

# Variational Mixture of Normalizing Flows

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November 20, 2019

Thesis to obtain the Master of Science degree in  
**Electrical and Computer Engineering**

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    - No approach to introduce discrete structure (multi-modality)

# Introduction and Motivation: Goal

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- Two questions:
  - What should the **mixture components** be?
  - How should their **parameters** be **estimated**?

- Mixture Models

# Outline

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- Experiments and results
- Conclusions and future work

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# Mixture Models: Definition

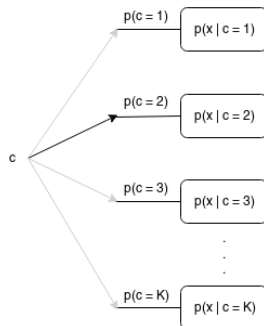
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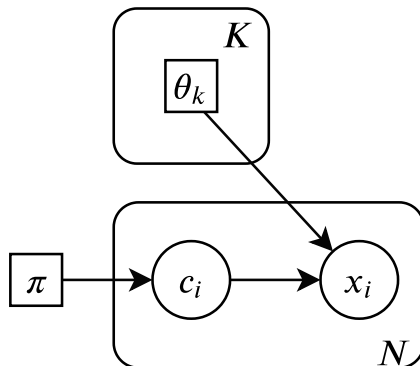
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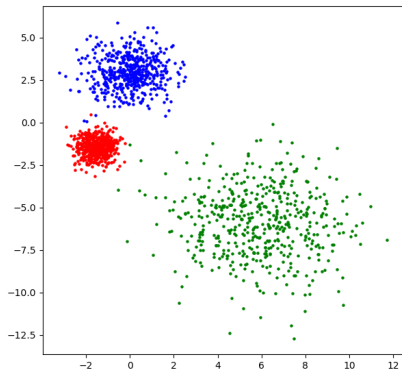
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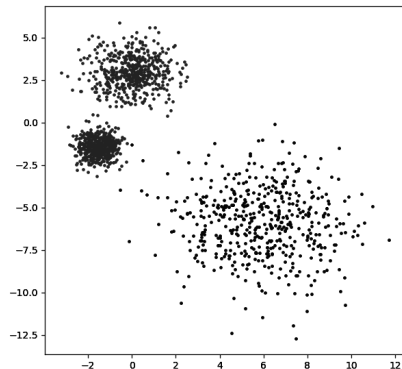
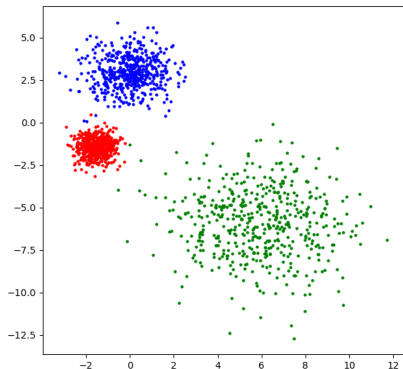
# Mixture Models: Plate diagram



# Mixture Models: Mixture of Gaussians



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This can be **optimized w.r.t.  $\boldsymbol{\theta}$** , to approximate an **arbitrary distribution**

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- c **Gradient** of  $\det \left( \frac{d}{dz} g(\mathbf{z}; \boldsymbol{\theta}) \right)$  w.r.t  $\boldsymbol{\theta}$  - computationally cheap



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- Normalizing Flows: **composition** of several “good” transformations
- I.e.,  $g = h_{L-1} \circ h_{L-2} \circ \dots \circ h_1 \circ h_0$
- Applying the formula to  $g$ , and taking the logarithm:

$$\log f_X(\mathbf{x}) = \log f_Z(g^{-1}(\mathbf{x})) - \sum_{\ell=0}^{L-1} \log \left| \det \left( \frac{d}{d\mathbf{x}_\ell} h_\ell(\mathbf{x}_\ell) \right) \right|.$$

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- The respective Jacobian matrix:

$$J_{f(\mathbf{z})} = \begin{bmatrix} \frac{\partial \mathbf{x}_1}{\partial \mathbf{z}_1} & \frac{\partial \mathbf{x}_1}{\partial \mathbf{z}_2} \\ \frac{\partial \mathbf{x}_2}{\partial \mathbf{z}_1} & \frac{\partial \mathbf{x}_2}{\partial \mathbf{z}_2} \end{bmatrix} = \begin{bmatrix} \text{diag}(\exp(s(\mathbf{z}_2))) & \frac{\partial \mathbf{x}_1}{\partial \mathbf{z}_2} \\ \mathbf{0} & I \end{bmatrix}$$

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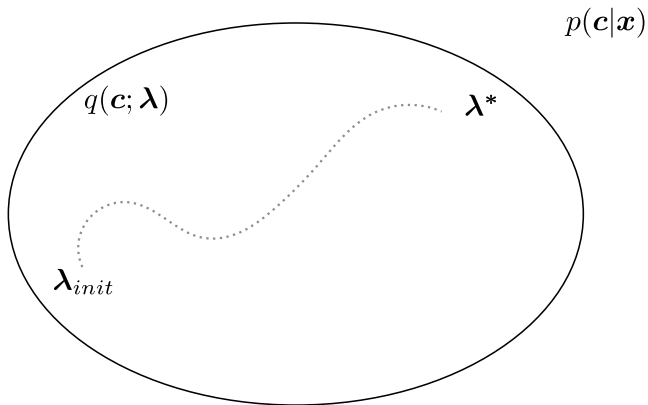
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- Problem: The integral is normally **intractable**
  - **Variational inference**: an **approximate inference** framework to overcome this intractability.

Given a family  $q(\mathbf{c}; \boldsymbol{\lambda})$ , find the parameters  $\boldsymbol{\lambda}^*$  such that:

$$\boldsymbol{\lambda}^* = \underset{\boldsymbol{\lambda}}{\operatorname{argmin}} KL(q(\mathbf{c}; \boldsymbol{\lambda}) || p(\mathbf{c}|\mathbf{x}))$$

# Variational Inference: Goal



$$KL(q(\mathbf{c})||p(\mathbf{z}|\mathbf{x})) = \int q(\mathbf{c}) \log \frac{q(\mathbf{c})}{p(\mathbf{c}|\mathbf{x})} d\mathbf{c}$$



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Which yields the lower bound (ELBO):

$$\begin{aligned}\text{ELBO}(q) &= \mathbb{E}_q[\log p(\mathbf{x}, \mathbf{c})] - \mathbb{E}_q[\log q(\mathbf{c})] \\&= \mathbb{E}_q[\log p(\mathbf{x}|\mathbf{c})] + \mathbb{E}_q[\log p(\mathbf{c})] - \mathbb{E}_q[\log q(\mathbf{c})]\end{aligned}$$

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Is it possible to **combine** the ideas from the previous sections, to obtain a mixture of flexible models?

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- Parameterize  $q(z|x)$  with a **neural network**

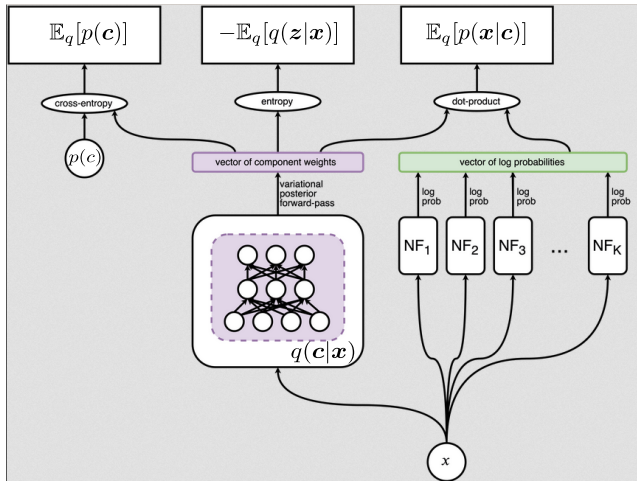


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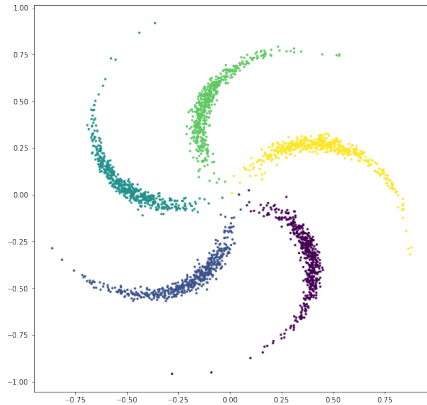
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- Parameterize  $q(z|x)$  with a **neural network**
- Optimize the ELBO, by **jointly** learning the variational posterior and the generative components.

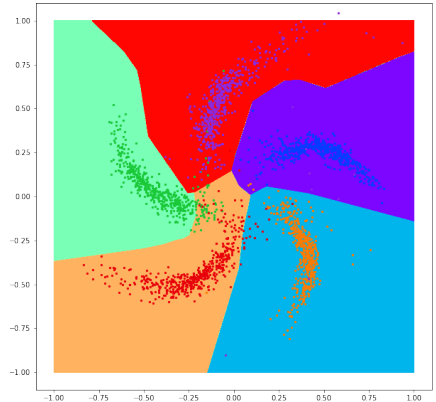
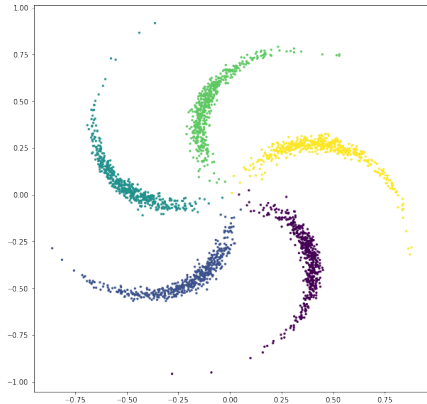
# VMoNF: Overview



# VMoNF: Experiments - Pinwheel (5 wings)

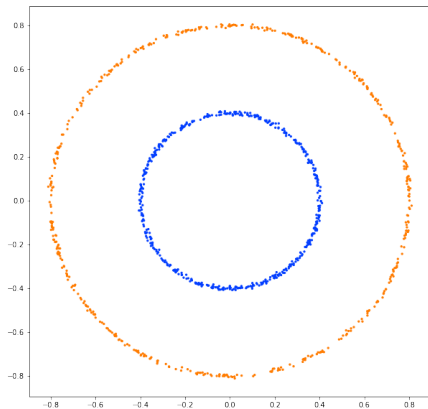


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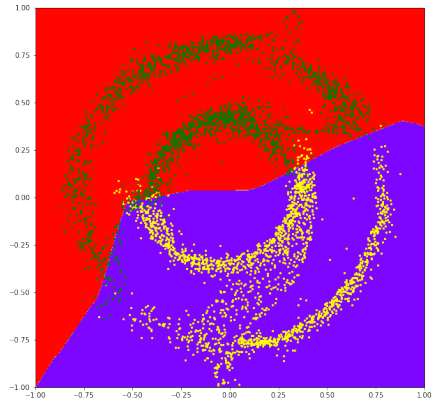
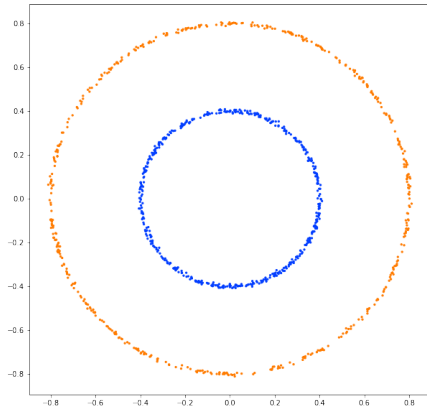


## Training Animation

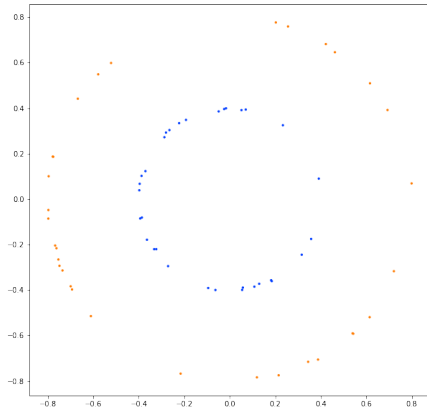
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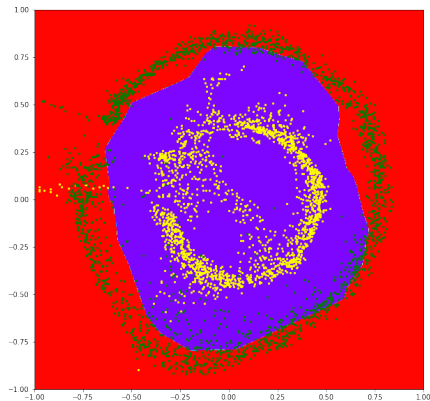
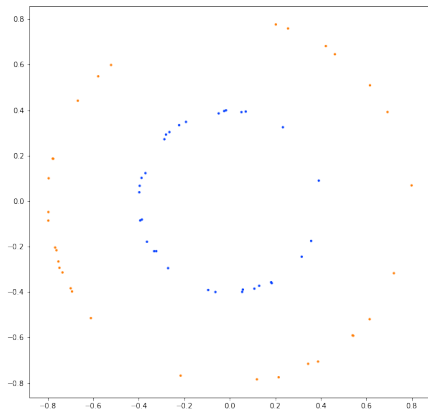


# VMoNF: Experiments - 2 Circles (semi supervised)



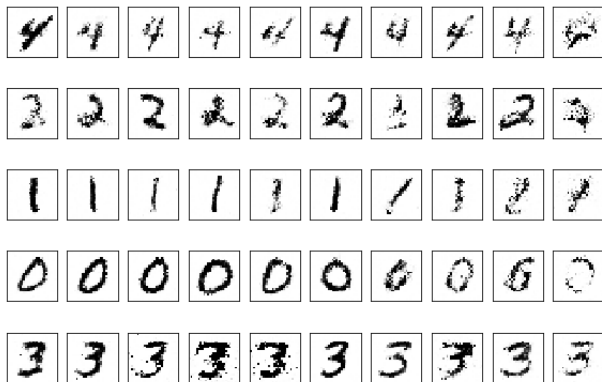


# VMoNF: Experiments - 2 Circles (semi supervised)



Note: 32 labeled points, 1024 unlabeled points

# VMoNF: Experiments - MNIST



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- (Controlled) component annihilation



Thank you!