

# Ch 3 - Oscillatory Motion & Chaos

Ex of Oscillatory phenomenon

- Motion of electrons in atoms
- Currents & voltages in electronic circuits
- Planetary orbits

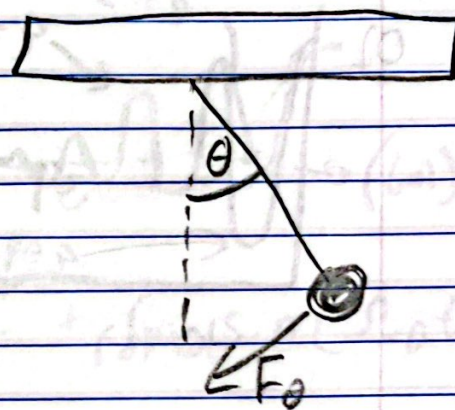
## 3.1 Simple harmonic motion

$$F_g = -m \cdot g \sin \theta$$

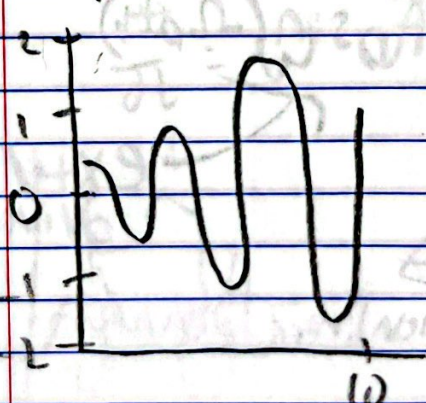
$$\theta = \theta_0 \sin(\omega t + \phi)$$

$$\omega = \sqrt{g/L}$$

$$\theta_{i+1} = \theta_i + \omega_i \Delta t$$



Simple Pendulum - Euler Method

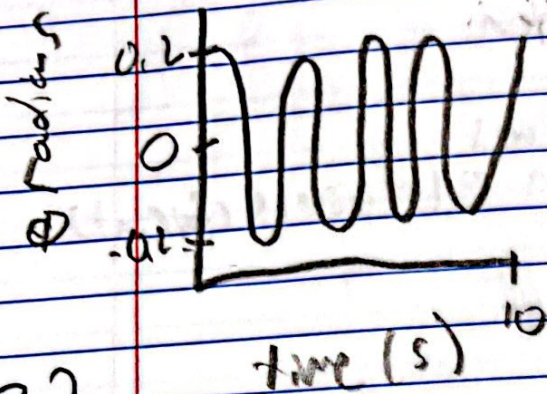


$$E = \frac{1}{2} m \omega^2 l^2 + mgl(1 - \cos \theta)$$

$$E_{i+1} = E_i + \frac{1}{2} mgl(\omega_i^2 + \frac{g}{L} \theta_i^2) \Delta t^2$$



## Simple Pendulum - Euler-Cromer Method

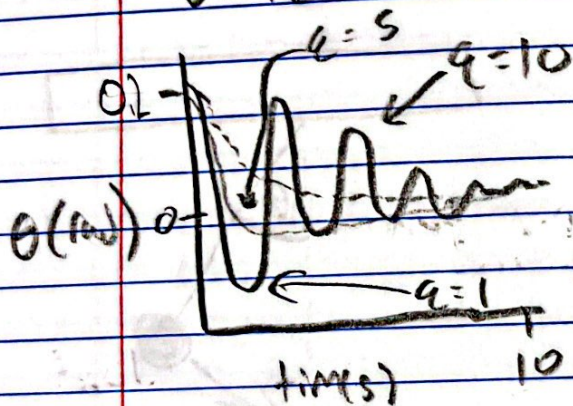


$$\frac{d^2x}{dt^2} = -kx^a$$

$$\theta(t) = \theta_0 e^{-\gamma t/2} \sin(\sqrt{\omega^2 - \gamma^2/4} t + \phi)$$

3.2

damped pendulum



$$\theta(t) = \theta_0 e^{-(\gamma/2 \pm \sqrt{\gamma^2/4 - \omega^2})t}$$

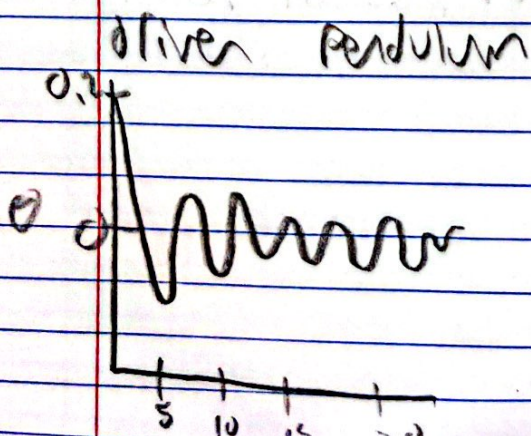
Between the two extremes

$$\theta(t) = (\theta_0 + \epsilon) e^{-\gamma t/2}$$

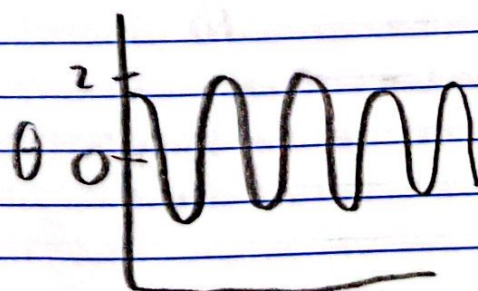
Equation of motion

$$\frac{d^2\theta}{dt^2} = -\frac{g}{L}\theta - \epsilon \frac{d\theta}{dt} + F_0 \sin(\omega_0 t)$$

external driving force



nonlinear pendulum





Steady State Solution:

$$\theta(t) = \theta_0 \sin(\Omega_0 t + \phi)$$

where:

$$\theta = \frac{F_0}{\sqrt{(\Omega^2 - \Omega_0^2)^2 + (c\Omega_0)^2}}$$

Now the equation of Motion =

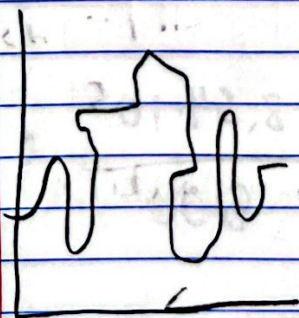
$$\frac{d^2\theta}{dt^2} = -\frac{g}{l} \sin\theta$$

3.3 - Driven Non-linear Pendulum  
equation of motion

$$\frac{d^2\theta}{dt^2} = -\frac{g}{l} \sin\theta - c \frac{d\theta}{dt} + F_0 \sin(\Omega_0 t)$$

$$\frac{dw}{dt} = -\frac{g}{l} \sin\theta - c \frac{d\theta}{dt} + F_0 \sin(\Omega_0 t)$$

$$\frac{d\theta}{dt} = w \quad \checkmark$$



← Example of non-linear  
chaotic pendulum