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#### Education

Sept. 2020 — Present Northeastern University, Boston, USA

> Ph.D. Candidate of Electrical & Computer Engineering GPA: 3.83/4

Advisor: Prof. Yun Raymond Fu

Xi'an Jiaotong University, Xi'an, China **Sept. 2017** — **Jun. 2020** 

> Master of Control Science and Engineering GPA: 85.07/100 Rank: 2/152

Advisor: Prof. Jing Yang & Prof. Shaoyi Du

Thesis: Pedestrian Trajectory Prediction in Complex Scenes.

Xi'an Jiaotong University, Xi'an, China Sept. 2013 — Jun. 2017

> Bachelor of Automation GPA: 82.53/100 Advisor: Prof. Longjun Liu & Prof. Pengju Ren

Thesis: Hardware-Friendly Compression Algorithm for Convolutional Neural Networks.



#### Fields of Interests

Computer Vision, Machine Learning, Behavior Prediction, Multimodal Learning, Visual-Language Model



## Publications

#### • Conferences & Journals

- [C13] Jianglin Lu, Yi Xu, Huan Wang, Yue Bai, Yun Fu, "Latent Graph Inference with Limited Supervision," Conference on Neural Information Processing Systems (NeurIPS), 2023. (accepted, to appear)
- [C12] Haichao Zhang, Yi Xu, Hongsheng Lu, Takayuki Shimizu, and Yun Fu, "Layout Sequence Prediction From Noisy Mobile Modality," ACM International Conference on Multimedia (MM), 2023. (accepted, to appear)
- [C11] Yizhou Wang, Yue Kang, Can Qin, Huan Wang, Yi Xu, Yulun Zhang, and Yun Fu, "Momentum is All You Need for Data-Driven Adaptive Optimization," IEEE International Conference on Data Mining (ICDM), 2023.
- [C10] Yi Xu, Armin Bazarjani, Hyung-gun Chi, Chiho Choi, Yun Fu, "Uncovering the Missing Pattern: Unified Framework Towards Trajectory Imputation and Prediction," IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR), 2023.
- [C9] Hyung-gun Chi, Kwonjoon Lee, Nakul Agarwal, Yi Xu, Karthik Ramani, Chiho Choi, "AdamsFormer for Spatial Action Localization in the Future," IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR), 2023.
- [C8] Yitian Zhang, Yue Bai, Huan Wang, Yi Xu, Yun Fu, "Look More but Care Less in Video Recognition," Conference on Neural Information Processing Systems (NeurIPS), 2022.
- [C7] Yizhou Wang, Can Qin, Yue Bai, Yi Xu, Xu Ma, Yun Fu, "Making Reconstruction-based Method Great Again for Video Anomaly Detection," IEEE International Conference on Data Mining (ICDM), 2022.
- [C6] Yizhou Wang, Can Qin, Rongzhe Wei, Yi Xu, Yue Bai, Yun Fu, "Self-supervision Meets Adversarial Perturbation: A Novel Framework for Anomaly Detection," ACM International Conference on Information and Knowledge Management (CIKM), 2022.
- [C5] Yi Xu, Lichen Wang, Yizhou Wang, Yun Fu, "Adaptive Trajectory Prediction via Transferable GNN," IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR), 2022.
- [C4] Yi Xu, Lichen Wang, Yizhou Wang, Can Qin, Yulun Zhang, Yun Fu, "MemREIN: Rein the Domain Shift for Cross-Domain Few-Shot Learning," International Joint Conference on Artificial Intelligence (IJCAI), 2022.
- [C3] Yi Xu\*, Dongchun Ren\*, Mingxia Li\*, Yuehai Chen, Mingyu Fan, Huaxia Xia, "Tra2Tra: Trajectory-to-Trajectory Prediction with a Global Social Spatial-Temporal Attentive Neural Network," International Conference on Robotics and Automation (ICRA), 2021.
- [C2] Yi Xu, Dongchun Ren, Mingxia Li, Yuehai Chen, Mingyu Fan, Huaxia Xia, "Robust Trajectory Prediction of Multiple Interacting Pedestrians via Incremental Active Learning," International Conference on Neural Information Processing (ICONIP), 2021.
- [C1] Yi Xu\*, Jing Yang\*, Shaoyi Du, "CF-LSTM: Cascaded Feature-Based Long Short-Term Networks for Predicting Pedestrian Trajectory," AAAI Conference on Artificial Intelligence (AAAI), 2020.

#### Journals

- [J4] Yanliang Zhu\*, Dongchun Ren\*, Yi Xu\*, Deheng Qian\*, Mingyu Fan\*, Xin Li\*, Huaxia Xia\*, "Simultaneous Past and Current Social Interaction-aware Trajectory Prediction for Multiple Intelligent Agents in Dynamic Scenes," ACM Transactions on Intelligent Systems and Technology (TIST), 2021.
- [J3] Yuehai Chen, Jing Yang, Kun Zhang, Yi Xu, Yuewen Liu, "A Feature-Cascaded Correntropy LSTM for Tourists Prediction," IEEE Access, 2021.
- [J2] Jing Yang, Yi Xu, Haijun Rong, Shaoyi Du, Hongmei Zhang, "A Method for Wafer Defect Detection Using Spatial Feature Points Guided Affine Iterative Closest Point Algorithm," IEEE Access, 2020.
- [J1] Jing Yang, Yi Xu, Haijun Rong, Shaoyi Du, Badong Chen, "Sparse Recursive Least Mean p-Power Extreme Learning Machine for Regression," IEEE Access, 2018.

#### Patents

- [P3] Yi Xu, Mingyu Fan, Dongchun Ren, Huaxia Xia, Yaxuan Dai, Deheng Qian, Yanliang Zhu, "An Obstacle Trajectory Prediction Method," granted China Invention Patent No. CN112348293A.
- [P2] Mingyu Fan, Yi Xu, Dongchun Ren, Huaxia Xia, Yanliang Zhu, Deheng Qian, "A Model Training Method," granted China Invention Patent No. CN112990375B.
- [P1] Mingyu Fan, Jiawen Huang, Dongchun Ren, Huaxia Xia, Yi Xu, "Model Training Method for Obstacle Trajectory Prediction Based on Transfer Learning," granted China Invention Patent No. CN113325855A.

## Competitions

#### INTERACTION-Dataset-Based PREdicTion (INTERPRET) Challenge in NeurIPS2020 | Vehicle Future Trajectory Prediction

- > Proposed dual transformer-based method to extract impact spatial-temporal feature representations.
- ightarrow Won  $\mathbf{1}^{st}$  Place of the Generalizability Track and  $\mathbf{2}^{nd}$  Place of the Regular Track.

# Experiences

#### **Research Assistant** 2020.09 - Present

### Northeastern University, Boston, USA. Computer Vision Transfer Learning Few-Shot Learning Time Series **⊳SMILE Lab.**

- > Propose effective behavior prediction methods to generalize to novel environments.
- > Delve into the behavior (i.e. trajectory, motion) prediction and understanding problem.
- > Explore unsupervised representation learning methods for time series.
- > Supervisor: Prof. Yun Raymond Fu

GNN CNN Self-/Cross-Attention Transformer

#### **Research Intern** 2023.05 - 2023.09

## Honda Research Institute, San Jose, USA. Visual Language Model Multimodel Learning Reasoning **⊳Cognition Team.**

- > Conducting research on multimodel learning in the autonomous driving scenario.
- > Leveraging visual-language model and LLM for scene reasoning and ego-car planning.
- > Supervisor: Dr. Kwonjoon Lee and Dr. Behzad Dariush.

Diffusion CLIP GPT BLIP-2 Flamingo

### Research Intern 2022.05 - 2022.09

## Honda Research Institute, San Jose, USA. Behavior Prediction Pattern Recognition Computer Vision **⊳Cognition Team.**

- > Proposed a unified framework for the joint problem of trajectory imputation and prediction, which is the pioneer which fills the gap in benchmarks and techniques for this joint problem.
- > Curated three practical datasets for the joint problem of trajectory imputation and prediction.
- > Supervisor: Dr. Chiho Choi

GNN CVAE VRNN GAN

## Research Intern 2020.06 - 2020.09

## **Meituan, Beijing, China.** Motion Prediction Pattern Recognition Computer Vision

- >Autonomous Delivery Center.
  - > Explored the importance of different trajectory samples with active learning and self-paced learning.

> Proposed effective methods for pedestrian/vehicle trajectory prediction in complex scenes.

> Supervisor : Prof. Mingyu Fan

GNN RNN GAN Transformer Active Learning Self-Paced Learning

### **Research Assistant** 2017.09 - 2020.06

#### Xi'an Jiaotong University, Xi'an, China. Computer Vision Machine Learning >Institute of Artificial Intelligence and Robotics.

- > Extra restrictions are explored for better point cloud registration.
- > Attention mechanism, correntropy are utilized for interaction-aware pedestrian trajectory prediction. Iterative Closest Point Algorithm Attention Mechanism LSTM Correntropy

## Projects

#### Hardware (FPGA) Project with Xilinx Company | Reinforcement Learning for Obstacle Avoidance

- > Proposed effective algorithms for obstacle avoidance via reinforcement learning.
- > Designed efficient parallel operation pipeline at the global level for hardware implementation on FPGA.



## Awards

2022 & 2023 Travel Award of Northeastern University.

2022 & 2023 Travel Award of CVPR 2022 & 2023.

- 2018 National Scholarship (Highest Honor in China).
- 2018 Excellent Graduate Student of Xi'an Jiaotong University.
- Third Prize of the 15th Mathematical Contest in Modeling. 2018
- 2018 Third Prize of the 4th Future Flight Vehicle Innovation Competition.