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**Optimal Time-Dependent Perturbations: A Constraint
Optimization Problem**

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We discuss the efficient numerical solution of the following constraint optimization problem. Let N be a (high dimensional) positive semi-definite operator, which can be thought of in block form

$$N = \begin{pmatrix} N_{11} & N_{12} & \dots & N_{1p} \\ N_{21} & N_{22} & \dots & N_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ N_{p1} & N_{p2} & \dots & N_{pp} \end{pmatrix}, \quad (1)$$

where $N_{ij} \in \mathbb{R}^{n \times n}$. We would like to find the vector $x = (x_1, x_2, \dots, x_p)$ that maximizes $x^T N x$ under the constraint

$$\|x_1\| \leq 1, \quad \|x_2\| \leq 1, \dots, \|x_p\| \leq 1. \quad (2)$$

Usually we do not have the operator N in matrix form. We can only compute the action of the operator on a vector. The motivation for studying this optimization problem is the sensitivity analysis of large scale systems of linear(ized) differential equations with respect to time-dependent perturbations.

We show that the optimum is attained on the boundary of the set over which is optimized, so that we may replace the constraints in (2) with

$$\|x_1\| = \|x_2\| = \dots = \|x_p\| = 1. \quad (3)$$

These equality constraints allow us to derive an Euler-Lagrange system of equa-

tions that has many connections with a symmetric eigenvalue problem:

$$\begin{pmatrix} N_{11} & N_{12} & \dots & N_{1p} \\ N_{21} & N_{22} & \dots & N_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ N_{p1} & N_{p2} & \dots & N_{pp} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{pmatrix} = \begin{pmatrix} \lambda_1 x_1 \\ \lambda_2 x_2 \\ \vdots \\ \lambda_p x_p \end{pmatrix}$$

$$\begin{aligned} x_1^T x_1 &= 1 \\ &\vdots \\ x_p^T x_p &= 1 \end{aligned}$$

We give a geometric characterization of the solutions to these Euler-Lagrange equations and conjecture about the number of solutions.

Based on the connections with the symmetric eigenvalue problem, we study numerical methods that are variants of their eigenvalue counterparts. We show that there exists an analogue of the power method for our optimization problem. This power method consists of the iteration of the map G defined by

$$G \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{pmatrix} = \begin{pmatrix} \frac{N_{11}x_1 + N_{12}x_2 + \dots + N_{1p}x_p}{\|N_{11}x_1 + N_{12}x_2 + \dots + N_{1p}x_p\|} \\ \frac{N_{21}x_1 + N_{22}x_2 + \dots + N_{2p}x_p}{\|N_{21}x_1 + N_{22}x_2 + \dots + N_{2p}x_p\|} \\ \vdots \\ \frac{N_{p1}x_1 + N_{p2}x_2 + \dots + N_{pp}x_p}{\|N_{p1}x_1 + N_{p2}x_2 + \dots + N_{pp}x_p\|} \end{pmatrix}. \quad (4)$$

We prove convergence of the iterations of G to local maxima.

Since the power method usually converges slowly, we propose a numerical procedure to accelerate the convergence of the power method, which is in fact an adopted version of the Arnoldi or Lanczos method for eigenvalue problems [0].

Using a number of test problems, we show that the proposed procedure is effective, particularly for large scale problems. Among the test problems is the Marshall and Molteni quasi-geostrophic model [0] for atmospheric dynamics.

Other numerical methods that could be used to numerically solve the constraint optimization problem, are the optimization methods described and developed by Smith [0]. These methods are optimization methods that work on Riemannian manifolds. The methods mentioned in [0] do not construct a search space. This is advantageous for the computer memory usage. However, we would like not only to find the global optimum, but also a subspace comprising the most amplifying perturbations. This is a feature of the variants of Krylov subspace methods.

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