

Education

- Sept. 2020 — 2025 (Expected) Northeastern University, Boston, USA**
Ph.D. Candidate of Electrical & Computer Engineering
Advisor : [Prof. Yun Raymond Fu](#)
- Sept. 2017 — Jun. 2020 Xi'an Jiaotong University, Xi'an, China**
Master of Control Science and Engineering GPA : 85.07/100 Rank : 2/152
Advisor : [Prof. Jing Yang](#) & [Prof. Shaoyi Du](#)
Thesis : Pedestrian Trajectory Prediction in Complex Scenes.
- Sept. 2013 — Jun. 2017 Xi'an Jiaotong University, Xi'an, China**
Bachelor of Automation GPA : 82.53/100
Advisor : [Prof. Longjun Liu](#) & [Prof. Pengju Ren](#)
Thesis : Hardware-Friendly Compression Algorithm for Convolutional Neural Networks.

Fields of Interests

Computer Vision, Machine Learning, Behavior Prediction, Transfer Learning, Representation Learning for Time Series

Publications

• Conferences & Journals

- **Yi Xu**, Lichen Wang, Yizhou Wang, Yun Fu, "Adaptive Trajectory Prediction via Transferable GNN." *2022 IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR)* . [\[Paper\]](#)
- **Yi Xu**, Lichen Wang, Yizhou Wang, Can Qin, Yulun Zhang, Yun Fu, "MemREIN : Rein the Domain Shift for Cross-Domain Few-Shot Learning." *2022 International Joint Conference on Artificial Intelligence (IJCAI)*. [\[Paper\]](#)
- **Yi Xu***, Dongchun Ren*, Mingxia Li*, Yuehai Chen, Mingyu Fan, Huaxia Xia, "Tra2Tra : Trajectory-to-Trajectory Prediction with a Global Social Spatial-Temporal Attentive Neural Network." *IEEE Robotics and Automation Letters (RA-L)/2021 International Conference on Robotics and Automation (ICRA)* . [\[Paper\]](#)
- **Yi Xu**, Dongchun Ren, Mingxia Li, Yuehai Chen, Mingyu Fan, Huaxia Xia, "Robust Trajectory Prediction of Multiple Interacting Pedestrians via Incremental Active Learning." *2021 International Conference on Neural Information Processing (ICONIP)*. [\[Paper\]](#)
- **Yi Xu***, Jing Yang*, Shaoyi Du, "CF-LSTM : Cascaded Feature-Based Long Short-Term Networks for Predicting Pedestrian Trajectory." *2020 AAAI Conference on Artificial Intelligence (AAAI)*. [\[Paper\]](#)
- Yitian Zhang, Yue Bai, Huan Wang, **Yi Xu**, Yun Fu, "Look More but Care Less in Video Recognition." *2022 Conference on Neural Information Processing Systems (NeurIPS)*.
- Yizhou Wang, Can Qin, Yue Bai, **Yi Xu**, Xu Ma, Yun Fu, "Making Reconstruction-based Method Great Again for Video Anomaly Detection." *2022 IEEE International Conference on Data Mining (ICDM)*.
- Yizhou Wang, Can Qin, Rongzhe Wei, **Yi Xu**, Yue Bai, Yun Fu, "Self-supervision Meets Adversarial Perturbation : A Novel Framework for Anomaly Detection." *2022 ACM International Conference on Information and Knowledge Management (CIKM)*. [\[Paper\]](#)
- Yanliang Zhu*, Dongchun Ren*, **Yi Xu***, Deheng Qian*, Mingyu Fan*, Xin Li*, Huaxia Xia*, "Simultaneous Past and Current Social Interaction-aware Trajectory Prediction for Multiple Intelligent Agents in Dynamic Scenes." *ACM Transactions on Intelligent Systems and Technology (TIST)* 2021. [\[Paper\]](#)
- Jing Yang, **Yi Xu**, Haijun Rong, Shaoyi Du, Badong Chen, "Sparse Recursive Least Mean p-Power Extreme Learning Machine for Regression," *IEEE Access* 2018. [\[Paper\]](#)
- Yuehai Chen, Jing Yang, Kun Zhang, **Yi Xu**, Yuewen Liu, "A Feature-Cascaded Correntropy LSTM for Tourists Prediction," *IEEE Access* 2021. [\[Paper\]](#)
- Jing Yang, **Yi Xu**, Haijun Rong, Shaoyi Du, Hongmei Zhang, "A Method for Wafer Defect Detection Using Spatial Feature Points Guided Affine Iterative Closest Point Algorithm," *IEEE Access* 2020. [\[Paper\]](#)

• Pre-prints

- Yizhou Wang, Yue Kang, Can Qin, **Yi Xu**, Huan Wang, Yulun Zhang, Yun Fu, "Adapting Stepsizes by Momentumized Gradients Improves Optimization and Generalization." [\[Paper\]](#)

• Patents

- **Yi Xu**, Mingyu Fan, Dongchun Ren, Huaxia Xia, Yaxuan Dai, Deheng Qian, Yanliang Zhu, "An Obstacle Trajectory Prediction Method." *Granted China Invention Patent No. CN112348293A*.
- Mingyu Fan, **Yi Xu**, Dongchun Ren, Huaxia Xia, Yanliang Zhu, Deheng Qian, "A Model Training Method." *Granted China Invention Patent No. CN112990375B*.

- Mingyu Fan, Jiawen Huang, Dongchun Ren, Huaxia Xia, **Yi Xu**, "Model Training Method for Obstacle Trajectory Prediction Based on Transfer Learning." *Granted China Invention Patent No. CN113325855A.*

Competitions

INTERACTION-Dataset-Based PREdiction (INTERPRET) Challenge in NeurIPS2020 | Vehicle Future Trajectory Prediction

- Proposed dual transformer-based method to extract impact spatial-temporal feature representations.
- Won **1st** Place of the Generalizability Track and **2nd** Place of the Regular Track.

Experiences

Research Assistant 2020.09 – Present

Northeastern University, Boston, USA.

Computer Vision

Transfer Learning

Few-Shot Learning

Time Series

▷SMILE Lab.

- Proposed effective behavior prediction methods to generalize to novel environments.
- Delved into the behavior (i.e. trajectory, motion) prediction and understanding problem.
- Explored unsupervised representation learning methods for time series.
- Supervisor : Prof. Yun Raymond Fu

GNN

CNN

Self-/Cross-Attention

Transformer

Research Intern 2022.05 – 2022.09

Honda Research Institute, San Jose, USA.

Behavior Prediction

Pattern Recognition

Computer Vision

▷Cognition Team.

- Proposed a unified framework for the joint problem of trajectory imputation and prediction, which is the pioneer which fills the gap in benchmarks and techniques for this joint problem.
- Curated three practical datasets for the joint problem of trajectory imputation and prediction.
- Supervisor : Dr. Chiho Choi

GNN

CVAE

VRNN

GAN

Research Intern 2020.06 – 2020.09

Meituan, Beijing, China.

Motion Prediction

Pattern Recognition

Computer Vision

▷Autonomous Delivery Center.

- Proposed effective methods for pedestrian/vehicle trajectory prediction in complex scenes.
- Explored the importance of different trajectory samples with active learning and self-paced learning.
- Supervisor : Prof. Mingyu Fan

GNN

RNN

GAN

Transformer

Active Learning

Self-Paced Learning

Research Assistant 2017.09 – 2020.06

Xi'an Jiaotong University, Xi'an, China.

Computer Vision

Machine Learning

▷Institute of Artificial Intelligence and Robotics.

- Extra restrictions are explored for better point cloud registration.
- Attention mechanism, correntropy are utilized for interaction-aware pedestrian trajectory prediction.

Iterative Closest Point Algorithm

Attention Mechanism

LSTM

Correntropy

Research Assistant 2016.06 – 2016.08

Xi'an Jiaotong University, Xi'an, China.

Machine Learning

Optimization

▷Information-Technology Talent Program.

- Various methods are explored for avoiding getting stuck in the local optimal.
- Proposed robust strategies for improve the performance of the fireworks algorithm.

Evolutionary Algorithms

Fireworks Algorithm

Particle Swarm Optimization

Projects

Hardware (FPGA) Project with Xilinx Company | Reinforcement Learning for Obstacle Avoidance

- Proposed effective algorithms for obstacle avoidance via reinforcement learning.
- Designed efficient parallel operation pipeline at the global level for hardware implementation on FPGA.

Awards

- 2022 Travel Award of PhD Network Northeastern University.
- 2022 Travel Award of CVPR 2022.
- 2018 National Scholarship (Highest Honor in China).
- 2018 Excellent Graduate Student of Xi'an Jiaotong University.
- 2018 Third Prize of the 15th Mathematical Contest in Modeling.
- 2018 Third Prize of the 4th Future Flight Vehicle Innovation Competition.

Skills

Languages Python, MATLAB, C/C++.

Tools VS Code, Docker, VIVADO.

Frameworks PyTorch, PyTorch Geometric, TensorFlow.