# Trace Management Facilities to Support V&V in Executable DSLs

DiverSE SLE Seminar

Erwan Bousse<sup>1</sup> Benoit Combemale<sup>2</sup> Benoit Baudry<sup>2</sup>

<sup>1</sup>University of Rennes 1 (IRISA), France <sup>2</sup>Inria, France

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### Outline

- 1 Problem Statement
- 2 Scalable Model Cloning
- 3 Rich Domain-Specific Trace Metamodels
- 4 Rich Omniscient Debugging
- 5 Conclusion

# Plan

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# Context: xDSLs and traces

- Recently, a lot of effort in the field of executable Domain Specific Languages (xDSLs)
- From a Verification and Validation (V&V) point of view, need for dynamic V&V approaches in order to analyse the behaviors of executable models

Central concept in dynamic V&V approaches: execution traces!

Examples of trace usages in dynamic V&V:

- Omniscient Debugging: a trace is used to step backward
- Model checking: counter example in the form of a trace
- Runtime monitoring: checks if a trace satisfies a property

## Context: xDSLs and traces

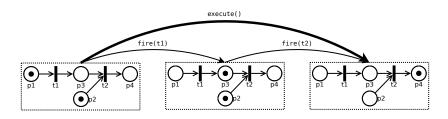
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### **Execution Trace**



#### Definition: Execution Trace

- An alternate sequence of *states* and *small steps*
- A state contains the values of all the mutable parts of a model
- A *small step* is the application of a transformation rule from the operational semantics
- A *big step* is a sequence of steps

# Concerns when Managing Traces

What kind of data structure for a trace?

How to handle a (potentially large) trace?

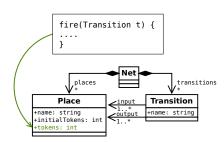
#### Concerns we focused on

- Usability, e.g. making information accessible without searching and without using type checks / casting
- Scalability in space, both offline (file or database storage) or online (in memory)
- Scalability in time, e.g. browsing a large trace

## Observation: mutable subset of a metamodel

- Operational semantics only access (read) and change (write) model elements corresponding to a subset of the considered metamodel
- We call the subset concerned by write operations the mutable subset of a metamodel

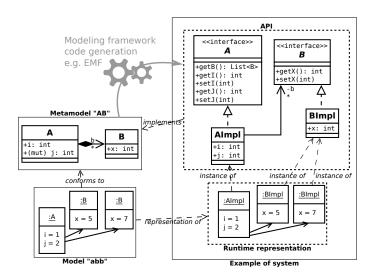




### Intuition: focus on mutable subset

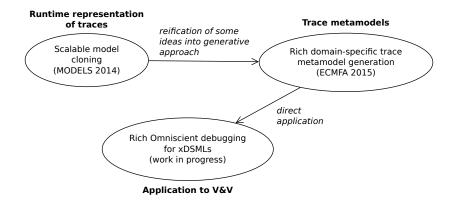
- When constructing the trace of an execution, we can focus on these mutable parts, and store only once the immutable parts
- In other words, we can reduce redundancies within execution traces
- This can be done both:
  - by working on the **runtime representation** of traces, using a memory data structure that avoids redundancy
  - by working on traces metamodels, in order to provide efficient representations of traces

# Example: a metamodel, a model, and runtime counterparts



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### Overview of the contributions



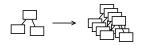
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### Context and motivation

#### Definition: clone

A *clone* is a model that is, when created, identical to an existing model. Both models conform to the same metamodel and are independent from one to another.

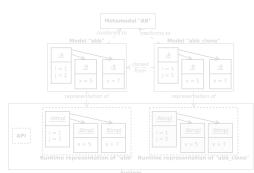


- New MDE activities which rely on the production of large quantities of models and variations of a set of models, that can be obtained through model cloning.
- In particular, cloning can be used to construct execution traces very conveniently

# Problem: efficient model cloning

- Need for the ability to clone a model
- Already possible using the most convenient cloning implementation: deep cloning (see EcoreUtil.Copier class)
- $deep\ cloning \equiv duplicating\ the\ model\ in\ memory$

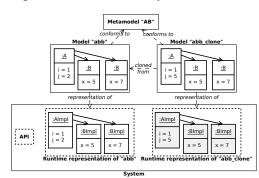
**Problem**: deep cloning has very poor memory performances



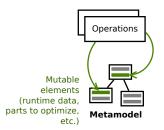
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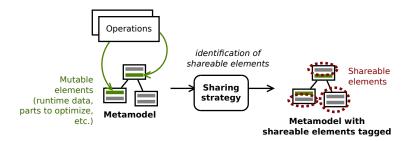
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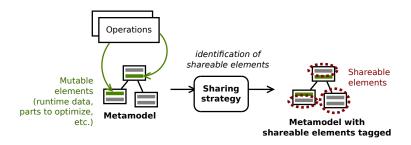
# Approach: static identification of safely shareable parts

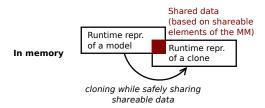


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### **Evaluation**

## Experiment

- data set: 100 randomly generated metamodels
- memory measures: gain as compared to deep cloning, after cloning the model 1000 times
- performance measures: loss of time as compared to the original model, when navigating 10 000 times through each object of the model while accessing all properties

#### Results

- memory: the more shareable parts, the more memory gain
- **performance**: worst median overhead is 9,5% wher manipulating clones with fields sharing

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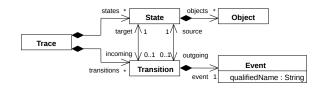
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# Plan

- Rich Domain-Specific Trace Metamodels

# Problem: generic trace metamodels are not good enough

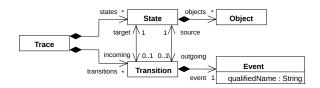
# Example of Generic trace metamodel (≡ sequence of clones)



- **Efficiency issues**: sequential structure ⇒ to navigate in a trace, each execution state has to be visited
- Usability issues: Domain-specific trace analyses have to handle domain-specific data that may be arbitrarily complex, and a generic set of objects is not convenient

# Problem: generic trace metamodels are not good enough

Example of Generic trace metamodel ( $\equiv$  sequence of clones)



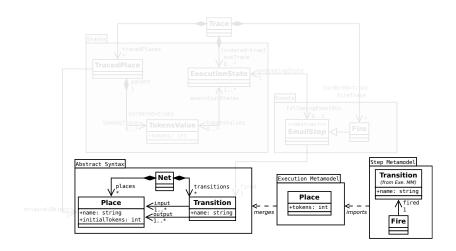
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# Approach: generating a domain-specific trace metamodel

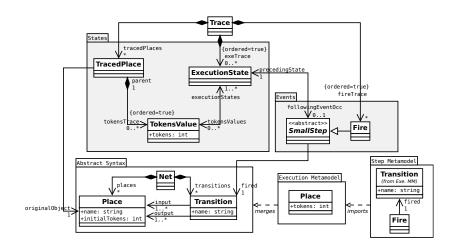
- Generative approach to automatically derive a domain-specific trace metamodel for a given xDSL
  - Domain-specific: domain concepts are directly accessible
  - Automation: Save language engineers the design of a complex metamodel, which is time-consuming and error-prone
- Enrichment with additional navigation facilities

#### Expectations:

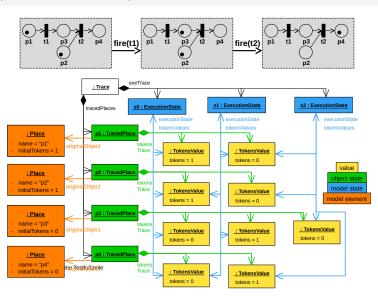
- Usability of traces is improved
- Efficiency of trace manipulations is improved



# Example of trace metamodel generation



# Example of Domain Specific Trace

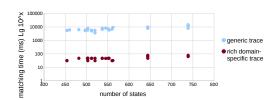


# Evaluation: performance and usability

### **Case study**: semantic differencing (ie. trace comparison)

Efficiency in time improvement

Usability improvement

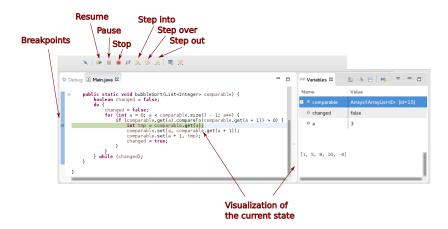


Elements	Generic	Rich Domain-Specific	Gain
Lines of code	136	55	60%
Statements	58	21	64%
Operation calls	32	13	60%
Loops	5	4	40%
Type checks	4	0	100%

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# Traditionnal (forward-only) debugging



Also notion of **frame** (e.g. a method in Java) into which we can *step* or from which we can *step out*.

# Omniscient debugging

- A debugger only gives services to go **forward in time**
- Omniscient debugging aims at providing operators that can go backwards in time as well
  - jump: to go back to a chosen previous state
  - step back into: go back one step
  - step back over: go back one step over a frame
  - step back out: go back out of a frame
  - play backwards: goes back though all previous states
  - visualization of history: a representation of the previous states (counter, trace, etc.)

Omniscient debuggers usually rely on **an execution trace** to store previous states and implement these services.

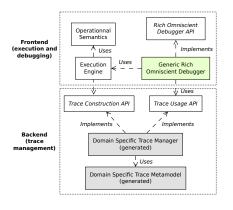
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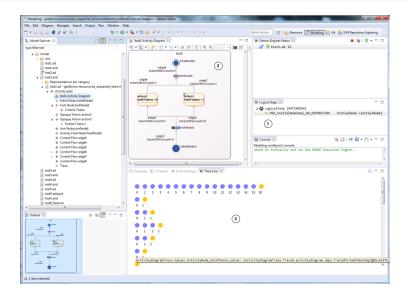
# Overview of the contribution (work in progress)

### A generative approach for rich omniscient debugging for xDSLs



- rich because of new jump services, e.g. jump to a specific field value
- allows the reuse of domain-specific traces in other domain-specific trace activities

# Implementation prototype in the GEMOC Studio



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### Conclusion

- xDSLs brings a lot of possibilities: simulation, dynamic V&V
- Dynamic V&V requires execution traces, which can be large and difficult to store/use
- Two studied approaches:
  - at the runtime representation level: Scalable Model Cloning
  - at the trace metamodel level: Rich domain-specific Trace metamodel generation
- Application to rich omniscient debugging for executable DSLs

### Perspectives

- Enhancing customisation of trace metamodels
- Experiment other V&V activities on top of generated trace metamodels

# Done!

Thank you for your attention! ©