## 8.3 Applications to physics and engineering centers Applications to Phisics and only neering So $m_1(\overline{x}-\overline{x}_1) = m_2(x_2-\overline{x}_2)$ = $\overline{x} = m_1x_1 + m_2x_2$ Moments $m_1 + m_2$ — +ose mss '(h general, a sistem of n objects / the controld is given by (x, y) $= \left(\frac{my}{m}, \frac{mx}{m}\right) \text{ where } m = \sum_{i=1}^{n} m_i = 4ptq(-muss)$ My = \$ mix; Mx = \$ mix; we moments Let R be 20 oblas with uniform donsity P Whate LEUNES 4- f(x), 4=g(x), (6)=g(x) on (0,6) We want to find control of r Sowe approximint R with rectugles and take limit r-(C) . Choose mappint X; $\gamma:g(x)$ form each subject x, $\frac{1}{2}\left(f(x)+g(x)\right)$ Mass of it is $PDX(f(\bar{x})+g(\bar{x}))$ So we compute moment is is $\mathbf{x}_{i}$ PD $\mathbf{x}(\mathbf{x}_{i})+\mathbf{g}(\mathbf{x}_{i})$ $\sum \overline{\mathbf{x}_i} P\Delta \mathbf{x} \left( f(\overline{\mathbf{x}_i}) + g(\overline{\mathbf{x}_i}) \right)$ So the moment as R limit

$$M_{y} = \lim_{n \to \infty} \overline{x}_{i} P \Delta x \left( f(\overline{x}) + g(\overline{x}) \right)$$

$$= P \int_{0}^{b} x \left( f(x) - g(x) \right) dx \qquad y \text{ usis}$$

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$$\frac{\left(\frac{1}{\lambda},\frac{1}{\lambda}\right)-\left(\frac{1}{A}\int_{a}^{b} x\cdot\left(f(x)-g(x)\right)dx}{\left(\frac{1}{\lambda}\int_{a}^{b}\frac{1}{\lambda}\left(f(x)-g(x)\right)dx}\right)dx}$$

Fx: find centraid of region bounded by come

$$\frac{1}{x^{2}} = \frac{1}{x^{2}} \int_{-1}^{2} \frac{1}{x^{2}} \left( \frac{1}{x^{2}} - \frac{1}{y^{2}} \right) dx \qquad x = \pm 2$$

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CevHvoid is (D,+)	$=\frac{3}{128}\left(64x-\frac{6x^{3}}{3}\right)\left[\frac{3}{78}\left(28-\frac{128}{3}\right)-\left(-118+\frac{128}{3}\right)\right]$