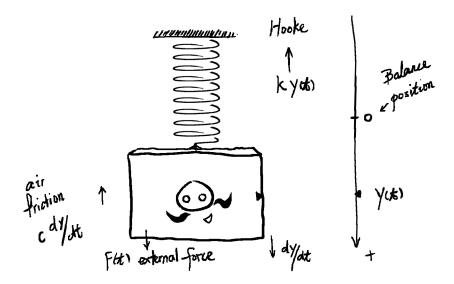
MATH 3430-02 WEEK 7-2

Key Words: Mass on a spring.

This lecture we study an application of constant coefficient 2nd order ODEs.

By 'a mass on a spring' we mean a mechanical system illustrated by the following picture:



The total force applied to the 'mass' is

The accelaration of the mass is

By Newton's second law of motion,

Thus the equation of motion of a 'mass on a spring' is a constant coefficient 2nd order ODE. Note that all parameters m, c, k are nonnegative. (In particular, it is natural to assume m, k to be positive.)

Several terminologies will bring us convenience:

The system is said to be

- i. forced if $F(t) \neq 0$;
- ii. free if F(t) = 0;
- iii. damped if c > 0;
- iv. undamped if c = 0.

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1. Free, undamped

The equation looks like

$$my'' + ky = 0.$$

Describe all the solutions. (The solutions can be put in the form $y(t) = A\cos(\omega_0 t - \phi)$, where A is the amplitude, ω_0 is called the 'natural frequency' of the system.)

2. Free, damped

The equation looks like

$$my'' + cy' + ky = 0.$$

Describe all the solutions. (Depending on the sign of $c^2 - 4mk$, we encounter cases of 'under-damped', 'overdamped', 'critically damped'. I'll explain.)

3. Forced, undamped

When the force is of the kind: $F(t)=a\cos\omega t$, the equation looks like $my''+ky=a\cos\omega t.$

What are the possible solutions? (The answer depends on whether $\omega = \sqrt{k/m}$.)

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4. Forced, damped

Again, consider the case when $F(t) = a \cos \omega t$. The equation looks like

$$my'' + cy' + ky = a\cos\omega t. \quad (c > 0)$$

Describe all solutions. (In this case, there will be the notion of a 'gain' and a 'phase shift' that is intrinsic to the system. I'll explain.)