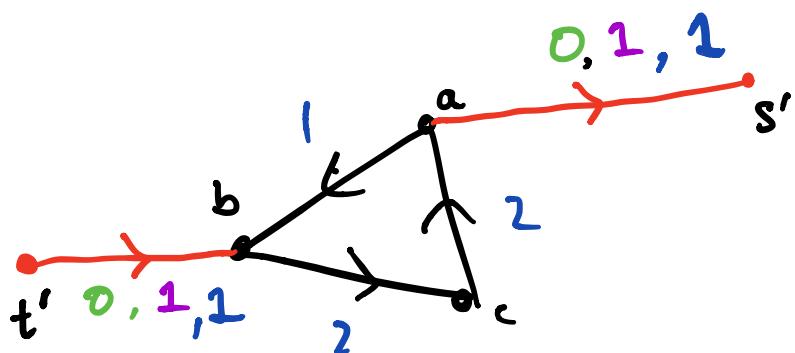
$$\text{def}(v) := \sum_{\delta^+(v)} y_e - \sum_{\delta^-(v)} y_e$$

e.g.



- To fix: add extra edges, source, sink to supply deficit.

e.g.



Formally: Let $G' = (V', E')$ with $V' = V \cup \{s', t'\}$

(i) add two vertices s', t'

(ii) let $V^+ = \{v : \text{def}(v) > 0\}$.

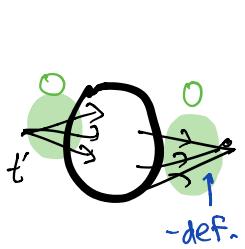
$V^- = \{v : \text{def}(v) < 0\}$.

(iii) For $v \in V^+$, add edge $e = (t', v)$
with $l(e) = 0$, $u(e) = \text{def}(v)$.

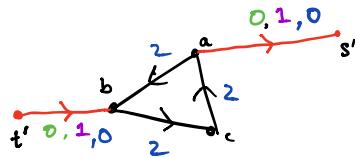
For $v \in V^-$, add $e = (v, s')$
w/ $l(e) = 0$, $u(e) = -\text{def}(v)$.

- Setting flow on new edges equal to upper capacities gives feasible flow for network G' with source s' , sink t' .

- initial value is



$$\sum_{v \in V} \text{def}(v) < 0.$$

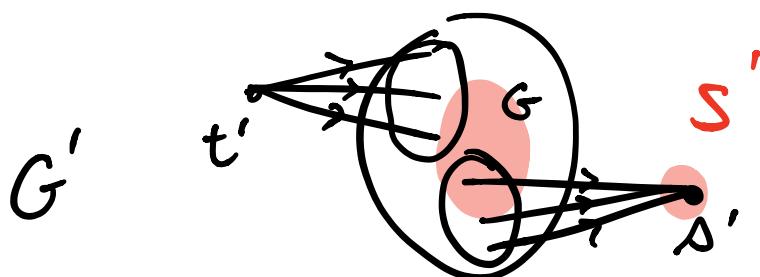


- Using this initial flow, apply Edmonds-Karp in G' to find max flow x ; note $|x| \leq 0$.
- If $|x| = 0$, restricting x to E gives circulation.
(all new edges have 0 flow).
- If $|x| < 0$, then no circ. exists (if it did, set flows to circ. values on old edges, flow 0 on new, \rightsquigarrow flow w/ value 0, contra.).

- In summary: to find feas. flow in G ,
find circulation in \tilde{G} by solving
max flow in \tilde{G}' . (if max flow in
 $\tilde{G}' < 0 \Rightarrow$ no circ. in $\tilde{G} \Rightarrow$ no feas. flow in
 G .)

When is a flow network
feasible?

- Enough to decide if there's
a circulation. (in \tilde{G})
- Use max-flow min-cut in \tilde{G}' .



- $s'-t'$ cut in G' is $S' = S \cup \{d\}$, $S \subseteq V$.
- MFM \Rightarrow maxflow = 0 $\Leftrightarrow C_{G'}(S') \geq 0$

- Capacity is

$\# s'-t' \text{ cuts}$
 S' .

$$C_G(S \cup \{S'\}) = C_G(S) = \sum_{e \in \delta^+(S)} u(e) - \sum_{e \in \delta^-(S)} l(e)$$

(because lower caps all 0 of new edges,

all new edges go into S' .).

To summarize:

Theorem G, l, u admits circulation iff $\forall S \subseteq V$,

$$\sum_{e \in \delta^+(S)} u(e) - \sum_{e \in \delta^-(S)} l(e) \geq 0. \quad \& l \leq u$$

Corollary Flow network feasible iff $l(e) \leq u(e) \forall e$ and

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$$\sum_{e \in \delta^+(S)} u(e) - \sum_{e \in \delta^-(S)} l(e) \geq 0$$

$\forall S$ s.t. $|S \cap \{s, t\}| \neq 1$.

PF: apply theorem to \tilde{G} , $c(S) = \infty$.

(General) min cut.

- Assume now $l=0$, so cut capacity is just

$$u(\delta^+(S)) := \sum_{e \in \delta^+(S)} u(e).$$

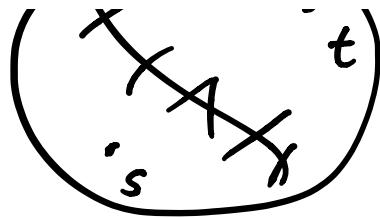
- We've shown how to find min s-t cut using max-flow.

- Can also solve

1-1 M

1-1 .

$$\min_{S-t \text{ cuts}} u(\delta(S))$$



in undirected graph by



- What about global minimum cut (not for fixed s, t)
- Can reduce to $2(n-1)$ maxflows:
 - (i) choose arbitrary vertex s
 - (ii) for any $t \in V \setminus \{s\}$,
solve for min $S-t$ cut,
min $t-S$ cut,
take whichever is smaller.

do this for all t .

- Fastest maxflow algos take around $\tilde{O}(mn)$ time (Goldberg-Tarjan), so our naive alg. takes $\tilde{O}(mn^2)$ time.
- Has-Orlin used relationships between the $O(n)$ flow problems to give an $O(mn \log(\frac{n^2}{m}))$ time alg for global mincut.

To do: • different alg. for

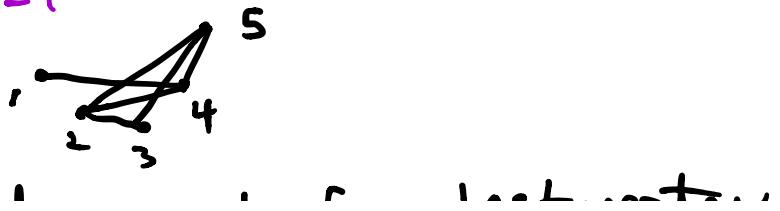
- ~~1.5 times~~ undirected "graphs.
- Not using max flow
 - Comparable runtime to
Hao-Orlin
- uses property of diminishing returns!
aka submodularity

Setup : • Let $G = (V, E)$ undirected,
• $u: E \rightarrow \mathbb{R}_{\geq 0}$ nonneg. edge costs.

Algorithm idea: arbitrary

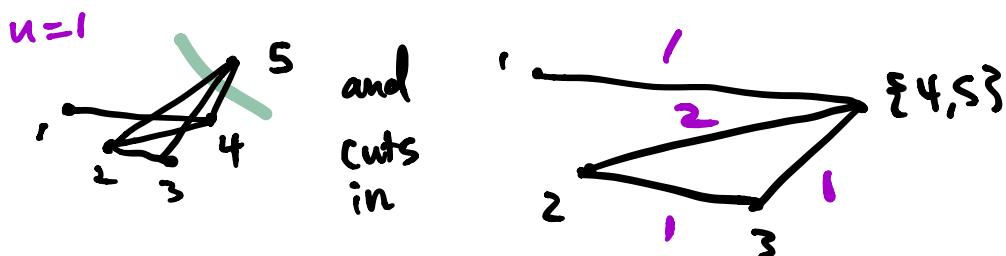
- starting with vertex,
build "max adjacency order",
i.e. greedily add the vertex w/
min cost to previous ones.

e.g. $u=1$



- Consider cut from last vertex,
and also cuts obtained by
shrinking last two vertices. (&
recursive?)

e.g.

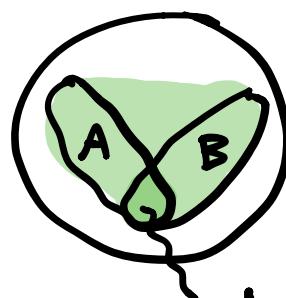


(duplicate edges get the sum of cost.).

- Claim: best cut found this way is global mincut.

Def: For $A, B \subseteq V$, define

$$u(A:B) := \sum_{\substack{i \in A \\ j \in B}} u((i,j)).$$



Algorithm (Stoer - Wagner)

$\text{MINCUT}(G)$ # output $\leq \dots$

▷ let v_1 any vertex of G

▷ $n := |V(G)|$

Create ordering

▷ initialize $S =$

▷ for $i=2 \dots n:$

▷ $v_i = \arg \min_{v \in V \setminus S} u(S \cup \{v\})$

▷ $S \leftarrow S \cup \{v_i\}$

▷ if $n=2:$

▷ return $\delta(\{v_1\})$.

▷ else:

▷ Get G' by shrinking $\{v_{n-1}, v_n\}$

recursive call

$r \wedge r'$

- ▷ Let $C = \text{MINCUT}(G)$
- ▷ return less costly of $C, \delta(\{V_n\})$.

Analysis: uses a claim.

Claim: $\{V_n\}$ is a min $V_{n-1} - V_n$ cut.

Claim \Rightarrow Correctness:

- The min cut is either a min $V_{n-1} - V_n$ cut, or not.
- If it is, claim \Rightarrow alg outputs it ✓
- If not, by induction on $n = |V(G)|$, algorithm outputs mincut in G ! ✓.

Proof of Claim:

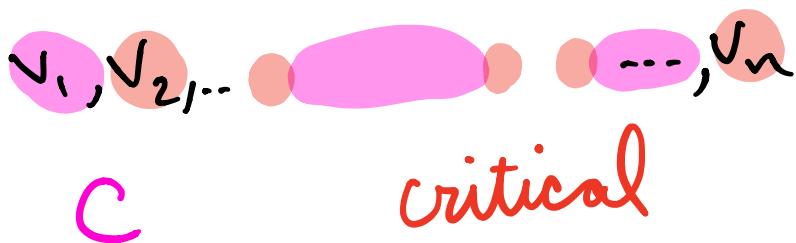
let $v_1, v_2, \dots, v_{n-1}, v_n$

be the ordering from alg.

- $A_j :=$ sequence v_1, \dots, v_{j-1}
- Consider candidate $v_{n-1}v_n$ cut, i.e. $C \subseteq V$ s.t.
 $v_{n-1} \in C, v_n \notin C$.
- Want to show
 $u(\delta(A_n)) \leq u(\delta(C))$,
.. (Ex 2)

incr_{v_i}, i.e. cut from $\{v_i\}$ is better than C.

- define v_i to be critical if either v_i or v_{i-1} in C but not both.



- Subclaim: Define $C_i := A_{i+1} \cap C$ iff v_i critical, then

$$u(A_i : \{v_i\}) \leq u(C_i : A_{i+1} \setminus C_i)$$

The diagram illustrates the subclaim. It shows two sequences of nodes. The top sequence is $v_1, v_2, \dots, v_i, v_{i+1}, \dots, v_m$. The bottom sequence is $v_1, v_2, \dots, v_{i-1}, v_i^*, v_{i+1}^*, \dots, v_m$. Green arrows point from v_i and v_{i+1} in the top sequence to v_i^* and v_{i+1}^* in the bottom sequence. A green bracket underlines the term $u(A_i : \{v_i\})$.



Subclaim suffices, because

$$\text{Subclaim} \Rightarrow \underbrace{u(\delta(A_n))}_{u(A_n : V_n)} \leq \underbrace{u(\delta(C))}_{u(C_n : A_{n+1} \setminus C_n)}$$

because V_n is critical.

Proof of subclaim:

by induction on seq. of critical vertices.

- **(base:)** true for first critical vertex.

- **(inductive:)** Assume true for critical v_i , let v_j next critical.

- Then

$$u(A_i : \{v_j\}) =$$

\leq

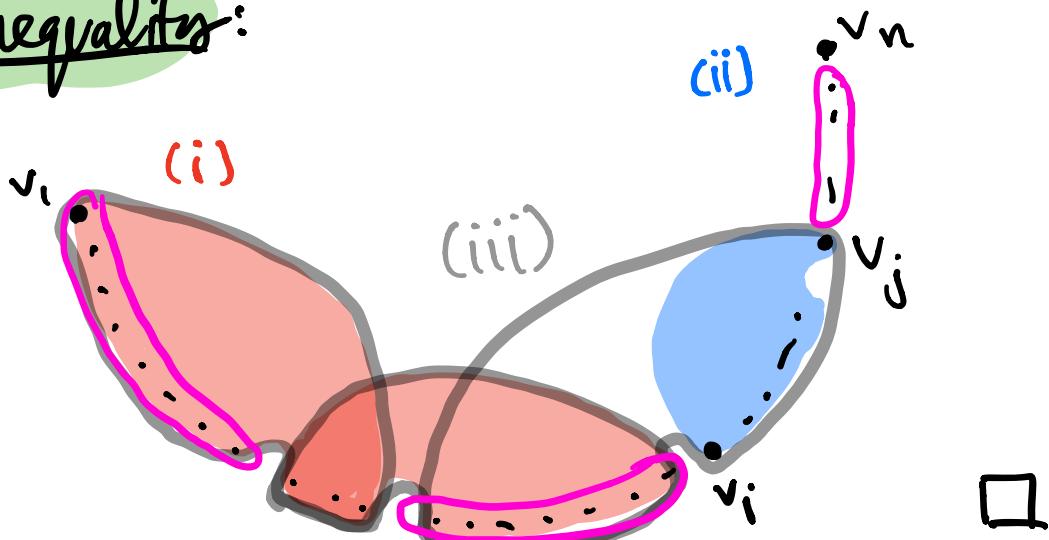
\leq

(i)

(ii)

$$\leq u(C_j : A_{j+1} \setminus C_j). \quad (iii)$$

Last inequality:



Running time:

Depends how you implement ordering:

- ▷ Exercise: each iteration can be done in $O(m + n \log n)$ time
(use e.g. Fibonacci heaps.)
- ▷ overall, \leq_n shrinks $\Rightarrow O(mn + n^2 \log n)$ time.

side note:

Submodularity

- Stoer-Wagner can be extended to minimize a more general class of functions than $S \mapsto u(\delta(S))$.
 - L' is submodular

- function $f: L \rightarrow \mathbb{R}$ submodular
 if $\boxed{\quad} \geq \boxed{\quad}$.

- Examples:

▷ $f(S) = \dots$,

▷ $f(S) = \dots$ for

u nonnegative, G undirected

Submodularity equivalent to
 "diminishing marginal returns":

For $S \supseteq T$, $v \notin S$,

$$\boxed{\quad} \leq \boxed{\quad}$$

- Above algorithm can be extended to minimize any symmetric ()
 submodular function.

↳ Queyranne '95.