

4.1 → Introduction

→ Goal: fit to set points & minimal estimates for θ 's

→ sometimes explicit expressions can be found

→ but often numerical methods are needed

→ typically there are iterative & based on the Newton-Raphson algorithm

4.2 → Example: Failure times

→ Weibull distribution

→ commonly used to model failure (or survival) times

$$f(y|\lambda, \theta) = \frac{\lambda y^{\lambda-1}}{\theta^\lambda} \exp\left\{-\left(\frac{y}{\theta}\right)^\lambda\right\}$$

→ for this example, parameter $\lambda=2$ is fixed

→ want to estimate θ

→ exponential family ✓

$$f(y|\lambda, \theta) = \exp\left\{\ln C - \frac{1}{\theta} y^\lambda\right\}$$

$$\downarrow = \exp\left\{(\lambda-1)\ln(\lambda) + \ln(\lambda) - \lambda \ln(\theta) - \frac{1}{\theta} y^\lambda\right\}$$

λ = distance $(\ln(\lambda))$ \rightarrow $\lambda \ln(\lambda)$ \rightarrow λ $\ln(\lambda)$ \rightarrow include regression term

→ not canonical form \rightarrow can't be used directly in specification of GLM

(unless $\lambda=1 \Rightarrow \exp(\theta)$) \rightarrow but can still be used to show parameter estimation in the exponential family

→ likelihood function

$$\rightarrow$$
 random sample $\rightarrow L(\theta|y_i, \lambda) = \prod_{i=1}^n \frac{\lambda y_i^{\lambda-1}}{\theta^\lambda} \exp\left\{-\left(\frac{y_i}{\theta}\right)^\lambda\right\}$

$$\downarrow = \frac{\lambda^n}{\theta^{n\lambda}} (\pi \theta)^{\lambda-1} \exp\left\{-\left(\frac{y_i}{\theta}\right)^\lambda\right\}$$

$$\rightarrow \log \text{likelihood} \rightarrow L(\theta) = n \ln(\lambda) - \lambda \ln(\theta) + (\lambda-1) \sum_{i=1}^n \ln(y_i) + \sum_{i=1}^n \left(-\frac{y_i^\lambda}{\theta}\right)$$

$$\downarrow \rightarrow y_i \rightarrow \text{but use } \left\{ \sum_{i=1}^n \ln(y_i) + c(\theta) + d(\theta) \right\} \text{ for to make easier for next steps}$$

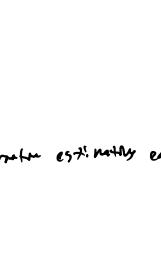
$$\downarrow = \sum_{i=1}^n \left[\ln(\lambda) + (\lambda-1) \ln(y_i) - \lambda \ln(\theta) - \left(\frac{y_i}{\theta}\right)^\lambda \right]$$

$$\rightarrow \text{Score function} \rightarrow U = \frac{dL}{d\theta} = \frac{d}{d\theta} \left[\dots \right]$$

$$\downarrow = \sum_{i=1}^n \left[-\frac{1}{\theta} + \frac{\lambda y_i^{\lambda-1}}{\theta^{1+\lambda}} \right] \quad \text{keep in sum!}$$

$$\rightarrow \text{MLE} \rightarrow \hat{\theta} \text{ such that } U(\hat{\theta}) = 0$$

→ in this case, can easily get expression for $\hat{\theta}$, but will use algorithm for demonstration purposes

→ Newton-Raphson \rightarrow basic idea  \rightarrow goal: find x where crosses \rightarrow x-axis ($f(x)=0$)

→ slope of $t \oplus x^{k+1}$ is given by

$$\left[\frac{dt}{dx} \right]_{x=x^{k+1}} = t'(x^{k+1}) = \frac{t(x^{k+1}) - t(x^{k+0})}{x^{k+1} - x^{k+0}} = \frac{\Delta t}{\Delta x} \text{ for small } \Delta x$$

→ want next guess to be the location $\rightarrow t/x^{k+0} = 0$

$$t'(x^{k+1}) = \dots \rightarrow \text{crosses } \rightarrow$$

$$t'(x^{k+1}) = t(x^{k+0}) - t(x^{k+1})$$

$$x^{k+1} = x^{k+0} - \frac{t(x^{k+0})}{t'(x^{k+0})} \rightarrow \text{Newton-Raphson formula}$$

→ For MLE using the score function

$$\rightarrow \hat{\theta}^{(m)} = \theta^{(m-1)} - \frac{U^{(m-1)}}{U'^{(m-1)}}$$

$$\rightarrow \text{with variable } \lambda=2 \rightarrow U = \sum_{i=1}^n \left[-\frac{1}{\theta} + \frac{\lambda y_i^{\lambda-1}}{\theta^{1+\lambda}} \right]$$

$$\downarrow = -\frac{\lambda n}{\theta} + \frac{\lambda}{\theta^{1+\lambda}} \sum_{i=1}^n y_i^{\lambda-1}$$

$$\downarrow = -\frac{2n}{\theta} + \frac{2}{\theta^2} \sum_{i=1}^n y_i^2$$

→ this gets eliminated at successive $\hat{\theta}^{(m)}$

$$\rightarrow U' = \frac{dU}{d\theta} = \frac{2n}{\theta^2} - \frac{2\sum_i y_i^2}{\theta^3}$$

→ for MLE, it's common to approximate U by its expected value $E(U)$

$$\rightarrow U' \approx E(U')$$

→ for exponential family, we can get TFB using the information \mathcal{I}

$$\mathcal{I} = E(t^2) \approx \sum_{i=1}^n E[t^2 u_i^2] = \sum_{i=1}^n E[t^2 u_i]$$

$$\text{Method-of-moments} \quad \text{for each obs} = \sum_{i=1}^n \left[\frac{E''(\theta) c''(\theta)}{E'(\theta)} - c''(\theta) \right]$$

$$\downarrow = C \rightarrow \text{first int.}$$

$$= \frac{\lambda^2 n}{\theta^2}$$

⇒ Alternative estimator equation \rightarrow Method of Scoring

$$\hat{\theta}^{(m)} = \theta^{(m-1)} + \frac{U^{(m-1)}}{\mathcal{I}^{(m-1)}}$$

→ Then iteratively estimate $\hat{\theta}^{(m)}$, until we're $\hat{\theta}^{(m)}$ is want

→ get a final estimate of $\hat{\theta}$ & can calculate $U + \mathcal{I}$ at this point

→ The curvature of the function in the vicinity of the mean determines the reliability of $\hat{\theta}$.

→ Curvature of U is defined by rate of change of $U (= U' \approx E(U'))$

→ If these values are small, then $\hat{\theta}$ is near $E(\hat{\theta})$ for a wide range of values

→ $\hat{\theta}$ is not well determined & its standard error is large

→ In this example $\rightarrow \hat{\theta} = 4.972$ $\approx -E(U) = 2.492$

→ On the other hand if $U(\hat{\theta})$ is inversely related to $\hat{\theta}$ \rightarrow $\hat{\theta}$ is well determined

→ If simple dist. of $\hat{\theta}$ is approximately normal

$$95\% \text{ CS} \times \hat{\theta} \rightarrow \hat{\theta} \pm 2\sigma \hat{\theta} = 4.972 \pm 1.16 \times 2.492 = [8.504, 11.788]$$

4.3 → Maximum Likelihood Estimation

→ Setup \rightarrow y_1, \dots, y_n are LL obs that satisfy properties of a GLM

→ goal: fit to estimate parameters β which are related to the y_i 's

$$\text{through } E(y_i) = \mu_i + g(\mu_i) = x_i^T \beta$$

→ Log likelihood function \rightarrow for each y_i , we have

$$l_i = y_i b(\theta_i) + c(\theta_i) + d(\theta_i)$$

$$\rightarrow \text{Also know } \rightarrow E(y_i) = \mu_i = \frac{c'(\theta_i)}{c''(\theta_i)}$$

$$V(y_i) = \left[b''(\theta_i) c''(\theta_i) - c'(\theta_i) b'(\theta_i) \right] / [b(\theta_i)]^2$$

$$g(\mu_i) = \mu_i^T \beta = \eta_i$$

$$\rightarrow \text{For all } y_i \rightarrow l = \sum_{i=1}^n l_i = \sum_{i=1}^n y_i b(\theta_i) + c(\theta_i) + d(\theta_i)$$

→ MLE \rightarrow To get $\hat{\theta} = \hat{\beta}$, need

$$\frac{\partial l}{\partial \beta_j} = U_j = \sum_{i=1}^n \left[\frac{\partial l_i}{\partial \beta_j} \right] = \sum_{i=1}^n \left[\frac{\partial y_i}{\partial \beta_j} \frac{\partial b(\theta_i)}{\partial \beta_j} + \frac{\partial c(\theta_i)}{\partial \beta_j} \right], \text{ using chain rule}$$

$$\rightarrow \frac{\partial l_i}{\partial \beta_j} = \frac{\partial y_i}{\partial \beta_j} \left[b(\theta_i) + c(\theta_i) + d(\theta_i) \right]$$

$$\downarrow = y_i \left[b(\theta_i) + c(\theta_i) \right]$$

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