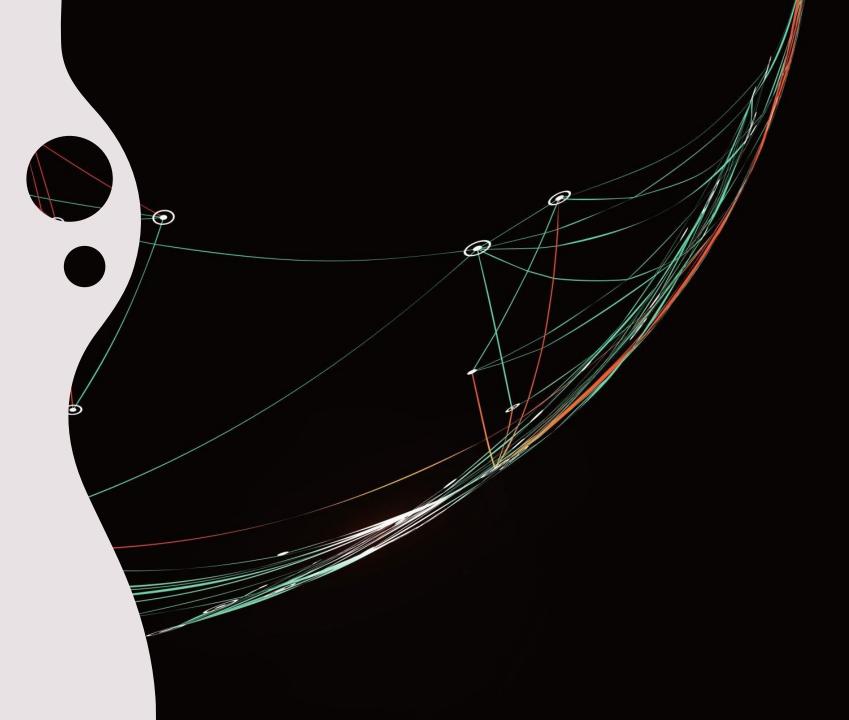
Computer Vision Assignment

Hugo Collins 40446925



Dataset Preparation

```
Folder: n02808440 - Label: 0 - Class Name: bathtub, bathing tub, bath, tub
Folder: n01742172 - Label: 1 - Class Name: boa constrictor, Constrictor constrictor
Folder: n01443537 - Label: 2 - Class Name: goldfish, Carassius auratus
Folder: n02909870 - Label: 3 - Class Name: bucket, pail
Folder: n02481823 - Label: 4 - Class Name: chimpanzee, chimp, Pan troglodytes
Folder: n02364673 - Label: 5 - Class Name: guinea pig, Cavia cobaya
Folder: n02788148 - Label: 6 - Class Name: bannister, banister, balustrade, balusters, handrail
Folder: n01984695 - Label: 7 - Class Name: spiny lobster, langouste, rock lobster, crawfish, crayfish, sea crawfish
Folder: n02504458 - Label: 8 - Class Name: African elephant, Loxodonta africana
Folder: n03126707 - Label: 9 - Class Name: crane
Folder: n03179701 - Label: 10 - Class Name: desk
Folder: n02509815 - Label: 11 - Class Name: lesser panda, red panda, panda, bear cat, cat bear, Ailurus fulgens
Folder: n02730930 - Label: 12 - Class Name: apron
Folder: n03160309 - Label: 13 - Class Name: backpack, back pack, knapsack, packsack, rucksack, haversack
```

- First 400 from each folder selected for training
- Last 100 selected for testing
- For fine tuning I needed a validation set
- So split 400 training into 300/100 with the last 100 used for validation
- Final split per folder
- 300/100/100
- Final Split Overall
- 4500 Training /1500 Validation /1500

Handcrafted Features

Preprocessing Differences:

SIFT - Used histogram equalisation and masking to enhance image

ORB - Resized images to 256 x 256

Model	Num_Words	Accuracy
SIFT Bag of Words	50	21.67%
SIFT Bag of Words	100	23.13%
SIFT Bag of Words	150	21.47%
SIFT Bag of Words	200	20.40%
ORB Bag of Words	50	24.07%
ORB Bag of Words	100	22.73%
ORB Bag of Words	150	22.40%
ORB Bag of Words	200	21.87%

Model	Num_Clusters	Accuracy
SIFT Fisher Vector	25	14.07%
SIFT Fisher Vector	50	18%
SIFT Fisher Vector	100	15.73%
ORB Fisher Vector	25	20.60%
ORB Fisher Vector	50	24.09%
ORB Fisher Vector	100	22.67%

Key Takeaways:

- SIFT was far more computationally expensive
- With BoW SIFT was more suited
- After 125 Key words overfitting happened
- The statistical power of GMM proved useful
- ORB and fisher vector outperformed other
- Still poor results with depedency on certain features and prone to default to guessing same label.

Linear Neural Network and Convolutional Neural Network Training Phase

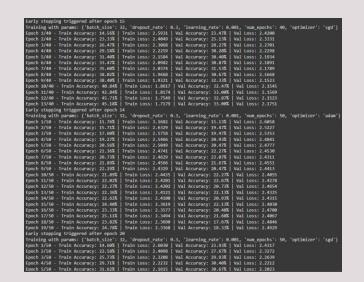
Preprocessing:

- Dataset had mix of greyscale and RGB
- Converted all to RGB
- Batched into default size of 32 using DataLoader
- Transformed to tensor and normalised data

Training Process:

- 1. Start with a base model with simple number of layers.
- 2. Find downfalls and try improve on previous
- 3. Create a set of models and test
- 4. Choose a model to take for further improvement
- 5. Apply techniques like early stopping, hyperparameter tuning and batch normalisation

```
param_grid = {{
    'learning_rate': [0.001, 0.01],
    'batch_size': [32,64,128,256],
    'dropout_rate': [0.3,0.5],
    'num_epochs': [40,50,60],
    'optimizer': ['adam', 'sgd'] #
}
```



Techniques Used:

- 1. Early Stopping with Patience
- 2. Hyperparameter Tuning:
 - Optimiser Type
 - Learning Rate
 - Batch Size
 - Number of epochs
 - Dropout Rate
 - Learning Rate Scheduler
- 3. Data Augmentation
- 1. Batch Normalisation
- 5. Global Average Pooling (CNN)

Linear Neural Network

Models:

LinearNNV1: Baseline

Input Size: 12288 (Flattened Image)

Hidden Layers: $2 \rightarrow [512, 256]$

Activation: ReLU

Dropout: 0.5 (after each layer)

Output: 15 neurons (for 15 classes)

LinearNNV2: Adding Layers

Hidden Layers: 4 → [1024, 512, 256, 128]

• Dropout: 0.3

LinearNNV3: Improved Feature Extraction

• Hidden Layers: 6 → [2048, 1024, 512, 256, 128, 64]

Dropout Strategy: Gradually decreasing $(0.5 \rightarrow 0.2)$

Goal: Better generalisation with strong feature learning

Final Model

- V2
- Early Stopping
- SGD (0.001 LR)
- Batch Size = 128

Model (architecture)	Epochs	Batch_Size	Optimiser	Data Augmentation	Early Stopping	Hyperparameter Tuning	Training Acc	Validation Acc	Test Acc	Test Loss
V1	40	32	Adam(lr=0.001)	No	No	No	27.73%	19.20%	22.60%	2.4754
V2	40	32	Adam(lr=0.001)	No	No	No	30.18%	18.07%	18.20%	2.6662
V3	40	32	Adam(lr=0.001)	No	No	No	33.93%	23.93%	25.73%	2.6344
V1	50	64	SGD(lr=0.001 Dropout=0.3)	No	Yes	Yes	48.31%	34.26%	33.47%	2.1243
V2	60	128	SGD(lr=0.01 Dropout=0.3)	No	Yes	Yes	39.73%	32.47%	31.53%	2.1900
V3	40	32	SGD(lr=0.01) Dropout=0.3	No	Yes	Yes	38.76%	28.13%	26.54%	2.4587

Model (architecture)	Epochs	Batch_Size	Optimiser	Data Augmentation	Early Stopping	Hyperparameter Tuning	Training Acc	Validation Acc	Test Acc	Test Loss
V2	60	128	SGD(0.001, momentum=0.9) Dropout Rate=0.3	No	Yes (Patience=5)	Yes	45.42%	32.47%	33.00%	2.1522.
V2	60	128	SGD(0.001, momentum=0.9) Dropout Rate=0.5	No	Yes (Patience=5)	Yes	32.09%	29.73%	30.00%	2.1893
V2	100	128	SGD(0.001, momentum=0.9) Dropout Rate=0.3	Yes	Yes (Patience-5)	Yes	44.20%	28.93%	30.47%	2.2116
V2	100	128	SGD(0.001, momentum=0.9) Dropout Rate=0.5	Yes	Yes (Patience-5)	Yes	35.00%	27.33%	27.67%	2.2888

Convolutional Neural Network

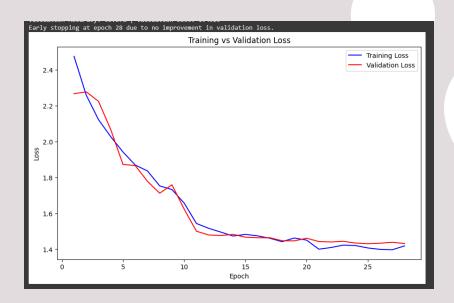
Had a varying number of models ranging from V1-V8

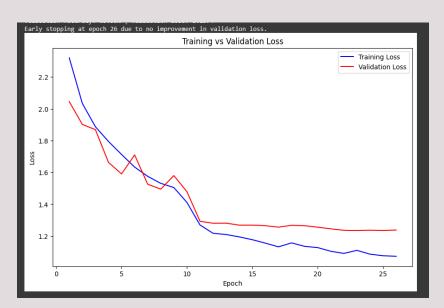
V1-V5 focused on varying number of convolutional layers, dropout rates and fully connected layers

V6-V8 built on this but incorporated batch normalisation and global average pooling

Key Takeaways

- Early Stopping was effective
- Four Convolutional Layers was best amount
- Battle between overfitting and performance
- Adam Optimiser best with small learning rate
- Augmentation improved fit





Comparison of Best Models

Model	Epochs/Number of Clusters	Architecture	Hyperparameters	Test Accuracy	
ORB Fisher Vector	50	Fitted Gaussian Mixture Model Classified using LinearSVC() Output (15 classes)	Max_iter=1000, C=0.1	24.09%	
LinearNNV2	60	Input Size - 64 x 64 x 3 Flattening Layer - (12288) Four Hidden Layers = [1024, 512,256,128] ReLU Activation Dropout - 30% Output(15 classes)	Batch_size = 128 Optimiser = SGD Learning Rate=0.001 Momentum = 0.9 Loss = CrossEntropy Dropout Rate=0.5 Early Stopping Patience = 5	33.00%	
CNNV7	100	Input (64×64×3) → Conv1 (16 filters, 3×3, ReLU, BN, MaxPool 2×2) → Conv2 (32 filters, 3×3, ReLU, BN, MaxPool 2×2) → Conv3 (64 filters, 3×3, ReLU, BN, MaxPool 2×2) → Conv4 (128 filters, 3×3, ReLU, BN, MaxPool 2×2) → Global Avg Pool → Fully Connected Layer (128 → 15) → Dropout (20%) → Output (15 classes). BN (Batch Normalisation)	Batch_size= 64 Optimiser = Adam Learning Rate=0.001 Scheduler = StepLR(10,0.1) Loss=CrossEntropy Dropout Rate = 0.2 Early Stopping Patience=3 Data Augmentation=No	62.27%	
CNNV7 Data Augmentation	100	Same as above	Same as above except Data Augmentation=True	58.67% (Neater Train/Valoss plot)	

Error Analysis

Linear NN vs Handcrafted Features

- •Handcrafted Model: Relied on dominant features → High recall, low precision (e.g., guinea pigs & spiny lobsters).
- •Linear NN: Learned more balanced features → Better precision & recall, improved performance on labels like 2 & 13.

Linear NN vs CNNs

- •Linear NN Mistakes: Predicted chimpanzee (4) as backpack (14) \rightarrow Features not informative.
- •CNN Advantage: Avoided major mistakes, instead misclassifying boa constrictor (1) as spiny lobster (7) \rightarrow More logical errors based on shared visual features.

Key Test Case: Bucket & Pail (Label 3)

- •Worst-performing category across all models due to distractions in images.
- •Handcrafted Model: Focused on irrelevant features (e.g., eyes).
- •CNN: Extracted useful spatial features, leading to far more correct predictions.





