

1.5.4 → Reliability of systems

Definition reliability: the probability that the component is functioning

→ reliability of a system is the prob. that the system is functioning

→ Reliability of a function can be expressed as a function of the reliability of its arguments \Rightarrow called the reliability function

→ Let x_i = binary RV representing the state of component i & let p_i be the prob. that component i functions ($P(x_i=1)=p_i$). Then define two vectors

$\rightarrow X = (x_1, x_2, \dots, x_n)$ is the vector of RVS for the components (similar to state vector x , but not being

$\rightarrow p = (p_1, p_2, \dots, p_n)$ is the vector of probabilities of the components in a system ($P(x_i=1)=p_i$ for all i)

→ $R(t) = \text{reliability function of a system} = S(\text{state vectors}) = S(p)$ (not stated)

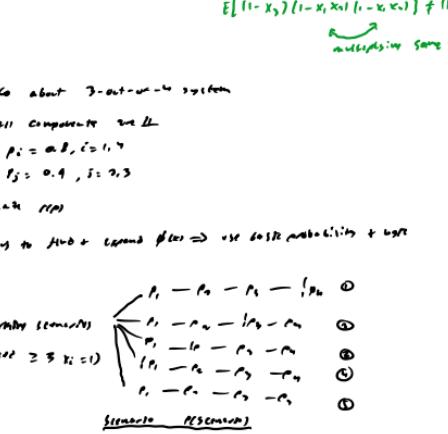
$$\boxed{R(t) = P\{X(t)=1\} = P\{x(t)=1\}}$$

→ If we know $R(t)$, we can determine $R(t)$ as

$$R(t) = E[R(t)] \quad \text{if } R(t) \text{ is a discrete RVS}$$

→ Example

in diagram $X(t)$



\rightarrow $R(t) = P(X(t)=1) = P(x(t)=1)$

$$= P\{x_1(0,t)=1\} + P\{x_2(0,t)=1\} + \dots + P\{x_3(0,t)=1\}$$

$$= (1-p_1)p_2p_3 + (1-p_2)p_1p_3 + \dots + p_1p_2p_3$$

$$= 1 - p_1p_2p_3$$

$$= 1 - P\{X(t)=0\} \quad \text{combi}$$

$$= 1 - [P\{x_1(0,t)=0\} + P\{x_2(0,t)=0\} + P\{x_3(0,t)=0\}]$$

$$= 1 - [(1-p_1)p_2p_3 + (1-p_2)p_1p_3 + \dots + (1-p_3)p_1p_2]$$

$$\downarrow p_1p_2 + p_2p_3 + p_1p_3$$

→ we also know $R(t) = x_1x_2 + x_2x_3 + x_1x_3$ from earlier example

$$\Rightarrow R(t) = E[R(t)]$$

$$= E[X_1x_2 + X_2x_3 + X_1x_3]$$

$$= E[X_1]E[X_2] + E[X_2]E[X_3] + E[X_1]E[X_3]$$

$$\checkmark = p_1p_2 + p_2p_3 + p_1p_3$$

→ Notice if know $R(t) \Rightarrow$ $E[R(t)]$ is \leq $R(t)$

$$\rightarrow \text{Suppose } R(t) = 0.7 \Rightarrow E[R(t)] = 0.7 \cdot 0.7 \cdot 0.7 = 0.343$$

→ If $R(t)$ is a reliability function of n components, then $R(t)$ is an increasing function of t \Rightarrow system is redundant

→ Examples

→ Given information \rightarrow minimal path sets are $A_1 = \{1\}$, $A_2 = \{2\}$, $A_3 = \{3\}$

\rightarrow all components work

\rightarrow $p_1 = p_2 = p_3 = 0.8$

\rightarrow calculate reliability

\rightarrow First probability \rightarrow $2^3 = 16$ possible state vectors

\rightarrow This leads to 121 min. path sets $\in P(X(t)=1)$

\rightarrow 111 total RVS + probability

\rightarrow system functions when $\left\{ \begin{array}{l} \text{1} \\ \text{2} \\ \text{3} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{1} \\ \text{2} \\ \text{3} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{1} \\ \text{2} \\ \text{3} \end{array} \right\}$ (1 = working, 0 = not working)

$$R(t) = \frac{1}{16} + 0.2 \cdot 0.8 \{ 0.8(0,0,0) + 0.8(0,0,1) + 0.8(0,1,0) \}$$

$$\downarrow = 0.4174$$

\rightarrow Structure function

$$\rightarrow f(t) = x_1 + x_2 + x_3 - x_1x_2 - x_1x_3 - x_2x_3 + x_1x_2x_3$$

(from earlier example)

$$\Rightarrow f(t) = E[f(t)]$$

$$= E[x_1 + x_2 + x_3 - x_1x_2 - x_1x_3 - x_2x_3 + x_1x_2x_3]$$

$$= p_1 + p_2 + \dots + p_3 - p_1p_2 - p_1p_3 - p_2p_3 + p_1p_2p_3$$

$$\downarrow \approx 0.534$$

$$E[(1-x_1)(1-x_2)(1-x_3)] = (1-E[x_1])(1-E[x_2])(1-E[x_3])$$

understanding same term is the clue need to keep boundary

→ Given info about 3-out-of-4 system

\rightarrow all components work

\rightarrow $p_1 = p_2 = p_3 = 0.9$

\rightarrow calculate RVS

\rightarrow Reducing to 3-out-of-4 RVS \Rightarrow use 2012 probability + logic

$$\rightarrow \begin{array}{c} p_1 = p_2 = p_3 = 1 \\ p_4 = p_5 = p_6 = 0 \end{array} \Rightarrow$$

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