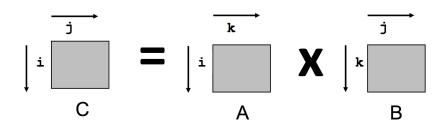
Lecture 11

$<\!2016\text{-}05\text{-}04\ Wed\!>$

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| 1 | M | atrix Multiplication | | | | | | | |
| \bullet multiply n \times n matrices | | | | | | | | | |
| | • el | ments are double | | | | | | | |
| | O(N³) total operations N reads per source element | | | | | | | | |
| | | | | | | | | | |
| | • N | values summed per destination | | | | | | | |
| | | | | | | | | | |

- but may be able to hold in register



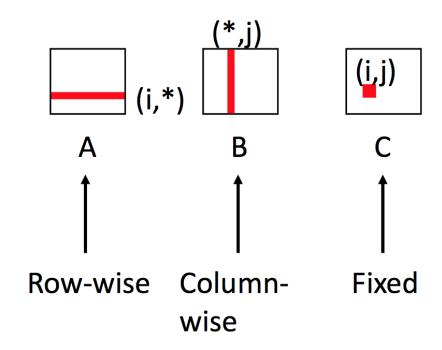
1.0.1 Basic

- assumptions
 - block size 32 bytes (4 doubles)
 - matrix dimension (N) very large
 - * approximate 1 / N as 0.0
 - cache is not big enough to hold multiple rows
 - n \times n matrix
- review
 - assume block size (B) > sizeof (a_{i,j})
 - C arrays allocated in row-major order
 - * each row in contiguous memory locations

```
for (i = 0; i < n; i++) {
  for (j = 0; j < n; j++) {
    sum = 0.0;
  for (k = 0; k < n; k++) {
      sum += a[i][k] * b[k][j];
    }</pre>
```

```
c[i][j] = sum;
}
```

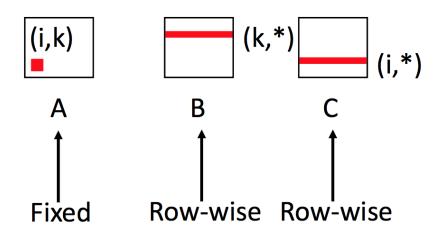
Inner loop:



```
miss per inner loop iteration explanation
  Α
                                    sizeof(double) / block size = 8 / 32
                              0.25
  В
                                    step by column, stride too big
                               1.0
  \mathbf{C}
                                   local variable, temporal locality
      kij / ikj
1.0.3
for (k = 0; k < n; k++) {
  for (i = 0; i < n; i++) {
    r = a[i][k];
    for (j = 0; j < n; j++) {
      c[i][j] += r * b[k][j];
    }
  }
```

}

Inner loop:



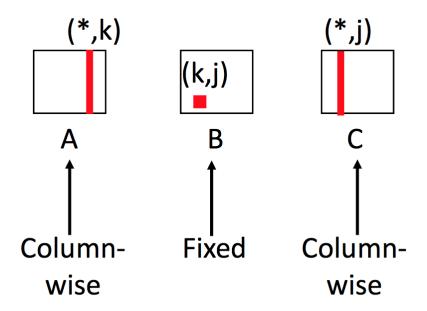
```
miss per inner loop iteration explanation
```

```
A 0.0 local variable, temporal locality B 0.25 sizeof(double) / block size = 8 / 32 C 0.25 sizeof(double) / block size = 8 / 32
```

1.0.4 jki / kji

```
for (j = 0; j < n; j++) {
  for (k = 0; k < n; k++) {
    r = b[k][j];
  for (i = 0; i < n; i++) {
    c[i][j] += a[i][k] * r;
  }
}</pre>
```

Inner loop:



| | miss per inner loop iteration | explanation |
|--------------|-------------------------------|-----------------------------------|
| A | 1.0 | step by column, stride too big |
| В | 0.0 | local variable, temporal locality |
| \mathbf{C} | 1.0 | stride too big, always miss |

1.0.5 Summary

| | ijk / jik | kij / ikj | jki / kji |
|----------------------|--------------------|-------------------|-------------------|
| loads & stores | 2 loads, 0 strores | 2 loads, 0 stores | 2 loads, 1 stores |
| misses per iteration | 1.25 | 0.5 | 2.0 |

1.1 Matrix Multiplication Without Block

```
void mmm(double *a, double *b, double *c, int n) {
  int i, j, k;
  for (i = 0; i < n; i++)
    for (j = 0; j < n; j++)
    for (k = 0; k < n; k++)</pre>
```

```
c[i*n + j] += a[i*n + k] * b[k*n + j];}
```

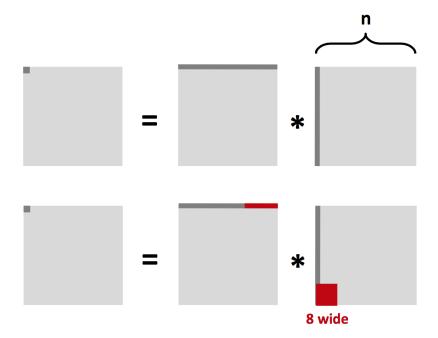
1.1.1 Cache Miss Analysis

- \bullet assume
 - matrix elements are double
 - cache block = 8 doubles (64)
 - cache size C much smaller than n
- misses each iteration

$$- n / 8 + n = 9n/8$$

• total miss

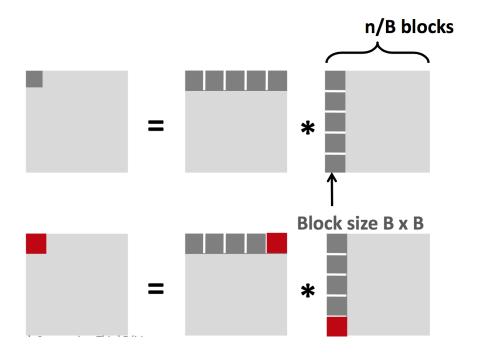
$$-9n/8 \times n^2 = (9/8) \times n^3$$



1.2 Blocked Matrix Multiplication

```
for (i = 0; i < n; i += B)
  for (j = 0; j < n; j += B)
  for (k = 0; k < n; k += B)
      /* B by B mini matrix multiplications */
  for (i1 = i; i1 < i+B; i1++)
      for (j1 = j; j1 < j+B; j1++)
      for (k1 = k; k1 < k+B; k1++)
            c[i1*n + j1] += a[i1*n + k1] * b[k1*n + j1];
}</pre>
```

- assume
 - cache block = 8 doubles
 - cache size C much smaller than n
 - (n/B) × (n/B) as a mini matrix, B × B mini matrix multiplications
 - 3 blocks can fit into cache: $3B^2 < C$
- misses per iteration
 - B²/8 misses per block
 - $-2n/B \times B^2/8 = nB/4$ (omitting matrix c)
- total misses
 - $nB/4 \times (n/B)^2 = n^3/(4B)$



1.2.1 Summary

- no blocking: $(9/8) \times n^3$
- blocking: $1/(4B) \times n^3$
- \bullet B has limit $3B^2 < C$
- reason for dramatic difference
 - matrix multiplication has inherent temporal locality
 - * input data: 3n², computation 2n³
 - * every element used O(n) times
 - but program has to be written properly

1.3 Summary

- the speed gap between CPU, memory and mass storage continues to widen
- well written programs exhibit a property called locality

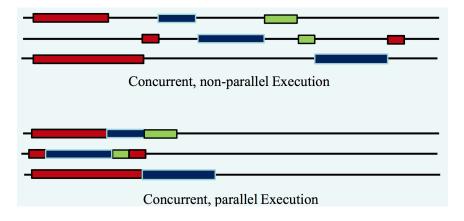
- memory hierarchies based on caching close the gap by exploiting locality
 - cache memories can have significant performance impact
- you can write your programs to exploit this
 - focus on the inner loops, where bulk of computations and memory accesses occur
 - try to maximize $spatial\ locality$ by reading data objects with sequentially with stride 1
 - try to maximize temporal locality by using data objects as often as possible once it's read from memory

2 OpenMP

• OpenMP is one of the most common parallel programming models in use today

2.1 Concurrency vs. Parallelism

- concurrency
 - a condition of a system in which multiple tasks are logically active at one time
- parallelism
 - a condition of a system in which multiple tasks are actually active at one time



• concurrent application

- an application for which computations *logically* execute simultaneously due to the semantics of the application

• parallel application

- an application for which the computations *actually* execute simultaneously in order to complete a problem in less time

2.2 OpenMP

- an API for writing multithreaded applications
 - a set of compiler directives and library routines for parallel application programmers
 - greatly simplifies writing multi-threaded programs in Fortran, C and C++
- compiler directives #pragma omp contruct [clause [clause] ...]
- function prototypes and types in the file omp.h

```
#pragma omp parallel num_threads(4)
#include <omp.h>
```

- most OpenMP constructs apply to a structured block
 - structured block
 - * a block of one or more statements with one point of entry at the top and one point of exit at the bottom
 - * it's OK to have an exit() within the structured block
- compiler flag
 - gcc -fopenmp foo.c
 - export OMP_NUM_THREADS=4 (for bash shell)

2.2.1 Example

```
#include <omp.h>
int main() {
    #pragma omp parallel
    {
        int ID = omp_get_thread_num();
        printf("hello(%d) ", ID);
        printf("world(%d)\n", ID);
    }
}
```

2.2.2 Shared Memory

- shared memory computer
 - any computer composed of multiple processing elements that share an address space
 - * symmetric multiprocessor (SMP)
 - \cdot a shared address space with "equal-time" access for each processor, and the OS treats every processor the same way
 - * non uniform address space multiprocessor (NUMA)
 - · different memory regions have different access costs ... think of memory segmented into "near" and "far" memory
- shared memory program
 - an instance of a program
 - * one process and lots of threads
 - * threads interact through reads/writes to a shared address space
 - * OS scheduler decides when to run which threads
 - · interleaved for fairness
 - st synchronization to assure every legal order results in correct results