

# With great power comes greater responsibility: cheating with bdots

## Abstract

Gutting this entire thing and starting from scratch

## 1 Introduction

Free write

The original bdots presented a method whereby the difference in time series between two groups could be analyzed using a FWER correction to the alpha based on the autocorrelation of the resulting t-statistics

While we can confirm that the published results do indeed hold for the case they presented, such a situation is likely atypical and not reflective of the typical case involving VWP data. bdots involved testing between two groups, yet assumed that all subjects within a group had identical mean structures – that is, there was no between-subject variability to be accounted for.

More likely it is the case that in the comparison of two groups, each group has a typical distribution of parameters for its subjects. God its annoying a little bit how bad and out of order this is, but free write so its ok for now. As we show, when the initial (and restrictive) assumptions made in the original bdots doesn't hold, the resulting TIE is beyond what would be acceptable in most cases.

What we present instead is two alternatives, accommodating flexibility in two of the assumptions made in the original bdots. First, we propose a modified bootstrapping procedure that adequately accounts for observed between subject variability while retaining the novel FWER adjustment method presented for autocorrelated errors. In addition to this, we offer a play on a standard permutation test between the groups, borrowing from the insight of the original bdots in that it also captures within-subject variability as demonstrated in the standard errors in the model fits. We begin by describing the two proposed alternatives to the original bdots bootstrap. We then outline the details of the simulations in demonstrating the TIE rate across a number of experimental conditions, along with the results. Finally if there is time we consider

a power analysis of the two resulting methods. I guess it's also fine to consider power in the case in which the original bdots does well. Naturally, the power is great, but then so what?

## 2 Detail on the original

Most generally the original bdots proposed that we have empirically observe data resulting from some mean structure with an associated error, with

$$y_{it} = f(\theta_{it}) + \epsilon_{it} \quad (1)$$

where

$$\epsilon_{it} = \phi\epsilon_{i,t-1} + w_{it}, \quad w_{it} \sim N(0, \sigma). \quad (2)$$

Under this paradigm, the errors could be iid normal (with  $\phi = 0$ ) or have an AR(1) structure, with  $0 < \phi < 1$ . The unspoken assumption, however, with two subjects from the same group is that  $\theta_{it} = \theta_{jt}$  for all  $i, j$ . In other words, it was assumed that there was no variability in the mean structure between subjects in the same group. This is also evidenced in the original bdots algorithm:

1. For each subject, fit the nonlinear function, specifying AR(1) autocorrelation structure for model errors. Assuming large sample normality, the sampling distribution of each estimator can be approximated by a normal distribution with mean corresponding to the point estimate and standard deviation corresponding to the standard error
2. Using the approximate sampling distributions in (1.), randomly draw one bootstrap estimate for each of the model parameters on every subject
3. Once a bootstrap estimate has been collected for each parameter and for every subject, for each parameter, find the mean of the bootstrap estimates across individuals
4. Use the mean estimates to determine the predicted population level curve, which provides the average population response at each time point

The previous statement is demonstrated in step (2.), where each subject is included in each iteration of the bootstrap.

Maybe here (to tie into the bottom) I could note that  $\theta_i \sim N(\theta, V)$  except here  $V = 0$

## 3 Proposed Methods

Here, we will describe in detail each of the proposed methods

### 3.1 Modified Bootstrap

A more likely case involving subjects in the VWP (or subjects within any group exhibiting between and within subject variability) is as such: suppose for example that we are considering a family of four parameter logistic curves, defined

$$f_{\theta}(t) = \frac{p - b}{1 + \exp\left(\frac{4s}{p-b}(x - t)\right)} + b \quad (3)$$

where  $\theta = (p, b, s, x)$ , the peak, baseline, slope, and crossover parameters, respectively. The distribution of parameters for subjects within this group may be normally distributed, with any individual subject  $i$ 's parameters following the distribution

$$\theta_i \sim N(\mu_{\theta}, V_{\theta}). \quad (4)$$

In the course of collecting observed data on subject  $i$ , we may find that there is a degree of variability in our observations between trials, reflected in the standard errors derived when fitting the observed data to the functional form in Equation 3. This gives us a distribution for the observed parameter,

$$\hat{\theta}_i \sim N(\theta_i, s_i^2). \quad (5)$$

This is where I perhaps don't have my notation quite how I want it (what do i know about bayesian things or hierarchical models? besides, im a man, i derive my statistics from the gut). We also need to be clear on language. We have a few things here:

1. It's not really a bootstrap when we sample  $\theta_{ib}^* \sim N(\hat{\theta}_i, s_i^2)$ . It's the  $b$ th estimate of  $\theta_i$  following distributoin just given
2. If we sample *without* replacement and take the mean, we essentially have a sum of independent normals (start notation from efron/tibshirani maybe will use it maybe not)

$$\theta_b^* = \frac{1}{n} \sum \theta_{ib}^*, \quad \theta_b^* \sim N\left(\mu_{\theta}, \frac{1}{n^2} \sum s_i^2\right) \quad (6)$$

but note that this isn't *really* a bootstrap of the  $\theta_i$  values. I'm not really sure what you would call this. Maybe we shouldn't have the  $b$  subscript but call it something else

3. Alternatively if we sample *with* replacement, we still have an individual draw for each bootstrapped subject,  $\theta_{ib}^* \sim N(\hat{\theta}_i, s_i^2)$ , but now the distribution of the for-real bootstrapped parameter is

$$\theta_b^* \sim N\left(\mu_{\theta}, \frac{1}{n} V_{\theta} + \frac{1}{n^2} \sum s_i^2\right) \quad (7)$$

The mean value across all bootstraps will be the same as before, but now we are actually accounting for the variability that exists.

4. As an aside, this sets us up for a useful callback – when describing the mean structure of the simulations, we can say that they both follow  $\theta \sim N(\mu_\theta, V_\theta)$ , but one has empirically determined  $V_\theta$  and the other sets  $V_\theta = 0$ . We can then be like hey go look at Equations 6 and 7 and see how the correct bootstrap can accommodate both cases but bad bootstrap cannot
5. Last aside – I have not simulated this yet, but Bob did make a comment about the TIE for the good bootstrap being too low, asking about sacrifice in power. While we haven’t done power yet (as of this writing), I wonder how the good bootstrap would look if we disregarded the  $s_i^2$  terms

—

We also note (and verify in the simulations) that it is not always necessary to specify an AR(1) autocorrelation structure to the errors in the model. While failing to include it slightly inflates the TIE error when the data truly is autocorrelated, when the data is not it can lead to overly conservative estimates. As such, we make the propose the following changes to the original bootstrap algorithm:

1. In step (1.), the specification of AR(1) structure is *optional* and can be modified with arguments to functions in `bdots`
2. In step (2.), we sample subjects *with replacement* and then for each drawn subject, randomly draw one bootstrap estimate for each of their model parameters based on the mean and standard errors derived from the `gnls` estimate.

A paired bootstrapping can be implemented by performing this same algorithm but ensuring that at each iteration of the bootstrap the same subjects are sampled with replacement in each group. This happened by default in the original implementation as each subject was retained in each iteration of the bootstrap.

### 3.2 Permutation Testing

The permutation method proposed is analogous to a traditional permutation method, but with an added step mirroring that of the previous in capturing the within-subject variability. For a specified FWER of  $\alpha$ , the proposed permutation algorithm is as follows:

1. For each subject, fit the nonlinear function with *optional* AR(1) autocorrelation structure for model errors. Assuming large sample normality, the sampling distribution of each estimator can be approximated by a normal distribution with mean corresponding to the point estimate and standard deviation corresponding to the standard error
2. Using the mean parameter estimates derived in (1.), find each subject’s corresponding fixation curve. Within each group, use these to derive the mean and standard deviations of the population level curves at each time point, denoted  $\bar{p}_{jt}$  and  $s_{jt}^2$  for  $j = 1, 2$ . Use these values to compute a test statistic  $T_t$  at each time point,

$$T_t = \frac{|\bar{p}_{1t} - \bar{p}_{2t}|}{\sqrt{s_{1t}^2 + s_{2t}^2}}. \quad (8)$$

This will be our observed test statistic.

3. Repeat (2)  $P$  additional times, each time shuffling the group membership between subjects. This time, we fitting each subject's corresponding fixation curve, draw a new set of parameter estimates using the distribution found in (1). Recalculate the test statistics  $T_t$ , each time retaining the maximum value. This collection of  $P$  statistics will serve as our null distribution which we denote  $\tilde{T}$  (or whatever we wanna call it). Let  $\tilde{T}_\alpha$  be the  $1 - \alpha/2$  quantile of  $\tilde{T}$
4. Compare each of the observed  $T_t$  with  $\tilde{T}_\alpha$ . Areas where  $T_t > \tilde{T}_\alpha$  are designated significant.

Paired permutation testing is implemented with a minor adjustment to step (3). Instead of permuting all of the labels between groups, choose one group and randomly assign each subject to either retain their current group membership or to change groups. Make the corresponding reassignment to members in the second group. This ensures that each permuted group contains one observation from each subject.

## 4 Type I Error Simulations

this section needs reorganized but it is as is for now

When now go about comparing the type I error rate of the three methods just described. In doing so, we will establish several conditions under which the observed subject data may have been generated or fit. This includes two conditions for the mean structure, two conditions for the error structure, paired and unpaired data, and data fit with and without an AR(1) assumption. Considering each permutation of this arrangement results in sixteen different simulations. Each simulation will then be examined for type I error using each of the three methods described ( I said that twice).

Each set of conditions generates two groups, with  $n = 25$  subjects in each group, with  $N = 100$  simulated trials for each subject. Each simulation was conducted 100 (1,000 running) times to determine the rate of type I error. And as this is an examination of the type I error rate, both of the two groups compared were constructed using the same distributions and manners described

### 4.1 Data Generation

Data was generated according to three conditions: mean structure, error structure, and paired status. We assume that each subject's data was of the general form

$$y_{it} = f_{\theta_i}(t) + \epsilon_{it}. \quad (9)$$

We assume that each group drew subject-specific parameters from a normal distribution,

$$\theta_i \sim N(\mu_\theta, V_\theta). \quad (10)$$

In all simulations, we set  $\mu_\theta = (0, 0.8, 0.002, 750)$  (it actually was not this, but I need to go look at what it was), corresponding to the baseline, peak, slope, and crossover parameters from Equation 3. In half of our simulations, we set  $V_\theta$  was determined following an empirical distribution from (Timbell 2017), giving an estimate of the typical amount of variability observed among normal hearing subjects. In the remaining cases, we set  $V_\theta = 0$ , a silly idea, sure, but assuming that each of the subjects' observations is derived from the same mean structure, with differences only in the observed error.

The error structure was of the form

$$e_{it} = \phi e_{i,t-1} + w_{it}, \quad w_{it} \sim N(0, \sigma) \quad (11)$$

where the  $w_{it}$  are iid with  $\sigma = 0.025$  (it actually is something else that is variable depending on number of trials, but such that for 100 trials it is equal to this, same as Oleson 2017).  $\phi$  corresponds to an autocorrelation parameter and is set to  $\phi = 0.8$  when the generated data is to be autocorrelated and set to  $\phi = 0$  when we assume the errors are all iid.

**Paired Data** Finally, we consider the paired data, which differs in creation according to the mean structure. In the case in which  $V_\theta \neq 0$ , we simply used the same value of  $\theta_i$  for the  $i$ th subject in each group, allowing the only difference to be that corresponding to the error structure. In the case when  $V_\theta = 0$ , however, it was already the case that the set of parameters were the same between subjects in each group (and indeed for all subjects in both groups). As such, letting the observed data for subject  $i$  in group  $A$  be denoted  $y_{iA}$ , we set

$$y_{iB} = y_{iA} + N(0, \sigma)$$

so that the only difference between paired subjects was uncorrelated normal noise at each time point. (I get that this is questionable, but what is the alternative? Truly it would just be to half the degrees of freedom in the t-test, which isn't really comparing IRL paired data)

## 4.2 Results

The parameters used in the group distributions were empirically determined from (timball 2017) and set  $b = 0.21$ ,  $p = 0.90$ ,  $s = 0.00165$  and  $x = 725.03$  (how many decimals, idk. Also won't include variability but I have that too). A four parameter logistic curve with these parameters has the following form:

#### 4.2.1 FWER

Here are the results for type I FWER (I have put the new values for permutation in parenthetical, this is after accounting for the within-subject variance with the additional drawing step for coefficients. I only tested this on the first four in unpaired, the rest are not updated)

manymeans	ar1	bdotscore	Bad Bootstrap	Good Bootstrap	Permutation (updated)
FALSE	TRUE	TRUE	0.06	0.01	0.21 (0.05)
FALSE	TRUE	FALSE	0.87	0.08	0.18 (0.11)
FALSE	FALSE	TRUE	0.08	0.00	0.14 (0.03)
FALSE	FALSE	FALSE	0.15	0.02	0.21 (0.04)
TRUE	TRUE	TRUE	0.92	0.03	0.03
TRUE	TRUE	FALSE	0.96	0.02	0.04
TRUE	FALSE	TRUE	0.99	0.05	0.01
TRUE	FALSE	FALSE	1.00	0.05	0.03

Table 1: TIE for realistic parameters (unpaired)

manymeans	ar1	bdotscore	Bad Bootstrap	Good Bootstrap	Permutation
FALSE	TRUE	TRUE	0.12	0.02	0.03
FALSE	TRUE	FALSE	0.86	0.08	0.03
FALSE	FALSE	TRUE	0.09	0.01	0.01
FALSE	FALSE	FALSE	0.14	0.01	0.03
TRUE	TRUE	TRUE	0.49	0.02	0.01
TRUE	TRUE	FALSE	0.94	0.03	0.02
TRUE	FALSE	TRUE	0.72	0.02	0.00
TRUE	FALSE	FALSE	0.74	0.04	0.00

Table 2: TIE for realistic parameters (paired)

### 4.2.2 Median per comparison error rate

manymeans	ar1	bdotscore	Bad Bootstrap	Good Bootstrap	Permutation (updated)
FALSE	TRUE	TRUE	0.01	0.00	0.04 (0.00)
FALSE	TRUE	FALSE	0.31	0.00	0.04 (0.02)
FALSE	FALSE	TRUE	0.00	0.00	0.02 (0.00)
FALSE	FALSE	FALSE	0.00	0.00	0.03 (0.00)
TRUE	TRUE	TRUE	0.51	0.01	0.01
TRUE	TRUE	FALSE	0.76	0.01	0.00
TRUE	FALSE	TRUE	0.86	0.01	0.00
TRUE	FALSE	FALSE	0.81	0.01	0.00

Table 3: median per comparison error rate (unpaired)

manymeans	ar1	bdotscore	Bad Bootstrap	Good Bootstrap	Permutation
FALSE	TRUE	TRUE	0.03	0.00	0.00
FALSE	TRUE	FALSE	0.26	0.00	0.00
FALSE	FALSE	TRUE	0.00	0.00	0.00
FALSE	FALSE	FALSE	0.01	0.00	0.00
TRUE	TRUE	TRUE	0.13	0.00	0.00
TRUE	TRUE	FALSE	0.52	0.02	0.00
TRUE	FALSE	TRUE	0.38	0.01	0.00
TRUE	FALSE	FALSE	0.44	0.01	0.00

Table 4: median per comparison error rate (paired)



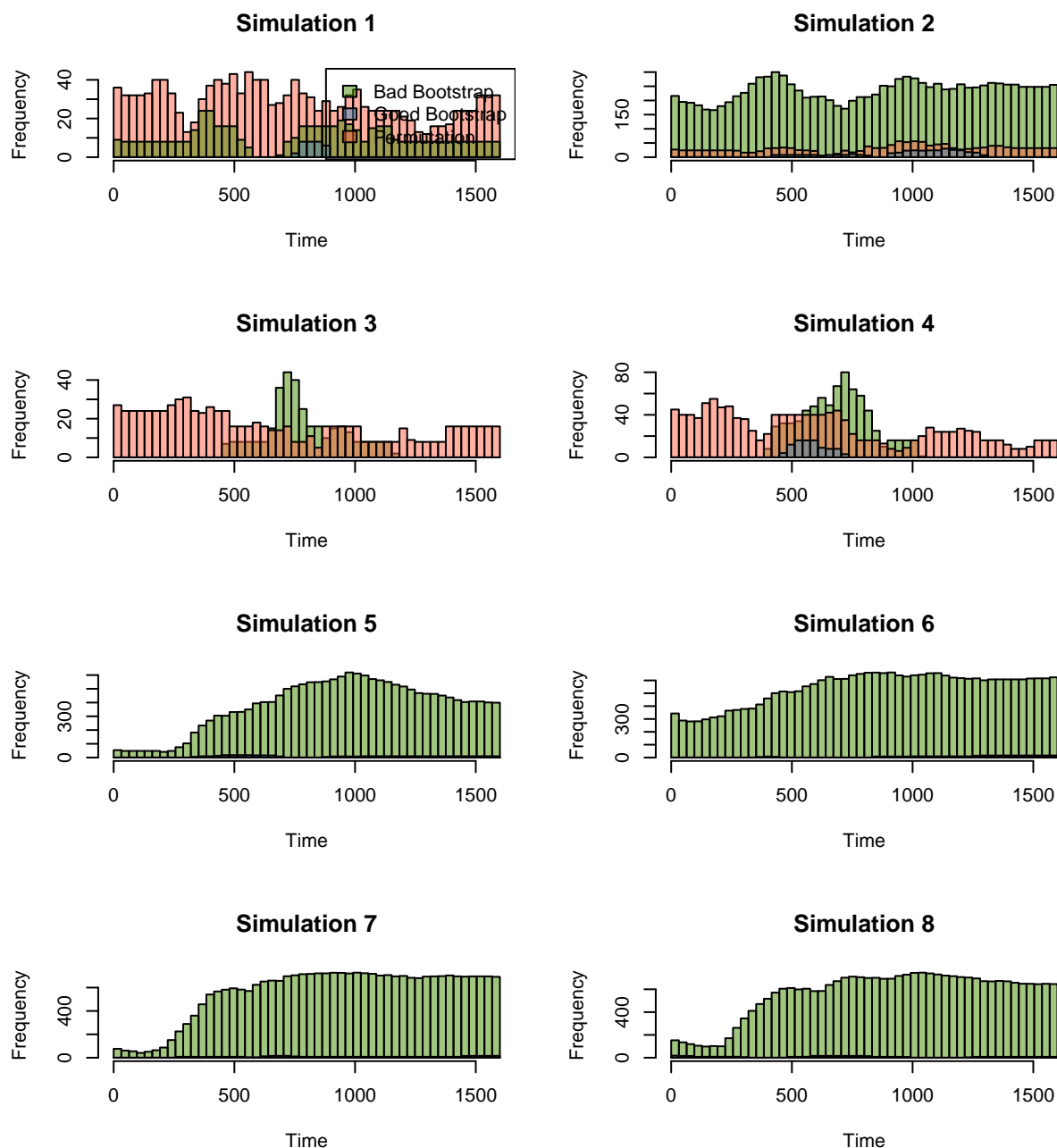


Figure 1: quick put together of what this might look like, frequency of TIE at each spot. Since there is no obvious trend here, though, I may just omit this entirely

## 5 Power Simulations

All this talk on the type I error rate sure is interesting, but what good is having a low type I rate if we are just trading it in for type II? In this hard hitting piece of investigative journalism, we set out to determine the

empirical power of the proposed methods under a variety of conditions, similar to those above but excluding the case of paired observations. Inb4 comments like “oh but power between paired cases is what we are interested in most!”, well, maybe if there’s time.

To determine power, two experimental groups were simulated with mean structures of the following form:

$$y = \begin{cases} b & x < 0 \\ mx + b & x \geq 0 \end{cases} \quad (12)$$

The first simulated group was “No Effect”, with intercept and slope parameters normally distributed and standard deviation  $\sigma$ . The second group, the “Effect” group, was similarly distributed, but with the slope parameter having mean value of  $\mu = 0.025$ . Absolute values were taken to ensure that all of the parameters were positive, and simulations were run with group variability values of  $\sigma = 0.005$  and  $\sigma = 0.025$ . The error structure was identical to that in the FWER simulations, with both an AR(1) error structure and independent noise included. Finally, we limited consideration to three possible scenarios: first, we assumed the conditions presented in Oleson 2017, assuming homogeneity between subject parameters and an AR(1) error structure, with the model fitting performed assuming autocorrelated errors. For the remaining scenarios, we assumed heterogeneity in the distribution of subject parameters, simulated with and without an AR(1) error structure. In both of these scenarios, we elected to *not* fit the model assuming autocorrelated errors. This was for two reasons: first, simulations exploring the type I error rate suggested that models fit with the autocorrelation assumption tended to be conservative. Second, and given the results of the first, this makes setting the assumption of autocorrelation to FALSE in `bdots` seem like a sensible default, and as such, it would be of interest to see how the model performs in these cases.

For each subject, parameters for their mean structure given in Equation 12 were drawn according to their group membership and fit using `bdots` on the interval  $(-0.1, 1)$ . Groups were then compared using each of the methods presented (names?). By including the interval  $(-0.1, 0)$  where there is no true difference, we are able to mitigate the effects of over-zealous methods, and we present this information in the following way: any bootstrapped or permuted resulting identifying the region  $(-0.1, 0)$  as being significantly different was marked as having a type I error, regardless of other regions identified. The proportions of simulations for which this occurred in given in the column labeled  $\alpha$ . The next column,  $\beta$ , is the type II error rate, giving the proportion of simulations in which no differences were identified. And finally in the remaining greek letter column is  $1 - \beta - \alpha$ , a modified power metric giving the proportion of simulations in which only differences in the correct region were identified. The remaining columns given a partial summary of the earliest onset of detection. As the true difference occurs on the interval  $t > 0$ , smaller values indicate greater power in

detecting differences. Finally, a base R plot of the power at each time point is given in Figure 2. This plot represents the true power, though note that this does not take into account the rate of type I errors which in all cases occur to the left of the red dashed line.

(I know I used too many colons)

100 simulations were conducted for each scenario. Here are the results.

## 5.1 Results

Presented in this section are the results of each of the aforementioned simulations. The first four columns indicate the parameters of the simulation: the mean structure, the error structure, the variability in the generating distributions and the effect size, or the slope. Note that as each of the simulations contained intervals where there was no difference in actuality, there is a column marked  $\alpha$  indicating the observed type I error; similarly, the column labeled  $\beta$  indicates the proportion of simulations in which no differences were detected. The remaining column,  $1 - \beta - \alpha$ , indicates the proportion of simulations in which differences were detected, but only in the regions in which they existed. Finally, the remaining columns offer a summary of when differences were detected. As the true value for this is 0, smaller numbers indicate greater ability to detect smaller effect sizes.

I removed Min and Max because who cares, it was noise and took up space. I also removed  $m = 0.005$  because it was pretty similar in all cases except for in the singlemeans case where basically the type II error rate was like 0.9 for everything including v1. It also effed up all my stats at the end. so let's just not do it. This makes my tables MUCH cleaner while conveying pretty much the same information. It's also worth noting (especially in the power plots) that there is nothing really all that more interesting when  $\sigma = 0.025$  over  $\sigma = 0.005$ . Maybe I'll just place these all in supplementary materials, indicating that yes we looked at this but there is not enough new information in those simulations to justify including them in the main body of the paper when all they are doing is taking up space.

### 5.1.1 Bootstrap v1

$V \neq 0$	AR(1)	$\sigma$	$\alpha$	$\beta$	$1 - \beta - \alpha$	1st Qu.	Median	3rd Qu.
FALSE	TRUE	0.005	0.01	0.00	0.99	0.247	0.303	0.339
FALSE	TRUE	0.025	0.00	0.00	1.00	0.265	0.324	0.347
TRUE	FALSE	0.005	0.90	0.00	0.10	0.008	0.017	0.030
TRUE	FALSE	0.025	0.97	0.00	0.03	0.012	0.015	0.016
TRUE	TRUE	0.005	0.89	0.00	0.11	0.048	0.059	0.066
TRUE	TRUE	0.025	0.91	0.00	0.09	0.023	0.032	0.037

Table 5: Power for v1 bootstrap

### 5.1.2 Bootstrap v2

$V \neq 0$	AR(1)	$\sigma$	$\alpha$	$\beta$	$1 - \beta - \alpha$	1st Qu.	Median	3rd Qu.
FALSE	TRUE	0.005	0.00	0.00	1.00	0.296	0.346	0.392
FALSE	TRUE	0.025	0.00	0.00	1.00	0.316	0.364	0.395
TRUE	FALSE	0.005	0.00	0.12	0.88	0.373	0.576	0.756
TRUE	FALSE	0.025	0.01	0.17	0.82	0.423	0.555	0.734
TRUE	TRUE	0.005	0.01	0.20	0.79	0.357	0.522	0.691
TRUE	TRUE	0.025	0.00	0.12	0.88	0.444	0.555	0.737

Table 6: Power for v2 bootstrap

## 5.2 Permutation

$V \neq 0$	AR(1)	$\sigma$	$\alpha$	$\beta$	$1 - \beta - \alpha$	1st Qu.	Median	3rd Qu.
FALSE	TRUE	0.005	0.05	0.00	0.95	0.259	0.299	0.332
FALSE	TRUE	0.025	0.10	0.00	0.90	0.275	0.302	0.334
TRUE	FALSE	0.005	0.03	0.05	0.92	0.454	0.609	0.748
TRUE	FALSE	0.025	0.08	0.08	0.84	0.490	0.610	0.721
TRUE	TRUE	0.005	0.08	0.12	0.80	0.418	0.578	0.743
TRUE	TRUE	0.025	0.00	0.06	0.94	0.493	0.619	0.746

Table 7: Power for permutation

### 5.2.1 Summary of methods

A general estimate of how well each of these methods does in a variety of conditions can be seen by taking the mean of the summary statistics across each of the trials, given in Table 8.

Method	$\alpha$	$\beta$	$1 - \beta - \alpha$	1st Qu.	Median	3rd Qu.
Bootstrap V1	0.613	0.000	0.387	0.101	0.125	0.139
Bootstrap V2	0.003	0.102	0.895	0.368	0.486	0.617
Permtuation	0.057	0.052	0.892	0.398	0.503	0.604

Table 8: Summary of methods for Type II error. It’s worth considering presenting the means separately depending on the  $V \neq 0$  assumption, because that fucking tanks the Type II error for all of them

As we can see, the permutation method is the most canonical of the methods considered, with a type I error rate close to the nominal  $\alpha = 0.05$  and a type II error rate of  $\beta = 0.195$ , corresponding to approximately 80% power. The V2 bootstrap, alternatively, is rather conservative, trading a portion of its power for controlling the type I error rate close to zero. Finally, the V1 bootstrap is a poor contender for identifying differences in time series, with its utility limited to the strict assumptions under which it was originally presented.

Even then, it is worth considering these methods again in this limited context. Considering only the case with single means, an AR(1) error structure and an effect size of  $m = 0.025$ , the V1 bootstrap is able to first detect an effect only marginally sooner than the V2 bootstrap but with a greater type I error rate. Researchers should carefully consider whether or not this greater acquisition of power is worth the risk.

Method	$V \neq 0$	AR(1)	$\sigma$	$\alpha$	$\beta$	$1 - \beta - \alpha$	1st Qu.	Median	3rd Qu.
V1	FALSE	TRUE	0.005	0.01	0.00	0.99	0.247	0.303	0.339
V1	FALSE	TRUE	0.025	0.00	0.00	1.00	0.265	0.324	0.347
V2	FALSE	TRUE	0.005	0.00	0.00	1.00	0.296	0.346	0.392
V2	FALSE	TRUE	0.025	0.00	0.00	1.00	0.316	0.364	0.395

Table 9: Summary of bootstraps with  $V \neq 0$  and with AR(1) error structure

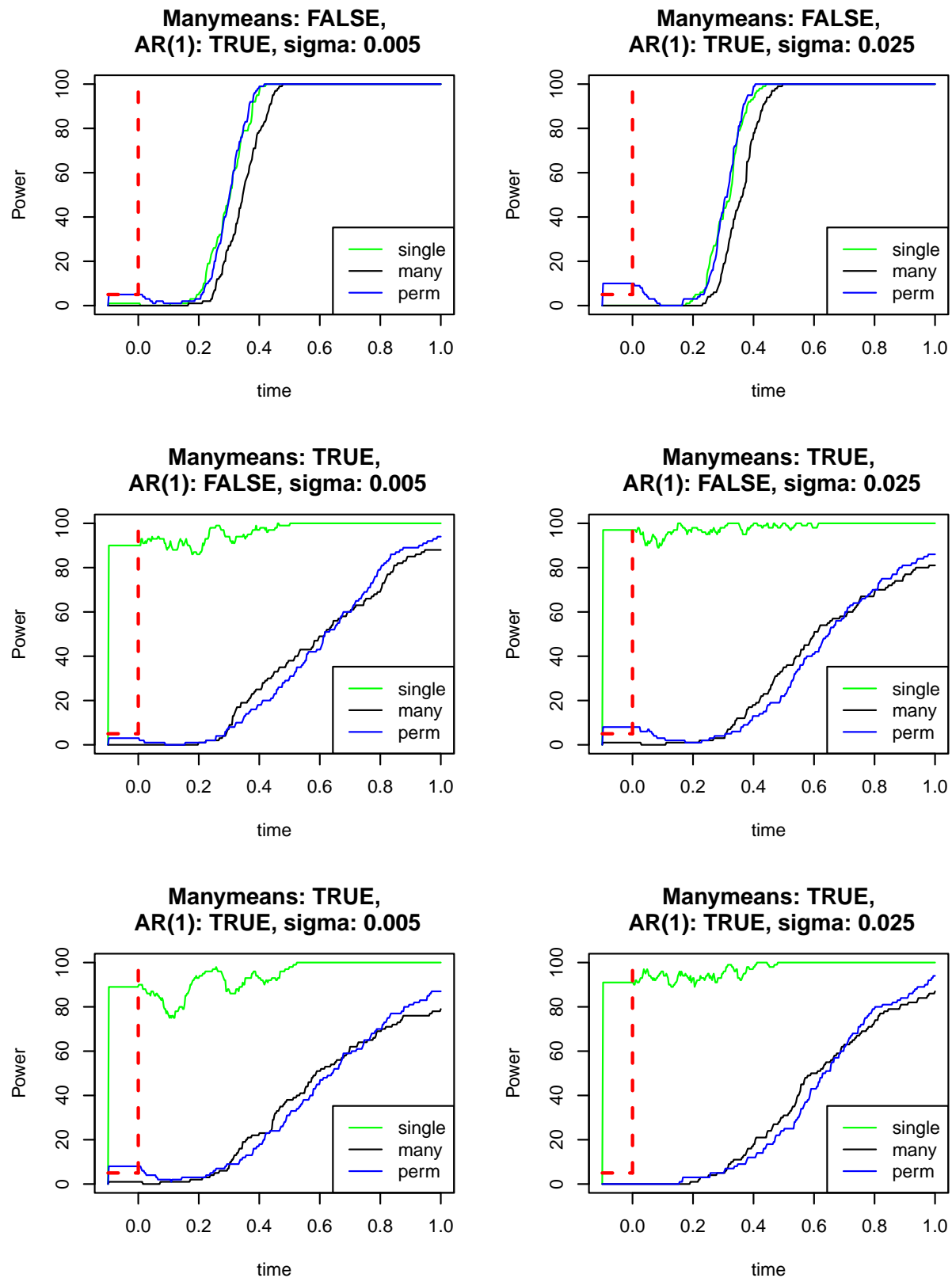


Figure 2: check out this badass plot in base R. Note that the bump in type I error before flattening out around 0.1 is a consequence of simulations in which the no effect group, on average, has a larger intercept than the effect group. When this occurs, the lines “cross” in the 0 to 0.2 range, making it seem like there is no effect there

## 6 Discussion and concluding remarks

Idk, discussion

It's worth noting that the FWER adjustment proposed in [?] is still valid, if not slightly conservative, and with power similar to that of the permutation method.

There are a few limitations to the current paper that are worthy of investigation. First, limited consideration was given to the effect of sample density on the observed type I error rate or power. As the fitting function in `bdots` simply returns a set of parameters, one could conceivably perform any of the methods presented on any arbitrary collection of points, whether or not any data were observed there. This extends itself to the condition in which subjects were sampled at heterogeneous time points, as may be the case in many clinical settings. What impact this may have or how to best handle these cases remains investigated. The current implementation of `bdots` takes the union of observed time points, though this runs the risk of extrapolating many subjects past what they were ever observed.

We conclude pretty much by noting that even in the best case presented in Oleson 2017, these other methods do an identical job, and in situations in which these assumptions are wrong, it is a veritable train wreck. It seems that the  $1 - \beta - \alpha$  (whatever this is called) is nearly identical between the v2 bootstrap and permutation, whereas the type II error is much greater in the bootstrap. This seems justification enough for making the permutation method the new default in `bdots` or, should i say PDOTS. It is conceivable that the assumptions presented in Oleson 2017 would have their place, say repeated observation from the same mechanism (i.e., not vwp data), in which case v1 bootstrap has optimal performance. Still, users of `bdots` will need to go out of their way in order to do so, possibly with a warning. Because really, even in that case, it hardly does any better than permutation, perhaps with a bit smaller of a type I error

## Appendix

Could include oleson 2017 parameters just to say we did it and verifying the two results that they had previously found (i.e., we have implemented this correctly). Commented out for now