Multi-View Visual Question Answering with Active Viewpoint Selection

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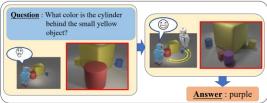


Motivation

- Visual Question Answering:
- > A vision and language multi-modal task that aims at answering a given question regarding the content of a provided image.
- Conventional single view VOA:
- > less ability to recognize geometrical information, so that they tend to fail to count or decide spatial relationship.
- > less ability to determine blind space for working in highly-occluded realworld environments.

Introduction

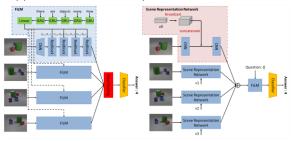




- A multi-view VOA framework with viewpoint selection
- ➤ A DNN archtecture incorporating VQA, Scene Representation and Viewpoint selection modules
- Results:
 - Keeps performance against VOA using all
 - Reduces trivial observation largely
 - Applicable on both CG and Real Images
 - Run time: 0.035 sec / VOA sample on average

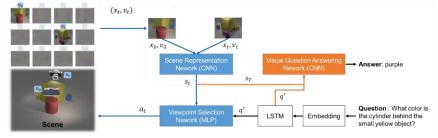
Approach

Approach 1: View pooling + FiLM (VQA Backbone) Approach 2: Scene Representation Network + FiLM



- View pooling : max/average pooling for integrating multiview image features.
- Scene Representation Network : CVAE-based structure for representing 3D scene and rendering images from guery viewpoint.
- > FiLM : Feature-wise Linear Modulation.

Approach 3: Scene Representation Network + Viewpoint Selection Network + FiLM



- Viewpoint Selection Network (Deep Q-learning Network based) :
- ✓ Input: Observed scene representation, question feature
- ✓ Output: Next observation viewpoint.
- ✓ Reward: Based on VOA accuracy and trajectory length.

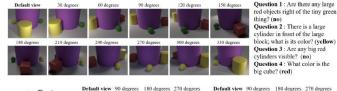
Dataset

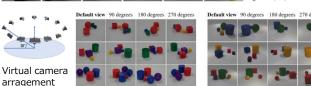
CG Dataset:

- ✓ Image generation: Place objects on blender scene. Photograph from multiple observation viewpoint.
- Question generation: Generated automatically from function programs based on scene information.

Real Dataset:

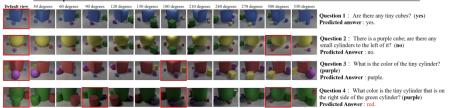
- Image generation: Real photograph
- Question generation : Generated from function program.





Experiments

Example results of SRN FiLM VS on Multi-view-CLEVR 12views CG dataset



Results on Multi-view-CLEVR 12views CG

Methods	Overall accuracy	Spati Exist	al-related Query color	Noi Exist	n-spatial Query color	Average used viewpoints
SRN_FiLM	97.37%	94.20%	98.20%	99.03%	98.11%	12
SRN_FiLM_VS	97.11%	95.27%	96.90%	99.03%	97.25%	2.98

Effect of viewpoint selection

Methods (viewpoint numbers)	Overall accuracy	Methods
SRN_FiLM_Random (3 views) SRN_FiLM_Equal (3 views) SRN_FiLM_VS (2.98 views)	81.39% 82.90% 97.11 %	SRN_FiLM SRN_FiLM

Methods		Accuracy	Used	Viewpoii	nts

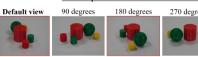
Results on Multi-view-CLEVR 4views CG

270 degrees

Methods	Accuracy	Used Viewpoints	
SRN_FiLM SRN_FiLM_VS	97.67% 97.64%	4 2.02	

Example results on Multi-view-CLEVR 12views Real dataset

Default view



Question 1 : Are there any small blue objects? (no) SRN FiLM (Fine-tuning): no SRN FiLM VS (Fine-tuning): no



SRN FiLM (Fine-tuning): yes

SRN FiLM VS (Fine-tuning): yes





Question 3: There is a blue sphere; are there any blocks behind it? (yes)

Question 2: The large sphere is what color? (blue) SRN FiLM (Fine-tuning): purple SRN FiLM VS (Fine-tuning); blue



Question 4: What color is the cube behind the big purple cube? (green) SRN FiLM (Fine-tuning): blue SRN FiLM VS (Fine-tuning); purple

Results on Multi-view-CLEVR 4views Real

Methods	Fine-tuning SRN FiLM		Accuracy
SRN_FiLM SRN_FiLM SRN_FiLM SRN_FiLM SRN_FiLM_VS SRN_FILM_VS	- - - - -	- √ - √	67.88% 76.14% 77.30% 82.62% 66.82% 79.99%
SRN_FiLM_VS SRN_FiLM_VS	√ ✓	- - -	91.56% 94.01 %

References

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