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cverth/README

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Took advantage of extra credit; all I/O in main.

```
BinarySearchTree::Node* BinarySearchTree::m_min(Node* node) {
    while (node->left) {
        node = node->left;
    }
      return node;
BinarySearchTree::Result BinarySearchTree::predecessor(int key) {
     auto keyNode = m_search(m_root, key);
if (!keyNode) { // 'key' itself not in tree
  return {Status::INVALID_ARGUMENT, 0};
     fauto predecessorNode = m_predecessor(keyNode);
if (!predecessorNode) { // no predecessor
   return {Status::DNE, 0};
      return {Status::FOUND, predecessorNode->key}; // predecessor found
BinarySearchTree::Result BinarySearchTree::successor(int key) {
     auto keyNode = m_search(m_root, key);
if (!keyNode) { // 'key' itself not in tree
    return {Status::INVALID_ARGUMENT, 0};
     auto successorNode = m_successor(keyNode);
if (!successorNode) { // no successor
   return {Status::DNE, 0};
     return {Status::FOUND, successorNode->key}; // successor found
BinarySearchTree::Node* BinarySearchTree::m_predecessor(Node* node) {
    // CASE 1: predecessor is the maximum value "just less" than key of 'node'
    if (node->left) {
        return m_max(node->left);
    }
}
     // CASE 2: predecessor is the node whose successor is key of 'node'
auto temp = node->parent;
while (temp != nullptr && node == temp->left) {
           node = temp;
temp = temp->parent;
      return temp;
BinarySearchTree::Node* BinarySearchTree::m_successor(Node* node) {
    // CASE ! successor is the minimum value "just more" than key of 'node'
    if (node->right) {
            return m_min(node->right);
     // CASE 2: successor is the node whose predecessor is key of 'node'
auto temp = node->parent;
while (temp != nullptr && node == temp->right) {
    node = temp;
    temp = temp->parent;
}
      return temp;
void BinarySearchTree::insert(int key) {
  Node* node = new Node(key);
  Node* temp = m_root; // used to search for position to place 'node'
  Node* prev = nullptr; // trails behind 'temp'
```

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```
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                                    cverth/binary search tree.cpp
  *
@author Cole Van Verth
@pengo cverth
@email colevanverth@gmail.com
@file binary_search_tree.cpp
@assignment 7: Binary Search Tree
#include "binary_search_tree.h'
BinarySearchTree::BinarySearchTree() {}
BinarySearchTree::~BinarySearchTree() {
    m_destruct(m_root);
void BinarySearchTree::m_destruct(Node* node) {
    if (node) {
  auto left = node->left;
        auto right = node->right;
delete node;
        m_destruct(left);
m_destruct(right);
   }
BinarySearchTree::Status BinarySearchTree::search(int key) {
        (m_search(m_root, key)) {
        return Status::FOUND;
    return Status::DNE;
BinarySearchTree::Node* BinarySearchTree::m_search(Node* node, int key) {
  if (!node || node->key == key) {
    return node;
    if (key < node->key) {
         return m_search(node->left, key);
    élse ·
          return m_search(node->right, key);
BinarySearchTree::Result BinarySearchTree::min() {
   if (m_root) { // Min value only exists if tree has nodes
        return {Status::FOUND, m_min(m_root)->key};
    return {Status::DNE, 0}:
BinarySearchTree::Result BinarySearchTree::max() {
   if (m_root) { // Max value only exists if tree has nodes
    return (Status::FOUND, m_max(m_root)->key);
    return {Status::DNE, 0}:
BinarySearchTree::Node* BinarySearchTree::m_max(Node* node) {
   while (node->right) {
      node = node->right;
    }
    return node;
```

```
cverth/binary_search_tree.cpp
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                                                                                                                                            Page 3
               // Search for position to place 'node'
while (temp) {
  prev = temp;
  if (node->key < temp->key) {
    temp = temp->left;
}
                     else {
                          temp = temp->right;
                node->parent = prev; // 'prev' is node above nullptr node
               if (!prev) { // tree empty edge case
    m_root = node;
                     m_root :
return;
                // Sets the children of 'prev'
if (node->key < prev->key) {
   prev->left = node;
                else {
   prev->right = node;
           std::vector<int> BinarySearchTree::inOrderTraverse() {
               m_traversalBuffer.clear(); // Clear buffer
m inOrderTraverse(m root);
                return m_traversalBuffer;
           std::vector<int> BinarySearchTree::postOrderTraverse() {
    m_traversalBuffer.clear(); // Clear buffer
    m_postOrderTraverse(m_root);
    return m_traversalBuffer;
          std::vector<int> BinarySearchTree::preOrderTraverse() {
    m_traversalBuffer.clear(); // Clear buffer
    m_preOrderTraverse(m_root);
    return m_traversalBuffer;
           void BinarySearchTree::m inOrderTraverse(Node* node) {
                    (node) {
m_inOrderTraverse(node->left);
m_traversalBuffer.push_back(node->key);
m_inOrderTraverse(node->right);
           void BinarySearchTree::m_postOrderTraverse(Node* node) {
                    (node) {
m_postOrderTraverse(node->left);
                     m_postOrderTraverse(node->right);
                     m_traversalBuffer.push_back(node->key);
          void BinarySearchTree::m_preOrderTraverse(Node* node) {
  if (node) {
                    (node) {
    m_traversalBuffer.push_back(node->key);
    m_preOrderTraverse(node->left);
    m_preOrderTraverse(node->right);
```

```
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                                              cverth/binary_search_tree.cpp
                                                                                                                                           Page 4 Mon May 15 19:29:57 2023
                                                                                                                                                                                                        cverth/binary_search_tree.h
                                                                                                                                                               Finds the predeccessor.

@param 'key' key to find predecessor of

@return 'Result' indicating if 'key' did not exist, if predecessor to
'key' did not exist, or if predecessor to 'key' did exist with the

predecessor key
BinarySearchTree::Status BinarySearchTree::remove(int key) {
  auto deleteNode = m search(m_root, key);
  if (!deleteNode) { // 'key' to delete does not exist
    return Status::INVALID_ARGUMENT;
                                                                                                                                                             Result predecessor(int key);
     m_remove(deleteNode);
return Status::FOUND;
                                                                                                                                                             * Searchs for a key.
* @param 'key' key to search for
* @return 'Status' object indicating if 'key' was found
void BinarySearchTree::m_remove(Node* node)
    // CASE 1/2: 'node' has zero or one child
if (!node->left) {
    m_transplant(node, node->right);
                                                                                                                                                             Status search(int kev):
     } -
else if (!node->right) {
  m_transplant(node, node->left);
                                                                                                                                                                Removes a key from the tree.

@param 'key' key to remove

@return 'Status' objecting indicating if 'key' did not exist or if it was
      // CASE 3: 'node' has two children
                                                                                                                                                                removed
           ie {
    auto successor = m_successor(node);
    if (successor != node->right) { // 'node' has a right subtree > 1 child
        // transplant successor with right child
        m_transplant(successor, successor->right);
                                                                                                                                                             Status remove(int kev):
                                                                                                                                                                Inserts a key into the tree. @param 'key' key to insert
                 // update successor's new inherited right tree
                                                                                                                                                             void insert(int kev);
                successor->right = node->right;
successor->right->parent = successor;
           }
// transplate successor to 'node' itself
                                                                                                                                                             ' Invokes an in order traversal from 'm_root'.
* @return 'std::vector' containing the keys of the tree in order
           m_transplant(node, successor);
           // update successor's new inherited left tree
successor->left = node->left;
successor->left->parent = successor;
                                                                                                                                                             std::vector<int> inOrderTraverse();
                                                                                                                                                             /**
* Invokes a pre order traversal from 'm_root'.
* @return 'std::wector' containing the keys of the tree pre order
     delete node:
                                                                                                                                                             std::vector<int> preOrderTraverse();
void BinarySearchTree::m_transplant(Node* remove, Node* merge) {
   if (!remove->parent) { // edge case where 'remove' is the root
      m_root = merge;
                                                                                                                                                             ' Invokes a post order traversal from 'm_root'.
* @return 'std::vector' containing the keys of the tree post order
     }
else if (remove->parent->left == remove) { // 'remove' is a left child
  remove->parent->left = merge;
                                                                                                                                                             std::vector<int> postOrderTraverse();
     } else { // 'remove' is a right child
   remove->parent->right = merge;
                                                                                                                                                       private:
     if (merge) { // 'merge' exists
  merge->parent = remove->parent;
                                                                                                                                                             * Searchs for a 'Node'.

* @param 'node' node of root of valid binary search tree

* @param 'key' key of node to find

* @return 'Node*' of node with 'key' in 'node', else nullptr if it does not
                                                                                                                                                                exist
                                                                                                                                                             Node* m search(Node* node, int key);
                                                                                                                                                              * Finds a 'Node' with the smallest key.

* @param 'node' node of root of valid binary search tree

* @return 'Node*' of node with smallest key in 'node'
                                                                                                                                                             Node* m_min(Node* node);
                                                                                                                                           Page 1 Mon May 15 19:29:57 2023
                                                                                                                                                                                                        cverth/binary search tree.h
                                                 cverth/binary search tree.h
                                                                                                                                                                                                                                                                                                   Page 3
   @author Cole Van Verth
   @email cole van vertn
@email colevanverth@gmail.com
@file binary_search_tree.h
@assignment 7: Binary Search Tree
                                                                                                                                                             * Finds a 'Node' with the largest key.

* @param 'node' node of root of valid binary search tree

* @return 'Node*' of node with smallest key in 'node'
                                                                                                                                                             Node* m max(Node* node);
```

```
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#pragma once
#include <utility>
#include <vector>
class BinarySearchTree {
    struct Node; // Forward declaration
public:
     \overset{\star}{*} 'Status' enumerators are returned by public methods and convey information ^* about the result of an operation.
     enum Status {
    DNE = 0, // The result does not exist
    FOUND, // The result exists
    INVALID_ARGUMENT // Operation to calculate result could not execute
     /** ^{\prime} 'Result' objects are returned by public methods and contain an integer ^{\prime} output whose validity depends on its associated 'Result'. ^{\prime}
     typedef std::pair<Status, int> Result;
     /**
* 'BinarySearchTree' default constructor.
     BinarySearchTree();
       'BinarySearchTree' destructor.
     ~BinarySearchTree();
     Finds the smallest key in the tree.

* @return 'Result' containing min key in tree and found status, else DNE
'Result' if tree is empty
     Result min();
     Finds the largest key in the tree.

* Greturn 'Result' containing max key in tree and found status, else DNE
'Result' if tree is empty
     Result max():
       Finds the successor.

@param 'key' key to find successor of
@return 'Result' indicating if 'key' did not exist, if successor to 'key
did not exist, or if successor to 'key' did exist with the successor key
     Result successor(int key);
```

```
* Finds the successor of a 'Node'.

* @param 'node' node to find successor of

* @return 'Node*' successor to 'node'
Node* m_successor(Node* node);
/**
Finds the predecessor of a 'Node'.

* @param 'node' node to find predecessor of

* @return 'Node*' predecessor to 'node'
Node* m predecessor(Node* node);
   Removes all 'Node' objects including and under a provided 'Node';
invoked by 'Binary Search Tree' destructor.
(param 'node' base node to destruct from
void m_destruct(Node* node);
  Connects the parent of a 'Node' to another 'Node'.

@param 'remove' pointer to Node to connect its parent to 'merge'

@param 'merge' pointer to Node to connect itself to the parent o

'upper'
void m transplant(Node* remove, Node* merge);
* Deletes a node.
* @param 'node' node to delete
void m_remove(Node* node);
' Traverses the tree in order, filling 'm_traversalBuffer'.
* @param 'node' node to begin traversal at
void m inOrderTraverse(Node* node):
* Traverses the tree pre order, filling 'm_traversalBuffer'.
* @param 'node' node to begin traversal at
void m preOrderTraverse(Node* node);
Traverses the tree post order, filling 'm_traversalBuffer'.

* @param 'node' node to begin traversal at
void m postOrderTraverse(Node* node);
std::vector<int> m_traversalBuffer; // Temp array storage for traversals
Node* m_root = nullptr; // Root of 'Binary Search Tree'
```

```
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                                           cverth/binary_search_tree.h
                                                                                                                           Page 4 Mon May 15 19:29:57 2023
                                                                                                                                                                                           cverth/main.cpp
                                                                                                                                                                                                                                                                 Page 2
       'Node' objects are units that compose a 'Binary Search Tree'; they contain keys and can connect to their parent and children 'Node' objects.
                                                                                                                                      * Executes predecessor and prints results.
* @param 'tree' BST
* @param 'key' key to predecessor of
    */
struct Node {
   Node() = default;
   Node(int key) : key(key) {}
   Node* left = nullptr;
   Node* right = nullptr;
   Node* parent = nullptr;
   int key;
                                                                                                                                      void predecessor(BST& tree, int key);
                                                                                                                                         Executes successor and prints results.
};
};
                                                                                                                                     void successor(BST& tree, int key);
                                                                                                                                      * Traverses and prints BST in order.
* @param 'tree' BST
                                                                                                                                      void inorder(BST& tree);
                                                                                                                                      /**
* Traverses and prints BST post order.
* @param 'tree' BST
                                                                                                                                      void postorder(BST& tree);
                                                                                                                                      * Traverses and prints BST pre order.
* @param 'tree' BST
                                                                                                                                      void preorder(BST& tree);
                                                                                                                                      * Prints a vector containing traversal elements to STDOUT.
* @param 'vec' vector containing traversal elements
                                                                                                                                      void printTraversal(std::vector<int> vec);
                                                                                                                                      void insert(BST& tree, int key) {
                                                                                                                                          tree.insert(key);
std::cout << "inserted " << key << "." << std::endl;
                                                                                                                                      void search(BST& tree, int key) {
  auto status = tree.search(key);
  if (status == BST::Status::FOUND) {
    std::cout << key << " found." << std::endl;
    return;</pre>
                                                                                                                                           std::cout << key << " not found." << std::endl;</pre>
                                                                                                                                      void min(BST& tree) {
  auto result = tree.min();
  if (result.first == BST::Status::FOUND) {
    std::cout << "min is " << result.second << "." << std::endl;</pre>
                                                                                                                                               return;
                                                                                                                                           std::cout << "tree empty." << std::endl;
                                                                                                                                     void max(BST% tree) {
  auto result = tree.max();
  if (result.first == BST::Status::FOUND) {
    std::cout << "max is " << result.second << "." << std::endl;
    cverth/main.cpp</pre>
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                                                                                                                           Page 1 Mon May 15 19:29:57 2023
                                                    cverth/main.cpp
                                                                                                                                                                                                                                                                 Page 3
```

```
*
@author Cole Van Verth
@pengo cverth
@email colevanverth@gmail.com
@file main.cpp
@assignment 7: Binary Search Tree
/**

* This program implements a Binary Search Tree (BST). A "session trace" is read

* from STDIN in 'main' that allows the user to interact with the BST; the

* results of these operations are outputted to STDOUT. The program was tested by

* hand and with valgrind for memory leaks and appears to be working to all
#include <iostream>
#include <utility>
#include <string>
#include <sstream>
#include "binary_search_tree.h"
 typedef std::pair<std::string, int> Command; // From parsed session trace
typedef BinarySearchTree BST; // For brevity
   Processes a trace into a command. @param 'trace' trace of command
   @return 'Command' parsed from trace
Command processTrace(std::string trace);
   Executes search on BST and prints results.
   @param 'tree' BST
@param 'key' to search for
void search(BST& tree, int key);
   Executes insert on BST and prints results. 
@param 'tree' BST
@param 'key' key to insert
void insert(BST& tree, int key);
* Executes remove on BST and prints results.

* @param 'tree' BST
* @param 'tree'
   @param 'tree' BST
@param 'key' key to remove
void remove(BST& tree, int key);
* Executes min on BST and prints the min. * @param 'tree' BST
void min(BST& tree):
/**
  * Executes max on BST and prints the max.
  * @param 'tree' BST
  */
void max(BST& tree);
```

```
return:
       std::cout << "tree empty." << std::endl;
void successor(BST& tree, int key) {
  auto result = tree.successor(key);
  if (result.first == BST::Status::FOUND) {
    std::cout << key << " successor is " << result.second << "."
    << std::endl;</pre>
      else if (result.first == BST::Status::DNE) {
   std::cout << "no successor for " << key << "." << std::endl;</pre>
            std::cout << key << " not in tree." << std::endl;
      }
void predecessor(BST& tree, int key) {
  auto result = tree.predecessor(key);
  if (result.first == BST::Status::FOUND) {
    std::cout << key << " predecessor is " << result.second << "."
    << std::endl;</pre>
      else if (result.first == BST::Status::DNE) {
   std::cout << "no predecessor for " << key << "." << std::endl;</pre>
      else {
             - .
std::cout << key << " not in tree." << std::endl;
      }
void preorder(BST& tree) {
  std::cout << "preorder traversal:";
  printTraversal(tree.preOrderTraverse());</pre>
void postorder(BST& tree) {
   std::cout << "postorder traversal:";
   printTraversal(tree.postOrderTraverse());</pre>
void inorder(BST& tree) {
   std::cout << "inorder traversal:";
   printTraversal(tree.inOrderTraverse());</pre>
void printTraversal(std::vector<int> vec) {
      std::cout << std::endl;
for (size_t i = 0; i < vec.size(); i++) {
   if (i != 0) {
      std::cout << " " << vec[i];
   }
}</pre>
                  std::cout << vec[i];
            }
      std::cout << std::endl:
void remove(BST& tree, int key) {
  auto status = tree.remove(key);
  if (status == BST::Status::FOUND) {
    std::cout << "deleted" << key << "." << std::endl;</pre>
            return;
```

```
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                                                                       cverth/main.cpp
                                                                                                                                                                           Page 4
        std::cout << "delete " << key << " - not found." << std::endl;</pre>
Command processTrace(std::string trace) {
    // Remove after comment if there is one
    size_t commentIndex = trace.find("\psi");
    if (commentIndex != std::string::npos) {
        trace.erase(commentIndex);
    }
}
       // Parses command type and argument
std::stringstream ss(trace);
std::string commandType;
int argument;
ss >> commandType;
ss >> argument;
       return {commandType, argument};
int main() {
   BST tree;
   std::string trace;
   while (std::getline(std::cin, trace)) {
        Command command = processTrace(trace);
        auto commandType = command.first;
        auto commandArgument = command.second;
        if (commandType == "search") {
            search(tree, commandArgument);
        }
}
              } else if (commandType == "insert") {
   insert(tree, commandArgument);
              else if (commandType == "delete") {
   remove(tree, commandArgument);
              }
else if (commandType == "min") {
   min(tree);
              else if (commandType == "max") {
   max(tree);
}
              predecessor(tree, commandArgument);
              }
else if (commandType == "successor") {
   successor(tree, commandArgument);
              else if (commandType == "inorder") {
  inorder(tree);
              }
else if (commandType == "postorder") {
   postorder(tree);
}
              } else if (commandType == "preorder") {
   preorder(tree);
 } // End of main
```

Mon May 15 19:29:57 2023 cverth/makefile

p7: main.o binary_search_tree.o
g++ -o p7 main.o binary_search_tree.o

main.o: main.opp
g++ -c main.cpp
binary_search_tree.o: binary_search_tree.cpp binary_search_tree.h
g++ -c binary_search_tree.cpp

clean:
rm -f p7 *.o *~

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