

# Modeling Metal Protein Complexes from Experimental Extended X-ray Absorption Fine-Structure using Computational Intelligence

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# Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
1.1	Biological Background . . . . .	1
1.2	X-ray Absorption Spectroscopy . . . . .	2
1.3	Force Fields aka Potential Energy . . . . .	3
1.4	Problem Definition . . . . .	3
<b>2</b>	<b>Background</b>	<b>5</b>
2.1	Evolutionary Algorithms . . . . .	5
2.1.1	Population . . . . .	6
2.1.2	Evaluation Function . . . . .	6
2.1.3	Stopping Criteria . . . . .	7
2.1.4	Evolving the Population . . . . .	7
2.2	Genetic Algorithm . . . . .	7
2.2.1	Genetic Operators . . . . .	8
2.3	Restering Genetic Algorithm . . . . .	10

2.4	Particle Swarm Optimization . . . . .	11
2.5	Differential Evolution . . . . .	11
<b>3</b>	<b>Previous Research</b>	<b>12</b>
3.1	Quantum Mechanics/Molecular Mechanics . . . . .	12
<b>4</b>	<b>Methodology</b>	<b>14</b>
4.1	Problem Encoding . . . . .	14
4.2	Population Generation . . . . .	15
4.2.1	Molecular Dynamics Simulation . . . . .	15
4.3	Genetic Operators . . . . .	16
4.3.1	Crossover . . . . .	16
4.3.2	Mutation . . . . .	17
4.3.3	Selection . . . . .	18
4.4	Parameters . . . . .	18
	<b>Bibliography</b>	<b>20</b>
	<b>Appendices</b>	<b>20</b>

# List of Tables

4.1	Minimum Move Required at 1% . . . . .	17
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# List of Figures

1.1	EXAFS Spectra of OEC in $S_1$ . . . . .	3
2.1	Population Individual Modification . . . . .	6
2.2	Simple Chromosome Representation . . . . .	8
2.3	Population Individual Modification . . . . .	8
2.4	2-Point Crossover . . . . .	9
2.5	Single-point Mutation . . . . .	9
4.1	Representation 1 . . . . .	14
4.2	Representation 2 . . . . .	15

# Chapter 1

## Introduction

The aim of this thesis is to find a better method for determining the atomic structure of a molecule using Extended X-Ray Absorption Fine Structure (EXAFS). The following thesis uses the oxygen-evolving complex (OEC) in state  $S_1$  as an example for structure refinement but the developed process can be applied to any given structure that has an EXAFS spectra. In this chapter, we introduce the biological background and terms, followed by the problem definition, and finally elaborate on the computer science theories applied to the problem.

### 1.1 Biological Background

The oxygen-evolving complex (OEC) [1] is the water-oxidizing enzyme of photosystem II [2]. The responsibility of the OEC is to accept water molecules as input and output the oxygen and hydrogen atoms to be used in the system. The incoming water molecules are put through five different states in order to perform the oxidization. The atomic structure of the OEC molecule is different in each state because each state has a unique role in the process.

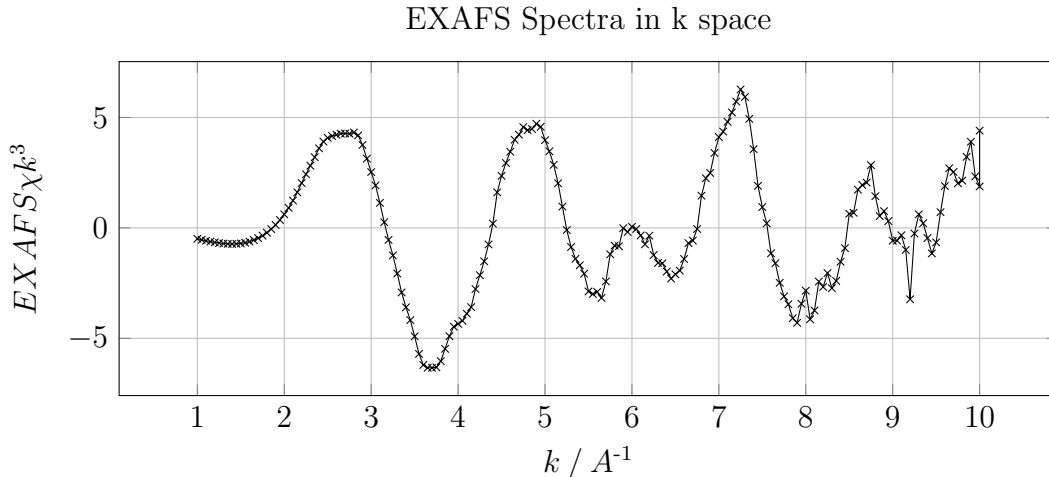
The most significant feature of this compound is its inorganic core  $Mn_4Ca_1O_xCl_{1-2}(HCO_3)_y$ . It is not found anywhere else in biology and offers the only biological blueprint for water splitting. By studying OEC the hope is to understand how water splitting can occur at such a low cost. Acquiring a better understanding of how the water splitting

process occurs will assist in creating biomimetic catalysts or engineered PSII enzymes for real world applications.

## 1.2 X-ray Absorption Spectroscopy

The following overview is based on information contained in Matthew Newvilles Fundamentals of XAFS (2004) [3]. X-Ray absorption fine structure (XAFS) is a method used to measure the absorption coefficient of a material as a function of energy. X-rays are part of the electromagnetic spectrum with wavelengths ranging from 25Å to 0.25Å. All atoms resonate at a specific wavelength. The x-ray is tuned to have the same wavelength as the target atom. A photon from an x-ray is absorbed by an electron in a tightly bound quantum core level of an atom. Absorption only takes place if the binding energy of the core level is less than the energy of the x-ray photon. At the time of absorption a core electron moves to an empty outer shell and another electron moves in to take its place. Eventually the affected electrons decay to their original state. During this time fluorescence energies are emitted that characterize a specific atom.

The absorption coefficients measured after the initial absorption are referred to as the EXAFS. During the decay of the electrons to their original state, oscillations occur in the measure of the absorption coefficient. The different frequencies found within the oscillations correspond to different near-neighbour coordination shells, which can be described and modeled according to the EXAFS equation. From the oscillations, the number of neighbouring atoms, the distances to the neighbouring atoms, and the disorder in the neighbour distances can be determined. The energy spectra for OEC in  $S_1$  is shown in Figure 1.1.

Figure 1.1: EXAFS Spectra of OEC in  $S_1$ 

### 1.3 Force Fields aka Potential Energy

### 1.4 Problem Definition

The goal of this thesis is to examine different search heuristics to determine the best method of finding the theoretical atomic structure of a molecule using the molecules EXAFS spectra for comparison. This problem contains two important but unrelated goals. Firstly, the algorithm must be able to find an atomic structure who's EXAFS spectra matches the experimental EXAFS spectra, and also create an atomic structure who's potential energy is as low as possible.

EXAFS can be used to identify properties of a molecule, but they do not provide enough detail to determine the atomic structure of a molecule in 3-dimensional space. An EXAFS spectra allows you to identify how far apart atoms are from each other, but does not give enough information to identify their dihedral angles. Fortunately, EXAFS can be used to assist in determining the atomic structure of a molecule. The energy spectra given off by the molecule is unique for its structure, meaning that you can create an atomic structure, obtain its EXAFS spectra, and compare the results. The hope is that if you create an atomic structure whose spectra closely matches the spectra of an actual model, then there is a high likelihood that the created structure will closely match the actual structure.



The IFEFFIT XAFS data analysis suite [4] is used to simulate the EXAFS experiments. FEFF6 is used to simulate an XAFS experiment and IFEFFIT does post processing of the simulated EXAFS spectra. During the atomic structure refinement, the generated atomic structures will be run through these applications to obtain an EXAFS spectra.

NAMD [5] will be used for the energy calculations. The NAMD Energy Plugin [6] will calculate the potential energy of the generated atomic structure.

# Chapter 2

## Background

The purpose of this chapter is to assist the reader in understand the search techniques used in this work.

### 2.1 Evolutionary Algorithms

An evolutionary algorithm (EA) is a population-based metaheuristic optimization algorithm. An evolutionary algorithm is a search heuristic that is based on Darwin's theory of natural evolution. Darwin theorized that over a period of time a population of individuals would naturally mate and create offspring that were better than themselves. He suggests that not all individuals are created equally and that eventually the weaker individuals would die off. This same principle can be applied to a search algorithm as a heuristic. An EA contains a population of individuals that are evolved to find improved candidate solutions.

Figure 2.1 demonstrates how the basic EA operates. An EA consists of many parts. The following subsections wil explain each of these parts.

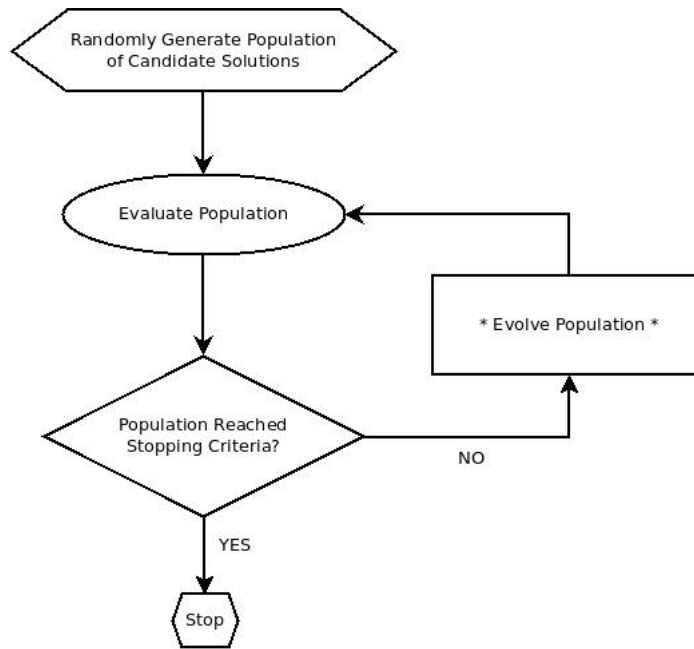


Figure 2.1: Population Individual Modification

### 2.1.1 Population

The population is a key piece to an EA. Each individual in the population represents a possible candidate solution to the problem that is trying to be solved. The representation of the individual is usually unique to the problem.

### 2.1.2 Evaluation Function

This operator determines the fitness of an individual. Each individual is evaluated and given a fitness score to represent how well the individual performed on the problem. This operation is problem specific and can be very difficult to determine how a problem should be evaluated. The evaluation function is important for differentiating individuals. A poor evaluation function can make each of the individuals appear to be similar when they actually have small key differences.

### 2.1.3 Stopping Criteria

Stopping criteria is used to determine when the EA should stop evolving. There are generally three ways a stopping criteria can be reached: a maximum number of iterations is reached, the population has converged on the same solution, or the solution has been found.

### 2.1.4 Evolving the Population

The evolutionary process of an EA is what is different in each implementation of an EA. Each algorithm has a different interpretation of how the population should be evolved. Evolving the population consists of using the individuals in the population to create a new population. Later in this work the different interpretations will be explained.

## 2.2 Genetic Algorithm

A genetic algorithm (GA) is a search heuristic that is based on Darwin's theory of natural evolution. Darwin theorized that over a period of time a population of individuals would naturally mate and create offspring that were better than themselves. He suggests that not all individuals are created equally and that eventually the weaker individuals would die off. This same principle can be applied to a search algorithm. A GA contains a population of individuals that are evolved to find improved candidate solutions.

The individuals of a GA represent possible candidate solutions to the problem. Individuals are referred to as chromosomes. Typically a chromosome is represented as an array where each index of the array represents a property of the candidate solution. There are no restrictions to the encoding of a chromosome but each property of the chromosome must be independent from the others. The simplest example of a representation is a binary array of 1's and 0's, as shown in Figure 2.2.

0	1	1	0	1	0	1	0
---	---	---	---	---	---	---	---

Figure 2.2: Simple Chromosome Representation

Finding a representation is only the first step in creating a genetic algorithm. The next step is to define your set of operators. A GA consists of multiple operators that assist in the evolution of the population. Figure 2.3 depicts the flowchart of a genetic algorithm and where each genetic operation is performed.

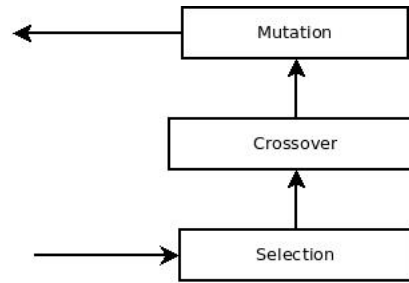


Figure 2.3: Population Individual Modification

### 2.2.1 Genetic Operators

Each of the following operators represent a piece of a genetic algorithm. They facilitate the evolutionary process in an effort to find better candidate solutions. Each of these operators has a unique purpose in the search algorithm but there are many different types of ways these goals can be carried out. Only a few of the different methods will be described in this work.

*Selection Operator:* This operator is very important to the *Crossover* and *Mutation* operators. The idea behind this operator is to put selectionary pressure on the population during the evolutionary process. Individuals with a better fitness score should be allowed a better chance of breeding to create the next population. During the selection process two individuals are chosen breeding or reproduction. There are several selection methods but in this only *k-Tournament selection* will be explained.

The *k-Tournament* selection method works by randomly selecting  $k$  individuals from the population, where  $k$  is less than the number of individuals in the population, and selecting the individual that has the best fitness score from the  $k$  individuals.

The value of  $k$  should be relatively small compared to the size of the population. If the value of  $k$  is too large it would defeat the purpose of this selection method. For example, if there is a population size of 100 the value of  $k$  should be around 2-5.

*Crossover Operator:* This operator is essential to evolving the individuals of the population. Crossover is how two individuals breed to create two new individuals. With respect to the evolutionary process, crossover exploits the current information that is contained within the population in order to find improved individuals. The most widely used type of crossover is N-point crossover.

N-point crossover works by randomly selecting N cutting points and swapping the information between the two individuals along those N points. Figure 2.4 demonstrates how the swapping of information occurs during 2-point crossover.

Parent 1	0	1	1	0	1	0	1	0
Parent 2	0	0	1	0	0	1	0	0

---

Child 1	0	0	1	0	1	1	0	0
Child 2	0	1	1	0	0	0	1	0

Figure 2.4: 2-Point Crossover

*Mutation Operator:* The mutation operator is used to introduce random changes to the individuals during evolution. Mutations to individuals are a way to explore the search space. Depending on how the initial population was created there may not be the necessary information in the population to find the optimal solution with crossover alone. Mutations allow for new information to possibly be introduced into the population. A common type of mutation is single-point mutation where a single index in your individual is modified. Figure 2.5 demonstrates single-point mutation.

Individual	0	1	1	0	1	0	1	0
------------	---	---	---	---	---	---	---	---

---

Mutant	0	1	1	1	1	0	1	0
--------	---	---	---	---	---	---	---	---

Figure 2.5: Single-point Mutation

*Elitism Operator:* During each generation of the genetic algorithm a new population is created using the individuals from the population in the previous generation. The new population is bred from the previous individuals with the hopes of creating better individuals. Sometimes this is not the case and the population can end up losing valuable information from individuals that were not chosen during the selection process. To prevent this from happening the elitism operator was created. The elitism operator works by seeding the next generations population with the individuals with the best fitness score. Typically only the top 1% of individuals are copied into the next generation.

## 2.3 Restering Genetic Algorithm

The restering genetic algorithm (RGA) is a variation of the recentering-restarting genetic algorithm (RRGA) [7] [8] which has had success in avoiding local minima. The RRGA is used to avoid fixating on local optima. RRGA works by running a series of standard GA runs and making adjustments to the starting population at the beginning of each run. At the beginning of a run the RRGA selects a center, which is a possible candidate solution to the problem, and at the end of each basic GA run the center is compared to the best individual in the population. If the best individual is better than the current center it is replaced with the best individual and the whole process is repeated. The center is used as a baseline for generating the population in the next run.

The RGA works similarly to the RRGA but there is no center for the population. Instead a basic GA is allowed to run until the population's fitness scores begins to converge. After the population has converged upon a minimum diversity, new individuals are introduced to the population. Duplicate individuals are removed from the population and new individuals that have not yet been in the population take their place. For example, if there is a population size of 100 and the convergence rate is 5% then after all the duplicates are removed there will only be 5 individuals remaining and 95 new individuals will be inserted into the population. Algorithm 1 shows the pseudo-code of the restarting method.

---

**Algorithm 1** Restarting the population

---

```
if population has converged to minimum diversity then  
    remove all duplicate individuals;  
    while population not full do  
        insert random draw from generated individuals into population;  
    end while  
end if
```

---

## 2.4 Particle Swarm Optimization

## 2.5 Differential Evolution



# Chapter 3

## Previous Research

Before we can begin explaining the techniques we used in the next chapter it is necessary that we explain what research has already been done in this field.

### 3.1 Quantum Mechanics/Molecular Mechanics

In [9] Sproviero, Eduardo M and Gascón, José A and McEvoy, James P and Brudvig, Gary W and Batista, and Victor S used DFT-QM/MM and R-QM/MM techniques to find close approximations of the experimental EXAFS spectra. The EXAFS spectra used in their calculations was at a poorer resolution compared to the spectra used in the experiments in this work.

Density functional theory quantum mechanics/molecular mechanics (DFT-QM/MM) uses the atoms spatially dependent electron density (**CITE?**) to determine the position of each atom. Since DFT largely uses function approximations this approach is very limited.

To increase their accuracy the researchers used a refined quantum mechanics/molecular mechanics (R-QM/MM) technique. This approach iteratively adjusted the molecular structure of the molecule and attempted to minimize a scoring function defined in terms of the sum of squared deviations between the experimental and calculated EXAFS spectra. A quadratic penalty was applied to each atom to ensure that their

positions did not deviate too far from their original position in order to keep the energy of the system at a minimum.

The researches speculate that even though the R-QM/MM technique was able to generate an EXAFS spectra closer to the experimental spectra their solution was only a local solution because it was based on their original DFT-QM/MM solution.

In [10] Lubner, Sandra and Rivalta, Ivan and Umena, Yasufumi and Kawakami, Keisuke and Shen, Jian-Ren and Kamiya, Nobuo and Brudvig, Gary W and Batista, Victor S repeated their original experiments performed in [9] with updated X-ray diffraction (XRD) data that had a resolution of 1.9Å. They have success rerunning the DFT-QM/MM experiment followed by the R-QM/MM experiment but still had the same speculations about remaining in a local solution.

# Chapter 4

## Methodology

### 4.1 Problem Encoding

A molecule consists of a number of atoms. Each of these atoms has its own 3-dimensional position within the molecule. For the structure refinement problem the individual 3-dimensional position values are not important. The important information about this problem is how the atoms are positioned with respect to each other. Two different forms of representation were used in this work. For each of these representations the number values are shown in Angstroms ( $\text{\AA}$ ).

The initial run of experiments used a representation that maintained the initial atomic positions of each atom. The 3-dimensional coordinates were treated as a list of coordinates as shown in 4.1. Using this representation meant that during any form of crossover the tuple of X, Y and Z values would stay together.

X	Y	Z
14.451	-13.346	1.133
15.336	-13.488	2.014
13.005	-13.364	1.452
0.019	0.011	0.045
...	...	...

Figure 4.1: Representation 1

14.451
-13.346
1.133
15.336
-13.488
2.014
13.005
...

Figure 4.2: Representation 2

The other representation used was a list of values. The initial list of 3-dimensional coordinates was converted to a single list of decimal points as shown in 4.2. Algorithms such as particle swarm optimization and differential evolution called for a more flexible representation. For fitness evaluation the list of number was converted back to a list of 3-dimensional coordinates by taking segments of three numbers to create a 3-dimensional position.

## 4.2 Population Generation

A population of different individuals needed to be created in order to begin refining the OEC atomic structure using an evolutionary algorithm. The initial OEC atomic structure came from the crystallographic photosystem II (PSII) structure [11]. It is available in the Protein Data Bank (PDB) [12] as PDB ID 3ARC. During the initial stages of experimentation the populations were created by randomly adjusting the atoms within our initial structure. To create a new individual each atom within the atomic structure would be random moved by 0.05-0.5Å. This form of population generation was quickly discarded because many of these individuals were either chemically infeasible or generated invalid EXAFS spectras.

### 4.2.1 Molecular Dynamics Simulation

An alternative method of population generation was needed to generate individuals that were usable in the experiments. To ensure that the atomic structure was as stable as possible, the structure was put into a molecular dynamics simulation. While in this

simulation the molecule is allowed to act as if it were in the real world. The atoms were allowed to move freely in space until the overall temperature of the system was reasonably low. This acted as the baseline atomic structure for all tests. NAMD [5] was used to run the molecular dynamics simulations.

Once the atom structure was stable the temperature within the system was increased. The increased temperature causes the atoms to oscillate their positions but still remain chemically feasible. During this process snapshots of the molecules atomic structure were recorded. The simulation was allowed to run for 10 000 steps and 10 000 snapshots of the atomic structure were recorded. Each of these snapshots create a feasible individual for the experiments.

Since 10 000 individuals is more than enough individuals to seed the populations the best individuals were picked. The generated atomic structures were run through IFEFFIT and compared to the target EXAFS spectra. The top 3% (roughly 300) were used to generate the initial populations in the evolutionary algorithms.

\*\*\*The atomic structures that were generated contained 1269 chemical elements. For the purposes of OEC structure refinement only 79 specific atoms were required for EXAFS analysis. The genetic algorithm only used the 79 atoms that required refinement.\*\*\* **This doesn't belong here.**

## 4.3 Genetic Operators

### 4.3.1 Crossover

The basic one-point crossover operator was chosen for the experiments. One point crossover is generally less destructive to the individuals than other forms of crossover. Other crossover operators that caused greater exploitation of the individuals had a negative affect on the overall fitness score. A crossover operator that causes minimal disruption to the individual was able to find better candidate solutions.

Table 4.1: Minimum Move Required at 1%

Element	1% Difference	5% Difference
O	0.025Å	0.5Å
Mn	0.01Å	0.5Å
Ca	1Å	5Å
C	0.5Å	5Å
N	0.5Å	5Å
H	5Å	5Å

### 4.3.2 Mutation

**Placeholder until representation is decided.**

For the mutation operator a single atomic coordinate will be moved. A random atomic coordinate is selected from the individual and its position is moved randomly by 0.05Å using Euclidean distance. The resulting position will be 0.05Å away from its original position. In order to determine how much distance the atomic position should be moved, an analysis was needed to learn more about how changing atomic positions affects the calculated EXAFS spectra.

The analysis consisted of moving each atom, individually, in a variety of directions and calculating its RMSD score. Each atom was moved in a total of six directions ( $\pm X$ ,  $\pm Y$ , and  $\pm Z$ ), at a variety of distances (0.001Å, 0.005Å, 0.01Å, 0.025Å, 0.05Å, 0.1Å, 0.5Å, 1Å, and 5Å). This was done to determine how much movement was required of an atom to make a significant change to the RMSD score. Table 4.1 shows results of how much movement is required to produce a 1% and 5% change to their RMSD scores. Since there is more than one instance of each chemical element in OEC, the distance chosen was the first distance that produced the minimum change because the goal was to find the absolute minimum for each chemical element.

The value of 0.05Å was chosen for the experiments as a middle ground that could be applied to each chemical element. It should be noted that the value of 0.05Å is particular to OEC. A similar analysis could be done to determine the minimum move distance for each element in another chemical complex.

### 4.3.3 Selection

For the selection operator a 3-tournament selection was used.

## 4.4 Parameters

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